

## CY7C024/024A/0241 CY7C025/0251

# 4K x 16/18 and 8K x 16/18 Dual-Port Static RAM with SEM, INT, BUSY

### Features

- True dual-ported memory cells, which allow simultaneous reads of the same memory location
- 4K x 16 organization (CY7C024/024A<sup>[1]</sup>)
- 4K x 18 organization (CY7C0241)
- 8K x 16 organization (CY7C025)
- 8K x 18 organization (CY7C0251)
- 0.65 micron CMOS for optimum speed and power
- High speed access: 15 ns
- Low operating power: I<sub>CC</sub> = 150 mA (typ)
- Fully asynchronous operation
- Automatic power down
- Expandable data bus to 32/36 bits or more using Master/Slave chip select when using more than one device
- On-chip arbitration logic
- Semaphores included to permit software handshaking between ports
- INT flag for port-to-port communication
- Separate upper-byte and lower-byte control
- Pin select for Master or Slave
- Available in 84-pin (Pb-free) PLCC, 84-pin PLCC, 100-pin (Pb-free) TQFP, and 100-pin TQFP

## **Functional Description**

The CY7C024/024A/0241 and CY7C025/0251 are low power CMOS 4K x 16/18 and 8K x 16/18 dual-port static RAMs. Various arbitration schemes are included on the CY7C024/ 0241 and CY7C025/0251 to handle situations when multiple processors access the same piece of data. Two ports are provided, permitting independent, asynchronous access for reads and writes to any location in memory. The CY7C024/ 0241 and CY7C025/0251 can be used as standalone 16 or 18-bit dual-port static RAMs or multiple devices can be combined to function as a 32-/36-bit or wider master/ slave dual-port static RAM. An M/S pin is provided for implementing 32-/36-bit or wider memory applications without the need for separate master and slave devices or additional discrete logic. Application areas include interprocessor/multiprocessor designs, communications status buffering, and dual-port video/graphics memory.

Each port has independent control pins: Chip Enable ( $\overline{CE}$ ), Read or Write Enable (R/W), and Output Enable ( $\overline{OE}$ ). Two flags are provided on each port (BUSY and INT). BUSY signals that the port is trying to access the same location currently being accessed by the other port. The Interrupt Flag (INT) permits communication between ports or systems by means of a mail box. The semaphores are used to pass a flag, or token, from one port to the other to indicate that a shared resource is in use. The semaphore logic is comprised of eight shared latches. Only one side can control the latch (semaphore) at any time. Control of a semaphore indicates that a shared resource is in use. An automatic power down feature is controlled independently on each port by a chip select ( $\overline{CE}$ ) pin.

The CY7C024/024A/0241 and CY7C025/0251 are available in 84-pin Pb-free PLCCs, 84-pin PLCCs (CY7C024 and CY7C025 only), 100-pin Pb-free Thin Quad Plastic Flatplack (TQFP), and 100-pin Thin Quad Plastic Flatpack.

Note

1. CY7C024 and CY7C024A are functionally identical.

Cypress Semiconductor Corporation Document #: 38-06035 Rev. \*D

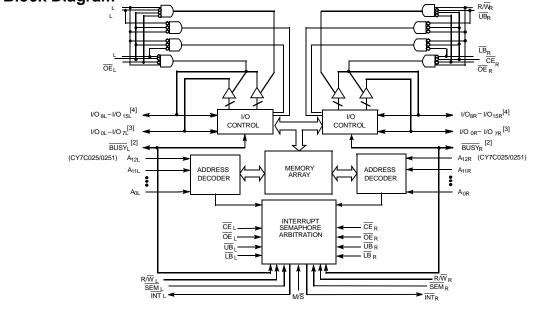
198 Champion Court

٠

San Jose, CA 95134-1709 • 408-943-2600 Revised December 09, 2008

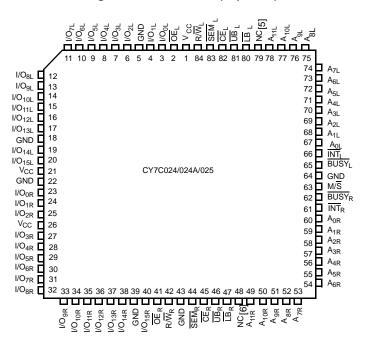


### Logic Block Diagram



#### **Pin Configurations**

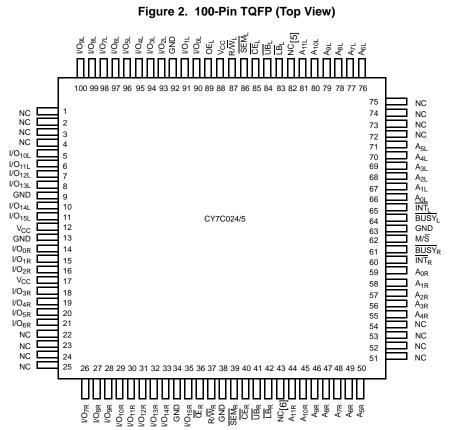
Figure 1. 84-Pin PLCC (Top View)



- BUSY is an output in master mode and an input in slave mode. 2. 3.
- $I/O_0 I/O_8$  on the CY7C0241/0251.
- 5.  $H_{0} = H_{0}$  of the CY7C0241/0251. 5.  $A_{12L}$  on the CY7C025/0251. 6.  $A_{12R}$  on the CY7C025/0251.



## Pin Configurations (continued)



#### **Pin Definitions**

Left Port	Right Port	Description
CEL	CE <sub>R</sub>	Chip Enable
R/WL	R/W <sub>R</sub>	Read/Write Enable
OEL	OE <sub>R</sub>	Output Enable
A <sub>0L</sub> -A <sub>11/12L</sub>	A <sub>0R</sub> -A <sub>11/12R</sub>	Address
I/O <sub>0L</sub> -I/O <sub>15/17L</sub>	I/O <sub>0R</sub> -I/O <sub>15/17R</sub>	Data Bus Input/Output
SEML	SEM <sub>R</sub>	Semaphore Enable
UBL	UB <sub>R</sub>	Upper Byte Select
LBL	LB <sub>R</sub>	Lower Byte Select
INTL	INT <sub>R</sub>	Interrupt Flag
BUSYL	BUSY <sub>R</sub>	Busy Flag
M/S	·	Master or Slave Select
V <sub>CC</sub>		Power
GND		Ground



### **Selection Guide**

Parameter	7C024/024A/0241–15 7C025/0251–15	7C024/0241–25 7C025/0251–25	7C024/0241–35 7C025/0251–35	7C024/0241–55 7C025/0251–55
Maximum Access Time (ns)	15	25	35	55
Typical Operating Current (mA)	190	170	160	150
Typical Standby Current for I <sub>SB1</sub> (mA)	50	40	30	20

### Architecture

The CY7C024/024A/0241 and CY7C025/0251 consist of an array of 4K words of 16/18 bits each and 8K words of 16/18 bits each of <u>dual-port RAM</u> cells, I/O and address lines, and control signals (CE, OE, R/W). These control pins permit independent access for reads or writes to any location in memory. To handle simultaneous writes/reads to the same location, a BUSY pin is provided on each port. Two interrupt (INT) pins can be used for port-to-port communication. Two semaphore (SEM) control pins are used for allocating shared resources. With the M/S pin, the CY7C024/024A/0241 and CY7C025/0251 can <u>function</u> as a master (BUSY pins are outputs) or as a slave (BUSY pins are inputs). The CY7C024/024A/0241 and CY7C025/0251 have an automatic power down feature controlled by <u>CE</u>. Each port is provided with its own output enable control (OE), which allows data to be read from the device.

