

### DESCRIPTION

The ADM202 device consists of two line drivers, two line receivers, and a dual charge-pump circuit with ±15-kV ESD protection pin to pin (serial-port connection pins, including GND). The device meets the requirements of TIA/EIA-232-F and provides the electrical interface between an asynchronous communication controller and the serial-port connector. The charge pump and four small external capacitors allow operation from a single 5-V supply. The device operates at data signaling rates up to 120 kbit/s and a maximum of 30-V/µs driver output slew rate.



- ESD Protection for RS-232 Bus Pins
   ±15-kV Human-Body Model
- Meets or Exceeds the Requirements of TIA/EIA-232-F and ITU v.28 Standards
- Operates at 5-V VCC Supply
- · Operates Up To 120 kbit/s
- External Capacitors...4 x 0.1 μF
- Latch-Up Performance Exceeds 100 mA Per JESD 78, Class II

### **APPLICATIONS**

- Battery-Powered System
- Notebooks
- Hand-Held devices
- Portable computer



SOP-16

### **FUNCTION TABLE**

### **Each Driver**

INPUT DIN	OUTPUT DOUT
L	Н
Н	L

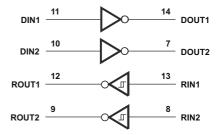
H = high level, L = low level

### **Each Receiver**

INPUT RIN	OUTPUT ROUT
L	Н
Н	L
Open	Н

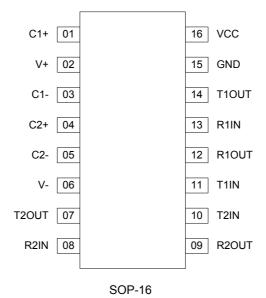
H = high level, L = low level, Open = input disconnected or connected driver off

### Logic Diagram (Positive Logic)





### **PIN CONFIGURATION**



### **PIN DESCRIPTION**

Pin No.	Pin Name	Pin Description
1	C1+	Terminal for Positive Charge-Pump C1 Capacitor
2	V+	Positive Voltage Generated by the Charge-Pump
3	C1-	Terminal for Negative Charge-Pump C1 Capacitor
4	C2+	Terminal for Positive Charge-Pump C2 Capacitor
5	C2-	Terminal for Negative Charge-Pump C2 Capacitor
6	V-	Negative Voltage Generated by the Charge-Pump
7	T2OUT	RS-232 Driver Output (Levels RS-232)
8	R2IN	RS-232 Receiver Input (Levels RS-232)
9	R2OUT	RS-232 Receiver Output (Levels TTL/CMOS)
10	T2IN	RS-232 Driver Input (Levels TTL/CMOS)
11	T1IN	RS-232 Driver Input (Levels TTL/CMOS)
12	R10UT	RS-232 Receiver Output (Levels TTL/CMOS)
13	R1IN	RS-232 Receiver Input (Levels RS-232)
14	T1OUT	RS-232 Driver Output (Levels RS-232)
15	GND	Ground
16	VCC	Supply Voltage Input



### **SPECIFICATIONS**

### **Absolute Maximum Ratings**

PARAMETER	SYMBOL	MIN.	MAX.	UNIT
Supply Voltage	V <sub>CC</sub>	-0.3	6.0	V
Transmitter High Output Voltage	V <sub>+</sub>	V <sub>CC</sub> -0.3	14	V
Transmitter Low Output Voltage	V.	-0.3	-14	V
Transmitter Input Voltage	$V_{TIN}$	-0.3	V <sub>+</sub> +0.3	V
Receiver Input Voltage	$V_{RIN}$	-30	30	V
Voltage Applied to Transmitter Output	V <sub>TOUT</sub>	V <sub>-</sub> -0.3	V <sub>+</sub> +0.3	V
Voltage Applied to Receiver Output	$V_{ROUT}$	-0.3	V <sub>CC</sub> +0.3	٧
Storage Temperature Range	T <sub>STG</sub>	-65	150	°C

**ESD** protection

PIN	TEST CONDITIONS	TYP	UNIT
D <sub>OUT</sub> , R <sub>IN</sub>	Human-Body Model	±15	kV

