## BTM7745G

High Current H-Bridge
Trilith IC 3G

Automotive Power

## Table of Contents

Table of Contents ..... 2
1 Overview ..... 3
2 Block Diagram ..... 4
3 Terms ..... 4
4 Pin Configuration ..... 5
4.1 Pin Assignment ..... 5
4.2 Pin Definitions and Functions ..... 5
5 General Product Characteristics ..... 6
5.1 Absolute Maximum Ratings ..... 6
5.2 Functional Range ..... 7
5.3 Thermal Resistance ..... 8
6 Block Description and Characteristics ..... 9
6.1 Supply Characteristics ..... 9
6.2 Power Stages ..... 10
6.2.1 Power Stages - Static Characteristics ..... 11
6.2.2 Switching Times ..... 12
6.2.3 Power Stages - Dynamic Characteristics ..... 13
6.3 Protection Functions ..... 13
6.3.1 Overvoltage Lock Out ..... 13
6.3.2 Undervoltage Shut Down ..... 14
6.3.3 Overtemperature Protection ..... 14
6.3.4 Current Limitation ..... 14
6.3.5 Short Circuit Protection ..... 16
6.3.6 Electrical Characteristics - Protection Functions ..... 16
6.4 Control and Diagnostics ..... 17
6.4.1 Input Circuit ..... 17
6.4.2 Dead Time Generation ..... 17
6.4.3 Status Flag Diagnosis ..... 17
6.4.4 Truth Table ..... 18
6.4.5 Electrical Characteristics - Control and Diagnostics ..... 19
$7 \quad$ Application Information ..... 20
7.1 Application and Layout Considerations ..... 20
8 Package Outlines ..... 22
9 Revision History ..... 23

High Current H-Bridge
BTM7745G

RoHS

## 1 Overview

## Features

- Integrated high current H-Bridge
- Path resistance of max. $500 \mathrm{~m} \Omega$ @ $150^{\circ} \mathrm{C}\left(\right.$ typ. $\left.250 \mathrm{~m} \Omega @ 25^{\circ} \mathrm{C}\right)$
- Low quiescent current of typ. $5 \mu \mathrm{~A} @ 25^{\circ} \mathrm{C}$
- Current limitation level of 12 A typ. ( 6 A min.)
- Driver circuit with logic inputs
- Status flag diagnosis
- Overtemperature shut down with latch behaviour
- Overvoltage lock out
- Undervoltage shut down


PG-DSO-36-29

- Switch-mode current limitation for reduced power dissipation in overcurrent situation
- Integrated dead time generation
- Operation up to 28 V
- Green Product (RoHS compliant)
- AEC Qualified


## Description

The BTM7745G is a fully integrated high current H-bridge for motor drive applications. It contains two p-channel highside MOSFETs and two n-channel lowside MOSFETs with an integrated driver IC in one package. Due to the p-channel highside switches the need for a charge pump is eliminated thus minimizing EMI. Interfacing to a microcontroller is made easy by the integrated driver IC which features logic level inputs, diagnosis,dead time generation and protection against overtemperature, overvoltage, undervoltage, overcurrent and short circuit.
The BTM7745G provides an optimized solution for protected high current motor drives with very low board space consumption.

| Type | Package | Marking |
| :--- | :--- | :--- |
| BTM7745G | PG-DSO-36-29 | BTM7745G |

## 2 Block Diagram



Figure 1 Block Diagram

## 3 <br> Terms

following figure shows the terms used in this data sheet.


Figure 2 Terms

## 4 Pin Configuration

### 4.1 Pin Assignment



Figure 3 Pin Configuration BTM7745G

### 4.2 Pin Definitions and Functions

Pins written in bold type need power wiring.

| Pin | Symbol | Function |
| :--- | :--- | :--- |
| $\mathbf{1 . . 4 , 3 3 . . 3 6}$ | OUT1 | Output of first half bridge |
| $\mathbf{5 . . 8 , 2 3 . 2 6}$ | GND | Ground |
| 9 | IN1 | Input of first half bridge |
| 10 | IN2 | Input of second half bridge |
| $\mathbf{1 1 . . 1 4 , 2 9 . . 3 2}$ | VS | Supply, all pins to be connected and shorted externally |
| $\mathbf{1 5 . . 2 2}$ | OUT2 | Output of second half bridge |
| 27 | INH | Inhibit pin, to set device in sleep/stand-by mode |
| 28 | ST | Status signal, open drain output |