### **Functional Description**

#### Write Operation

Data <u>must</u> be set up for a duration of  $t_{SD}$  before the rising edge of R/W to guarantee a valid write. A write operation is controlled by either the R/W pin (see Figure 7) or the CE pin (see Figure 8). Required inputs for non contention operations are summarized in Table 1.

If a location is being written to by one port and the opposite port attempts to read that location, a port-to-port flowthrough delay must occur before the data is read on the output; otherwise the data read is not deterministic. Data is valid on the port  $t_{DDD}$  after the data is presented on the other port.

#### Read Operation

When reading the device, the user must assert both the  $\overline{OE}$  and  $\overline{CE}$  pins. Data is available  $t_{ACE}$  after  $\overline{CE}$  or  $t_{DOE}$  after  $\overline{OE}$  is asserted. If the user of the CY7C024/024A/0241 or CY7C025/0251 wishes to access a semaphore flag, then the SEM pin must be asserted instead of the  $\overline{CE}$  pin, and  $\overline{OE}$  must also be asserted.

#### Interrupts

The upper two memory locations may be used for message passing. The highest memory location (FFF for the CY7C024/024A/0241, 1FFF for the CY7C025/0251) is the mailbox for the right port and the second-highest memory location (FFE for the CY7C024/024A/0241, 1FFE for the CY7C025/0251) is the mailbox for the left port. When one port writes to the other port's mailbox, an interrupt is generated to the owner. The interrupt is reset when the owner reads the contents of the mailbox. The message is user defined.

Each port can read the other por<u>t's mailbox</u> without resetting the interrupt. The active state of the BUSY signal (to a port) prevents the por<u>t from</u> setting the interrupt to the winning port. Also, an active BUSY to a port prevents that port from reading its own mailbox and thus resetting the interrupt to it.

If your application does not require message passing, do not connect the interrupt pin to the processor's interrupt request input pin.

The operation of the interrupts and their interaction with Busy are summarized in *Table 2* on page 5.

#### Busy

The CY7C024/024A/0241 and CY7C025/0251 provide on-chip arbitration to resolve simultaneous memory location access (contention). If both ports' CEs are asserted and an address match occurs within  $t_{PS}$  of each other, the busy logic determines which port has access. If  $t_{PS}$  is violated, one port definitely gains permission to the location, but which one is not predictable. BUSY is asserted  $t_{BLA}$  after an address match or  $t_{BLC}$  after CE is taken LOW.

#### Master/Slave

A M/S pin is provided to expand the word width by configuring the device as either a master or a slave. The BUSY output of the master is connected to the BUSY input of the slave. This allows the device to interface to a master device with no external components. Writing to slave devices must be delayed until after the BUSY input has settled ( $t_{BLC}$  or  $t_{BLA}$ ). Otherwise, the slave chip may begin a write cycle during a contention situation. When tied HIGH, the M/S pin allows the device to be used as a master and, therefore, the BUSY line is an output. BUSY can then be used to send the arbitration outcome to a slave.

#### **Semaphore Operation**

The CY7C024/024A/0241 and CY7C025/0251 provide eight semaphore latches, which are separate from the dual-port memory locations. Semaphores are used to reserve resources that are shared between the two ports. The state of the semaphore indicates that a resource is in use. For example, if the left port wants to request a given resource, it sets a latch by writing a zero to a semaphore location. The left port then verifies its success in setting the latch by reading it. After writing to the semaphore, SEM or OE must be deasserted for tSOP before attempting to read the semaphore. The semaphore value is available  $t_{SWRD}$  +  $t_{DOE}$  after the rising edge of the semaphore write. If the left port was successful (reads a zero), it assumes control of the shared resource, otherwise (reads a one) it assumes the right port has control and continues to poll the semaphore. When the right side has relinquished control of the semaphore (by writing a one), the left side succeeds in gaining control of the semaphore. If the left side no longer requires the semaphore, a one is written to cancel its request.



Semaphores are accessed by asserting  $\overline{SEM}$  LOW. The  $\overline{SEM}$  pin functions as a chip select for the semaphore latches ( $\overline{CE}$  must remain HIGH during  $\overline{SEM}$  LOW). A0–2 represents the semaphore address. OE and R/W are used in the same manner as a normal memory access. When writing or reading a semaphore, the other address pins have no effect.

When writing to the semaphore, only  $I/O_0$  is used. If a zero is written to the left port of an available semaphore, a one appears at the same semaphore address on the right port. That semaphore can now only be modified by the side showing zero (the left port in this case). If the left port now relinquishes control by writing a one to the semaphore, the semaphore is set to one

for both sides. However, if the right port had requested the semaphore (written a zero) while the left port had control, the right port immediately owns the semaphore as soon as the left port released it. Table 3 shows sample semaphore operations.

When reading a semaphore, all sixteen/eighteen data lines output the semaphore value. The read value is latched in an output register to prevent the semaphore from changing state during a write from the other port. If both ports attempt to access the semaphore within  $t_{SPS}$  of each other, the semaphore is definitely obtained by one side or the other, but there is no guarantee which side controls the semaphore

		In	puts			Out	puts	Operation
CE	R/W	OE	UB	LB	SEM	I/O <sub>0</sub> –I/O <sub>7</sub> <sup>[3]</sup>	I/O <sub>8</sub> -I/O <sub>15</sub> <sup>[4]</sup>	Operation
Н	Х	Х	Х	Х	Н	High Z	High Z	Deselected: Power Down
Х	Х	Х	Н	Н	Н	High Z	High Z	Deselected: Power Down
L	L	Х	L	Н	Н	High Z	Data In	Write to Upper Byte Only
L	L	Х	Н	L	Н	Data In	High Z	Write to Lower Byte Only
L	L	Х	L	L	Н	Data In	Data In	Write to Both Bytes
L	Н	L	L	Н	Н	High Z	Data Out	Read Upper Byte Only
L	Н	L	Н	L	Н	Data Out	High Z	Read Lower Byte Only
L	Н	L	L	L	Н	Data Out	Data Out	Read Both Bytes
Х	Х	Н	Х	Х	Х	High Z	High Z	Outputs Disabled
Н	Н	L	Х	Х	L	Data Out	Data Out	Read Data in Semaphore Flag
Х	Н	L	Н	Н	L	Data Out	Data Out	Read Data in Semaphore Flag
Н		Х	Х	Х	L	Data In	Data In	Write D <sub>IN0</sub> into Semaphore Flag
Х		Х	Н	Н	L	Data In	Data In	Write D <sub>IN0</sub> into Semaphore Flag
L	Х	Х	L	Х	L			Not Allowed
L	Х	Х	Х	L	L			Not Allowed

