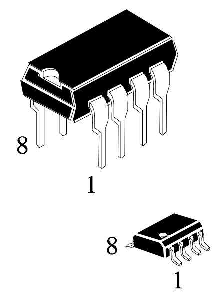
Closed Loop Brushless Motor Adapter

(compatible to MC33039&NCV33039)

The HT33039 is a high performance closed−loop speed control adapter specifically designed for use in brushless DC motor control systems. Implementation will allow precise speed regulation without the need for a magnetic or optical tachometer. This device contains three input buffers each with hysteresis for noise immunity, three digital edge detectors, a programmable monostable, and an internal shunt regulator. Also included is an inverter output for use in systems that require conversion of sensor phasing. Although this device is primarily intended for use with the MC33035 brushless motor controller, it can be used cost effectively in many other closed−loop speed control applications.



ORDERING INFORMATION

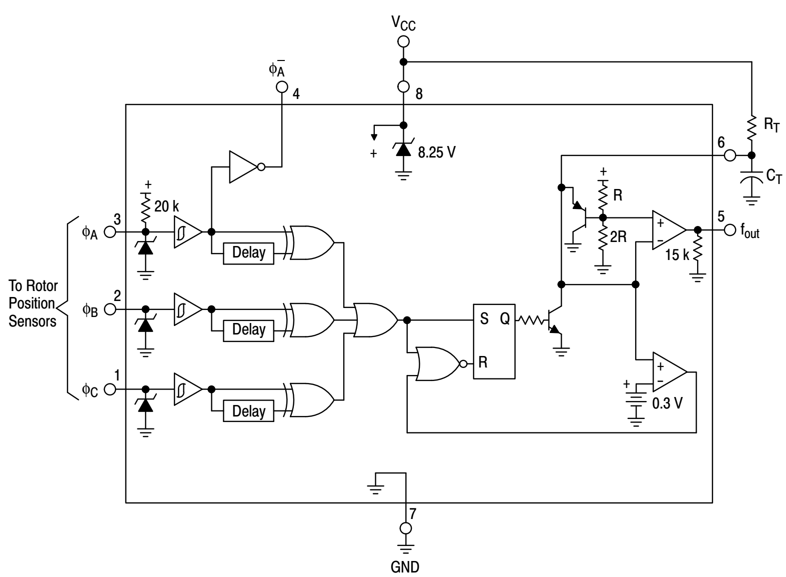
HT33039ANZ DIP8

HT33039ARZ SOP8

T_A = -40° to 85°C for all packages.

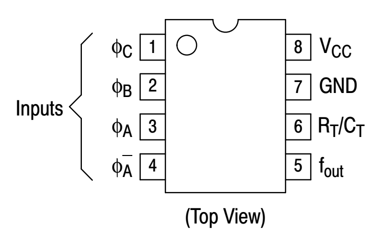
Features

- Digital Detection of Each Input Transition for Improved Low Speed Motor Operation
- TTL Compatible Inputs With Hysteresis
- Operation Down to 5.5 V for Direct Powering from MC33035 Reference
- Internal Shunt Regulator Allows Operation from a Non−Regulated Voltage Source
- Inverter Output for Easy Conversion between 60°/300° and 120°/240° Sensor Phasing Conventions
- Pb−Free Packages are Available



Representative Block Diagram

PIN CONNECTIONS



MAXIMUM RATINGS

Rating	Symbol	Value	Unit
V_{CC} Zener Current	$I_{Z(V_{CC})}$	30	mA
Logic Input Current (Pins 1, 2, 3)	I_{IH}	5.0	mA
Output Current (Pins 4, 5), Sink or Source	I_{DRV}	20	mA
Power Dissipation and Thermal Characteristics Maximum Power Dissipation @ T_A = + 85°C Thermal Resistance, Junction–to–Air	 P_D $R_{\theta JA}$	 650 100	 mW °C/W
Operating Junction Temperature	T_J	+150	°C
Operating Ambient Temperature Range HT33039A HT33039V	T_A	 –40 to +85 –40 to +125	°C
Storage Temperature Range	T_{stg}	–65 to +150	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

