## General Description

The AUR9718B is a high efficiency step-down DC-DC voltage converter. The chip operation is optimized by peak-current mode architecture with built-in synchronous power MOSFET switchers.

The oscillator and timing capacitors are all built-in providing an internal switching frequency of 1.5 MHz that allows the use of small surface mount inductors and capacitors for portable product implementations. Additional features including Soft Start (SS), Under Voltage Lock Out (UVLO), Thermal Shutdown Detection (TSD) and short circuit protection are integrated to provide reliable product applications.

The device is available in adjustable output voltage versions ranging from 0.8 V to $\mathrm{V}_{\text {IN }}$ when input voltage range is from 2.7 V to 5.5 V , and is able to deliver up to 2.5 A .

The AUR9718B is available in DFN-3×3-6 package.

## Features

- High Efficiency Buck Power Converter
- Low $\mathrm{R}_{\mathrm{DS}(\mathrm{ON})}$ Internal Switches : $100 \mathrm{~m} \Omega$
- Output Current: 2.5A
- Adjustable Output Voltage from 0.8 V to $\mathrm{V}_{\text {IN }}$
- Wide Operating Voltage Range: 2.7 V to 5.5 V
- Built-in Power Switchers for Synchronous Rectification with High Efficiency
- Feedback Voltage Allows Output: 800 mV
- 1.5 MHz Switching Frequency
- Thermal Shutdown Protection
- Low Drop-out Operation at 100\% Duty Cycle
- No Schottky Diode Required
- Input Over Voltage Protection


## Applications

- LCD TV
- Set Top Box
- Post DC-DC Voltage Regulation
- PDA and Notebook Computer


Figure 1. Package Type of AUR9718B

## Pin Configuration

> D Package
> (DFN-3×3-6)


Figure 2. Pin Configuration of AUR9718B (Top View)

## Pin Description

| Pin Number | Pin Name | Function |
| :---: | :---: | :--- |
| 1 | FB | Output voltage feedback pin |
| 2 | GND | Ground pin |
| 3 | SW | Switch output pin |
| 4 | VIN_SW | Power supply input for the MOSFET switch |
| 5 | VIN_A | Supply input for the analog circuit |
| 6 | EN | Enable pin, active high |

## Functional Block Diagram



Figure 3. Functional Block Diagram of AUR9718B

## Ordering Information



| Package | Temperature <br> Range | Part Number | Marking ID | Packing Type |
| :---: | :---: | :--- | :--- | :---: |
| DFN-3 $\times 3-6$ | -40 to $80^{\circ} \mathrm{C}$ | AUR9718BGD | 9718 B | Tape \& Reel |

BCD Semiconductor's Pb -free products, as designated with " G " in the part number, are RoHS compliant and green.

## Absolute Maximum Ratings (Note 1)

| Parameter | Symbol | Value | Unit |
| :--- | :---: | :---: | :---: |
| Supply Input Voltage ( pin VIN_SW) | $\mathrm{V}_{\mathrm{IN} \text { _SW }}$ | 0 to 6.5 | V |
| Supply Input Voltage ( pin VIN_A) | $\mathrm{V}_{\text {IN_A }}$ | 0 to 6.5 | V |
| SW Pin Switch Voltage | $\mathrm{V}_{\mathrm{SW}}$ | -0.3 to $\mathrm{V}_{\text {IN_SW }}+0.3$ | V |
| Enable Voltage | $\mathrm{V}_{\mathrm{EN}}$ | -0.3 to $\mathrm{V}_{\text {IN_A }}+0.3$ | V |
| SW Pin Switch Current | $\mathrm{I}_{\mathrm{SW}}$ | 3.5 | A |
| Power Dissipation (On PCB, $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ ) | $\mathrm{P}_{\mathrm{D}}$ | 2.49 | W |
| Thermal Resistance (Junction to Ambient, Simulation) | $\theta_{\mathrm{JA}}$ | 40.11 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Operating Junction Temperature | $\mathrm{T}_{\mathrm{J}}$ | 150 | ${ }^{\circ} \mathrm{C}$ |
| Operating Temperature | $\mathrm{T}_{\mathrm{OP}}$ | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature | $\mathrm{T}_{\mathrm{STG}}$ | -55 to 150 | ${ }^{\circ} \mathrm{C}$ |
| ESD (Human Body Model) | $\mathrm{V}_{\mathrm{HBM}}$ | 2000 | $\mathrm{~V}^{\mathrm{V}}$ |
| ESD (Machine Model) | $\mathrm{V}_{\mathrm{MM}}$ | 200 | $\mathrm{~V}^{\mathrm{V}}$ |

Note 1: Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "Recommended Operating Conditions" is not implied. Exposure to "Absolute Maximum Ratings" for extended periods may affect device reliability.

