# CUI DEVICES

The Step Motor Specialists BACKED BY MOONS'

## SERIES: NEMA23-AMT112S | DESCRIPTION: STEPPER SERVO MOTOR

#### FEATURES

- CUI Devices AMT112S encoder + LIN Engineering stepper motor
- stepper motor with encoder for closed-loop mode when paired with a controller
- small, compact NEMA 23 frame size
- up to 270 oz-in (1.90 N-m) holding torque
- patented capacitive encoder ASIC technology
- incremental resolutions up to 4096 PPR
- resolutions programmable with AMT Viewpoint<sup>™</sup> PC software
- digitally set zero position



## ROHS CE

MODEL	step angle	current/ phase	resistance/ phase	inductance /phase	max holding torque	max optimal speed	body length
	(°)	(A)	<b>typ</b> (Ω±10%)	<b>typ</b> (mH±20%)	(oz-in)	(RPS)	<b>max</b> (inch)
NEMA23-17-15SD-AMT112S	1.8	2.10	1.2	2.18	85.0	13	1.74
NEMA23-17-15PD-AMT112S	1.8	4.20	0.3	0.39	85.0	24	1.74
NEMA23-17-01SD-AMT112S	1.8	1.40	2.8	4.1	85.0	6	1.74
NEMA23-17-01PD-AMT112S	1.8	2.80	0.7	1.15	85.0	11	1.74
NEMA23-22-02SD-AMT112S	1.8	2.10	1.8	4.8	170.0	3	2.22
NEMA23-22-02PD-AMT112S	1.8	4.20	0.5	1.2	170.0	9	2.22
NEMA23-31-01SD-AMT112S	1.8	1.40	4.5	12.76	270.0	2	3.1
NEMA23-31-01PD-AMT112S	1.8	2.80	1.1	3.82	270.0	5	3.1

## **AMT112S ENCODER ELECTRICAL**

parameter	conditions/description	min	typ	max	units
power supply	VDD	4.5	5	5.5	V
start up time			200		ms
current consumption	with unloaded output		16		mA
output high level		VDD-0.1			V
output low level				0.1	V
output current (per channel)				15	mA
rise/fall time			8		ns

### **INCREMENTAL CHARACTERISTICS**

conditions/description min	n typ	max	units
CMOS Voltage: A, B, Z			
CMOS voltage square wave			
A leads B for CCW rotation (viewed from front)			
quadrature resolutions1   48, 96, 100, 125, 192, 200, 250, 256, 360, 384, 400, 500, 512, 768, 800, 1000, 1024, 1600, 2000, 2048, 2500, 4096			PPR
one pulse per 360 degree rotation			
	0.2		degrees
	50		%
	CMOS Voltage: A, B, Z       CMOS voltage square wave       A leads B for CCW rotation (viewed from front)       48, 96, 100, 125, 192, 200, 250, 256, 360, 384, 400, 500, 512, 768, 800, 1000, 1024, 1600, 2000, 2048, 2500, 4096	CMOS Voltage: A, B, Z     CMOS voltage square wave     A leads B for CCW rotation (viewed from front)     48, 96, 100, 125, 192, 200, 250, 256, 360, 384, 400, 500, 512, 768, 800, 1000, 1024, 1600, 2000, 2048, 2500, 4096     one pulse per 360 degree rotation     0.2	CMOS Voltage: A, B, Z     CMOS voltage square wave     A leads B for CCW rotation (viewed from front)     48, 96, 100, 125, 192, 200, 250, 256, 360, 384, 400, 500, 512, 768, 800, 1000, 1024, 1600, 2000, 2048, 2500, 4096     one pulse per 360 degree rotation     0.2

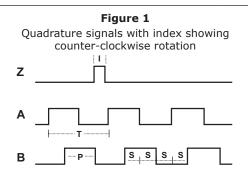
Resolution programmed with AMT Viewpoint<sup>™</sup> PC software. Default resolution set to 400 PPR.
Zero position alignment set with AMT One Touch Zero<sup>™</sup> module, AMT Viewpoint<sup>™</sup> PC software, or serial commands

#### **MECHANICAL**

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parameter	conditions/description	min	typ	max	units
weight			15.7		g
rotational speed (at each resolution)	48, 96, 100, 125, 192, 200, 250, 256, 384, 400, 500, 512, 800, 1000, 1024, 2048			8000	RPM
	360, 768, 1600, 2000, 4096			4000	RPM
	2500			2500	RPM