ELECTRICAL CHARACTERISTICS (V_{CC} = 6.25 V, R_T = 10 k, C_T = 22 nF, T_A = 25°C, unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
LOGIC INPUTS					
Input Threshold Voltage High State Low State Hysteresis	 V_{IH} V_{IL} V_H	 2.4 – 0.4	 2.1 1.4 0.7	 – 1.0 0.9	V
Input Current High State (V_{IH} = 5.0 V) ϕ_A ϕ_B, ϕ_C Low State (V_{IL} = 0 V) ϕ_A ϕ_B, ϕ_C	I_{IH} I_{IL}	 – 40 – – 190 –	 – 60 – 0.3 – 300 – 0.3	 – 80 – 5.0 – 380 – 5.0	µA
MONOSTABLE AND OUTPUT SECTIONS					
Output Voltage High State f_{out} (I_{source} = 5.0 mA) $\overline{\phi_A}$ (I_{source} = 2.0 mA) Low State f_{out} (I_{sink} = 10 mA) $\overline{\phi_A}$ (I_{sink} = 10 mA)	V_{OH} V_{OL}	 3.60 4.20 – –	 3.95 4.75 0.25 0.25	 4.20 – 0.50 0.50	V
Capacitor C_T Discharge Current	I_{dischg}	20	35	60	mA
Output Pulse Width (Pin 5)	t_{PW}	205	225	245	µs
POWER SUPPLY SECTION					
Power Supply Operating Voltage Range HT33039A (T_A = –40° to +85°C) HT33039V (T_A = –40° to +125°C)	V_{CC}	5.5	–	V_Z	V
Power Supply Current	I_{CC}	1.8	3.9	5.0	mA
Zener Voltage (I_Z = 10 mA)	V_Z	7.5	8.25	9.0	V
Zener Dynamic Impedance (ΔI_Z = 10 mA to 20 mA, f ≤ 1.0 kHz)	$\lvert Z_{ka} \rvert$	–	2.0	5.0	Ω