#### Table 1. Non-Contending Read/Write

Table 2. Interrupt Operation Example (Assumes  $\overline{\text{BUSY}}_{L} = \overline{\text{BUSY}}_{R} = \text{HIGH})^{[7]}$ 

Function	Left Port					Right Port					
Function	R/₩ <sub>L</sub>		OEL	A <sub>0L-11L</sub>	INT	R/W <sub>R</sub>	CER	OER	A <sub>0R-11R</sub>	INT <sub>R</sub>	
Set Right INT <sub>R</sub> Flag	L	L	Х	(1)FFF	Х	Х	Х	Х	Х	L <sup>[9]</sup>	
Reset Right INT <sub>R</sub> Flag	Х	Х	Х	Х	Х	Х	L	L	(1)FFF	H <sup>[8]</sup>	
Set Left INT <sub>L</sub> Flag	Х	Х	Х	Х	L <sup>[8]</sup>	L	L	Х	(1)FFE	Х	
Reset Left INT Flag	Х	L	L	(1)FFE	H <sup>[9]</sup>	Х	Х	Х	Х	Х	



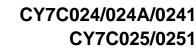
#### Table 3. Semaphore Operation Example

Function	I/O <sub>0</sub> I/O <sub>15/17</sub> Left	I/O <sub>0</sub> I/O <sub>15/17</sub> Right	Status
No action	1	1	Semaphore-free
Left port writes 0 to semaphore	0	1	Left Port has semaphore token
Right port writes 0 to semaphore	0	1	No change. Right side has no write access to semaphore.
Left port writes 1 to semaphore	1	0	Right port obtains semaphore token
Left port writes 0 to semaphore	1	0	No change. Left port has no write access to semaphore
Right port writes 1 to semaphore	0	1	Left port obtains semaphore token
Left port writes 1 to semaphore	1	1	Semaphore-free
Right port writes 0 to semaphore	1	0	Right port has semaphore token
Right port writes 1 to semaphore	1	1	Semaphore-free
Left port writes 0 to semaphore	0	1	Left port has semaphore token
Left port writes 1 to semaphore	1	1	Semaphore-free

Notes

A A<sub>0L-12L</sub> and A<sub>0R-12R</sub>, 1FFF/1FFE for the CY7C025.
 If <u>BUSY</u><sub>R</sub>=L, then no change.
 If <u>BUSY</u><sub>L</sub>=L, then no change.

Page 6 of 21





## Maximum Ratings <sup>[10]</sup>

Exceeding maximum ratings may shorten the useful life of the device. User guidelines are not tested.

Storage Temperature65°C to +150°C
Ambient Temperature with Power Applied55°C to +125°C
Supply Voltage to Ground Potential0.3V to +7.0V
DC Voltage Applied to Outputs in High-Z State0.5V to +7.0V

DC Input Voltage <sup>[11]</sup>	–0.5V to +7.0V
Output Current into Outputs (LOW)	
Static Discharge Voltage (per MIL-STD-883, Method 3015)	> 2001V
Latch Up Current	> 200 mA

**Operating Range** 

Range	Ambient Temperature	V <sub>CC</sub>
Commercial	0°C to +70°C	$5V\pm10\%$
Industrial	–40°C to +85°C	$5V\pm10\%$

### Electrical Characteristics Over the Operating Range

Parameter	Description	Test Conditions			/024A/0 25/025	241–15 1–15	7C024 7C0	Unit		
					Тур	Max	Min	Тур	Max	
V <sub>OH</sub>	Output HIGH Voltage	$V_{CC}$ = Min, $I_{OH}$ = -4.0 mA		2.4			2.4			V
V <sub>OL</sub>	Output LOW Voltage	$V_{CC}$ = Min, $I_{OL}$ = 4.0 mA				0.4			0.4	V
V <sub>IH</sub>	Input HIGH Voltage			2.2			2.2			V
V <sub>IL</sub>	Input LOW Voltage			-0.7		0.8	-0.7		0.8	V
I <sub>IX</sub>	Input Leakage Current	$GND \leq V_I \leq V_{CC}$		-10		+10	-10		+10	μΑ
I <sub>OZ</sub>	Output Leakage Current	Output Disabled, $GND \leq V_O \leq V_{CC}$		-10		+10	-10		+10	μA
I <sub>CC</sub> O	Operating Current	V <sub>CC</sub> = Max, I <sub>OUT</sub> = 0 mA, Outputs Disabled	Com'l		190	300		170	250	mA
			Ind		200	320		170	290	
I <sub>SB1</sub>	Standby Current	$\label{eq:cell} \frac{CE_{L}}{f} = f_{MAX}^{[12]} \\ $	Com'l		50	70		40	60	mA
	(Both Ports IIL Levels)		Ind		50	70			75	
I <sub>SB2</sub>	Standby Current	$\overline{CE}_{L} \text{ or } \overline{CE}_{R} \ge V_{IH},$ f = f <sub>MAX</sub> <sup>[12]</sup>	Com'l		120	180		100	150	mA
	(One Port TTL Level)	$t = t_{MAX}^{I + 2J}$	Ind		120	180		100	170	
I <sub>SB3</sub>	Standby Current	Both Ports $\overline{CE}$ and $\overline{CE}_{R} \ge$	Com'l		3	15		3	15	mA
	(Both Ports CMOS Levels)	$V_{CC} - 0.2V, V_{IN} \ge V_{CC} - 0.2V$ or $V_{IN} \le 0.2V, f = 0^{[12]}$	Ind		3	15		3	15	
I <sub>SB4</sub>	Standby Current	One Port CEL or	Com'l		110	160		90	130	mA
	(Both Ports CMOS Levels)	$\begin{array}{l} CE_R \geq V_{CC} - 0.2V, \\ V_{IN} \geq V_{CC} - 0.2V \text{ or } V_{IN} \leq 0.2V, \\ \text{Active Port Outputs, } f = f_{MAX}^{[12]} \end{array}$	Ind		110	160		90	150	

