

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

## **Key Features**

- 33.00x13.46x 8.25 mm (1.30 x 0.530 x 0.335in.)
- 10A output current
- 8.3-16 V input voltage range
- Output voltages from 0.75V up to 5.5V
- More than 5 million hours MTBF

## **General Characteristics**

- Operating temperature: -45°C to 115°C
- Output short-circuit protection
- Under voltage protection
- Remote sense
- Remote control
- Highly automated manufacturing ensures quality
- ISO 9001/14001 certified supplier

## **Technical Specification**

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB



Safety Approvals



## **Design for Environment**



Meets requirements in hightemperature lead-free soldering processes.

## Contents

General Information	
Safety Specification	
Absolute Maximum Ratings	
Product Program	Ordering No.
1.0-5.0 V. 10 Å / 50W	PMC 8518T S
1.0 V, 10 A / 10W Electrical Specification	5
1.2 V, 10 A / 12W Electrical Specification	8
1.5 V, 10 A / 15W Electrical Specification	
1.8 V, 10 A / 18W Electrical Specification	14
2.5 V, 10 A / 25W Electrical Specification	
3.3 V, 10 A / 33W Electrical Specification	
5.0 V, 10 A / 50W Electrical Specification	
EMC Specification	
Operating Information	
Thermal Consideration	
Connections	
Mechanical Information	
Soldering Information	
Delivery Information	
Product Qualification Specification	

PMC 8518 series	
POL regulator, Input 12 V, Output 10 A/50 W	

## **General Information**

## **Ordering Information**

See Contents for individual product ordering numbers.

Option	Suffix	Ordering No.
Negative Remote Control Logic	Ν	PMC 8518T SN

## Reliability

The Mean Time Between Failure (MTBF) is calculated at full output power and an operating ambient temperature ( $T_A$ ) of +40°C, which is a typical condition in Information and Communication Technology (ICT) equipment. Different methods could be used to calculate the predicted MTBF and failure rate which may give different results. Ericsson Power Modules currently uses Telcordia SR332.

Predicted MTBF for the series is:

- 5 million hours according to Telcordia SR332, issue 1, Black box technique.

Telcordia SR332 is a commonly used standard method intended for reliability calculations in ICT equipment. The parts count procedure used in this method was originally modelled on the methods from MIL-HDBK-217F, Reliability Predictions of Electronic Equipment. It assumes that no reliability data is available on the actual units and devices for which the predictions are to be made, i.e. all predictions are based on generic reliability parameters.

## **Compatibility with RoHS requirements**

The products are compatible with the relevant clauses and requirements of the RoHS directive 2002/95/EC and have a maximum concentration value of 0.1% by weight in homogeneous materials for lead, mercury, hexavalent chromium, PBB and PBDE and of 0.01% by weight in homogeneous materials for cadmium.

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

Exemptions in the RoHS directive utilized in Ericsson Power Modules products include:

- Lead in high melting temperature type solder (used to solder the die in semiconductor packages)
- Lead in glass of electronics components and in electronic ceramic parts (e.g. fill material in chip resistors)
- Lead as an alloying element in copper alloy containing up to 4% lead by weight (used in connection pins made of Brass)

## **Quality Statement**

The products are designed and manufactured in an industrial environment where quality systems and methods like ISO 9000,  $6\sigma$  (sigma), and SPC are intensively in use to boost the continuous improvements strategy. Infant mortality or early failures in the products are screened out and they are subjected to an ATE-based final test. Conservative design rules, design reviews and product qualifications, plus the high competence of an engaged work force, contribute to the high quality of our products.

## Warranty

Warranty period and conditions are defined in Ericsson Power Modules General Terms and Conditions of Sale.

## Limitation of Liability

Ericsson Power Modules does not make any other warranties, expressed or implied including any warranty of merchantability or fitness for a particular purpose (including, but not limited to, use in life support applications, where malfunctions of product can cause injury to a person's health or life).

## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

## **Safety Specification**

## **General information**

Ericsson Power Modules DC/DC converters and DC/DC regulators are designed in accordance with safety standards IEC/EN/UL60950, *Safety of Information Technology Equipment*.

IEC/EN/UL60950 contains requirements to prevent injury or damage due to the following hazards:

- Electrical shock
- Energy hazards
- Fire
- Mechanical and heat hazards
- Radiation hazards
- Chemical hazards

On-board DC-DC converters are defined as component power supplies. As components they cannot fully comply with the provisions of any Safety requirements without "Conditions of Acceptability". It is the responsibility of the installer to ensure that the final product housing these components complies with the requirements of all applicable Safety standards and Directives for the final product.

Component power supplies for general use should comply with the requirements in IEC60950, EN60950 and UL60950 *"Safety of information technology equipment"*.

There are other more product related standards, e.g. IEEE802.3af "Ethernet LAN/MAN Data terminal equipment power", and ETS300132-2 "Power supply interface at the input to telecommunications equipment; part 2: DC", but all of these standards are based on IEC/EN/UL60950 with regards to safety.

Ericsson Power Modules DC/DC converters and DC/DC regulators are UL60950 recognized and certified in accordance with EN60950.

The flammability rating for all construction parts of the products meets requirements for V-0 class material according to IEC 60695-11-10.

The products should be installed in the end-use equipment, in accordance with the requirements of the ultimate application. Normally the output of the DC/DC converter is considered as SELV (Safety Extra Low Voltage) and the input source must be isolated by minimum Double or Reinforced Insulation from the primary circuit (AC mains) in accordance with IEC/EN/UL60950.

## Isolated DC/DC converters

It is recommended that a slow blow fuse with a rating twice the maximum input current per selected product be used at the input of each DC/DC converter. If an input filter is used in the circuit the fuse should be placed in front of the input filter.

Technical Specification EN/LZT 146 063 R3A Aug 2007

© Ericsson Power Modules AB

In the rare event of a component problem in the input filter or in the DC/DC converter that imposes a short circuit on the input source, this fuse will provide the following functions:

- Isolate the faulty DC/DC converter from the input power source so as not to affect the operation of other parts of the system.
- Protect the distribution wiring from excessive current and power loss thus preventing hazardous overheating.

The galvanic isolation is verified in an electric strength test. The test voltage ( $V_{iso}$ ) between input and output is 1500 Vdc or 2250 Vdc for 60 seconds (refer to product specification).

Leakage current is less than 1 µA at nominal input voltage.

## 24 V DC systems

The input voltage to the DC/DC converter is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.

## 48 and 60 V DC systems

If the input voltage to the DC/DC converter is 75 Vdc or less, then the output remains SELV (Safety Extra Low Voltage) under normal and abnormal operating conditions.

Single fault testing in the input power supply circuit should be performed with the DC/DC converter connected to demonstrate that the input voltage does not exceed 75 Vdc.

If the input power source circuit is a DC power system, the source may be treated as a TNV2 circuit and testing has demonstrated compliance with SELV limits and isolation requirements equivalent to Basic Insulation in accordance with IEC/EN/UL60950.

## Non-isolated DC/DC regulators

The input voltage to the DC/DC regulator is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.

	Technical Specification	4
PMC 8518 series	EN/LZT 146 063 R3A Aug 2007	

POL regulator, Input 12 V, Output 10 A/50 W

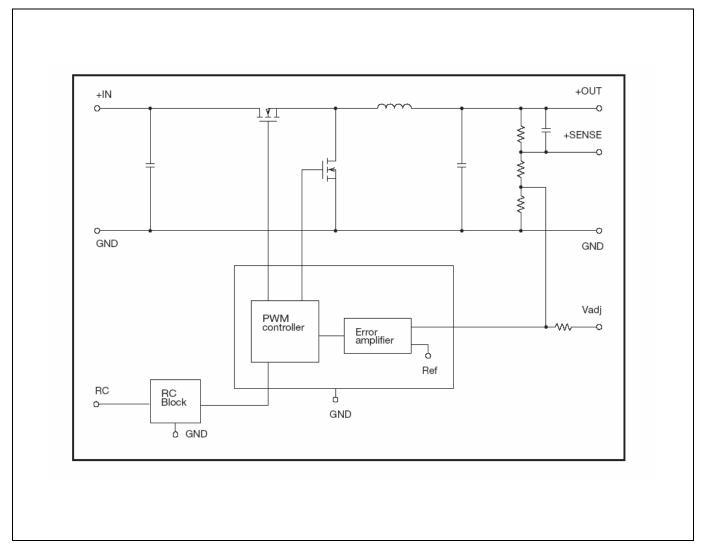
© Ericsson Power Modules AB

## Absolute Maximum Ratings

Chara	Characteristics			typ	max	Unit
T <sub>ref</sub>	T <sub>ref</sub> Operating Temperature (see Thermal Consideration section)		-40		85	°C
Ts	S Storage temperature		-40		125	°C
VI	Input voltage		8.3	12.0	16	V
v	Remote Control pin voltage	Positive logic option	1.7		16	V
V <sub>RC</sub> (see Op	(see Operating Information section)	Negative logic option	-0.3		0.3	V
$V_{\text{adj}}$	Adjust pin voltage (see Operating Information section)		N/A		N/A	V

Stress in excess of Absolute Maximum Ratings may cause permanent damage. Absolute Maximum Ratings, sometimes referred to as no destruction limits, are normally tested with one parameter at a time exceeding the limits of Output data or Electrical Characteristics. If exposed to stress above these limits, function and performance may degrade in an unspecified manner.