**Recommended Operating Conditions** over operating free-air temperature range (unless otherwise noted<sup>(1)</sup>)

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
	Supply voltage	4.5	5	5.5	V
V <sub>IH</sub>	Driver high-level input voltage (D <sub>IN</sub> )	2			V
V <sub>IL</sub>	Driver low-level input voltage (D <sub>IN</sub> )			0.8	V
V	Driver input voltage (D <sub>IN</sub> )	0		5.5	1/
VI	Receiver input voltage	- 30		30	V

<sup>(1)</sup> Test conditions are C1 - C4 =  $0.1\mu F$  at  $V_{CC}$  = 5V  $\pm 0.5 V$ .

### **Thermal Information**

SYMBOL	THERMAL METRIC	TYP	UNIT
R <sub>0 JA</sub>	Junction-to-ambient thermal resistance	84.6	°C/W
R <sub>0</sub> JC(top)	Junction-to-case (top) thermal resistance	43.5	°C/W
R <sub>0 JB</sub>	Junction-to-board thermal resistance	43.2	°C/W
Ψ ЈТ	Junction-to-top characterization parameter	10.4	°C/W
ψ ЈВ	Junction-to-board characterization parameter	42.8	°C/W

### **Electrical Characteristics**

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
Icc	Supply current	No load, V <sub>CC</sub> = 5 V		8	15	mA

<sup>(1)</sup> All typical values are at  $V_{CC} = 5 \text{ V}$ , and  $T_A = 25^{\circ}\text{C}$ .



### **Driver Section**

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>OH</sub>	High-level output voltage	$D_{OUT}$ at $R_L = 3k \Omega$ to GND, $D_{IN} = GND$	5	9		V
V <sub>OL</sub>	Low-level output voltage	$D_{OUT}$ at $R_L = 3k \Omega$ to GND, $D_{IN} = V_{CC}$	- 5	- 9		V
I <sub>IH</sub>	High-level input current	$V_I = V_{CC}$		0	200	μΑ
I <sub>IL</sub>	Low-level input current	V <sub>I</sub> at 0V		0	- 200	μΑ
I <sub>OS</sub> <sup>(1)</sup>	Short-circuit output current	V <sub>CC</sub> = 5.5V, V <sub>O</sub> = 0V		±10	±60	mA
r <sub>O</sub>	Output resistance	$V_{CC}$ , V+, and V - = 0V, $V_{O}$ = ±2V	300			Ω

<sup>(1)</sup> Short-circuit durations should be controlled to prevent exceeding the device absolute power-dissipation ratings, and not more than one output should be shorted at a time.

### **Receiver Section**

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>OH</sub>	High-level output voltage	I <sub>OH</sub> = -1mA	3.5	V <sub>CC</sub> - 0.4		V
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 1.6mA			0.4	V
V <sub>IT+</sub>	Positive-going input threshold voltage	V <sub>CC</sub> = 5V, T <sub>A</sub> = 25°C		1.7	2.4	V
V <sub>IT</sub> -	Negative-going input threshold voltage	V <sub>CC</sub> = 5V, T <sub>A</sub> = 25°C	0.8	1.2		V
V <sub>hys</sub>	Input hysteresis (V <sub>IT+</sub> - V <sub>IT-</sub> )		0.2	0.5	1	V
r <sub>i</sub>	Input resistance	V <sub>I</sub> = ±3V to ±25V	3	5	7	kΩ

# SWITCHING CHARACTERISTICS Driver Section

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Maximum data rate	C <sub>L</sub> = 50pF to 1000pF, R <sub>L</sub> = 3k $\Omega$ to 7k $\Omega$ one D <sub>OUT</sub> switching	120			kbit/s
t <sub>PLH(D)</sub>	Propagation delay time, low- to high-level output	$C_L$ = 2500pF, $R_L$ = 3k $\Omega$ , all drivers loaded		2		μs
t <sub>PHL(D)</sub>	Propagation delay time, high- to low-level output	$C_L$ = 2500pF, $R_L$ = 3k $\Omega$ , all drivers loaded		2		μs
t <sub>sk(p)</sub>	Pulse skew <sup>(1)</sup>	$C_L$ = 150 to 2500pF, $R_L$ = 3k $\Omega$ to 7 k $\Omega$		300		ns
SR(tr)	Slew rate, transition region	$C_L$ = 50 to 1000pF, $R_L$ = 3k $\Omega$ to 7 k $\Omega$ , $V_{CC}$ = 5V	3	6	30	V/µs