#### Electrical Characteristics Over the Operating Range

Parameter	Description	Test Conditions		/024A/0 25/025	241–35 1–35	7C024/ 7C0	Unit		
			Min	Тур	Max	Min	Тур	Max	
V <sub>OH</sub>	Output HIGH Voltage	$V_{CC} = Min, I_{OH} = -4.0 \text{ mA}$	2.4			2.4			V
V <sub>OL</sub>	Output LOW Voltage	$V_{CC} = Min, I_{OL} = 4.0 \text{ mA}$			0.4			0.4	V
V <sub>IH</sub>	Input HIGH Voltage		2.2			2.2			V
V <sub>IL</sub>	Input LOW Voltage		-0.7		0.8	-0.7		0.8	V
I <sub>IX</sub>	Input Leakage Current	$GND \le V_I \le V_{CC}$	-10		+10	-10		+10	μΑ
I <sub>OZ</sub>	Output Leakage Current	Output Disabled, $GND \le V_O \le V_{CC}$	-10		+10	-10		+10	μΑ

Notes 10. The voltage on any input or I/O pin cannot exceed the power pin during power up 11. Pulse width < 20 ns.

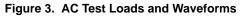
12. f<sub>MAX</sub> = 1/t<sub>RC</sub> = All inputs cycling at f = 1/t<sub>RC</sub> (except output enable). f = 0 means no address or control lines change. This applies only to inputs at CMOS level standby I<sub>SB3</sub>.

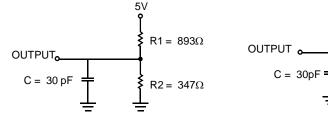


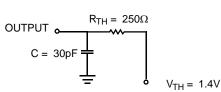
Parameter	Description	Test Conditions		/024A/0 )25/025	241–35 1–35	7C024, 7C0	Unit			
						Max	Min	Тур	Max	
I <sub>CC</sub>	Operating Current	V <sub>CC</sub> = Max, I <sub>OUT</sub> = 0 mA,	Com'l		160	230		150	230	mA
		Outputs Disabled	Ind		160	260		150	260	
I <sub>SB1</sub>	Standby Current	$\overline{CE}_{L}$ and $\overline{CE}_{R} \ge V_{IH}$ , f = f <sub>MAX</sub> <sup>[12]</sup>	Com'l		30	50		20	50	mA
	(Both Ports TTL Levels)	$f = f_{MAX}^{[12]}$	Ind		30	65		20	65	
I <sub>SB2</sub>	Standby Current (One Port TTL Level)	$\label{eq:cell} \frac{CE_L \mbox{ or } \overline{CE}_R \geq V_{IH},}{f = f_{MAX}^{[12]}}$	Com'l		85	135		75	135	mA
			Ind		85	150		75	150	
I <sub>SB3</sub>	Standby Current	Both Ports $\overline{CE}$ and $\overline{CE}_R \ge$	Com'l		3	15		3	15	mA
	(Both Ports CMOS Levels)	$ V_{CC} - 0.2V, V_{IN} \ge V_{CC} - 0.2V \\ or V_{IN} \le 0.2V, f = 0^{[12]} $	Ind		3	15		3	15	
I <sub>SB4</sub>	Standby Current	One Port CEL or	Com'l		80	120		70	120	mA
	(Both Ports CMOS Levels)	$ \begin{array}{l} CE_R \geq V_{CC} - \bar{0}.2V, \\ V_{IN} \geq V_{CC} - 0.2V \text{ or } V_{IN} \leq 0.2V, \\ \text{Active Port Outputs, } f = f_{MAX} \end{array} $	Ind		80	135		70	135	

### Capacitance<sup>[13]</sup>

Parameter	Description	Test Conditions	Max	Unit
C <sub>IN</sub>	Input Capacitance	$T_A = 25 \times C, f = 1 \text{ MHz},$	10	pF
C <sub>OUT</sub>	Output Capacitance	$V_{CC} = 5.0V$	10	pF

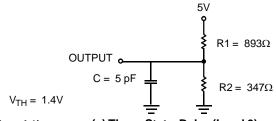






(b) Thévenin Equivalent (Load 1)

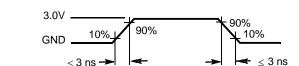
ALL INPUT PULSES



(c) Three-State Delay (Load 3)



(a) Normal Load (Load 1)



Load (Load 2)

C = 30 pF

Note 13. Tested initially and after any design or process changes that may affect these parameters.



### Switching Characteristics Over the Operating Range [14]

Parameter	Description		4A/0241–15 0251–15	7C024/024A/0241–25 7C025/0251–25		7C024/024A/0241–35 7C025/0251–35		5 7C024/024A/0241–55 7C025/0251–55		Unit	
		Min	Max	Min	Max	Min	Max	Min	Max		
Read Cycle									•		
t <sub>RC</sub>	Read Cycle Time	15		25		35		55		ns	
t <sub>AA</sub>	Address to Data Valid		15		25		35		55	ns	
t <sub>OHA</sub>	Output Hold From Address Change	3		3		3		3		ns	
t <sub>ACE</sub> <sup>[15]</sup>	CE LOW to Data Valid		15		25		35		55	ns	
t <sub>DOE</sub>	OE LOW to Data Valid		10		13		20		25	ns	
	OE Low to Low Z	3		3		3		3		ns	
t <sub>HZOE</sub> [16, 17, 18]	OE HIGH to High Z		10		15		20		25	ns	
	CE LOW to Low Z	3		3		3		3		ns	
	CE HIGH to High Z		10		15		20		25	ns	
t <sub>PU</sub> <sup>[18]</sup>	CE LOW to Power Up	0		0		0		0		ns	
t <sub>PD</sub> <sup>[18]</sup>	CE HIGH to Power Down		15		25		25		55	ns	
t <sub>ABE</sub> <sup>[15]</sup>	Byte Enable Access Time		15		25		35		55	ns	
Write Cycle						•			•		
t <sub>WC</sub>	Write Cycle Time	15		25		35		55		ns	
t <sub>SCE</sub> <sup>[15]</sup>	CE LOW to Write End	12		20		30		35		ns	
t <sub>AW</sub>	Address Setup to Write End	12		20		30		35		ns	
t <sub>HA</sub>	Address Hold From Write End	0		0		0		0		ns	
t <sub>SA</sub> <sup>[15]</sup>	Address Setup to Write Start	0		0		0		0		ns	
t <sub>PWE</sub>	Write Pulse Width	12		20		25		35		ns	
t <sub>SD</sub>	Data Setup to Write End	10		15		15		20		ns	
t <sub>HD</sub>	Data Hold From Write End	0		0		0		0		ns	
t <sub>HZWE</sub> [17, 18]	R/W LOW to High Z		10		15		20		25	ns	
t <sub>LZWE</sub> <sup>[17, 18]</sup>	R/W HIGH to Low Z	0		0		0		0		ns	
t <sub>WDD</sub> <sup>[19]</sup>	Write Pulse to Data Delay		30		50		60		70	ns	
t <sub>DDD</sub> <sup>[19]</sup>	Write Data Valid to Read Data Valid		25		35		35		45	ns	

Notes

14. Test conditions assume signal transition time of 3 ns or less, timing reference levels of 1.5V, input pulse levels of 0 to 3.0V, and output loading of the specified I<sub>OI</sub>/I<sub>OH</sub> and 30 pF load capacitance.
15. To access RAM, CE=L, UB=L, SEM=H. To access semaphore, CE=H and SEM=L. Either condition must be valid for the entire t<sub>SCE</sub> time.
16. At any given temperature and voltage condition for any given device, t<sub>HZCE</sub> is less than t<sub>LZCE</sub> and t<sub>HZOE</sub> is less than t<sub>LZOE</sub>.
17. Test conditions used are Load 3.
18. This normeters is guaranteed by the tracterd.

