ESP32-C3 Series

Datasheet

Ultra-Low-Power SoC with RISC-V Single-Core CPU
Supporting IEEE 802.11b/g/n (2.4 GHz Wi-Fi) and Bluetooth® 5 (LE)

Including:

ESP32-C3

ESP32-C3FN4

ESP32-C3FH4



Product Overview

ESP32-C3 series of SoCs is an ultra-low-power and highly-integrated MCU-based solution that supports 2.4 GHz Wi-Fi and Bluetooth[®] Low Energy (Bluetooth LE). The block diagram of ESP32-C3 is shown below.

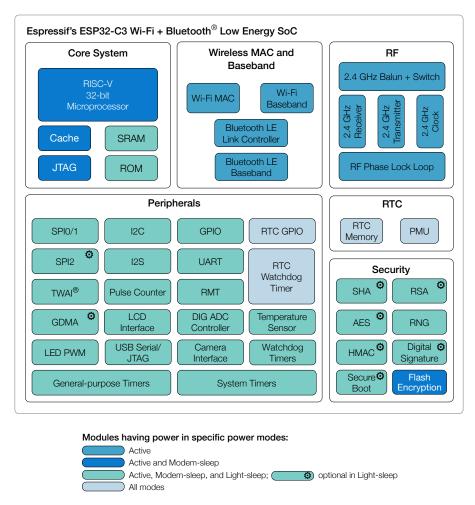


Figure 1: Block Diagram of ESP32-C3

Solution Highlights

- A complete Wi-Fi subsystem that complies with IEEE 802.11b/g/n protocol and supports Station mode, SoftAP mode, SoftAP + Station mode, and promiscuous mode
- A Bluetooth LE subsystem that supports features of Bluetooth 5 and Bluetooth mesh
- 32-bit RISC-V single-core processor with a four-stage pipeline that operates at up to 160 MHz
- State-of-the-art power and RF performance

- Storage capacities ensured by 400 KB of SRAM (16 KB for cache) and 384 KB of ROM on the chip, and SPI, Dual SPI, Quad SPI, and QPI interfaces that allow connection to external flash
- Reliable security features ensured by
 - Cryptographic hardware accelerators that support AES-128/256, Hash, RSA, HMAC, digital signature and secure boot
 - Random number generator
 - Permission control on accessing internal

- memory, external memory, and peripherals
- External memory encryption and decryption
- Rich set of peripheral interfaces and GPIOs, ideal for various scenarios and complex applications

Features

Wi-Fi

- IEEE 802.11 b/g/n-compliant
- Supports 20 MHz, 40 MHz bandwidth in 2.4 GHz band
- 1T1R mode with data rate up to 150 Mbps
- Wi-Fi Multimedia (WMM)
- TX/RX A-MPDU, TX/RX A-MSDU
- Immediate Block ACK
- Fragmentation and defragmentation
- Transmit opportunity (TXOP)
- Automatic Beacon monitoring (hardware TSF)
- 4 × virtual Wi-Fi interfaces
- Simultaneous support for Infrastructure BSS in Station mode, SoftAP mode, Station + SoftAP mode, and promiscuous mode
 Note that when ESP32-C3 scans in Station mode, the SoftAP channel will change along with the Station channel
- Antenna diversity
- 802.11mc FTM
- Supports external power amplifier

Bluetooth

- Bluetooth LE: Bluetooth 5, Bluetooth mesh
- High power mode (18 dBm)
- Speed: 125 Kbps, 500 Kbps, 1 Mbps, 2 Mbps
- Advertising extensions
- Multiple advertisement sets
- Channel selection algorithm #2
- Internal co-existence mechanism between Wi-Fi and Bluetooth to share the same antenna

CPU and Memory

- 32-bit RISC-V single-core processor, up to 160 MHz
- CoreMark[®] score:
 - 1 core at 160 MHz: 407.22 CoreMark; 2.55
 CoreMark/MHz
- 384 KB ROM
- 400 KB SRAM (16 KB for cache)
- 8 KB SRAM in RTC
- Embedded flash (see details in Chapter 1 ESP32-C3 Series Comparison)
- SPI, Dual SPI, Quad SPI, and QPI interfaces that allow connection to multiple external flash
- Access to flash accelerated by cache
- Supports flash in-Circuit Programming (ICP)

Advanced Peripheral Interfaces

- 22 × programmable GPIOs
- · Digital interfaces:
 - 3 × SPI
 - 2 × UART
 - 1 × I2C
 - $-1 \times 12S$
 - Remote control peripheral, with 2 transmit channels and 2 receive channels
 - LED PWM controller, with up to 6 channels
 - Full-speed USB Serial/JTAG controller
 - General DMA controller (GDMA), with 3 transmit channels and 3 receive channels
 - 1 x TWAI[®] controller compatible with ISO 11898-1 (CAN Specification 2.0)
- Analog interfaces:

- 2 × 12-bit SAR ADCs, up to 6 channels
- 1 × temperature sensor
- Timers:
 - 2 × 54-bit general-purpose timers
 - 3 × watchdog timers
 - 1 × 52-bit system timer

Low Power Management

• Power Management Unit with four power modes

Security

Secure boot

- Flash encryption
- 4096-bit OTP, up to 1792 bits for use
- Cryptographic hardware acceleration:
 - AES-128/256 (FIPS PUB 197)
- Permission Control
- SHA Accelerator (FIPS PUB 180-4)
- RSA Accelerator
- Random Number Generator (RNG)
- HMAC
- Digital signature

Applications (A Non-exhaustive List)

With ultra-low power consumption, ESP32-C3 is an ideal choice for IoT devices in the following areas:

- Smart Home
 - Light control
 - Smart button
 - Smart plug
 - Indoor positioning
- Industrial Automation
 - Industrial robot
 - Mesh network
 - Human machine interface (HMI)
 - Industrial field bus
- Health Care
 - Health monitor
 - Baby monitor
- Consumer Electronics
 - Smart watch and bracelet
 - Over-the-top (OTT) devices

- Wi-Fi and Bluetooth speaker
- Logger toys and proximity sensing toys
- Smart Agriculture
 - Smart greenhouse
 - Smart irrigation
 - Agriculture robot
- Retail and Catering
 - POS machines
 - Service robot
- Audio Device
 - Internet music players
 - Live streaming devices
 - Internet radio players
- Generic Low-power IoT Sensor Hubs
- Generic Low-power IoT Data Loggers

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ESP32-C3 Series Comparison

ESP32-C3 Series Nomenclature

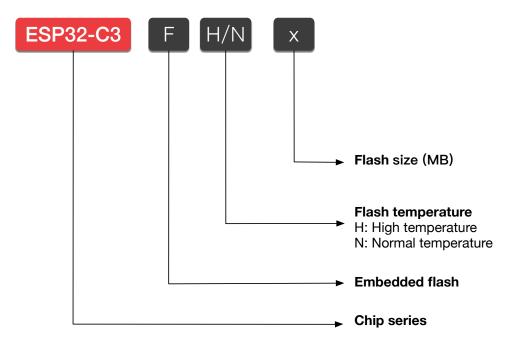


Figure 2: ESP32-C3 Series Nomenclature

1.2 Comparison

Table 1: ESP32-C3 Series Comparison

Ordering Code	Embedded Flash	Ambient Temperature (°C)	Package (mm)
ESP32-C3	_	− 40 ~ 105	QFN32 (5*5)
ESP32-C3FN4	4 MB	− 40 ~ 85	QFN32 (5*5)
ESP32-C3FH4	4 MB	− 40 ~ 105	QFN32 (5*5)

2. Pin Definition

2.1 Pin Layout

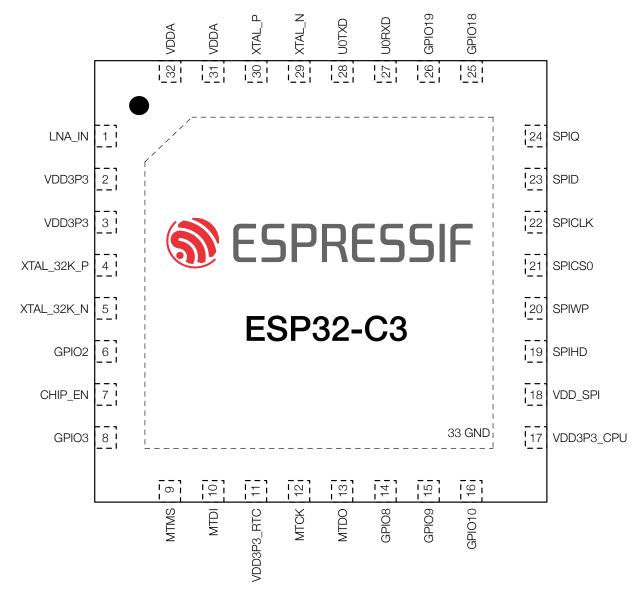


Figure 3: ESP32-C3 Pin Layout (Top View)

