ESP32-WROVER-E & ESP32-WROVER-IE

Datasheet



About This Document

This document provides the specifications for the ESP32-WROVER-E and ESP32-WROVER-IE modules.

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1. Overview

ESP32-WROVER-E and ESP32-WROVER-IE are two powerful, generic WiFi-BT-BLE MCU modules that target a wide variety of applications, ranging from low-power sensor networks to the most demanding tasks, such as voice encoding, music streaming and MP3 decoding.

ESP32-WROVER-E comes with a PCB antenna, and ESP32-WROVER-IE with an IPEX antenna. They both feature a 4 MB external SPI flash and an additional 8 MB SPI Pseudo static RAM (PSRAM). The information in this datasheet is applicable to both modules.

The ordering information of the two modules is listed as follows:

Table 1: Ordering Information

Module	Chip embedded	Flash	PSRAM	Module dimensions (mm)		
ESP32-WROVER-E (PCB)	ESP32-D0WD-V3	4 MB ¹	8 MB	(18.00±0.15)×(31.40±0.15)×(3.30±0.15)		
ESP32-WROVER-IE (IPEX)	L3F32-D0VVD-V3	4 1010	OIVID	(16.00±0.15)×(31.40±0.15)×(3.30±0.		

Notes:

- 1. The module with 8 MB flash or 16 MB flash is available for custom order.
- 2. For detailed ordering information, please see Espressif Product Ordering Information.
- 3. For dimensions of the IPEX connector, please see Chapter 11.

At the core of the module is the ESP32-D0WD-V3 chip*. The chip embedded is designed to be scalable and adaptive. There are two CPU cores that can be individually controlled, and the CPU clock frequency is adjustable from 80 MHz to 240 MHz. The chip also has a low-power co-processor that can be used instead of the CPU to save power while performing tasks that do not require much computing power, such as monitoring of peripherals. ESP32 integrates a rich set of peripherals, ranging from capacitive touch sensors, Hall sensors, SD card interface, Ethernet, high-speed SPI, UART, I2S and I2C.

Note:

* For details on the part numbers of the ESP32 family of chips, please refer to the document ESP32 Datasheet.

The integration of Bluetooth[®], Bluetooth LE and Wi-Fi ensures that a wide range of applications can be targeted, and that the module is all-around: using Wi-Fi allows a large physical range and direct connection to the Internet through a Wi-Fi router, while using Bluetooth allows the user to conveniently connect to the phone or broadcast low energy beacons for its detection. The sleep current of the ESP32 chip is less than 5 μ A, making it suitable for battery powered and wearable electronics applications. The module supports a data rate of up to 150 Mbps, and 20 dBm output power at the antenna to ensure the widest physical range. As such the module does offer industry-leading specifications and the best performance for electronic integration, range, power consumption, and connectivity.

The operating system chosen for ESP32 is freeRTOS with LwIP; TLS 1.2 with hardware acceleration is built in as well. Secure (encrypted) over the air (OTA) upgrade is also supported, so that users can upgrade their products even after their release, at minimum cost and effort.

Table 2 provides the specifications of the two modules.

Table 2: ESP32-WROVER-E & ESP32-WROVER-IE Specifications

Categories	Items	Specifications		
Certification	RF certification	FCC/CE-RED/SRRC		
Test	Reliablity	HTOL/HTSL/uHAST/TCT/ESD		
		802.11 b/g/n (802.11n up to 150 Mbps)		
 Wi-Fi	Protocols	A-MPDU and A-MSDU aggregation and 0.4 μ s guard in-		
VVI-FI		terval support		
	Frequency range	2412 ~ 2484 MHz		
	Protocols	Bluetooth v4.2 BR/EDR and BLE specification		
		NZIF receiver with -97 dBm sensitivity		
Bluetooth	Radio	Class-1, class-2 and class-3 transmitter		
		AFH		
	Audio	CVSD and SBC		
		SD card, UART, SPI, SDIO, I ² C, LED PWM, Motor PWM,		
	Module interfaces	I ² S, IR, pulse counter, GPIO, capacitive touch sensor,		
		ADC, DAC		
	On-chip sensor	Hall sensor		
	Integrated crystal	40 MHz crystal		
	Integrated SPI flash	4 MB		
Hardware	Integrated PSRAM	8 MB		
	Operating voltage/Power supply	3.0 V ~ 3.6 V		
	Minimum current delivered by	500 mA		
	power supply	000 11111		
	Recommended operating tem-	_40 °C ~ 85 °C		
	perature range			
	Package size	(18.00±0.15) mm × (31.40±0.15) mm × (3.30±0.15) mm		
	Moisture sensitivity level (MSL)	Level 3		

