

# GD9Ax2GxF2A DATASHEET

## Contents

<b>1. FEATURES .....</b>	<b>4</b>
<b>2. GENERAL DESCRIPTION .....</b>	<b>5</b>
2.1 PRODUCT LIST .....	5
<b>3. PACKAGE .....</b>	<b>6</b>
3.1 TSOPI-48 .....	6
3.2 FBGA-63 .....	6
3.3 FBGA-48 .....	7
<b>4. BLOCK DIAGRAM .....</b>	<b>8</b>
<b>5. ARRAY ORGANIZATION .....</b>	<b>10</b>
5.1 ADDRESSING (X8) .....	11
5.2 ADDRESSING (X16) .....	11
5.3 FACTORY DEFECT MAPPING.....	12
5.3.1. Device Requirements .....	12
5.3.2. Host Requirements .....	12
<b>6. COMMAND SET .....</b>	<b>14</b>
<b>7. BUS OPERATION .....</b>	<b>15</b>
7.1 COMMAND INPUT CYCLE .....	16
7.2 ADDRESS INPUT CYCLE .....	16
7.3 DATA INPUT CYCLE.....	17
7.4 DATA OUTPUT CYCLE .....	18
7.5 WRITE PROTECT .....	19
<b>8. OPERATION DESCRIPTION .....</b>	<b>20</b>
8.1 PAGE READ OPERATION .....	20
8.1.1 Common Page Read (00H-30H).....	20
8.1.2 Random Data Output (05H-E0H).....	21
8.1.3 Random Data Output (06H-E0H).....	21
8.1.4 Cache Read Operation with Internal ECC disabled (31H/3FH) .....	22
8.1.5 Read for copy back (00H-35H).....	24
8.1.6 Special read for copy back (00H-36H) .....	24
8.1.7 Read Two Plane (00H-32H-00H-30H).....	25
8.1.8 Read for Two-Plane Copy Back (00H-32H-00H-35H) .....	26
8.2 PAGE PROGRAM OPERATION .....	27
8.2.1 Common Page Program (80H-10H).....	27
8.2.2 Page Program Operation with Random Data Input (85H-10H) .....	28
8.2.3 Page Re-program (8BH-10H).....	28
8.2.4 Cache Program Operation with Internal ECC disabled (80H-15H).....	29
8.2.5 Copy-Back Program (85H-10H) with Random Data Output (00H-35H).....	31

8.2.6 Multi-Plane Program (80H-11H-80/81H-10H) .....	31
8.2.7 Multi-Plane Re-Program (8BH-11H-8BH-10H) .....	33
8.2.8 Multi-Plane Cache Program with Internal ECC disabled (80H-11H-80/81H-15H-80H-11H-80/81H-10H).....	34
8.2.9 Multi-Plane Copy Back Program (85H-11H-85H-10H) .....	35
<b>8.3 BLOCK ERASE OPERATION.....</b>	<b>36</b>
8.3.1 Common Block Erase Operation (60H-D0H) .....	36
8.3.2 Multi-Plane Block Erase Operation (60H-60H-D0H).....	37
8.3.3 Multi-Plane Block Erase Operation-ONFI (60H-D1H-60H-D0H) .....	38
<b>8.4 RESET (FFH) .....</b>	<b>39</b>
<b>8.5 READ DEVICE INFORMATION.....</b>	<b>40</b>
8.5.1 Read ID and ONFI Signature (90H) .....	40
8.5.2 Read Unique ID (EDH) .....	43
8.5.3 Read Parameter Page (ECH) .....	44
<b>8.6 READ STATUS (70H) .....</b>	<b>49</b>
<b>8.7 READ STATUS ENHANCED – ONFI (78H).....</b>	<b>52</b>
<b>8.8 SET FEATURE (EFH) .....</b>	<b>53</b>
<b>8.9 GET FEATURE (EEH).....</b>	<b>55</b>
<b>8.10 READY/BUSY# (R/B#) .....</b>	<b>56</b>
<b>8.11 DATA PROTECTION &amp; POWER ON/OFF SEQUENCE .....</b>	<b>57</b>
<b>8.12 MULTI-PLANE OPERATION LIMITATION .....</b>	<b>58</b>
<b>8.13 INTERNAL ECC.....</b>	<b>59</b>
<b>8.14 ADDRESSING FOR PROGRAM OPERATION .....</b>	<b>61</b>
<b>8.15 SEVERAL PROGRAMMING CYCLES ON THE SAME PAGE (PARTIAL PAGE PROGRAM).....</b>	<b>62</b>
<b>9. ABSOLUTE MAXIMUM RATINGS .....</b>	<b>63</b>
<b>10. VALID BLOCKS .....</b>	<b>64</b>
<b>11. DC CHARACTERISTICS.....</b>	<b>65</b>
<b>12. AC CHARACTERISTICS.....</b>	<b>66</b>
12.1 TEST CONDITION .....	66
12.2 CAPACITANCE (TA=25°C, F=1.0MHz).....	66
12.3 AC TIMING CHARACTERISTICS .....	67
12.4 PERFORMANCE CHARACTERISTICS.....	68
<b>13. PACKAGE INFORMATION .....</b>	<b>69</b>
13.1 TSOPI-48 .....	69
13.2 FBGA-63 .....	71
13.3 FBGA-48 .....	72
<b>14. PART NUMBERING INFORMATION.....</b>	<b>73</b>
<b>15. REVISION HISTORY .....</b>	<b>74</b>

## 1. FEATURES

- ◆ Single level cell technology
- ◆ ONFI 1.0 Compatible
- ◆ Power Supply Voltage
  - VCC/VCCQ = 1.7 ~ 1.95v(GD9AS)
  - VCC/VCCQ = 2.7 ~ 3.6v (GD9AU)
- ◆ Memory Cell Organization
  - Page size:
    - X8: 2K + 64bytes
    - X16: 1K + 32words
  - Block size: 64 pages
    - X8: 128K + 4K bytes
    - X16: 64K + 2K words
  - Plane size: 1024 blocks
  - Device size: 2Gb: 2048 blocks
- ◆ Page Read / Program time
  - Random Read Time (tR): 50us Max.
  - Sequential Access Time
    - 3.3v Device: 20ns Min.
    - 1.8v Device: 25ns Min.
  - Page Program(tPROG): 400us Typ.
- ◆ Block Erase
  - Block Erase Time(tBERS): 3ms Typ.
- ◆ Advantage Feature
  - cache read
  - multi-plane operation
- ◆ Operating Current
  - Read(25ns cycle): 15mA
  - Program(Typ): 15mA
  - Erase(Typ): 15mA
  - Standby(Max):50uA (CMOS)
- ◆ Reliability
  - P/E cycles with ECC: 100K
  - Data retention: 10 Years
- ◆ Internal ECC
  - 4bit/528bytes
- ◆ Operating Temperature
  - Industrial (I): -40°C ~ 85°C
- ◆ Chip Enable Don't Care Option
- ◆ Security
  - OTP area
  - Protection with WP#
  - UID
- ◆ Package
  - TSOP48 12mm x 20mm
  - FBGA63 9mm x 11mm
  - FBGA48 6mm x 8mm

Note: 1. ECC on is default, which can enable/disable by user after power-on.

## 2. GENERAL DESCRIPTION

GigaDevice GD9Ax2GxF2A is 2Gbit with 64Mbit spare capacity. A program operation can be performed in typical tPROG on the whole page and an erase operation can be performed in typical tBERS on each block. Data in the page can be read out at tRC cycle time per byte. The I/O pins serve as the ports for address and data input/output as well as command input. GD9Ax2GxF2A provides extended reliability of 100K program/erase cycles with ECC (Error Correcting Code).

### 2.1 Product List

PART NUMBER	ORGANIZATION	VCC RANGE	PACKAGE
GD9AU2G8F2A	256M x 8bit	2.7v ~ 3.6v	TSOP48/ FBGA63/BGA48
GD9AU2G6F2A	128M x 16bit	2.7v ~ 3.6v	TSOP48/ FBGA63/BGA48
GD9AS2G8F2A	256M x 8bit	1.7v ~ 1.95v	TSOP48/ FBGA63/BGA48
GD9AS2G6F2A	128M x 16bit	1.7v ~ 1.95v	TSOP48/ FBGA63/BGA48

### 3. PACKAGE

#### 3.1 TSOPI-48

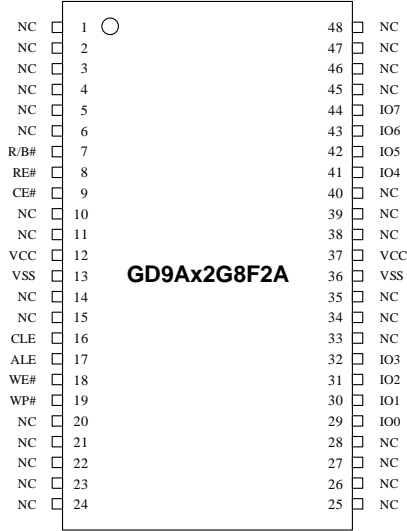


Figure3-1\_a: GD9Ax2G8F2AMG package figures

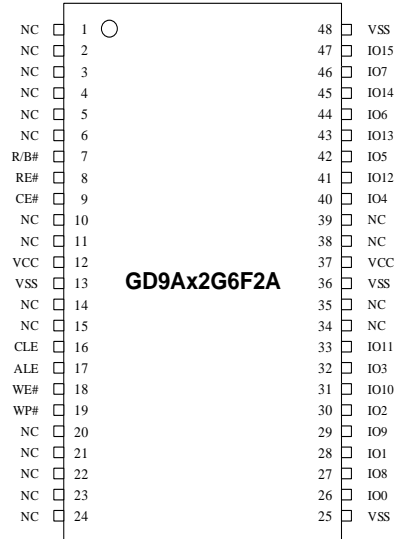


Figure3-1\_b: GD9Ax2G6F2AMG package figures

#### 3.2 FBGA-63

	1	2	3	4	5	6	7	8	9	10
A	NC	NC							NC	NC
B	NC								NC	NC
C			WP#	ALE	VSS	CE#	WE#	R/B#		
D			NC	RE#	CLE	NC	NC	NC		
E			NC	NC	NC	NC	NC	NC		
F			NC	NC	NC	NC	NC	NC		
G			NC	NC	NC	NC	NC	NC		
H			NC	IO0	NC	NC	NC	VCC		
J			NC	IO1	NC	VCC	IO5	IO7		
K			VSS	IO2	IO3	IO4	IO6	VSS		
L	NC	NC							NC	NC
M	NC	NC							NC	NC

TOP VIEW

GD9Ax2G8F2A

	1	2	3	4	5	6	7	8	9	10
A	NC	NC							NC	NC
B	NC								NC	NC
C			WP#	ALE	VSS	CE#	WE#	R/B#		
D			NC	RE#	CLE	NC	NC	NC		
E			NC	NC	NC	NC	NC	NC		
F			NC	NC	NC	NC	NC	NC		
G			NC	NC	NC	IO13	IO15	NC		
H			IO8	IO0	IO10	IO12	IO14	VCC		
J			IO9	IO1	IO11	VCC	IO5	IO7		
K			VSS	IO2	IO3	IO4	IO6	VSS		
L	NC	NC							NC	NC
M	NC	NC							NC	NC

TOP VIEW

GD9Ax2G6F2A

Figure3-2\_a: 63-FBGA x8 device ball location figures

Figure3-2\_b: 63-FBGA x16 device ball location figures

### 3.3 FBGA-48

	1	2	3	4	5	6
A	WP#	ALE	VSS	CE#	WE#	R/B#
B	NC	RE#	CLE	NC	NC	NC
C	NC	NC	NC	NC	NC	NC
D	NC	NC	NC	NC	NC	NC
E	NC	NC	NC	NC	NC	NC
F	NC	IO0	NC	NC	NC	VCC
G	NC	IO1	NC	VCC	IO5	IO7
H	VSS	IO2	IO3	IO4	IO6	VSS

TOP VIEW

Figure 3-3\_a: 48-FBGA x8 device ball location figures

	1	2	3	4	5	6
A	WP#	ALE	VSS	CE#	WE#	R/B#
B	NC	RE#	CLE	NC	NC	NC
C	NC	NC	NC	NC	NC	NC
D	NC	NC	NC	NC	NC	NC
E	NC	NC	NC	IO13	IO15	NC
F	IO8	IO0	IO10	IO12	IO14	VCC
G	IO9	IO1	IO11	VCC	IO5	IO7
H	VSS	IO2	IO3	IO4	IO6	VSS

TOP VIEW

Figure 3-3\_b: 48-FBGA x16 device ball location figures

## 4. BLOCK DIAGRAM

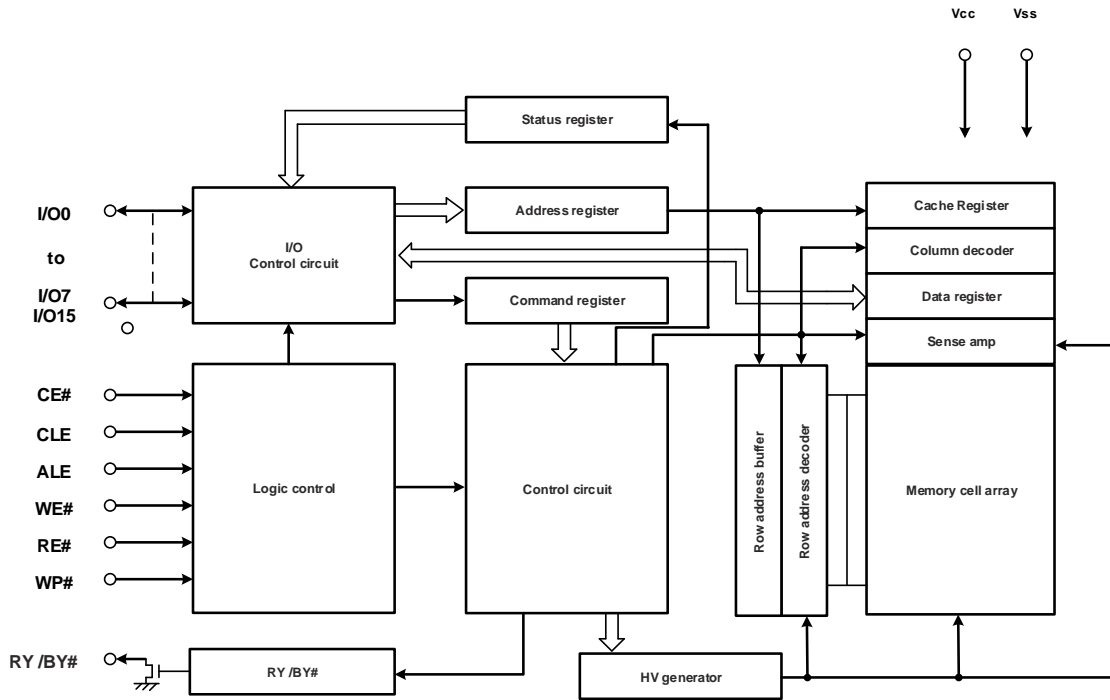


Figure 4-1: Block Diagram figures



**PIN DESCRIPTION**

Signal Name	Input/ Output	Description
R/B#	O	Ready/Busy : Open drain output to indicate the target status, low to indicate that one or more operations are in progress.
RE#	I	Read Enable : Enables serial data output, active low.
CE#	I	Chip Enable : When high and the target is in the ready state, the target goes into a low-power standby state. When low, the target is selected.
CLE	I	Command Latch Enable : Enable signal to load a command into the target on the rising edge of WE#, active high.
ALE	I	Address Latch Enable : Enable signal to load an address into the target on the rising edge of WE#, active high.
WE#	I	Write Enable : Data, Commands, and Addresses are latched on the rising edge of WE#.
WP#	I	Write Protect : Low to disable Flash array program and erase operations.
IO0 ~ IO7	I/O	I/O Port, bits 0-7 : 8-bit wide bidirectional port for transferring address, command, and data to and from the device.
IO8 ~ IO15	I/O	I/O Port, bits 8-15 : Upper 8 bits for the 16-bit wide bidirectional port used to transfer data to and from the device.
VCC	I	Power : Power supply to the device.
VSS	I	Ground : Power supply ground.
NC	-	No Connection : Lead is not internally connected.

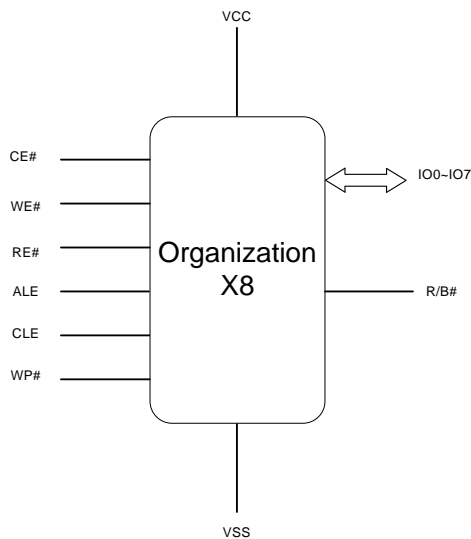


Figure 4-2\_a: GD9Ax2G8F2A figures

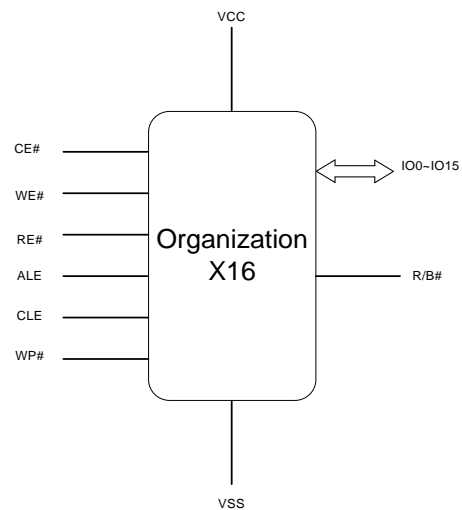


Figure 4-2\_b: GD9Ax2G6F2A figures

## 5. ARRAY ORGANIZATION

Each device has	Each block has	Each page has	
2Gb			
256M+8M	128K+4K	2K+64	bytes
2048 x 64	64	-	pages
2048	-	-	blocks

Logical Unit

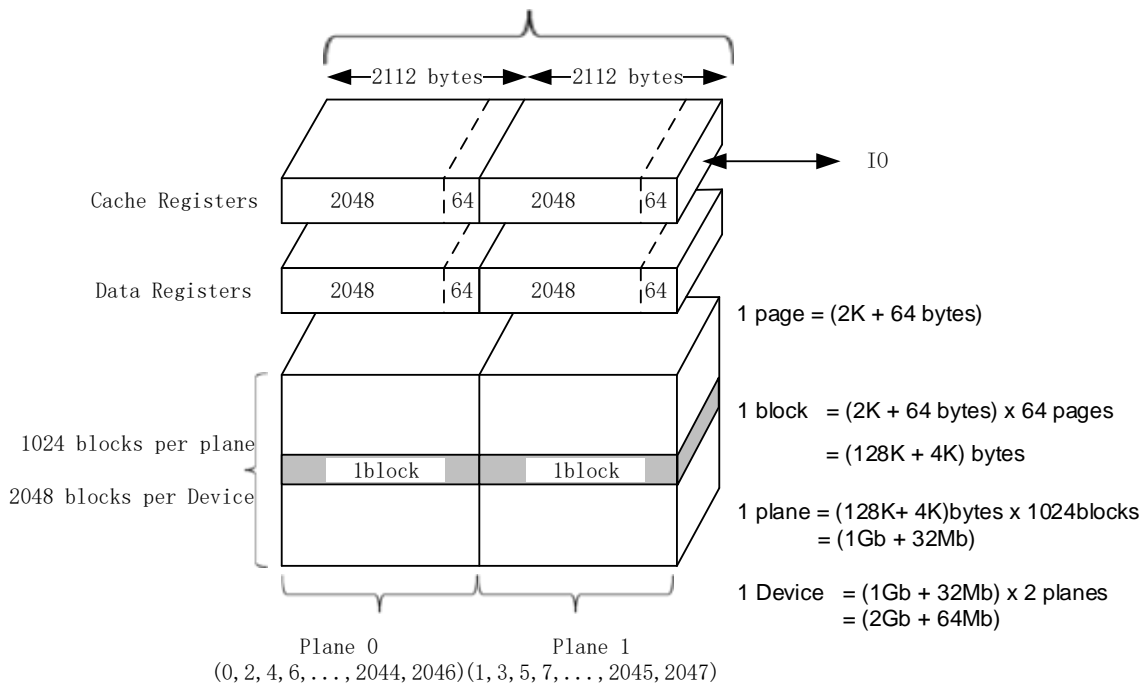


Figure 5-1: Array Organization figures

## 5.1 Addressing (X8)

Bus Cycle	IO0	IO1	IO2	IO3	IO4	IO5	IO6	IO7
1 <sup>st</sup> Cycle	A0	A1	A2	A3	A4	A5	A6	A7
2 <sup>nd</sup> Cycle	A8	A9	A10	A11	L	L	L	L
3 <sup>rd</sup> Cycle	A12	A13	A14	A15	A16	A17	A18	A19
4 <sup>th</sup> Cycle	A20	A21	A22	A23	A24	A25	A26	A27
5 <sup>th</sup> Cycle	A28	L	L	L	L	L	L	L

A0-A11: column address in the page

A12-A17: page address in the block

A18: plane address (for multi-plane operations) / block address (for normal operations)

A18-A28: block address

## 5.2 Addressing (X16)

Bus Cycle	IO0	IO1	IO2	IO3	IO4	IO5	IO6	IO7
1 <sup>st</sup> Cycle	A0	A1	A2	A3	A4	A5	A6	A7
2 <sup>nd</sup> Cycle	A8	A9	A10	L	L	L	L	L
3 <sup>rd</sup> Cycle	A11	A12	A13	A14	A15	A16	A17	A18
4 <sup>th</sup> Cycle	A19	A20	A21	A22	A23	A24	A25	A26
5 <sup>th</sup> Cycle	A27	L	L	L	L	L	L	L

A0-A10: column address in the page

A11-A16: page address in the block

A17: plane address (for multi-plane operations) / block address (for normal operations)

A17-A27: block address

## 5.3 Factory Defect Mapping

The Flash array is not presumed to be pristine, and a number of defects that makes the blocks unusable may be present. Invalid blocks shall be sorted out from normal blocks by software.

### 5.3.1. Device Requirements

If a block is defective, the manufacturer shall mark the block as defective by setting the Defective Block Marking, as shown in Figure of “Area marked in first or last page of block indicating defect”, of the last page of the defective block to a value of non-FFh. The Defective Block Marking is located on the first byte of user data area or the first byte of spare data area in the pages within a block.

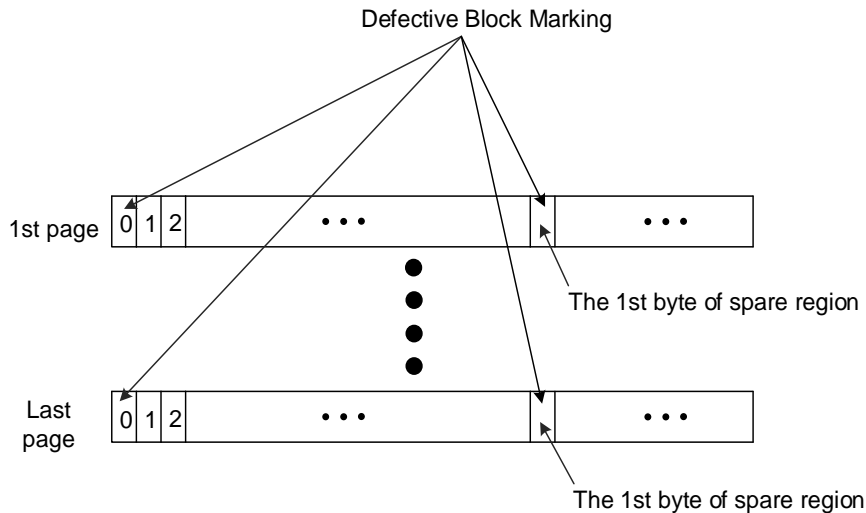


Figure 5-2: area marked in first or last page of block indicating defect sequential figures

### 5.3.2. Host Requirements

The host shall not erase or program blocks marked as defective by the manufacturer, and any attempt to do so yields indeterminate results.

Figure of “Flow chart to create initial invalid block table” outlines the flow chart how to create an initial invalid block table. It should be performed by the host to create the initial bad block table prior to performing any erase or programming operations on the target. The 1st byte of both main and spare region in non-defective blocks are read FFh with ECC enabled on the controller. A defective block is indicated by the majority of bits being read non-FFh in the Defective Block Marking location of either the first page or last page of the block. The host shall check the Defective Block Marking location of both the first and last past page of each block to verify the block is valid prior to any erase or program operations on that block.

