

# 1.5MHz, RRIO, Micro-power Zero-Drift Operational Amplifiers

#### **Features**

■ Low offset Voltage: 50µV (Max.)

■ Zero Drift: 0.005µV/°C

■ Low Quiescent Current: 55µA

■ Gain Bandwidth Product: 1.5MHz

■ Operates on 1.8V ~ 5.5V Supplies

■ Slew Rate: 0.9V/µs

■ Rail-to-Rail Input and Output (RRIO)

Unity Gain Stable

No Phase Reversal

Extended Temperature Ranges
 From -40°C to +125°C

Small Packaging
 COS8552 available in SOP-8/MSOP-8
 COS8554 available in SOP14/TSSOP14

# **Applications**

- Sensor Conditioning
- Temperature Measurements
- Transducers
- Test Equipment
- Medical Instrumentation
- Battery Powered Instruments
- A/D converters

## **General Description**

The COS8552 (dual) and COS8554 (quad) are micro power, zero-drift operational amplifiers operated on 1.8 to 5.5 supplies. COS855x family use chopper stabilized technique to provide very low offset voltage (less than 20µV maximum) and near zero drift over temperature. Low quiescent supply current of 55µA per amplifier and very low input bias current make the devices an ideal choice for low offset, low power consumption and high impedance applications.

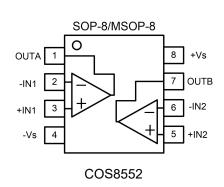
Despite their low quiescent current, the COS855x family provides excellent overall performance and versatility. They have both rail-to-rail input and output range. The output voltage swing extends to within 5mV of each rail, providing the maximum output dynamic range with excellent overdrive recovery. COS855x family is unity gain stable and has a gain bandwidth product of 1.5MHz (typical).

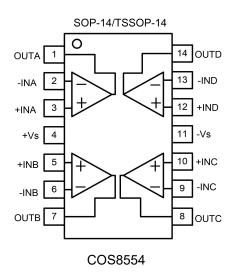
Rev1.5
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# 1. Pin Configuration and Functions





# **Pin Functions**

Name	Description	Note
+Vs	Positive power supply	A bypass capacitor of 0.1µF as close to the part as possible should be placed between power supply pins or between supply pins and ground.
-Vs	Negative power supply or ground	If it is not connected to ground, bypass it with a capacitor of 0.1µF as close to the part as possible.
-IN	Negative input	Inverting input of the amplifier. Voltage range of this pin can go from -Vs -0.3V to +Vs + 0.3V.
+IN	Positive input	Non-inverting input of the amplifier. This pin has the same voltage range as –IN.
OUT	Output	The output voltage range extends to within millivolts of each supply rail.
NC	No connection	

# 2. Ordering Information

Channel	Model	Order Number	Package	Package Option	Marking Information
	COS8552A	COS8551SRA			
	COS8552B	COS8552SRB		Tape and Reel, 4000	COS8552SR
	COS8552C	COS8552SRC			
2	COS8552A	COS8552MRA			
	COS8552B	COS8552MRB	MSOP-8	MSOP-8 Tape and Reel, 4000	COS8552MR
	COS8552C	COS8552MRC			



	COS8554A	COS8554SRA			
	COS8554B	COS8554SRB	SOP-14	Tape and Reel, 4000	COS8554SR
4	COS8554C	COS8554SRC			
4	COS8554A	COS8554TRA			
	COS8554B	COS8554TRB	TSSOP-14	Tape and Reel, 4000	COS8554TR
	COS8554C	COS8554TRC			

# 3. Product Specification

## 3.1 Absolute Maximum Ratings (1)

Parameter	Rating	Units
Power Supply: +Vs to -Vs	7.5	V
Input Voltage	-Vs -0.5V to +Vs + 0.5V	V
Input Current (2)	10	mA
Storage Temperature Range	-65 to 150	°C
Junction Temperature	150	°C
Operating Temperature Range	-40 to 125	°C
ESD Susceptibility, HBM	2000	V

<sup>(1)</sup> Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

#### 3.2 Thermal Data

Parameter	Rating	Unit
Package Thermal Resistance	190 (SOT23-5) 206 (MSOP8) 155 (SOP8) 105 (TSSOP14) 82 (SOP14)	°C/W

#### 3.3 Recommended Operating Conditions

monaca operating conditions				
Parameter	Rating	Unit		
DC Supply Voltage	1.8V ~ 5.5V	V		
Input common-mode voltage range	-Vs ~ +Vs	V		
Operating ambient temperature	-40 to +85	°C		

<sup>(2)</sup> Input terminals are diode-clamped to the power-supply rails. Input signals that can swing more than 0.5V beyond the supply rails should be current-limited to 10mA or less.