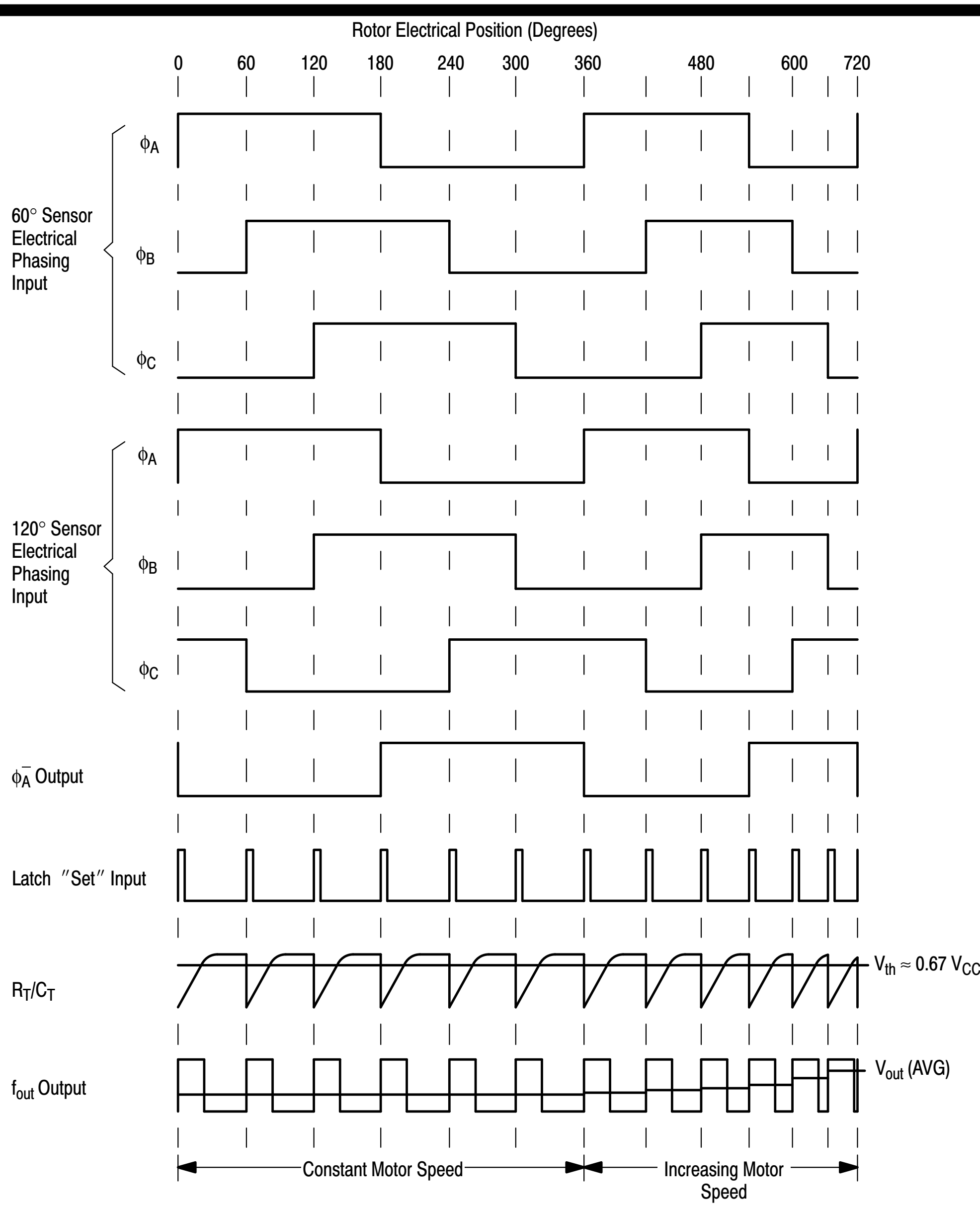


Figure 1. Typical Three Phase, Six Step Motor Application

OPERATING DESCRIPTION

The HT33039 provides an economical method of implementing closed–loop speed control of brushless DC motors by eliminating the need for a magnetic or optical tachometer. Shown in the timing diagram of Figure 1, the three inputs (Pins 1, 2, 3) monitor the brushless motor rotor position sensors. Each sensor signal transition is digitally detected, OR′ed at the Latch ′Set′ Input, and causes C_T to discharge. A corresponding output pulse is generated at f_{out} (Pin 5) of a defined amplitude, and programmable width determined by the values selected for R_T and C_T (Pin 6). The average voltage of the output pulse train increases with motor speed. When fed through a low pass filter or integrator, a DC voltage proportional to speed is generated. Figure 2 shows the proper connections for a typical closed loop application using the MC33035 brushless motor controller. Constant speed operation down to 100 RPM is possible with economical three phase four pole motors.

The ϕ_A inverter output (Pin 4) is used in systems where the controller and motor sensor phasing conventions are not compatible. A method of converting from either convention to the other is shown in Figure 3. For a more detailed explanation of this subject, refer to the text above Figure 39 on the MC33035 data sheet.

The output pulse amplitude V_{OH} is constant with temperature and controlled by the supply voltage on V_{CC} (Pin 8). Operation down to 5.5 V is guaranteed over temperature. For systems without a regulated power supply, an internal 8.25 V shunt regulator is provided.