NOTE: Over the lifetime use of a NAND device, the Defective Block Marking of defective blocks may encounter read disturbs that cause bit changes. The initial defect marks by the manufacturer may change value over the lifetime of the device, and are expected to be read by the host and used to create a bad block table during initial use of the part.

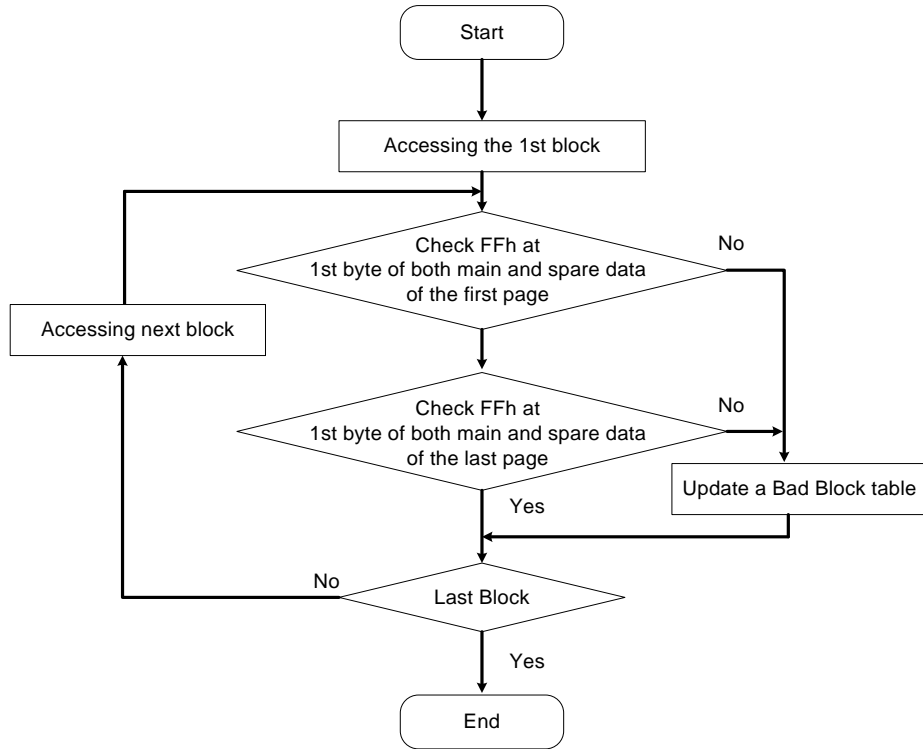


Figure 5-3: flow chart to create initial invalid block table sequential figures

## 6. COMMAND SET

Function	1 <sup>st</sup>	2 <sup>nd</sup>	3 <sup>rd</sup>	4 <sup>th</sup>	During busy
Page read	00H	30H	--	--	No
Read for copy-back	00H	35H	--	--	No
Special read for copy back	00H	36H	--	--	No
Random data output(change column address)	05H	E0H	--	--	No
Random data output(change row address)	06H	E0H	--	--	No
Cache read start	31H	--	--	--	No
Cache read random	00H	31H	--	--	No
Cache read end	3FH	--	--	--	No
Read id	90H	--	--	--	No
Read status register	70H	--	--	--	Yes
Read status enhanced (ONFI)	78H	--	--	--	Yes
Page program start / Cache program end	80H	10H	--	--	No
Random data input	85H	--	--	--	No
Copy back program	85H	10H	--	--	No
Cache program start	80H	15H	--	--	No
Block erase	60H	D0H	--	--	No
Reset	FFH	--	--	--	Yes
Page re-program	8BH	10H	--	--	No
Read parameter page	ECH	--	--	--	No
Read unique ID	EDH	--	--	--	No
Get Features	EEH	--	--	--	No
Set Features	EFH	--	--	--	No
Multi-Plane program	80H	11H	80/81H	10H	No
Multi-Plane re-program	8BH	11H	8BH	10H	No
Multi-Plane cache program	80H	11H	80/81H	15H	
	80H	11H	80/81H	10H	No
Multi-Plane copy back program	85H	11H	85H	10H	No
Multi-Plane block erase	60H	60H	D0H		No
Multi-Plane block erase (ONFI)	60H	D1H	60H	D0H	No
Read page two-plane	00H	32H	00H	30H	No
Read for two-plane copy back	00H	32H	00H	35H	No

## 7. BUS OPERATION

The bus on the device is multiplexed. Data I/O, addresses, and commands all share the same pins. I/O[15:8] are used only for data in the x16 configuration. Addresses and commands are always supplied on I/O[7:0].

The command sequence typically consists of a COMMAND LATCH cycle, address input cycles, and one or more data cycles, either READ or WRITE.

There are several standard bus operations that control the device. These are Command Input, Address Input, Data Input, Data Output, Write Protect, and Standby.

CLE	ALE	CE#	WE#	RE#	WP#	MODE
H	L	L	Rising	H	X	Command input for read mode
L	H	L	Rising	H	X	Address input (5 cycles) for read mode
H	L	L	Rising	H	H	Command input for write mode
L	H	L	Rising	H	H	Address input (5 cycles) for write cycle
L	L	L	Rising	H	H	Data input
L	L	L	H	Falling	X	Sequential read and data output
L	L	L	H	H	X	During read(busy)
X	X	X	X	X	H	During program/Erase(busy)
X	X	X	X	X	L	Write protect
X	X	H	X	X	0V / VCC	Standby

### Notes:

1. X can be VIL or VIH. H = Logic level HIGH. L = Logic level LOW.
2. WP# should be biased to CMOS high or CMOS low for stand-by mode.
3. WE# and RE# during Read Busy must be keep on high to prevent unplanned command/address/data input or to avert unintended data out. In this time, only Reset and Read Status can be input to the device.

## 7.1 Command Input Cycle

Command Input bus operation is used to give a command to the memory device. Commands are accepted with Chip Enable low, Command Latch Enable High, Address Latch Enable low and Read Enable High and latched on the rising edge of Write Enable. Moreover for commands that starts a modify operation (write/erase) the Write Protect pin must be high.

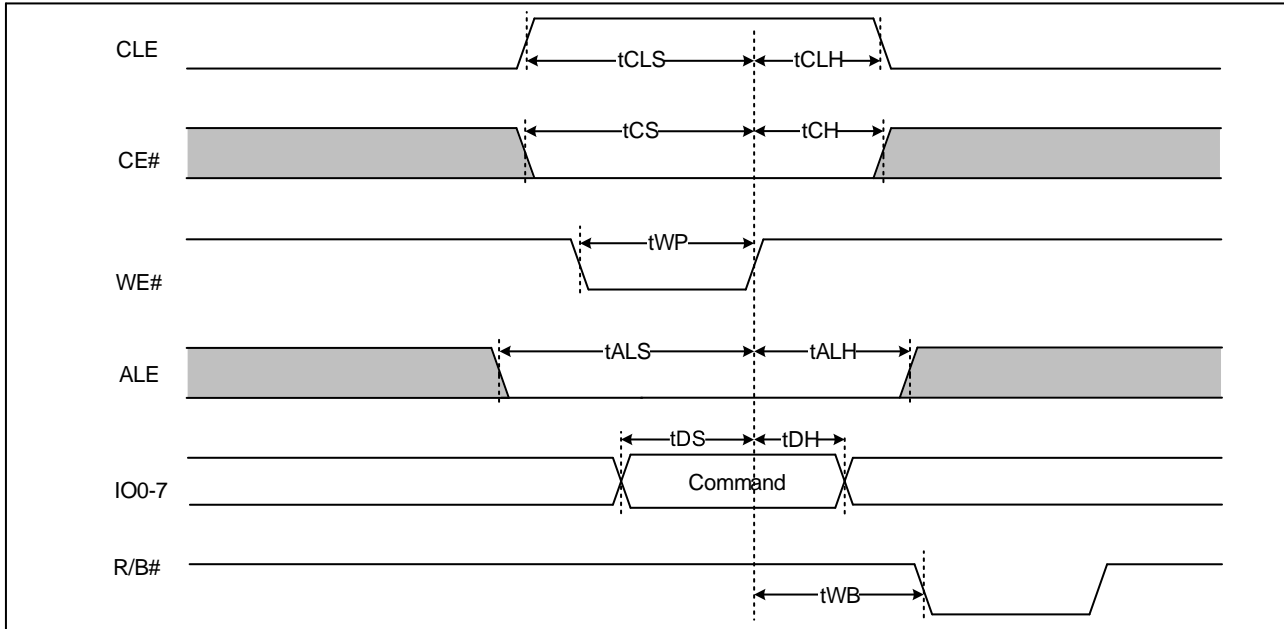


Figure 7-1: Command Input Cycle figures

## 7.2 Address Input Cycle

Address Input bus operation allows the insertion of the memory address. Addresses are accepted with Chip Enable low, Address Latch Enable High, Command Latch Enable low and Read Enable High and latched on the rising edge of Write Enable. Moreover for commands that starts a modify operation (write/erase) the Write Protect pin must be high.

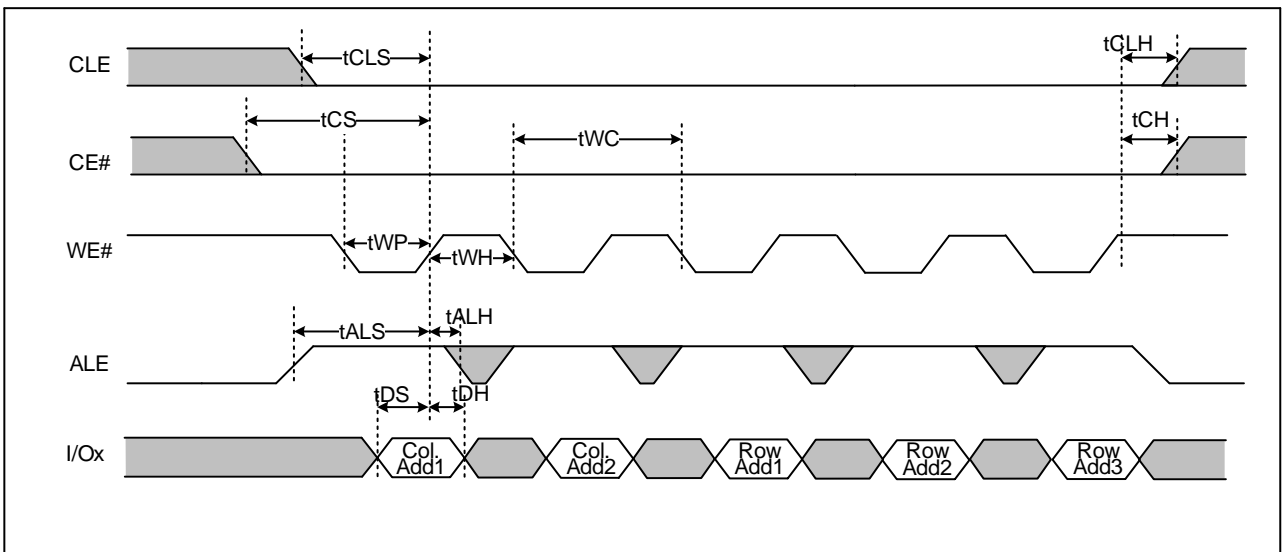


Figure 7-2: Address Input Cycle figures



### 7.3 Data Input Cycle

Data Input bus operation allows to feed to the device the data to be programmed. The data insertion is serially and timed by the Write Enable cycles. Data are accepted only with Chip Enable low, Address Latch Enable low, Command Latch Enable low, Read Enable High, and Write Protect High and latched on the rising edge of Write Enable.

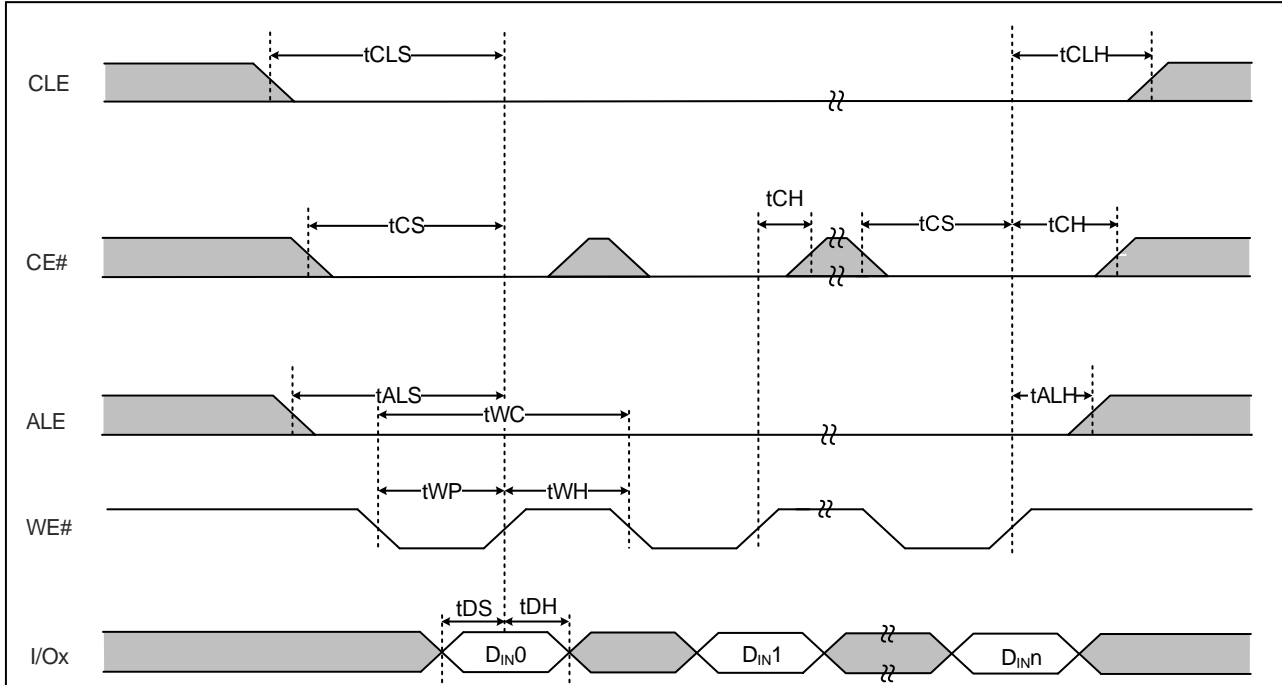


Figure 7-3: Data Input Cycle figures

## 7.4 Data Output Cycle

Data Output bus operation allows to output data from the device. The data output cycle is serially and timed by the Read Enable cycles. Data output may be used with CE# don't care. However, if CE# don't care is used tCEA and tCOH timing requirements shall be met by the host.

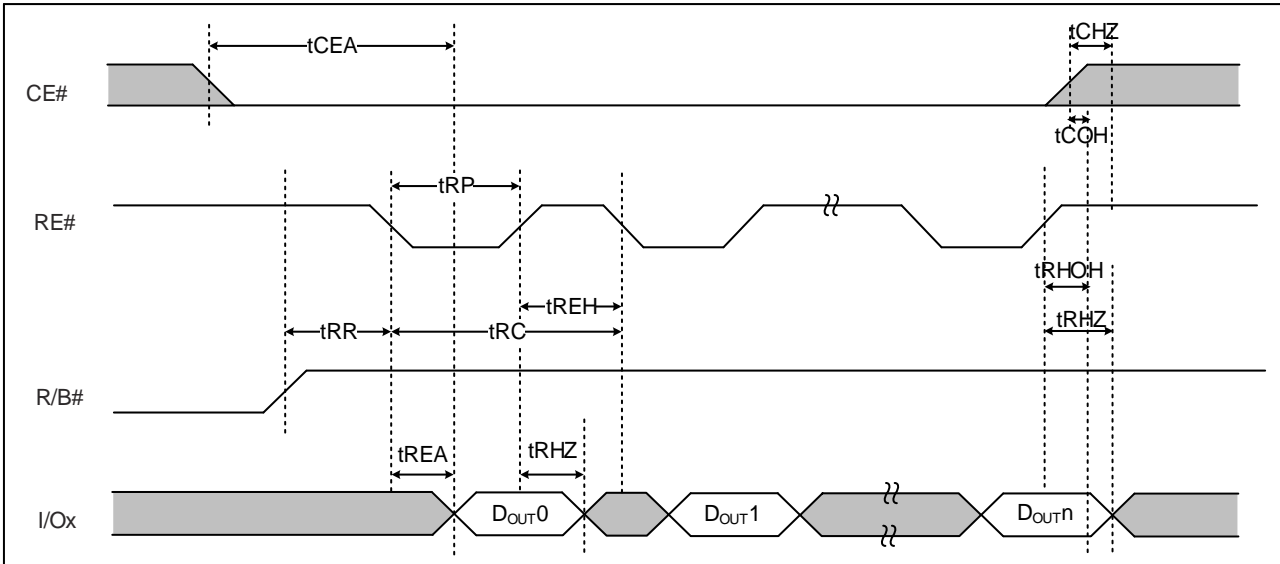


Figure 7-4\_a: Data Output Cycle figures

If the host side uses a sequential access time ( $t_{RC}$ ) of less than 30ns, the data can be latched on the next falling edge of RE# as the waveform of EDO (Extended data output) mode.

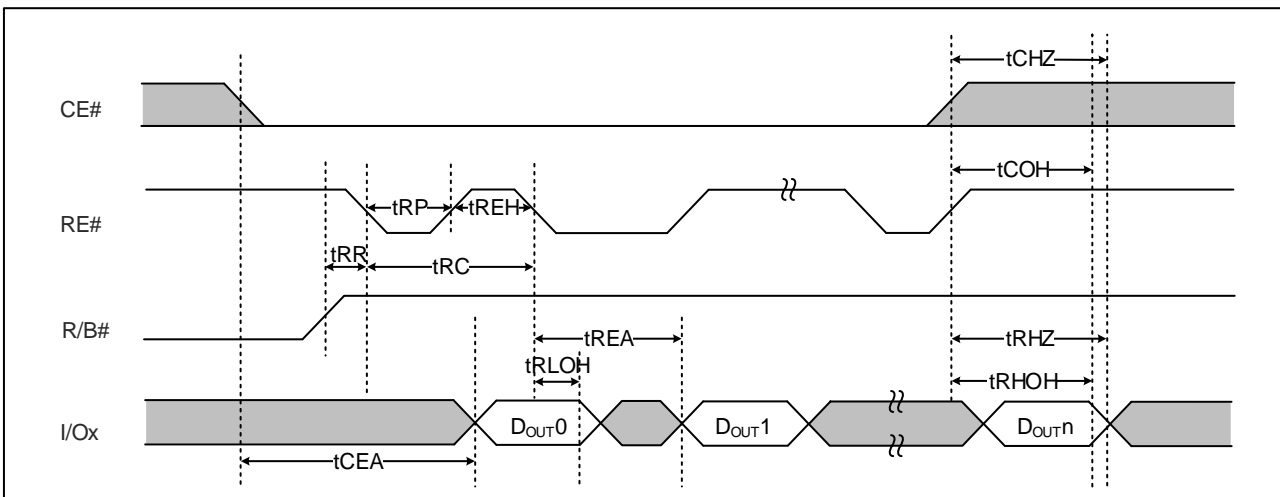


Figure 7-4\_b: Data Output Cycle figures

## 7.5 Write Protect

The Erase and Program Operations are automatically reset when WP# goes Low. The operations are enabled and disabled as follows.

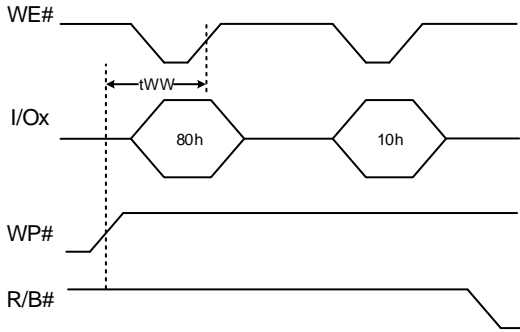


Figure7-5\_a: Write Protect Disable with program figures

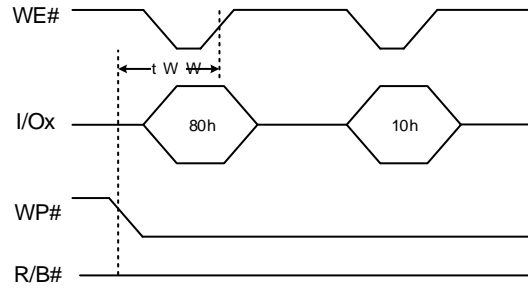


Figure 7-5\_b: Write Protect Enable with program figures

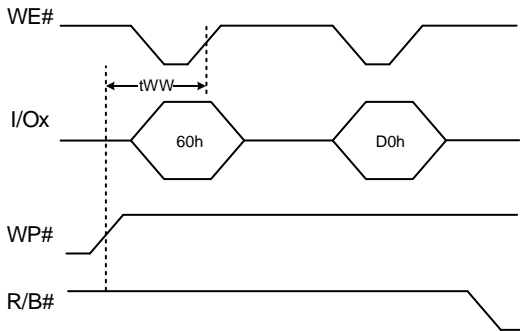


Figure 7-5\_c: Write Protect Disable with erase figures

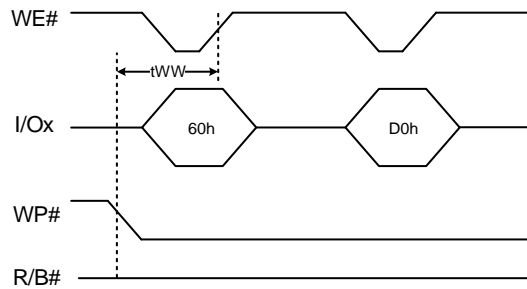


Figure 7-5\_d: Write Protect Enable with erase figures

## 8. OPERATION DESCRIPTION

### 8.1 Page Read Operation

#### 8.1.1 Common Page Read (00H-30H)

Read is initiated by writing 00H-30H to the command register along with five address cycles. After initial power up, 00h command is latched automatic, therefore only 5 address cycles and 30H command are need input to initiates the read operation. Then the whole page bytes data within the selected page are transferred to the cache registers. The system controller can detect the completion of this data transfer ( $t_R$ ) by analyzing the output of R/B# pin or read status command. Once the data in a page is loaded into the data registers, they may be read out in  $t_{RC}$  by sequentially toggle RE#. The repetitive high to low transitions of the RE# clock make the device output the data starting from the selected column address up to the last column address.

After the last data has been read out, CE# may be pulled up for some time to end the read operation, while during the RE# toggle cycle, CE# maybe don't care when RE# is high. The CE# don't care feature may simplify the system interface, which allows controller to directly download the code from flash device, and the CE# transitions will not stop the read operation during the latency time.

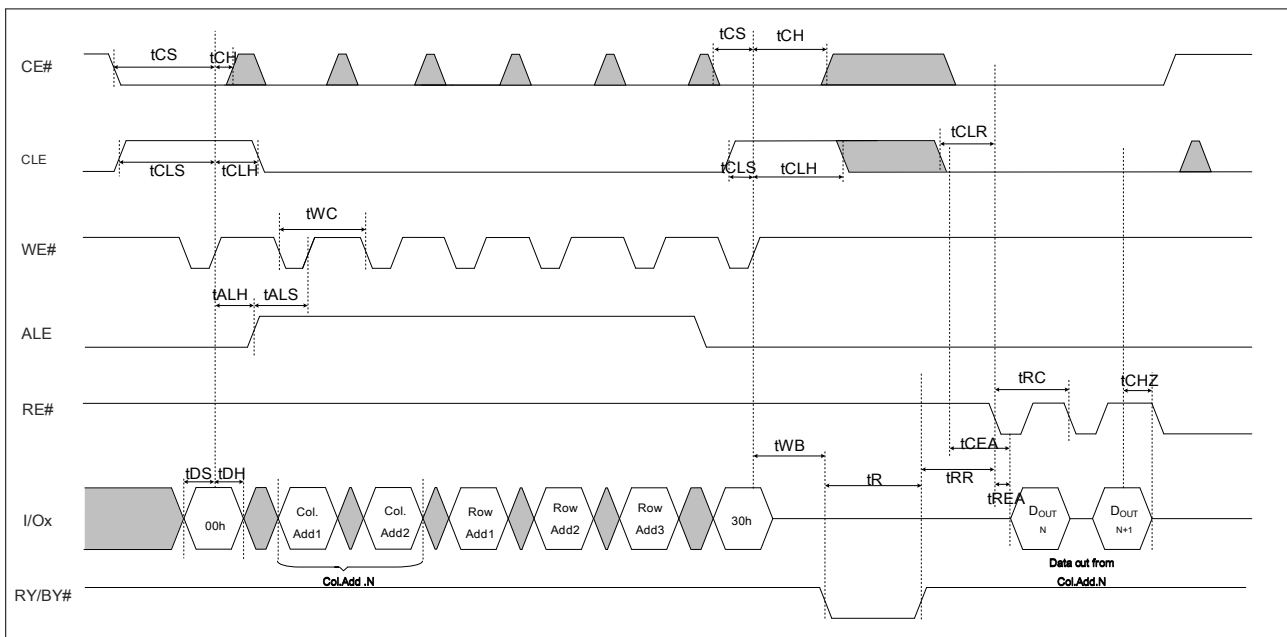


Figure 8-1: Common Page Read figures

### 8.1.2 Random Data Output (05H-E0H)

The device may output random data in a page instead of the consecutive sequential data by writing random data output command (05H-E0H). The column address of next data, which is going to be out, may be changed to the address which follows random data output command. Random data output can be operated multiple times regardless of how many times it is done in a page Change Read Column shall only be issued when the device is in a read idle condition.