## Fundamental Circuit Diagram



## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

## 1.0 V/10 A Electrical Specification

 $\begin{array}{l} T_{ref} = -40 \ to \ +85^{\circ}C, \ V_{I} = 8.3 \ to \ 16 \ V, \ R_{adj} = 41.42 \ k\Omega, \ unless \ otherwise \ specified \ under \ Conditions. \\ Typical \ values \ given \ at: \ T_{ref} = +25^{\circ}C, \ V_{I} = 12 \ V, \ max \ I_{0} \ , \ unless \ otherwise \ specified \ under \ Conditions. \\ Additional \ C_{in} = 4 \times 4.7 \ \mu F \ and \ C_{out} = 2 \times 150 \ \mu F. \ See \ Operating \ Information \ section \ for \ selection \ of \ capacitor \ types. \\ Connect \ the \ sense \ pin, \ where \ available, \ to \ the \ output \ pin. \end{array}$ 

Characteristics		Conditions	min	typ	max	Unit
VI	Input voltage range		8.3		16	V
$V_{\text{loff}}$	Turn-off input voltage	Decreasing input voltage		7.8		V
Vlon	Turn-on input voltage	Increasing input voltage		8.0		V
Cı	Internal input capacitance			30		μF
Po	Output power		0		10	W
n	Efficiency	50 % of max I <sub>o</sub>		83.5		%
II.		max I <sub>0</sub>		84.2		70
Pd	Power Dissipation	max I <sub>0</sub>		1.9	2.2	W
Pli	Input idling power	I <sub>O</sub> = 0 A, V <sub>I</sub> = 12.0 V		0.5		W
$P_{RC}$	Input standby power	V <sub>I</sub> = 12.0 V (turned off with RC)		35		mW
ls	Static Input current	V <sub>I</sub> = 12.0 V, max I <sub>0</sub>		1.0		А
f <sub>s</sub>	Switching frequency	0-100 % of max I <sub>0</sub>	260	300	340	kHz

V <sub>Oi</sub>	Output voltage initial setting and accuracy	$T_{ref} = +25^{\circ}C, V_{I} = 12.0 V, max I_{O}$	-2		+2	%V
	Output voltage tolerance band	10-100 % of max I <sub>0</sub>	-3		+3	%V
	Idling voltage	I <sub>0</sub> = 0 A	-2		+2	%V
Vo	Line regulation	max I <sub>o</sub>		2		mV
	Load regulation	$V_{I}$ = 12.0 V, 0-100 % of max $I_{O}$		10		mV
V <sub>tr</sub>	Load transient voltage deviation	V <sub>1</sub> = 12.0 V, Load step 25-75-25 %		±100		mV
t <sub>tr</sub>	Load transient recovery time	of max I <sub>o</sub> , di/dt = 5 A/µs		40		μs
tr	Ramp-up time (from 10–90 % of V <sub>Oi</sub> )	max Io		3		ms
t <sub>s</sub>	Start-up time (from V <sub>I</sub> connection to 90 % of V <sub>Oi</sub> )	up time		7		
+	V <sub>I</sub> shut-down fall time.	Max I <sub>o</sub>		1		ms
t <sub>f</sub>	(From V <sub>I</sub> off to 10 % of V <sub>O</sub> )	I <sub>0</sub> = 0 A		22		S
	RC start-up time	Max I <sub>o</sub>		7		ms
$t_{\text{RC}}t_{\text{Inh}}$	RC shut-down fall time	Max I <sub>o</sub>		1		ms
	(From RC off to 10 % of $V_{\rm O}$ )	I <sub>o</sub> = 0 A		24		S
lo	Output current		0		10	А
l <sub>lim</sub>	Current limit threshold	T <sub>ref</sub> < max T <sub>ref</sub>	20	23		А
l <sub>sc</sub>	Short circuit current	T <sub>ref</sub> = 25°C, See Operating Information section.		24	25	А
$V_{\text{Oac}}$	Output ripple & noise	See ripple & noise section, max $I_{\rm O}$		35	70	mVp-p

## PMC 8518T S

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

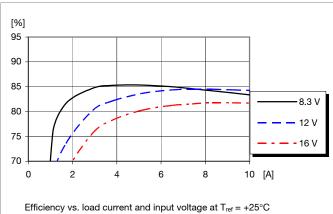
EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

**Technical Specification** 

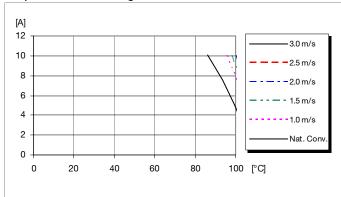
## © Ericsson Power Modules A

## 1.0 V/10 A Typical Characteristics

## Efficiency

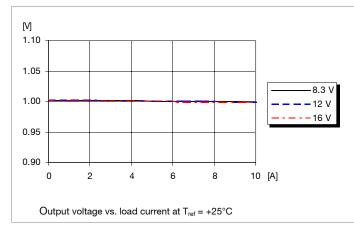


## **Output Current Derating**

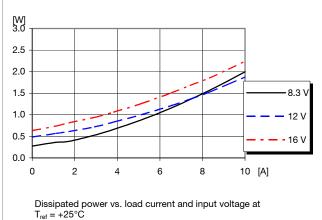


Available load current vs. ambient air temperature and airflow at  $V_{\rm I}$  = 12 V. See Thermal Consideration section.

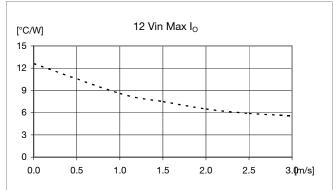
## **Output Characteristics**





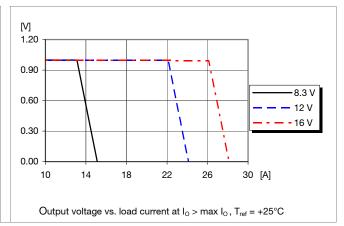


## **Thermal Resistance**



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section.





6

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

Technical Specification EN/LZT 146 063 R3A Aug 2007

© Ericsson Power Modules AB

## 1.0 V/10 A Typical Characteristics

# Star-up Stur-down Image: Construction of the start of the start

Trace: output voltage (20 mV/div.). Time scale: (2 μs/div.).

## Output Voltage Adjust (see operating information)

Output voltage ripple at:  $T_{ref} = +25^{\circ}C$ ,  $V_{I} = 12 V$ ,  $I_{O} = 10 A$  resistive load. //div.). Output voltage response to load current stepchange (2.5-7.5-2.5 A) at: Bottom trace: load current (10 A/div.). T<sub>ref</sub>=+25°C, V<sub>I</sub> = 12 V. Time scale: (0.1 ms/div.).

## PMC 8518T S

## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

## 1.2 V/10 A Electrical Specification

 $\begin{array}{l} T_{ref} = -40 \ to \ +85^{\circ}C, \ V_{I} = 8.3 \ to \ 16 \ V, \ R_{adj} = 22.46 \ k\Omega, \ unless \ otherwise \ specified \ under \ Conditions. \\ Typical \ values \ given \ at: \ T_{ref} = +25^{\circ}C, \ V_{I} = 12 \ V, \ max \ I_{0} \ , \ unless \ otherwise \ specified \ under \ Conditions. \\ Additional \ C_{in} = 4 \times 4.7 \ \mu F \ and \ C_{out} = 2 \times 150 \ \mu F. \ See \ Operating \ Information \ section \ for \ selection \ of \ capacitor \ types. \\ Connect \ the \ sense \ pin, \ where \ available, \ to \ the \ output \ pin. \end{array}$ 

Chara	cteristics	Conditions	min	typ	max	Unit
Vı	Input voltage range		8.3		16	V
$V_{\text{loff}}$	Turn-off input voltage	Decreasing input voltage		7.8		V
Vlon	Turn-on input voltage	Increasing input voltage		8.0		V
Cı	Internal input capacitance			30		μF
Po	Output power		0		12	W
_	Efficiency	50 % of max I <sub>0</sub>		85.6		%
II.	Efficiency	max I <sub>0</sub>		86.3		70
Pd	Power Dissipation	max I <sub>0</sub>		1.9	2.2	W
Pli	Input idling power	I <sub>O</sub> = 0 A, V <sub>I</sub> = 12.0 V		0.5		W
P <sub>RC</sub>	Input standby power	V <sub>I</sub> = 12.0 V (turned off with RC)		35		mW
ls	Static Input current	V <sub>I</sub> = 12.0 V, max I <sub>0</sub>		1.2		А
f <sub>s</sub>	Switching frequency	0-100 % of max I <sub>0</sub>	260	300	340	kHz

V <sub>Oi</sub>	Output voltage initial setting and accuracy	$T_{ref} = +25^{\circ}C, V_{I} = 12.0 V, max I_{O}$	-2		+2	%V
	Output voltage tolerance band	10-100 % of max I <sub>0</sub>	-3		+3	%V
V	Idling voltage	I <sub>0</sub> = 0 A	-2		+2	%V
Vo	Line regulation	max I <sub>o</sub>		2		mV
	Load regulation	$V_{I} = 12.0 \text{ V}, 0-100 \% \text{ of max } I_{O}$		10		mV
V <sub>tr</sub>	Load transient voltage deviation	V <sub>1</sub> = 12.0 V, Load step 25-75-25 %		±100		mV
t <sub>tr</sub>	Load transient recovery time	of max I <sub>o</sub> , di/dt = 5 A/µs		40		μs
t <sub>r</sub>	Ramp-up time (from 10–90 % of V <sub>Oi</sub> )	max Io		3		ms
ts	Start-up time (from V <sub>I</sub> connection to 90 % of V <sub>Oi</sub> )	tart-up time		7		
+	V <sub>I</sub> shut-down fall time.	Max I <sub>o</sub>		1		ms
t <sub>f</sub>	(From V <sub>I</sub> off to 10 % of V <sub>O</sub> )	I <sub>0</sub> = 0 A		21		s
	RC start-up time	Max I <sub>o</sub>		7		ms
$t_{\text{RC}}  t_{\text{Inh}}$	RC shut-down fall time	Max I <sub>0</sub>		1		ms
	(From RC off to 10 % of $V_{\rm O}$ )	I <sub>o</sub> = 0 A		21		S
lo	Output current		0		10	А
l <sub>lim</sub>	Current limit threshold	T <sub>ref</sub> < max T <sub>ref</sub>	19	22		А
I <sub>sc</sub>	Short circuit current	T <sub>ref</sub> = 25°C, See Operating Information section.		22	24	А
$V_{\text{Oac}}$	Output ripple & noise	See ripple & noise section, max $I_0$		35	70	mVp-p