## **ENCODER WAVEFORMS**



The following parameters are defined by the resolution selected for each encoder, where R = resolution.

period	360/R	mechanical degrees
pulse width	T/2	mechanical degrees
index width	P/2	mechanical degrees
A/B state width	P/2	mechanical degrees
-	pulse width index width	pulse width T/2   index width P/2

## STEPPER MOTOR SPECIFICATIONS

parameter	conditions/description min	typ	max	units
motor frame size	NEMA Size 23			
step angle		1.8		0
rated current/phase	see page 1 for details			
rated voltage		24-80		Vdc
resistance/phase	see page 1 for details			
inductance/phase	see page 1 for details			
connection type	bipolar			
rotor inertia	NEMA23-22-02SD-AMT112S, NEMA23-22-02PD-AMT112S     1.5       NEMA23-31-01SD-AMT112S     2.60       NEMA23-31-01PD-AMT112S     3.60       all other models     0.70			oz-in <sup>2</sup> oz-in <sup>2</sup> oz-in <sup>2</sup> oz-in <sup>2</sup>
max holding torque	see page 1 for details			
bearing type	ABEC3			
front shaft OD		6.35		mm
front shaft length		0.81		inch
max optimal speed	see page 1 for details			
max axial load			15	lb
radial play	at 1 lb load		0.001	inch
end play	at 2 lbs load		0.003	inch
shaft run out		0.002		inch TIR
dielectric strength		500		V
EMI/EMC	EN 55014-1:2007			

## **SWITCHING SEQUENCE**

SWITCHING SEQUENCE						
CCW	STEP	А	А	В	В	
	1	+	-	+	-	
	2	+	-	-	+	
	3	-	+	-	+	
	4	-	+	+	-	
•	1	+	-	+	-	
٩	Motor Rotation Viewed from Front Shaft End					

## **ENVIRONMENTAL**

parameter	conditions/description	min	typ	max	units
operating temperature		-20		50	°C
storage temperature		-20		100	°C
humidity	non-condensing		85	%	
vibration	10~500 Hz, 5 minute sweep, 2 hours on each XYZ 5		G		
shock	3 pulses, 6 ms, 3 on each XYZ 200		200	G	
RoHS	yes				

#### **TORQUE CURVES**

60

50 orque (oz-in)

40

30

20

10

1000

2000

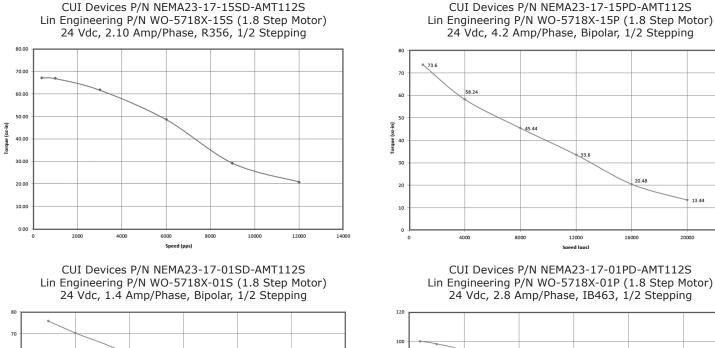
3000

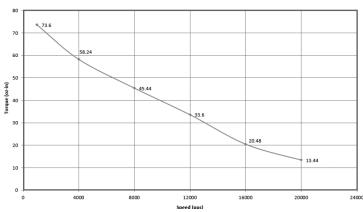
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speed (pps)