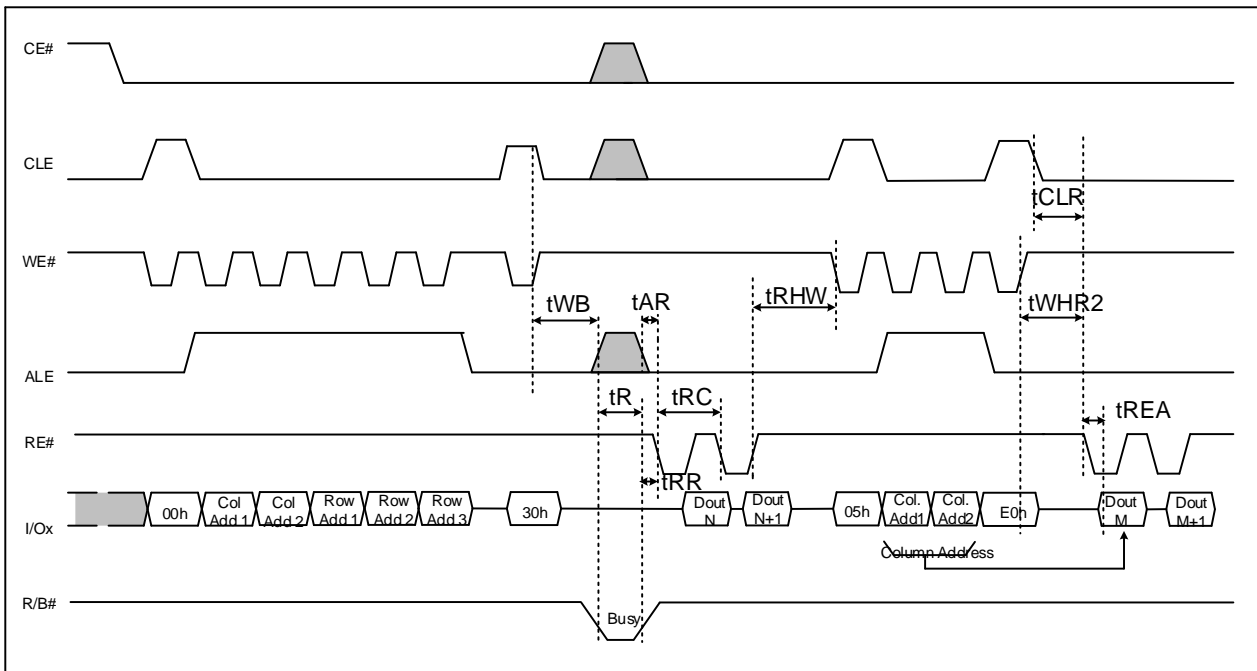


Figure 8-2: Random Data Output figures

Note: the address followed 05h can be only 2bytes address cycle.

### 8.1.3 Random Data Output (06H-E0H)

The device may output random data in a page instead of the consecutive sequential data by writing random data output command (06H-E0H). The row address and column address of next data, which is going to be out, may be changed to the address which follows random data output command. Random data output can be operated multiple times regardless of how many times it is done in a page. Change Read Row shall only be issued when the device is in a read idle condition.

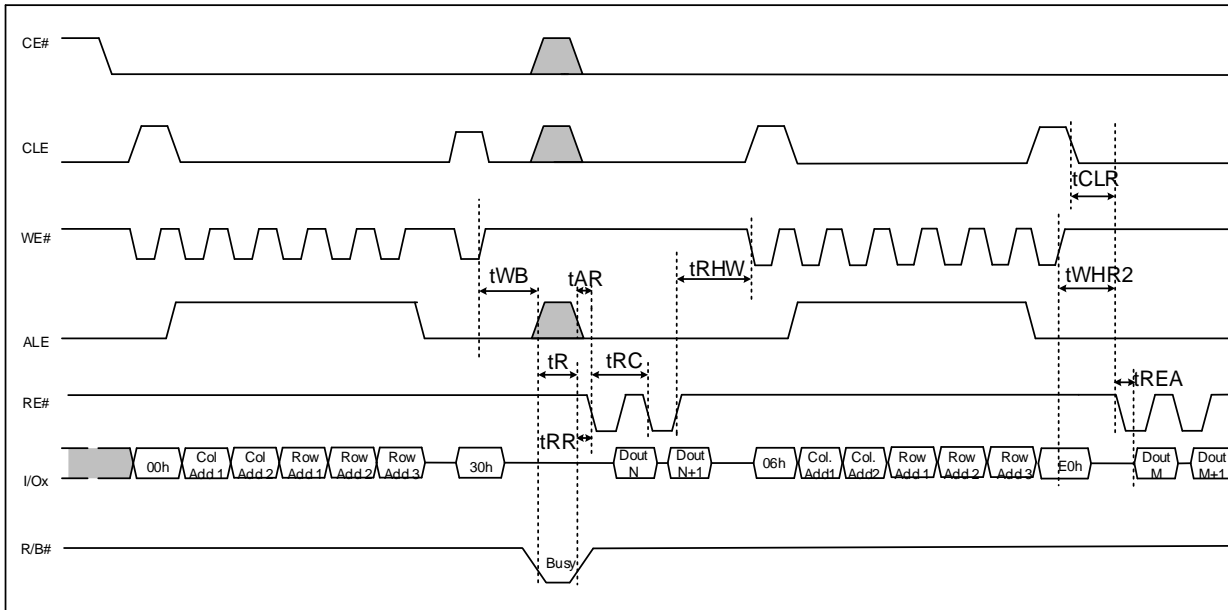


Figure 8-3: Random Data Output sequential figures

Note: the address followed 06h can be 2bytes address cycle or 5 bytes address cycle.

### 8.1.4 Cache Read Operation with Internal ECC disabled (31H/3FH)

The Cache Read function permits a page to be read from the cache register while another page is simultaneously read from the Flash array. A Read Page command shall be issued prior to the initial sequential or random Read Cache command in a read cache sequence. A Read Cache command shall be issued prior to a Read Cache End (3FH) command being issued. The Cache Read function may be issued after the Read function is complete. The host may enter the address of the next page to be read from the Flash array. Data output always begins at column address 00H. If the host does not enter an address to retrieve, the next sequential page is read, when the Read Cache function is issued. After the operation, R/B# is set to high (ready) and the host may begin to read the data from the previous Read or Read Cache function. Issuing an additional Read Cache function copies the data most recently read from the array into the cache register. When no more pages are to be read, the final page is copied into the cache register by issuing the 3FH command.

The host may begin to read data from the cache register when R/B# is set to high (ready). When the 31H and 3FH commands are issued, R/B# shall be cleared to low (busy) until the whole page data has finished being copied from the Flash array to cache register.

Note: These commands supported only with ECC disabled

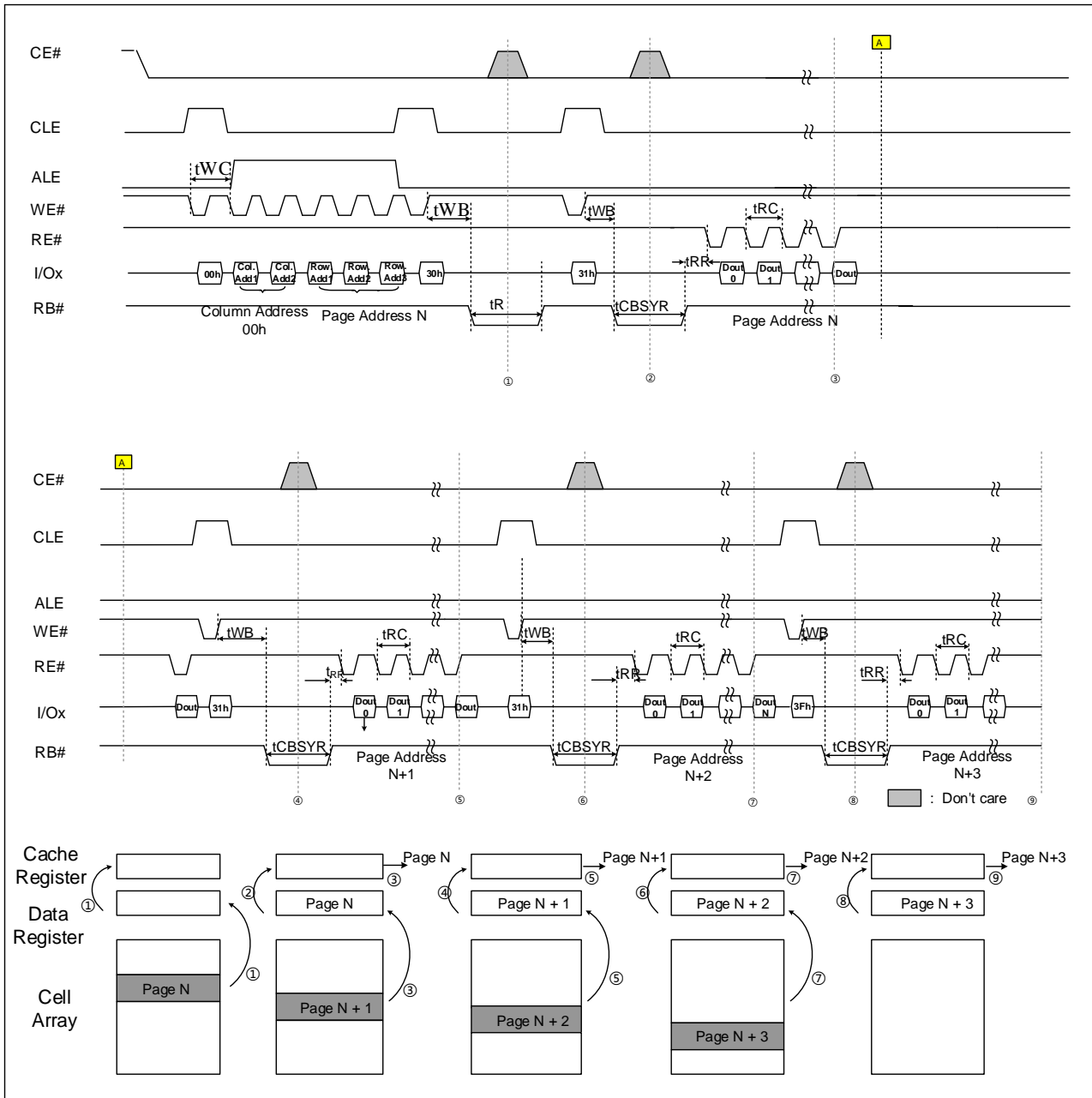


Figure 8-4: Cache Read Operation figures

Note:

C1-C2 : Column address of the page to retrieve. C1 is the least significant byte.

R1-R3 : Row address of the page to retrieve. R1 is the least significant byte.

D0-Dn : Data bytes/words read from page requested by the original Read or the previous cache operation.

### 8.1.5 Read for copy back (00H-35H)

The Copy-Back Read is configured to efficiently rewrite data stored in a page without data reloading when no error within the page is found. The data is read out only at cache buffer for copy-back program.

Though it is not required, it is recommended that the host read the data out of the device to verify the data prior to issuing the Copy-Back Program (85h-10h) command to prevent the propagation of data errors.

If internal

is enabled, the data does not need to be toggled out by the host to be corrected and moving data can then be written to a new page without data reloading, which improves system performance.

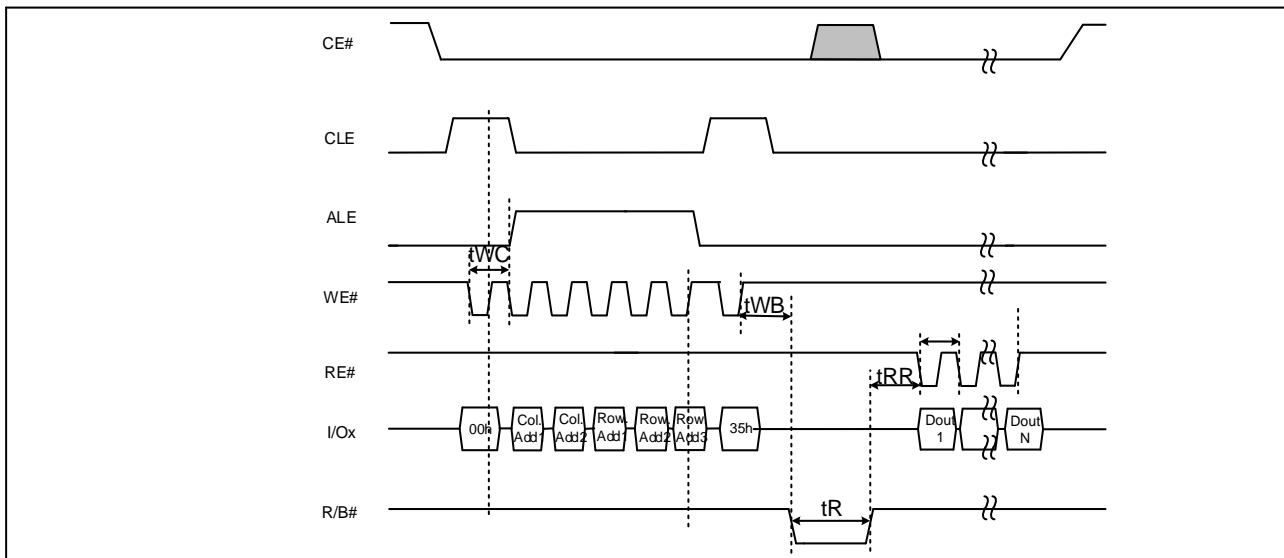


Figure 8-5: Copy-Back read sequential figures

### 8.1.6 Special read for copy back (00H-36H)

If copy back read is triggered with confirm command "36h" instead "35h", copy-back read from target page(s) will be executed with an increased internal voltage.

This special feature is used in order to try to recover incorrigible ECC read errors due to over-program or read disturb: it shall be used ONLY if ECC read errors have occurred in the source page using "standard read" or "standard read for copy back" sequences.

Before the copy-back read command (36H) is issued, all other features described in standard copy-back remain valid.



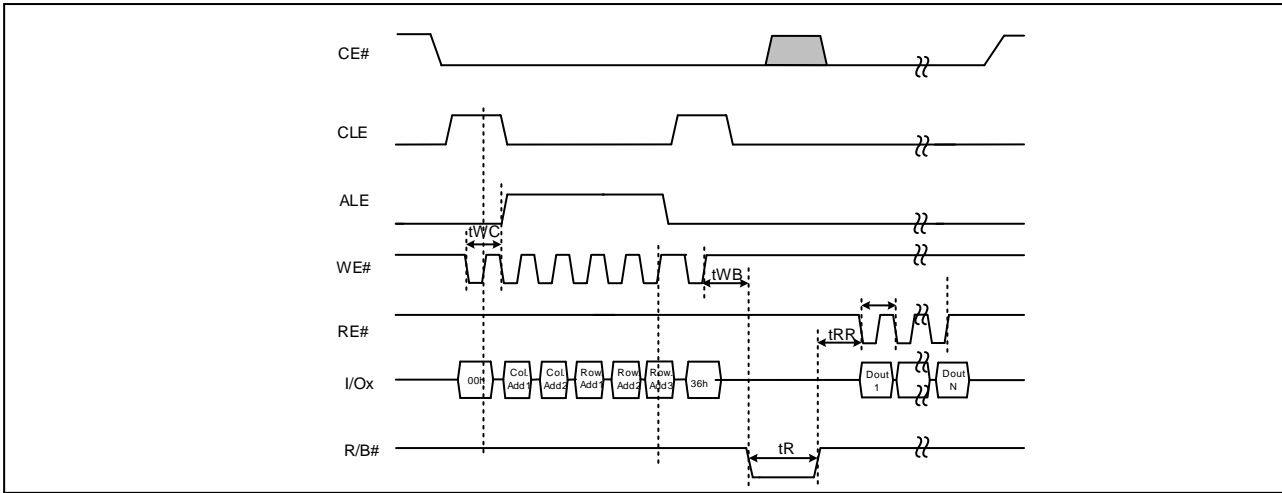


Figure 8-6: Special read for copy-back sequential figures

### 8.1.7 Read Two Plane (00H-32H-00H-30H)

The Two-Plane Page Read operation is an extension of the Page Read operation. The device supporting Two-plane page read operation also allows multi Random data-output from each plane(i.e. Two-Plane Random Data Output) once multi-pages from each plane are loaded to cache registers. With the primary command, R/B# returns to ready in a short time (i.e.  $t_{DBSY}$ ) after the first command 32h since it does not load data from a selected page, and the selected page data of each plane are transferred to the cache registers in less than  $t_R$  (or  $t_{R\_ECC}$ ) after command 30h. When setting page addresses of each plane, the page addresses shall be identical although block addresses differ.

The Two-plane addresses shall be set in a consecutive manner from a lower address plane to a higher address plane and the same plane address shall not be set twice within a set of address setting sequence for the Two-Plane Page Read Operation.

Once the data is loaded into the cache registers, the data on the first plane can be read out by issuing the Two-Plane Random Data Output command. The data on the other plane can be also read out using the identical command sequences. The following figure defines Two-plane Page Read and Two-Plane Random Data Output behavior and timings.

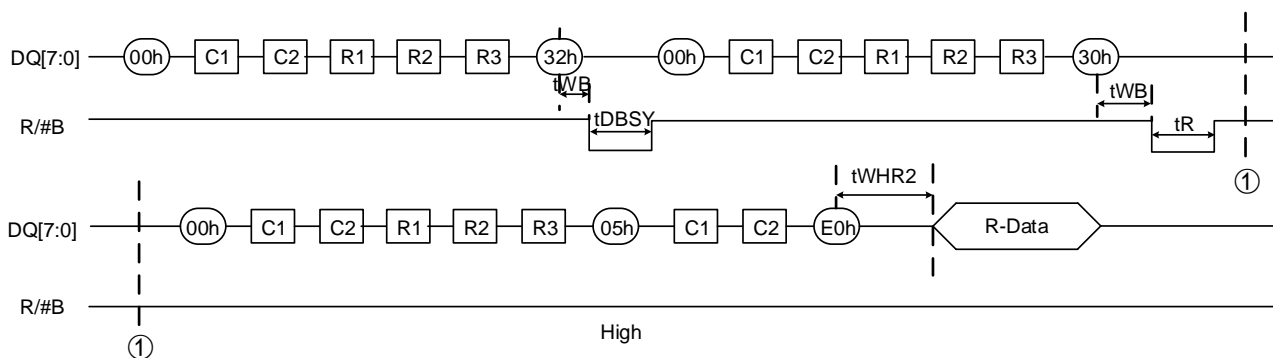


Figure 8-7: Read Two Plane sequential figures

### 8.1.8 Read for Two-Plane Copy Back (00H-32H-00H-35H)

The Two-Plane Copy-Back Program is an extension of the Copy-back Program. Two-Plane Copy-Back Program operation is executed two sets of commands, Two-Plane Read for Copy-Back and Two-Plane Copy-Back Program. The Two-plane addresses shall be set in a consecutive manner from a lower address plane to a higher address plane and the same plane address shall not be set twice within a set of address setting sequence for the Two-Plane Copy-Back Program Operation. Starting plane address shall be plane0 and the number of planes which are set for Two-Plane Copy-Back Program Operation shall be even.

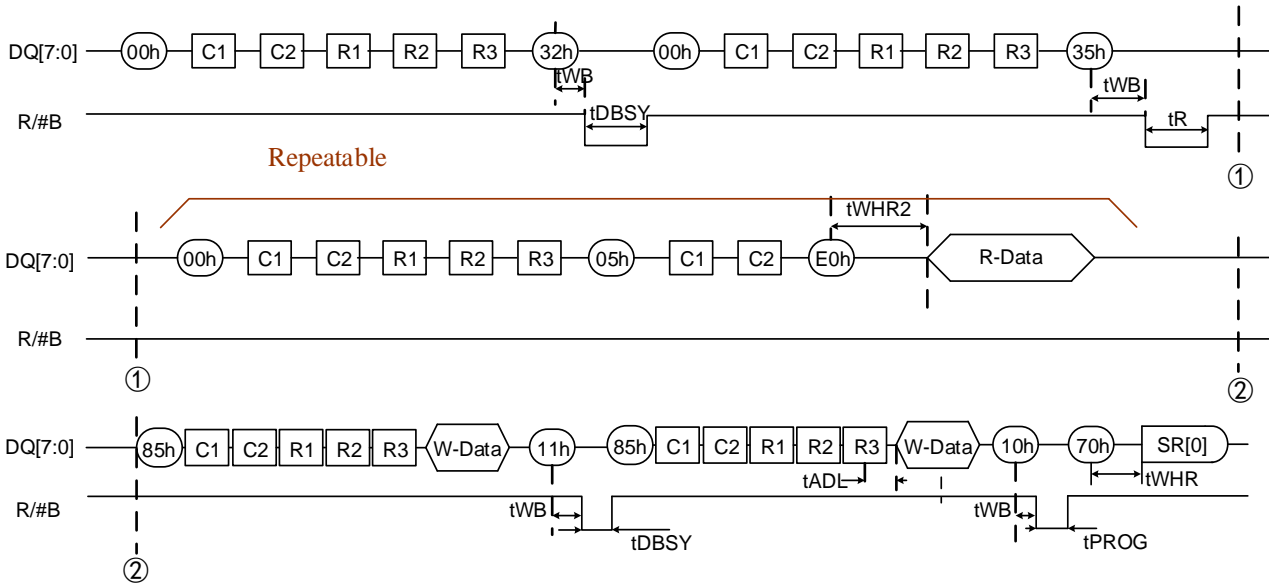


Figure 8-8: Read for Two-Plane Copy Back sequential figures

Note: the data followed 85h command is optional.

## 8.2 Page Program Operation

### 8.2.1 Common Page Program (80H-10H)

The device is programmed basically on a page basis, but it does allow multiple partial pages programming of a word or consecutive bytes up to whole page program cycle. The number of consecutive partial page programming operation within the same page without an intervening erase operation must not exceed 4 times for main array spare array.

The addressing must be done in sequential order in a block.

A page program cycle consists of a serial data loading period in which up to whole page data may be loaded into the cache register, followed by a non-volatile programming period where the loaded data is programmed into the appropriate cell.

The serial data loading period begins by inputting the Serial Data Input command (80h), followed by the five cycle address inputs and then serial data loading. The words other than those to be programmed do not need to be loaded.

The Page Program Confirm command (10h) initiates the programming process. Writing 10h alone without previously entering the serial data will not initiate the programming process. The internal write state controller automatically executes the algorithms and timings necessary for program and verify, thereby freeing the system controller for other tasks. Once the program process starts, the Read Status command may be issued to read the status register.

The command register remains in Read Status command mode until another valid command is written to the command register.