High Current H-Bridge
BTM7745G

General Product Characteristics

## 5 General Product Characteristics

### 5.1 Absolute Maximum Ratings

## Absolute Maximum Ratings ${ }^{1)}$

$T_{\mathrm{j}}=-40^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$; all voltages with respect to ground (unless otherwise specified)

| Pos. | Parameter | Symbol | Limit Values |  | Unit | Conditions |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  | Min. | Max. |  |  |
| 5.1 .1 | Supply voltage | $V_{\mathrm{S}}$ | -0.3 | 45 | V | - |
| 5.1 .2 | Logic Input Voltage | $V_{\mathrm{IN} 1}, V_{\mathrm{IN} 2,}$ <br> $V_{\mathrm{INH}}$ | -0.3 | 5.5 | V | - |
| 5.1 .3 | HS/LS continuous drain current | $I_{\mathrm{D}(\mathrm{HS})}$ <br> $I_{\mathrm{D}(\mathrm{LS})}$ | -3.2 | 3.2 | A | $T_{\mathrm{C}}<85^{\circ} \mathrm{C}$ <br> switch active |
| 5.1 .4 | Voltage at ST pin | $V_{\mathrm{ST}}$ | -0.3 | 45 | V | - |
| 5.1 .5 | ST pin continuous current | $I_{\mathrm{ST}}$ | 0 | 2 | mA | - |
| 5.1 .6 | ST pin peak current | $I_{\mathrm{ST}}$ | 0 | 4 | mA | $t_{\text {peak }}<10 \mu \mathrm{~s}$ |

Thermal Maximum Ratings

| 5.1 .7 | Junction temperature | $T_{\mathrm{j}}$ | -40 | 150 | ${ }^{\circ} \mathrm{C}$ | - |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 5.1 .8 | Storage temperature | $T_{\text {stg }}$ | -55 | 150 | ${ }^{\circ} \mathrm{C}$ | - |

ESD Susceptibility

| 5.1 .9 | ESD susceptibility | $V_{\text {ESD }}$ |  |  | kV | $\mathrm{HBM}^{2)}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | IN1, IN2, ST, INH |  | -2 | 2 |  |  |
|  | OUT1, OUT2, GND, VS |  | -4 | 4 |  |  |

1) Not subject to production test, specified by design.
2) HBM according to EIA/JESD 22-A $114 \mathrm{~B}(1.5 \mathrm{k} \Omega, 100 \mathrm{pF})$

Note: Stresses above the ones listed here may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: Integrated protection functions are designed to prevent IC destruction under fault conditions described in the data sheet. Fault conditions are considered as "outside" normal operating range. Protection functions are not designed for continuous repetitive operation.

High Current H-Bridge BTM7745G

## Maximum Single Pulse Current



Figure 4 BTM7745G Maximum Single Pulse Current ( $\left.T_{\mathrm{C}}=T_{\mathrm{j}(0)}<85^{\circ} \mathrm{C}\right)$
This diagram shows the maximum single pulse current that can be driven for a given pulse time $t_{\text {pulse }}$. The maximum reachable current may be smaller depending on the current limitation level. Pulse time may be limited due to thermal protection of the device.

### 5.2 Functional Range

| Pos. | Parameter | Symbol | Limit Values |  | Unit | Conditions |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  | Min. | Max. |  |  |
| 5.2 .1 | Supply Voltage Range for <br> Normal Operation | $V_{\text {S(nor) }}$ | 8 | 18 | V | VS pins shorted |
| 5.2 .2 | Extended Supply Voltage Range <br> for Operation | $V_{\text {S(ext) }}$ | 5.5 | 28 | V | VS pins shorted; <br> Parameter <br> deviations possible; <br> $1)$ |
| 5.2 .3 | Junction Temperature | $T_{\mathrm{j}}$ | -40 | 150 | ${ }^{\circ} \mathrm{C}$ | - |

1) Overtemperature protection available up to supply voltage $V_{S}=18 \mathrm{~V}$.

Note: Within the functional range the IC operates as described in the circuit description. The electrical characteristics are specified within the conditions given in the related electrical characteristics table.

High Current H-Bridge BTM7745G

### 5.3 Thermal Resistance

Note: This thermal data was generated in accordance with JEDEC JESD51 standards. For more information, go to www.jedec.org.