## PMC 8518T S

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

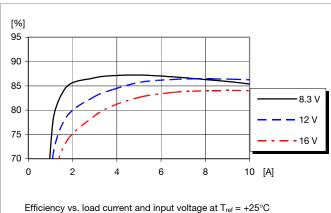
EN/LZT 146 063 R3A Aug 2007

**Technical Specification** 

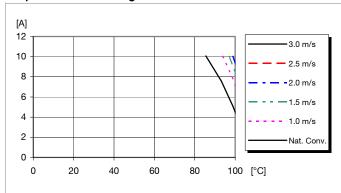
© Ericsson Power Modules AB

## 1.2 V/10 A Typical Characteristics

## Efficiency

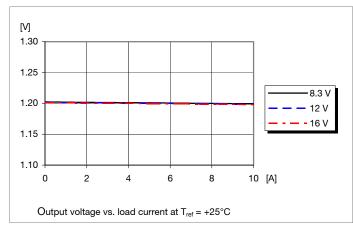


## **Output Current Derating**

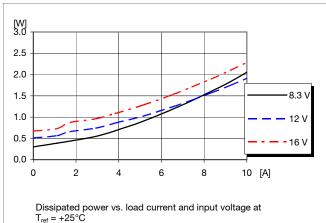


Available load current vs. ambient air temperature and airflow at V<sub>I</sub> = 12 V. See Thermal Consideration section.

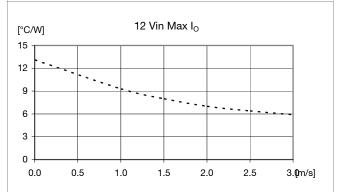
## **Output Characteristics**



## Power Dissipation

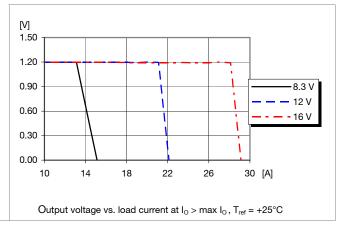






Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section.





9

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007

© Ericsson Power Modules AB

**Technical Specification** 

## 1.2 V/10 A Typical Characteristics

# Start-up Shut-down Start-up Shut-down Start-up Shut-down Start-up Shut-down Start-up Shut-down Start-up analysic by connecting Vati: Top trace-output voltage (10 Vidiv), ibm trace: input voltage (10 Vi

## Output Voltage Adjust (see operating information)

## PMC 8518T S

## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

## 1.5 V/10 A Electrical Specification

 $\begin{array}{l} T_{ref} = -40 \ to \ +85^{\circ}C, \ V_l = 8.3 \ to \ 16 \ V, \ R_{adj} = 13.05 \ k\Omega, \ unless \ otherwise \ specified \ under \ Conditions. \\ Typical \ values \ given \ at: \ T_{ref} = \ +25^{\circ}C, \ V_l = 12 \ V, \ max \ I_0, \ unless \ otherwise \ specified \ under \ Conditions. \\ Additional \ C_{in} = \ 4\times4.7 \ \mu F \ and \ C_{out} = \ 2\times150 \ \mu F. \ See \ Operating \ Information \ section \ for \ selection \ of \ capacitor \ types. \\ Connect \ the \ sense \ pin, \ where \ available, \ to \ the \ output \ pin. \end{array}$ 

Characteristics		Conditions	min	typ	max	Unit
VI	Input voltage range		8.3		16	V
V <sub>loff</sub>	Turn-off input voltage	Decreasing input voltage		7.8		V
V <sub>Ion</sub>	Turn-on input voltage	Increasing input voltage		8.0		V
Cı	Internal input capacitance			30		μF
Po	Output power		0		15	W
	Efficiency	50 % of max I <sub>0</sub>		87.7		%
II.		max I <sub>0</sub>		88.3		70
Pd	Power Dissipation	max I <sub>0</sub>		2.0	2.3	W
Pli	Input idling power	I <sub>O</sub> = 0 A, V <sub>I</sub> = 12.0 V		0.6		W
$P_{RC}$	Input standby power	V <sub>I</sub> = 12.0 V (turned off with RC)		35		mW
ls	Static Input current	V <sub>I</sub> = 12.0 V, max I <sub>0</sub>		1.4		А
f <sub>s</sub>	Switching frequency	0-100 % of max I <sub>0</sub>	260	300	340	kHz

V <sub>Oi</sub>	Output voltage initial setting and accuracy	$T_{ref} = +25^{\circ}C, V_{I} = 12.0 V, max I_{O}$	-2		+2	%V
	Output voltage tolerance band	10-100 % of max I <sub>0</sub>	-3		+3	%V
Vo	Idling voltage	I <sub>0</sub> = 0 A	-2		+2	%V
	Line regulation	max I <sub>o</sub>		2		mV
	Load regulation	$V_{I}$ = 12.0 V, 0-100 % of max $I_{O}$		10		mV
V <sub>tr</sub>	Load transient voltage deviation	V <sub>1</sub> = 12.0 V, Load step 25-75-25 %		±100		mV
t <sub>tr</sub>	Load transient recovery time	of max I <sub>o</sub> , di/dt = 5 A/µs		40		μs
t <sub>r</sub>	Ramp-up time (from 10–90 % of V <sub>Oi</sub> )	max Io		3		ms
ts	Start-up time (from V <sub>I</sub> connection to 90 % of V <sub>Oi</sub> )	tart-up time		7		
+	V <sub>I</sub> shut-down fall time.	Max I <sub>o</sub>		1		ms
t <sub>f</sub>	(From V <sub>I</sub> off to 10 % of V <sub>O</sub> )	I <sub>0</sub> = 0 A		20		S
	RC start-up time	Max I <sub>o</sub>		7		ms
$t_{\text{RC}}  t_{\text{Inh}}$	RC shut-down fall time	Max I <sub>o</sub>		1		ms
	(From RC off to 10 % of $V_{\rm O}$ )	I <sub>o</sub> = 0 A		20		S
lo	Output current		0		10	А
l <sub>lim</sub>	Current limit threshold	T <sub>ref</sub> < max T <sub>ref</sub>	13	19		А
l <sub>sc</sub>	Short circuit current	T <sub>ref</sub> = 25°C, See Operating Information section.		19	21	А
$V_{\text{Oac}}$	Output ripple & noise	See ripple & noise section, max $I_0$		35	70	mVp-p

# ERICSSON 🔰

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

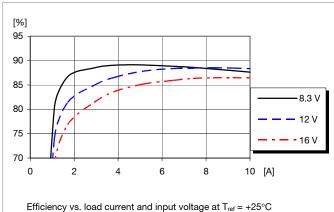
EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

**Technical Specification** 

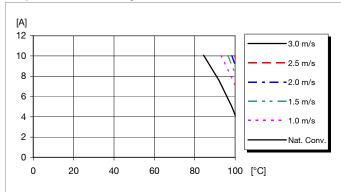
## PMC 8518T S

## 1.5 V/10 A Typical Characteristics

## Efficiency

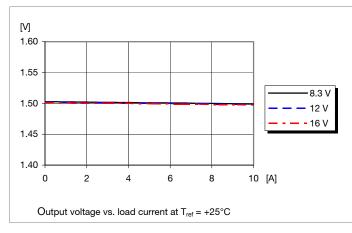


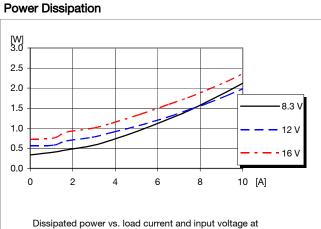
## **Output Current Derating**



Available load current vs. ambient air temperature and airflow at  $V_1 = 12$  V. See Thermal Consideration section.

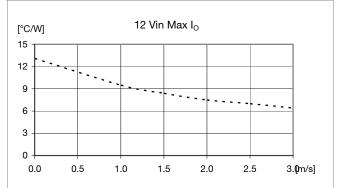
## **Output Characteristics**





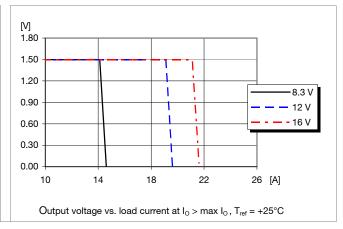
 $T_{ref} = +25^{\circ}C$ 

## **Thermal Resistance**



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section.





## PMC 8518 series

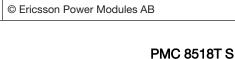
POL regulator, Input 12 V, Output 10 A/50 W

**Technical Specification** EN/LZT 146 063 R3A Aug 2007

## 1.5 V/10 A Typical Characteristics

# Shut-down Start-up Top trace: output voltage (1.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). Shut-down enabled by disconnecting V<sub>i</sub> at: $T_{ref} = +25^{\circ}C$ , V<sub>i</sub> = 12 V, I<sub>O</sub> = 10 A resistive load. Top trace: output voltage (1.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). $\begin{array}{l} \mbox{Start-up enabled by connecting $V_{l}$ at:} \\ \mbox{$T_{ref}$} = +25^{\circ}C, $V_{l}$ = 12 $V$, \\ \mbox{$I_{O}$} = 10 $A$ resistive load. \end{array}$ **Output Ripple & Noise Output Load Transient Response** V 14 M (M M 4 · Output voltage ripple at: $T_{ref} = +25^{\circ}C$ , $V_{I} = 12 V$ , $I_{O} = 10 A$ resistive load. Trace: output voltage (20 mV/div.). Time scale: (2 µs/div.).