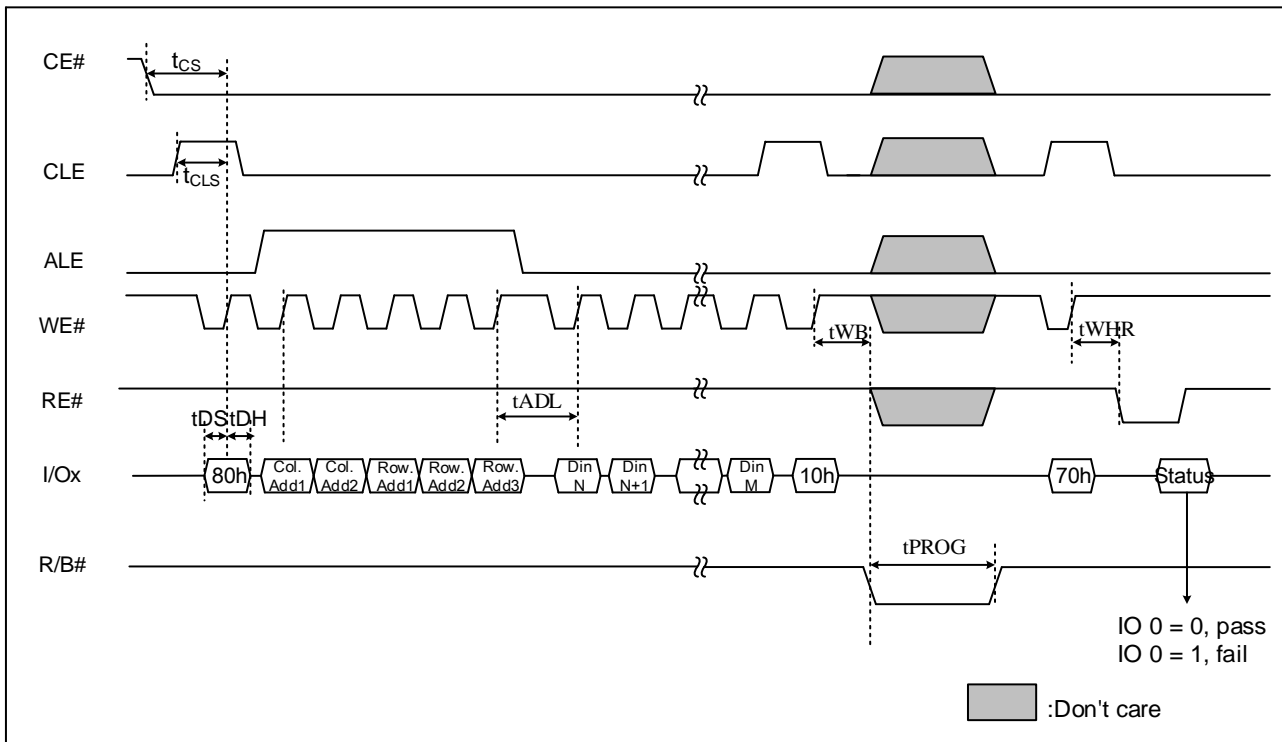


Figure 8-9: Common Page Program figures

### 8.2.2 Page Program Operation with Random Data Input (85H-10H)

The device supports random data input in a page. The column address of next data, which will be entered, may be changed to the address which follows random data input command (85H). Random data input may be operated multiple times regardless of how many times it is done in a page.

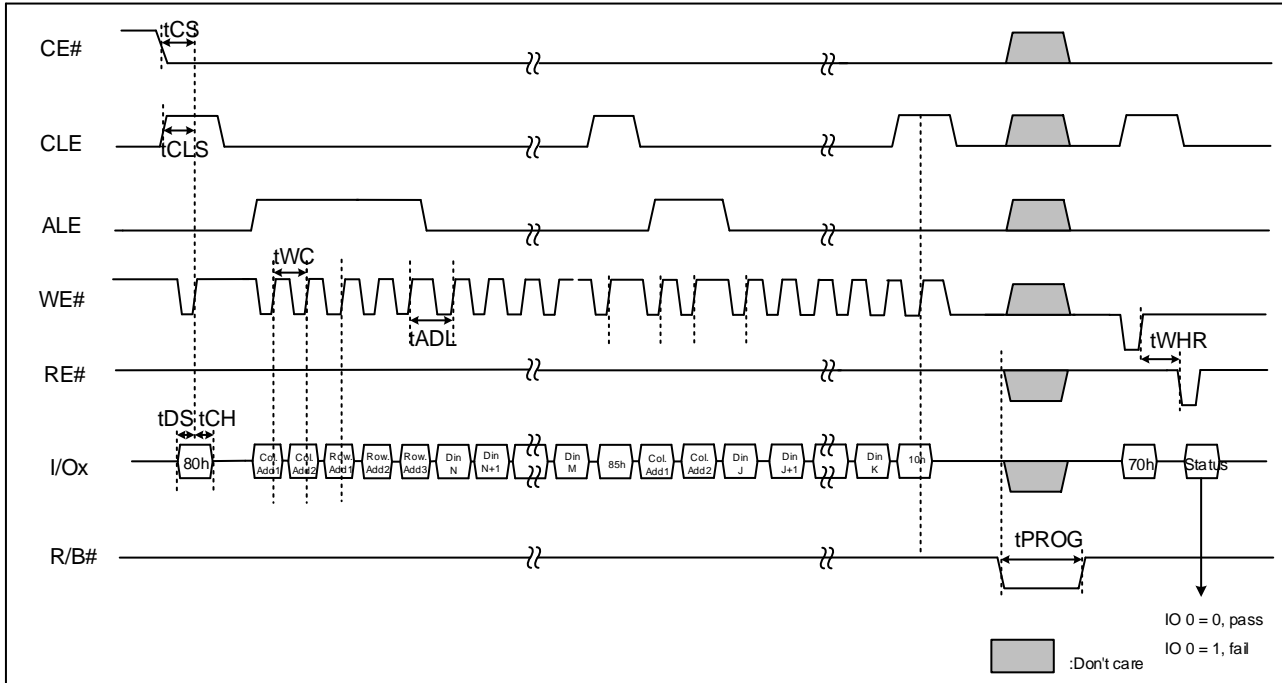


Figure 8-10: Page Program Operation with Random Data Input figures

### 8.2.3 Page Re-program (8BH-10H)

It was also highlighted that page program may result in a fail, which can be detected by Read Status Register. In this event, it implements the innovative feature of “page re-program”. This command allows the re-programming of the same pattern of the (failed) page into another memory location. The command sequence initiates with re-program setup (8BH), followed by the five cycle address inputs of the target page. If the target pattern for the destination page is not changed compared to the page, the program confirm can be issued (10H) without any data input cycle.

On the other hand, if the pattern bound for the target page is different from that of the previous page, data in cycles can be issued before program confirm “10H”

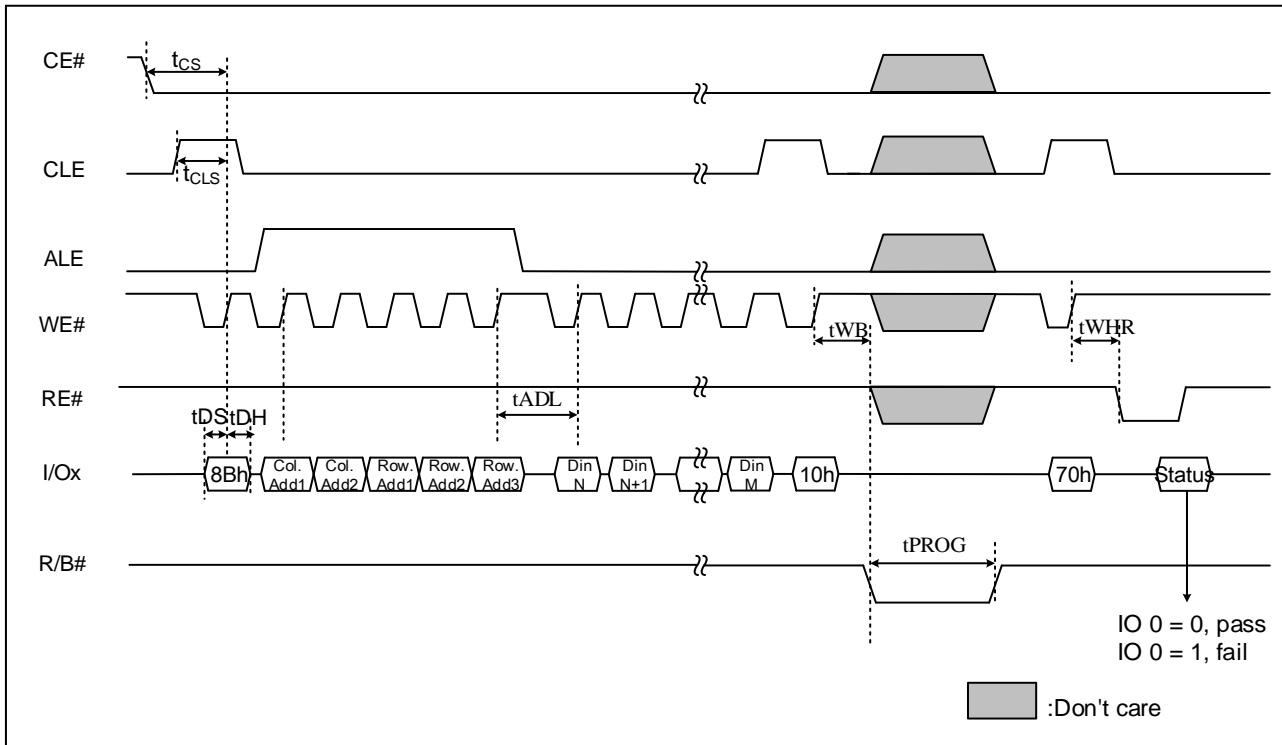


Figure 8-11: Page Re-program figures

Note: the data followed 8BH is optional.

## 8.2.4 Cache Program Operation with Internal ECC disabled (80H-15H)

Cache Program is an extension of Page Program, which is executed with one cache register and one data register, and is available only within a block. Since serial data input cache register may be executed while data stored in data register are programmed into memory cell.

After writing the first set of data up to one page into the selected cache registers, Cache Program command (15H) instead of actual Page Program (10H) is inputted to make cache registers free and to start internal program operation. To transfer data from cache registers to data registers, the device remains in Busy state for a short period of time ( $t_{CBSYW}$ ) and has its cache registers ready for the next data-input while the internal programming gets started with the data loaded into data registers. Read Status command (70H) may be issued to find out when cache registers become ready by polling the Cache-Busy status bit (I/O6). Pass/fail status of only the previous page is available upon the return to Ready state. When the next set of data is loaded with the Cache Program command,  $t_{CBSYW}$  is affected by the progress of pending internal programming. The programming of the cache registers is initiated only when the pending program cycle is finished and the data registers are available for the transfer of data from cache registers. The status bit (I/O5) for internal Ready/Busy may be polled to identify the completion of internal programming. If the system monitors the progress of programming only with R/B#, the last page of the target programming sequence must be programmed with actual Page Program command (10H).

Note: These commands supported only with ECC disabled

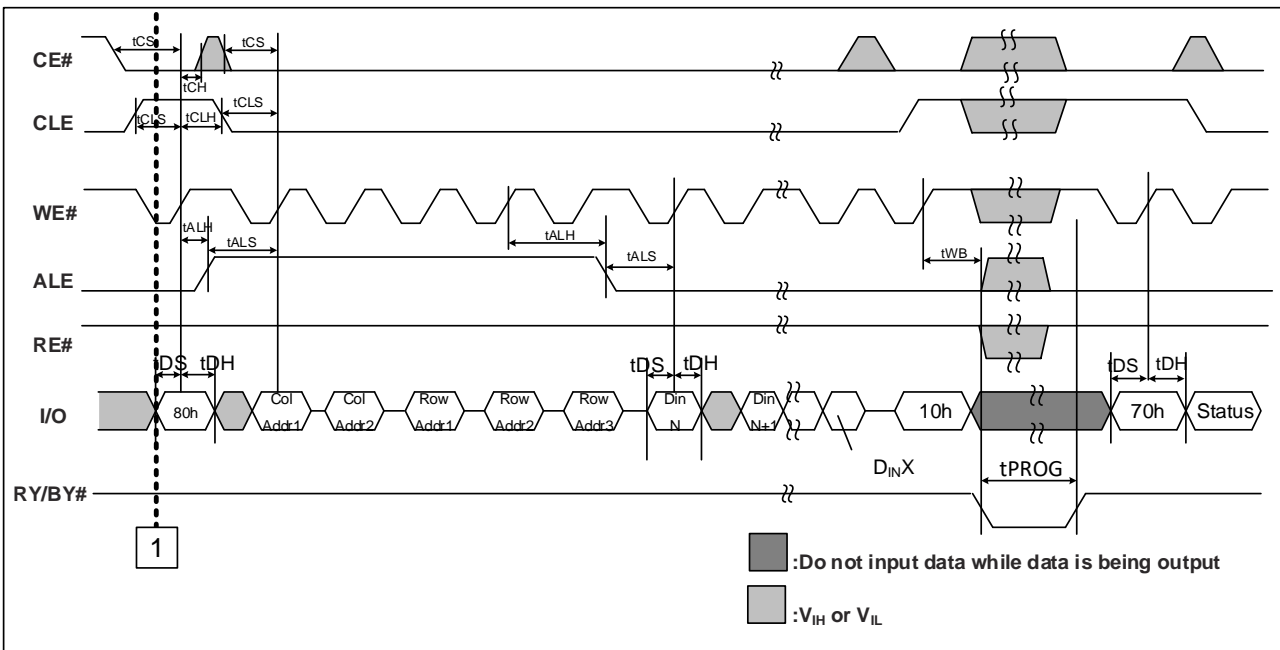
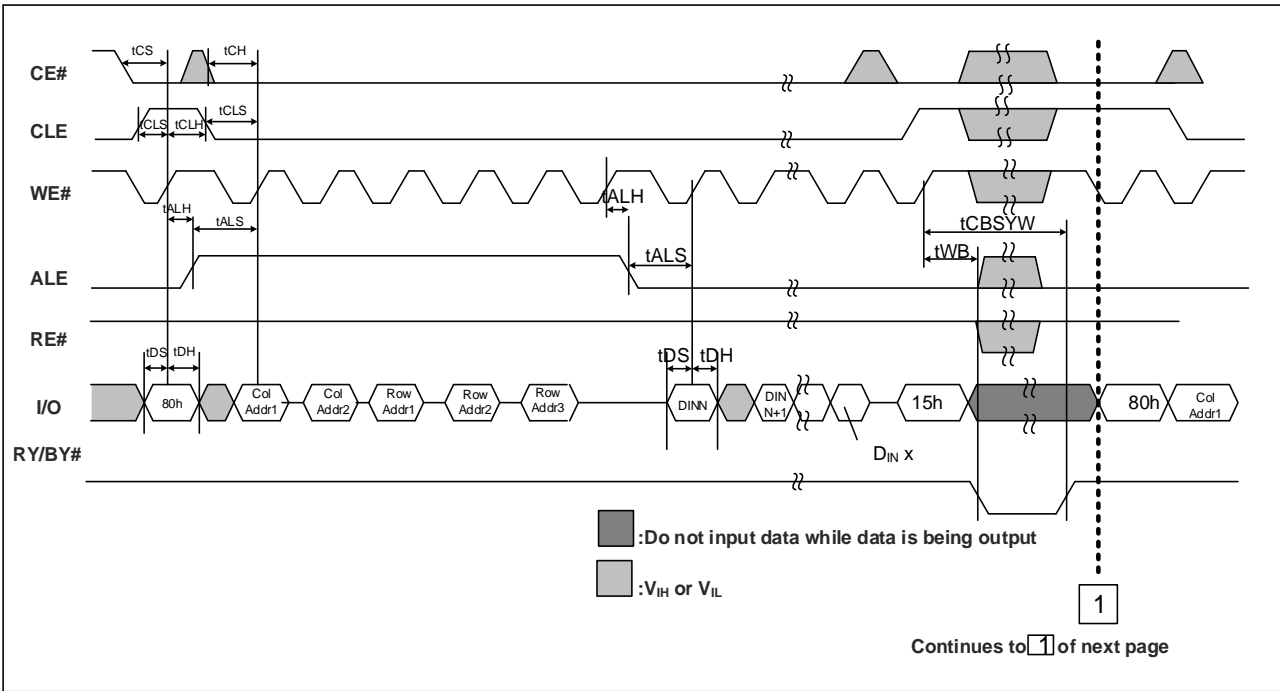


Figure 8-12: Cache Program Operation figures

### 8.2.5 Copy-Back Program (85H-10H) with Random Data Output (00H-35H)

The copy-back program is configured to quickly and efficiently rewrite data stored in one page without utilizing an external memory. Since the time-consuming cycles of serial access and re-loading cycles are removed, the system performance is improved.

The benefit is especially obvious when a portion of a block is updated and the rest of the block is also needed to be copied to the newly assigned free block.

The operation for performing a copy-back program is a sequential execution of page-read without serial access and copying-program with the address of destination page. A read operation with “35h” command and the address of the source page moves the whole page bytes data into the internal data register. As soon as the device returns to Ready state, optional data read-out is allowed by toggling RE#, or Copy Back command (85H) with the address cycles of destination page may be written. The Program Confirm command (10H) is required to actually begin the programming operation. Data input cycle for modifying a portion or multiple distant portions of the source page is allowed. When there is a program-failure at Copy-Back operation, error is reported by pass/fail status.

Please note that Random Data Input (with/without data) is entered before Program Confirm command (10H) after Random Data output.

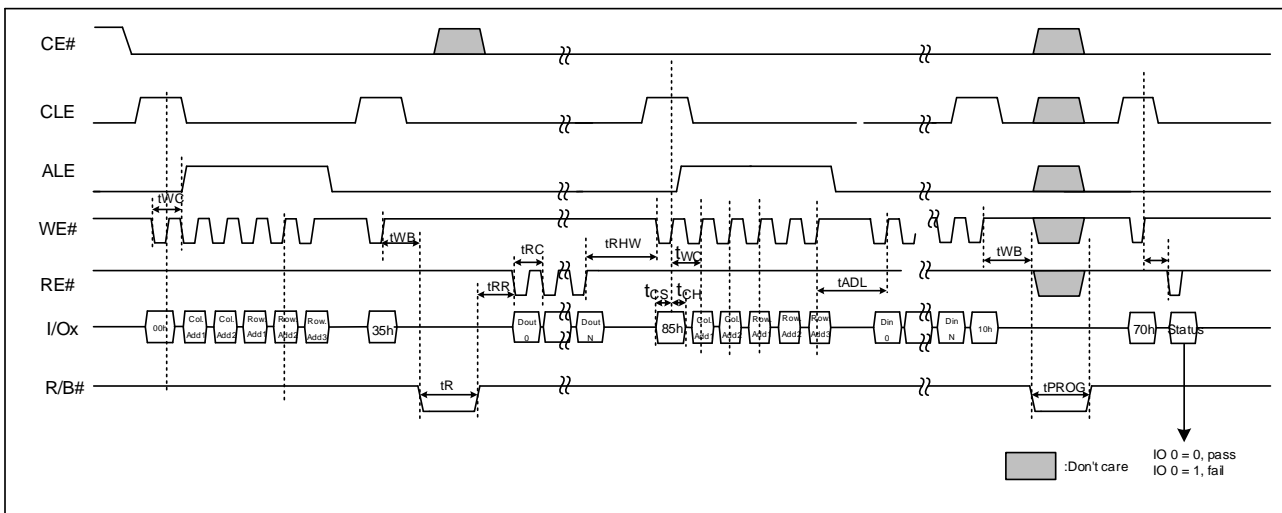


Figure 8-13: Copy-Back Program with Random Data Input figures

Note: the data followed 85h is optional.

### 8.2.6 Multi-Plane Program (80H-11H-80/81H-10H)

Device supports multiple plane program: it is possible to program 2 pages in parallel, one per each plane.

A multiple plane program cycle consists of a double serial data loading period in which up to one page data may be loaded into the cache register, followed by a non-volatile programming period where the loaded data is programmed into the memory cell. The serial data loading period begins with inputting the Serial Data Input command (80h), followed by the five cycle address inputs and serial data for the 1st page. Address for this page must be in the 1st plane. The device supports random data input exactly same as in the case of page program operation. The Dummy Page Program Confirm command (11h) stops 1st page data input and devices becomes busy for a short time (tDBSY).

Once it has become ready again, either the traditional "81h" or the ONFI "80h" command must be issued, followed by

2nd page address (5 cycles) and its serial data input. Address for this page must be in the 2nd plane. Program Confirm command (10h) makes parallel programming of both pages to start. Follow figure describe the sequences. User can check operation status by monitoring RB# pin or reading status register commands (70h or 78h), as if it were a normal page program: read status register command is also available during Dummy Busy time (tDBSY). In case of fail in any of 1st and 2nd page program, fail bit of status register will be set however, in order to know which page failed, read status enhanced command must be issued for further info.

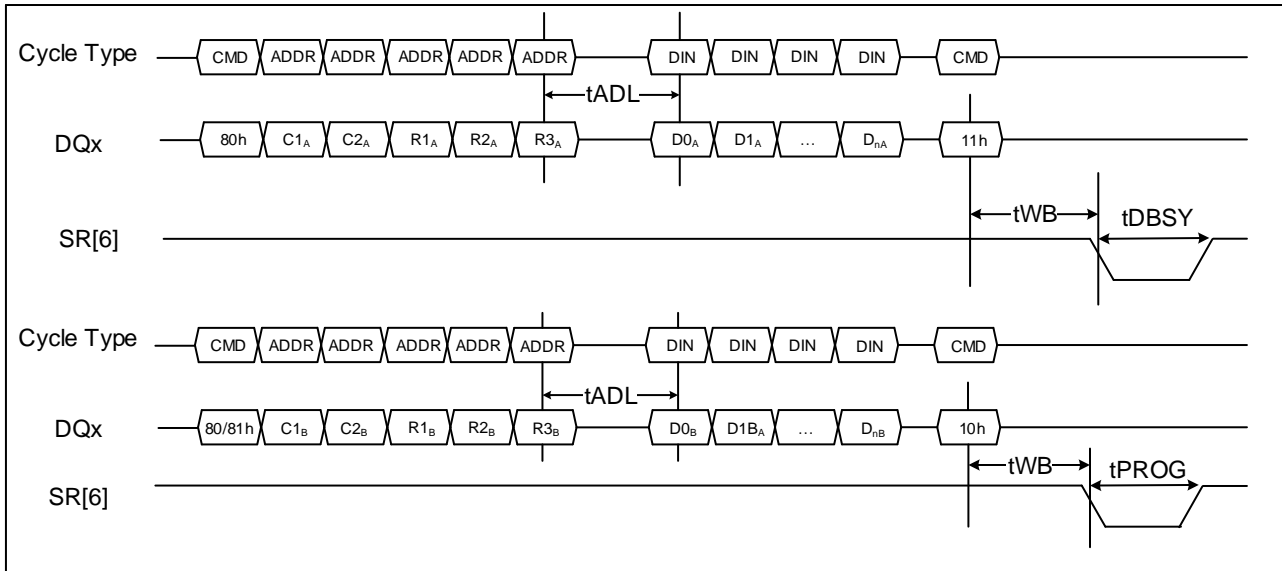


Figure 8-14: Multi-Plane Program sequential figures

Note: In figure, the 80/81h is compatible traditional/ONFI multi-plane program.



### 8.2.7 Multi-Plane Re-Program (8BH-11H-8BH-10H)

The operation is similar with multi-plane page program, the only different is use the 8BH substitute the command 80H, the data input is optional.