| Pos. | Parameter | Symbol | Limit Values |  |  | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. |  |  |
| 5.3 .1 | Thermal Resistance Junction to Soldering Point, Low Side Switch $R_{\mathrm{th} \mathrm{SP}(\mathrm{LS})}=\Delta T_{\mathrm{j}(\mathrm{LS})} / P_{\mathrm{v}(\mathrm{LS})}$ | $R_{\text {thjSP(LS) }}$ | - | - | 29 | K/W | 1) |
| 5.3.2 | Thermal Resistance Junction to Soldering Point, High Side Switch $R_{\mathrm{thjSP}(\mathrm{HS})}=\Delta T_{\mathrm{j}(\mathrm{HS})} / P_{\mathrm{v}(\mathrm{HS})}$ | $R_{\text {thjSP(HS) }}$ | - | - | 29 | K/W | 1) |
| 5.3.3 | Thermal Resistance Junction to Soldering Point, both switches $\begin{aligned} & R_{\mathrm{thjSP}}=\max \left[\Delta T_{\mathrm{j}(\mathrm{HS})}, \Delta T_{\mathrm{j}(\mathrm{LS})}\right] / \\ & \left(P_{\mathrm{v}(\mathrm{HS})}+P_{\mathrm{v}(\mathrm{LS})}\right) \end{aligned}$ | $R_{\text {thiSP }}$ | - | - | 29 | K/W | 1) |
| 5.3.4 | Thermal Resistance Junction-Ambient | $R_{\text {thja }}$ | - | 46 | - | K/W | ${ }^{1)}$; ${ }^{\text {) }}$ |

1) Not subject to production test, specified by design.
2) Specified $R_{\text {thja }}$ value is according to Jedec JESD51-2, -7 at natural convection on FR4 2s2p board; The product (chip+package) was simulated on a $76.2 \times 114.3 \times 1.5 \mathrm{~mm}$ board with 2 inner copper layers ( $2 \times 70 \mu \mathrm{~m} \mathrm{Cu}, 2 \times 35 \mu \mathrm{~m} \mathrm{Cu}$ ).

## Transient thermal impedance $Z_{\text {thja }}$

Figure 5 is showing the typical transient thermal impedance of high side or low side switch of BTM7745G mounted according to JEDEC JESD51-7 at natural convection on FR4 2s2p board. The device (chip+package) was simulated on a $76.2 \times 114.3 \times 1.5 \mathrm{~mm}$ board with 2 inner copper layers ( $2 \times 70 \mu \mathrm{~m} \mathrm{Cu}, 2 \times 35 \mu \mathrm{~m} \mathrm{Cu}$ ). For the simulation each chip was separately powered with 1 W at an ambient temperature $T_{\mathrm{a}}$ of $85^{\circ} \mathrm{C}$.


Figure 5 Typical transient thermal impedance of BTM7745G on JESD51-7 2s2p board (1W each chip (separately heated), $T_{a}=85^{\circ} \mathrm{C}$, single pulse)

High Current H-Bridge
BTM7745G

## Block Description and Characteristics

## 6 Block Description and Characteristics

### 6.1 Supply Characteristics

$V_{\mathrm{S}}=8 \mathrm{~V}$ to $18 \mathrm{~V}, T_{\mathrm{j}}=-40^{\circ} \mathrm{C}$ to $+150{ }^{\circ} \mathrm{C}, I_{\mathrm{L}}=0 \mathrm{~A}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

| Pos. | Parameter | Symbol | Limit Values |  |  | Unit | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. |  |  |
| General |  |  |  |  |  |  |  |
| 6.1.1 | Supply Current | $I_{\text {S(on) }}$ | - | 5 | 9.5 | mA | $V_{\mathrm{INH}} \text { or } V_{\mathrm{IN} 1} \text { or } V_{\mathrm{IN} 2}=5 \mathrm{~V}$ <br> DC-mode normal operation (no fault condition) |
| 6.1 .2 | Quiescent Current | $I_{\text {S(off) }}$ | - | 5 | 15 | $\mu \mathrm{A}$ | $\begin{aligned} & V_{\mathrm{INH}}=V_{\mathrm{IN} 1}=V_{\mathrm{IN} 2}=0 \mathrm{~V} \\ & T_{\mathrm{j}}<85^{\circ} \mathrm{C} ;{ }^{1)} \end{aligned}$ |
|  |  |  | - | - | 30 | $\mu \mathrm{A}$ | $V_{\text {INH }}=V_{\text {IN } 1}=V_{\text {IN2 }}=0 \mathrm{~V}$ |

1) Not subject to production test, specified by design.


Figure 6 Typical Quiescent Current vs. Junction Temperature (typ. @ $V_{\mathrm{S}}=13.5 \mathrm{~V}$ )

### 6.2 Power Stages

The power stages of the BTM7745G consist of p-channel vertical DMOS transistors for the high side switches and n-channel vertical DMOS transistors for the low side switches. All protection and diagnostic functions are located in a separate control chip. Both switches, high side and low side, allow active freewheeling and thus minimize power dissipation in the forward operation of the integrated diodes.
The on state resistance $R_{\mathrm{ON}}$ is dependent on the supply voltage $V_{\mathrm{S}}$ as well as on the junction temperature $T_{\mathrm{j}}$. The typical on state resistance characteristics are shown in Figure 7.