18. This parameter is guaranteed but not tested.

19. For information on port-to-port delay through RAM cells from writing port to reading port, refer to Figure 11.



#### Switching Characteristics Over the Operating Range (continued)<sup>[14]</sup>

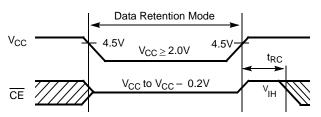
Parameter	Description	7C024/024A/0241–15 7C025/0251–15		7C024/024A/0241–25 7C025/0251–25		7C024/024A/0241–35 7C025/0251–35		7C024/024A/0241–55 7C025/0251–55		Unit
	·	Min	Max	Min	Max	Min	Max	Min	Max	
Busy Timin	ig <sup>[20]</sup>									
t <sub>BLA</sub>	BUSY LOW from Address Match		15		20		20		45	ns
t <sub>BHA</sub>	BUSY HIGH from Address Mismatch		15		20		20		40	ns
t <sub>BLC</sub>	BUSY LOW from CE LOW		15		20		20		40	ns
t <sub>BHC</sub>	BUSY HIGH from CE HIGH		15		20		20		35	ns
t <sub>PS</sub>	Port Setup for Priority	5		5		5		5		ns
t <sub>WB</sub>	R/W HIGH after BUSY (Slave)	0		0		0		0		ns
t <sub>WH</sub>	R/W HIGH after BUSY HIGH (Slave)	13		20		30		40		ns
t <sub>BDD</sub> <sup>[21]</sup>	BUSY HIGH to Data Valid		Note 21		Note 21		Note 21		Note 21	ns
Interrupt Ti	ming <sup>[20]</sup>									
t <sub>INS</sub>	INT Set Time		15		20		25		30	ns
t <sub>INR</sub>	INT Reset Time		15		20		25		30	ns
Semaphore	Timing				•					
t <sub>SOP</sub>	$\frac{\underline{\text{SEM}}}{\underline{\text{SEM}}} Flag  \text{Update Pulse}  (\overline{\text{OE}} \text{ or} \\ \overline{\underline{\text{SEM}}})$	10		12		15		20		ns
t <sub>SWRD</sub>	SEM Flag Write to Read Time	5		10		10		15		ns
t <sub>SPS</sub>	SEM Flag Contention Window	5		10		10		15		ns
t <sub>SAA</sub>	SEM Address Access Time		15		25		35		55	ns

### **Data Retention Mode**

The CY7C024/024A/0241 is designed with battery backup in mind. Data retention voltage and supply current are guaranteed over temperature. The following rules insure data retention:

- 1. Chip enable (CE) must be held HIGH during data retention, within  $V_{CC}$  to  $V_{CC} - 0.2V$ .
- 2.  $\overline{\text{CE}}$  must be kept between V\_{CC} 0.2V and 70% of V\_{CC} during the power up and power down transitions.
- 3. The RAM can begin operation  ${\rm >t_{RC}}$  after  ${\rm V_{CC}}$  reaches the minimum operating voltage (4.5V).

#### Timing



Parameter	Test Conditions <sup>[22]</sup>	Max	Unit
ICC <sub>DR1</sub>	At VCC <sub>DR</sub> = 2V	1.5	mA

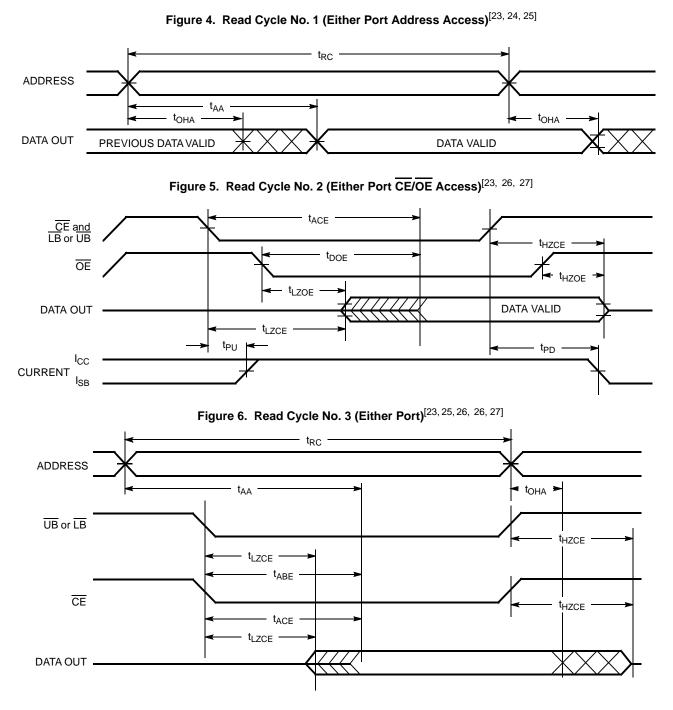
Notes

20. Test conditions used are Load 2.

21.  $\underline{t_{BDD}}$  is a calculated parameter and is the greater of  $t_{WDD}$ –  $t_{PWE}$  (actual) or  $t_{DDD}$ –  $t_{SD}$  (actual). 22.  $\overline{CE} = V_{CC}$ ,  $V_{in} = GND$  to  $V_{CC}$ ,  $T_A = 25^{\circ}C$ . This parameter is guaranteed but not tested.



### **Switching Waveforms**



- 23. R/W is HIGH for read cycles
- 24. <u>Device is continuously selected  $\overline{CE} = V_{IL}$  and  $\overline{UB}$  or  $\overline{LB} = V_{IL}$ . This waveform cannot be used for semaphore reads.</u>

- 25.  $\overline{OE} = V_{IL}$ . 26. Address valid prior to or coincident with  $\overline{CE}$  transition LOW. 27. To access RAM,  $\overline{CE} = V_{IL}$ , UB or  $\overline{LB} = V_{IL}$ , SEM =  $V_{IH}$ . To access semaphore,  $\overline{CE} = V_{IH}$ ,  $\overline{SEM} = V_{IL}$ .