## Recommended Operating Conditions

| Parameter | Symbol | Min | Max | Unit |
| :--- | :---: | :---: | :---: | :---: |
| Supply Input Voltage | $\mathrm{V}_{\mathrm{IN}}$ | 2.7 | 5.5 | V |
| Junction Temperature Range | $\mathrm{T}_{\mathrm{J}}$ | -40 | 125 | ${ }^{\circ} \mathrm{C}$ |
| Ambient Temperature Range | $\mathrm{T}_{\mathrm{A}}$ | -40 | 80 | ${ }^{\circ} \mathrm{C}$ |

## Electrical Characteristics

$\mathrm{V}_{\text {IN_SW }}=\mathrm{V}_{\text {IN_A }}=\mathrm{V}_{\mathrm{EN}}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=1.2 \mathrm{~V}, \mathrm{~V}_{\mathrm{FB}}=0.8 \mathrm{~V}, \mathrm{~L}=3.3 \mu \mathrm{H}, \mathrm{C}_{\text {IN }}=4.7 \mu \mathrm{~F}, \mathrm{C}_{\text {OUT }}=22 \mu \mathrm{~F}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise specified.

| Parameter | Symbol | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input Voltage Range | $\mathrm{V}_{\text {IN }}$ |  | 2.7 |  | 5.5 | V |
| Shutdown Current | $\mathrm{I}_{\text {OFF }}$ | $\mathrm{V}_{\mathrm{EN}}=0 \mathrm{~V}$ |  |  | 1 | $\mu \mathrm{A}$ |
| Active Current | $\mathrm{I}_{\mathrm{ON}}$ | $\mathrm{V}_{\mathrm{FB}}=0.95 \mathrm{~V}$ |  | 310 |  | $\mu \mathrm{A}$ |
| Regulated Feedback Voltage | $\mathrm{V}_{\text {FB }}$ | For Adjustable Output Voltage | 0.784 | 0.8 | 0.816 | V |
| Regulated Output Voltage Accuracy | $\Delta \mathrm{V}_{\text {OUT }} / \mathrm{V}_{\text {OUT }}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=2.7 \mathrm{~V} \text { to } 5.5 \mathrm{~V}, \mathrm{I}_{\mathrm{OUT}}=10 \mathrm{~mA} \\ & \text { to } 2.5 \mathrm{~A} \end{aligned}$ | -3 |  | 3 | \% |
| Peak Inductor Current | $\mathrm{I}_{\mathrm{PK}}$ |  | 3.0 | 3.5 |  | A |
| Oscillator Frequency | $\mathrm{f}_{\text {OSC }}$ |  | 1.2 | 1.5 | 1.8 | MHz |
| PMOSFET R ${ }_{\text {ON }}$ | $\mathrm{R}_{\mathrm{ON}(\mathrm{P})}$ | $\mathrm{I}_{\mathrm{SW}}=0.75 \mathrm{~A}$ |  | 100 |  | $\mathrm{m} \Omega$ |
| NMOSFET R ${ }_{\text {ON }}$ | $\mathrm{R}_{\mathrm{ON}(\mathrm{N})}$ | $\mathrm{I}_{\mathrm{SW}}=0.75 \mathrm{~A}$ |  | 100 |  | $\mathrm{m} \Omega$ |
| EN High-level Input Voltage | $\mathrm{V}_{\text {EN_H }}$ |  | 1.5 |  |  | V |
| EN Low-level Input Voltage | $\mathrm{V}_{\text {EN_L }}$ |  |  |  | 0.4 | V |
| EN Input Current | $\mathrm{I}_{\mathrm{EN}}$ |  |  |  | 1 | $\mu \mathrm{A}$ |
| Soft-start time | $\mathrm{t}_{\text {SS }}$ |  |  | 400 |  | $\mu \mathrm{S}$ |
| $\begin{aligned} & \hline \begin{array}{l} \text { Maximum } \\ \text { Cycle } \end{array} \\ & \hline \end{aligned}$ | $\mathrm{D}_{\text {MAX }}$ |  | 100 |  |  | \% |
| Under Voltage Lock Out | $\mathrm{V}_{\text {UVLO }}$ | Rising |  | 2.4 |  | V |
|  |  | Falling |  | 2.3 |  |  |
| Hysteresis |  | Hysteresis |  | 0.1 |  | V |
| OVP Threshold | $\mathrm{V}_{\text {OVP }}$ |  | 5.8 | 5.9 | 6.0 | V |
| Hysteresis on OVP |  |  | 300 | 400 | 500 | mV |
| Thermal Shutdown | $\mathrm{T}_{\text {SD }}$ | Hysteresis $=30^{\circ} \mathrm{C}$ |  | 150 |  | ${ }^{\circ} \mathrm{C}$ |