## Low Side Switch



Figure $7 \quad$ Typical On State Resistance vs. Supply Voltage

High Current H-Bridge
BTM7745G

Block Description and Characteristics

### 6.2.1 Power Stages - Static Characteristics

$V_{\mathrm{S}}=8 \mathrm{~V}$ to $18 \mathrm{~V}, T_{\mathrm{j}}=-40^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

| Pos. | Parameter | Symbol | Limit Values |  | Unit | Test Conditions |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | Min. | Typ. | Max. |  |  |

High Side Switch - Static Characteristics

| 6.2.1 | On state high side resistance | $R_{\text {ON(HS) }}$ | - | $\begin{aligned} & 100 \\ & 140 \end{aligned}$ | $190$ | $\mathrm{m} \Omega$ | $\begin{aligned} & I_{\mathrm{OUT}}=1 \mathrm{~A} \\ & V_{\mathrm{S}}=13.5 \mathrm{~V} \\ & T_{\mathrm{j}}=25^{\circ} \mathrm{C} ;{ }^{1)} \\ & T_{\mathrm{j}}=150^{\circ} \mathrm{C} \\ & \hline \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 6.2 .2 | Leakage current high side | $I_{\text {L(LKHS) }}$ | - | - | $\begin{aligned} & 1 \\ & 5 \end{aligned}$ | $\mu \mathrm{A}$ | $\begin{aligned} & V_{\text {INH }}=V_{\text {IN } 1}=V_{\text {IN2 }}=0 \mathrm{~V} \\ & V_{\text {OUT }}=0 \mathrm{~V} \\ & T_{\mathrm{j}}<85^{\circ} \mathrm{C} ;{ }^{1)} \\ & T_{\mathrm{j}}=150^{\circ} \mathrm{C} \end{aligned}$ |
| 6.2.3 | Reverse diode forward-voltage high side ${ }^{2)}$ | $V_{\text {DS(HS) }}$ | $\left[\begin{array}{l} - \\ - \\ - \end{array}\right.$ | $\begin{aligned} & 0.9 \\ & 0.8 \\ & 0.6 \end{aligned}$ | $\left\lvert\, \begin{aligned} & - \\ & - \\ & 0.8 \end{aligned}\right.$ | V | $\begin{aligned} & I_{\text {OUT }}=-1 \mathrm{~A} \\ & T_{\mathrm{j}}=-40^{\circ} \mathrm{C} ;{ }^{1)} \\ & T_{\mathrm{j}}=25^{\circ} \mathrm{C} ;{ }^{1)} \\ & T_{\mathrm{j}}=150^{\circ} \mathrm{C} \\ & \hline \end{aligned}$ |

Low Side Switch - Static Characteristics

| 6.2.4 | On state low side resistance | $R_{\text {ON(LS) }}$ | - | $\begin{aligned} & 150 \\ & 250 \end{aligned}$ | $300$ | $\mathrm{m} \Omega$ | $\begin{aligned} & I_{\text {OUT }}=-1 \mathrm{~A} \\ & V_{\mathrm{S}}=13.5 \mathrm{~V} \\ & T_{\mathrm{j}}=25^{\circ} \mathrm{C} ;{ }^{1)} \\ & T_{\mathrm{j}}=150^{\circ} \mathrm{C} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 6.2.5 | Leakage current low side | $-I_{\text {L(LKLS) }}$ | - | - | $\begin{aligned} & 1 \\ & 3 \end{aligned}$ | $\mu \mathrm{A}$ | $\begin{aligned} & V_{\text {INH }}=V_{\text {IN } 1}=V_{\text {IN } 2}=0 \mathrm{~V} \\ & V_{\text {OUT }}=V_{\mathrm{S}} \\ & \left.T_{\mathrm{j}}<85^{\circ} \mathrm{C} ; 1\right) \\ & T_{\mathrm{j}}=150^{\circ} \mathrm{C} \end{aligned}$ |
| 6.2.6 | Reverse diode forward-voltage low side ${ }^{2)}$ | $V_{\text {SD(LS) }}$ | - | $\begin{aligned} & 0.9 \\ & 0.8 \\ & 0.6 \end{aligned}$ | $\left\lvert\, \begin{aligned} & - \\ & - \\ & 0.8 \end{aligned}\right.$ | V | $\begin{aligned} & I_{\text {OUT }}=1 \mathrm{~A} \\ & T_{\mathrm{j}}=-40^{\circ} \mathrm{C} ;{ }^{1)} \\ & T_{\mathrm{j}}=25^{\circ} \mathrm{C} ;{ }^{1)} \\ & T_{\mathrm{j}}=150^{\circ} \mathrm{C} \\ & \hline \end{aligned}$ |

1) Not subject to production test, specified by design.
2) Due to active freewheeling diode is conducting only until related switch is on.