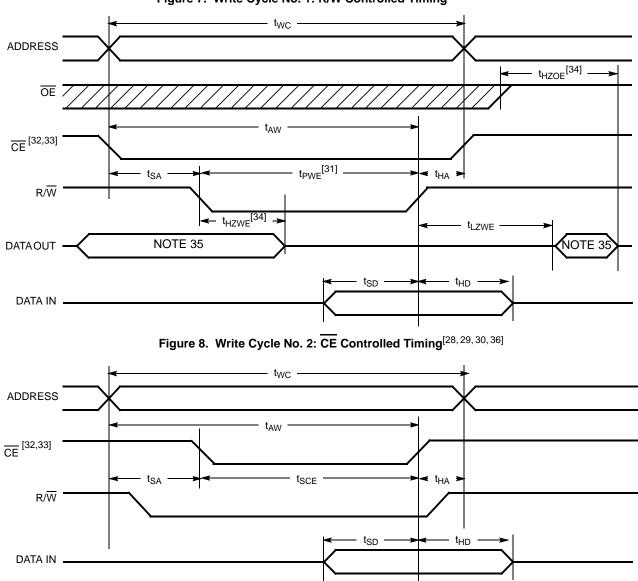


Figure 7. Write Cycle No. 1: R/W Controlled Timing<sup>[28, 29, 30, 31]</sup>

- 28. R/W must be HIGH during all address transitions.

- 28. R/W must be HIGH during all address transitions.
  29. A write occurs during the overlap (t<sub>SCE</sub> or t<sub>PME</sub>) of a LOW CE or SEM and a LOW UB or LB.
  30. t<sub>Ha</sub> is measured from the earlier of CE or R/W or (SEM or R/W) going HIGH at the end of write cycle.
  31. If OE is LOW during a R/W controlled write cycle, the write pulse width must be the larger of t<sub>PWE</sub> or (t<sub>HZWE</sub> + t<sub>SD</sub>) to allow the I/O drivers to turn off and data to be placed on the bus for the required t<sub>SD</sub>. If OE is HIGH during an R/W controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified t<sub>PWE</sub>.
  32. To access RAM, CE = V<sub>IL</sub>, SEM = V<sub>IH</sub>.
  33. To access upper byte, CE = V<sub>IL</sub>, UB = V<sub>IL</sub>, SEM = V<sub>IH</sub>.
  34. Transition is measured ±500 mV (trans teady state with a 5 pE load (including scope and iic). This perspector is compled and pet 400% teated.

- 34. Transition is measured ±500 mV from steady state with a 5 pF load (including scope and jig). This parameter is sampled and not 100% tested.
- 35. During this period, the I/O pins are in the output state, and input signals must not be applied. 36. If the CE or SEM LOW transition occurs simultaneously with or after the RW LOW transition, the outputs remain in the high impedance state.



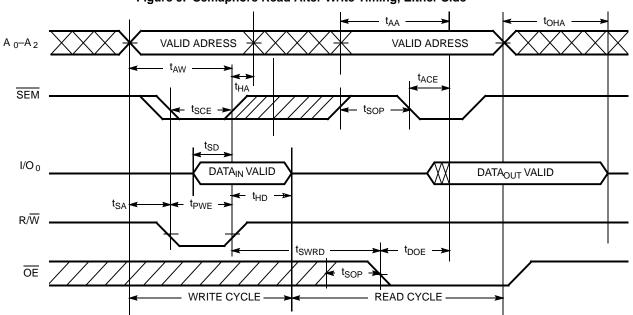
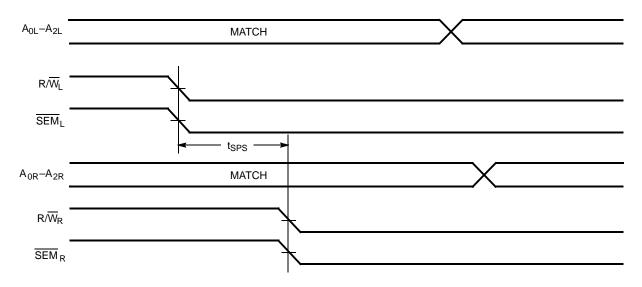


Figure 9. Semaphore Read After Write Timing, Either Side<sup>[37]</sup>

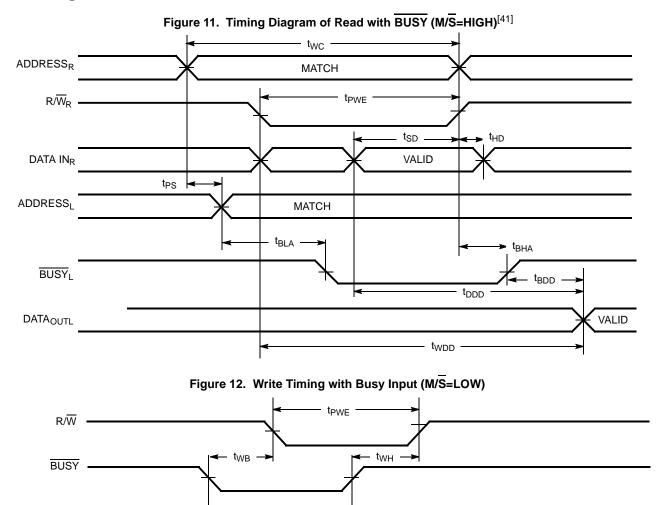
Figure 10. Timing Diagram of Semaphore Contention<sup>[38, 39, 40]</sup>



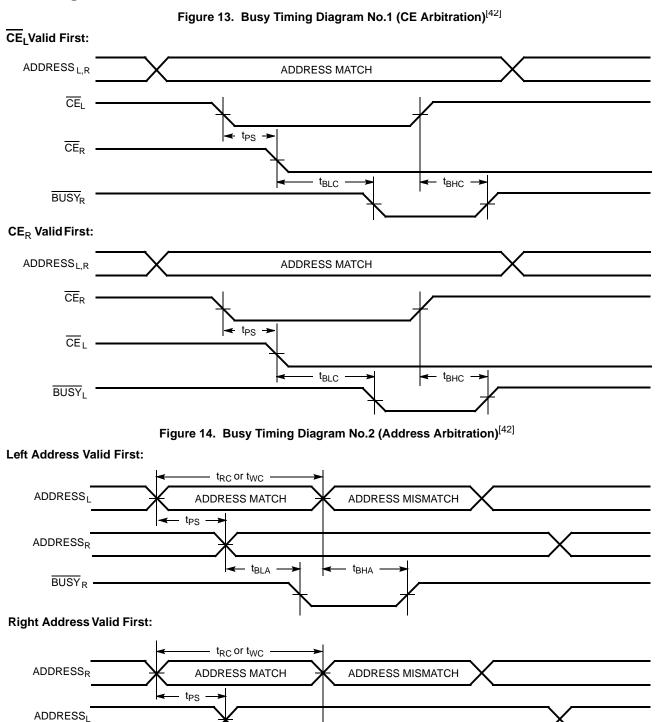
- 37. CE = HIGH for the duration of the above timing (both write and read cycle).
- 38.  $I/O_{0R} = I/O_{0L} = LOW$  (request semaphore);  $CE_R = CE_L = HIGH$ . 39. Semaphores are reset (available to both ports) at cycle start.