## Output Voltage Adjust (see operating information)



## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

## 1.8 V/10 A Electrical Specification

 $\begin{array}{l} T_{ref} = -40 \ to \ +85^{\circ}C, \ V_l = 8.3 \ to \ 16 \ V, \ R_{adj} = 9.024 \ k\Omega, \ unless \ otherwise \ specified \ under \ Conditions. \\ Typical \ values \ given \ at: \ T_{ref} = +25^{\circ}C, \ V_l = 12 \ V, \ max \ I_0 \ , \ unless \ otherwise \ specified \ under \ Conditions. \\ Additional \ C_{in} = 4 \times 4.7 \ \mu F \ and \ C_{out} = 2 \times 150 \ \mu F. \ See \ Operating \ Information \ section \ for \ selection \ of \ capacitor \ types. \\ Connect \ the \ sense \ pin, \ where \ available, \ to \ the \ output \ pin. \end{array}$ 

Chara	cteristics	Conditions	min	typ	max	Unit
VI	Input voltage range		8.3		16	V
$V_{\text{loff}}$	Turn-off input voltage	Decreasing input voltage		7.8		V
$V_{\text{lon}}$	Turn-on input voltage	Increasing input voltage		8.0		V
Cı	Internal input capacitance			30		μF
Po	Output power		0		18	W
	Efficiency	50 % of max I <sub>0</sub>		89.2		%
η		max I <sub>o</sub>		89.7		70
$P_{d}$	Power Dissipation	max I <sub>0</sub>		2.1	2.4	W
Pli	Input idling power	I <sub>O</sub> = 0 A, V <sub>I</sub> = 12.0 V		0.6		W
$P_{RC}$	Input standby power	V <sub>I</sub> = 12.0 V (turned off with RC)		35		mW
ls	Static Input current	V <sub>I</sub> = 12.0 V, max I <sub>0</sub>		1.7		А
f <sub>s</sub>	Switching frequency	0-100 % of max I <sub>o</sub>	260	300	340	kHz

V <sub>Oi</sub>	Output voltage initial setting and accuracy	$T_{ref}$ = +25°C, V <sub>I</sub> = 12.0 V, max I <sub>O</sub>	-2		+2	%V
	Output voltage tolerance band	10-100 % of max I <sub>0</sub>	-3		+3	%V
v	Idling voltage	I <sub>0</sub> = 0 A	-2		+2	%V
Vo	Line regulation	max I <sub>o</sub>		2		mV
	Load regulation	$V_{\rm I}$ = 12.0 V, 0-100 % of max $I_{\rm O}$		10		mV
V <sub>tr</sub>	Load transient voltage deviation	V <sub>1</sub> = 12.0 V, Load step 25-75-25 %		±100		mV
t <sub>tr</sub>	Load transient recovery time	of max I <sub>o</sub> , di/dt = 5 A/µs	40			μs
tr	Ramp-up time (from 10–90 % of V <sub>Oi</sub> )	max Io		3		ms
ts	Start-up time (from V <sub>I</sub> connection to 90 % of V <sub>Oi</sub> )			7		ms
+	V <sub>I</sub> shut-down fall time.	Max I <sub>o</sub>	1			ms
t <sub>f</sub>	(From V <sub>I</sub> off to 10 % of V <sub>O</sub> )	I <sub>0</sub> = 0 A	18		S	
	RC start-up time	Max I <sub>o</sub>		7		ms
$t_{\text{RC}}t_{\text{Inh}}$	RC shut-down fall time	Max I <sub>o</sub>		1		ms
	(From RC off to 10 % of $V_{\rm O}$ )	I <sub>o</sub> = 0 A		18		S
lo	Output current		0		10	А
l <sub>lim</sub>	Current limit threshold	T <sub>ref</sub> < max T <sub>ref</sub>	13	19		А
l <sub>sc</sub>	Short circuit current	T <sub>ref</sub> = 25°C, See Operating Information section.		19	21	А
$V_{\text{Oac}}$	Output ripple & noise	See ripple & noise section, max ${\rm I}_{\rm O}$		35	70	mVp-p

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

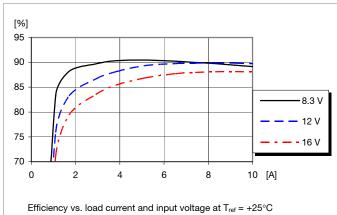
EN/LZT 146 063 R3A Aug 2007

**Technical Specification** 

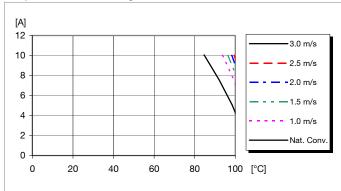
© Ericsson Power Modules AB

## 1.8 V/10 A Typical Characteristics

## Efficiency

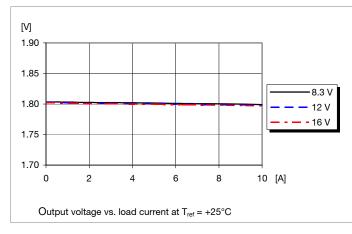


## **Output Current Derating**

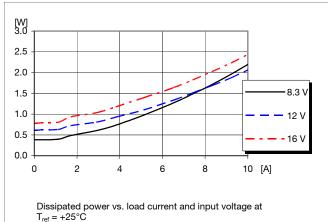


Available load current vs. ambient air temperature and airflow at V<sub>I</sub> = 12 V. See Thermal Consideration section.

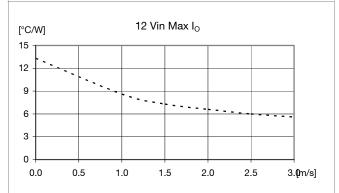
## **Output Characteristics**



## Power Dissipation

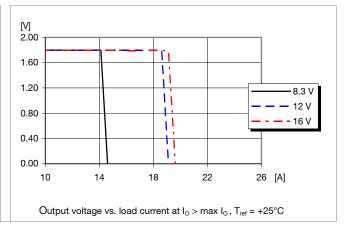


## **Thermal Resistance**



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section.





15

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007

© Ericsson Power Modules AB

**Technical Specification** 

## 1.8 V/10 A Typical Characteristics

# Shut-down Start-up Top trace: output voltage (1.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). Shut-down enabled by disconnecting V<sub>i</sub> at: $T_{ref} = +25^{\circ}C$ , V<sub>i</sub> = 12 V, I<sub>O</sub> = 10 A resistive load. Top trace: output voltage (1.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). $\begin{array}{l} \mbox{Start-up enabled by connecting $V_{l}$ at:} \\ \mbox{$T_{ref}$} = +25^{\circ}C, $V_{l}$ = 12 $V$, \\ \mbox{$I_{O}$} = 10 $A$ resistive load. \end{array}$ **Output Ripple & Noise Output Load Transient Response** Ŵ (mr Ŵ W VW Output voltage ripple at: $T_{ref} = +25^{\circ}C$ , $V_{I} = 12 V$ , $I_{O} = 10 A$ resistive load. Trace: output voltage (20 mV/div.). Time scale: (2 µs/div.).

## Output Voltage Adjust (see operating information)



## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

## 2.5 V/10 A Electrical Specification

 $\begin{array}{l} T_{ref} = -40 \ to \ +85^{\circ}C, \ V_{I} = 8.3 \ to \ 16 \ V, \ R_{adj} = 5.009 \ k\Omega, \ unless \ otherwise \ specified \ under \ Conditions. \\ Typical \ values \ given \ at: \ T_{ref} = +25^{\circ}C, \ V_{I} = 12 \ V, \ max \ I_{0} \ , \ unless \ otherwise \ specified \ under \ Conditions. \\ Additional \ C_{in} = 4 \times 4.7 \ \mu F \ and \ C_{out} = 2 \times 150 \ \mu F. \ See \ Operating \ Information \ section \ for \ selection \ of \ capacitor \ types. \\ Connect \ the \ sense \ pin, \ where \ available, \ to \ the \ output \ pin. \end{array}$ 

Characteristics		haracteristics Conditions		typ	max	Unit
VI	Input voltage range		8.3		16	V
$V_{\text{loff}}$	Turn-off input voltage	Decreasing input voltage		7.8		V
$V_{\text{lon}}$	Turn-on input voltage	Increasing input voltage		8.0		V
Cı	Internal input capacitance			30		μF
Po	Output power		0		25	W
	Efficiency	50 % of max I <sub>0</sub>		91.2		%
η		max I <sub>0</sub>		91.8		70
$P_{d}$	Power Dissipation	max I <sub>0</sub>		2.2	2.5	W
Pli	Input idling power	I <sub>O</sub> = 0 A, V <sub>I</sub> = 12.0 V		0.7		W
$P_{RC}$	Input standby power	V <sub>I</sub> = 12.0 V (turned off with RC)		35		mW
ls	Static Input current	V <sub>I</sub> = 12.0 V, max I <sub>0</sub>		2.3		А
f <sub>s</sub>	Switching frequency	0-100 % of max I <sub>o</sub>	260	300	340	kHz

V <sub>Oi</sub>	Output voltage initial setting and accuracy	$T_{ref}$ = +25°C, V <sub>I</sub> = 12.0 V, max I <sub>O</sub>	-2		+2	%V
	Output voltage tolerance band	10-100 % of max I <sub>0</sub>	-3		+3	%V
v	Idling voltage	I <sub>0</sub> = 0 A	-2		+2	%V
Vo	Line regulation	max I <sub>o</sub>		2		mV
	Load regulation	$V_{I}$ = 12.0 V, 0-100 % of max $I_{O}$		10		mV
V <sub>tr</sub>	Load transient voltage deviation	V <sub>1</sub> = 12.0 V, Load step 25-75-25 %		±100		mV
t <sub>tr</sub>	Load transient recovery time	of max I <sub>o</sub> , di/dt = 5 A/µs		40		μs
t <sub>r</sub>	Ramp-up time (from 10–90 % of V <sub>Oi</sub> )	max Io		3		ms
t <sub>s</sub>	Start-up time (from $V_1$ connection to 90 % of $V_{Oi}$ )	111ax 10		7		ms
+	V <sub>I</sub> shut-down fall time.	Max I <sub>0</sub>		1		ms
t <sub>f</sub>	(From $V_1$ off to 10 % of $V_0$ )	I <sub>O</sub> = 0 A		16		S
	RC start-up time	Max I <sub>0</sub>		7		ms
$t_{\text{RC}}t_{\text{lnh}}$	RC shut-down fall time	Max I <sub>0</sub>		1		ms
	(From RC off to 10 % of $V_{\rm O}$ )	I <sub>o</sub> = 0 A		16		S
lo	Output current		0		10	А
l <sub>lim</sub>	Current limit threshold	T <sub>ref</sub> < max T <sub>ref</sub>	13	19		А
l <sub>sc</sub>	Short circuit current	T <sub>ref</sub> = 25°C, See Operating Information section.		19	21	А
$V_{\text{Oac}}$	Output ripple & noise	See ripple & noise section, max ${\rm I}_{\rm O}$		35	70	mVp-p