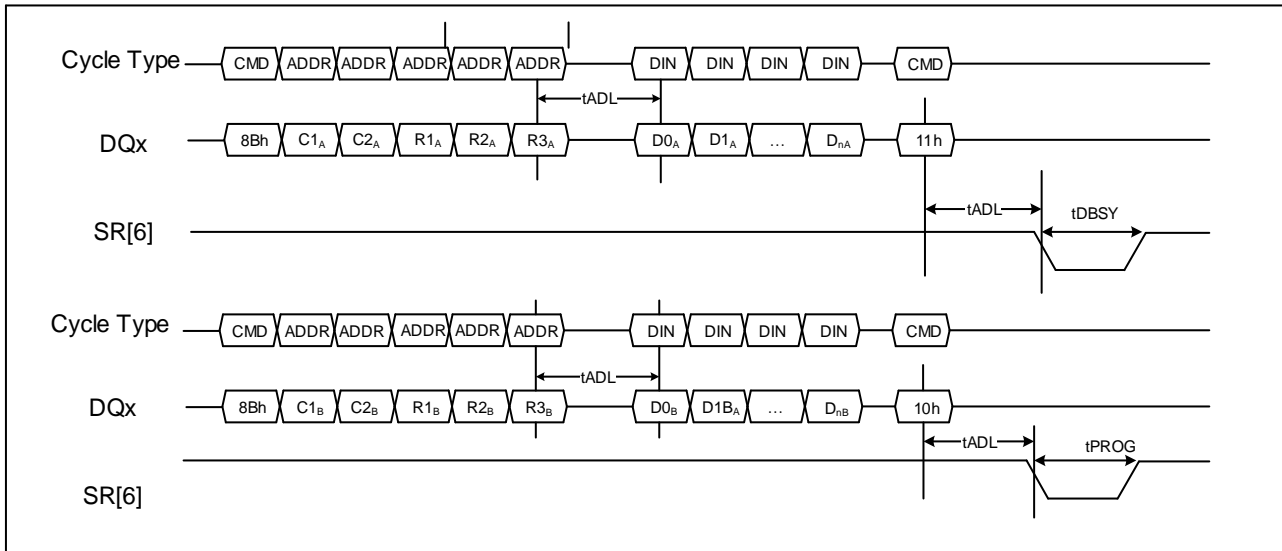


Figure 8-15: Multi-Plane Re-Program sequential figures

## 8.2.8 Multi-Plane Cache Program with Internal ECC disabled (80H-11H-80/81H-15H-80H-11H-80/81H-10H)

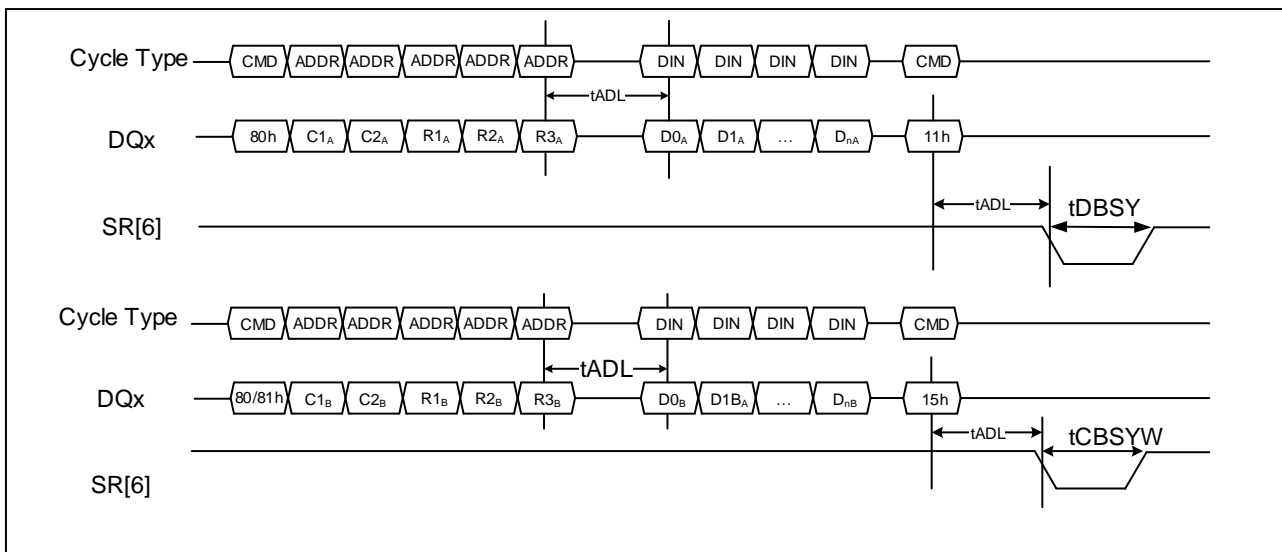
The device supports multi-plane cache program, which enables high program throughput by programming two pages in parallel while exploiting the data and cache registers of both planes to implement cache. The device supports both the traditional and ONFI 1.0 command sets.

User can check operation status by R/B# pin or read status register commands (70h or 78h) If user opts for 70h, Status register read will provide a "global" information about the operation in the two planes.

More in detail:

- I/O6 indicates when both cache registers are ready to accept new data.
- I/O5 indicates when the cell programming of the current data registers is complete
- I/O1 identifies if the previous pages in both planes (pages N-1) have been successfully programmed or not. The latter can be polled upon I/O6 status bit changing to "1".
- I/O0 identifies if any error has been detected by the program / erase controller while programming the two pages N. The latter can be polled upon I/O5 status bit changing to "1". If the system monitor the progress of the operation only with R/B#, the last pages of the target program sequence must be programmed with Page Program Confirm command (10h). If the Cache Program command (15h) is used instead, the status bit I/O5 must be polled to find out if the last programming is finished before starting any other operation.

Note: These commands supported only with ECC disabled



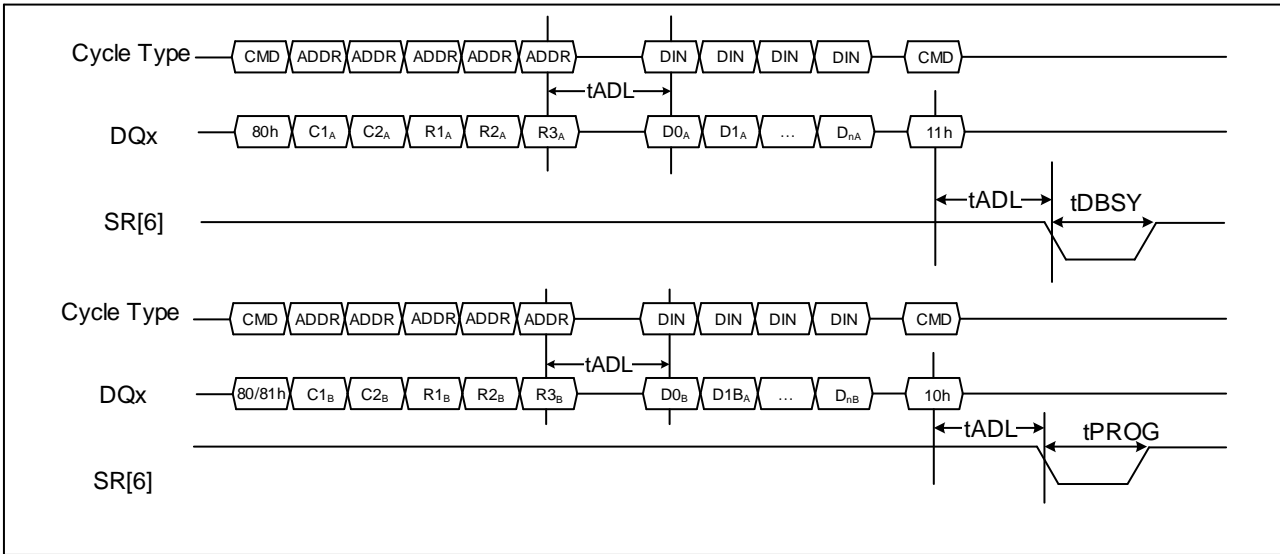


Figure 8-16: Multi-Plane Cache Program sequential figures

### 8.2.9 Multi-Plane Copy Back Program (85H-11H-85H-10H)

As for page program, device supports Multi-plane copy back program with exactly same sequence and limitations. Multi-plane copy back program must be preceded by 2 single page read for copy back command sequences (one page for each plane).

Multi-plane copy back cannot cross plane boundary, the contents of the source page of one device plane can be copied only to a destination page of the same plane.

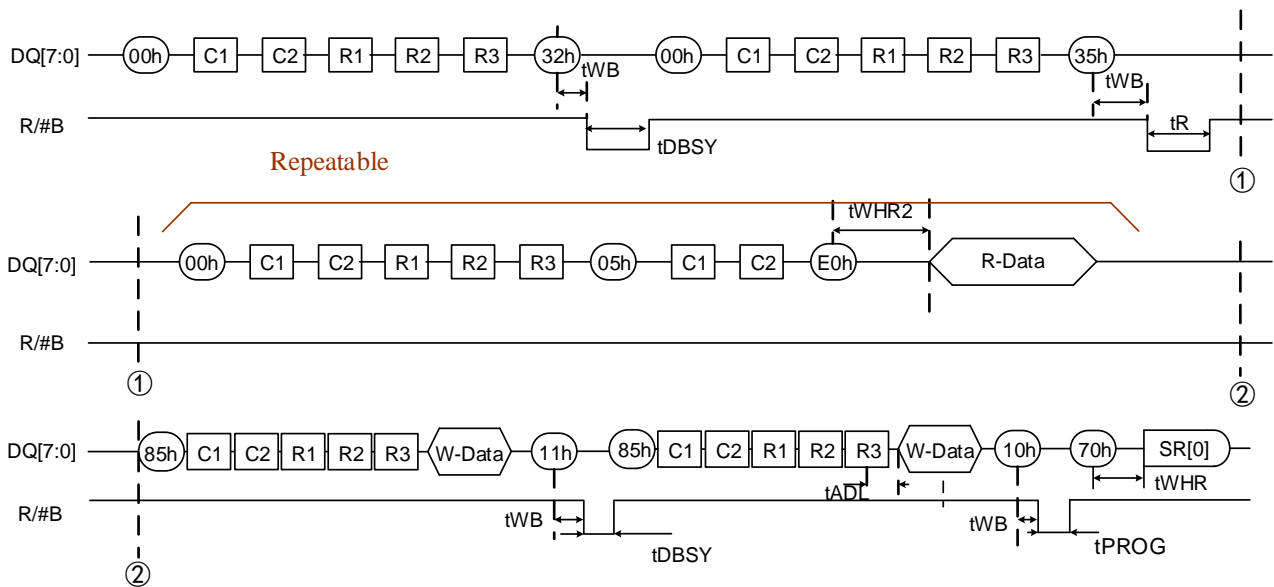


Figure 8-17: Multi-Plane Copy Back Program sequential figures

Note: the data followed 85H is optional.

## 8.3 Block Erase Operation

### 8.3.1 Common Block Erase Operation (60H-D0H)

The Erase operation is done on a block basis. Block address loading is accomplished in three cycles initiated by an Erase Setup command (60H). Only Row Address is needed. The Erase Confirm command (D0H) following the block address loading initiates the internal erasing process. At the rising edge of WE after the erase confirm command input, the NAND device handles erase operation. Once the erase process starts, the Read Status command can be used to read the status register. The system controller can detect the completion of an erase by monitoring the R/B output, or the Status bit (I/O6) of the Status Register. Only the Read Status command and Reset command are valid while erasing is in progress. When the erase operation is completed, the Status Bit (I/O0) may be checked if the erase is successful or not.

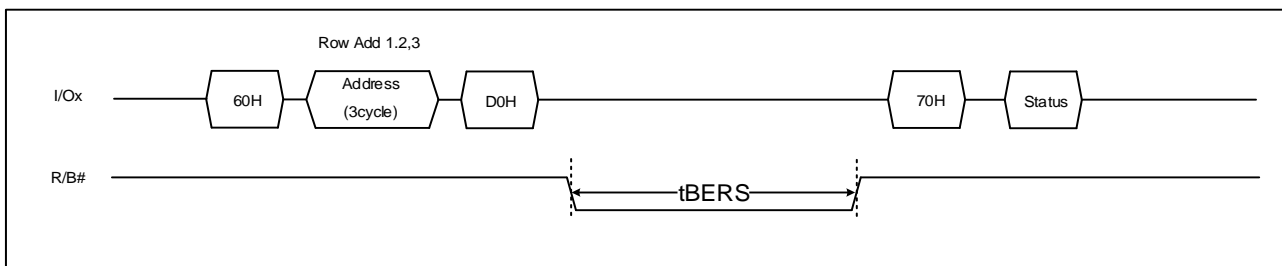


Figure 8-18: Common Block Erase Operation figures

### 8.3.2 Multi-Plane Block Erase Operation (60H-60H-D0H)

Multi-plane Block Erase allows the erase of two blocks in parallel, one block per memory plane.

The Block erase setup command (60h) must be repeated two times, followed by 1st and 2nd block address respectively (3 cycles each). As for block erase, D0h command makes embedded operation start. In this case, multi-plane erase does not need any Dummy Busy Time between 1st and 2nd block insertion and should obey the multi-plane operation rule.

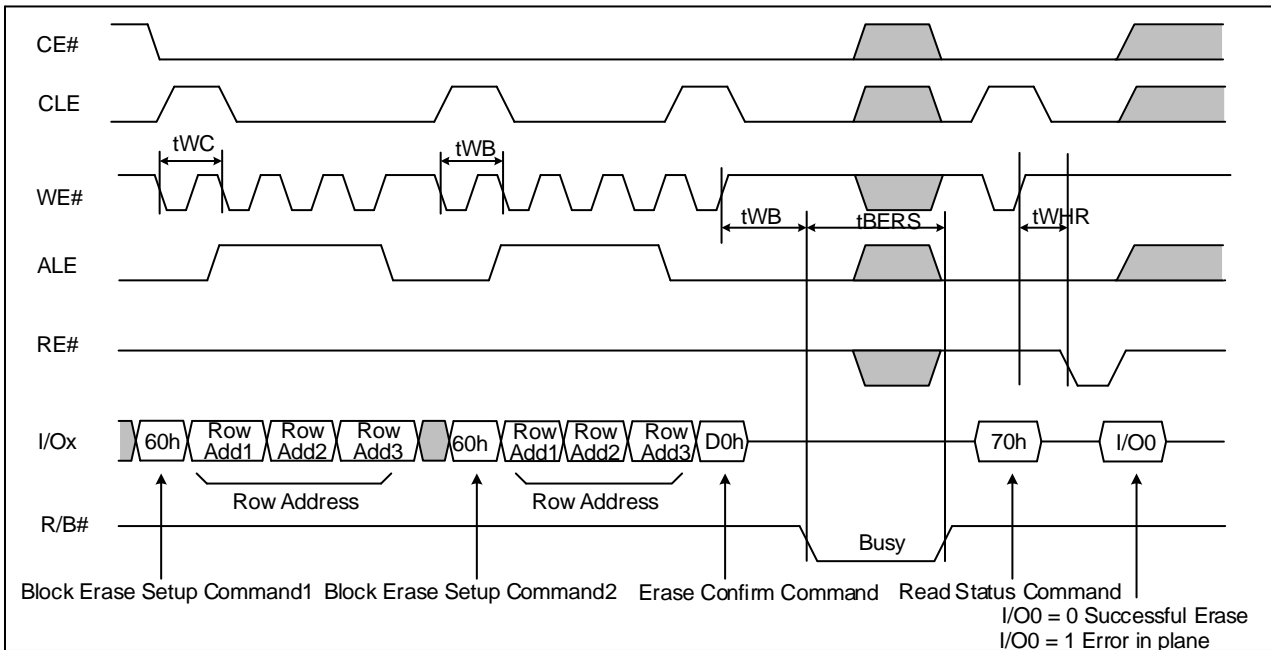


Figure 8-19: Multi-Plane Block Erase Operation sequential figures

### 8.3.3 Multi-Plane Block Erase Operation-ONFI (60H-D1H-60H-D0H)

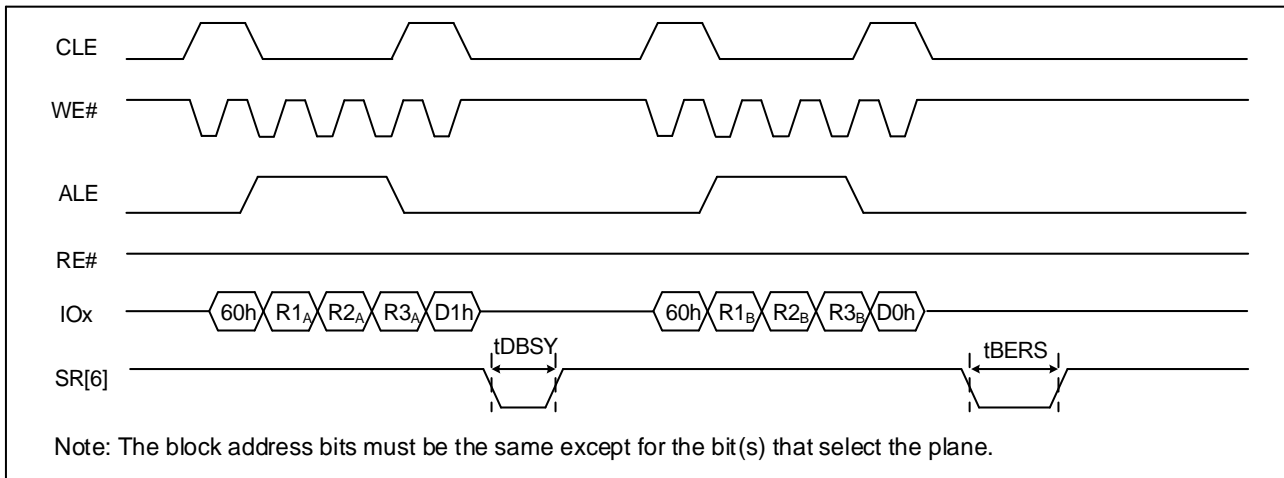


Figure 8-20: Multi-plane Block Erase Operation-ONFI sequential figures

## 8.4 Reset (FFH)

The device offers a reset feature, executed by writing FFH to the command register. When the device is in busy state during random read, program or erase mode, the reset operation will abort these operations. The contents of memory cells being altered are no longer valid, as the data will be partially programmed or erased. The command register is cleared to wait for the next command, and the Status Register is cleared to value E0h when R/B# is high. If the device is already in reset state a new reset command will be accepted by the command register. The R/B# pin transitions to low for tRST after the Reset command is written.

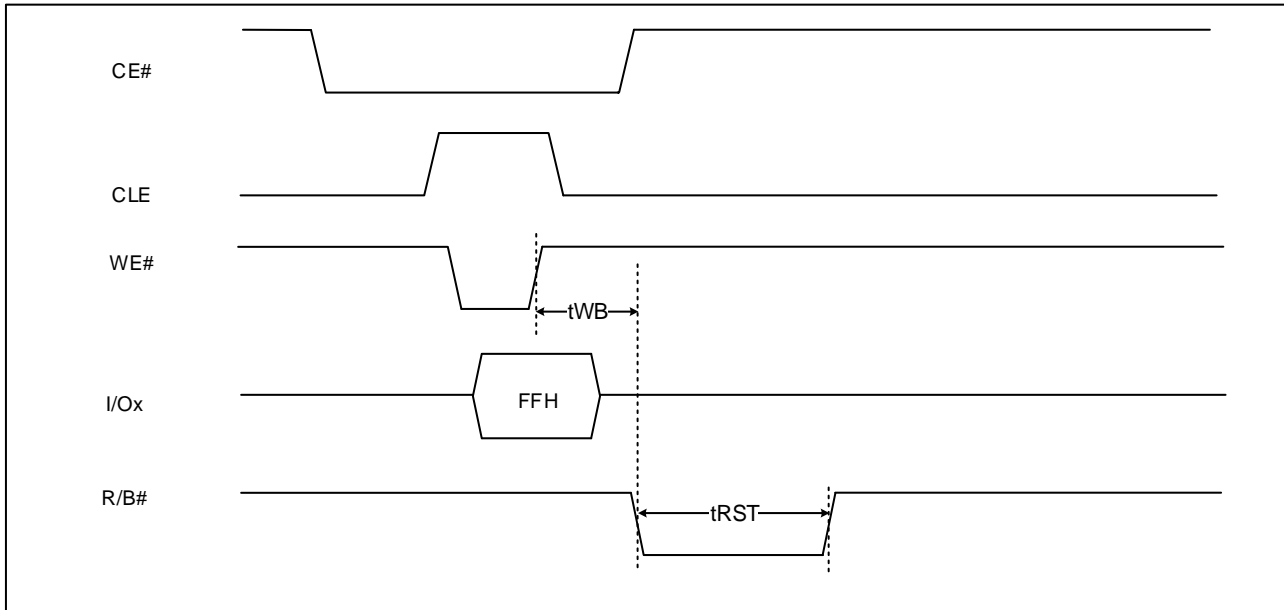


Figure 8-21: Reset (FFH) figures

## 8.5 Read Device Information

### 8.5.1 Read ID and ONFI Signature (90H)

The device contains a product identification mode, initiated by writing 90H to the command register, followed by an address input of 00H. Five read cycles sequentially output the manufacturer code, and the device code and other information, respectively. The command register remains in Read ID mode until further commands are issued to.

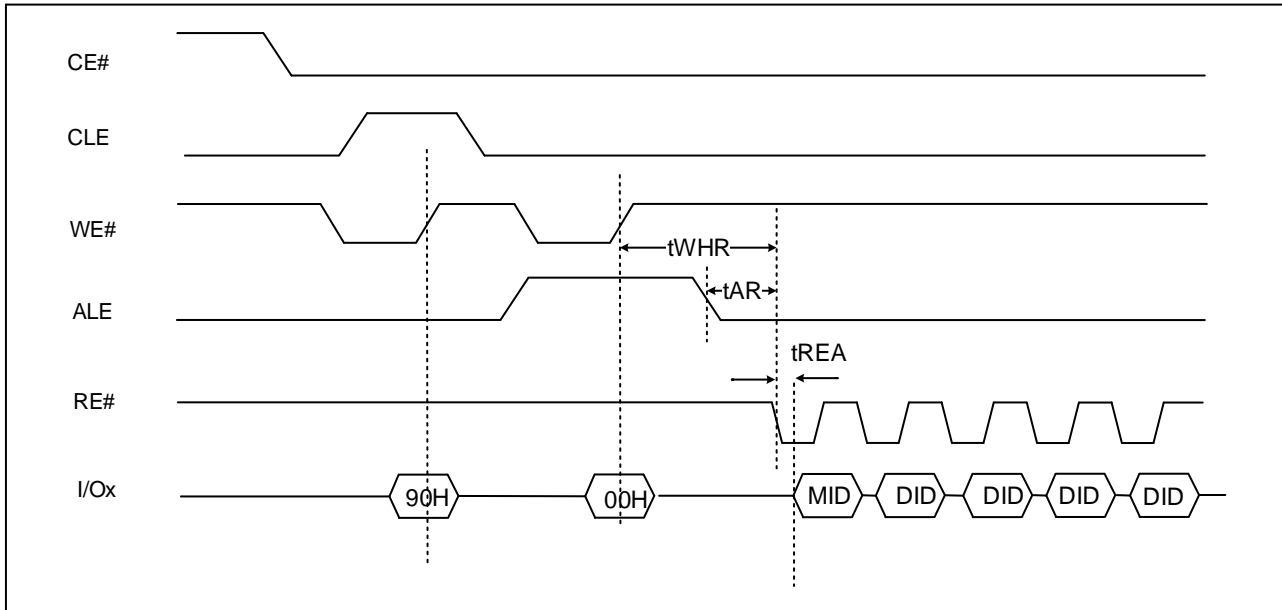


Figure 8-22: Read ID figures

#### ID Definition Table

Byte	Description
1 <sup>st</sup> Byte	Manufacturer Code (MID)
2 <sup>nd</sup> Byte	Device Code (DID)
3 <sup>rd</sup> Byte	Internal Chip Number, Cell Type, Number of Simultaneously Programmed Pages, Interleaved Program, Write Cache
4 <sup>th</sup> Byte	Page size, Block size, Spare size, Organization
5 <sup>th</sup> Byte	ECC & Plane

#### Read ID Data Table

Part Number	VCC	Bus Width	MID(1 <sup>st</sup> )	DID(2 <sup>nd</sup> )	3 <sup>rd</sup>	4 <sup>th</sup>	5 <sup>th</sup>
GD9AU2G8F2A	3.3v	x8	C8H	DAH	90H	95H	C6H
GD9AU2G6F2A	3.3v	x16	C8H	CAH	90H	D5H	C6H
GD9AS2G8F2A	1.8v	x8	C8H	AAH	90H	15H	C6H
GD9AS2G6F2A	1.8v	x16	C8H	BAH	90H	55H	C6H



**3<sup>rd</sup> Byte of Device Identifier Description**

3 <sup>rd</sup> Cycle	Description	IO7	IO6	IO5	IO4	IO3	IO2	IO1	IO0
Internal Chip Number	1							0	0
	2							0	1
	4							1	0
	8							1	1
Cell Type	2 Level Cell					0	0		
	4 Level Cell					0	1		
	8 Level Cell					1	0		
	16 Level Cell					1	1		
Number of Simultaneously Programmed Pages	1			0	0				
	2			0	1				
	4			1	0				
	8			1	1				
Interleaved Program Between Multiple Die	Not Supported		0						
	Supported		1						
Write Cache (Cache Programming)	Not Supported	0							
	Supported	1							

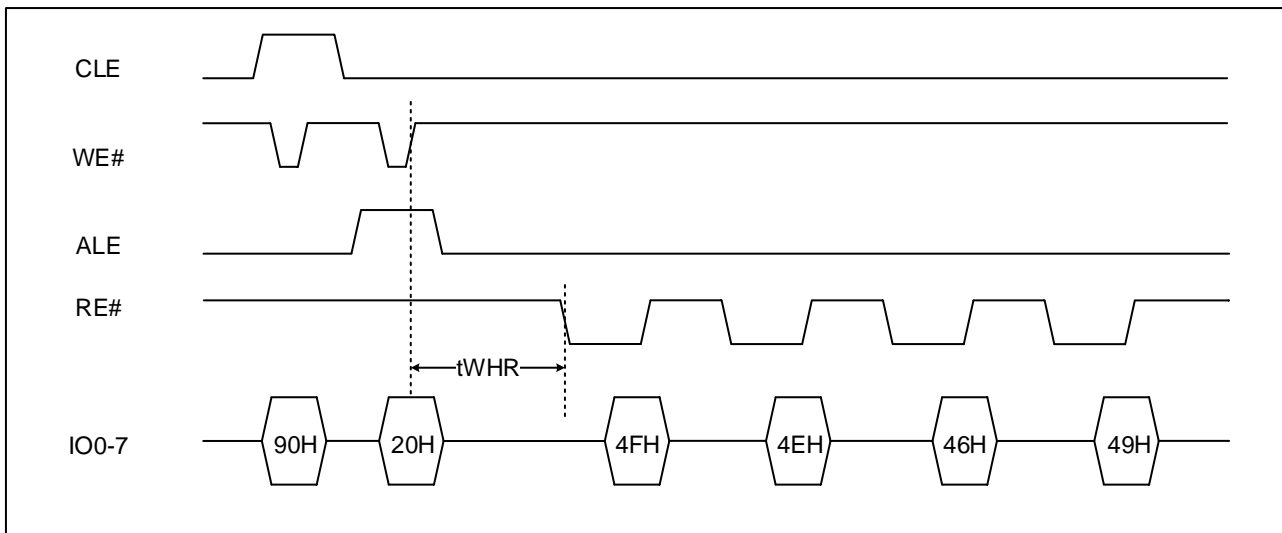
**4<sup>th</sup> Byte of Device Identifier Description**

4 <sup>th</sup> Cycle	Description	IO7	IO6	IO5	IO4	IO3	IO2	IO1	IO0
Page Size (without Spare Area)	1KB							0	0
	2KB							0	1
	4KB							1	0
	8KB							1	1
Size of spare area (byte per 512-byte)	16						1		
Serial Access Time	25ns(1.8V)	0				0			
	20ns(3.3V)	1				0			
Block Size (Without Spare Area)	64KB			0	0				
	128KB			0	1				
	256KB			1	0				
	512KB			1	1				
Organization	x8		0						
	x16		1						

**5<sup>th</sup> Byte of ECC & Plane**

5 <sup>th</sup> Cycle	Description	IO7	IO6	IO5	IO4	IO3	IO2	IO1	IO0
Internal ECC Level	1							0	0
	2							0	1
	4							1	0
	8							1	1
Plane Number	1					0	0		
	2					0	1		
	4					1	0		
	8					1	1		
Reserved			1	0	0				
Internal ECC	ECC disabled	0							
	ECC enabled	1							

To retrieve the ONFI signature, the command 90H together with an address of 20H shall be entered. The ONFI signature is the ASCII encoding of 'ONFI' where 'O' = 4FH, 'N' = 4EH, 'F' = 46H, and 'I' = 49H. Reading beyond four bytes yields indeterminate values.