<sup>40.</sup> If t<sub>SPS</sub> is violated, the semaphore is definitely obtained by one side or the other, but which side gets the semaphore is unpredictable.









#### Note

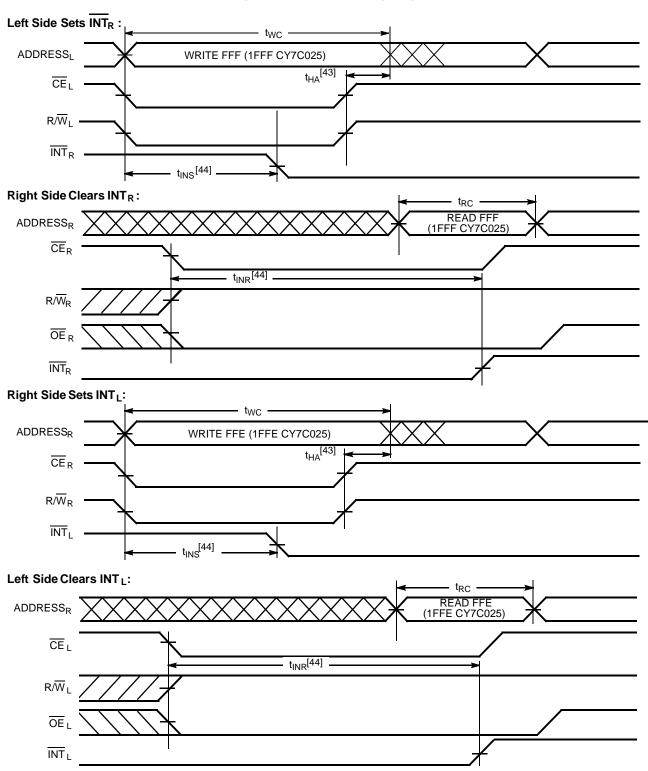
42. If t<sub>PS</sub> is violated, the busy signal is asserted on one side or the other, but there is no guarantee to which side BUSY is asserted.

t<sub>BHA</sub>

– t<sub>BLA</sub>

BUSYL





#### Figure 15. Interrupt Timing Diagrams

#### Notes

43.  $t_{HA}$  depends on which enable pin ( $\overline{CE}_L$  or  $\overline{RW}_L$ ) is deasserted first. 44.  $t_{INS}$  or  $t_{INR}$  depends on which enable pin ( $\overline{CE}_L$  or  $R/W_L$ ) is asserted last.



## Ordering Information (4K x16 Dual-Port SRAM)

Speed (ns)	Ordering Code	Package Name	Package Type	Operating Range
15	CY7C024-15AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C024-15AXC A100 1		100-Pin Pb Free Thin Quad Flat Pack	
	CY7C024–15JC	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C024-15JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
25	CY7C024-25AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C024-25AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C024-25JC	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C024A-25JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
	CY7C024–25AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C024-25AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
			84-Pin Plastic Leaded Chip Carrier	
	CY7C024-25JXI	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
35	CY7C024-35AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C024-35AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C024–35JC	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C024-35JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
	CY7C024-35AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C024-35AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C024–35JI	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C024-35JXI	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
55	CY7C024-55AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C024-55AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C024-55JC	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C024-55JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
	CY7C024–55AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C024-55AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C024–55JI	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C024-55JXI	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	

## Ordering Information (8K x 16 Dual-Port SRAM)

Speed (ns)	Ordering Code	Package Name	Package Type	Operating Range
15	CY7C025–15AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C025-15AXC	A100 100-Pin Pb Free Thin Quad Flat Pack		
	CY7C025–15JC	J83	J83 84-Pin Plastic Leaded Chip Carrier	
	CY7C025-15JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
	CY7C025–15AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C025-15AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	



## Ordering Information (8K x 16 Dual-Port SRAM) (continued)

Speed (ns)	Ordering Code	Package Name	Package Type	Operating Range
25	5 CY7C025–25AC A100 100-Pin Thin Quad		100-Pin Thin Quad Flat Pack	Commercial
	CY7C025-25AXC	A100 100-Pin Pb Free Thin Quad Flat Pack		
	CY7C025-25JC	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C025-25JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
	CY7C025–25AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C025-25AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C025–25JI	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C025-25JXI	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
35	CY7C025-35AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C025-35AXCA100100-Pin Pb Free Thin Quad Flat PackCY7C025-35JCJ8384-Pin Plastic Leaded Chip Carrier			
			84-Pin Plastic Leaded Chip Carrier	
	CY7C025-35JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
	CY7C025-35AI	7C025–35AI A100 100-Pin Thin Quad Flat Pack		Industrial
	CY7C025-35AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C025-35JI	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C025-35JXI	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
55	CY7C025-55AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C025-55AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C025–55JC	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C025-55JXC	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	
	CY7C025–55AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C025-55AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C025–55JI	J83	84-Pin Plastic Leaded Chip Carrier	
	CY7C025-55JXI	J83	84-Pin Pb Free Plastic Leaded Chip Carrier	

## Ordering Information (4K x 18 Dual-Port SRAM)

Speed (ns)	Ordering Code	Package Name	Package Type	Operating Range
15	CY7C0241–15AC A100		100-Pin Thin Quad Flat Pack	Commercial
	CY7C0241-15AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C0241-15AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C0241-15AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
25	CY7C0241-25AC	7C0241–25AC A100 100-Pin Thin Quad Flat Pack		Commercial
	CY7C0241-25AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C0241-25AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C0241-25AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
35	CY7C0241-35AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C0241-35AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C0241-35AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C0241-35AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	



## Ordering Information (4K x 18 Dual-Port SRAM) (continued)

Speed (ns)	Ordering Code	Package Name	Package Type	Operating Range
55	CY7C0241-55AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C0241-55AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C0241-55AI	A100	A100 100-Pin Thin Quad Flat Pack	
	CY7C0241-55AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	