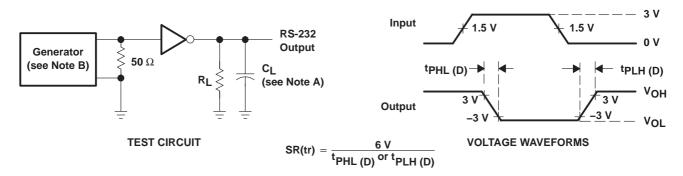
<sup>(1)</sup> Pulse skew is defined as  $|t_{PLH} - t_{PHL}|$  of each channel of the same device.

### **Receiver Section**

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>PLH(R)</sub>	Propagation delay time, low- to high-level output	C <sub>L</sub> = 150pF		0.5	10	μs
t <sub>PHL(R)</sub>	Propagation delay time, high- to low-level output	C <sub>L</sub> = 150pF		0.5	10	μs
t <sub>sk(p)</sub>	Pulse skew <sup>(1)</sup>	C <sub>L</sub> = 150pF		300		ns

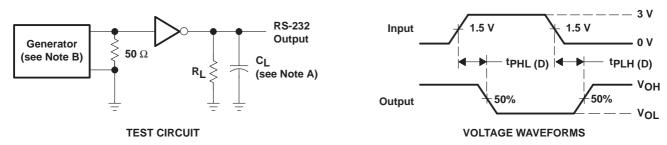
<sup>(1)</sup> Pulse skew is defined as  $|t_{PLH} - t_{PHL}|$  of each channel of the same device.

### PARAMETER MEASUREMENT INFORMATION



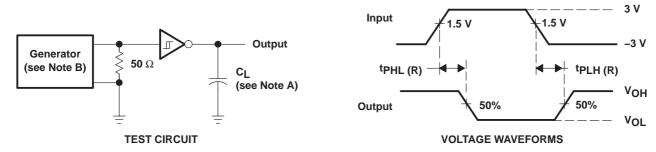
- NOTES: A. C<sub>L</sub> includes probe and jig capacitance.
  - B. The pulse generator has the following characteristics: PRR = 120 kbit/s,  $Z_O = 50 \Omega$ , 50% duty cycle,  $t_\Gamma \le 10$  ns.  $t_f \le 10$  ns.

Figure 1. Driver Slew Rate



- NOTES: A. C<sub>L</sub> includes probe and jig capacitance.
  - B. The pulse generator has the following characteristics: PRR = 120 kbit/s,  $Z_O = 50 \Omega$ , 50% duty cycle,  $t_f \le 10$  ns.

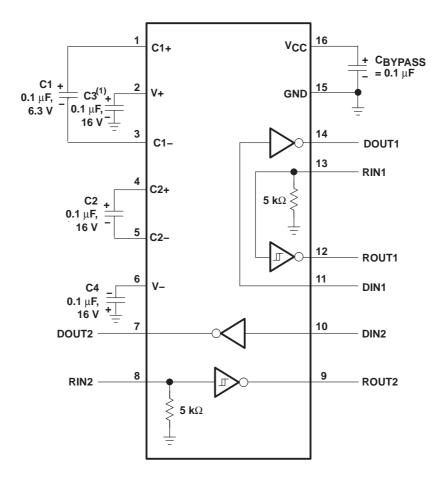
Figure 2. Driver Pulse Skew



- NOTES: A.  $C_L$  includes probe and jig capacitance.
  - B. The pulse generator has the following characteristics:  $Z_O = 50 \ \Omega$ , 50% duty cycle,  $t_\Gamma \le 10 \ ns$ .

Figure 3. Receiver Propagation Delay Times

### **APPLICATION INFORMATION**



(1) C3 can be connected to V<sub>CC</sub> or GND.

NOTES: A. Resistor values shown are nominal.