**Figure 8-23: Read ONFI Signature figures**

## 8.5.2 Read Unique ID (EDH)

The Read Unique ID function is used to retrieve the 16 byte unique ID (UID) for the device. The unique ID when combined with the device manufacturer shall be unique.

The UID data may be stored within the Flash array. To allow the host to determine if the UID is without bit errors, the UID is returned with its complement. If the XOR of the UID and its bit-wise complement is all ones, then the UID is valid. To accommodate robust retrieval of the UID in the case of bit errors, sixteen copies of the UID and the corresponding complement shall be stored by the target. For example, reading bytes 32-63 returns to the host another copy of the UID and its complement.

To change the data output location, it is recommended to use the Random Data Out command set (05H-E0H). The Status Read command (70H) can be used to check the completion. To continue the read operation, a following read command (00h) to re-enable the data out is necessary.

Bytes	Value
0-15	UID
16-31	UID complement (bit-wise)

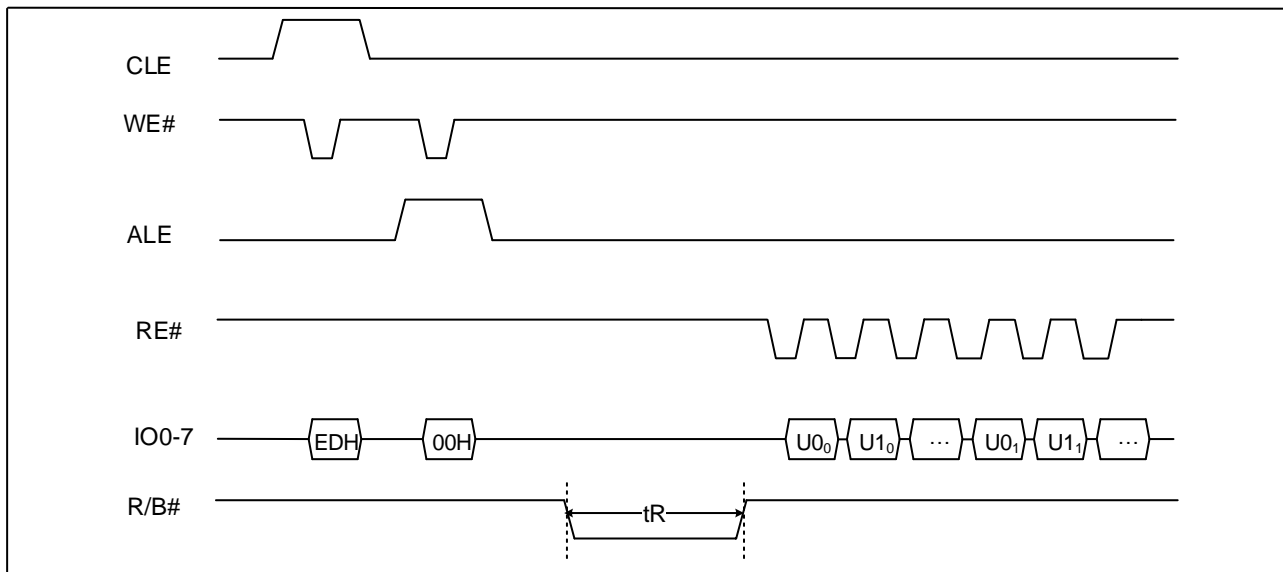


Figure 8-24: Read UID figures

### 8.5.3 Read Parameter Page (ECH)

The Read Parameter Page function retrieves the data structure that describes the chip's organization, features, timing-and other behavioral parameters. This data structure enables the host processor to automatically recognize the NAND Flash configuration of a device. The whole data structure is repeated at least three times. The Random Data Read command (05H-E0H) can be issued during execution of the read parameter page to read specific portion-of the parameter page. The Read Status command (70H) may be used to check the status of read parameter page during execution. After completion of the Read Status command, 00H is issued by the host on the command line to continue with the data output flow for the Read Parameter Page command.

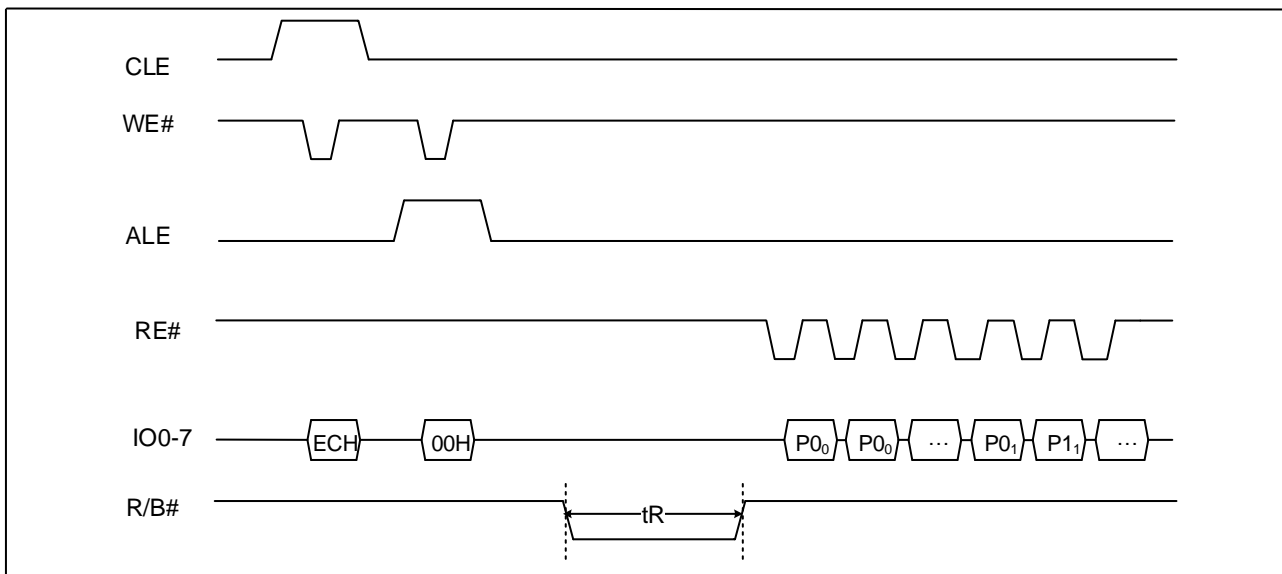


Figure 8-25: Read Parameter Page figures

Byte	O/M	Description	
0-3	M	Parameter page signature Byte 0: 4FH, "O" Byte 1: 4EH, "N" Byte 2: 46H, "F" Byte 3: 49H, "I"	4FH 4EH 46H 49H
4-5	M	Revision number 2-15 Reserved (0) 1 1 = supports ONFI version 1.0 0 Reserved (0)	02H 00H
6-7	M	Features supported 5-15 Reserved (0) 4 1 = supports odd to even page Copy back 3 1 = supports interleaved operations 2 1 = supports non-sequential page programming 1 1 = supports multiple LUN operations 0 1 = supports 16-bit data bus width	10H(X8)/ 11H(X16) 00H

8-9	M	Optional commands supported 6-15 Reserved (0) 5 1 = supports Read Unique ID 4 1 = supports Copy-back 3 1 = supports Read Status Enhanced 2 1 = supports Get Features and Set Features 1 1 = supports Read Cache Integrity 0 1 = supports Page Cache Program command	3FH 00H															
10-31		Reserved (0)	00H ... 00H															
		Manufacturer Information block																
32-43	M	Device manufacturer (12 ASCII characters)"GIGADEVICE "	47H 49H 47H 41H 44H 45H 56H 49H 43H 45H 20H 20H															
44-63	M	Device model (20 ASCII characters) <table border="1" data-bbox="316 1234 1171 1451"> <thead> <tr> <th>Device Model</th> <th>ORGANIZATION</th> <th>VCC RANGE</th> </tr> </thead> <tbody> <tr> <td>"GD9AS2G8F2A"</td> <td>256M x 8bit</td> <td>1.7v ~ 1.95v</td> </tr> <tr> <td>"GD9AS2G6F2A"</td> <td>128M x 16bit</td> <td>1.7v ~ 1.95v</td> </tr> <tr> <td>"GD9AU2G8F2A"</td> <td>256M x 8bit</td> <td>2.7v ~ 3.6v</td> </tr> <tr> <td>"GD9AU2G6F2A"</td> <td>128M x 16bit</td> <td>2.7v ~ 3.6v</td> </tr> </tbody> </table>	Device Model	ORGANIZATION	VCC RANGE	"GD9AS2G8F2A"	256M x 8bit	1.7v ~ 1.95v	"GD9AS2G6F2A"	128M x 16bit	1.7v ~ 1.95v	"GD9AU2G8F2A"	256M x 8bit	2.7v ~ 3.6v	"GD9AU2G6F2A"	128M x 16bit	2.7v ~ 3.6v	47H 44H 39H 41H 53H/55H 32H 47H 38H/36H 46H 32H 41H 20H 20H 20H 20H 20H 20H 20H 20H
Device Model	ORGANIZATION	VCC RANGE																
"GD9AS2G8F2A"	256M x 8bit	1.7v ~ 1.95v																
"GD9AS2G6F2A"	128M x 16bit	1.7v ~ 1.95v																
"GD9AU2G8F2A"	256M x 8bit	2.7v ~ 3.6v																
"GD9AU2G6F2A"	128M x 16bit	2.7v ~ 3.6v																

64	M	JEDEC manufacturer ID“C8”	C8H
65-66	O	Date code	00H 00H
67-79		Reserved	00H 00H 00H
		Memory organization block	
80-83	M	Number of data bytes per page	00H 08H 00H 00H
84-85	M	Number of spare bytes per page	40H 00H
86-89	M	Number of data bytes per partial page	00H 02H 00H 00H
90-91	M	Number of spare bytes per partial page	10H 00H
92-95	M	Number of pages per block	40H 00H 00H 00H
96-99	M	Number of blocks per logical unit (LUN)	00H 08H 00H 00H
100	M	Number of logical units (LUNs)	01H
101	M	Number of address cycles 4-7 Column address cycles 0-3 Row address cycles	23H
102	M	Number of bits per cell	01H
103-104	M	Bad blocks maximum per LUN	28H 00H
105-106	M	Block endurance	01H 05H
107	M	Guaranteed valid blocks at beginning of target	01H
108-109	M	Block endurance for guaranteed valid blocks	00H 00H
110	M	Number of programs per page	04H
111	M	Partial programming attributes 5-7 Reserved 4 1 = partial page layout is partial page data followed by partial page spare 1-3 Reserved	00H

		0 1 = partial page programming has constraints	
112	M	Number of bits ECC correct ability	00H
113	M	Number of interleaved address bits 4-7 Reserved (0) 0-3 Number of interleaved address bits	00H
114	O	Interleaved operation attributes 4-7 Reserved (0) 3 Address restrictions for program cache 2 1 = program cache supported 1 1 = no block address restrictions 0 Overlapped / concurrent interleaving support	00H
115-127		Reserved	00H ... 00H
		Electrical parameters block	
128	M	I/O capacitance	06H
129-130	M	Timing mode support 6-1 5Reserved (0) 5 1 = supports timing mode 5 4 1 = supports timing mode 4 3 1 = supports timing mode 3 2 1 = supports timing mode 2 1 1 = supports timing mode 1 0 1 = supports timing mode 0, shall be 1	3FH(3.3V)/ 1FH(1.8V) 00H
131-132	O	Program cache timing mode support 6-1 5Reserved (0) 5 1 = supports timing mode 5 4 1 = supports timing mode 4 3 1 = supports timing mode 3 2 1 = supports timing mode 2 1 1 = supports timing mode 1 0 1 = supports timing mode 0,	3FH(3.3V)/ 1FH(1.8V) 00H
133-134	M	tPROG Maximum page program time (us)	58H 02H
135-136	M	tBERS Maximum block erase time (us)	88H 13H
137-138	M	tR Maximum page read time (us)	32H 00H
139-140	M	tCCS Minimum Change Column setup time (ns)	3CH 00H
141-163		Reserved	00H
		Vendor block	
164-165	M	Vendor specific Revision number	00H
166-253		Vendor specific	00H

254-255	M	Integrity CRC	
		Redundant parameter pages	
256-511	M	Value of bytes 0-255	
512-767	M	Value of bytes 0-255	
768+	O	Additional redundant parameter pages	

**Notes:**

1. "O" Stands for Optional, "M" for Mandatory
2. The Integrity CRC (Cycling Redundancy Check) field is used to verify that the contents of the parameters page were transferred correctly to the host. Please refer to ONFI 1.0 specifications for details.

The CRC shall be calculated using the following 16-bit generator polynomial:  $G(X) = X^{16} + X^{15} + X^2 + 1$ , This polynomial in hex may be represented as 8005h.

3. The CRC value shall be initialized with a value of 4F4Eh before the calculation begins. There is no XOR applied to the final CRC value after it is calculated. There is no reversal of the data bytes or the CRC calculated value.

**Parameter page CRC value table**

Device Model	ORGANIZATION	VCC RANGE	CRC value B254/B255
"GD9AS2G8F2A"	256M x 8bit	1.7v ~ 1.95v	3CH/6EH
"GD9AS2G6F2A"	128M x 16bit	1.7v ~ 1.95v	14H/ADH
"GD9AU2G8F2A"	256M x 8bit	2.7v ~ 3.6v	7CH/9FH
"GD9AU2G6F2A"	128M x 16bit	2.7v ~ 3.6v	54H/5CH



## 8.6 Read Status (70H)

The device contains a Status Register which may be read to find out whether an operation is completed and whether the program or erase operation is completed successfully. After writing 70H command to the command register, a read cycle outputs the content of the Status Register to the I/O pins on the falling edge of CE# or RE#, whichever occurs last. This allows the system to poll the progress of each device in multiple memory connections even when R/B# pins are common-wired. RE# or CE# does not need to be toggled for updated status. The command register remains in Status Read mode until further commands are issued to it. Therefore, if the status register is read during a random read cycle, the read command (00h) should be given before starting read cycles.

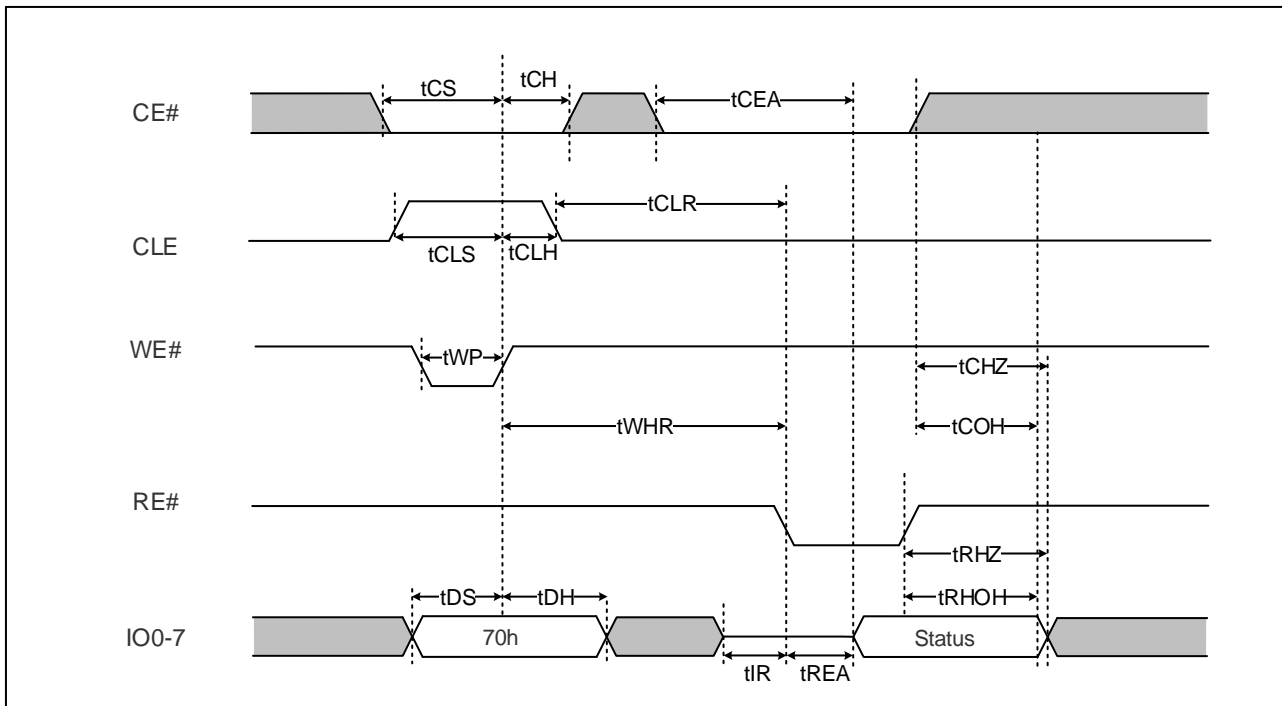


Figure 8-26: Read Status figures

**Status Register Definitions**

SR Bit	Definition	Independent per Plane <sup>1</sup>	Description
I/O0	FAIL	Yes	Pass/Fail (N): 0 = Pass 1 = Fail This bit is set if the most recently finished operation on the selected die (LUN) failed. This bit is valid only when ARDY (SR bit 5) is 1. It applies to PROGRAM-, ERASE-, and COPYBACK PROGRAM-series operations (80h-10h, 80h-15h, 60h-D0h, 85h-10h). This bit is not valid following a READ-series operation.
I/O1	FAILC	Yes	Pass/Fail (N - 1): 0 = Pass 1 = Fail This bit is set if the previous operation on the selected die (LUN) failed. This bit is valid only when RDY (SR bit 6) is 1. It applies to PROGRAM-, and COPYBACK PROGRAM-series operations (80h-10h, 80h-15h, 85h-10h). This bit is not valid following an ERASE-series or READ-series operation.
I/O2	-	-	Reserved
I/O3	ECC Status	-	Refer to "8.13 Internal ECC " ECC Status Table.
I/O4			
I/O5	ARDY	-	Ready/Busy Array: 0 = Busy 1 = Ready This bit goes LOW (busy) when an array operation is occurring on any plane of the selected die (LUN). It goes HIGH when all array operations on the selected die (LUN) finish. This bit applies only to the selected die (LUN).
I/O6	RDY	-	Ready/Busy I/O: 0 = Busy 1 = Ready This bit indicates that the selected die (LUN) is not available to accept new commands, address, or data I/O cycles with the exception of RESET (FFh), READ STATUS (70h), and READ STATUS ENHANCED (78h). This bit applies only to the selected die (LUN).
I/O7	WP#	-	Write Protect: 0 = Protected 1 = Not protected In the normal array mode, this bit indicates the value of the WP# signal. In OTP mode this bit is set to 0 if a PROGRAM OTP PAGE operation is attempted and the OTP area is protected.

I/O No.	Page Program	Block Erase	Cache Program	Read	Cache Read	Definition
I/O 0	Pass/Fail	Pass/Fail	Pass/Fail(N)	Not use	Not use	FAIL N Page Pass : 0 Fail : 1
I/O 1	Not use	Not use	Pass/Fail(N-1)	Not use	Not use	FAILC N-1 Page Pass : 0 Fail : 1
I/O 2	Not use	Not use	Not use	Not use	Not use	"0"
I/O 3	0	0	0	ECC Status	ECC Status (N-1)	Refer to "8.13 Internal ECC" ECC Status Table
I/O 4						
I/O 5	Ready/Busy	Ready/Busy	Ready/Busy	Ready/Busy	Ready/Busy	ARDY Ready/Busy for Array Operation Busy : 0 Ready : 1
I/O 6	Ready/Busy	Ready/Busy	Ready/Busy	Ready/Busy	Ready/Busy	RDY Ready/Busy Busy : 0 Ready : 1
I/O 7	Write Protect	Write Protect	Write Protect	Write Protect	Write Protect	WP# Protected:0 Not Protected:1

**Notes:**

1. I/O0: This bit is only valid for Program and Erase operations. During Cache Program operations, this bit is only valid when I/O5 is set to 1.
2. I/O1: This bit is only valid for cache program operations. This bit is not valid until after the second 15h command or the 10h command has been transferred in a Cache program sequence.
3. I/O7: the bit indicates if the block is protected, which include WP protected, and Permanent Protection and other protection.

## 8.7 Read Status Enhanced – ONFI (78H)

Read Status Enhanced is an additional feature used to retrieve the status value for a previous Operation in the following cases:

- On a specific die of a multi-die stack configurations (single CE#), in case of concurrent operations

When the die are stacked (\*) to form DDP or QDP (single CE#), it is possible to run a first operation on the first die, then activate a concurrent operation on the second (or third or fourth) device. (Examples: Erase while Read, Read while Program, etc.)

- On a specific plane in case of multi-plane operations in the same die.

Follow figure defines the Read Status Enhanced behavior and timings. Writing 78h to the command register, followed by three row address cycles containing the page, block, and LUN addresses.

The command register remains in Status Read mode until further commands are issued.