### 6.2.2 Switching Times



Figure 8 Definition of switching times high side ( $\mathrm{R}_{\text {load }}$ to GND)


Figure 9 Definition of switching times low side ( $\mathrm{R}_{\text {load }}$ to VS)
Due to the timing differences for the rising and the falling edge there will be a slight difference between the length of the input pulse and the length of the output pulse. It can be calculated using the following formulas:

- $\Delta t_{\mathrm{HS}}=\left(t_{\mathrm{dr}(\mathrm{HS})}+0.2 t_{\mathrm{r}(\mathrm{HS})}\right)-\left(t_{\mathrm{df}(\mathrm{HS})}+0.8 t_{\mathrm{f}(\mathrm{HS})}\right)$
- $\Delta t_{\mathrm{LS}}=\left(t_{\mathrm{df}(\mathrm{LS})}+0.2 t_{\mathrm{f}(\mathrm{LS})}\right)-\left(t_{\mathrm{dr}(\mathrm{LS})}+0.8 t_{\mathrm{r}(\mathrm{LS})}\right)$.

High Current H-Bridge BTM7745G

### 6.2.3 Power Stages - Dynamic Characteristics

$V_{\mathrm{S}}=13.5 \mathrm{~V}, \boldsymbol{T}_{\mathrm{j}}=+150^{\circ} \mathrm{C}, \boldsymbol{R}_{\text {Load }}=12 \Omega, \mathrm{~V}_{\mathrm{INH}}=5 \mathrm{~V}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

| Pos. | Parameter | Symbol | Limit Values |  |  | Unit | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. |  |  |
| High Side Switch Dynamic Characteristics |  |  |  |  |  |  |  |
| 6.2.7 | Rise-time of HS | $t_{\mathrm{r}(\mathrm{HS})}$ | 5 | 15 | 25 | $\mu \mathrm{s}$ | - |
| 6.2.8 | Slew rate HS on | $\begin{aligned} & \Delta V_{\text {OUT }} / \\ & t_{\mathrm{r}(\mathrm{HS})} \end{aligned}$ | - | 0.4 | - | $\mathrm{V} / \mu \mathrm{s}$ | - |
| 6.2 .9 | Switch on delay time HS | $t_{\text {dr( }}^{\text {(HS })}$ | 50 | 95 | 140 | $\mu \mathrm{s}$ | - |
| 6.2 .10 | Fall-time of HS | $t_{f(H S)}$ | 5 | 15 | 25 | $\mu \mathrm{s}$ | - |
| 6.2.11 | Slew rate HS off | $\begin{aligned} & -\Delta V_{\mathrm{OUT}} / \\ & t_{\mathrm{f}(\mathrm{HS})} \\ & \hline \end{aligned}$ | - | 0.4 | - | $\mathrm{V} / \mu \mathrm{s}$ | - |
| 6.2.12 | Switch off delay time HS | $t_{\text {df( }}^{\text {(HS }}$ ) | 25 | 55 | 80 | $\mu \mathrm{s}$ | - |

## Low Side Switch Dynamic Characteristics

| 6.2 .13 | Rise-time of LS | $t_{\mathrm{r}(\mathrm{LS})}$ | 10 | 20 | 30 | $\mu \mathrm{~s}$ | - |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 6.2 .14 | Slew rate LS switch off | $\Delta V_{\mathrm{OUT}} /$ <br> $t_{\mathrm{r}(\mathrm{LS})}$ | - | 0.4 | - | $\mathrm{V} / \mu \mathrm{s}$ | - |
| 6.2 .15 | Switch off delay time LS | $t_{\mathrm{dr}(\mathrm{LS})}$ | 30 | 60 | 90 | $\mu \mathrm{~s}$ | - |
| 6.2 .16 | Fall-time of LS | $t_{\mathrm{f}(\mathrm{LS})}$ | 10 | 20 | 30 | $\mu \mathrm{~s}$ | - |
| 6.2 .17 | Slew rate LS switch on | $-\Delta V_{\mathrm{OUT}} /$ <br> $t_{\mathrm{f}(\mathrm{LS})}$ | - | 0.4 | - | $\mathrm{V} / \mu \mathrm{s}$ | - |
| 6.2 .18 | Switch on delay time LS | $t_{\mathrm{df}(\mathrm{LS})}$ | 40 | 80 | 120 | $\mu \mathrm{~s}$ | - |

### 6.3 Protection Functions

The device provides integrated protection functions. These are designed to prevent IC destruction under fault conditions described in the data sheet. Fault conditions are considered as "outside" normal operating range. Protection functions are not to be used for continuous or repetitive operation, with the exception of the current limitation (Chapter 6.3.4). Overvoltage, overtemperature and overcurrent are indicated by switching the open drain output ST to low. Although the slew rate is defined as above (Chapter 6.2.3), in case of overvoltage and overcurrent the device will have a higher slew rate of typically $11 \mathrm{~V} / \mu \mathrm{s}$.