2.2 Pin Description

Table 2: Pin Description

Name	No.	Type	Power Domain	Function	
LNA_IN	1	I/O	_	RF input and output	
VDD3P3	2	P_A	_	Analog power supply	
VDD3P3	3	P_A	_	Analog power supply	
XTAL_32K_P	4	I/O/T	VDD3P3_RTC	GPIOO, ADC1_CH0, XTAL_32K_P	
XTAL_32K_N	5	I/O/T	VDD3P3_RTC	GPIO1, ADC1_CH1, XTAL_32K_N	
GPIO2	6	I/O/T	VDD3P3_RTC	GPIO2, ADC1_CH2, FSPIQ	

Name	No.	Туре	Power Domain	Function		
				High: on, enables the chip.		
CHIP_EN	7	l	VDD3P3_RTC	Low: off, the chip powers off.		
				Note: Do not leave the CHIP_EN pin floating.		
GPIO3	8	I/O/T	VDD3P3_RTC	GPIO3, ADC1_CH3		
MTMS	9	I/O/T	VDD3P3_RTC	GPIO4, ADC1_CH4, FSPIHD, MTMS		
MTDI	10	I/O/T	VDD3P3_RTC	GPIO5, ADC2_CH0, FSPIWP, MTDI		
VDD3P3_RTC	11	P_D	_	Input power supply for RTC		
MTCK	12	I/O/T	VDD3P3_CPU	GPIO6, FSPICLK, MTCK		
MTDO	13	I/O/T	VDD3P3_CPU	GPIO7, FSPID, MTDO		
GPIO8	14	I/O/T	VDD3P3_CPU	GPIO8		
GPIO9	15	I/O/T	VDD3P3_CPU	GPIO9		
GPIO10	16	I/O/T	VDD3P3_CPU	GPIO10, FSPICS0		
VDD3P3_CPU	17	P_D	_	Input power supply for CPU IO		
VDD_SPI	18	I/O/T/P _D	VDD3P3_CPU	GPIO11, output power supply for flash		
SPIHD	19	I/O/T	VDD3P3_CPU	GPIO12, SPIHD		
SPIWP	20	I/O/T	VDD3P3_CPU	GPIO13, SPIWP		
SPICS0	21	I/O/T	VDD3P3_CPU	GPIO14, SPICS0		
SPICLK	22	I/O/T	VDD3P3_CPU	GPIO15, SPICLK		
SPID	23	I/O/T	VDD3P3_CPU	GPIO16, SPID		
SPIQ	24	I/O/T	VDD3P3_CPU	GPIO17, SPIQ		
GPIO18	25	I/O/T	VDD3P3_CPU	GPIO18, USB_D-		
GPIO19	26	I/O/T	VDD3P3_CPU	GPIO19, USB_D+		
U0RXD	27	I/O/T	VDD3P3_CPU	GPIO20, U0RXD		
U0TXD	28	I/O/T	VDD3P3_CPU	GPIO21, U0TXD		
XTAL_N	29			External crystal output		
XTAL_P	30	_	_	External crystal input		
VDDA	31	P_A		Analog power supply		
VDDA	32	P_A	_	Analog power supply		
GND	33	G	_	Ground		

¹ P_A : analog power supply; P_D : power supply for RTC IO; I: input; O: output; T: high impedance.

- CS# = SPICS0
- IO0/DI = SPID
- IO1/DO = SPIQ
- CLK = SPICLK
- IO2/WP# = SPIWP
- IO3/HOLD# = SPIHD

These pins are not recommended for other uses.

² Pin functions in bold font are the default pin functions in SPI boot mode.

³ Ports of embedded flash correspond to pins of ESP32-C3FN4 and ESP32-C3FH4 as follows:

⁴ For the data port connection between ESP32-C3 and external flash please refer to Section 3.4.2 *Serial Peripheral Interface (SPI)*.

⁵ The pin function in this table refers only to some fixed settings and do not cover all cases for signals that can be input and output through the GPIO matrix. For more information on the GPIO matrix, please refer to Chapter IO MUX and GPIO Matrix (GPIO, IO_MUX) in <u>ESP32-C3 Technical Reference Manual</u>.

2.3 Power Scheme

ESP32-C3 has four input power pins:

- VDDA1
- VDDA2
- VDD3P3_RTC
- VDD3P3_CPU

And one input/output power pin:

• VDD_SPI

VDDA1 and VDDA2 are the input power supply for the analog domain.

When working as an output power supply, VDD_SPI can be powered by VDD3P3_CPU via R_{SPI} (nominal 3.3 V). VDD_SPI can be powered off via software to minimize the current leakage of flash in Deep-sleep mode.

RTC IO is powered from VDD3P3_RTC.

The RTC domain is powered from Low Power Voltage Regulator, which is powered from VDD3P3_RTC.

The Digital System domain is powered from Digital System Voltage Regulator, which is powered from VDD3P3_CPU and VDD3P3_RTC at the same time.

Digital IO is powered from VDD3P3_CPU.

The power scheme diagram is shown in Figure 4.

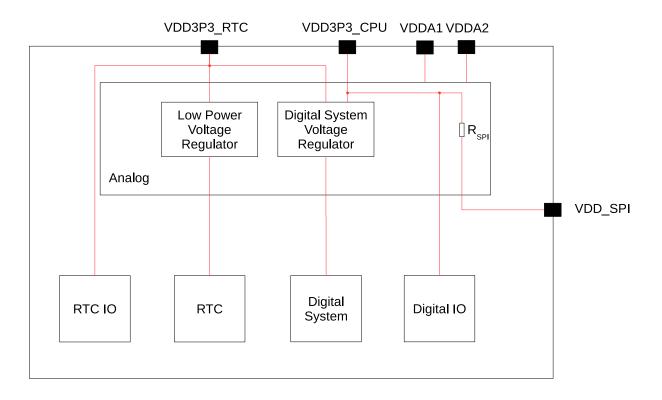


Figure 4: ESP32-C3 Power Scheme

Notes on CHIP_EN:

Figure 5 shows the power-up and reset timing of ESP32-C3. Details about the parameters are listed in Table

3.

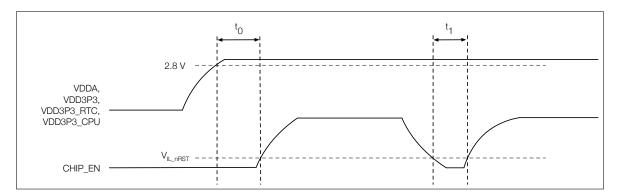


Figure 5: ESP32-C3 Power-up and Reset Timing

Table 3: Description of ESP32-C3 Power-up and Reset Timing Parameters

Parameter	Parameter Description		
+	Time between bringing up the VDDA, VDD3P3, VDD3P3_RTC, and	50	
t_0	VDD3P3_CPU rails, and activating CHIP_EN		
+	Duration of CHIP_EN signal level $<$ V_{IL_nRST} (refer to its value in	50	
t ₁	Table 14) to reset the chip	50	

2.4 Strapping Pins

ESP32-C3 has three strapping pins:

- GPIO2
- GPI08
- GPI09

Software can read the values of GPIO2, GPIO8 and GPIO9 from GPIO_STRAPPING field in GPIO_STRAP_REG register. For register description, please refer to Section GPIO Matrix Register Summary in ESP32-C3 Technical Reference Manual.

During the chip's system reset, the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down.

Types of system reset include:

- power-on reset
- RTC watchdog reset
- brownout reset
- analog super watchdog reset
- crystal clock glitch detection reset

By default, GPIO9 is connected to the internal weak pull-up resistor. If GPIO9 is not connected or connected to an external high-impedance circuit, the latched bit value will be "1"

To change the strapping bit values, you can apply the external pull-down/pull-up resistances, or use the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32-C3.

After reset, the strapping pins work as normal-function pins.

Table 4 lists detailed booting configurations of the strapping pins.

Table 4: Strapping Pins

	Booting Mode ¹						
Pin Default		SPI Boot	Download Boot				
GPIO2	N/A	1	1				
GPIO8	N/A	Don't care	1				
GPIO9	Internal weak	4	0				
GFIO9	pull-up		0				
	Enabling/Disabling ROM Messages Print During Booting						
Pin	Pin Default Functionality						
		When the value of eFuse field EFUS	E_UART_PRINT_CONTROL is				
	GPIO8 N/A	0 (default), print is enabled and not controlled by GPIO8.					
GPIO8		1, if GPIO8 is 0, print is enabled; if GPIO8 is 1, it is disabled.					
		2, if GPIO8 is 0, print is disabled; if GPIO8 is 1, it is enabled.					
		3, print is disabled and not controlle	ed by GPIO8.				

¹ The strapping combination of GPIO8 = 0 and GPIO9 = 0 is invalid and will trigger unexpected behavior.

Figure 6 shows the setup and hold times for the strapping pins before and after the CHIP_EN signal goes high. Details about the parameters are listed in Table 5.

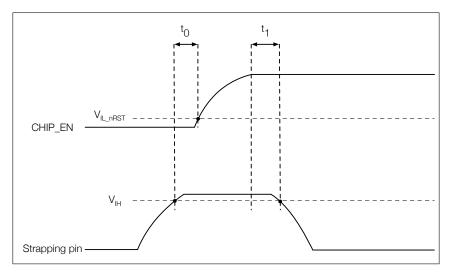


Figure 6: Setup and Hold Times for the Strapping Pins

Table 5: Parameter Descriptions of Setup and Hold Times for the Strapping Pins

Parameter	Description	Min (ms)
t_0	Setup time before CHIP_EN goes from low to high	0
t_1	Hold time after CHIP_EN goes high	3

3. Functional Description

This chapter describes the functions of ESP32-C3.

