Interlock Switches

HE1G Basic Grip Enabling Switch

Key features:

- 3 position functionality (Off On Off) as required for manual robotic control
- Ideally suited for use as an enabling (aka "deadman") switch for robotic cells
- Provides a high level of safety based on human behavioral studies that determine personnel may squeeze OR let go when presented with a panic situation
- Contacts will not re-close when released from Off \rightarrow On (3 \rightarrow 1) (per IEC60204-1; 9.2.5.8)
- Optional E-Stop switch built in
- Connection for conduit and cable strain relief built in
- IP66 waterproof sealing
- Meets ANSI RIA 15.06 robotics standards
- Optional momentary pushbutton or E-Stop built in















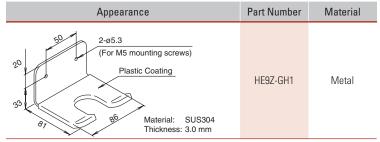
Part Numbers

Contact Configuration			Rubber Boot	Part No.	
3-position Switch	Monitor Switch	Pushbutton	Hubber Doot	r art ivo.	
	With (1NC)		Silicon Rubber / yellow	HE1G-21SM	
2 contacts		_	NBR/PVC Polyblend / gray	HE1G-21SM-1N	
		Momentary Pushbutton (1NO) (1NO: AB6M-M1PB)	Silicon Rubber / yellow	HE1G-21SMB	
			NBR/PVC Polyblend / gray	HE1G-21SMB-1N	
	Without	Emergency Stop Switch (2NC)	Silicon Rubber / yellow	HE1G-20ME	
		(2NC: HA1E-V2S2R)	NBR/PVC Polyblend / gray	HE1G-20ME-1N	
		Momentary Pushbutton (2NO)	Silicon Rubber / yellow	HE1G-20MB	
		(2NO: AB6M-M2PB)	NBR/PVC Polyblend / gray	HE1G-20MB-1N	

Accessories Replacement Rubber Cover

Appearance	Part Number	Material	Color
	HE9Z-GBK1	Silicon Rubber	Yellow
	HE9Z-GBK1-1N	NBR/PVC	Gray

Mounting Plate (secures grip switch)



Specifications

Conforming to Standards	UL508 (UL listed), CSA C22.2, No. 14 (c-UL listed), IEC/EN 60947-5-1 (TÜV/BG approval), GS-ET-22 (TÜV/BG approval)		
Applicable Standards	ISO 12100-1, -2, EN12100-1, -2, IEC 60204-1 / EN 60204-1, ISO11161 / prEN11161, ISO 10218 / EN 775, ANSI/RIA R15.06, ANSI B11.19		
Operating Temperature	−25 to +60°C (no freezing)		
Operating Humidity	45 to 85% RH maximum (no condensation)		
Storage Temperature	−40 to +80°C (no freezing)		
Pollution Degree	3		
Contact Resistance	100mΩ maximum		
Insulation Resistance	Between live & dead metal parts: $100M\Omega$ maximum Between positive & negative live parts: $100M\Omega$ minimum		



Specifications con't

Impulse Withstand Voltage		2.5kV		
Operating Frequency		1200 operations/hour		
Mechanical Life		Position $1 \rightarrow 2 \rightarrow 1$: 1,000,000 operations minimum		
Mechanical Lii	e	Position $1 \rightarrow 2 \rightarrow 3 \rightarrow 1$: 100,000 operations minimum		
Electrical Life		100,000 minimum at rated load		
Shock	Operating Extremes	150m/s ² (15 G)		
Resistance	Damage Limits	1000m/s ² (100 G)		
Vibration	Operating Extremes	5 to 55Hz, amplitude 0.5mm minimum		
Resistance	Damage Limits	16.7Hz, amplitude 1.5mm minimum		
Recommend W	/ire Size	0.14 to 1.5mm ² (24AWG - 16AWG)		
Recommend Ca	able Size	ø7 to 13mm		
Conduit Size		M20		
Terminal Pullin	g Strength	20N minimum		
Terminal Screw Torque		0.5 to 0.6Nm		
Danuar of Dunt	aatian	HE1G-21SM: IP66, HE1G-20MB: IP65		
Degree of Protection		HE1G-20ME: IP65, HE1G-21SMB: IP65		
Conditional Short Circuit Current		50A (250V)		
Recommended Short Circuit Protection		250V/10A fast blow fuse (IEC 60127-1)		
Weight (approx.)		HE1G-21SM: 210g HE1G-20ME: 250g HE1G-20MB/HE1G-21SMB: 220g		