In the following the protection functions are listed in order of their priority. Overvoltage lock out overrides all other error modes.

### 6.3.1 Overvoltage Lock Out

To assure a high immunity against overvoltages (e.g. load dump conditions) the device shuts both lowside MOSFETs off and turns both highside MOSFET on, if the supply voltage $V_{S}$ is exceeding the over voltage protection level $V_{\mathrm{OV}(\mathrm{OFF})}$. The IC operates in normal mode again with a hysteresis $V_{\mathrm{OV}(\mathrm{HY})}$ if the supply voltage decreases below the switch-on voltage $V_{\mathrm{OV}(\mathrm{ON})}$. This behavior of the BTM7745G will lead to freewheeling in highside during over voltage.

### 6.3.2 Undervoltage Shut Down

To avoid uncontrolled motion of the driven motor at low voltages the device shuts off (both outputs are tri-state), if the supply voltage $V_{\mathrm{S}}$ drops below the switch-off voltage $V_{\mathrm{UV}(\mathrm{OFF})}$. In this case all latches will be reset. The IC becomes active again with a hysteresis $V_{\mathrm{UV}(\mathrm{HY})}$ if the supply voltage rises above the switch-on voltage $V_{\mathrm{UV}(\mathrm{ON})}$.

### 6.3.3 Overtemperature Protection

The BTM7745G is protected against overtemperature by integrated temperature sensors. Each half bridge, which consists of one high side and one low side switch, is protected by one temperature sensor located in the high side switch. Both temperature sensors function independently. A detection of overtemperature through temperature sensor leads to a shut down of both switches in the half bridge. This state is latched until the device is reset by a low signal with a minimum length of $t_{\text {reset }}$ simultaneously at the $\mathbb{I N H}$ pin and both $\mathbb{I N}$ pins, provided that its temperature has decreased at least the thermal hysteresis $\Delta T$ in the meantime.
Overtemperature protection is available up to supply voltage $V_{\mathrm{S}}=18 \mathrm{~V}$.
For sufficient over temperature protection please consider also operation below the limitations outlined in Figure 4 and Figure 5.
Repetitive use of the overtemperature protection might reduce lifetime.

### 6.3.4 Current Limitation

The current in the bridge is measured in all four switches. As soon as the current in forward direction in one switch is reaching the limit $I_{\mathrm{CLx}}$, this switch is deactivated for $t_{\mathrm{CLs}}$. In case of $\mathrm{INH}=5 \mathrm{~V}$ (high) the other switch of the same half bridge is activated for the same time ( $t_{\mathrm{CLS}}$ ). During that time all changes at the related IN pin are ignored. However, the INH pin can still be used to switch all MOSFETs off. After $t_{\mathrm{CLs}}$ the switches return to their initial setting. The error signal at the ST pin is reset after $1.5^{*} t_{\mathrm{CLS}}$ if no overcurrent state is detected in the meantime. Unintentional triggering of the current limitation by short current spikes (e.g. inflicted by EMI coming from the motor) is suppressed by internal filter circuitry. Due to thresholds and reaction delay times of the filter circuitry the effective current limitation level $I_{\text {CLx }}$ depends on the slew rate of the load current di/dt as shown in Figure 11.


Figure 10 Timing Diagram Current Limitation and Status Flag

High Current H-Bridge BTM7745G

High Side Switch


Low Side Switch


Figure 11 Current Limitation Level vs. Current Slew Rate dIL/dt

High Side Switch


Low Side Switch


Figure 12 Typical Current Limitation Detection Levels vs. Supply Voltage

In combination with a typical inductive load, such as a motor, this results in a switched mode current limitation. This method of limiting the current has the advantage that the power dissipation in the BTM7745G is much smaller than by driving the MOSFETs in linear mode. Therefore it is possible to use the current limitation for a short time without exceeding the maximum allowed junction temperature (e.g. for limiting the inrush current during motor start up). However, the regular use of the current limitation is allowed as long as the specified maximum junction temperature is not exceeded. Exceeding this temperature can reduce the lifetime of the device.

