

## Low-Power, Slew-Rate-Limited RS-485/RS-422 Transceivers

#### General Description

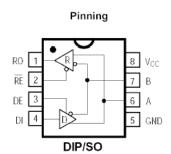
The HGX485E is low-power transceivers for RS-485 and RS-422 communication. IC contains one driver and one receiver. The driver slew rates of the HGX485 is not limited, allowing them to transmit up to 2.5Mbps.

These transceivers draw between 120µA and 500µA of supply current when unloaded or fully loaded with disabled drivers. All parts operate from a single 5V supply. Drivers are short-circuit current limited and are protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high-impedance state. The receiver input has a fail-safe feature that guarantees a logic-high output if the input is open circuit. The HGX485E is designed for half-duplex applications.



#### **Features**

- Low Quiescent Current: 300µA
- -7V to +12V Common-Mode Input Voltage Range
- Three-State Outputs
- 30ns Propagation Delays, 5ns Skew
- Full-Duplex and Half-Duplex Versions Available
- Operate from a Single 5V Supply
- Allows up to 32 Transceivers on the Bus
- Data rate: 2,5 Mbps
- Current-Limiting and Thermal Shutdown for Driver Overload Protection





#### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage ( $V_{CC}$ ) 12V Control Input Voltage -0.5V to ( $V_{CC}$  + 0.5V)

Driver Input Voltage (DI) -0.5V to (V<sub>CC</sub>+ 0.5V)

Driver Output Voltage (A, B) -8V to +12.5V Receiver Input Voltage (A, B) -8V to +12.5V Receiver Output Voltage (RO) -0.5V to  $(V_{\rm CC}+0.5V)$ 

Continuous Power Dissipation (T<sub>A</sub>= +70°C) 8-Pin Plastic DIP (derate 9.09mW/°C above +70°C) 727mW

8-Pin SO (derate 5.88mW/°C above +70°C) 471mW

Operating Temperature Ranges0°C to +70°C Storage Temperature Range -65°C to +160°C Lead Temperature (soldering, 10sec) +300°C

#### DC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = 5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.})$  (Notes 1, 2)

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNITS	
Differential Driver Output (no load)	V <sub>OD1</sub>				5	V	
Differential Driver Output	V <sub>OD2</sub>	$R = 50\Omega (RS-422)$		2			V
(with load)		$R = 27\Omega$ (RS-485), F	igure 4	1.5		5	
Change in Magnitude of Driver Differential Output Voltage for Complementary Output States	ΔVod	R = $27\Omega$ or $50\Omega$ , Figu			0.2	V	
Driver Common-Mode Output Voltage	Voc	R = 27 $\Omega$ or 50 $\Omega$ , Figu			3	V	
Change in Magnitude of Driver Common-Mode Output Voltage for Complementary Output States	ΔVod	R = $27\Omega$ or $50\Omega$ , Figu			0.2	V	
Input High Voltage	VIH	DE, DI, RE	2.0			V	
Input Low Voltage	VIL	DE, DI, RE			0.8	V	
Input Current	l <sub>IN1</sub>	DE, DI, RE			±2	μA	
Input Current	l <sub>IN2</sub>	DE = 0V; V <sub>IN</sub> = 12V				1.0	mA
(A, B)		$V_{CC} = 0V \text{ or } 5.25V,$	V <sub>IN</sub> = -7V			-0.8	
Receiver Differential Threshold Voltage	<b>V</b> TH	-7V ≤ V <sub>CM</sub> ≤12V		-0.2		0.2	V
Receiver Input Hysteresis	$\Delta V$ th	V <sub>CM</sub> = 0V		70		mV	
Receiver Output High Voltage	Vон	Io = -4mA, VID = 200	3.5			V	
Receiver Output Low Voltage	Vol	Io = 4mA, VID = -200mV				0.4	V
Three-State (high impedance) Output Current at Receiver	lozr	0.4V ≤ Vo ≤ 2.4V			±1	μΑ	
Receiver Input Resistance	RIN	-7V ≤ Vcм ≤ 12V				kΩ	