2. Block Diagram

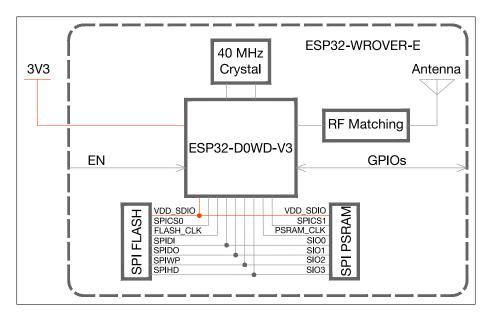


Figure 1: ESP32-WROER-E Block Diagram

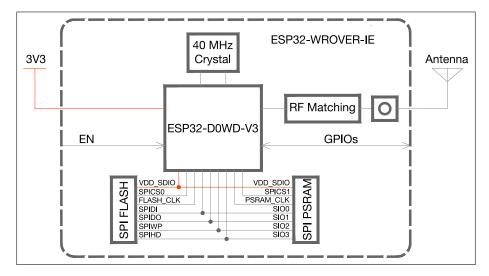


Figure 2: ESP32-WROVER-IE Block Diagram

3. Pin Definitions

3.1 Pin Layout

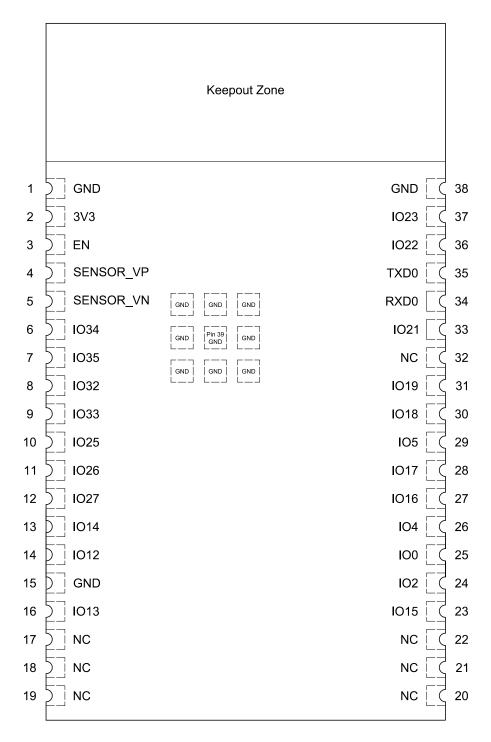


Figure 3: Pin Layout (Top View)

3.2 Pin Description

The module has 38 pins. See pin definitions in Table 3.