3.1 CPU and Memory

3.1.1 CPU

ESP32-C3 has a low-power 32-bit RISC-V single-core microprocessor with the following features:

- four-stage pipeline that supports a clock frequency of up to 160 MHz
- RV32IMC ISA
- 32-bit multiplier and 32-bit divider
- up to 32 vectored interrupts at seven priority levels
- up to 8 hardware breakpoints/watchpoints
- up to 16 PMP regions
- JTAG for debugging

3.1.2 Internal Memory

ESP32-C3's internal memory includes:

- 384 KB of ROM: for booting and core functions.
- 400 KB of on-chip SRAM: for data and instructions, running at a configurable frequency of up to 160 MHz. Of the 400 KB SRAM, 16 KB is configured for cache.
- RTC FAST memory: 8 KB of SRAM that can be accessed by the main CPU. It can retain data in Deep-sleep mode.
- 4 Kbit of eFuse: 1792 bits are reserved for your data, such as encryption key and device ID.
- Embedded flash: See details in Chapter 1 ESP32-C3 Series Comparison.

3.1.3 External Flash

ESP32-C3 supports SPI, Dual SPI, Quad SPI, and QPI interfaces that allow connection to multiple external flash.

CPU's instruction memory space and read-only data memory space can map into external flash of ESP32-C3, whose size can be 16 MB at most. ESP32-C3 supports hardware encryption/decryption based on XTS-AES to protect developers' programs and data in flash.

Through high-speed caches, ESP32-C3 can support at a time up to:

- 8 MB of instruction memory space which can map into flash as individual blocks of 64 KB. 8-bit, 16-bit and 32-bit reads are supported.
- 8 MB of data memory space which can map into flash as individual blocks of 64 KB. 8-bit, 16-bit and 32-bit reads are supported.

Note:

After ESP32-C3 is initialized, software can customize the mapping of external flash into the CPU address space.

3.1.4 Address Mapping Structure

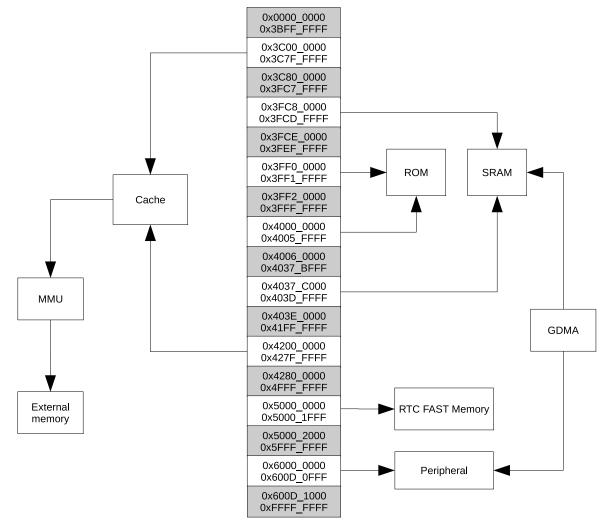


Figure 7: Address Mapping Structure

Note:

The memory space with gray background is not available for use.

3.1.5 Cache

ESP32-C3 has an eight-way set associative cache. This cache is read-only and has the following features:

• size: 16 KB

• block size: 32 bytes

pre-load function

• lock function

critical word first and early restart

3.2 System Clocks

3.2.1 CPU Clock

The CPU clock has three possible sources:

- external main crystal clock
- fast RC oscillator (typically about 17.5 MHz, and adjustable)
- PLL clock

The application can select the clock source from the three clocks above. The selected clock source drives the CPU clock directly, or after division, depending on the application. Once the CPU is reset, the default clock source would be the external main crystal clock divided by 2.

3.2.2 RTC Clock

The RTC slow clock is used for RTC counter, RTC watchdog and low-power controller. It has three possible sources:

- external low-speed (32 kHz) crystal clock
- internal slow RC oscillator (typically about 136 kHz, and adjustable)
- internal fast RC oscillator divided clock (derived from the fast RC oscillator divided by 256)

The RTC fast clock is used for RTC peripherals and sensor controllers. It has two possible sources:

- external main crystal clock divided by 2
- internal fast RC oscillator divide-by-N clock (typically about 17.5 MHz, and adjustable)

3.3 Analog Peripherals

3.3.1 Analog-to-Digital Converter (ADC)

ESP32-C3 integrates two 12-bit SAR ADCs.

- ADC1 supports measurements on 5 channels, and is factory-calibrated.
- ADC2 supports measurements on 1 channel, and is not factory-calibrated.

For ADC characteristics, please refer to Table 15.

3.3.2 Temperature Sensor

The temperature sensor generates a voltage that varies with temperature. The voltage is internally converted via an ADC into a digital value.

The temperature sensor has a range of –40 °C to 125 °C. It is designed primarily to sense the temperature changes inside the chip. The temperature value depends on factors like microcontroller clock frequency or I/O load. Generally, the chip's internal temperature is higher than the operating ambient temperature.

3.4 Digital Peripherals

3.4.1 General Purpose Input / Output Interface (GPIO)

ESP32-C3 has 22 GPIO pins which can be assigned various functions by configuring corresponding registers. Besides digital signals, some GPIOs can be also used for analog functions, such as ADC.

All GPIOs have selectable internal pull-up or pull-down, or can be set to high impedance. When these GPIOs are configured as an input, the input value can be read by software through the register. Input GPIOs can also be set to generate edge-triggered or level-triggered CPU interrupts. All digital IO pins are bi-directional, non-inverting and tristate, including input and output buffers with tristate control. These pins can be multiplexed with other functions, such as the UART, SPI, etc. For low-power operations, the GPIOs can be set to holding state.

The IO MUX and the GPIO matrix are used to route signals from peripherals to GPIO pins. Together they provide highly configurable I/O. Using GPIO Matrix, peripheral input signals can be configured from any IO pins while peripheral output signals can be configured to any IO pins. Table 6 shows the IO MUX functions of each pin. For more information about IO MUX and GPIO matrix, please refer to Chapter IO MUX and GPIO Matrix (GPIO, IO_MUX) in ESP32-C3 Technical Reference Manual.

Name No. Function 0 Function 1 Function 2 Reset **Notes** XTAL_32K_P 4 GPI00 R GPI00 0 XTAL_32K_N 5 GPIO1 0 R GPIO1 GPIO2 6 GPIO2 GPIO2 **FSPIQ** 1 R GPIO3 8 GPIO3 1 R GPIO3 **MTMS** 9 **MTMS** GPIO4 **FSPIHD** 1 R MTDI 10 MTDI GPIO5 **FSPIWP** 1 R 12 1* GPIO6 G **MTCK MTCK FSPICLK MTDO** 13 **MTDO** GPIO7 **FSPID** 1 G GPIO8 14 GPIO8 GPIO8 1 GPIO9 15 GPIO9 3 GPI09 GPIO10 16 **GPIO10** GPIO10 FSPICS0 1 G VDD SPI 18 **GPIO11** GPIO11 0 **SPIHD** 19 **SPIHD** GPIO12 3 **SPIWP** 20 **SPIWP** 3 **GPIO13** SPICS0 21 SPICS0 GPIO14 3 **SPICLK** 22 **SPICLK** GPIO15 3 **SPID** 23 SPID GPIO16 3 **SPIQ** SPIQ GPIO17 3 24 USB, G **GPIO18** 25 **GPIO18** GPIO18 0 **GPIO19 GPIO19** 0* **USB** 26 GPIO19 3 **UORXD** 27 **UORXD** GPIO20 G 28 4 **UOTXD U0TXD GPIO21**

Table 6: IO MUX Pin Functions

Reset

The default configuration of each pin after reset:

- 0 input disabled, in high impedance state (IE = 0)
- 1 input enabled, in high impedance state (IE = 1)
- 2 input enabled, pull-down resistor enabled (IE = 1, WPD = 1)
- 3 input enabled, pull-up resistor enabled (IE = 1, WPU = 1)
- 4 output enabled, pull-up resistor enabled (OE = 1, WPU = 1)

- 0* input disabled, pull-up resistor enabled (IE = 0, WPU = 0, USB WPU = 1). See details in Notes
- 1* When the value of eFuse bit EFUSE_DIS_PAD_JTAG is
 - 0, input enabled, pull-up resistor enabled (IE = 1, WPU = 1)
 - 1, input enabled, in high impedance state (IE = 1)

We recommend pulling high or low GPIO pins in high impedance state to avoid unnecessary power consumption. You may add pull-up and pull-down resistors in your PCB design referring to Table 14, or enable internal pull-up and pull-down resistors during software initialization.

Notes

- R These pins have analog functions.
- USB GPIO18 and GPIO19 are USB pins. The pull-up value of a USB pin is controlled by the pin's pull-up value together with USB pull-up value. If any of the two pull-up values is 1, the pin's pull-up resistor will be enabled. The pull-up resistors of USB pins are controlled by USB_SERIAL_JTAG_DP_PULLUP bit.
- G These pins have glitches during power-up. See details in Table 7.