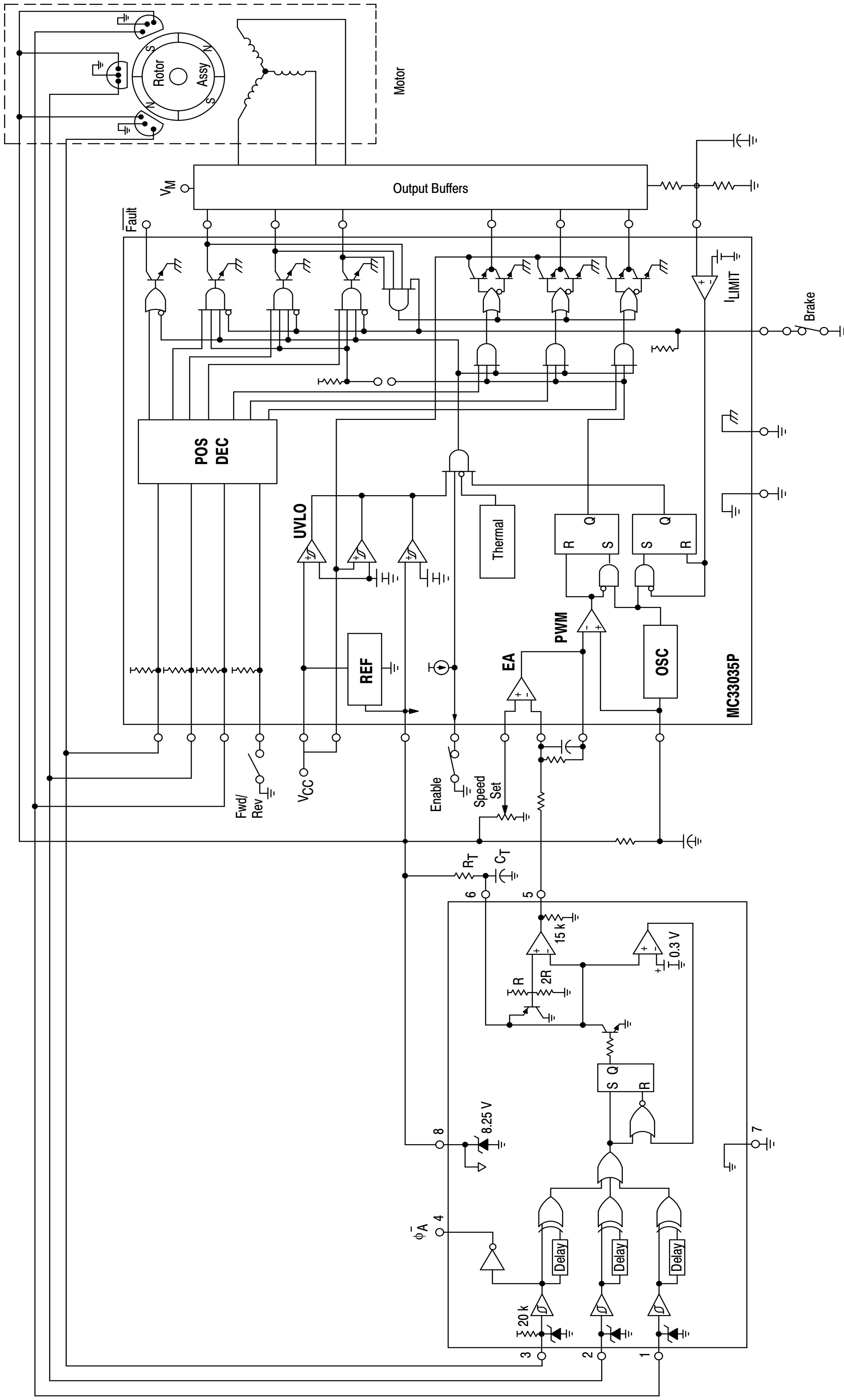


Figure 2. Typical Closed Loop Speed Control Application

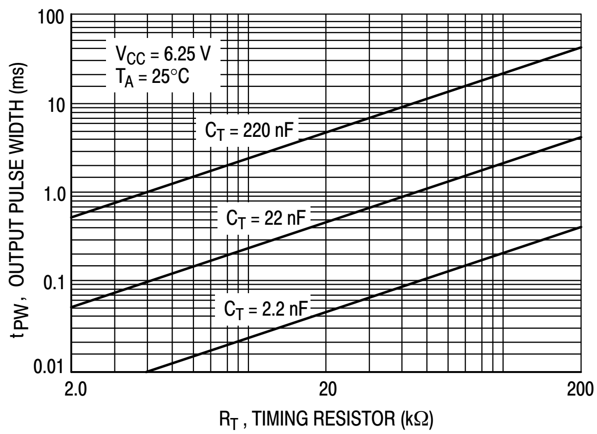


Figure 3. f_{out}, Pulse Width versus Timing Resistor

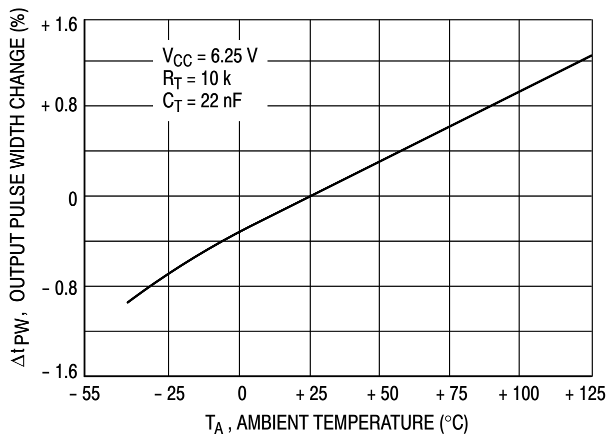


Figure 4. f_{out}, Pulse Width Change versus Temperature

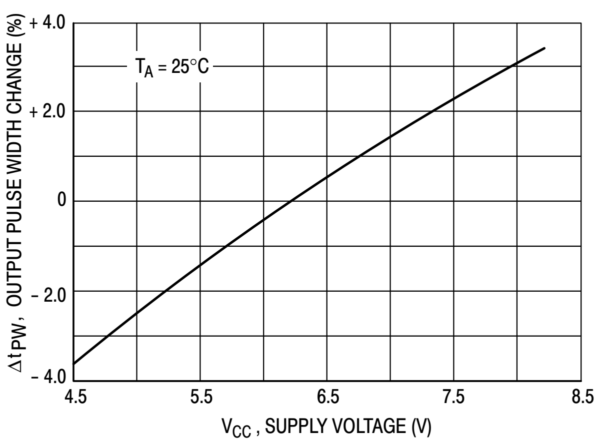


Figure 5. f_{out}, Pulse Width Change versus Supply Voltage

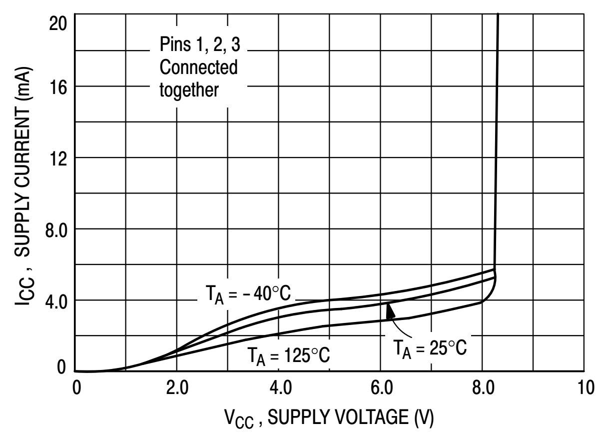


Figure 6. Supply Current versus Supply Voltage