Enabling Switches

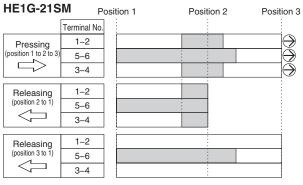
Contact Ratings

Rated Insulation Voltage (Ui)					250V			
Thermal Current (Ith)					3A			
Rated Operating V	oltage (l	Ue)			30V	125V	250V	
			AC	Resistive Load (AC-12) –	3A	1.5A	
	3 Position Switch	osition Switch	AU	Inductive Load (AC-15	i) –	1.5A	0.75A	
	(Term	inal No.1-2, 3-4)	DO	Resistive Load (DC-12) 2A	0.4A	0.2A	
			DC	Inductive Load (DC-13	1A	0.22A	0.1A	
			AC	Resistive Load (AC-12) –	2A	1A	
Rated Operating	Monitor Switch (Terminal No. 5-6 of HE1G-21SM)			Inductive Load (AC-15	i) –	1A	0.5A	
Current (le)		DC	Resistive Load (DC-12) 2A	0.4A	0.2A		
	·		Inductive Load (DC-13	1A	0.22A	0.1A		
	Emergency Stop Pushbutton (Terminal No. 5-6, 7-8		AC	Resistive Load (AC-12) –	_	_	
				Inductive Load (AC-15	i) –	-	0.5A	
			DC	Resistive Load (DC-12) –	-	_	
	OT	of HE1G-20ME)		Inductive Load (DC-13	-	-	0.1A	
Contact Configuration		3	3 Position Switch			2 Contacts		
		Monitor Switch		0	0 or 1 Contact			
		Emergency Stop Pushbutton		0 0	0 or 2 Contacts			
		Momentary Pushbutton		0 t	0 to 2 contacts			



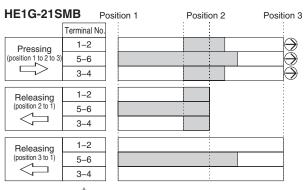
The minimum load (reference) = AC/DC3V • 5mA (for reference only.

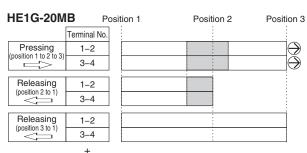
Operating Characteristics Contact Movement



HE1G-20N	IE Po	sition 1	Position	2 Pos	ition 3
	Terminal No.				
Pressing	1–2				\supset
(position 1 to 2 to 3)	3–4				\supseteq
Releasing	1–2				
(position 2 to 1)	3–4				
Releasing	1-2				j
(position 3 to 1)	3-4				

Emergency Stop Switch: 2NC contact (terminal no. 5-6, 7-8)





Momentary Pushbutton: 2NO contact (terminal no. 5-6, 7-8)

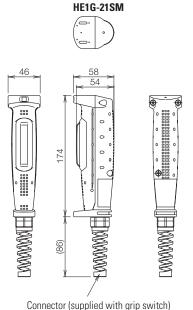
+ Momentary Pushbutton: 1NO contact (terminal no. 7-8)

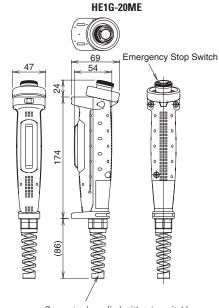
: contact ON (closed) : contact OFF (open)

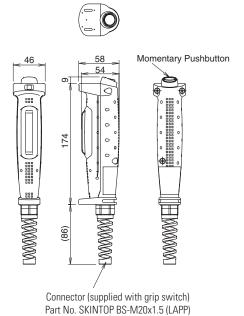
Notes:

- 1. 3-position switches operate with direct opening action Θ when shifting from position 2 to position 3.
- 2. For the output of the enabling device, use terminals 1-2 and 3-4.
- 3. The above operation characteristics show when the center of the button is pressed. Pressing the edge of a button turns on one contact earlier than the other contact, causing a delay in operation.

Dimensions (mm)







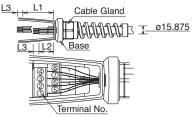
HE1G-20MB/21SMB

Connector (supplied with grip switch)
Part No. SKINTOP BS-M20x1.5 (LAPP)
Connector (supplied with grip switch)
Part No. SKINTOP BS-M20x1.5 (LAPP)

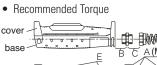
Wiring Precautions HE1G

• Wire Stripping Information

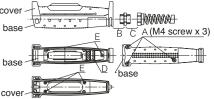
Wire Length	Terminal Number 1-4	Terminal Number 5-8	
L1, L2 (mm)	L1=40mm	L2=27mm	
L3 (mm)	L3=6	Gmm	



• Applicable Wire Size:0.14 to 1.5mm² (24 - 16AWG, one wire per terminal)



Enabling Switches



	See Drawing Above	Recommended Torque
Rubber Boot & Base	А	1.2±0.1Nm
Connector & Grip Switch	В	4.0±0.3Nm
Connector	С	4.0±0.3Nm
Terminal Screw	D	0.5±0.6Nm
Do Not Remove	Е	

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