#### 3.4 Electrical Characteristics

(+V<sub>S</sub>=+5V, -V<sub>S</sub>=0, V<sub>CM</sub>=V<sub>S</sub>/2,  $T_A$ =+25°C,  $R_L$ =10k $\Omega$  to  $V_S$ /2, unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit	
Input Characteristics				·			
		COS8552A		5	20		
		COS8552B			50		
		COS8552C			100	.,	
Input Offset Voltage	Vos	COS8554A		10	50	μV	
		COS8554B			100		
		COS8554C			150		
Input Offset Voltage Drift	ΔV <sub>OS</sub> /ΔΤ	-40 to 125°C		0.005	0.05	μV/°C	
Input Bias Current	IB			±3		pA	
Input Offset Current	los			±3		pA	
Common-Mode Voltage Range	V <sub>CM</sub>	V <sub>S</sub> = 5.5V	-0.1		5.6	V	
Common-Mode Rejection Ratio	CMRR	V <sub>CM</sub> =0.1V to 4.9V		120		dB	
Open-Loop Voltage Gain	AOL	V <sub>O</sub> =0.2V to 4.8V		145		dB	
Output Characteristics							
		R <sub>L</sub> =100kΩ		5		mV	
Output Voltage Swing from Rail		R <sub>L</sub> =10kΩ		15		mV	
01 10: 110 1	I <sub>SR</sub>	Sourcing		7		mA	
Short-Circuit Current	I <sub>SK</sub>	Sinking		-7		mA	
Power Supply			ı	•			
Operating Voltage Range			1.8		5.5	V	
Power Supply Rejection Ratio	PSRR	V <sub>S</sub> = 1.8V to 5.5V	80	100		dB	
Quiescent Current / Amplifier	IQ	V <sub>S</sub> = 3.0V		55		μA	



Dynamic Performance						
Gain Bandwidth Product	GBWP	G=+1		1.5		MHz
Slew Rate	SR	G = +1 , 2V Output Step		0.9		V/µs
Noise Performance						
Voltage Noise Density	en	f=1kHz		50		nV/ √ Hz

## 4.0 Application Notes

#### **Driving Capacitive Loads**

Driving large capacitive loads can cause stability problems for voltage feedback op amps. As the load capacitance increases, the feedback loop's phase margin decreases, and the closed loop bandwidth is reduced. This produces gain peaking in the frequency response, with overshoot and ringing in the step response. A unity gain buffer (G = +1) is the most sensitive to capacitive loads, but all gains show the same general behavior.

When driving large capacitive loads with these op amps (e.g., > 100 pF when G = +1), a small series resistor at the output (R<sub>ISO</sub> in Figure 1) improves the feedback loop's phase margin (stability) by making the output load resistive at higher frequencies. It does not, however, improve the bandwidth.

To select  $R_{ISO}$ , check the frequency response peaking (or step response overshoot) on the bench. If the response is reasonable, you do not need  $R_{ISO}$ . Otherwise, start  $R_{ISO}$  at 1 k $\Omega$  and modify its value until the response is reasonable.

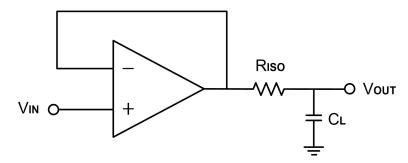


Figure 1. Indirectly Driving Heavy Capacitive Load

An improvement circuit is shown in Figure 2. It provides DC accuracy as well as AC stability.  $R_F$  provides the DC accuracy by connecting the inverting signal with the output,  $C_F$  and  $R_{ISO}$  serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier's inverting input, thereby preserving phase margin in the overall feedback loop.