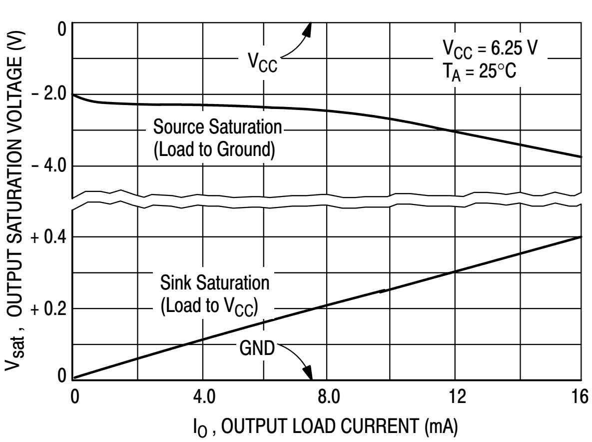


Figure 7. f_{out}, Saturation versus Load Current

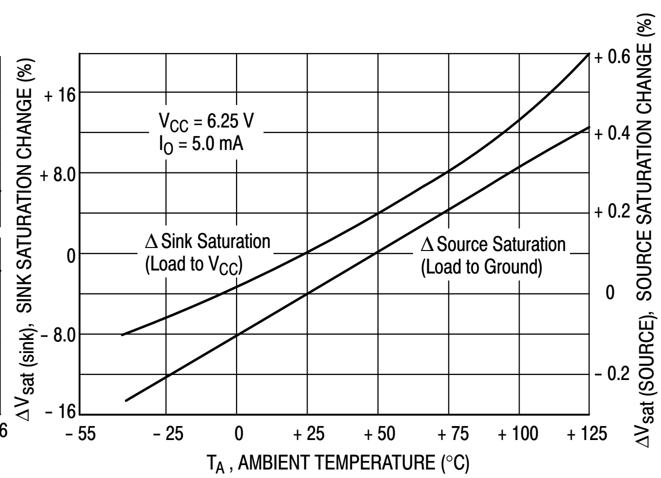
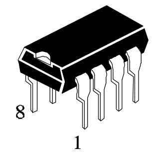
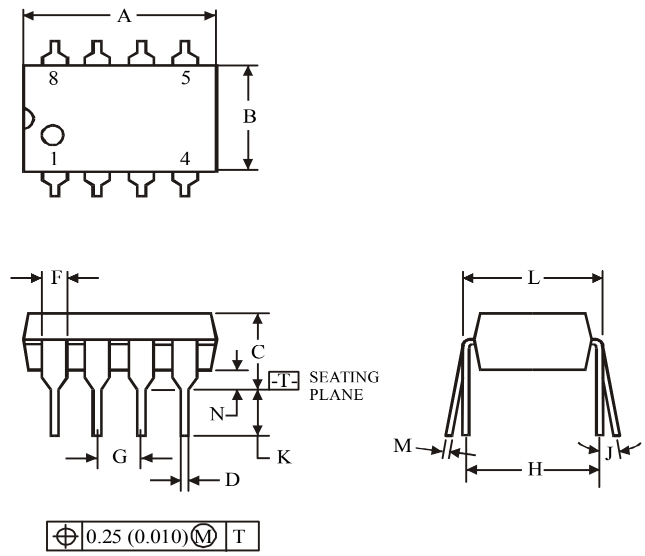


Figure 8. f_{out}, Saturation Change versus Temperature

(DIP8)



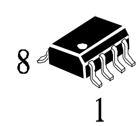


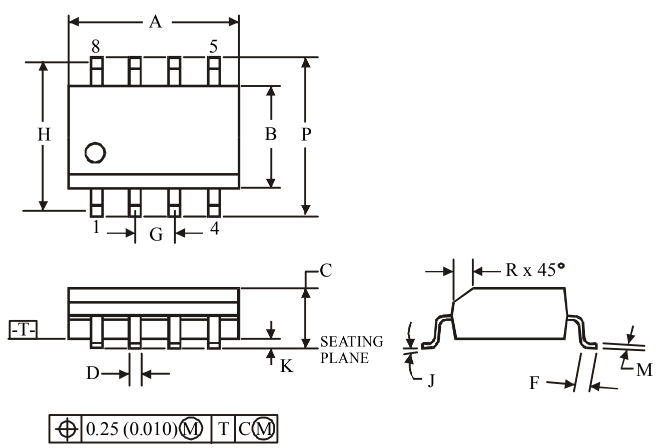
	Dimension, mm	
Symbol	**MIN**	**MAX**
A	8.51	10.16
B	6.1	7.11
C		5.33
D	0.36	0.56
F	1.14	1.78
G	2.54	
H	7.62	
J	0°	10°
K	2.92	3.81
L	7.62	8.26
M	0.2	0.36
N	0.38	

NOTES:

1. Dimensions “A”, “B” do not include mold flash or protrusions.
   Maximum mold flash or protrusions 0.25 mm (0.010) per side.

(SOP8)





	Dimension, mm	
Symbol	**MIN**	**MAX**
A	4.8	5
B	3.8	4
C	1.35	1.75
D	0.33	0.51
F	0.4	1.27
G	1.27	
H	5.72	
J	0°	8°
K	0.1	0.25
M	0.19	0.25
P	5.8	6.2
R	0.25	0.5

NOTES:

1. Dimensions A and B do not include mold flash or protrusion.
2. Maximum mold flash or protrusion 0.15 mm (0.006) per side
   for A; for B ‑ 0.25 mm (0.010) per side.