# DC ELECTRICAL CHARACTERISTICS (continued) (Vcc = 5V ±5%, Ta = Tmin to Tmax, unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
No-Load Supply Current	Icc	DE = V <sub>CC</sub>		500	900	
(Note 3)		RE = 0V or Vcc		300	500	μA
		DE = 0V				
Driver Short-Circuit Current,						
	losd1	-7V ≤ Vo ≤ 12V (Note 4)	35		250	mA
Vo = High						
Driver Short-Circuit Current,						
	losd2	-7V ≤ Vo ≤12V (Note 4)	35		250	mA
Vo = Low						
Receiver Short-Circuit Current	Iosr	0V ≤ Vo ≤ Vcc	7		95	mA

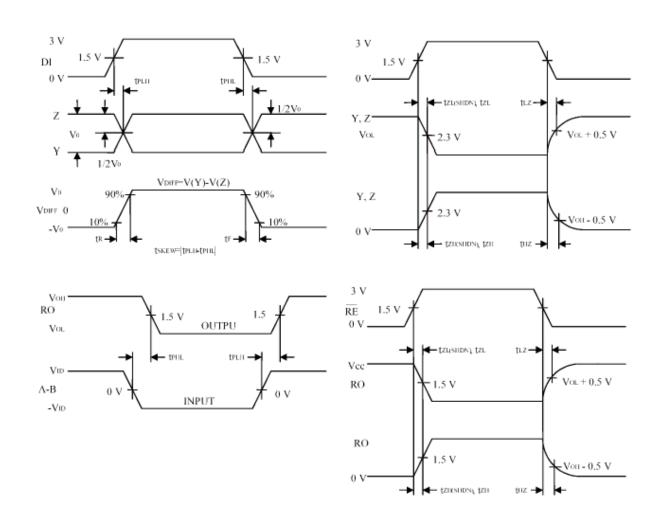
#### **SWITCHING CHARACTERISTICS**

(Vcc = 5V ±5%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Input to Output	<b>t</b> PLH	RDIFF = $54\Omega$	10	30	60	ns
	<b>t</b> PHL	C <sub>L1</sub> = C <sub>L2</sub> = 100pF	10	30	60	
Driver Output Skew to Output	<b>t</b> skew	RDIFF = $54\Omega$ , CL1 = CL2 = $100$ pF		5	10	ns
Driver Enable to Output High	tzн	C <sub>L</sub> = 100pF, S2 closed		40	70	ns
Driver Enable to Output Low	<b>t</b> zL	C <sub>L</sub> = 100pF, S1 closed	40	70	ns	
Driver Disable Time from Low	tız	C <sub>L</sub> = 15pF, S1 closed		40	70	ns
Driver Disable Time from High	<b>t</b> HZ	C <sub>L</sub> = 15pF, S2 closed		40	70	ns
tPLH - tPHL   Differential	<b>t</b> skd	RDIFF = $54\Omega$		13		ns
Receiver Skew		C <sub>L1</sub> = C <sub>L2</sub> = 100pF				
Receiver Enable to Output Low	<b>t</b> zL	C <sub>RL</sub> = 15pF, S1 closed		20	50	ns
Receiver Enable to Output High	tzн	C <sub>RL</sub> = 15pF, S2 closed		20	50	ns
Receiver Disable Time from Low	<b>t</b> LZ	C <sub>RL</sub> = 15pF, S1 closed		20	50	ns
Receiver Disable Time from High	<b>t</b> HZ	C <sub>RL</sub> = 15pF, S2 closed		20	50	ns
Maximum Data Rate	fmax		2.5			Mbps



## Operation timing diagrams of HGX 485



### **Table of HGX 485 operation**

Transmission				Receipt				
	Inputs		Outp	uts X	Inputs			Outputs
RE	DE	DI	Z	Υ	RE	DE	A-B	RO
Х	1	1	0	1	0	0	+0.2V	1
Х	1	0	1	0	0	0	-0.2V	0
0	0	Х	Z	Z	0	0	open	1
1	0	Χ	Z	Z	1	0	Х	Z

X-don't care Z-high resistance



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