## PMC 8518 series

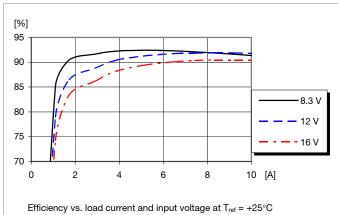
POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

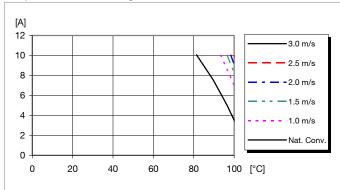
**Technical Specification** 

## 2.5 V/10 A Typical Characteristics

## Efficiency

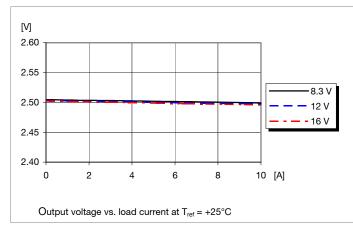


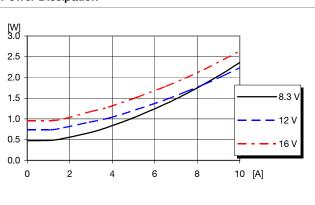
## **Output Current Derating**

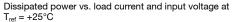


Available load current vs. ambient air temperature and airflow at  $V_{\rm I}$  = 12 V. See Thermal Consideration section.

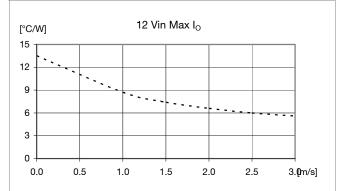
## **Output Characteristics**





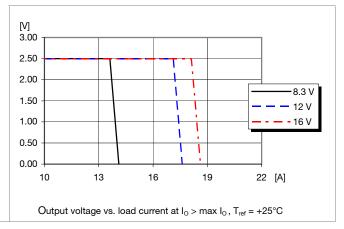


## **Thermal Resistance**



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section.





Power Dissipation

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

Technical Specification EN/LZT 146 063 R3A Aug 2007

© Ericsson Power Modules AB

## 2.5 V/10 A Typical Characteristics

# Stat-up Stu-down Image: Stat-up of the state of the sta

Output Voltage Adjust (see operating information)

## PMC 8518T S

## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

## 3.3 V/10 A Electrical Specification

 $\begin{array}{l} T_{ref} = -40 \ to \ +85^{\circ}C, \ V_{I} = 8.3 \ to \ 16 \ V, \ R_{adj} = 3.122 \ k\Omega, \ unless \ otherwise \ specified \ under \ Conditions. \\ Typical \ values \ given \ at: \ T_{ref} = +25^{\circ}C, \ V_{I} = 12 \ V, \ max \ I_{0} \ , \ unless \ otherwise \ specified \ under \ Conditions. \\ Additional \ C_{in} = 4 \times 4.7 \ \mu F \ and \ C_{out} = 2 \times 150 \ \mu F. \ See \ Operating \ Information \ section \ for \ selection \ of \ capacitor \ types. \\ Connect \ the \ sense \ pin, \ where \ available, \ to \ the \ output \ pin. \end{array}$ 

Characteristics		aracteristics Conditions		typ	max	Unit
Vı	Input voltage range		8.3		16	V
V <sub>loff</sub>	Turn-off input voltage	Decreasing input voltage		7.8		V
Vlon	Turn-on input voltage	Increasing input voltage		8.0		V
Cı	Internal input capacitance			30		μF
Po	Output power		0		33	W
n F#:-:	Efficiency	50 % of max I <sub>o</sub>		92.6		%
Ч	Enciency	max I <sub>0</sub>		93.2		
Pd	Power Dissipation	max I <sub>0</sub>		2.4	2.7	W
Pli	Input idling power	I <sub>0</sub> = 0 A, V <sub>1</sub> = 12.0 V		0.9		W
P <sub>RC</sub>	Input standby power	V <sub>I</sub> = 12.0 V (turned off with RC)		35		mW
ls	Static Input current	V <sub>I</sub> = 12.0 V, max I <sub>0</sub>		3.0		А
f <sub>s</sub>	Switching frequency	0-100 % of max I <sub>o</sub>	260	300	340	kHz

V <sub>Oi</sub>	Output voltage initial setting and accuracy	$T_{ref} = +25^{\circ}C, V_{I} = 12.0 V, max I_{O}$	-2		+2	%V
	Output voltage tolerance band	10-100 % of max I <sub>0</sub>	-3		+3	%V
V	Idling voltage	$I_{O} = 0 A$	-2		+2	%V
Vo	Line regulation	max I <sub>o</sub>		2		mV
	Load regulation	$V_{I} = 12.0 \text{ V}, 0-100 \text{ \% of max } I_{O}$		10		mV
V <sub>tr</sub>	Load transient voltage deviation	V <sub>1</sub> = 12.0 V, Load step 25-75-25 %		±100		mV
t <sub>tr</sub>	Load transient recovery time	of max I <sub>o</sub> , di/dt = 5 A/µs	40		μs	
tr	Ramp-up time (from 10–90 % of V <sub>Oi</sub> )	max I <sub>o</sub>		3		ms
ts	Start-up time (from $V_1$ connection to 90 % of $V_{Oi}$ )			7		ms
+	V <sub>I</sub> shut-down fall time.	Max I <sub>o</sub>		1		ms
t <sub>f</sub>	(From $V_1$ off to 10 % of $V_0$ )	I <sub>O</sub> = 0 A	16			s
	RC start-up time	Max I <sub>o</sub>		7		ms
$t_{\text{RC}}t_{\text{lnh}}$	RC shut-down fall time	Max I <sub>o</sub>		1		ms
	(From RC off to 10 % of $V_{\rm O}$ )	I <sub>o</sub> = 0 A		16		S
lo	Output current		0		10	А
l <sub>lim</sub>	Current limit threshold	T <sub>ref</sub> < max T <sub>ref</sub>	12	17		А
l <sub>sc</sub>	Short circuit current	T <sub>ref</sub> = 25°C, See Operating Information section.		17	19	А
$V_{\text{Oac}}$	Output ripple & noise	See ripple & noise section, max $I_0$		35	70	mVp-p

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

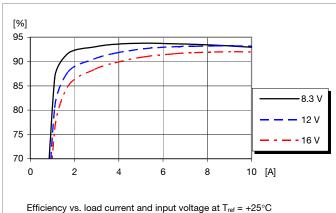
EN/LZT 146 063 R3A Aug 2007

**Technical Specification** 

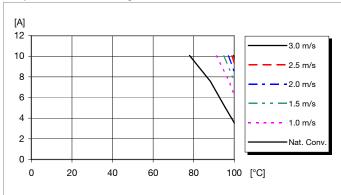
## © Ericsson Power Modules AB

## 3.3 V/10 A Typical Characteristics

## Efficiency

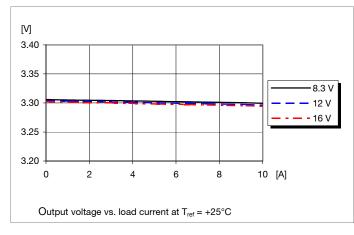


## **Output Current Derating**

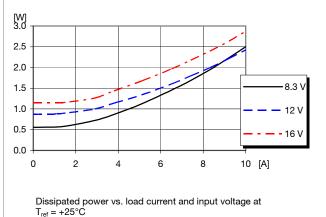


Available load current vs. ambient air temperature and airflow at V<sub>I</sub> = 12 V. See Thermal Consideration section.

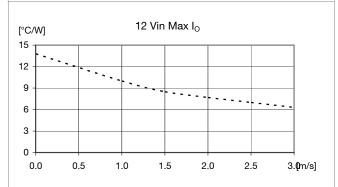
## **Output Characteristics**



## Power Dissipation

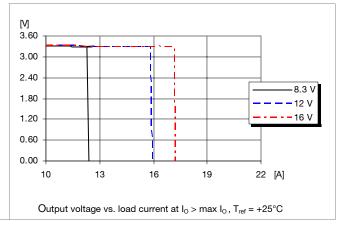


## **Thermal Resistance**



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section.





21

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

22 **Technical Specification** EN/LZT 146 063 R3A Aug 2007

© Ericsson Power Modules AB

## 3.3 V/10 A Typical Characteristics

# Shut-down Start-up Top trace: output voltage (1.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). Shut-down enabled by disconnecting V<sub>i</sub> at: $T_{ref} = +25^{\circ}C$ , V<sub>i</sub> = 12 V, I<sub>O</sub> = 10 A resistive load. Top trace: output voltage (1.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). $\begin{array}{l} \mbox{Start-up enabled by connecting $V_{l}$ at:} \\ \mbox{$T_{ref}$} = +25^{\circ}C, $V_{l}$ = 12 $V$, \\ \mbox{$I_{O}$} = 10 $A$ resistive load. \end{array}$ **Output Ripple & Noise Output Load Transient Response** Output voltage ripple at: $T_{ref} = +25^{\circ}C$ , $V_{I} = 12 V$ , $I_{O} = 10 A$ resistive load.