Table 3: Pin Definitions

GND 1 P Ground 3V3 2 P Power supply EN 3 I Module-enable signal. Active high. SENSOR, VP 4 I GPI036, ADC1_CH3, RTC_GPI00 SENSOR, VN 5 I GPI039, ADC1_CH3, RTC_GPI03 IO34 6 I GPI034, ADC1_CH3, RTC_GPI06 IO35 7 I GPI035, ADC1_CH7, RTC_GPI06 IO32 8 I/O GPI032, XTAL_32K, P (82.768 kHz crystal oscillator input), ADC1_CH4, TOUCH9, RTC_GPI09 IO33 9 I/O GPI033, XTAL_32K, P (82.768 kHz crystal oscillator output), ADC1_CH4, TOUCH9, RTC_GPI09 IO25 10 I/O GPI025, DAC_1, ADC2_CH9, RTC_GPI06, EMAC_RXD0 IO26 11 I/O GPI026, DAC_2, ADC2_CH9, RTC_GPI07, EMAC_RX_DV IO14 13 I/O GPI027, ADC2_CH3, TOUCH3, RTC_GPI016, MTMS, HSPICLK, HS2_DATA2, SD_CDATA2, EMAC_TXD2 IO14 13 I/O GPI014, ADC2_CH3, TOUCH3, RTC_GPI016, MTDI, HSPIQ, HS2_DATA2, SD_DATA2, EMAC_TXD3 IO13 16 I/O GPI013, ADC2_CH4, TOUCH4, RTC_GPI014, MTCK, HSPID, HS2_DATA2, SD_DATA3, SD_DATA3, EMAC	Name	No.	Туре	Function
EN 3 I Module-enable signal. Active high. SENSOR_VP 4 I GPI036, ADC1_CH0, RTC_GPI00 SENSOR_VN 5 I GPI039, ADC1_CH3, RTC_GPI03 IO34 6 I GPI034, ADC1_CH6, RTC_GPI04 IO35 7 I GPI035, ADC1_CH6, RTC_GPI05 IO32 8 VO GPI032, XTAL_32K_P (32.768 kHz crystal oscillator input), ADC1_CH4, TOUCH9, RTC_GPI09 IO33 9 VO GPI033, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH4, TOUCH9, RTC_GPI09 IO33 9 VO GPI033, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH5, TOUCH9, RTC_GPI09 IO25 10 I/O GPI025, DAC_1, ADC2_CH8, RTC_GPI06, EMAC_RXD0 IO26 11 I/O GPI026, DAC_2, ADC2_CH9, RTC_GPI06, EMAC_RXD0 IO27 12 I/O GPI027, ADC2_CH4, TOUCH7, RTC_GPI07, EMAC_RX_DV GPI014, ADC2_CH6, TOUCH6, RTC_GPI016, MTMS, HSPICLK, HS2_CLK, SD_CLK, EMAC_TXD2 IO14 14 I/O GPI012, ADC2_CH5, TOUCH5, RTC_GPI015, MTDI, HSPIQ, HS2_CLK, SD_CLK, EMAC_TXD3 GND 15 P Ground IO13 16 I/O GPI013, ADC2_CH4, TOUCH4, RTC_GPI014, MTCK, HSPID, HS2_DATA2, SD_DATA2, EMAC_TXD3 IO16 18 - COUNTY, COU	GND	1	Р	Ground
SENSOR_VP 4	3V3	2	Р	Power supply
SENSOR_VN 5	EN	3	I	Module-enable signal. Active high.
1034 6	SENSOR_VP	4	I	GPIO36, ADC1_CH0, RTC_GPIO0
IO35	SENSOR_VN	5	I	GPIO39, ADC1_CH3, RTC_GPIO3
IO32	IO34	6	I	GPIO34, ADC1_CH6, RTC_GPIO4
1032 8	IO35	7	I	GPIO35, ADC1_CH7, RTC_GPIO5
1033 9	IO32	8	I/O	
IO26	IO33	9	I/O	
1027	IO25	10	I/O	GPIO25, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXD0
IO14	IO26	11	I/O	GPIO26, DAC_2, ADC2_CH9, RTC_GPIO7, EMAC_RXD1
IO14	1027	12	I/O	GPIO27, ADC2_CH7, TOUCH7, RTC_GPIO17, EMAC_RX_DV
HS2_CLK, SD_CLK, EMAC_TXD2	1014	10	1/0	GPIO14, ADC2_CH6, TOUCH6, RTC_GPIO16, MTMS, HSPICLK,
14	1014	13	1/0	HS2_CLK, SD_CLK, EMAC_TXD2
HS2_DATA2, SD_DATA2, EMAC_TXD3	1012	1./	1/0	GPIO12, ADC2_CH5, TOUCH5, RTC_GPIO15, MTDI, HSPIQ,
IO13	1012	14	1/0	HS2_DATA2, SD_DATA2, EMAC_TXD3
NC * 17 - - - -	GND	15	Р	Ground
HS2_DATA3, SD_DATA3, EMAC_RX_ER	1013	16	1/0	GPIO13, ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID,
NC * 18 - - NC * 19 - - NC * 20 - - NC * 21 - - NC * 22 - - IO15 23 - GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICSO, RTC_GPIO13, HS2_CMD, SD_CMD, EMAC_RXD3 IO2 24 I/O GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, SD_DATA0 IO0 25 I/O GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK IO4 26 I/O GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER NC 27 - - NC 28 - - IO5 29 I/O GPIO5, VSPICSO, HS1_DATA6, EMAC_RX_CLK IO19 31 I/O GPIO19, VSPIQ, UOCTS, EMAC_TXDO	1013	10	1/0	HS2_DATA3, SD_DATA3, EMAC_RX_ER
NC * 19 - - NC * 20 - - NC * 21 - - NC * 22 - - IO15 23 - GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICSO, RTC_GPIO13, HS2_CMD, SD_CMD, EMAC_RXD3 IO2 24 I/O GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, SD_DATA0 IO0 25 I/O GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK IO4 26 I/O GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER NC 27 - - NC 28 - - IO5 29 I/O GPIO5, VSPICS0, HS1_DATA6, EMAC_RX_CLK IO18 30 I/O GPIO18, VSPICLK, HS1_DATA7 IO19 31 I/O GPIO19, VSPIQ, UOCTS, EMAC_TXD0	NC *	17	-	-
NC * 20 - - NC * 21 - - NC * 22 - - IO15 23 - GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICSO, RTC_GPIO13, HS2_CMD, SD_CMD, EMAC_RXD3 IO2 24 I/O GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, SD_DATA0 IO0 25 I/O GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK IO4 26 I/O GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER NC 27 - - NC 28 - - IO5 29 I/O GPIO18, VSPICSO, HS1_DATA6, EMAC_RX_CLK IO18 30 I/O GPIO18, VSPICLK, HS1_DATA7 IO19 31 I/O GPIO19, VSPIQ, UOCTS, EMAC_TXD0	NC *	18	-	-
NC * 21 - - NC * 22 - - IO15 23 - GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICSO, RTC_GPIO13, HS2_CMD, SD_CMD, EMAC_RXD3 IO2 24 I/O GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, SD_DATA0 IO0 25 I/O GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK IO4 26 I/O GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER NC 27 - - NC 28 - - IO5 29 I/O GPIO18, VSPICSO, HS1_DATA6, EMAC_RX_CLK IO18 30 I/O GPIO19, VSPIQ, UOCTS, EMAC_TXDO	NC *	19	-	-
NC * 22 - - IO15 23 - GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICSO, RTC_GPIO13, HS2_CMD, SD_CMD, EMAC_RXD3 IO2 24 I/O GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, SD_DATA0 IO0 25 I/O GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK IO4 26 I/O GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER NC 27 - - NC 28 - - IO5 29 I/O GPIO5, VSPICSO, HS1_DATA6, EMAC_RX_CLK IO18 30 I/O GPIO18, VSPICLK, HS1_DATA7 IO19 31 I/O GPIO19, VSPIQ, UOCTS, EMAC_TXDO	NC *	20	-	-
IO15 23	NC *	21	-	-
HS2_CMD, SD_CMD, EMAC_RXD3	NC *	22	-	-
IO2	IO15	23	-	
IOO 25	IO2	24	I/O	
IO4 26	IO0	25	I/O	GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1,
NC 27 - - NC 28 - - IO5 29 I/O GPIO5, VSPICSO, HS1_DATA6, EMAC_RX_CLK IO18 30 I/O GPIO18, VSPICLK, HS1_DATA7 IO19 31 I/O GPIO19, VSPIQ, U0CTS, EMAC_TXD0	104	26	I/O	GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1,
NC 28 - - IO5 29 I/O GPIO5, VSPICSO, HS1_DATA6, EMAC_RX_CLK IO18 30 I/O GPIO18, VSPICLK, HS1_DATA7 IO19 31 I/O GPIO19, VSPIQ, U0CTS, EMAC_TXD0	NC	27	-	
IO5 29 I/O GPIO5, VSPICSO, HS1_DATA6, EMAC_RX_CLK IO18 30 I/O GPIO18, VSPICLK, HS1_DATA7 IO19 31 I/O GPIO19, VSPIQ, U0CTS, EMAC_TXD0			-	-
IO18 30 I/O GPIO18, VSPICLK, HS1_DATA7 IO19 31 I/O GPIO19, VSPIQ, U0CTS, EMAC_TXD0			I/O	GPIO5, VSPICSO, HS1 DATA6, EMAC RX CLK
IO19 31 I/O GPIO19, VSPIQ, U0CTS, EMAC_TXD0				
	NC	32		

