 COS-2/24V: 8595188155441

| Technical parameters | COS-2 |
| :---: | :---: |
| Supply |  |
| Supply terminals: | A1-A2 |
| Voltage range: | AC 230 V, AC 110 V, AC 400 V or AC/DC 24 V (AC $50 / 60 \mathrm{~Hz}$ ) |
| Burden max.: | 2.5 W/5 VA (AC $110 \mathrm{~V}, \mathrm{AC} 230 \mathrm{~V}, \mathrm{AC} 400 \mathrm{~V}$ ), 1.4 W/2 VA (AC/DC 24 V ) |
| Max. dissipated power <br> (Un + terminals): | 4 W |
| Operating range: | -15\%; +10 \% |
| Measuring |  |
| Voltage set: | $3 \times 400 \mathrm{~V} / 230 \mathrm{~V}(50 / 60 \mathrm{~Hz})$ |
| Terminals: | L1, L2, L3, B1 |
| Upper level cos- $\varphi$ : | adjustable 0.1-0.99 |
| Bottom level cos- $\varphi$ : | adjustable 0.1-0.99 |
| Max. permanent voltage: | (input L1, L2, L3) AC 3 x 460 V |
| Current range: | 0.1-16A |
| Current overloading: | 20 A (<3 sec.) |
| Hysteresis: | adjustable 5 \% or 10 \% |
| Time delay t1: | adjustable $0.1-10 \mathrm{~s}$ |
| Time delay t2: | adjustable 0.1-10 s |

## Accuracy

| Accuracy setting (mechanical): | 5 \% |
| :---: | :---: |
| Accuracy of repetition: | $<1 \%$ |
| Temperature dependance: | $<0.1 \% /{ }^{\circ} \mathrm{C}$ ( ${ }^{\circ} \mathrm{F}$ ) |
| Limit values tolerance: | 5 \% |
| Output |  |
| Number of contacts: | 2x changeover/SPDT (AgNi/Silver Alloy) |
| Current rating: | $16 \mathrm{~A} / \mathrm{AC} 1$ |
| Breaking capacity: | 4000 VA/AC1, 384 W/DC |
| Inrush current: | $20 \mathrm{~A} /<3 \mathrm{~s}$ |
| Switching voltage: | 250 V AC/ 24 V DC |
| Output indication: | yellow LED |
| Mechanical life: | 30.000.000 operations |
| Electrical life (AC1): | 70.000 operations |
| Other information |  |
| Operating temperature: | $-20^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}\left(-4{ }^{\circ} \mathrm{F}\right.$ to $\left.131{ }^{\circ} \mathrm{F}\right)$ |
| Storage temperature: | $-30^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}\left(-22^{\circ} \mathrm{F}\right.$ to $\left.158{ }^{\circ} \mathrm{F}\right)$ |
| Dielectrical strength: | 4 kV (supply - output) |
| Operating position: | any |
| Mounting: | DIN rail EN 60715 |
| Protection degree: | IP40 from front panel/IP20 terminals |
| Overvoltage category: | III. |
| Pollution degree: | 2 |

max. $1 \times 2.5$, max. $2 \times 1.5 /$
with sleeve max. $1 \times 1.5$ (AWG 12)
$90 \times 52 \times 65 \mathrm{~mm}\left(3.5^{\prime \prime} \times 2^{\prime \prime} \times 2.6^{\prime}\right)$
Weight:
Standards:


COS-2

Max. cable size ( $\mathrm{mm}^{2}$ ):

Dimensions:

- Relay monitors phase shift between current and voltage in 3-phase or 1 -phase networks - evaluates $\operatorname{COS} \varphi$ (replacement COS-1).
- The relay is designed to monitor overload/relieve the motors.
- Relay is designed for $3 \times 400 / 230 \mathrm{~V}$ circuits.
- Galvanically isolated power supply AC 230 V, AC 110 V, AC 400 V or AC/DC 24 V .
- Adjustable upper and lower level $\operatorname{COS} \varphi$.
- Possibility to extend the current range using a current transformer.
- Two output relays (for each level independent).
- Adjustable delay eliminating engine start-up.


## Description

| Supply voltage terminals |
| :--- |
| (A1-A2) |


| Upper level $\cos \varphi$ |
| :--- |
| max/timing t 2 |


| OK/timing |
| :--- |
| status t 1 |


| COS Lower Level $\mathrm{C} \varphi$ |
| :--- |
| min/timing t2 |

## Description and importance of DIP switches



## Connection

Connection with 3-phase connection

1-phase connection current transformer


## Symbol



## Function



After powering on, the device sets the delay time t1 and yellow LED flashes. Both relays are switched on. The delay serves to eliminate a faulty state when starting the motor. After the time delay t 1 begins monitoring $\operatorname{COS} \varphi$ only.

If the $\operatorname{COS} \varphi$ is in the band between the upper and lower limits set, both relays are switched on and the yellow LED is on.
If the $\operatorname{COS} \varphi$ is outside the set limits ( $>\operatorname{COS} \varphi \max$ or $<\operatorname{COS} \varphi \min$ ), an error condition occurs - the time t 2 is delayed while the red LED corresponding to the $\operatorname{COS} \varphi$ blinks at the same time. After the time delay t2 red LED lights and the corresponding relay remains off.

When the $\operatorname{COS} \varphi$ returns to set limits, the time t1 is delayed and the yellow LED flashes at the same time as the corresponding red LED. After the time delay stops blinking yellow LED, the corresponding red LED turns off and the relay switches on.

At low wattage ( $<100 \mathrm{~mA}$ ) or with a power failure, an error is reported by the simultaneous blinking of both red LEDs. After resuming the voltage or the current being watched, the relay returns to the normal state where the $\operatorname{COS} \varphi$ value is monitored.

When the memory is turned off (DIP switch 2 OFF) and the allowable reset (DIP switch 1 ON), the pressing state is reached after the power is turned on, i.e. flashing yellow LED, both relays are switched on, with time delay t1.
When the memory (DIP switch 2 ON) is in an error state (high or low value for $\cos \varphi$ ) it should be reset (by pressing the RESET button).

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