		Typical Time Period
Pin	Glitch ¹	(ns)
MTCK	Low-level glitch	5
MTDO	Low-level glitch	5
GPIO10	Low-level glitch	5
U0RXD	Low-level glitch	5
GPIO18	Pull-up glitch	50000

Table 7: Power-Up Glitches on Pins

3.4.2 Serial Peripheral Interface (SPI)

ESP32-C3 features three SPI interfaces (SPI0, SPI1, and SPI2). SPI0 and SPI1 can only be configured to operate in SPI memory mode, while SPI2 can be configured to operate in both SPI memory and general-purpose SPI modes.

SPI Memory mode

In SPI memory mode, SPI0, SPI1 and SPI2 interface with external SPI memory. Data is transferred in bytes. Up to four-line STR reads and writes are supported. The clock frequency is configurable to a maximum of 120 MHz in STR mode.

• SPI2 General-purpose SPI (GP-SPI) mode

When SPI2 acts as a general-purpose SPI, it can operate in master and slave modes. SPI2 supports two-line full-duplex communication and single-/two-/four-line half-duplex communication in both master and slave modes. The host's clock frequency is configurable. Data is transferred in bytes. The clock polarity (CPOL) and phase (CPHA) are also configurable. The SPI2 interface can connect to GDMA.

 In master mode, the clock frequency is 80 MHz at most, and the four modes of SPI transfer format are supported.

¹ Low-level glitch: the pin is at a low level during the time period; High-level glitch: the pin is at a high level during the time period; Pull-up glitch: the pin is pulled up during the time period; Pull-down glitch: the pin is pulled down during the time period.

- In slave mode, the clock frequency is 60 MHz at most, and the four modes of SPI transfer format are also supported.

The mapping between SPI bus signals and GPIO pins is shown in Table 8:

Table 8: Mapping of SPI Signals and Chip Pads

Full-Duplex	Half-Duplex	Chip Pin Signal		
SPI Signal	SPI Signal	Pin Function	FSPI Signals	
MOSI	MOSI	D	FSPID	
MISO	(MISO)	Q	FSPIQ	
CS	CS	CS	FSPICS0 ~ 5	
CLK	CLK	CLK	FSPICLK	
_	_	WP	FSPIWP	
_	_	HD	FSPIHD	

In most cases, the data port connection between ESP32-C3 and external flash is as follows:

Table 9: Connection Between ESP32-C3 and External Flash

	External Flash Data Port					
Chip Pin	SPI Single-Line Mode	SPI Two-Line Mode	SPI Four-Line Mode			
SPID (SPID)	DI	100	100			
SPIQ (SPIQ)	DO	IO1	IO1			
SPIWP (SPIWP)	WP#	_	IO2			
SPIHD (SPIHD)	HOLD#	_	IO3			

3.4.3 Universal Asynchronous Receiver Transmitter (UART)

ESP32-C3 has two UART interfaces, i.e. UART0 and UART1, which support IrDA and asynchronous communication (RS232 and RS485) at a speed of up to 5 Mbps. The UART controller provides hardware flow control (CTS and RTS signals) and software flow control (XON and XOFF). Both UART interfaces connect to GDMA via UHCIO, and can be accessed by the GDMA controller or directly by the CPU.

3.4.4 I2C Interface

ESP32-C3 has an I2C bus interface which is used for I2C master mode or slave mode, depending on your configuration. The I2C interface supports:

- standard mode (100 Kbit/s)
- fast mode (400 Kbit/s)
- up to 800 Kbit/s (constrained by SCL and SDA pull-up strength)
- 7-bit and 10-bit addressing mode
- double addressing mode
- 7-bit broadcast address

You can configure instruction registers to control the I2C interface for more flexibility.

3.4.5 I2S Interface

ESP32-C3 includes a standard I2S interface. This interface can operate as a master or a slave in full-duplex mode or half-duplex mode, and can be configured for 8-bit, 16-bit, 24-bit, or 32-bit serial communication. BCK clock frequency, from 10 kHz up to 40 MHz, is supported.

The I2S interface supports TDM PCM, TDM MSB alignment, TDM standard, and PDM TX interface. It connects to the GDMA controller.

3.4.6 Remote Control Peripheral

The Remote Control Peripheral (RMT) supports two channels of infrared remote transmission and two channels of infrared remote reception. By controlling pulse waveform through software, it supports various infrared and other single wire protocols. All four channels share a 192×32 -bit memory block to store transmit or receive waveform.

3.4.7 LED PWM Controller

The LED PWM controller can generate independent digital waveform on six channels. The LED PWM controller:

- can generate digital waveform with configurable periods and duty cycle. The accuracy of duty cycle can be
 up to 18 bits.
- has multiple clock sources, including APB clock and external main crystal clock.
- can operate when the CPU is in Light-sleep mode.
- supports gradual increase or decrease of duty cycle, which is useful for the LED RGB color-gradient generator.

3.4.8 General DMA Controller

ESP32-C3 has a general DMA controller (GDMA) with six independent channels, i.e. three transmit channels and three receive channels. These six channels are shared by peripherals with DMA feature. The GDMA controller implements a fixed-priority scheme among these channels, whose priority can be configured.

The GDMA controller controls data transfer using linked lists. It allows peripheral-to-memory and memory-to-memory data transfer at a high speed. All channels can access internal RAM.

Peripherals on ESP32-C3 with DMA feature are SPI2, UHCl0, I2S, AES, SHA, and ADC.

3.4.9 USB Serial/JTAG Controller

ESP32-C3 integrates a USB Serial/JTAG controller. This controller has the following features:

- USB 2.0 full speed compliant, capable of up to 12 Mbit/s transfer speed (Note that this controller does not support the faster 480 Mbit/s high-speed transfer mode)
- CDC-ACM virtual serial port and JTAG adapter functionality
- programming embedded/external flash
- CPU debugging with compact JTAG instructions
- a full-speed USB PHY integrated in the chip

3.4.10 TWAI® Controller

ESP32-C3 has a TWAI® controller with the following features:

- compatible with ISO 11898-1 protocol (CAN Specification 2.0)
- standard frame format (11-bit ID) and extended frame format (29-bit ID)
- bit rates from 1 Kbit/s to 1 Mbit/s
- multiple modes of operation: Normal, Listen Only, and Self-Test (no acknowledgment required)
- 64-byte receive FIFO
- acceptance filter (single and dual filter modes)
- error detection and handling: error counters, configurable error interrupt threshold, error code capture, arbitration lost capture

3.5 Radio and Wi-Fi

ESP32-C3 radio consists of the following blocks:

- 2.4 GHz receiver
- 2.4 GHz transmitter
- bias and regulators
- balun and transmit-receive switch
- · clock generator

3.5.1 2.4 GHz Receiver

The 2.4 GHz receiver demodulates the 2.4 GHz RF signal to quadrature baseband signals and converts them to the digital domain with two high-resolution, high-speed ADCs. To adapt to varying signal channel conditions, ESP32-C3 integrates RF filters, Automatic Gain Control (AGC), DC offset cancelation circuits, and baseband filters.

3.5.2 2.4 GHz Transmitter

The 2.4 GHz transmitter modulates the quadrature baseband signals to the 2.4 GHz RF signal, and drives the antenna with a high-powered CMOS power amplifier. The use of digital calibration further improves the linearity of the power amplifier.

Additional calibrations are integrated to cancel any radio imperfections, such as:

- carrier leakage
- I/Q amplitude/phase matching
- · baseband nonlinearities
- RF nonlinearities
- antenna matching

These built-in calibration routines reduce the cost, time, and specialized equipment required for product testing.

3.5.3 Clock Generator

The clock generator produces quadrature clock signals of 2.4 GHz for both the receiver and the transmitter. All components of the clock generator are integrated into the chip, including inductors, varactors, filters, regulators and dividers.

The clock generator has built-in calibration and self-test circuits. Quadrature clock phases and phase noise are optimized on chip with patented calibration algorithms which ensure the best performance of the receiver and the transmitter.

3.5.4 Wi-Fi Radio and Baseband

ESP32-C3 Wi-Fi radio and baseband support the following features:

- 802.11b/g/n
- 802.11n MCS0-7 that supports 20 MHz and 40 MHz bandwidth
- 802.11n MCS32
- 802.11n 0.4 μs guard interval
- data rate up to 150 Mbps
- RX STBC (single spatial stream)
- adjustable transmitting power
- antenna diversity ESP32-C3 supports antenna diversity with an external RF switch. This switch is controlled by one or more GPIOs, and used to select the best antenna to minimize the effects of channel imperfections.

3.5.5 Wi-Fi MAC

ESP32-C3 implements the full 802.11 b/g/n Wi-Fi MAC protocol. It supports the Basic Service Set (BSS) STA and SoftAP operations under the Distributed Control Function (DCF). Power management is handled automatically with minimal host interaction to minimize the active duty period.