Name	No.	Type	Function
IO21	33	I/O	GPIO21, VSPIHD, EMAC_TX_EN
RXD0	34	I/O	GPIO3, U0RXD, CLK_OUT2
TXD0	35	I/O	GPIO1, U0TXD, CLK_OUT3, EMAC_RXD2
IO22	36	I/O	GPIO22, VSPIWP, UORTS, EMAC_TXD1
IO23	37	I/O	GPIO23, VSPID, HS1_STROBE
GND	38	Р	Ground

Notice:

* Pins GPIO6 to GPIO11 on the ESP32-D0WD-V3 chip are connected to the SPI flash integrated on the module and are not led out.

3.3 Strapping Pins

ESP32 has five strapping pins, which can be seen in Chapter 7 Schematics:

- MTDI
- GPI00
- GPI02
- MTDO
- GPI05

Software can read the values of these five bits from register "GPIO_STRAPPING".

During the chip's system reset release (power-on-reset, RTC watchdog reset and brownout reset), the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down. The strapping bits configure the device's boot mode, the operating voltage of VDD_SDIO and other initial system settings.

Each strapping pin is connected to its internal pull-up/pull-down during the chip reset. Consequently, if a strapping pin is unconnected or the connected external circuit is high-impedance, the internal weak pull-up/pull-down will determine the default input level of the strapping pins.

To change the strapping bit values, users can apply the external pull-down/pull-up resistances, or use the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32.

After reset release, the strapping pins work as normal-function pins.

Refer to Table 4 for a detailed boot-mode configuration by strapping pins.

Table 4: Strapping Pins

	Voltage of Internal LDO (VDD_SDIO)							
Pin Default 3.3 V 1.8 V								
MTDI	Pull-down	0	1					
	Booting Mode							
Pin	Default	Download Boot						

GPI00	Pull-up	-	1	()
GPIO2	Pull-down	Don't	-care	()
Е	nabling/Disa	bling Debugging	g Log Print over	U0TXD During I	Booting
Pin Default U0TXD Active U0TXD Silent					
MTDO	Pull-up	-	1	()
		Timinç	g of SDIO Slave		
		FE Sampling	FE Sampling	RE Sampling	RE Sampling
Pin	Default	FE Output RE Output		FE Output	RE Output
MTDO	Pull-up	0	0 0		1
GPIO5	Pull-up	0	1	0	1

Note:

- FE: falling-edge, RE: rising-edge.
- Firmware can configure register bits to change the settings of "Voltage of Internal LDO (VDD_SDIO)" and "Timing of SDIO Slave" after booting.
- Internal pull-up resistor (R9) for MTDI is not populated in the module, as the flash and SRAM in the module only support a power voltage of 3.3 V (output by VDD_SDIO).

4. Functional Description

This chapter describes the modules and functions integrated in ESP32-WROVER-E and ESP32-WROVER-IE.

4.1 CPU and Internal Memory

ESP32-D0WD-V3 contains two low-power Xtensa® 32-bit LX6 microprocessors. The internal memory includes:

- 448 KB of ROM for booting and core functions.
- 520 KB of on-chip SRAM for data and instructions.
- 8 KB of SRAM in RTC, which is called RTC FAST Memory and can be used for data storage; it is accessed by the main CPU during RTC Boot from the Deep-sleep mode.
- 8 KB of SRAM in RTC, which is called RTC SLOW Memory and can be accessed by the co-processor during the Deep-sleep mode.
- 1 Kbit of eFuse: 256 bits are used for the system (MAC address and chip configuration) and the remaining 768 bits are reserved for customer applications, including flash-encryption and chip-ID.

4.2 External Flash and SRAM

ESP32 supports multiple external QSPI flash and SRAM chips. More details can be found in Chapter SPI in the <u>ESP32 Technical Reference Manual</u>. ESP32 also supports hardware encryption/decryption based on AES to protect developers' programs and data in flash.

ESP32 can access the external QSPI flash and SRAM through high-speed caches.

- The external flash can be mapped into CPU instruction memory space and read-only memory space simultaneously.
 - When external flash is mapped into CPU instruction memory space, up to 11 MB + 248 KB can be mapped at a time. Note that if more than 3 MB + 248 KB are mapped, cache performance will be reduced due to speculative reads by the CPU.
 - When external flash is mapped into read-only data memory space, up to 4 MB can be mapped at a time. 8-bit, 16-bit and 32-bit reads are supported.
- External SRAM can be mapped into CPU data memory space. Up to 4 MB can be mapped at a time. 8-bit, 16-bit and 32-bit reads and writes are supported.