### 8K x 18 Dual-Port SRAM

Speed (ns)	Ordering Code	Package Name	Package Type	Operating Range
15	15 CY7C0251–15AC		100-Pin Thin Quad Flat Pack	Commercial
	CY7C0251-15AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
25	CY7C0251-25AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C0251-25AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C0251-25AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C0251-25AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
35	CY7C0251-35AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C0251-35AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C0251-35AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C0251-35AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	
55	CY7C0251-55AC	A100	100-Pin Thin Quad Flat Pack	Commercial
	CY7C0251-55AXC	A100	100-Pin Pb Free Thin Quad Flat Pack	
	CY7C0251-55AI	A100	100-Pin Thin Quad Flat Pack	Industrial
	CY7C0251-55AXI	A100	100-Pin Pb Free Thin Quad Flat Pack	



### **Package Diagrams**

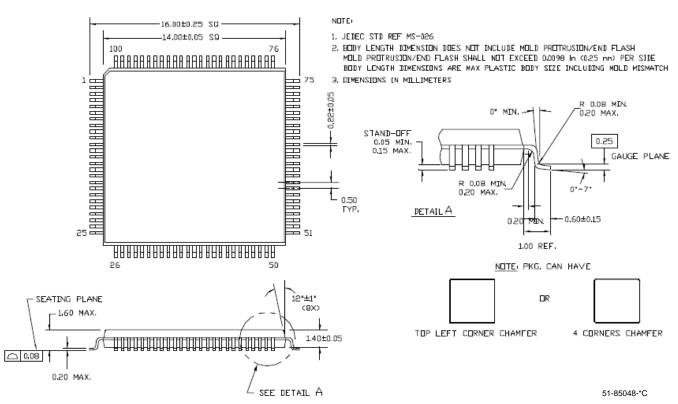
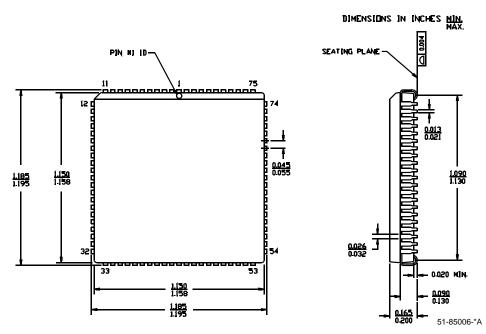


Figure 16. 100-Pin Pb-Free Thin Plastic Quad Flat Pack (TQFP) A100





Page 20 of 21



### **Document History Page**

	Document Title: CY7C024/024A/0241, CY7C025/0251 4K x 16/18 and 8K x 16/18 Dual-Port Static RAM with Sem, Int, Busy Document Number: 38-06035								
Rev.	ECN No.	Orig. of Change	Submission Date	Description of Change					
**	110177	SZV	09/29/01	Change from Spec number: 38-00255 to 38-06035					
*A	122286	RBI	12/27/02	Power up requirements added to Maximum Ratings Information					
*В	236754	YDT	See ECN	Removed cross information from features section					
*C	279132	RUY	See ECN	Added Lead (Pb)-Free packaging information					
*D	2623540	VKN/PYRS	12/17/08	Added CY7C024A part Updated Ordering information table					

### Sales, Solutions, and Legal Information

#### Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at cypress.com/sales.

Products		<b>PSoC Solutions</b>	
PSoC	psoc.cypress.com	General	psoc.cypress.com/solutions
Clocks & Buffers	clocks.cypress.com	Low Power/Low Voltage	psoc.cypress.com/low-power
Wireless	wireless.cypress.com	Precision Analog	psoc.cypress.com/precision-analog
Memories	memory.cypress.com	LCD Drive	psoc.cypress.com/lcd-drive
Image Sensors	image.cypress.com	CAN 2.0b	psoc.cypress.com/can
		USB	psoc.cypress.com/usb

© Cypress Semiconductor Corporation, 2001-2008. The information contained herein is subject to change without notice. Cypress Semiconductor Corporation assumes no responsibility for the use of any circuitry other than circuitry embodied in a Cypress product. Nor does it convey or imply any license under patent or other rights. Cypress products are not warranted nor intended to be used for medical, life support, life saving, critical control or safety applications, unless pursuant to an express written agreement with Cypress. Furthermore, Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress products in life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Any Source Code (software and/or firmware) is owned by Cypress Semiconductor Corporation (Cypress) and is protected by and subject to worldwide patent protection (United States and foreign), United States copyright laws and international treaty provisions. Cypress hereby grants to licensee a personal, non-exclusive, non-transferable license to copy, use, modify, create derivative works of, and compile the Cypress Source Code and derivative works for the sole purpose of creating custom software and or firmware in support of licensee product to be used only in conjunction with a Cypress integrated circuit as specified in the applicable agreement. Any reproduction, modification, translation, compilation, or representation of this Source Code except as specified above is prohibited without the express written permission of Cypress.

Disclaimer: CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. Cypress reserves the right to make changes without further notice to the materials described herein. Cypress does not assume any liability arising out of the application or use of any product or circuit described herein. Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress' product in a life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Use may be limited by and subject to the applicable Cypress software license agreement.

Document #: 38-06035 Rev. \*D

Revised December 09, 2008

Page 21 of 21

All products and company names mentioned in this document may be the trademarks of their respective holders.

# **X-ON Electronics**

Largest Supplier of Electrical and Electronic Components

Click to view similar products for SRAM category:

Click to view products by Cypress manufacturer:

Other Similar products are found below :

5962-8855206XA CY6116A-35DMB CY7C128A-45DMB CY7C1461KV33-133AXI CY7C199-45LMB CYDM128B16-55BVXIT GS8161Z36DD-200I GS88237CB-200I R1QDA7236ABB-20IB0 RMLV0408EGSB-4S2#AA0 IS64WV3216BLL-15CTLA3 IS66WVE4M16ECLL-70BLI PCF8570P K6T4008C1B-GB70 CY7C1353S-100AXC AS6C8016-55BIN 515712X IS62WV51216EBLL-45BLI IS63WV1288DBLL-10HLI IS66WVE2M16ECLL-70BLI 47L16-E/SN IS66WVE4M16EALL-70BLI IS62WV6416DBLL-45BLI IS61WV102416DBLL-10TLI CY7C1381KV33-100AXC CY7C1381KV33-100BZXI CY7C1373KV33-100AXC CY7C1381KVE33-133AXI CY7C4042KV13-933FCXC 8602501XA 5962-3829425MUA 5962-8855206YA 5962-8866201XA 5962-8866201YA 5962-8866204TA 5962-8866206MA 5962-8866207NA 5962-8866208UA 5962-8872502XA 5962-8959836MZA 5962-8959841MZA 5962-9062007MXA 5962-9161705MXA N08L63W2AB7I 7130LA100PDG GS81284Z36B-250I M38510/28902BVA IS62WV12816ALL-70BLI 5962-8971203XA 5962-8971202ZA