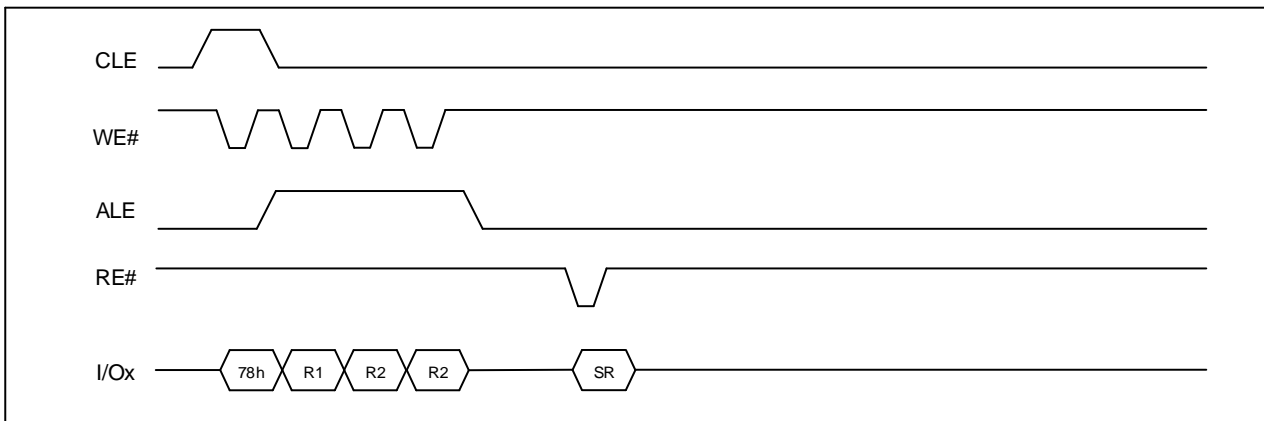


Figure 8-27: Read Status Enhanced-ONFI sequential figures

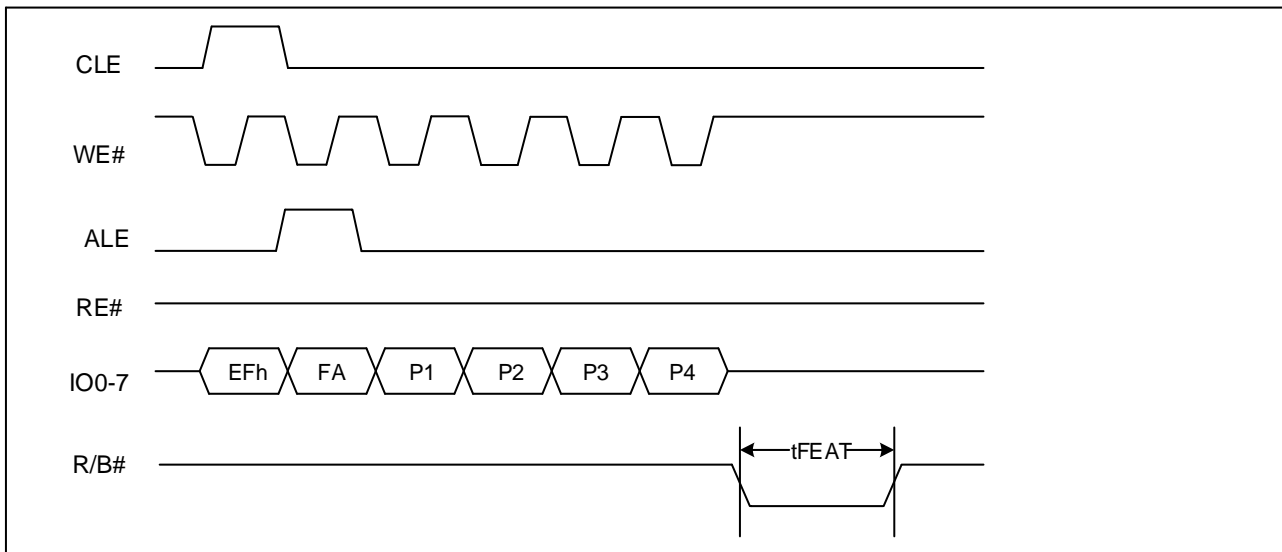
Note: SR, status register

R1/R2/R3: row address for status read.

### 8.8 Set Feature (EFH)

Users may set particular features using 'Set Feature' operation. Once a feature is set by users, it shall not be changed until the device is powered off or setting is changed by users. Figure of "Set Feature Sequence" defines the Set Features behavior and timings and follow Table defines features that users can change. Note that FFh command is not allowed during SET FEATURE sequence.

The NAND device may remain the current feature set until next power cycle since the feature set data is volatile. However, the reset command (FFh) cannot reset the current feature set Unless otherwise specified in the features table



Note: FA, feature address

Figure 8-28: Set Feature (EFH) sequential figures

Table Feature address define

Command cycle	Feature address	Description
EFh	10h	Output Driver strength setting
	90h	Array Operation Mode feature address
	Other	Reserved

Table Feature address 10h: Output Driver strength setting

Feature parameter	Option	IO7	IO6	IO5	IO4	IO3	IO2	IO1	IO0	value	Note
P1	Normal	0	0	0	0	0	0	0	0	00h	1
	Overdrive1	0	0	0	0	0	0	0	1	01h	
	Overdrive2	0	0	0	0	0	0	1	0	02h	
	Under drive	0	0	0	0	0	0	1	1	03h	
P2	Reserved	0	0	0	0	0	0	0	0	00h	
P3	Reserved	0	0	0	0	0	0	0	0	00h	
P4	Reserved	0	0	0	0	0	0	0	0	00h	

Note: 1. See follow Output Drive Strength Impedance Values table for details. Output Driver Strength Settings

Setting	Driver Strength	VccQ
Normal	1.0x =35 Ohms	3.3V/1.8V
Overdrive 1	1.4x =25 Ohms	
Overdrive 2	2.0x =18 Ohms	
Under drive	0.5x= 75Ohms	

Table Feature address 90h: Array Operation Mode

Sub feature Parameter	Options	IO7	IO6	IO5	IO4	IO3	IO2	IO1	IO0	Value	Note
P1											
Operation Mode option	Normal	0	0	0	0	1	0	0	0	00h	1
	Disable ECC	0	0	0	0	0	0	0	0	00h	1
	Enable ECC	0	0	0	0	1	0	0	0	08h	1
P2											
Reserved		Reserved(0)								00h	
P3											
Reserved		Reserved(0)								00h	
P4											
Reserved		Reserved(0)								00h	

Note:

These bits are reset to default value on power cycle.

## 8.9 Get Feature (EEH)

Users find how the target is set through 'Get Feature' command. The function shall return the current setting information (including modifications that may have been previously made with the Set Features function). If a host starts to read the first byte of data (i.e. P1 value), the host shall complete reading all four bytes of data before issuing another command (including Read Status or Read Status Enhanced). Follow figure of "Get Feature Sequence" defines the Get Features behavior and timings.

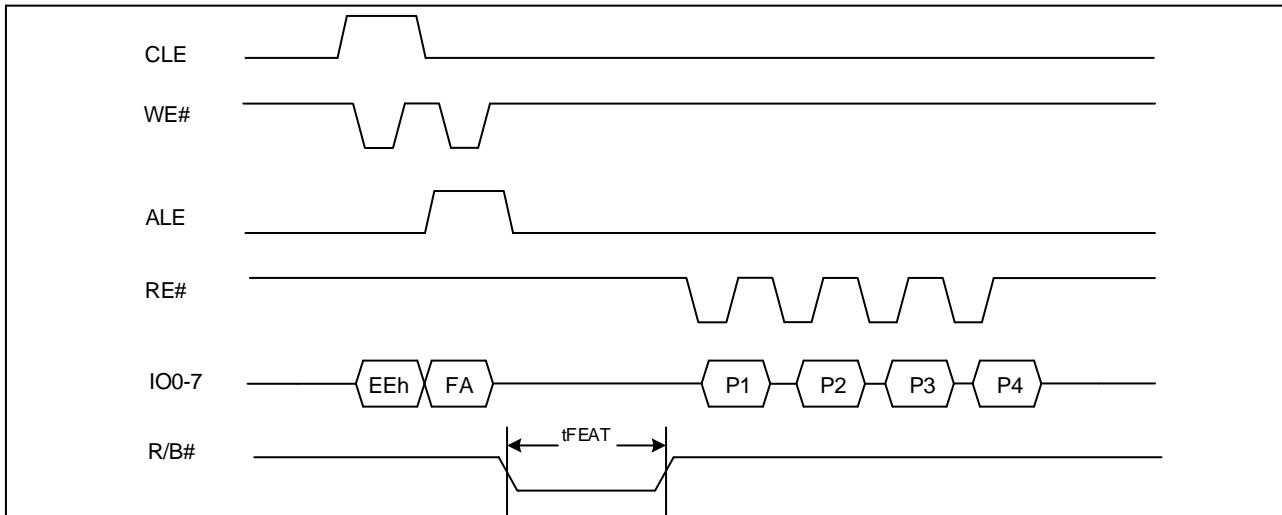


Figure 8-29: Get Feature (EEH) sequential figures

P1~P4 is the returned information with get feature command, which is same as the content of set feature command.

### 8.10 Ready/Busy# (R/B#)

The device has a Ready/Busy output that provides method of indicating the completion of a page program, erase, copy-back and random read completion. The R/B# pin is normally high and goes to low when the device is busy (after a reset, read, program, and erase operation). It returns to high when the internal controller has finished the operation. The pin is an open-drain driver thereby allowing two or more R/B# outputs to be Or-tied. Because pull-up resistor value is related to tR (R/B#), an appropriate value can be obtained with the following reference below chart. Its value can be determined by the following guidance.

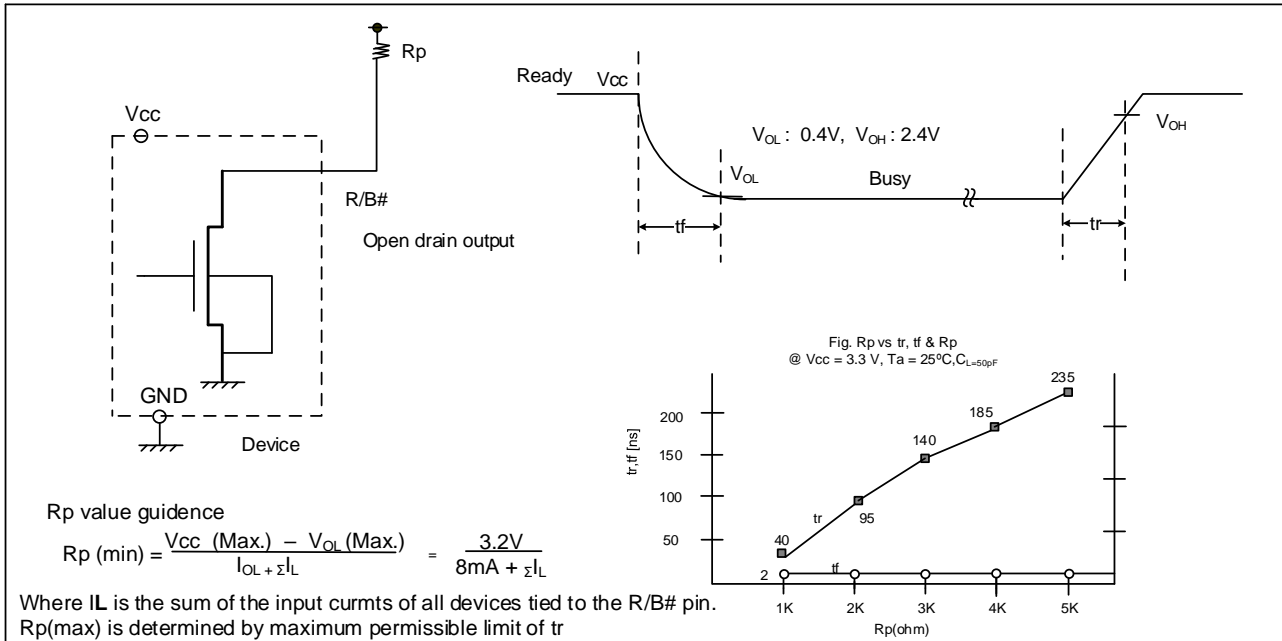


Figure 8- 30: Ready/Busy figures



## 8.11 Data Protection & Power on/off Sequence

The device is designed to offer protection from any involuntary program/erase during power-transitions. WP# pin provides hardware protection and is recommended to be kept at V<sub>IL</sub> during power-up and power-down. The two-step command sequence for program/erase provides additional software protection.

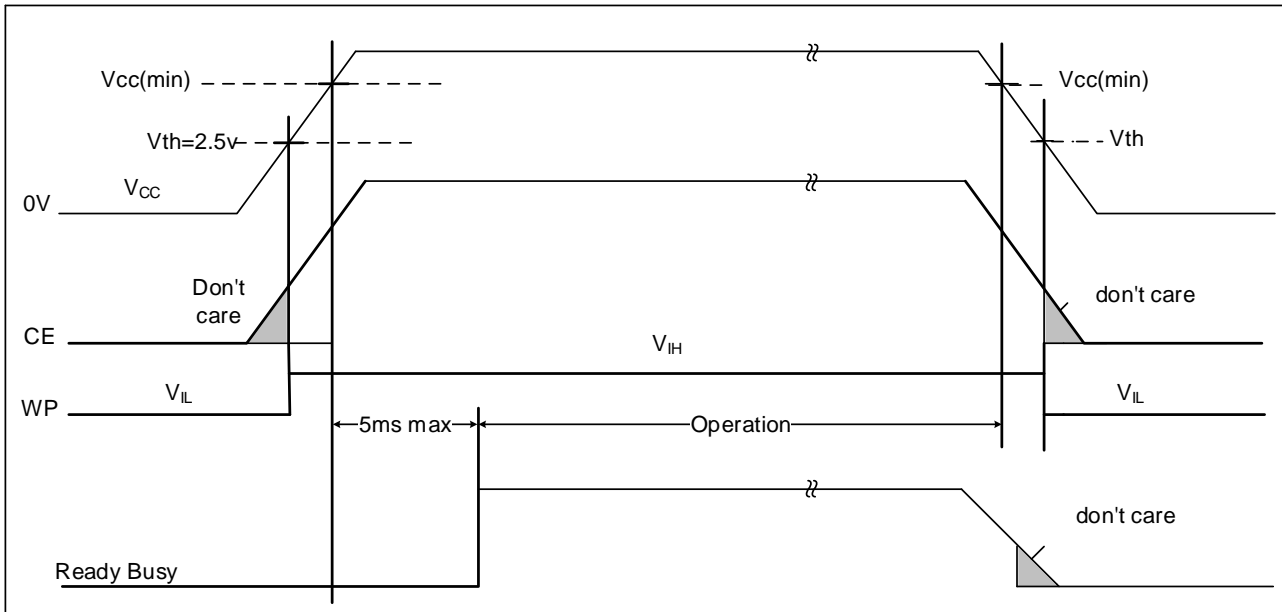


Figure 8-31\_a: Data protection and Power on/off (3.3V Device)

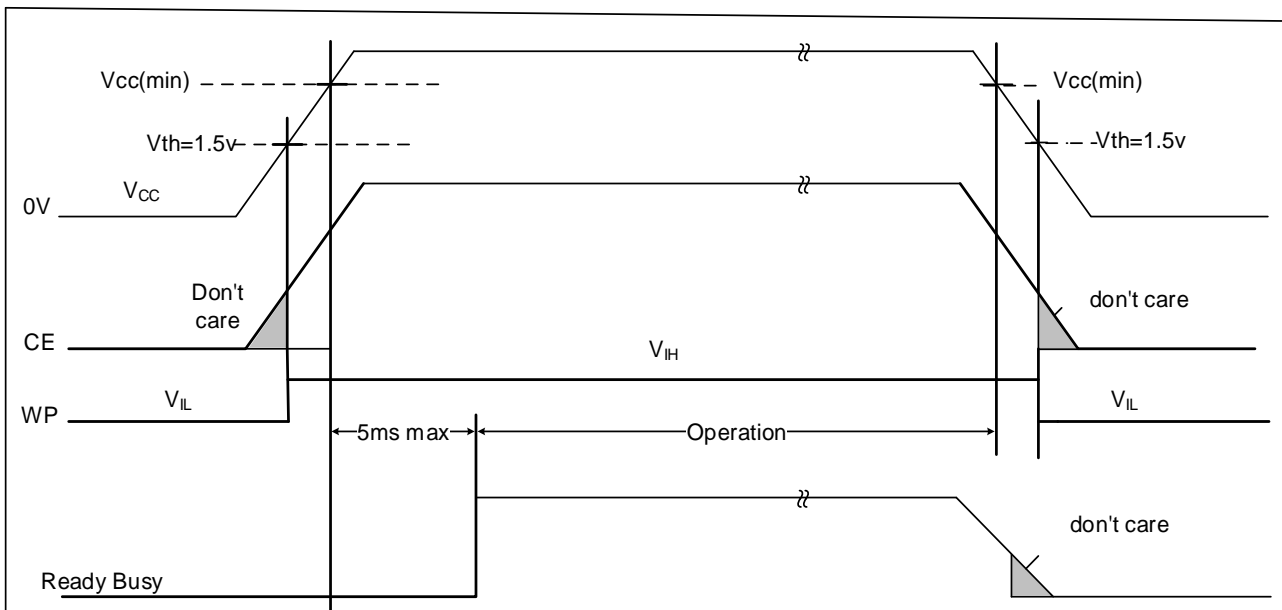


Figure 8-31\_b: Data protection and Power on/off (1.8V Device)

## 8.12 Multi-Plane Operation Limitation

Multi-plane commands require an address per operational plane. For a given multi-plane operation, these addresses are subject to the following requirements:

- Multi-plane operation should in the same LUN.
- The plane address bits must be different for each issued address.
- The block address exclude plane address may be different for each issued address.
- The page address bits must be identical for each issued address.
- Multi-plane copy back cannot cross plane boundaries.

## 8.13 Internal ECC

The ECC logic manages 4 bit error correction in each 512Bytes of main data and 32Byte spare data. READs and PROGRAMs with internal ECC can be enabled or disabled by setting Array operation Mode feature address (90h).

ECC is enabled default after device power up, so the default READ and PROGRAM commands operate with internal ECC in the “active” state when ECC enable.

To enable/disable ECC, perform the following command sequence:

- Issue the SET FEATURES command (EFH).
- Set the Array operation Mode feature address (90h)
  1. To enable ECC, Set ECC bit 3-0 to 1000b.
  2. To disable ECC, Set ECC bit 3-0 to 0000b.

During a PROGRAM operation, the device calculates an ECC code on the 2KB page in the cache register, before the page is written to the NAND Flash array.

During a READ operation, the page data is read from the array to the cache register, where the ECC code is calculated and compared with the ECC code value read from the array. If error bits are detected, the error is corrected in the cache register. Only corrected data is output on the I/O bus. The ECC status bit indicates whether or not the error correction was successful. The ECC Protection table below shows the ECC protection scheme for ECC segments used throughout a page. Each segment include Main and spare, for example, segment0 contains Main0 and spare0.

With internal ECC, the user must accommodate the following:

- Spare area definitions provided in the ECC Protection table below.
- ECC can protect main data and spare areas data. Any data wrote to the ECC Parity Data area are ignored.

**The Distribution of ECC Segment and Spare Area in a Page**

Main Area(2KB)				Spare Area(64B)			
				User meta data			
Main0	Main1	Main2	Main3	Spare0	Spare1	Spare2	Spare3
(512B)	(512B)	(512B)	(512B)	(16B)	(16B)	(16B)	(16B)

**Spare area Mapping**

Max Byte Address	Min Byte Address	ECC Protected	Area	Description
1FFH	000H	Yes	Main 0	User data 0
3FFH	200H	Yes	Main 1	User data 1
5FFH	400H	Yes	Main 2	User data 2
7FFH	600H	Yes	Main 3	User data 3
80Fh	800h	Yes	Spare 0	User meta data
81Fh	810h	Yes	Spare 1	User meta data
82Fh	820h	Yes	Spare 2	User meta data
83Fh	830h	Yes	Spare 3	User meta data

Note:

1. When ECC off, all the Spare Area is User data area
2. When ECC is on, the ECC for main/spare area (840H-87FH) is prohibited for user.
3. 800H is reserved for initial bad block mark, and please check the initial bad block mark with internal ECC off.

When user read the data from array, then use read status (70H) command to read out ECC status for the last read page data.

The follow table list the ECC error indicator, which is the most error for all ECC segments.

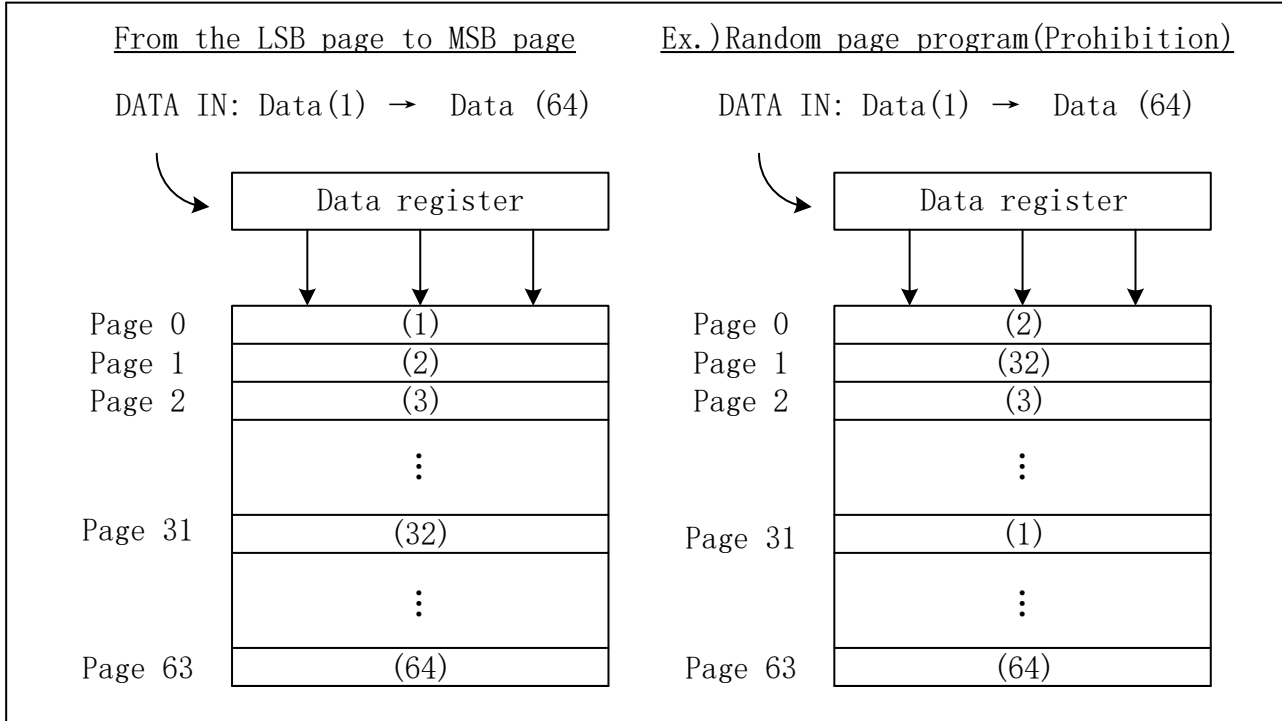
**ECC Status Table**

Bit 4	Bit 3	Bit 0	Description
0	0	0	No errors
0	1	0	1 to 2bits errors were detected and corrected. Refresh is recommended.
1	0	0	3 bits errors were detected and corrected. Refresh is recommended
1	1	0	4 bits errors were detected and corrected. Refresh is recommended
0	0	1	Multiple bit errors were detected and not corrected

Note: bit4, bit3, bit0 is the NAND status

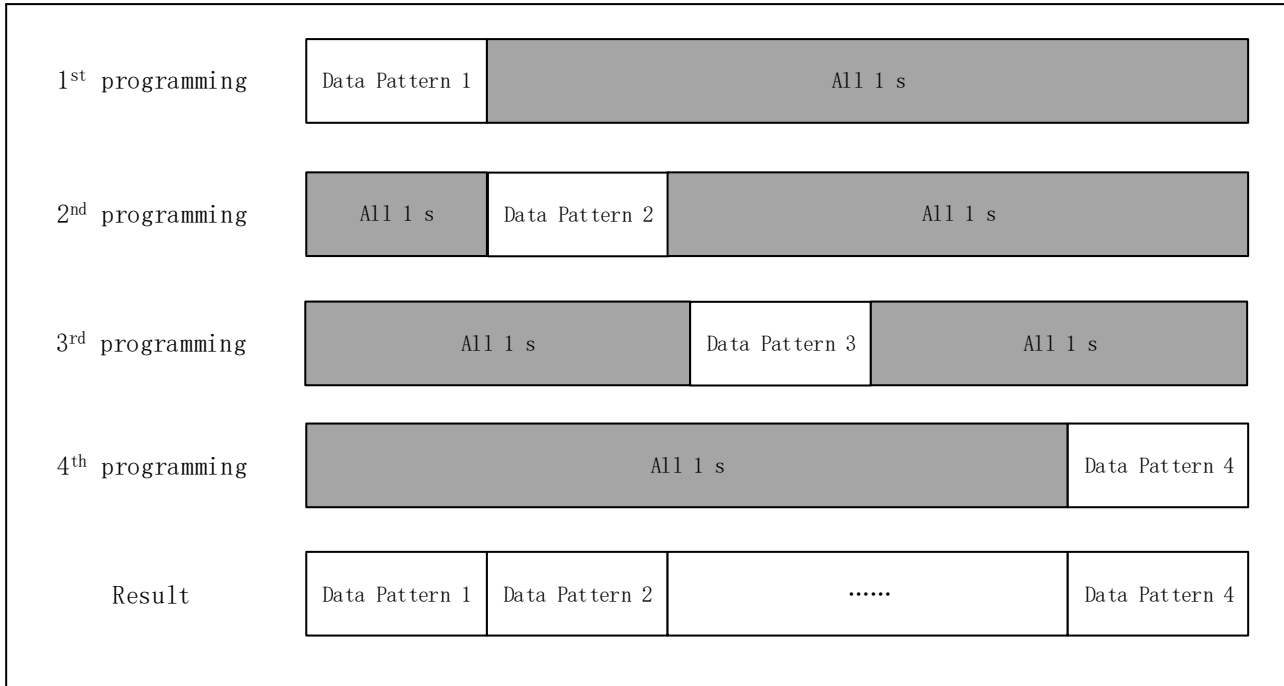
## 8.14 Addressing for program operation

Within a block, the pages must be programmed consecutively from the LSB (least significant bit) page of the block to MSB (most significant bit) page of the block. Random page address programming is prohibited.