ESP32-C3 Wi-Fi MAC applies the following low-level protocol functions automatically:

- 4 × virtual Wi-Fi interfaces
- infrastructure BSS in Station mode, SoftAP mode, Station + SoftAP mode, and promiscuous mode
- RTS protection, CTS protection, Immediate Block ACK
- fragmentation and defragmentation
- TX/RX A-MPDU, TX/RX A-MSDU
- transmit opportunity (TXOP)
- Wi-Fi multimedia (WMM)
- GCMP, CCMP, TKIP, WAPI, WEP, BIP, WPA2-PSK/WPA2-Enterprise, and WPA3-PSK/WPA3-Enterprise
- automatic beacon monitoring (hardware TSF)
- 802.11mc FTM

3.5.6 Networking Features

Espressif provides libraries for TCP/IP networking, ESP-WIFI-MESH networking, and other networking protocols over Wi-Fi. TLS 1.0, 1.1 and 1.2 is also supported.

3.6 Bluetooth LE

ESP32-C3 includes a Bluetooth Low Energy subsystem that integrates a hardware link layer controller, an RF/modem block and a feature-rich software protocol stack. It supports the core features of Bluetooth 5 and Bluetooth mesh.

3.6.1 Bluetooth LE Radio and PHY

Bluetooth Low Energy radio and PHY in ESP32-C3 support:

- 1 Mbps PHY
- 2 Mbps PHY for higher data rates
- coded PHY for longer range (125 Kbps and 500 Kbps)
- listen before talk (LBT), implemented in hardware
- antenna diversity with an external RF switch

 This switch is controlled by one or more GPIOs, and used to select the best antenna to minimize the effects of channel imperfections.

3.6.2 Bluetooth LE Link Layer Controller

Bluetooth Low Energy Link Layer Controller in ESP32-C3 supports:

- · LE advertising extensions, to enhance broadcasting capacity and broadcast more intelligent data
- multiple advertisement sets
- simultaneous advertising and scanning
- multiple connections in simultaneous central and peripheral roles
- · adaptive frequency hopping and channel assessment
- LE channel selection algorithm #2
- connection parameter update
- high duty cycle non-connectable advertising
- LE privacy 1.2
- LE data packet length extension
- link layer extended scanner filter policies
- low duty cycle directed advertising
- link layer encryption
- LE Ping

3.7 Low Power Management

With the use of advanced power-management technologies, ESP32-C3 can switch between different power modes.

- · Active mode: CPU and chip radio are powered on. The chip can receive, transmit, or listen.
- Modem-sleep mode: The CPU is operational and the clock speed can be reduced. Wi-Fi base band, Bluetooth LE base band, and radio are disabled, but Wi-Fi and Bluetooth LE connection can remain active.
- Light-sleep mode: The CPU is paused. Any wake-up events (MAC, host, RTC timer, or external interrupts) will wake up the chip. Wi-Fi and Bluetooth LE connection can remain active.
- Deep-sleep mode: CPU and most peripherals are powered down. Only the RTC memory is powered on. Wi-Fi connection data are stored in the RTC memory.

For power consumption in different power modes, please refer to Table 17.

3.8 Timers

3.8.1 General Purpose Timers

ESP32-C3 is embedded with two 54-bit general-purpose timers, which are based on 16-bit prescalers and 54-bit auto-reload-capable up/down-timers.

The timers' features are summarized as follows:

- a 16-bit clock prescaler, from 1 to 65536
- a 54-bit time-base counter programmable to be incrementing or decrementing
- able to read real-time value of the time-base counter
- halting and resuming the time-base counter
- programmable alarm generation
- level interrupt generation

3.8.2 System Timer

ESP32-C3 integrates a 52-bit system timer, which has two 52-bit counters and three comparators. The system timer has the following features:

- counters with a fixed clock frequency of 16 MHz
- three types of independent interrupts generated according to alarm value
- two alarm modes: target mode and period mode
- 52-bit target alarm value and 26-bit periodic alarm value
- automatic reload of counter value
- counters can be stalled if the CPU is stalled or in OCD mode

3.8.3 Watchdog Timers

ESP32-C3 contains three watchdog timers: one in each of the two timer groups (called Main System Watchdog Timers, or MWDT) and one in the RTC module (called the RTC Watchdog Timer, or RWDT).

During the flash boot process, RWDT and the MWDT in timer group 0 (TIMG0) are enabled automatically in order to detect and recover from booting errors.

Watchdog timers have the following features:

- four stages, each with a programmable timeout value. Each stage can be configured, enabled and disabled separately
- interrupt, CPU reset, or core reset for MWDT upon expiry of each stage; interrupt, CPU reset, core reset, or system reset for RWDT upon expiry of each stage
- 32-bit expiry counter
- · write protection, to prevent RWDT and MWDT configuration from being altered inadvertently
- flash boot protection
 If the boot process from an SPI flash does not complete within a predetermined period of time, the watchdog will reboot the entire main system.

3.9 Cryptographic Hardware Accelerators

ESP32-C3 is equipped with hardware accelerators of general algorithms, such as AES-128/AES-256 (FIPS PUB 197), ECB/CBC/OFB/CFB/CTR (NIST SP 800-38A), SHA1/SHA224/SHA256 (FIPS PUB 180-4), and RSA3072. The chip also supports independent arithmetic, such as Big Integer Multiplication and Big Integer Modular Multiplication. The maximum operation length for RSA and Big Integer Modular Multiplication is 3072 bits. The maximum factor length for Big Integer Multiplication is 1536 bits.

3.10 Physical Security Features

- Transparent external flash encryption (AES-XTS algorithm) with software inaccessible key prevents unauthorized readout of your application code or data.
- Secure boot feature uses a hardware root of trust to ensure only signed firmware (with RSA-PSS signature)
 can be booted.
- HMAC module can use a software inaccessible MAC key to generate MAC signatures for identity verification and other purposes.
- Digital Signature module can use a software inaccessible secure key to generate RSA signatures for identity verification.
- World Controller provides two running environments for software. All hardware and software resources are sorted to two groups, and placed in either secure or general world. The secure world cannot be accessed by hardware in the general world, thus establishing a security boundary.

3.11 Peripheral Pin Configurations

Table 10: Peripheral Pin Configurations

Interface	Signal	Pin	Function
ADC	ADC1_CH0	XTAL_32K_P	Two 12-bit SAR ADCs
	ADC1_CH1	XTAL_32K_N	
	ADC1_CH2	GPIO2	

Interface	Signal	Pin	Function
	ADC1_CH3	GPIO3	
	ADC1_CH4	MTMS	
	ADC2_CH0	MTDI	
JTAG	MTDI	MTDI	JTAG for software debugging
	MTCK	MTCK	
	MTMS	MTMS	
	MTDO	MTDO	
UART	U0RXD_in	Any GPIO pins	Two UART channels with hardware flow control
	U0CTS_in		and GDMA
	U0DSR_in		
	U0TXD_out	1	
	U0RTS_out	1	
	U0DTR_out		
	U1RXD_in	1	
	U1CTS_in	1	
	U1DSR_in	1	
	U1TXD_out	1	
	U1RTS_out	1	
	U1DTR_out		
I2C	I2CEXTO_SCL_in	Any GPIO pins	One I2C channel in slave or master mode
	I2CEXTO_SDA_in		
	I2CEXT1_SCL_in		
	I2CEXT1_SDA_in		
	I2CEXTO_SCL_out		
	I2CEXT0_SDA_out		
	I2CEXT1_SCL_out		
	I2CEXT1_SDA_out	1	
LED PWM	ledc_ls_sig_out0~5	Any GPIO pins	Six independent PWM channels
I2S	I2S0O_BCK_in	Any GPIO pins	Stereo input and output from/to the audiocodec
	I2S_MCLK_in		
	I2SO_WS_in		
	I2SI_SD_in		
	I2SI_BCK_in		
	I2SI_WS_in	1	
	I2SO_BCK_out		
	I2S_MCLK_out	1	
	I2SO_WS_out	1	
	I2SO_SD_out	1	
	I2SI_BCK_out	1	
	I2SI_WS_out	1	
	I2SO_SD1_out	1	
Remote Control	RMT_SIG_IN0~1	Any GPIO pins	Two channels for an IR transceiver of various
Peripheral	RMT_SIG_OUT0~1]	waveforms

Interface	Signal	Pin	Function
SPI0/1	SPICLK_out_mux	SPICLK	Support Standard SPI, Dual SPI, Quad SPI, and
	SPICS0_out	SPICS0	QPI that allow connection to external flash
	SPICS1_out	Any GPIO pins	
	SPID_in/_out	SPID	
	SPIQ_in/_out	SPIQ	
	SPIWP_in/_out	SPIWP	
	SPIHD_in/_out	SPIHD	
SPI2	FSPICLK_in/_out_mux	Any GPIO pins	Master mode and slave mode of SPI, Dual
	FSPICS0_in/_out		SPI, Quad SPI, and QPI
	FSPICS1~5_out		 Connection to external flash, RAM, and
	FSPID_in/_out		other SPI devices
	FSPIQ_in/_out		Four modes of SPI transfer format
	FSPIWP_in/_out		Configurable SPI frequency
	FSPIHD_in/_out		64-byte FIFO or GDMA buffer
USB Serial/JTAG	USB_D+	GPIO19	USB-to-serial converter, and USB-to-JTAG
	USB_D-	GPIO18	converter
TWAI	twai_rx	Any GPIO pins	Compatible with ISO 11898-1 protocol
	twai_tx		
	twai_bus_off_on		
	twai_clkout		

Electrical Characteristics

4.1 **Absolute Maximum Ratings**

Stresses beyond the absolute maximum ratings listed in the table below may cause permanent damage to the device. These are stress ratings only, and do not refer to the functional operation of the device.