Output Voltage Adjust (see operating information)

Trace: output voltage (20 mV/div.). Time scale: (2 µs/div.).

## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

## 5.0 V/10 A Electrical Specification

 $\begin{array}{l} T_{ref} = -40 \ to \ +85^{\circ}C, \ V_{I} = 8.3 \ to \ 16 \ V, \ R_{adj} = 1.472 \ k\Omega, \ unless \ otherwise \ specified \ under \ Conditions. \\ Typical \ values \ given \ at: \ T_{ref} = +25^{\circ}C, \ V_{I} = 12 \ V, \ max \ I_{0} \ , \ unless \ otherwise \ specified \ under \ Conditions. \\ Additional \ C_{in} = 4 \times 4.7 \ \mu F \ and \ C_{out} = 2 \times 150 \ \mu F. \ See \ Operating \ Information \ section \ for \ selection \ of \ capacitor \ types. \\ Connect \ the \ sense \ pin, \ where \ available, \ to \ the \ output \ pin. \end{array}$ 

Characteristics		Conditions	min	typ	max	Unit
VI	Input voltage range		8.3		16	V
$V_{\text{loff}}$	Turn-off input voltage	Decreasing input voltage		7.8		V
$V_{\text{lon}}$	Turn-on input voltage	Increasing input voltage		8.0		V
Cı	Internal input capacitance			30		μF
Po	Output power		0		50	W
	Efficiency	50 % of max I <sub>o</sub>		94.3		- %
η	Enciency	max I <sub>0</sub>		94.8		
$P_{d}$	Power Dissipation	max I <sub>0</sub>		2.7	3.0	W
Pli	Input idling power	I <sub>O</sub> = 0 A, V <sub>I</sub> = 12.0 V		1.1		W
$P_{RC}$	Input standby power	V <sub>I</sub> = 12.0 V (turned off with RC)		35		mW
ls	Static Input current	V <sub>I</sub> = 12.0 V, max I <sub>O</sub>		4.4		А
fs	Switching frequency	0-100 % of max I <sub>0</sub>	260	300	340	kHz

r						
$V_{\text{Oi}}$	Output voltage initial setting and accuracy	$T_{ref}$ = +25°C, $V_I$ = 12.0 V, max $I_O$	-2		+2	%V
	Output voltage tolerance band	10-100 % of max I <sub>0</sub>	-3		+3	%V
Vo	Idling voltage	I <sub>0</sub> = 0 A	-2		+2	%V
VO	Line regulation	max I <sub>0</sub>		2		mV
	Load regulation	$V_{I} = 12.0 \text{ V}, 0-100 \text{ \% of max } I_{O}$		10		mV
V <sub>tr</sub>	Load transient voltage deviation	V <sub>1</sub> = 12.0 V, Load step 25-75-25 %		±100		mV
t <sub>tr</sub>	Load transient recovery time	of max I <sub>o</sub> , di/dt = 5 A/µs		40		μs
t <sub>r</sub>	Ramp-up time (from 10–90 % of V <sub>Ol</sub> )	max Io		3		ms
ts	Start-up time (from V <sub>I</sub> connection to 90 % of V <sub>Oi</sub> )			7		ms
+	V <sub>I</sub> shut-down fall time.	Max I <sub>0</sub>		1		ms
t <sub>f</sub>	(From V <sub>I</sub> off to 10 % of V <sub>O</sub> )	I <sub>0</sub> = 0 A	16			S
	RC start-up time	Max I <sub>0</sub>		7		ms
$t_{RC}t_{Inh}$	RC shut-down fall time	Max I <sub>0</sub>		1		ms
	(From RC off to 10 % of $V_{\rm O}$ )	I <sub>o</sub> = 0 A		15		S
lo	Output current		0		10	А
l <sub>lim</sub>	Current limit threshold	T <sub>ref</sub> < max T <sub>ref</sub>	11	14		А
I <sub>sc</sub>	Short circuit current	T <sub>ref</sub> = 25°C, See Operating Information section.		14	16	А
$V_{\text{Oac}}$	Output ripple & noise	See ripple & noise section, max $I_{\rm O}$		35	70	mVp-p

## PMC 8518 series

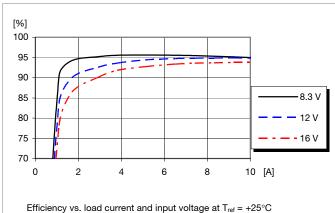
POL regulator, Input 12 V, Output 10 A/50 W

EN/LZT 146 063 R3A Aug 2007 © Ericsson Power Modules AB

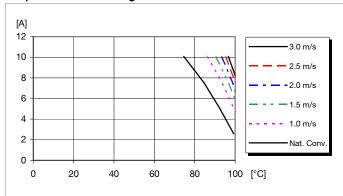
**Technical Specification** 

## 5.0 V/10 A Typical Characteristics

## Efficiency

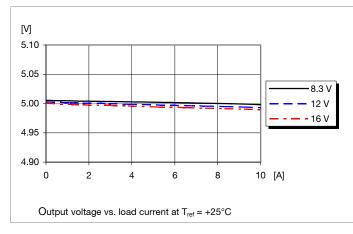


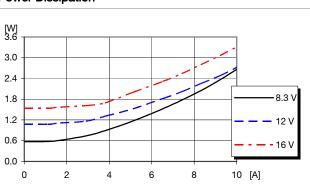
## **Output Current Derating**

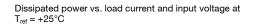


Available load current vs. ambient air temperature and airflow at V<sub>I</sub> = 12 V. See Thermal Consideration section.

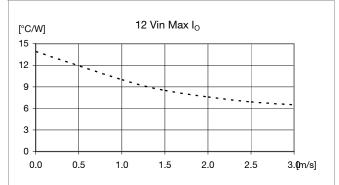
## **Output Characteristics**





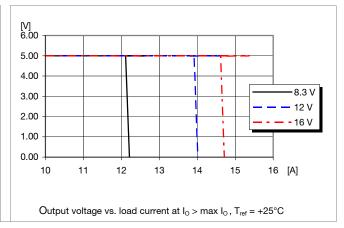


## **Thermal Resistance**



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section.





## Power Dissipation

24

## PMC 8518 series

POL regulator, Input 12 V, Output 10 A/50 W

**Technical Specification** EN/LZT 146 063 R3A Aug 2007

© Ericsson Power Modules AB

## 5.0 V/10 A Typical Characteristics

# Shut-down Start-up Top trace: output voltage (2.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). Shut-down enabled by disconnecting V<sub>i</sub> at: $T_{ref} = +25^{\circ}C$ , V<sub>i</sub> = 12 V, I<sub>O</sub> = 10 A resistive load. Top trace: output voltage (2.0 V/div.). Bottom trace: input voltage (10 V/div.). Time scale: (2 ms/div.). $\begin{array}{l} \mbox{Start-up enabled by connecting $V_{l}$ at:} \\ \mbox{$T_{ref}$} = +25^{\circ}C, $V_{l}$ = 12 $V$, \\ \mbox{$I_{O}$} = 10 $A$ resistive load. \end{array}$ **Output Ripple & Noise Output Load Transient Response**

Output voltage ripple at:  $T_{ref} = +25^{\circ}C$ ,  $V_{I} = 12 V$ ,  $I_{O} = 10 A$  resistive load.

Output Voltage Adjust (see operating information)

Trace: output voltage (20 mV/div.). Time scale: (2 µs/div.).

## PMC 8518T S

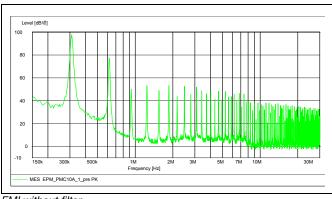
# ERICSSON 🔰

## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

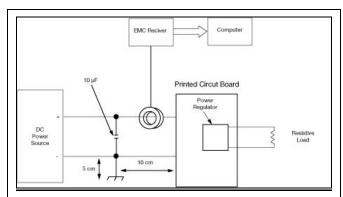
## **EMC** Specification

Conducted EMI measured according to test set-up. The fundamental switching frequency is 300 kHz for PMC 8518T S @  $V_I = 12 V$ , max  $I_O$ .

Conducted EMI Input terminal value (typ)



EMI without filter



Test set-up

## Layout recommendation

The radiated EMI performance of the DC/DC regulator will depend on the PCB layout and ground layer design. It is also important to consider the stand-off of the DC/DC regulator.

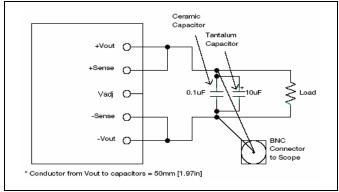
If a ground layer is used, it should be connected to the output of the DC/DC regulator and the equipment ground or chassis.

A ground layer will increase the stray capacitance in the PCB and improve the high frequency EMC performance.

# Technical Specification 26 EN/LZT 146 063 R3A Aug 2007 Image: Compare the second s

## Output ripple and noise

Output ripple and noise measured according to figure below. See Design Note 022 for detailed information.



Output ripple and noise test setup

## **Operating information**

See "Output Voltage Adjust (Vadj)" section.

## Input Voltage

The input voltage range 8.3 to 16 Vdc makes the PMC 8000 easy to use in intermediate bus applications when powered by a regulated bus converter. For output voltage trims over 5.25 Vout, the input voltage must be reduced to a maximum of 14 V in order to maintain specified data.

## Turn-off Input Voltage

The PMC 8000 Series DC/DC regulators monitor the input voltage and will turn on and turn off at predetermined levels. The minimum hysteresis between turn on and turn off input voltage is 0.2V where the turn on input voltage is the highest.