B. Nonpolarized ceramic capacitors are acceptable. If polarized tantalum or electrolytic capacitors are used, they should be connected as shown.

Figure 4. Typical Operating Circuit and Capacitor Values

### APPLICATION INFORMATION

### **Capacitor Selection**

The capacitor type used for C1 through C4 is not critical for proper operation. The ADM202 requires 0.1µF capacitors. Capacitors up to 10µF can be used without harm. Ceramic dielectrics are suggested for the 0.1µF capacitors. When using the minimum recommended capacitor values, make sure the capacitance value does not degrade excessively as the operating temperature varies. If in doubt, use capacitors with a larger (for example, 2x) nominal value. The capacitors' effective series resistance (ESR), which usually rises at low temperatures, influences the amount of ripple on V+ and V - .

Use larger capacitors (up to  $10\mu F$ ) to reduce the output impedance at V+ and V - .

Bypass V<sub>CC</sub> to ground with at least 0.1µF. In applications sensitive to power-supply noise generated by the charge pumps, decouple V<sub>CC</sub> to ground with a capacitor the same size as (or larger than) the charge-pump capacitors (C1 to C4).

### **ESD Protection**

ADM202 devices have standard ESD protection structures incorporated on all pins to protect against electrostatic discharges encountered during assembly and handling. In addition, the RS-232 bus pins (driver outputs and receiver inputs) of these devices have an extra level of ESD protection. Advanced ESD structures were designed to successfully protect these bus pins against ESD discharge of ±15kV when powered down.

### **ESD Test Conditions**

Stringent ESD testing is performed by TI based on various conditions and procedures. Please contact TI for a reliability report that documents test setup, methodology, and results.

### **Human-Body Model (HBM)**

The HBM of ESD testing is shown in Figure 5, Figure 6 shows the current waveform that is generated during a discharge into a low impedance. The model consists of a 100-pF capacitor, charged to the ESD voltage of concern, and subsequently discharged into the device under test (DUT) through a 1.5-k  $\Omega$  resistor.

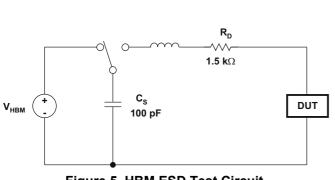


Figure 5. HBM ESD Test Circuit

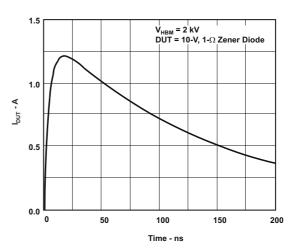


Figure 6. Typical HBM Current Waveform

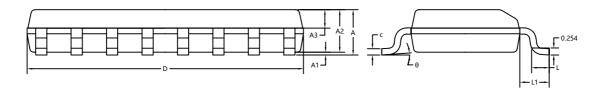
### Machine Model (MM)

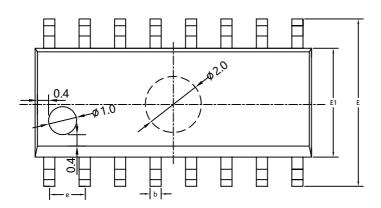
The MM ESD test applies to all pins using a 200-pF capacitor with no discharge resistance. The purpose of the MM test is to simulate possible ESD conditions that can occur during the handling and assembly processes of manufacturing. In this case, ESD protection is required for all pins, not just RS-232 pins. However, after PC board assembly, the MM test no longer is as pertinent to the RS-232 pins.



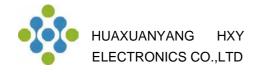
### **PACKAGE OUTLINE DIMENSIONS**

SOP-16





SYMBOL	MILLIMETER		
	MIN	NOM	MAX
А	1.50	1.60	1.70
A1	0.10	0.15	0.25
A2	1.40	1.45	1.50
A3	0.60	0.65	0.70
b	0.30	0.40	0.50
С	0.15	0.20	0.25
D	9.80	9.90	10.00
E	5.80	6.00	6.20
E1	3.85	3.90	3.95
e	1.27BSC		
L	0.50	0.60	0.70
L1	1.05BSC		
θ	0°	4°	8°



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