ESP32-WROVER-E and ESP32-WROVER-IE integrate a 4 MB SPI flash and an 8 MB PSRAM for more memory space.

4.3 Crystal Oscillators

The module uses a 40-MHz crystal oscillator.

4.4 RTC and Low-Power Management

With the use of advanced power-management technologies, ESP32 can switch between different power modes.

For details on ESP32's power consumption in different power modes, please refer to section "RTC and Low-Power Management" in *ESP32 Datasheet*.

5. Peripherals and Sensors

Please refer to Section Peripherals and Sensors in ESP32 Datasheet.

Note:

External connections can be made to any GPIO except for GPIOs in the range 6-11, 16, or 17. GPIOs 6-11 are connected to the module's integrated SPI flash and PSRAM. GPIOs 16 and 17 are connected to the module's integrated PSRAM. For details, please see Section 7 *Schematics*.

6. Electrical Characteristics

6.1 Absolute Maximum Ratings

Stresses beyond the absolute maximum ratings listed in the table below may cause permanent damage to the device. These are stress ratings only, and do not refer to the functional operation of the device that should follow the recommended operating conditions.

Table 5: Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit
VDD33	Power supply voltage	-0.3	3.6	V
I_{output}^{-1}	Cumulative IO output current	-	1,100	mA
T_{store}	Storage temperature	-40	85	°C

- 1. The module worked properly after a 24-hour test in ambient temperature at 25 °C, and the IOs in three domains (VDD3P3_RTC, VDD3P3_CPU, VDD_SDIO) output high logic level to ground. Please note that pins occupied by flash and/or PSRAM in the VDD_SDIO power domain were excluded from the test.
- 2. Please see Appendix IO_MUX in ESP32 Datasheet for IO's power domain.

6.2 Recommended Operating Conditions

Table 6: Recommended Operating Conditions

Symbol	Parameter	Min	Typical	Max	Unit
VDD33	Power supply voltage	3.0	3.3	3.6	V
I_{VDD}	Current delivered by external power supply	0.5	-	-	Α
Т	Operating temperature	-40	-	85	°C

6.3 DC Characteristics (3.3 V, 25 °C)

Table 7: DC Characteristics (3.3 V, 25 °C)

Symbol	Parameter	Min	Тур	Max	Unit
C_{IN}	Pin capacitance	-	2	-	рF
V_{IH}	High-level input voltage	0.75×VDD ¹	-	VDD1+0.3	V
V_{IL}	Low-level input voltage	-0.3	-	0.25×VDD ¹	V
$ I_{IH} $	High-level input current	-	-	50	nA
$ I_{IL} $	Low-level input current	-	-	50	nA
V_{OH}	High-level output voltage	0.8×VDD ¹	-	-	V
V_{OL}	Low-level output voltage	-	-	0.1×VDD ¹	V

Symbol	Parameter		Min	Тур	Max	Unit
	High-level source current (VDD 1 = 3.3 V, V _{OH} >= 2.64 V, output drive strength set to the maximum)	VDD3P3_CPU power domain ^{1, 2}	-	40	-	mA
I_{OH}		VDD3P3_RTC power domain ^{1, 2}	-	40	-	mA
		VDD_SDIO power domain ^{1, 3}	-	20	-	mA
I_{OL}	Low-level sink current (VDD 1 = 3.3 V, V $_{OL}$ = 0.495 V, output drive strength set to the maximum)		-	28	-	mA
R_{PU}	Resistance of internal pull-up resistor		-	45	-	kΩ
R_{PD}	Resistance of internal pull-down resistor		-	45	-	kΩ
V_{IL_nRST}	Low-level input voltage of CHIP_PU to power off the chip		-	-	0.6	V

Notes:

- 1. Please see Appendix IO_MUX in <u>ESP32 Datasheet</u> for IO's power domain. VDD is the I/O voltage for a particular power domain of pins.
- 2. For VDD3P3_CPU and VDD3P3_RTC power domain, per-pin current sourced in the same domain is gradually reduced from around 40 mA to around 29 mA, $V_{OH}>=2.64$ V, as the number of current-source pins increases.
- 3. Pins occupied by flash and/or PSRAM in the VDD_SDIO power domain were excluded from the test.

6.4 Wi-Fi Radio

Table 8: Wi-Fi Radio Characteristics

Parameter	Condition	Min	Typical	Max	Unit
Operating frequency range note1	-	2412	_	2484	MHz
Output impedance note2	-	-	*	-	Ω
TX power note3	11n, MCS7	12	13	14	dBm
1X power	11b mode	18.5	19.5	20.5	dBm
	11b, 1 Mbps	-	-97	-	dBm
	11b, 11 Mbps	-	-88	-	dBm
	11g, 6 Mbps	-	-92	-	dBm
Sensitivity	11g, 54 Mbps	-	-75	-	dBm
Sensitivity	11n, HT20, MCS0	-	-92	-	dBm
	11n, HT20, MCS7	-	-72	-	dBm
	11n, HT40, MCS0	-	-89	-	dBm
	11n, HT40, MCS7	-	-69	-	dBm
	11g, 6 Mbps	-	27	-	dB
Adjacent channel rejection	11g, 54 Mbps	-	13	-	dB
Adjacent charmentejection	11n, HT20, MCS0	-	27	-	dB
	11n, HT20, MCS7	-	12	-	dB

Notes:

- 1. Device should operate in the frequency range allocated by regional regulatory authorities. Target operating frequency range is configurable by software.
- 2. For the modules that use IPEX antennas, the output impedance is 50 Ω . For other modules without IPEX antennas, users do not need to concern about the output impedance.
- 3. Target TX power is configurable based on device or certification requirements.