## **Remote Control (RC)**

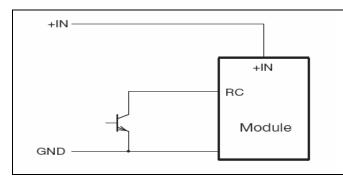
Standard Version with "positive logic"

The RC pin may be used to turn on or turn off the regulator using a suitable open collector function.

Turn off is achieved by connecting the RC pin to ground. The regulator will run in normal operation when the RC pin is left open.

RC	Regulator condition	Min	Тур	Max	Unit
Low level	OFF	-0.3		0.3	V
Open	ON	1.7		16	V

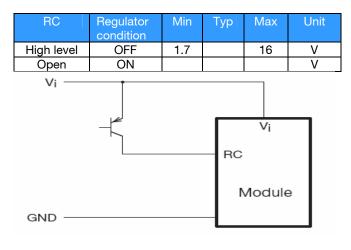
## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W



## Standard Version with "negative logic"

The RC pin may be used to turn on or turn off the regulator using a suitable open collector function.

Turn off is achieved by connecting the RC pin to the input voltage. The regulator will run in normal operation when the RC pin is left open.



## **External Capacitors**

## **Required Input Filter:**

External input capacitors are required to increase the lifetime of the internal capacitors. Low ESR ceramics should be used, the minimum input capacitance is stated below.

## PMC 8518T S 1 x 4.7 uF.

## **Optional Input Filter:**

To minimize input ripple and to ensure even better stability more capacitors can be added, see table below. Consider the max output power in a given application and choose sufficient capacitors to obtain desired ripple level. Make sure that the extra capacitors are placed near the input pins. The table below is just an example since the board layout also has effect on the result.

Output	Desired input ripple (mVp-p)				
power	150	250	500		
0-20 W	2x4.7uF				

Technical Specification	
-------------------------	--

EN/LZT 146 063 R3A Aug 2007
© Ericsson Power Modules AB

27

20-40 W	5x4.7uF	2x4.7uF	
40-50 W	8x4.7uF	4x4.7uF	2x4.7uF

## Required output filter:

External output capacitance is also required to reduce the output ripple and to obtain specified load step response. It is recommended to use low ESR polymer capacitors or low ESR ceramic capacitors.

## Minimum requirement:

PMC 8518T S 2 x 150 uF. (low ESR polymer type). This is the output filter used in the verification and a requirement to meet the specification.

## Input And Output Impedance

The impedance of both the power source and the load will interact with the impedance of the DC/DC regulator. It is most important to have low characteristic impedance, both at the input and output, as the regulators have a low energy storage capability. Use capacitors across the input if the source inductance is greater than 4.7 uH. Suitable input capacitors are 22 uF - 220 uF low ESR ceramics.

## **Maximum Capacitive Load**

When powering loads with significant dynamic current requirements, the voltage regulation at the load can be improved by addition of decoupling capacitance at the load. The most effective technique is to locate low ESR ceramic capacitors as close to the load as possible, using several capacitors to lower the total ESR. These ceramic capacitors will handle short duration high-frequency components of dynamic load changes. In addition, higher values of capacitors (electrolytic capacitors) should be used to handle the mid-frequency components. It is equally important to use good design practice when configuring the DC distribution system.

Low resistance and low inductance PCB layouts and cabling should be used. Remember that when using remote sensing, all resistance (including the ESR), inductance and capacitance of the distribution system is within the feedback loop of the regulator. This can affect on the regulators compensation and the resulting stability and dynamic response performance.

Very low ESR and high capacitance must be used with care. A "rule of thumb" is that the total capacitance must never exceed typically 500-700 uF if only low ESR (< 2 m $\Omega$ ) ceramic capacitors are used. If more capacitance is needed, a combination of low ESR type and electrolytic capacitors should be used; otherwise the stability will be affected. The PMC 8000 series regulator can accept up to 5 mF of capacitive load on the output at full load. This gives <500 uF/A of Io. When using that large capacitance it is important to consider the selection of output capacitors; the resulting behaviour is a combination of the amount of capacitance and ESR.

A combination of low ESR and output capacitance exceeding

PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

5 mF for PMC 8518 can cause the regulator into over current protection mode (hick-up) due to high start up current. The output filter must therefore be designed without exceeding the above stated capacitance levels if the ESR is lower then 30-40 m $\Omega$ .

## Output Voltage Adjust (Vadj)

All PMC 8000 Series DC/DC regulators have an Output Voltage adjust pin(Vadj). This pin can be used to adjust the output voltage about output voltage initial setting(0.75V). When increasing the output voltage the maximum power rating of the converter remains the same, and the output current capability will therefore decrease correspondingly. To increase the output voltage a resistor or a voltage signal should be connected/applied between Vadj pin and GND. The resistor/voltage signal value for some standard output setponts are given below, for other voltage setpoints use the formulas to calculate the correct resistor or voltage signal. For output voltages of 5.25V and higher the input voltage is restricted to maximum 14Vin.

Formula 1: Radj = (10500/(Vout – 0.7525)) – 1000 (ohm) Formula 2: Vtrim = (0.7 – 0.0667 x (Vout – 0.7525)) (V)

Vout (V)	Radj (kohm)	Vtrim (V)
0.75	Open	Open
1.00	41.42	0.684
1.20	22.46	0.670
1.50	13.05	0.650
1.80	9.024	0.630
2.50	5.009	0.583
3.30	3.122	0.530
5.00	1.472	0.417
5.50	1.212	0.383

## **Parallel Operation**

The PMC 8000 Series DC/DC regulators can be connected in parallel with a common input. Paralleling is accomplished by connecting the output voltage pins directly and using a load sharing device on the input. Layout considerations should be made to avoid load imbalance. For more details on paralleling, please consult your local applications support.

## **Remote Sense**

All PMC 8000 Series DC/DC regulators have a positive remote sense pin that can be used to compensate for moderate amounts of resistance in the distribution system and allow for voltage regulation at the load or other selected point. The remote sense line will carry very little current and does not need a large cross sectional area. However, the sense line on the PCB should be located close to a ground trace or ground plane. The remote sense circuitry will compensate for up to 10% voltage drop between the sense voltage and the voltage at the output pins from Vonom. If the remote sense is not needed the sense pin should be left open or connected to the positive output. Technical Specification

# © Ericsson Power Modules AB

## **Over Temperature Protection (OTP)**

The PMC 8000 Series DC/DC regulators are protected from thermal overload by an internal over temperature shutdown circuit. When the PCB temperature near the IC circuit reaches 130 °C the converter will shut down immediately. The regulator will make continuous attempts to start up (nonlatching mode) and resume normal operation automatically when the temperature has dropped below the temperature threshold.

## **Over Current Protection (OCP)**

The PMC 8000 Series DC/DC regulators include current limiting circuitry that allows them to withstand continuous overloads or short circuit conditions on the output. The output voltage will decrease towards zero for output currents in excess of max output current (lomax). When the current limit is reached the regulator will go into hiccup mode. The current limit is temperature dependent, i.e. the limit decrease at higher operating temperature, the regulator is guaranteed to start at lomax  $\times$  1.25 @ Tref 115°C. The regulator will resume normal operation after removal of the overload. The load distribution system should be designed to carry the maximum output short circuit current specified.

	Technical Specification	29
PMC 8518 series	EN/LZT 146 063 R3A Aug 2007	
POL regulator, Input 12 V, Output 10 A/50 W	© Ericsson Power Modules AB	

## **Thermal Consideration**

## General

The regulators are designed to operate in different thermal environments and sufficient cooling must be provided to ensure reliable operation.

Cooling is achieved mainly by conduction, from the pins to the host board, and convection, which is dependant on the airflow across the regulator. Increased airflow enhances the cooling of the regulator.

The Output Current Derating graph found in the Output section for each model provides the available output current vs. ambient air temperature and air velocity at  $V_{in} = 12$  V.

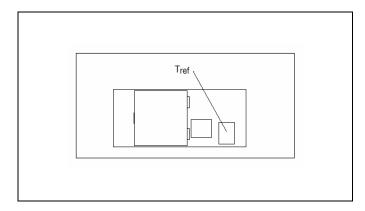
The DC/DC regulator is tested on a 254 x 254 mm, 35  $\mu$ m (1 oz), 8-layer test board mounted vertically in a wind tunnel with a cross-section of 305 x 305 mm.

Proper cooling of the DC/DC regulator can be verified by measuring the temperature at positions P1, P2 and P3. The temperature at these positions should not exceed the max values provided in the table below.

Note that the max value is the absolute maximum rating (non destruction) and that the electrical Output data is guaranteed up to  $T_{\text{ref}}$ .

See Design Note 019 for further information.

Position	Device	Designation	max value
P <sub>1</sub>	Pcb		
P <sub>2</sub>	Mosfet	T <sub>ref</sub>	115º C
P <sub>3</sub>	Inductor		



## PMC 8518 series POL regulator, Input 12 V, Output 10 A/50 W

## **Thermal Consideration continued**

## Definition of reference temperature (T<sub>ref</sub>)

The reference temperature is used to monitor the temperature limits of the product. Temperatures above maximum  $T_{ref}$  are not allowed and may cause degradation or permanent damage to the product.  $T_{ref}$  is also used to define the temperature range for normal operating conditions.  $T_{ref}$  is defined by the design and used to guarantee safety margins, proper operation and high reliability of the module.

## **Ambient Temperature Calculation**

By using the thermal resistance the maximum allowed ambient temperature can be calculated.