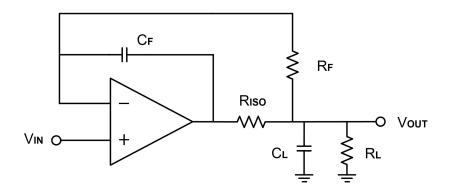


Figure 2. Indirectly Driving Heavy Capacitive Load with DC Accuracy

For noninverting configuration, there are two others ways to increase the phase margin: (a) by increasing the amplifier's gain or (b) by placing a capacitor in parallel with the feedback resistor to counteract the parasitic capacitance associated with inverting node, as shown in Figure 3.

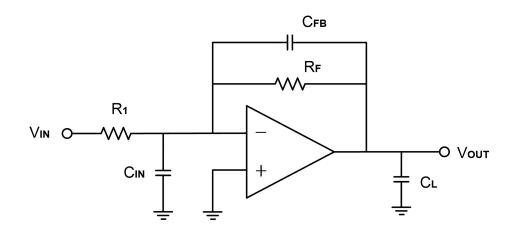


Figure 3. Adding a Feedback Capacitor in the Noninverting Configuration

#### **Power-Supply Bypassing and Layout**

The COS855x operates from a single +1.8V to +5.5V supply or dual  $\pm 0.9V$  to  $\pm 2.75V$  supplies. For single-supply operation, bypass the power supply +Vs with a  $0.1\mu F$  ceramic capacitor which should be placed close to the +Vs pin. For dual-supply operation, both the +Vs and the -Vs supplies should be bypassed to ground with separate  $0.1\mu F$  ceramic capacitors.  $2.2\mu F$  tantalum capacitor can be added for better performance.

The length of the current path is directly proportional to the magnitude of parasitic inductances and thus the high frequency impedance of the path. High speed currents in an inductive ground return create an unwanted voltage noise. Broad ground plane areas will reduce the parasitic inductance. Thus a ground plane layer is important for high speed circuit design.



#### **Typical Application Circuits**

#### **Differential Amplifier**

The circuit shown in Figure 4 performs the differential function. If the resistors ratios are equal  $(R_4 / R_3 = R_2 / R_1)$ , then  $V_{OUT} = (V_{IP} - V_{IN}) \times R_2 / R_1 + V_{REF}$ .

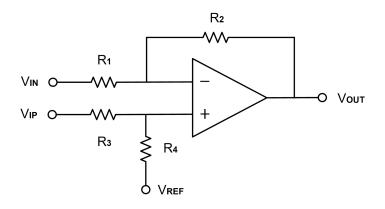


Figure 4. Differential Amplifier

#### **Low Pass Active Filter**

When receiving low-level signals, limiting the bandwidth of the incoming signals into the system is often required. The simplest way to establish this limited bandwidth is to place an RC filter at the noninverting terminal of the amplifier. If even more attenuation is needed, a multiple pole filter is required. The Sallen-Key filter can be used for this task, as Figure 5. For best results, the amplifier should have a bandwidth that is 8 to 10 times the filter frequency bandwidth. Failure to follow this guideline can result in reduction of phase margin. The large values of feedback resistors can couple with parasitic capacitance and cause undesired effects such as ringing or oscillation in high-speed amplifiers. Keep resistors value as low as possible and consistent with output loading consideration.

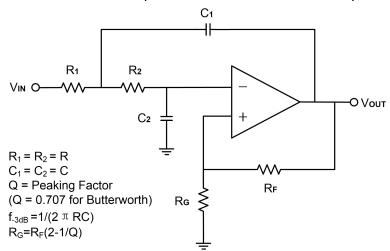
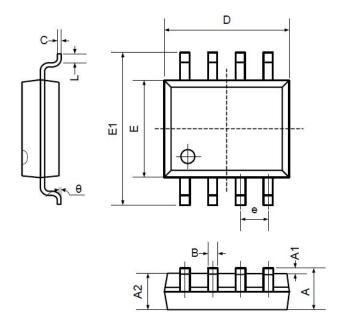


