SERIES 60AD

Optical Encoder with integrated Joystick and Pushbutton

FEATURES

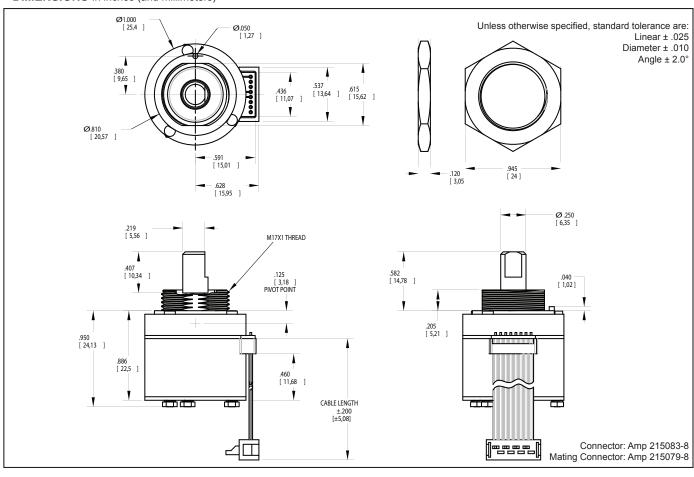
- Dome contacts provide excellent tactile feedback in all directions
- · Choices of actuation force, cable length and termination
- · Customized solutions available

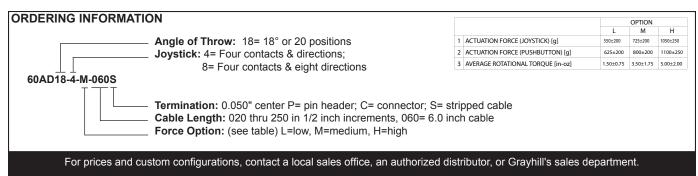
APPLICATIONS

- Aerospace
- Automotive
- · Medical devices

DIMENSIONS in inches (and millimeters)

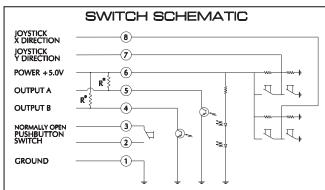






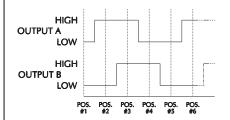


JOYSTICK OPERATION + ENCODER WAVEFORM AND TRUTH TABLE Standard Quadrature 2-Bit Code



*EXTERNAL PULL-UP RESISTORS REQUIRED FOR OPERATION (2.2k\(\Omega\)).

ENCODER WAVEFORM (C.W. ROTATION)

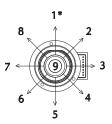


ENCODER TRUTH TABLE [C.W. ROTATION]

POSITION	OUTPUT A	OUTPUT B
#1	0	0
#2		0
#3		0
#4	0	0

 INDICATES LOGIC-HIGH INDICATES LOGIC-LOW CODE REPEATS EVERY FOUR POSITIONS

JOYSTICK POSITION DIAGRAM INDICATES DIRECTION OF D-FLAT ON BUSHING



JOYSTICK TRUTH TABLE

POSITION	X OUTPUT	Y OUTPUT	
1	NEUTRAL	HIGH	
2	HIGH	HIGH	
3	HIGH	NEUTRAL	
4	HIGH	LOW	
5	NEUTRAL	LOW	
6	LOW	LOW	
7	LOW	NEUTRAL	
8	LOW	HIGH	
9	NEUTRAL	NEUTRAL	

SPECIFICATIONS

Rotary Specifications

Operating Voltage: 5.00 ± 0.25 Vdc Supply Current: 20mA max at 5 Vdc Minimum Sink Current: 2.0mA at 5 Vdc Power Consumption: 0.1mW max at 5 Vdc Output: Open collector phototransistor, 2.2k Ω external pull-up resistors are required Output Code: 2-Bit quadrature, channel A leads channel B by 90° in clockwise rotation

Logic Output Characteristics: High: No less than 3.5 Vdc Low: No greater than 1.0 Vdc

Mechanical Life: 1 million rotational cycles (through all positions and a full return)

Rotational Torque: see table

Maximum Rotational Speed: 100 RPM Mounting Torque: 15 in-lbs. maximum Shaft Push/Pull Out Force: 45 lbs min. Shaft Side-Load Force: 20 lbs. max. Terminal Strength: 15 lbs pull-out force min.

Pushbutton Specifications

Rating: 10 mA at 5 Vdc resistive Contact Resistance: less than 10 ohms Contact Bounce: < 4ms make. <10 ms break Mechanical Life: 1 million actuations min.

Actuation Force: see table Pushbutton Travel: .027 ± .010 in.

Joystick Specifications Supply Current: 5mA max

Output Code: 2-Bit

Logic Output Characteristics: Neutral Position: 2.5 ± 0.5 Vdc

High-State Position: >4.5 Vdc Low-State Position: <0.5 Vdc Mechanical Life: 500k cycles min. Actuation Force: see table Angle of Throw: 3.5° +2°/-1°

Environmental Ratings

Operating Temp. Range: -40°C to 85°C Storage Temp. Range: -55°C to 100°C Relative Humidity: 96 hours at 90-95%

humidity at 40°C

Vibration: Harmonic motion with amplitude of 15g, within 10 to 2000 Hz for 12 hours

Mechanical Shock:

Test 1: 100g for 6ms half-sine wave with a

velocity change of 12.3 ft/s

Test 2: 100g for 6ms sawtooth wave with a

velocity change of 9.7 ft/s

Materials and Finishes Detent Housing: Nylon 6/10

Shaft: Nylon 6/10

Shaft Insert: 303 stainless steel Joystick Housing: Nylon 6,10 Centering Plate: Nylon 6,10 **Detent Balls:** Carbon steel **Detent Springs:** Music wire Dome Contacts: Stainless steel

Dome Housings: Polycarbonate over brass-

lead frame

Dome Retainers: Nylon 6,0; 30% glass-filled Joystick Actuators: Polyphthalamide; 50%

glass filled

Pushbutton Dome Retainer: Polycarbonate Printed Circuit Board: NEMA grade FR-4. Glass-cloth epoxy, double clad with copper Infrared Emitter: Gallium arsenide Phototransistor: Planar silicon

Resistors: Metal oxide on ceramic substrate Solder: 95.5% SN, 3% AG, 0.5% CU

OPTIONS

Contact Grayhill for custom terminations, rotational torque, number of positions, shaft configurations, and resolutions.

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M11L001C M11L0X1P USBM31Q081RMJ4S USBC20O051JMJS TW08BLK12 HRS202B1 S30L0M1CSJBLK HF11R11 HG-44MIS000-2654 HG-44MIS000-U-2655 4P182F1E55475 TS4A1S00A BD140D01GR0000 BD150SD4BL1200 3140SAL6475 TW01BLK11
TW01GRY1 ZD4PA203 HF44S10UMJ0 TS3N2S00A TS1R1U00A TS1R1S09A TS1D2S00A TS1D1U02A HFX45S02 HFX10S00
HF11P11 4R28-2S1E-55-00 BD150A01RE0000 ZD4PA24 ZD4PA22 ZD4PA12