6.5 BLE Radio

6.5.1 Receiver

Table 9: Receiver Characteristics - BLE

Parameter	Conditions	Min	Тур	Max	Unit
Sensitivity @30.8% PER	-	-94	-93	-92	dBm
Maximum received signal @30.8% PER	-	0	-	-	dBm
Co-channel C/I	-	-	+10	-	dB
	F = F0 + 1 MHz	-	-5	-	dB
	F = F0 – 1 MHz	-	-5	-	dB
Adjacent channel selectivity C/I	F = F0 + 2 MHz	-	-25	-	dB
Adjacent charmer selectivity C/1	F = F0 – 2 MHz	-	-35	-	dB
	F = F0 + 3 MHz	-	-25	-	dB
	F = F0 - 3 MHz	-	-45	-	dB
	30 MHz ~ 2000 MHz	-10	-	-	dBm
Out of hand blooking performance	2000 MHz ~ 2400 MHz	-27	-	-	dBm
Out-of-band blocking performance	2500 MHz ~ 3000 MHz	-27	-	-	dBm
	3000 MHz ~ 12.5 GHz	-10	-	-	dBm
Intermodulation	-	-36	-	-	dBm

6.5.2 Transmitter

Table 10: Transmitter Characteristics - BLE

Parameter	Conditions	Min	Тур	Max	Unit
RF transmit power	-	-	0	-	dBm
Gain control step	-	-	3	-	dBm
RF power control range	-	-12	-	+9	dBm
	$F = F0 \pm 2 MHz$	-	-52	-	dBm
Adjacent channel transmit power	$F = F0 \pm 3 \text{ MHz}$	-	-58	-	dBm
	$F = F0 \pm > 3 MHz$	-	-60	-	dBm
$\Delta f1_{ ext{avg}}$	-	-	-	265	kHz
$\Delta~f2_{\sf max}$	-	247	-	-	kHz
$\Delta f 2_{ m avg}/\Delta f 1_{ m avg}$	-	-	+0.92	-	-
ICFT	-	-	-10	-	kHz
Drift rate	-	-	0.7	-	kHz/50 μs
Drift	-	-	2	-	kHz

6.6 Reflow Profile

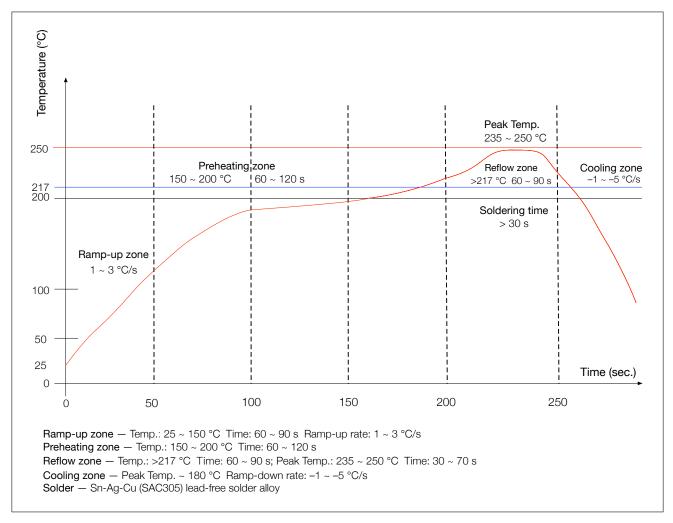


Figure 4: Reflow Profile

Note:

Solder the module in a single reflow. If the PCBA requires multiple reflows, place the module on the PCB during the final reflow.

7. Schematics

This is the reference design of the module.