High Current H-Bridge
BTM7745G

Block Description and Characteristics

### 6.3.5 Short Circuit Protection

The device provides embedded protection functions against

- output short circuit to ground
- output short circuit to supply voltage
- short circuit of load

The short circuit protection is realized by the previously described current limitation in combination with the overtemperature shut down (see Chapter 6.3.3) of the device.

### 6.3.6 Electrical Characteristics - Protection Functions

$V_{\mathrm{S}}=8 \mathrm{~V}$ to $18 \mathrm{~V}, T_{\mathrm{j}}=-40^{\circ} \mathrm{C}$ to $+150{ }^{\circ} \mathrm{C}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

| Pos. | Parameter | Symbol | Limit Values |  |  | Unit | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. |  |  |
| Over Voltage Lock Out |  |  |  |  |  |  |  |
| 6.3.1 | Switch-ON voltage | $V_{\text {OV(ON) }}$ | 27.8 | - | - | V | $V_{\text {s }}$ decreasing |
| 6.3.2 | Switch-OFF voltage | $V_{\text {OV(OFF) }}$ | 28 | - | 30 | V | $V_{\mathrm{s}}$ increasing |
| 6.3 .3 | ON/OFF hysteresis | $V_{\text {OV(HY) }}$ | - | 0.2 | - | V | 1) |
| Under Voltage Shut Down |  |  |  |  |  |  |  |
| 6.3.4 | Switch-ON voltage | $V_{\text {UV(ON) }}$ | - | - | 5.5 | V | $V_{\text {S }}$ increasing |
| 6.3 .5 | Switch-OFF voltage | $V_{\text {UV(OFF) }}$ | 4.0 | - | 5.4 | V | $V_{S}$ decreasing |
| 6.3 .6 | ON/OFF hysteresis | $V_{\mathrm{UV} \text { (HY) }}$ | - | 0.2 | - | V | 1) |

## Thermal Shut Down

| 6.3 .7 | Thermal shut down junction <br> temperature | $T_{\mathrm{jSD}}$ | 155 | 175 | 200 | ${ }^{\circ} \mathrm{C}$ | ${ }^{1)} ; V_{\mathrm{S}} \leq 18 \mathrm{~V}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 6.3 .8 | Thermal switch on junction <br> temperature | $T_{\mathrm{jSO}}$ | 153 | - | 190 | ${ }^{\circ} \mathrm{C}$ | ${ }^{1)}$ |
| 6.3 .9 | Thermal hysteresis | $\Delta T$ | - | 7 | - | ${ }^{\circ} \mathrm{C}$ | ${ }^{1)}$ |
| 6.3 .10 | Reset pulse at INH and IN pin <br> (INH, IN1 and IN2 low) | $t_{\text {reset }}$ | 8 | - | - | $\mu \mathrm{S}$ | ${ }^{1)}$ |

## Current Limitation

| 6.3 .11 | Current limitation detection <br> level high side | $I_{\text {CLHO }}$ | 6 | 12 | 16 | A | $V_{\mathrm{S}}=13.5 \mathrm{~V}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 6.3 .12 | Current limitation detection <br> level low side | $I_{\mathrm{CLLO}}$ | 6 | 12 | 16 | A | $V_{\mathrm{S}}=13.5 \mathrm{~V}$ |
| 6.3 .13 | Shut off time for HS and LS | $t_{\mathrm{CLS}}$ | 50 | 100 | 200 | $\mu \mathrm{~s}$ | $V_{\mathrm{S}}=13.5 \mathrm{~V}, T_{\mathrm{j}}=25^{\circ} \mathrm{C}$ |

1) Not subject to production test, specified by design.

### 6.4 Control and Diagnostics

### 6.4.1 Input Circuit

The control inputs INx and INH consist of TTL/CMOS compatible schmitt triggers with hysteresis which control the integrated gate drivers for the MOSFETs. To set the device in stand-by mode, INH and INx pins need to be all connected to GND. When the INH is high, in each half bridge one of the two power switches (HSx or LSx) is switched on, while the other power switch is switched off, depending on the status of the INx pin. When INH is low, a high INx signal will turn the corresponding highside switches on. This provides customer the possibility to switch on one high side switch while keeping the other switches off and therefore to do an open load detection together with external circuitry (see also Chapter 7 - Application Information). A low on all INx and INH signal will turn off both power switches. To drive the logic inputs no external driver is needed, therefore the BTM7745G can be interfaced directly to a microcontroller.

### 6.4.2 Dead Time Generation

In bridge applications it has to be assured that the highside and lowside MOSFET are not conducting at the same time, connecting directly the battery voltage to GND. This is assured by a circuit in the driver IC, which senses the status of the MOSFETs to ensure that the high or low side switch can be switched on only if the corresponding low or high side switch is completely turned off.