Table 11: Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit
VDDA, VDD3P3, VDD3P3_RTC,	Voltage applied to power supply pins	-0.3	3.6	\/
VDD3P3_CPU, VDD_SPI	per power domain	-0.3	3.0	V
T_{STORE}	Storage temperature	-40	150	°C

Recommended Operating Conditions

Table 12: Recommended Operating Conditions

Symbol	Parameter	Parameter		Тур	Max	Unit
VDDA, VDD3P3		ower supply pins per	3.0	3.3	3.6	V
VDD3P3_RTC	power domain					
VDD_SPI (working as			3.0	3.3	3.6	V
input power supply)1			0.0	5.	0.0	V
VDD3P3_CPU ^{2, 3}	Voltage applied to p	ower supply pin	3.0	3.3	3.6	V
I_{VDD}^{4}	Current delivered by	external power supply	0.5			А
	Operating ambient	ESP32-C3			105	
$ T_A $	temperature -	ESP32-C3FN4	-40	_	85	°C
		ESP32-C3FH4			105	

¹ For more information, please refer to Section 2.3 *Power Scheme*.

4.3 VDD_SPI Output Characteristics

Table 13: VDD_SPI Output Characteristics

Symbol	Parameter	Тур	Unit
R_{SPI}	On-resistance in 3.3 V mode	7.5	Ω

² When VDD_SPI is used to drive peripherals, VDD3P3_CPU should comply with the peripherals' specifications. For more information, please refer to Table 13.

³ To write eFuse, VDD3P3_CPU should not be higher than 3.3 V.

⁴ If you use a single power supply, the recommended output current is 500 mA or more.

Note:

In real-life applications, when VDD_SPI works in 3.3 V output mode, VDD3P3_CPU may be affected by R_{SPI} . For example, when VDD3P3_CPU is used to drive a 3.3 V flash, it should comply with the following specifications:

VDD3P3_CPU > VDD_flash_min + I_flash_max* R_{SPI}

Among which, VDD_flash_min is the minimum operating voltage of the flash, and I_flash_max the maximum current.

For more information, please refer to section 2.3 Power Scheme.

DC Characteristics (3.3 V, 25 °C)

Table 14: DC Characteristics (3.3 V, 25 °C)

Symbol	Parameter	Min	Тур	Max	Unit
C_{IN}	Pin capacitance	_	2	_	рF
V_{IH}	High-level input voltage	$0.75 \times VDD^1$	_	VDD ¹ + 0.3	V
V_{IL}	Low-level input voltage	-0.3	_	$0.25 \times VDD^1$	V
$ I_{IH} $	High-level input current	_	_	50	nA
$ I_{IL} $	Low-level input current	_	_	50	nA
V_{OH}^2	High-level output voltage	$0.8 \times VDD^1$	_	_	V
V_{OL}^2	Low-level output voltage	_	_	$0.1 \times VDD^1$	V
1	High-level source current (VDD1= 3.3 V,		40		mA
$ _{OH}$	$V_{OH} >= 2.64 \text{ V, PAD_DRIVER} = 3)$		40	_	
1	Low-level sink current (VDD 1 = 3.3 V, V $_{OL}$ =		28		mA
$ I_{OL} $	0.495 V, PAD_DRIVER = 3)		20		IIIA
R_{PU}	Pull-up resistor	_	45		kΩ
R_{PD}	Pull-down resistor	_	45	_	kΩ
V_{IH_nRST}	Chip reset release voltage	$0.75 \times VDD^1$	_	VDD ¹ + 0.3	V
V_{IL_nRST}	Chip reset voltage	-0.3	_	$0.25 \times VDD^1$	V

¹ VDD is the I/O voltage for a particular power domain of pins.

ADC Characteristics

Table 15: ADC Characteristics

Symbol	Parameter	Min	Max	Unit
DNL (Differential nonlinearity) ¹	ADC connected to an external	-7	7	LSB
DNE (Billerertial Horillinearity)	100 nF capacitor; DC signal input;	-1	1	LOD
INL (Integral nonlinearity)	ambient temperature at 25 °C;	-12	12	LSB
II VE (II REGIAI FIOTIIII learity)	Wi-Fi off	-12	12	LOD
Sampling rate	_		100	kSPS ²
	ATTEN0	0	750	mV
Effective Range	ATTEN1	0	1050	mV
Lifective Harige	ATTEN2	0	1300	mV
	ATTEN3	0	2500	mV

 $^{^2\,\}mathrm{V}_{OH}$ and V_{OL} are measured using high-impedance load.

4.6 Current Consumption

The current consumption measurements are taken with a 3.3 V supply at 25 °C of ambient temperature at the RF port. All transmitters' measurements are based on a 100% duty cycle.

Table 16: Current Consumption Depending on RF Modes

Work mode	Description		Description P		Peak (mA)
	TX	802.11b, 1 Mbps, @21 dBm	335		
		802.11g, 54 Mbps, @19 dBm	285		
		802.11n, HT20, MCS7, @18.5 dBm	276		
Active (RF working)		802.11n, HT40, MCS7, @18.5 dBm	278		
	DV	802.11b/g/n, HT20	84		
	RX	802.11n, HT40	87		

Table 17: Current Consumption Depending on Work Modes

Work mode	Description		Тур	Unit
Modem-sleep ^{1, 2}	The CPU is	160 MHz	20	mA
Modern-Sieep	powered on ³	80 MHz	15	mA
Light-sleep	_		130	μΑ
Deep-sleep	RTC timer + RTC memory		5	μΑ
Power off	CHIP_PU is set to low level, the chip is powered off		1	μΑ

¹ The current consumption figures in Modem-sleep mode are for cases where the CPU is powered on and the cache idle.

4.7 Reliability

Table 18: Reliability Qualifications

Test Item	Test Conditions	Test Standard	
HTOL (High Temperature	125 °C, 1000 hours	JESD22-A108	
Operating Life)	123 0, 1000 hours	JESD22-A100	
ESD (Electro-Static	HBM (Human Body Mode) ¹ ± 2000 V	JS-001	
Discharge Sensitivity)	CDM (Charge Device Mode) ² ± 1000 V	JS-002	
Latch up	Current trigger ± 200 mA	JESD78	
Latorrup	Voltage trigger 1.5 × VDD $_{max}$	JLODIO	

¹ To get better DNL results, you can sample multiple times and apply a filter, or calculate the average value.

² kSPS means kilo samples-per-second.

² When Wi-Fi is enabled, the chip switches between Active and Modem-sleep modes. Therefore, current consumption changes accordingly.

³ In Modem-sleep mode, the CPU frequency changes automatically. The frequency depends on the CPU load and the peripherals used.

Table 18 - cont'd from previous page

Test Item	Test Conditions	Test Standard
	Bake 24 hours @125 °C	J-STD-020, JESD47,
Preconditioning	Moisture soak (level 3: 192 hours @30 °C, 60% RH)	JESD22-A113
	IR reflow solder: 260 + 0 °C, 20 seconds, three times	JLODZZ-ATTO
TCT (Temperature Cycling	_65 °C / 150 °C, 500 cycles	JESD22-A104
Test)	-03 07 130 C, 300 cycles	JL3D22-A104
uHAST (Highly		
Accelerated Stress Test,	130 °C, 85% RH, 96 hours	JESD22-A118
unbiased)		
HTSL (High Temperature	150 °C, 1000 hours	JESD22-A103
Storage Life)	130 G, 1000 flours	JL3D22-A103
LTSL (Low Temperature	– 40 °C, 1000 hours	JESD22-A119
Storage Life)	- 40 O, 1000 Hours	00022-7119

¹ JEDEC document JEP155 states that 500 V HBM allows safe manufacturing with a standard ESD control process.

4.8 Wi-Fi Radio

Table 19: Wi-Fi Frequency

Parameter	Min	Typ	Max
	(MHz)	(MHz)	(MHz)
Center frequency of operating channel	2412	_	2484

4.8.1 Wi-Fi RF Transmitter (TX) Specifications

Table 20: TX Power with Spectral Mask and EVM Meeting 802.11 Standards

	Min	Тур	Max
Rate	(dBm)	(dBm)	(dBm)
802.11b, 1 Mbps	_	21.0	_
802.11b, 11 Mbps	_	21.0	
802.11g, 6 Mbps	_	21.0	_
802.11g, 54 Mbps	_	19.0	_
802.11n, HT20, MCS0		20.0	_
802.11n, HT20, MCS7	_	18.5	_
802.11n, HT40, MCS0		20.0	_
802.11n, HT40, MCS7	_	18.5	

² JEDEC document JEP157 states that 250 V CDM allows safe manufacturing with a standard ESD control process.