1. The power loss is calculated by using the formula  $((1/\eta) - 1) \times$  output power = power losses (Pd).  $\eta$  = efficiency of regulator. E.g 88 % = 0.88

2. Find the thermal resistance (Rth) in the Thermal Resistance graph found in the Output section for each model. Calculate the temperature increase ( $\Delta$ T).  $\Delta$ T = Rth x Pd

3. Max allowed ambient temperature is: Max Tref -  $\Delta T$ .

E.g 5 V output at 1 m/s, full load, 12 Vin :

1.  $((\frac{1}{0.948}) - 1) \times 50 \text{ W} = 2.74 \text{ W}$ 

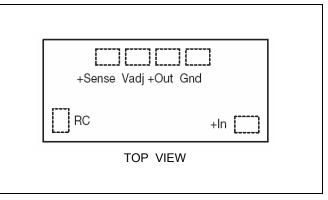
2. 2.74 W × 10.0°C/W = 27.4°C

3. 115 °C – 27.4°C = max ambient temperature is 87.6°C

The actual temperature will be dependent on several factors such as the PCB size, number of layers and direction of airflow.

# Technical Specification30EN/LZT 146 063 R3A Aug 2007

## Connections



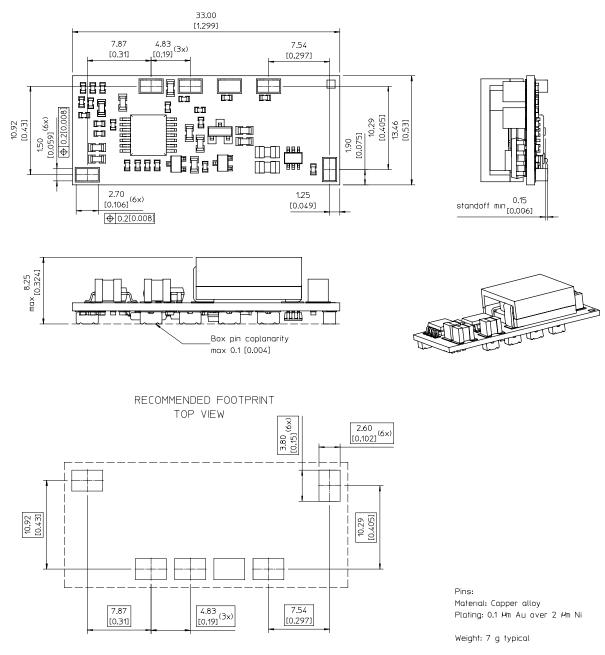
© Ericsson Power Modules AB

Pin	Designation	Function
1	RC	Remote Control
2	+ln	Positive input
3	Gnd	Ground
4	+Out	Positive output
5	Vadj	External output adjust
6	+Sense	Positive remote sense

# ERICSSON 📁

	Technical Specification	31
PMC 8518 series	EN/LZT 146 063 R3A Aug 2007	
POL regulator, Input 12 V, Output 10 A/50 W	© Ericsson Power Modules AB	

## Mechanical Information



All dimensions in mm [inch]. Tolerances unless specified x.x mm ±0.5 mm [0.02] x.xx mm ±0.25 mm [0.01] (not applied on footprint or typical values)

 $\epsilon$ 

PMC 8518 series
POL regulator, Input 12 V, Output 10 A/50 W

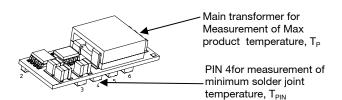
## Soldering Information - Surface Mounting

The product is intended for convection or vapor phase reflow SnPb or Pb-free processes. To achieve a good and reliable soldering result, make sure to follow the recommendations from the solder paste supplier, to use state-of-the-art reflow equipment and reflow profiling techniques as well as the following guidelines.

A no-clean flux is recommended to avoid entrapment of cleaning fluids in cavities inside the product or between the product and the host board. The cleaning residues may affect long time reliability and isolation voltage.

## **Minimum Pin Temperature Recommendations**

Pin number 4 is chosen as reference location for the minimum pin temperature recommendations since this will likely be the coolest solder joint during the reflow process.



## SnPb solder processes

For Pb solder processes, a pin temperature ( $T_{PIN}$ ) in excess of the solder melting temperature, ( $T_L$ , +183°C for Sn63/Pb37) for more than 30 seconds, and a peak temperature of +210°C is recommended to ensure a reliable solder joint.

## Lead-free (Pb-free) solder processes

For Pb-free solder processes, a pin temperature ( $T_{PIN}$ ) in excess of the solder melting temperature ( $T_L$ , +217 to +221 °C for Sn/Ag/Cu solder alloys) for more than 30 seconds, and a peak temperature of +235°C on all solder joints is recommended to ensure a reliable solder joint.

	EN/LZT 146 063 R3A Aug 2007	
	© Ericsson Power Modules AB	

**Technical Specification** 

32

Main transformer is chosen as reference location for the maximum (peak) allowed product temperature since this will likely be the warmest parts of the product during the reflow process.

To avoid damage or performance degradation of the product, the reflow profile should be optimized to avoid excessive heating. A sufficiently extended preheat time is recommended to ensure an even temperature across the host PCB, for both small and large devices. To reduce the risk of excessive heating is also recommended to reduce the time in the reflow zone as much as possible.

## SnPb solder processes

For conventional SnPb solder processes, the product is qualified for MSL 1 according to IPC/JEDEC standard J-STD-020C.

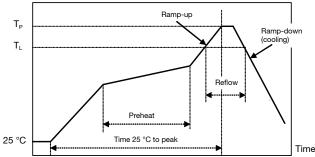
During reflow, T<sub>P</sub> must not exceed +225 °C at any time.

## Lead-free (Pb-free) solder processes

For Pb-free solder processes, the product is qualified for MSL 1 according to IPC/JEDEC standard J-STD-020C.

During reflow,  $T_P$  must not exceed +245 °C at any time.





Profile features		Sn/Pb eutectic assembly	Pb-free assembly
Average ramp-up rate		3 °C/s max	3 °C/s max
Solder melting temperature (typical)	TL	+183 °C	+217 °C
Peak product temperature	T <sub>P</sub>	+225 °C 1	+245 °C
Average ramp-down rate		6 °C/s max	6 °C/s max
Time 25 °C to peak temperature		6 minutes max	8 minutes max

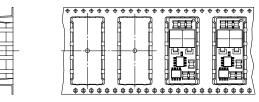
# ERICSSON 🔰

	Technical Specification	33
PMC 8518 series	EN/LZT 146 063 R3A Aug 2007	
POL regulator, Input 12 V, Output 10 A/50 W	© Ericsson Power Modules AB	

## **Delivery Package Information**

The products are delivered in antistatic carrier tape (EIA 481 standard).

Carrier Tape Specifications		
Material	Dissipative polystyrene (PS)	
Surface resistance	Ohm/square < 10 <sup>5</sup>	
Bak	The tape is not bake	
Tape width	44 mm [1.732 inch]	
Pocket pitch	24 mm [0.945 inch]	
Pocket depth	8.6 mm [0.339 inch]	
Reel diameter	330 mm [13 inch]	
Reel capacity	200 products /reel	
Reel weight	1.9 kg/full reel (typical)	



# ERICSSON 🔰

	Technical Specification	34
PMC 8518 series	EN/LZT 146 063 R3A Aug 2007	
POL regulator, Input 12 V, Output 10 A/50 W	© Ericsson Power Modules AB	

## **Product Qualification Specification**

Characteristics			
External visual inspection	IPC-A-610D		
Change of temperature (Temperature cycling)	JESD22-A104-B	Temperature range Number of cycles Dwell/transfer time	-40 to +125 °C 300 30 min/0-1 min
Cold (in operation)	IEC 68-2-1 Ad	Temperature T <sub>A</sub> Duration	-45 °C 72 h
Damp heat	JESD22-A101-B	Temperature Humidity Duration	+85 °C 85 % RH 1000 hours
Dry heat	JESD22-A103-B	Temperature Duration	+125  °C 1000 h
Mechanical shock	JESD22-B104-B	Peak acceleration Duration	200 g 1.5 ms
Moisture reflow sensitivity classification	J-STD-020C	SnPb Eutectic Pb free	MSL 1, peak reflow @ 225 °C MSL 1, peak reflow @ 245 °C
Operational life test		Ambient temperature Load Maximum input voltage ON Input voltage OFF Duration	85 °C Nominal 9 min 3 min 1000 h
Lead integrity	JESD22-B105-C	Weight on all terminals	1000 g
Random vibration	JESD22-B103-B	Frequency Acceleration density	2-500 Hz 0.008-0.2 g <sup>2</sup> / Hz
Solderability	IEC 68-2-58 Td	Solder immersion depth Time for onset of wetting Wetting force	1 mm < 4 s > 100 mN / m
Sinusoidal vibration	JESD22-B103-B	Frequency Acceleration amplitude	101000 Hz 10 g

# **X-ON Electronics**

Largest Supplier of Electrical and Electronic Components

Click to view similar products for Non-Isolated DC/DC Converters category:

Click to view products by Ericsson manufacturer:

Other Similar products are found below :

PSR152.5-7IR APTH003A0X-SRZ SPM1004-3V3C R-785.0-05 10E24-P15-10PPM 1E24-P4-25PPM-SHV-5KV CA-17205-L4 PROPOWER-3.3V MYGTM01210BZN JRCS016A0S4-HZ 3V12-N0.8 6AA24-P30-I5-M BM2P101X-Z ROF-78E12-0.5SMD-R RPMA5.0-8.0/OF PTV03010WAD PTV05020WAH PTV12010LAH PTV12020WAD R-7212D R-7212P R-78AA5.0-1.0SMD 30A24-N15-E 10A12-P4-M 10C24-N250-I5 10C24-P125 10C24-P250-I5 6A24-P20-I10-F-M-25PPM 1A24-P30-F-M-C TSR 1-24150SM 1/2AA24-N30-I10 1C24-N125 12C24-N250 V7806-1500 PTV05010WAH PTN04050CAZT PTH12020WAD PTH12020LAS PTH05T210WAH V7803-2000R AXA005A0XZ NSR020A0X43Z TPS82677SIPR OKR-T/30-W12-C NID30S24-15 NID30S48-24 LXDC2HL25A-053 LXDC2HL10A-080 PTH05T210WAD PTH08T210WAS