4000

5000

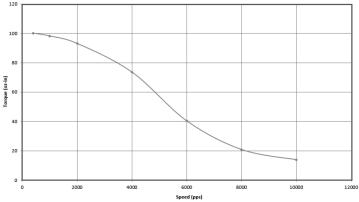




CUI Devices P/N NEMA23-17-15PD-AMT112S

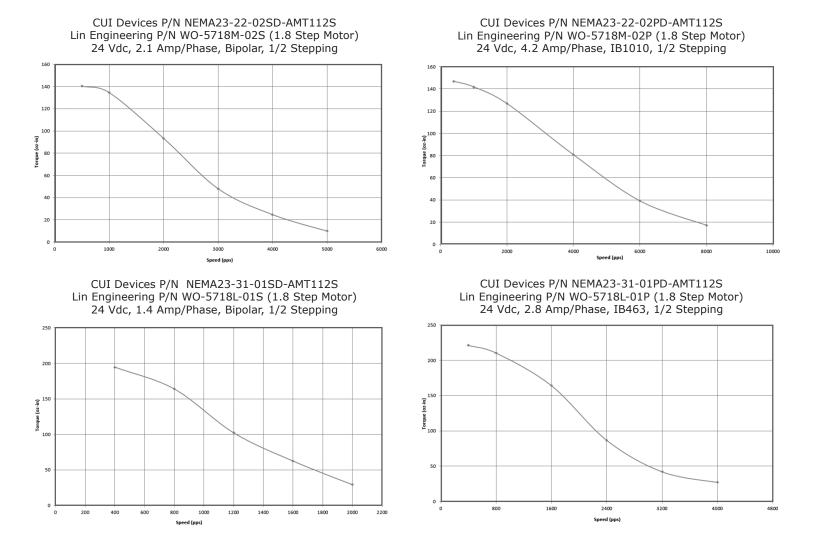
24 Vdc, 4.2 Amp/Phase, Bipolar, 1/2 Stepping

CUI Devices P/N NEMA23-17-01PD-AMT112S Lin Engineering P/N WO-5718X-01P (1.8 Step Motor) 24 Vdc, 2.8 Amp/Phase, IB463, 1/2 Stepping



## **TORQUE CURVES (CONTINUED)**

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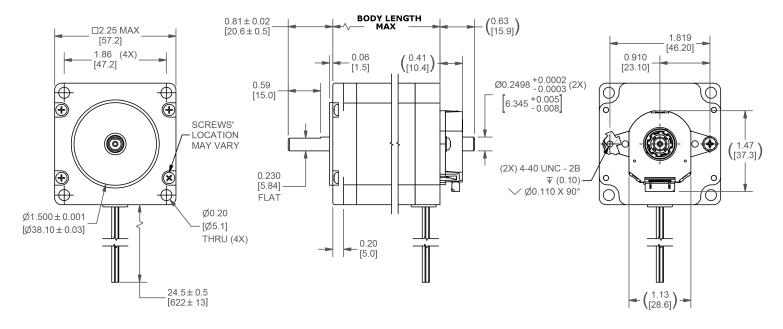


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#### **MECHANICAL DRAWING**

units: inch [mm] tolerance: X.XX ±0.01 [±0.25] X.XXX ±0.005 [±0.13] X.XXXX ±0.0005 [±0.013]



MOTOR WIRE CONNECTIONS				
Color Function				
red	А			
blue	Ā			
green	В			
black	B			
22 AWG, PVC				

MODEL NO.	BODY LENGTH (inch)	WEIGHT (lb)
NEMA23-17-15SD-AMT112S	1.74	1.05
NEMA23-17-15PD-AMT112S	1.74	1.05
NEMA23-17-01SD-AMT112S	1.74	1.05
NEMA23-17-01PD-AMT112S	1.74	1.05
NEMA23-22-02SD-AMT112S	2.22	1.50
NEMA23-22-02PD-AMT112S	2.22	1.50
NEMA23-31-01SD-AMT112S	3.10	2.35
NEMA23-31-01PD-AMT112S	3.10	2.35

17 15 13 11 9 7 5 3 1
/ʃ d d d d d d d d //
16 14 12 10 8 6 4 2
Mating Connector:
JAE FI-W17S

ENCODER CONNECTIONS				
#	Function			
1	TX_ENC+			
2	RX_ENC+			
3	N/A			
4	GND			
5	N/A			
6	+5 V			
7	N/A			
8	B+			
9	N/A			
10	A+			
11	N/A			
12	Z+			
13	N/A			
14	MCLRB			
15	N/A			
16	N/A			
17	N/A			

#### **REVISION HISTORY**

rev.	description	date
1.0	initial release	06/26/2018
1.01	brand update	02/20/2020

The revision history provided is for informational purposes only and is believed to be accurate.

**CUI** DEVICES

CUI Devices offers a one (1) year limited warranty. Complete warranty information is listed on our website.

CUI Devices reserves the right to make changes to the product at any time without notice. Information provided by CUI Devices is believed to be accurate and reliable. However, no responsibility is assumed by CUI Devices for its use, nor for any infringements of patents or other rights of third parties which may result from its use.

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CUI Devices products are not authorized or warranted for use as critical components in equipment that requires an extremely high level of reliability. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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