Table 21: TX EVM Test

	Min	Тур	SL ¹
Rate	(dB)	(dB)	(dB)
802.11b, 1 Mbps, @21 dBm	_	-24.5	-10
802.11b, 11 Mbps, @21 dBm		-25.0	-10
802.11g, 6 Mbps, @21 dBm	_	-23.0	-5
802.11g, 54 Mbps, @19 dBm		-27.5	-25
802.11n, HT20, MSC0, @20 dBm	_	-22.5	- 5
802.11n, HT20, MSC7, @18.5 dBm		-29.0	-27
802.11n, HT40, MSC0, @20 dBm	_	-22.5	- 5
802.11n, HT40, MSC7, @18.5 dBm	_	-28.0	-27

¹ SL stands for standard limit value.

4.8.2 Wi-Fi RF Receiver (RX) Specifications

Table 22: RX Sensitivity

	Min	Тур	Max
Rate	(dBm)	(dBm)	(dBm)
802.11b, 1 Mbps	_	-98.4	_
802.11b, 2 Mbps	_	-96.0	_
802.11b, 5.5 Mbps	_	-93.0	_
802.11b, 11 Mbps	_	-88.6	
802.11g, 6 Mbps	_	-93.8	
802.11g, 9 Mbps		-92.2	
802.11g, 12 Mbps		-91.0	
802.11g, 18 Mbps		-88.4	
802.11g, 24 Mbps		-85.8	
802.11g, 36 Mbps		-82.0	
802.11g, 48 Mbps		-78.0	_
802.11g, 54 Mbps		-76.6	_
802.11n, HT20, MCS0	_	-93.6	_
802.11n, HT20, MCS1		-90.8	_
802.11n, HT20, MCS2	_	-88.4	_
802.11n, HT20, MCS3		-85.0	_
802.11n, HT20, MCS4	_	-81.8	_
802.11n, HT20, MCS5		-77.8	_
802.11n, HT20, MCS6		-76.0	_
802.11n, HT20, MCS7		-74.8	_
802.11n, HT40, MCS0	_	-90.0	_
802.11n, HT40, MCS1	_	-88.0	_
802.11n, HT40, MCS2		-85.2	
802.11n, HT40, MCS3	_	-82.0	_
802.11n, HT40, MCS4	_	-78.8	_

Table 22 - cont'd from previous page

	Min	Тур	Max
Rate	(dBm)	(dBm)	(dBm)
802.11n, HT40, MCS5	_	-74.6	_
802.11n, HT40, MCS6	_	-73.0	_
802.11n, HT40, MCS7	_	-71.4	_

Table 23: Maximum RX Level

	Min	Тур	Max
Rate	(dBm)	(dBm)	(dBm)
802.11b, 1 Mbps	_	5	_
802.11b, 11 Mbps	_	5	_
802.11g, 6 Mbps	_	5	_
802.11g, 54 Mbps		0	_
802.11n, HT20, MCS0	_	5	_
802.11n, HT20, MCS7	_	0	_
802.11n, HT40, MCS0		5	_
802.11n, HT40, MCS7	_	0	_

Table 24: RX Adjacent Channel Rejection

	Min	Тур	Max
Rate	(dB)	(dB)	(dB)
802.11b, 1 Mbps	_	35	_
802.11b, 11 Mbps	_	35	_
802.11g, 6 Mbps	_	31	_
802.11g, 54 Mbps	_	20	_
802.11n, HT20, MSC0	_	31	_
802.11n, HT20, MSC7	_	16	_
802.11n, HT40, MSC0	_	25	_
802.11n, HT40, MSC7		11	_

4.9 Bluetooth LE Radio

Table 25: Bluetooth LE Frequency

Parameter	Min	Typ	Max
	(MHz)	(MHz)	(MHz)
Center frequency of operating channel	2402		2480

Bluetooth LE RF Transmitter (TX) Specifications 4.9.1

Table 26: Transmitter Characteristics - Bluetooth LE 1 Mbps

Parameter	Description	Min	Тур	Max	Unit
RF transmit power	RF power control range	-27.00	0	18.00	dBm
	Gain control step	_	3.00	_	dB
	$ Max _{n=0,1,2,k}$	_	17.00	_	kHz
Carrier frequency offset and drift	$Max \left f_0 - f_n \right $		1.75	_	kHz
Carrier frequency offset and drift	$Max \left f_{n-} f_{n-5} \right $		1.46	_	kHz
	$ f_1 - f_0 $	_	0.80	_	kHz
	$\Delta~f1_{ ext{avg}}$		250.00	_	kHz
Modulation characteristics	Min Δ $f2_{\rm max}$ (for at least	10	190.00		kHz
iviodulation characteristics	99.9% of all Δ $f2_{\rm max}$)	_	190.00		KI IZ
	$\Delta~f2_{\mathrm{avg}}/\Delta~f1_{\mathrm{avg}}$	_	0.83	_	_
In-band spurious emissions	± 2 MHz offset		-37.62	_	dBm
	± 3 MHz offset		-41.95		dBm
	± > 3 MHz offset		-44.48	_	dBm

Table 27: Transmitter Characteristics - Bluetooth LE 2 Mbps

Parameter	Description	Min	Тур	Max	Unit
DE transmit navyer	RF power control range	-27.00	0	18.00	dBm
RF transmit power	Gain control step		3.00	_	dB
			20.80	_	kHz
Carrier frequency offset and drift	$Max f_0 - f_n $		1.30	_	kHz
Carrier frequency offset and drift	$Max \left f_{n-} f_{n-5} \right $		1.33	_	kHz
	$ f_1-f_0 $	_	0.70		kHz
	$\Delta f1_{ ext{avg}}$		498.00		kHz
Modulation characteristics	Min Δ $f2_{\rm max}$ (for at least		430.00		kHz
	99.9% of all Δ $f2_{\text{max}}$)				
	$\Delta f 2_{ m avg}/\Delta f 1_{ m avg}$	_	0.93		_
In-band spurious emissions	± 4 MHz offset		-43.55		dBm
	± 5 MHz offset		-45.26	_	dBm
	± > 5 MHz offset		-45.26		dBm

Table 28: Transmitter Characteristics - Bluetooth LE 125 Kbps

Parameter	Description	Min	Тур	Max	Unit
RF transmit power	RF power control range	-27.00	0	18.00	dBm
	Gain control step	_	3.00		dB
Carrier frequency offset and drift		_	17.50	_	kHz
	$ Max f_0 - f_n $	_	0.45	_	kHz
	$ f_{n}-f_{n-3} $		0.70		kHz
	$ f_0-f_3 $	_	0.30	_	kHz

Table 28 - cont'd from previous page

Parameter	Description	Min	Тур	Max	Unit
	$\Delta f 1_{ ext{avg}}$		250.00		kHz
Modulation characteristics	Min Δ $f1_{\rm max}$ (for at least 99.9% of all Δ $f2_{\rm max}$)		235.00	_	kHz
	± 2 MHz offset		-37.90	_	dBm
In-band spurious emissions	± 3 MHz offset	_	-41.00	_	dBm
	± > 3 MHz offset		-42.50	_	dBm

Table 29: Transmitter Characteristics - Bluetooth LE 500 Kbps

Parameter	Description	Min	Тур	Max	Unit
RF transmit power	RF power control range	-27.00	0	18.00	dBm
ni transmit power	Gain control step	_	3.00	_	dB
	$ \text{Max} _{n=0,\;1,\;2,\;k}$	_	17.00	_	kHz
Carrier frequency offset and drift	$Max f_0 - f_n $	_	0.88	_	kHz
Carrier frequency offset and drift	$ f_n - f_{n-3} $	_	1.00	_	kHz
	$ f_0 - f_3 $	_	0.20		kHz
	$\Delta f 2_{avg}$	_	208.00		kHz
Modulation characteristics	Min Δ $f2_{\rm max}$ (for at least		100.00	17.00 — 0.88 — 1.00 — 0.20 — 208.00 — 190.00 — -37.90 — -41.30 —	kHz
	99.9% of all Δ $f2_{ ext{max}}$)	_	190.00		KI IZ
In-band spurious emissions	± 2 MHz offset		-37.90		dBm
	± 3 MHz offset	_	-41.30	_	dBm
	± > 3 MHz offset	_	-42.80		dBm

4.9.2 Bluetooth LE RF Receiver (RX) Specifications

Table 30: Receiver Characteristics - Bluetooth LE 1 Mbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-97		dBm
Maximum received signal @30.8% PER	_	_	5	_	dBm
Co-channel C/I	_	_	8	_	dB
	F = F0 + 1 MHz	_	-3	_	dB
	F = F0 – 1 MHz	_	-4	_	dB
	F = F0 + 2 MHz	_	-29	_	dB
Adjacent channel selectivity C/I	F = F0 - 2 MHz	_	-31	_	dB
Adjacent channel selectivity C/1	F = F0 + 3 MHz	_	-33	_	dB
	F = F0 - 3 MHz	_	-27	_	dB
	F ≥ F0 + 4 MHz	_	-29	_	dB
	$F \le F0 - 4 MHz$	_	-38	_	dB
Image frequency	_	_	-29	_	dB
A dia contrabannal to impage from page.	$F = F_{image} + 1 \text{ MHz}$	_	-41	_	dB
Adjacent channel to image frequency	$F = F_{image} - 1 \text{ MHz}$	_	-33		dB