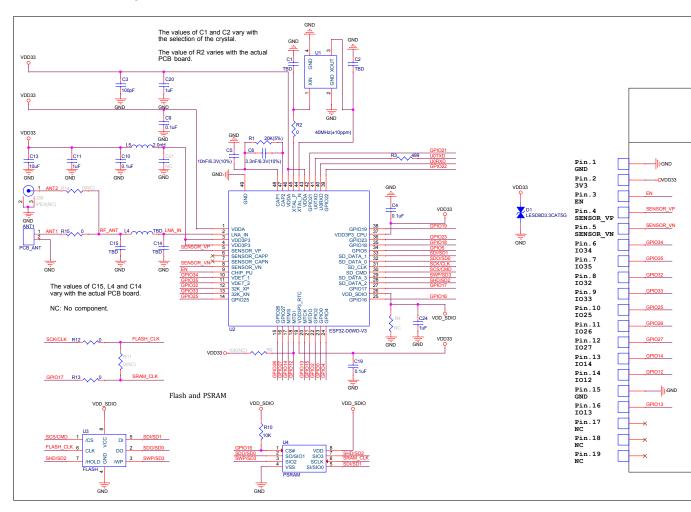


Figure 5: Schematics of ESP32-WROVER-E

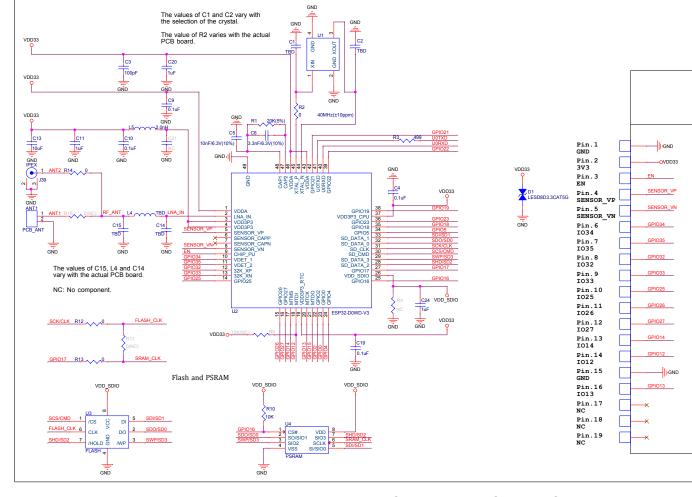


Figure 6: Schematics of ESP32-WROVER-IE

8. Peripheral Schematics

This is the typical application circuit of the module connected with peripheral components (for example, power supply, antenna, reset button, JTAG interface, and UART interface).

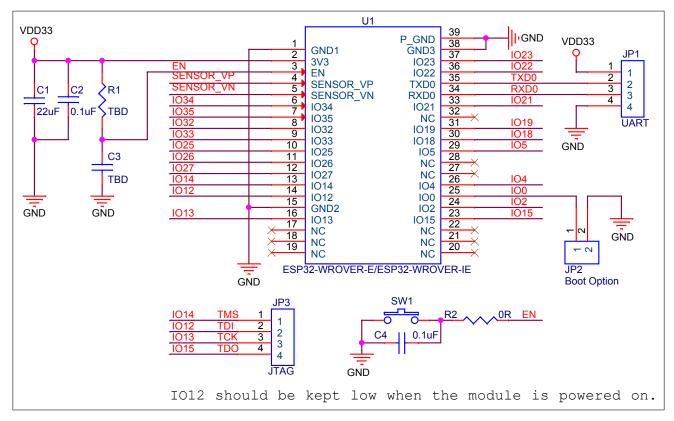


Figure 7: Peripheral Schematics

Note:

- Soldering Pad 39 to the Ground of the base board is not necessary for a satisfactory thermal performance. If users do want to solder it, they need to ensure that the correct quantity of soldering paste is applied.
- To ensure the power supply to the ESP32 chip during power-up, it is advised to add an RC delay circuit at the EN pin. The recommended setting for the RC delay circuit is usually R = 10 k Ω and C = 0.1 μ F. However, specific parameters should be adjusted based on the power-up timing of the module and the power-up and reset sequence timing of the chip. For ESP32's power-up and reset sequence timing diagram, please refer to Section *Power Scheme* in *ESP32 Datasheet*.

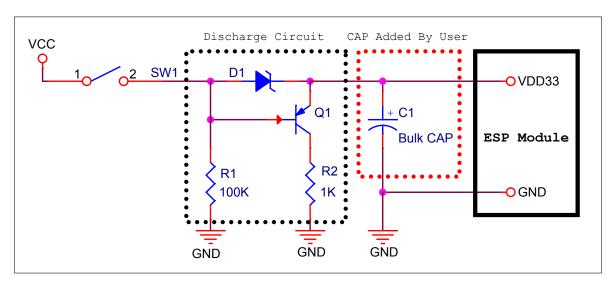


Figure 8: Discharge Circuit for VDD33 Rail

Note:

The discharge circuit can be applied in scenarios where ESP32 is powered on and off repeatedly by switching the power rails, and there is a large capacitor on the VDD33 rail. For details, please refer to Section *Power Scheme* in *ESP32 Datasheet*.

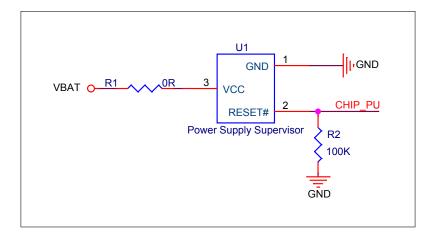


Figure 9: Reset Circuit

Note:

When battery is used as the power supply for ESP32 series of chips and modules, a supply voltage supervisor is recommended to avoid boot failure due to low voltage. Users are recommended to pull CHIP_PU low if the power supply for ESP32 is below 2.3 V.