## Typical Performance Characteristics



Figure 4. Efficiency vs. Output Current


Figure 6. Efficiency vs. Output Current


Figure 5. Efficiency vs. Output Current


Figure 7. 3.3V Load Regulation

## Typical Performance Characteristics (Continued)



Figure 8. 1.2V Load Regulation


Figure 10. 3.3V Line Regulation


Figure 9. 1.0V Load Regulation


Figure 11. 1.2V Line Regulation

## Typical Performance Characteristics (Continued)



Figure 12. 1.0V Line Regulation


Figure 14. Reference Voltage vs. Output Current


Figure 13. EN Threshold vs. Input Voltage


Figure 15. Temperature vs. Output Current

## Typical Performance Characteristics (Continued)



Figure 16. $\mathrm{V}_{\text {out }}$ Ripple
$\left(\mathrm{V}_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}\right.$, lout $=500 \mathrm{~mA}$ )
Figure 17. $\mathrm{V}_{\text {out }}$ Ripple
$\left(\mathrm{V}_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}\right.$, I IOUT $=1000 \mathrm{~mA}$ )


Figure 18. Vout Ripple (lout=2500mA)


Time $200 \mu \mathrm{~s} / \mathrm{div}$

Figure 19. Dynamic Mode
(lout=500mA to 2500 mA )

## Typical Performance Characteristics (Continued)



Time $40 \mu \mathrm{~s} / \mathrm{div}$

Figure 20. Dynamic Mode (Rising)


Figure 22. EN Pin L to H
$\left(\mathrm{V}_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}\right.$, I lout $\left.=100 \mathrm{~mA}\right)$


Time $40 \mu \mathrm{~s} / \mathrm{div}$

Figure 21. Dynamic Mode (Falling)


Figure 23. EN Pin L to H
$\left(V_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}\right.$, Iout $=1000 \mathrm{~mA}$ )

## Typical Performance Characteristics (Continued)



Time 200 $2 \mathrm{~s} / \mathrm{div}$

Figure 24. EN Pin H to L
$\left(\mathrm{V}_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}\right.$, Iout $\left.=1 \mathrm{~A}\right)$


Figure 25. Soft Start Function ( $\mathrm{V}_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}$, I IOUT $=0 \mathrm{~A}$ )


Time $100 \mu \mathrm{~s} / \mathrm{div}$

Figure 26. Soft Start Function
( $\mathrm{V}_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}$, I IOUT $=1 \mathrm{~A}$ )
Figure 27. OTP Function

## Typical Performance Characteristics (Continued)



Figure 28. OVP Function
( $\mathrm{V}_{\mathrm{IN}}=5 \mathrm{~V}$ to 6 V )

Figure 29. Leave OVP Function
( $\mathrm{V}_{\mathrm{IN}}=6 \mathrm{~V}$ to 5 V )

## Application Information

The basic AUR9718B application circuit is shown in Figure 34.

## 1. Inductor Selection

For most applications, the value of inductor is chosen based on the required ripple current with the range of $1.0 \mu \mathrm{H}$ to $6.8 \mu \mathrm{H}$.

$$
\Delta I_{L}=\frac{1}{f \times L} V_{\text {OUT }}\left(1-\frac{V_{\text {OUT }}}{V_{I N}}\right)
$$

The largest ripple current occurs at the highest input voltage. Having a small ripple current reduces the ESR loss in the output capacitor and improves the efficiency. The highest efficiency is realized at low operating frequency with small ripple current. However, larger value inductors will be required. A reasonable starting point for ripple current setting is $\triangle \mathrm{I}_{\mathrm{L}}=40 \% \mathrm{I}_{\mathrm{MAX}}$. For a maximum ripple current stays below a specified value, the inductor should be chosen according to the following equation:

$$
L=\left[\frac{V_{\text {OUT }}}{f \times \Delta I_{L}(M A X)}\right]\left[1-\frac{V_{\text {OUT }}}{V_{I N}(M A X)}\right]
$$

The DC current rating of the inductor should be at least equal to the maximum output current plus half the highest ripple current to prevent inductor core saturation. For better efficiency, a lower DC-resistance inductor should be selected.