### 8.15 Several programming cycles on the same page (Partial Page Program)

Each segment can be programmed individually as follows:



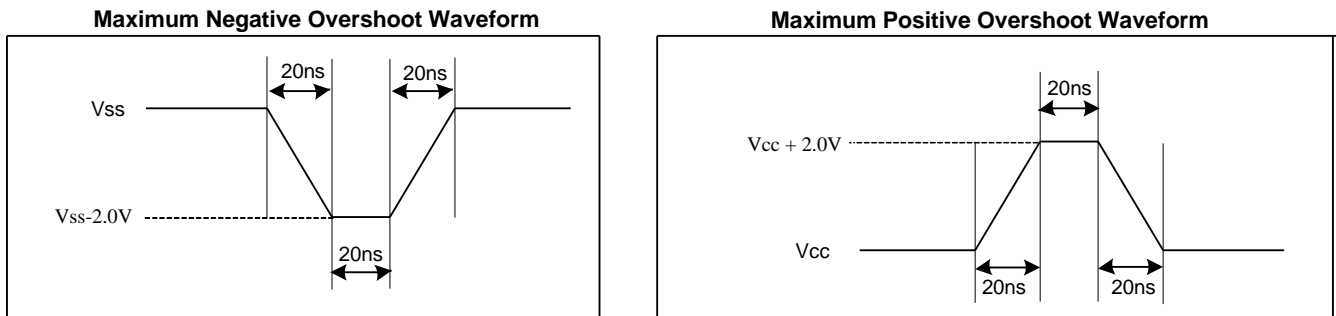
## 9. ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Value	Unit
Voltage on any pin relative to VSS	VIN/OUT	-0.6 to VCC+0.4	V
	VCC(3.3V)	-0.6 to + 4.0	
	VCC(1.8V)	-0.6 to + 2.5	
Temperature Under Bias	TBIAS	-50 to +125	°C
Storage Temperature	TSTG	-65 to +150	°C

**Notes:**

1. Minimum DC voltage is -0.6V on input/output pins.
2. Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

**Figure 9-1. Input Test Waveform and Measurement Level**



## 10. VALID BLOCKS

	Density	Min	Typ.	Max	Unit
Valid Block Number	2Gb	2008		2048	Blocks

**Notes:**

1. The 1<sup>st</sup> block is guaranteed to be a valid block with ECC at the time of shipment.
2. Invalid blocks are one that contains one or more bits. The device may contain invalid blocks upon shipment.



## 11. DC CHARACTERISTICS

Parameter		Symbol	Test Conditions	1.7v ~ 1.95v / 2.7v ~ 3.6v			Unit
				Min	Typ.	Max	
Power on reset current		I <sub>CC0</sub>	FFh command after power on			50	mA
Operating Current	Page Read with Serial Access	I <sub>CC1</sub>	t <sub>RC</sub> =Min, CE#=V <sub>IL</sub> , I <sub>OUT</sub> =0mA	-	15	30	mA
	Program	I <sub>CC2</sub>	-	-	15	30	
	Erase	I <sub>CC3</sub>	-	-	15	30	
Standby Current (CMOS)		I <sub>SB</sub>	CE#=V <sub>CC</sub> -0.2, WP#=0V/V <sub>CC</sub>	-	10	50	μA
Input Leakage Current		I <sub>LI</sub>	V <sub>IN</sub> =0 to V <sub>CC</sub> (max)	-	-	±10	
Output Leakage Current		I <sub>LO</sub>	V <sub>OUT</sub> =0 to V <sub>CC</sub> (max)	-	-	±10	
Input High Voltage		V <sub>IH</sub>	-	0.8xV <sub>CC</sub>	-	V <sub>CC</sub> +0.3	V
Input Low Voltage		V <sub>IL</sub>	-	-0.3	-	0.2xV <sub>CC</sub>	
Output High Voltage Level		V <sub>OH</sub>	I <sub>OH</sub> =-400μA	V <sub>CC</sub> -0.3	-	-	
Output Low Voltage Level		V <sub>OL</sub>	I <sub>OL</sub> =2.1mA	-	-	0.4	
Output Low Current(R/B#)		I <sub>OL(R/B#)</sub>	V <sub>OL</sub> =0.45V	3/8	4/10	-	mA

## 12. AC CHARACTERISTICS

### 12.1 Test Condition

(TA=-40 to 85°C VCC=1.7V~1.95V /2.7V~3.6V)

Parameter	GD9Ax2GxF2A
Input Pulse Levels	0V to V <sub>CC</sub>
Input Rise and Fall Times	5ns
Input and Output Timing Levels	V <sub>CC</sub> /2
Output Load	1 TTL GATE and CL=30fF

### 12.2 Capacitance (TA=25°C, F=1.0MHz)

Parameter	Symbol	Test condition	Min	Max	Unit
Input/Output Capacitance	C <sub>I/O</sub>	V <sub>IL</sub> =0V	-	6	pF
Input Capacitance	C <sub>IN</sub>	V <sub>IN</sub> =0V	-	8	pF

Notes: Capacitance is periodically sampled and not 100% tested.

### 12.3 AC Timing Characteristics

Parameter	Symbol	3.3V		1.8V		
		Min	Max	Min	Max	
CE# setup time	tCS	15	-	15	-	ns
CE# hold time	tCH	5	-	5	-	ns
CLE setup time	tCLS	12	-	12	-	ns
CLE Hold time	tCLH	5	-	5	-	ns
ALE setup time	tALS	10	-	10	-	ns
ALE hold time	tALH	5	-	5	-	ns
Data setup time	tDS	7	-	10	-	ns
Data hold time	tDH	5	-	5	-	ns
Write cycle time	tWC	20	-	25	-	ns
WE# pulse width	tWP	10	-	12	-	ns
WE# high hold time	tWH	7	-	10	-	ns
Address to data loading time	tADL	300	-	300	-	ns
WE# high to busy	tWB	-	100	-	100	ns
Ready to WE# low	tRW	20	-	20	-	ns
Ready to RE# low	tRR	20	-	20	-	ns
CLE to RE# delay	tCLR	10	-	10	-	ns
ALE to RE# delay	tAR	10	-	10	-	ns
Read cycle time	tRC	20	-	25	-	ns
RE# pulse width	tRP	10	-	12	-	ns
RE# high hold time	tREH	7	-	10	-	ns
RE# access time	tREA	-	18	-	20	ns
CE# access time	tCEA	-	23	-	25	ns
RE# high to output high Z	tRHZ	-	100	-	100	ns
CE# high to output high Z	tCHZ	-	50	-	50	ns
CE# high to ALE or CLE Don't care	tCSD	10	-	10	-	ns
CE# high to output hold	tCOH	15	-	15	-	ns
RE# high to output hold	tRHOH	15	-	15	-	ns
RE# low to output hold	tRLOH	5	-	5	-	ns
Output Hi-Z to RE# Low	tIR	0	-	0	-	ns
CE# low to RE# low	tCR	10	-	10	-	ns
RE# high to WE# low	tRHW	100	-	100	-	ns
WE# high to RE# low	tWHR	60	-	60	-	ns
WE# high to RE# low for random data out	tWHR2	60		60		
Write protect time	tWW	100	-	100	-	ns

## 12.4 Performance Characteristics

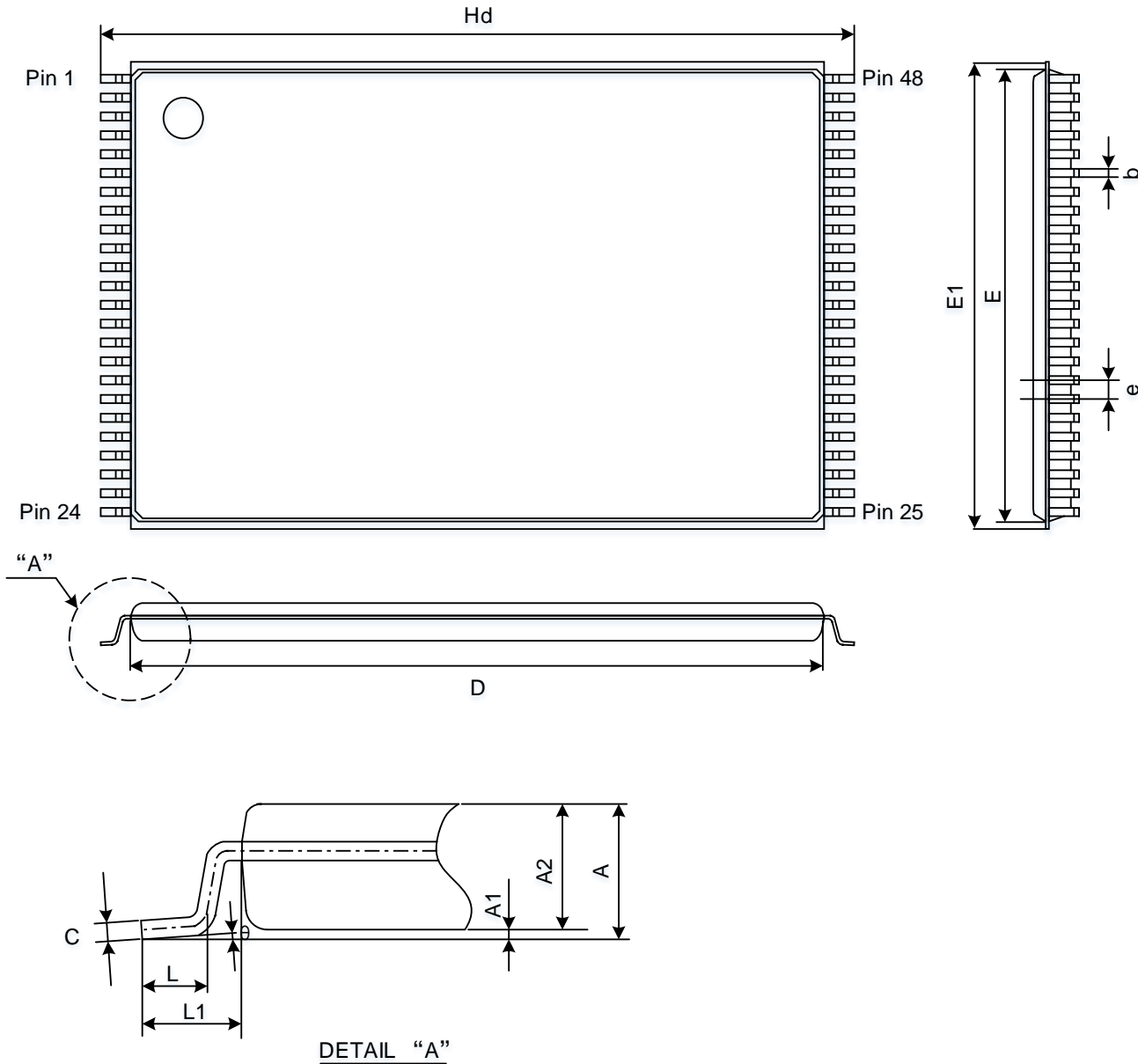
Parameter	Symbol	Min	Typ.	Max	Unit
Data transfer from cell to register	tR			25	us
Data transfer from cell to register with ECC	tR_ECC		45	50	us
Program Time	tPROG	-	300	600	μs
Program Time with ECC	tPROG_ECC		400	600	μs
Page Programming or Erase Time for a Protection Page	tPBSY				us
Read Cache busy time	tCBSYR		5	tR	μs
Cache Program short busy time	tCBSYW		5	tPROG	μs
Dummy busy time	tDBSY		0.5	1	us
Number of Partial Program Cycles in the Same Page	NOP	-	-	4	cycles
Block Erase Time	tBERS	-	3	5	ms
Device resetting time	Read			10	us
	Program			20	us
	Erase			500	us

**Note:** Typical value is measured at VCC=3.3V, TA=25°C(3.3V Device) or VCC=1.8 V, TA=25°C(1.8V Device).

### 13. PACKAGE INFORMATION

#### 13.1 TSOPI-48

Figure 13-1: TSOPI-48 figures

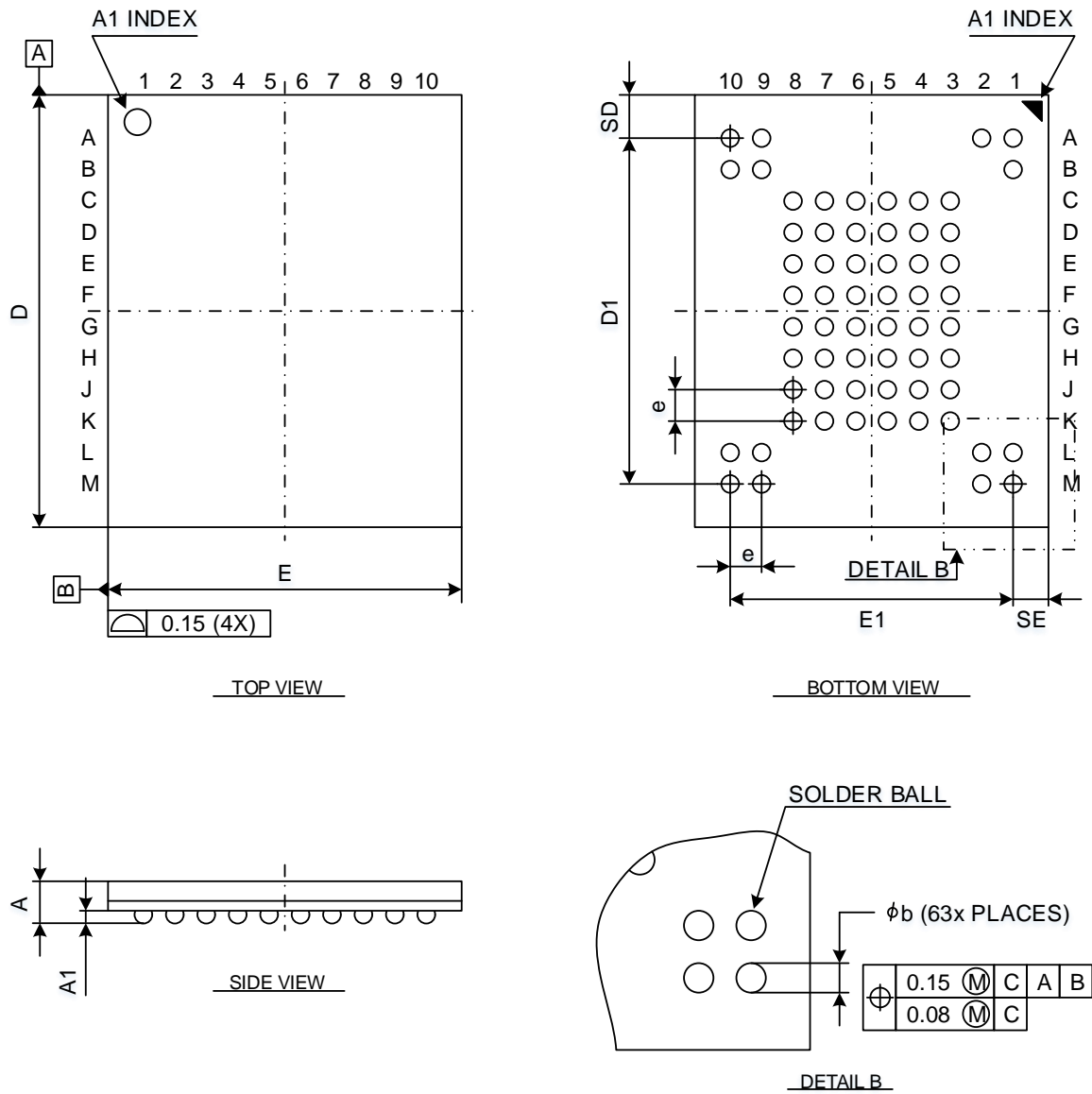


#### Dimensions

Symbol		A	A1	A2	b	D	Hd	E	E1	e	L	L1	θ
Unit													
mm	Min	-	0.05	0.90	0.14	18.30	19.80	11.90	-	0.50	0.425	0.60	0
	Nom	-	0.10	1.00	0.22	18.40	20.00	12.00	-		0.525	0.80	-
	Max	1.20	0.15	1.10	0.30	18.50	20.20	12.10	12.40		0.625	1.00	7

Note:

1. Tolerance of the dimension should be  $\pm 0.1$  unless otherwise specified.
2. Corner radius should be less than  $\pm 0.1R$  unless otherwise specified (excluding outer lead).
3. Tolerance of the angles should be  $\pm 0.5$  degree unless otherwise specified.
4. The mold surface should have a finish  $8\pm 2S$  without luster.  
Trace of knockout pin and the shaded portion of detail "A" should be polish surface.
5. Discrepancies between upper and lower molding cavity should be less than 0.05 of the package.
6. Mold flush should be less than 0.2mm.

**13.2 FBGA-63**
**Figure 13-2: FBGA-63 figures**

**Dimensions**

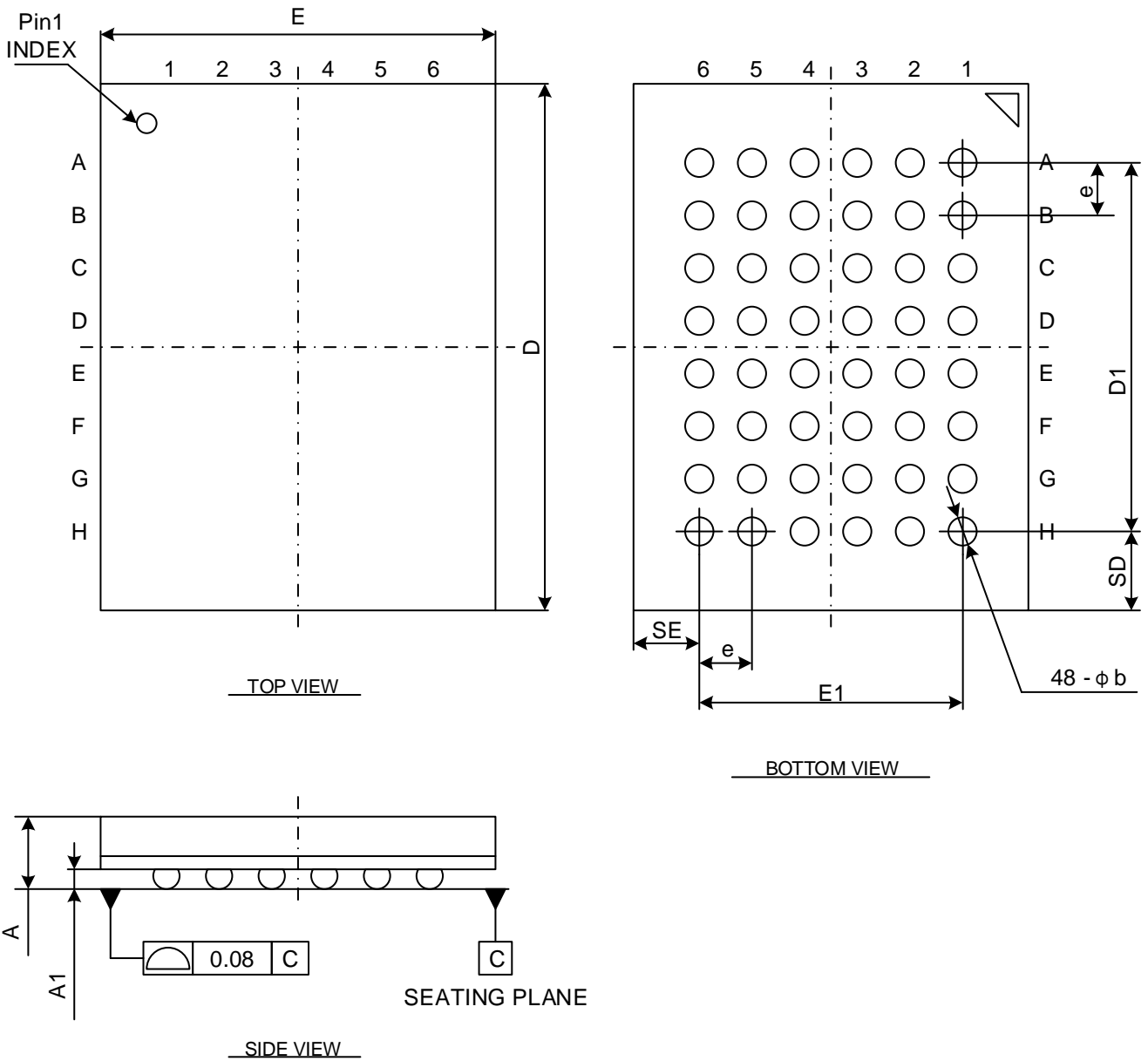
Symbol		A	A1	b	E	E1	D	D1	e	SD	SE
Unit											
mm	Min	-	0.25	0.40	8.90	7.20 BSC	10.90	8.80 BSC	0.80 BSC	1.10 TYP	0.90 TYP
	Nom	-	0.30	0.45	9.00		11.00				
	Max	1.00	0.40	0.50	9.10		11.10				

Note:

- Controlling dimension: millimeter.
- Reference document: JEDEC MO-207
- The diameter of pre-reflow solder ball is  $\varnothing 0.42\text{mm}$  (0.40mm SMO).

### 13.3 FBGA-48

Figure 13-3: FBGA-48 figures



#### Dimensions

Symbol		A	A1	b	E	E1	D	D1	e	SD	SE
Unit											
mm	Min	-	0.25	0.40	5.90	4.00 BSC	7.90	5.60 BSC	0.80 BSC	1.20 TYP	1.00 TYP
	Nom	-	0.30	0.45	6.00		8.00				
	Max	1.00	0.40	0.50	6.10		8.10				

Note:

- Controlling dimension: millimeter.



## 14. Part Numbering Information

GD 9F U 2G 8 F 2 A M G I  
 1      2      3      4      5      6      7      8      9      10    11

### 1. GD

### 2. Memory Type

9F: Parallel NAND without Internal ECC

9A: Parallel NAND with Internal ECC

### 3. Power Supply

	V <sub>CCQ</sub>	V <sub>CC</sub>
U	2.7v ~ 3.6v	2.7v ~ 3.6v
S	1.7v ~ 1.95v	1.7v ~ 1.95v

### 4. Density:

1G: 1Gb

2G: 2Gb

4G: 4Gb

8G: 8Gb

AG: 16Gb

### 5. Organization

8: x8

6: x16

### 6. NAND Type:

F: SLC, 1Die, 1nCE, 1Rnb

E: SLC; 2Die, 1nCE, 1Rnb

D: SLC; 4Die, 1nCE, 1Rnb

### 7. Function Mode:

2: Spare size is 128bytes;

3: Spare size is 64bytes;

4: Spare size is 256 bytes;

### 8. Process Generation:

A: A GEN

B: B GEN

### 9. Package

M: TSOPI-48

L: FBGA-63

W: Wafer

D: FBGA-48

### 10. Package Material & Packing

G: Lead & Halogen Free

W: Wafer

### 11. Temperature Grade

I: Industrial (-40°C ~ 85°C)

F: Industrial+ (-40°C ~ 85°C)

J: Industrial (-40°C ~ 105°C)

Note: (1) F: Industrial+, Full Function Test for Automotive application and No AECQ

## 15. Revision History

Version No.	History Description	Page	Date
0.0	Initial Preliminary Release		2019-03-4
0.1	Recalculate CRC		2019-03-21
0.9	Remove the "An internal voltage detector disables all functions whenever VCC is below VLKO" in Data Protection& Power on/off Sequence	57	2019-05-20
	Modify the description of the status register.	50/51	
	Update the Parameter Page 108~109Byte, 129Byte, 131Byte, 137Byte and recalculate the CRC.	46/47/48	
	Update the tWC/tWP/tWH/tRC/tRP/tREH in DC characteristics.	67	
	Modify the description of the Applied Input/output Voltage and VCC	63	
	Add Input Test Waveform and Measurement Level	63	
	Remove the DID1 Description and modify the DID (2nd) in Read ID Data Table.	40	
	Modify the Serial Access Time in 4th Byte of Device Identifier Description "25ns" <IO7,IO3> to <1,0>.	41	
	Modify the size of spare area "16" <IO2> to <1>	41	
	Modify the Plane size per LUN "1Gb" <IO6,IO5,IO4> to <0,0,0>	41	
	Update the product ID Data Table	40	
	Modify the ECC status in 8.13 Internal ECC	60	

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