9. Physical Dimensions

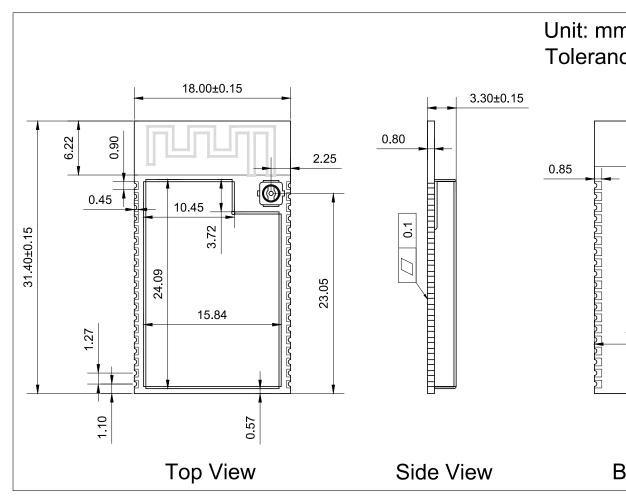


Figure 10: Physical Dimensions

10. Recommended PCB Land Pattern

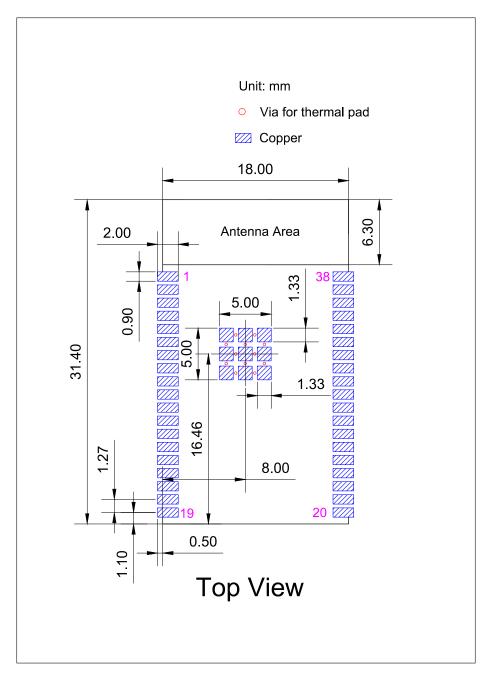


Figure 11: Recommended PCB Land Pattern

11. U.FL Connector Dimensions

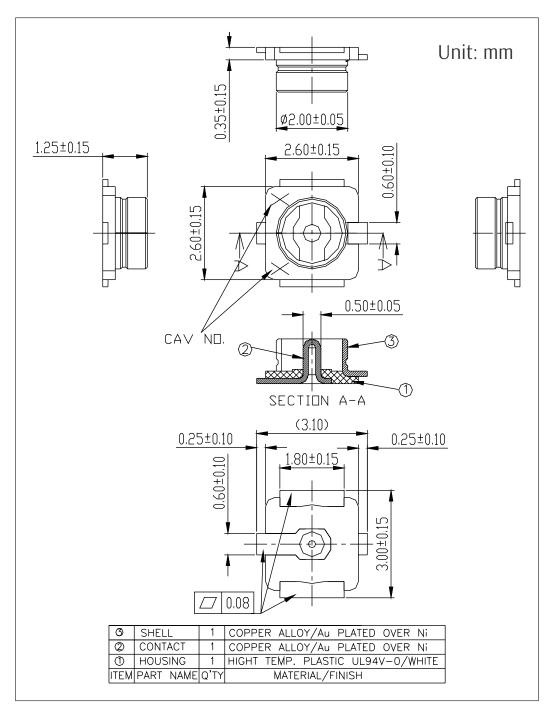


Figure 12: U.FL Connector Dimensions

12. Learning Resources

12.1 Must-Read Documents

The following link provides documents related to ESP32.

• ESP32 Datasheet

This document provides an introduction to the specifications of the ESP32 hardware, including overview, pin definitions, functional description, peripheral interface, electrical characteristics, etc.

• ESP32 ECO V3 User Guide

This document describes differences between V3 and previous ESP32 silicon wafer revisions.

• ECO and Workarounds for Bugs in ESP32

This document details hardware errata and workarounds in the ESP32.

• ESP-IDF Programming Guide

It hosts extensive documentation for ESP-IDF ranging from hardware guides to API reference.

• ESP32 Technical Reference Manual

The manual provides detailed information on how to use the ESP32 memory and peripherals.

• ESP32 Hardware Resources

The zip files include the schematics, PCB layout, Gerber and BOM list of ESP32 modules and development boards.

• ESP32 Hardware Design Guidelines

The guidelines outline recommended design practices when developing standalone or add-on systems based on the ESP32 series of products, including the ESP32 chip, the ESP32 modules and development boards.

• ESP32 AT Instruction Set and Examples

This document introduces the ESP32 AT commands, explains how to use them, and provides examples of several common AT commands.

• Espressif Products Ordering Information

12.2 Must-Have Resources

Here are the ESP32-related must-have resources.

• ESP32 BBS

This is an Engineer-to-Engineer (E2E) Community for ESP32 where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.

• ESP32 GitHub

ESP32 development projects are freely distributed under Espressif's MIT license on GitHub. It is established to help developers get started with ESP32 and foster innovation and the growth of general knowledge about the hardware and software surrounding ESP32 devices.

• ESP32 Tools

This is a webpage where users can download ESP32 Flash Download Tools and the zip file "ESP32 Certification and Test".

• ESP-IDF

This webpage links users to the official IoT development framework for ESP32.

• ESP32 Resources

This webpage provides the links to all available ESP32 documents, SDK and tools.

Revision History

Date	Version	Release notes
		Updated the following figures:
2020-06-11	V1.1	Figure 1 ESP32-WROVER-E Block Diagram
		Figure 2 ESP32-WROVER-IE Block Diagram
2020-05-22	V1.0	Official release

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