## 2. Capacitor Selection

The input capacitance, $\mathrm{C}_{\mathrm{IN}}$, is needed to filter the trapezoidal current at the source of the top MOSFET. To prevent large ripple voltage, a low ESR input capacitor sized for the maximum RMS current must be used. The maximum RMS capacitor current is given by:

$$
I_{\text {RUS }}=I_{\text {OMAX }} \times \frac{\left[V_{\text {OUT }}\left(V_{\text {IN }}-V_{\text {OUT }}\right)\right]^{\frac{1}{2}}}{V_{I N}}
$$

It indicates a maximum value at $\mathrm{V}_{\text {IN }}=2 \mathrm{~V}_{\text {OUT }}$, where $\mathrm{I}_{\mathrm{RMS}}=\mathrm{I}_{\mathrm{OUT}} / 2$. This simple worse-case condition is commonly used for design because even significant
deviations do not much relieve. The selection of Cout is determined by the Effective Series Resistance (ESR) that is required to minimize output voltage ripple and load step transients, as well as the amount of bulk capacitor that is necessary to ensure that the control loop is stable. The output ripple, $\triangle \mathrm{V}_{\text {OUT }}$, is determined by:

$$
\Delta V_{\text {OUT }} \leq \Delta I_{L}\left[E S R+\frac{1}{8 \times f \times C_{\text {OUT }}}\right]
$$

The output ripple is the highest at the maximum input voltage since $\triangle I_{L}$ increases with input voltage.

## 3. Load Transient

A switching regulator typically takes several cycles to respond to the load current step. When a load step occurs, $\mathrm{V}_{\text {OUT }}$ immediately shifts by an amount equal to $\triangle \mathrm{I}_{\mathrm{LOAD}} \times \mathrm{ESR}$, where ESR is the effective series resistance of output capacitor. $\triangle \mathrm{I}_{\text {LOAD }}$ also begins to charge or discharge $\mathrm{C}_{\text {OUt }}$ generating a feedback error signal used by the regulator to return $\mathrm{V}_{\text {OUT }}$ to its steady-state value. During the recovery time, $\mathrm{V}_{\text {Out }}$ can be monitored for overshoot or ringing that would indicate a stability problem.

## 4. Output Voltage Setting

The output voltage of AUR9718B can be adjusted by a resistive divider according to the following formula:
$V_{\text {OUT }}=V_{\text {REF }} \times\left(1+\frac{R_{1}}{R_{2}}\right)=0.8 V \times\left(1+\frac{R_{1}}{R_{2}}\right)$
The resistive divider senses the fraction of the output voltage as shown in Figure 30.


Figure 30. Setting the Output Voltage

## Application Information (Continued)

## 5. Short Circuit Protection

When AUR9718B output node is shorted to GND, as $\mathrm{V}_{\mathrm{FB}}$ drops under 0.4 V , the chip will enter soft-start to protect itself; when short circuit is removed, and $\mathrm{V}_{\mathrm{FB}}$ rises over 0.4 V , the chip will enter normal operation again. If AUR9718B reaches OCP threshold while short circuit, it will enter soft-start cycle and last until the current drops under OCP threshold.

## 6. Efficiency Considerations

The efficiency of switching regulator is equal to the output power divided by the input power times $100 \%$. It is usually useful to analyze the individual losses to determine what is limiting efficiency and which change could produce the largest improvement. Efficiency can be expressed as:

Efficiency=100\%-L1-L2-.....
Where L1, L2, etc. are the individual losses as a percentage of input power.