Table 30 - cont'd from previous page

Parameter	Description	Min	Тур	Max	Unit
Out-of-band blocking performance	30 MHz ~ 2000 MHz	_	- 5	_	dBm
	2003 MHz ~ 2399 MHz	_	-18	_	dBm
	2484 MHz ~ 2997 MHz	_	-15	_	dBm
	3000 MHz ~ 12.75 GHz	_	- 5	_	dBm
Intermodulation	_	_	-30	_	dBm

Table 31: Receiver Characteristics - Bluetooth LE 2 Mbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-93	_	dBm
Maximum received signal @30.8% PER	_	_	3	_	dBm
Co-channel C/I	_	_	10	_	dB
	F = F0 + 2 MHz	_	-7	_	dB
	F = F0 – 2 MHz	_	-7	_	dB
	F = F0 + 4 MHz	_	-28	_	dB
Adjacent channel calcativity C/I	F = F0 – 4 MHz	_	-26	_	dB
Adjacent channel selectivity C/I	F = F0 + 6 MHz	_	-26	_	dB
	F = F0 – 6 MHz	_	-27	_	dB
	F ≥ F0 + 8 MHz	_	-29	_	dB
	$F \le F0 - 8 MHz$	_	-28	_	dB
Image frequency	_	_	-28	_	dB
Adjacent channel to image frequency	$F = F_{image} + 2 MHz$	_	-26	_	dB
Adjacent charmer to image frequency	$F = F_{image} - 2 \text{ MHz}$	_	-7	_	dB
Out-of-band blocking performance	30 MHz ~ 2000 MHz	_	- 5	_	dBm
	2003 MHz ~ 2399 MHz	_	-19	_	dBm
	2484 MHz ~ 2997 MHz	_	-16	_	dBm
	3000 MHz ~ 12.75 GHz	_	- 5	_	dBm
Intermodulation	_	_	-29	_	dBm

Table 32: Receiver Characteristics - Bluetooth LE 125 Kbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-105	_	dBm
Maximum received signal @30.8% PER	_	_	5	_	dBm
Co-channel C/I	_		3	_	dB
	F = F0 + 1 MHz	_	-6	_	dB
	F = F0 - 1 MHz	_	-6		dB
	F = F0 + 2 MHz		-33	_	dB
Adjacent channel selectivity C/I	F = F0 - 2 MHz	_	-43		dB
Adjacent channel selectivity 0/1	F = F0 + 3 MHz	_	-37	_	dB
	F = F0 - 3 MHz		-47	_	dB
	$F \ge F0 + 4 MHz$		-40	_	dB
	$F \le F0 - 4 MHz$	_	-50	_	dB

Table 32 - cont'd from previous page

Parameter	Description	Min	Тур	Max	Unit
Image frequency	_	_	-40	_	dB
Adjacent channel to image frequency	$F = F_{image} + 1 \text{ MHz}$	_	-50	_	dB
Adjacent channel to image frequency	$F = F_{image} - 1 \text{ MHz}$	_	-37	_	dB

Table 33: Receiver Characteristics - Bluetooth LE 500 Kbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-100	_	dBm
Maximum received signal @30.8% PER	_	_	5	_	dBm
Co-channel C/I	_	_	3	_	dB
	F = F0 + 1 MHz	_	-2	_	dB
	F = F0 – 1 MHz	_	-3	_	dB
	F = F0 + 2 MHz	_	-32	_	dB
Adjacent channel selectivity C/I	F = F0 – 2 MHz	_	-33	_	dB
Adjacent channel selectivity C/1	F = F0 + 3 MHz	_	-23	_	dB
	F = F0 - 3 MHz	_	-40	_	dB
	$F \ge F0 + 4 MHz$	_	-34	_	dB
	$F \le F0 - 4 MHz$	_	-44	_	dB
Image frequency	_	_	-34	_	dB
Adjacent abannal ta imaga fraguenay	$F = F_{image} + 1 \text{ MHz}$		-46	_	dB
Adjacent channel to image frequency	$F = F_{image} - 1 \text{ MHz}$	_	-23	_	dB

Package Information 5.

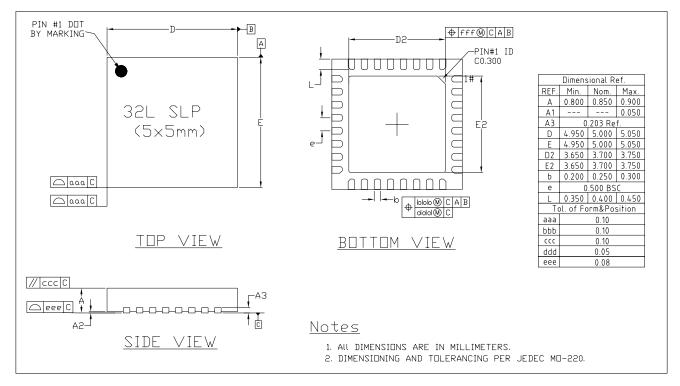


Figure 8: QFN32 (5×5 mm) Package

Note:

- For the source file of recommended PCB land pattern (dxf), you can view it with Autodesk Viewer;
- For information about tape, reel, and product marking, please refer to Espressif Chip-Packing Information.

Related Documentation and Resources

Related Documentation

- ESP32-C3 Technical Reference Manual Detailed information on how to use the ESP32-C3 memory and peripherals.
- Certificates
 - http://espressif.com/en/support/documents/certificates
- Documentation Updates and Update Notification Subscription http://espressif.com/en/support/download/documents

Developer Zone

- ESP-IDF Programming Guide for ESP32-C3 Extensive documentation for the ESP-IDF development framework.
- ESP-IDF and other development frameworks on GitHub.
 - http://github.com/espressif
- ESP32 BBS Forum Engineer-to-Engineer (E2E) Community for Espressif products where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.
 - http://esp32.com/
- The ESP Journal Best Practices, Articles, and Notes from Espressif folks.
 - http://blog.espressif.com/
- See the tabs SDKs and Demos, Apps, Tools, AT Firmware. http://espressif.com/en/support/download/sdks-demos

Products

- ESP32-C3 Series SoCs Browse through all ESP32-C3 SoCs.
 - http://espressif.com/en/products/socs?id=ESP32-C3
- ESP32-C3 Series Modules Browse through all ESP32-C3-based modules.
 - http://espressif.com/en/products/modules?id=ESP32-C3
- ESP32-C3 Series DevKits Browse through all ESP32-C3-based devkits.
 - http://espressif.com/en/products/devkits?id=ESP32-C3
- ESP Product Selector Find an Espressif hardware product suitable for your needs by comparing or applying filters. http://products.espressif.com/#/product-selector?language=en

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Revision History

Date	Version	Release Notes
2021-10-26	v1.1	 Updated Figure Block Diagram of ESP32-C3 to show power modes; Added CoreMark score in Features; Updated Table Pin Description to show default pin functions; Updated Figure ESP32-C3 Power Scheme and related descriptions; Added Table Mapping of SPI Signals and Chip Pads; Added note 3 to Table Recommended Operating Conditions; Other updates to wording.
2021-05-28	v1.0	 Updated power modes; Updated Section 2.4 Strapping Pins; Updated some clock names and their frequencies in Section 3.2 System Clocks; Added clarification about ADC1 and ADC2 in Section 3.3.1 Analog-to-Digital Converter (ADC); Updated the default configuration of U0RXD andU0TXD after reset in Table IO MUX Pin Functions; Updated sampling rate in Table ADC Characteristics; Updated Table Reliability Qualifications; Added the link to recommended PCB land pattern in Chapter 5 Package Information.
2021-04-23	v0.8	Updated Wi-Fi Radio and Bluetooth LE Radio data.
2021-04-07	v0.7	 Updated information about USB Serial/JTAG Controller; Added GPIO2 to Section 2.4 Strapping Pins; Updated Figure Address Mapping Structure; Added Table IO MUX Pin Functions and Table Power-Up Glitches on Pins in Section 3.4.1 General Purpose Input / Output Interface (GPIO); Updated information about SPI2 in Section 3.4.2 Serial Peripheral Interface (SPI); Updated fixed-priority channel scheme in Section 3.4.8 General DMA Controller; Updated Table Reliability Qualifications.
2021-01-18	v0.6	 Clarified that of the 400 KB SRAM, 16 KB is configured as cache; Updated maximum value to standard limit value in Table TX EVM Test in Section 4.8.1 Wi-Fi RF Transmitter (TX) Specifications.

Date	Version	Release Notes
2021-01-13	v0.5	 Updated information about Wi-Fi; Added connection between embedded flash ports and chip pins to table notes in Section 2.2 Pin Description; Updated Figure ESP32-C3 Power Scheme, added Figure ESP32-C3 Power-up and Reset Timing and Table Description of ESP32-C3 Power-up and Reset Timing Parameters in Section 2.3 Power Scheme; Added Figure Setup and Hold Times for the Strapping Pins and Table Parameter Descriptions of Setup and Hold Times for the Strapping Pins in Section 2.4 Strapping Pins; Updated Table Peripheral Pin Configurations in Section 3.11 Peripheral Pin Configurations; Added Chapter 4 Electrical Characteristics; Added Chapter 5 Package Information.
2020-11-27	v0.4	Preliminary version.



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