Figure 5. Two-Pole Low-Pass Sallen-Key Active Filter



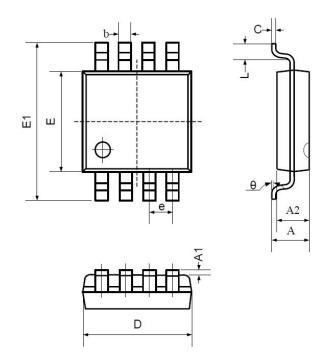
# 5. Package Information

# 5.1 SOP8 (Package Outline Dimensions)



Symbol	Dimer In Milli		Dimensions In Inches		
	Min	Max	Min	Max	
Α	1.350	1.750	0.053	0.069	
A1	0.100	0.250	0.004	0.010	
A2	1.350	1.550	0.053	0.061	
В	0.330	0.510	0.013	0.020	
С	0.190	0.250	0.007	0.010	
D	4.780	5.000	0.188	0.197	
E	3.800	4.000	0.150	0.157	
E1	5.800	6.300	0.228	0.248	
е	1.270	TYP	0.050TYP		
L	0.400	1.270	0.016	0.050	
θ	0°	8°	0° 8°		

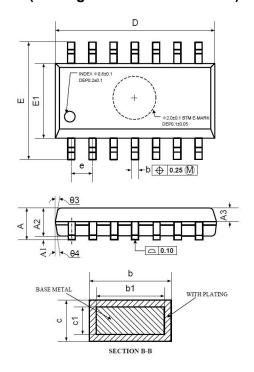
# **5.2 MSOP8 (Package Outline Dimensions)**

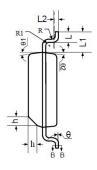


Symbol		nsions meters	Dimensions In Inches		
	Min	Max	Min	Max	
Α	0.800	1.200	0.031	0.047	
A1	0.000	0.200	0.000	0.008	
A2	0.760	0.970	0.030	0.038	
b	0.30 TYP		0.012 TYP		
С	0.15	TYP	0.006 TYP		
D	2.900	3.100	0.114	0.122	
е	0.65 TYP		0.026	TYP	
E	2.900	3.100	0.114	0.122	
E1	4.700	5.100	0.185	0.201	
L	0.410	0.650	0.016	0.026	
θ	0°	6°	0°	6°	



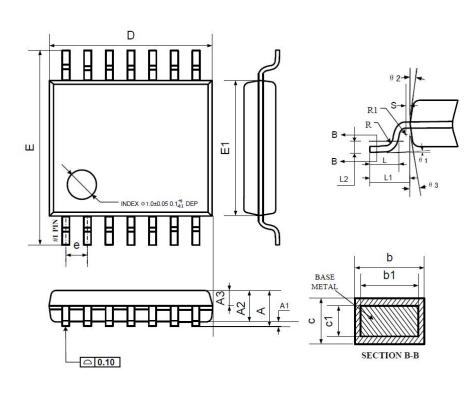
## 5.3 SOP14 (Package Outline Dimensions)





C b . l		imensio	
Symbol		Millime	
	MIN	MOM	MAX
Α	1.35	1.60	1.75
A1	0.10	0.15	0.25
A2	1.25	1.45	1.65
A3	0.55	0.65	0.75
b	0.36		0.49
b1	0.35	0.40	0.45
С	0.16		0.25
c1	0.15	0.20	0.25
D	8.53	8.63	8.73
Е	5.80	6.00	6.20
E1	3.80	3.90	4.00
е		1.27 BS0	
L	0.45	0.60	0.80
L1		1.04 REI	
L2		0.25 BS0	2
R	0.07		
R1	0.07		
h	0.30	0.40	0.50
θ	0°		8°
91	6°	8°	10°
θ2	6°	8°	10°
θ3	5°	7°	9°
θ4	5°	<b>7</b> °	9°

## **5.4 TSSOP14 (Package Outline Dimensions)**



Symbol	AND THE RESIDENCE OF THE PROPERTY OF THE PROPE				
	MIN	NOM	MAX		
Α	<u>-1-12</u>	-	1.20		
A1	0.05	-	0.15		
A2	0.90	1.00	1.05		
A3	0.34	0.44	0.54		
b	0.20	_	0.28		
b1	0.20	0.22	0.24		
С	0.10	( <del>,</del> );	0.19		
c1	0.10	0.13	0.15		
D	4.86	4.96	5.06		
E	6.20	6.40	6.60		
E1	4.30	4.40	4.50		
е		0.65 BSC			
L	0.45	0.60	0.75		
L1		1.00 REF			
L2		0.25 BSC			
R	0.09	_	_		
R1	0.09	10-11	_		
S	0.20	<u> </u>			
θ1	0°	3—3	8°		
θ2	10°	12°	14°		
θ3	10°	12°	14°		

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