Although all dissipative elements in the regulator produce losses, two major sources usually account for most of the power losses: $\mathrm{V}_{\text {IN }}$ quiescent current and $I^{2} \mathrm{R}$ losses. The $\mathrm{V}_{\text {IN }}$ quiescent current loss dominates the efficiency loss at very light load currents and the $\mathrm{I}^{2} \mathrm{R}$ loss dominates the efficiency loss at medium to heavy load currents.
6.1 The $\mathrm{V}_{\text {IN }}$ quiescent current loss comprises two parts: the DC bias current as given in the electrical characteristics and the internal MOSFET switch gate charge currents. The gate charge current results from switching the gate capacitance of the internal power MOSFET switches. Each cycle the gate is switched from high to low, then to high again, and the packet of charge, dQ moves from $\mathrm{V}_{\mathrm{IN}}$ to ground. The resulting $\mathrm{dQ} / \mathrm{dt}$ is the current out of $\mathrm{V}_{\text {IN }}$ that is typically larger than the internal DC bias current. In continuous mode,
$I_{G A T E}=f \times\left(Q_{P}+Q_{N}\right)$
Where $\mathrm{Q}_{\mathrm{P}}$ and $\mathrm{Q}_{\mathrm{N}}$ are the gate charge of power PMOSFET and NMOSFET switches. Both the DC bias current and gate charge losses are proportional to
the $\mathrm{V}_{\text {IN }}$ and this effect will be more serious at higher input voltages.
6.2 $I^{2} R$ losses are calculated from internal switch resistance, $\mathrm{R}_{\text {SW }}$ and external inductor resistance $\mathrm{R}_{\mathrm{L}}$. In continuous mode, the average output current flowing through the inductor is chopped between power PMOSFET switch and NMOSFET switch. Then, the series resistance looking into the SW pin is a function of both PMOSFET $R_{\text {DS(ON)P }}$ and NMOSFET $R_{\text {DS(ON)N }}$ resistance and the duty cycle (D):
$R_{S W}=R_{D S(\text { ON }) P} \times D+R_{D S(\text { ON }) N} \times(1-D)$

Therefore, to obtain the $I^{2} R$ losses, simply add $R_{\text {sw }}$ to $\mathrm{R}_{\mathrm{L}}$ and multiply the result by the square of the average output current.

Other losses including $\mathrm{C}_{\mathrm{IN}}$ and $\mathrm{C}_{\text {OUt }}$ ESR dissipative losses and inductor core losses generally account for less than $2 \%$ of total additional loss.

## 7. Thermal Characteristics

In most applications, the part does not dissipate much heat due to its high efficiency. However, in some conditions when the part is operating in high ambient temperature with high $\mathrm{R}_{\mathrm{DS}(\mathrm{ON})}$ resistance and high duty cycles, such as in LDO mode, the heat dissipated may exceed the maximum junction temperature. To avoid the part from exceeding maximum junction temperature, the user should do some thermal analysis. The maximum power dissipation depends on the layout of PCB , the thermal resistance of IC package, the rate of surrounding airflow and the temperature difference between junction and ambient.

## 8. Input Over Voltage Protection

When the input voltage of AUR9718B exceeds V ${ }_{\text {ovp }}$, the IC would enter the mode of Input Over Voltage Protection. It will be shutdown and there will be no output voltage. As the input voltage goes down below 5.5 V , the IC would leave input OVP mode and the output voltage will be recovered.

## 9. PC Board Layout Considerations

When laying out the printed circuit board, the following checklist should be used to optimize the

## Application Information (Continued)

performance of AUR9718B.

1. The power traces, including the GND trace, the SW trace and the VIN trace should be kept direct, short and wide.
2. Put the input capacitor as close as possible to the VIN_SW, VIN_A and GND pins.
3. The FB pin should be connected directly to the feedback resistor divider.
4. Keep the switching node SW away from the sensitive FB pin and the node should be kept small area.

The following is an example of 2-layer PCB layout as shown in Figure 32 and Figure 33 for reference.


Figure 31. The Evaluation Board Schematic


Figure 32. Top Layer for Demo Board


Figure 33. Bottom Layer for Demo Board

## Typical Application



Note 2: $V_{\text {OUT }}=V_{F B} \times\left(1+\frac{R_{1}}{R_{2}}\right)$

Figure 34. Typical Application Circuit of AUR9718B (Note 2)

Table 1. Component Guide

| $\mathbf{V}_{\text {OUT }} \mathbf{( V )}$ | $\mathbf{R 1}(\mathbf{k} \boldsymbol{\Omega})$ | $\mathbf{R 2} \mathbf{( k \Omega} \mathbf{)}$ | $\mathbf{L}(\mu \mathbf{H})$ |
| :---: | :---: | :---: | :---: |
| 3.3 | 31.25 | 10 | 3.3 |
| 2.5 | 21.5 | 10 | 3.3 |
| 1.8 | 12.5 | 10 | 3.3 |
| 1.2 | 5 | 10 | 3.3 |
| 1.0 | 3 | 10 | 3.3 |

## Mechanical Dimensions

DFN-3×3-6
Unit: mm(inch)


Pin 1 options

## BCH A

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