### 6.4.3 Status Flag Diagnosis

The status pin provides diagnostic signal of the device. It is an open drain output which requires a pull-up resistor. In case of overvoltage, overtemperature and overcurrent situation the status output is switched to low. In case of current limitation the status output is activated for $1.5{ }^{*} t_{\mathrm{CLS}}$.

High Current H-Bridge BTM7745G

Block Description and Characteristics

### 6.4.4 Truth Table

| Device State | Inputs |  |  | Outputs |  |  |  |  | Mode |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | INH | IN1 | IN2 | HS1 | LS1 | HS2 | LS2 | ST |  |
| Normal operation | 0 | 0 | 0 | OFF | OFF | OFF | OFF | 1 | Stand-by mode, reset |
|  | 1 | 0 | 0 | OFF | ON | OFF | ON | 1 | - |
|  | 1 | 0 | 1 | OFF | ON | ON | OFF | 1 | - |
|  | 1 | 1 | 0 | ON | OFF | OFF | ON | 1 | - |
|  | 1 | 1 | 1 | ON | OFF | ON | OFF | 1 | - |
| Open-Load detection mode | 0 | 0 | 1 | OFF | OFF | ON | OFF | 1 | Enable Open-load detection |
|  | 0 | 1 | 0 | ON | OFF | OFF | OFF | 1 | Enable Open-load detection |
|  | 0 | 1 | 1 | ON | OFF | ON | OFF | 1 |  |
| Over-voltage (OV) | X | X | X | ON | OFF | ON | OFF | 0 | Shut-down of LSS, HSS activated, error detected |
| Under-voltage (UV) | X | X | X | OFF | OFF | OFF | OFF | 1 | UV lockout, reset |
| Overtemperature or short circuit of HSS or LSS ${ }^{1)}$ | 0 | 0 | 0 | OFF | OFF | OFF | OFF | 1 | Stand-by mode, reset of latch |
|  | 1 | X | X | OFF | OFF | OFF | OFF | 0 | Shut-down with latch, error detected |
|  | X | 1 | X |  |  |  |  |  |  |
|  | X | X | 1 |  |  |  |  |  |  |
| Current limitation mode half bridge 1 | 1 | 0 | X | ON | OFF | X | X | 0 | Short Circuit in LS1 detected, half bridge 2 operates in normal mode |
|  | 1 | 1 | X | OFF | ON | X | X | 0 | Short Circuit in HS1 detected, half bridge 2 operates in normal mode |
|  | 0 | 1 | X | OFF | OFF | X | X | 0 | Short Circuit in HS1 detected |
| Current limitation mode half bridge 2 | 1 | X | 0 | X | X | ON | OFF | 0 | Short Circuit in LS2 detected, half bridge 1 operates in normal mode |
|  | 1 | X | 1 | X | X | OFF | ON | 0 | Short Circuit in HS2 detected, half bridge 1 operates in normal mode |
|  | 0 | X | 1 | X | X | OFF | OFF | 0 | Short Circuit in HS2 detected |

1) In short circuit of HSS or LSS, the junction temperature will arise and as soon as the over temperature shut down threshold is reached the device will shut down and latch the status. Short circuit of HSS and LSS itself won't be detected as failure.

| Inputs: | Switches | Status Flag ST: |
| :--- | :--- | :--- |
| $0=$ Logic LOW | OFF $=$ switched off | $0=$ Logic LOW (error) |
| $1=$ Logic HIGH | ON = switched on | $1=$ Logic HIGH (normal operation) |
| $X=0$ or 1 | X = switched on or off |  |

## BTM7745G

## Block Description and Characteristics

### 6.4.5 Electrical Characteristics - Control and Diagnostics

$V_{\mathrm{S}}=8 \mathrm{~V}$ to $18 \mathrm{~V}, T_{\mathrm{j}}=-40^{\circ} \mathrm{C}$ to $+150{ }^{\circ} \mathrm{C}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

| Pos. | Parameter | Symbol | Limit Values |  |  | Unit | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. |  |  |
| Control Inputs (IN and INH) |  |  |  |  |  |  |  |
| 6.4.1 | High level threshold voltage INH, IN1, IN2 | $\begin{aligned} & V_{\mathrm{INH}(\mathrm{H})}, \\ & V_{\mathrm{IN} 1(\mathrm{H})}, V_{\mathrm{IN} 2(\mathrm{H})} \end{aligned}$ | - | 1.6 | 2 | V | - |
| 6.4.2 | Low level threshold voltage INH, IN1, IN2 | $\begin{aligned} & V_{\operatorname{INH}(\mathrm{L})} \\ & V_{\mathrm{IN} 1(\mathrm{~L})}, V_{\mathrm{IN} 2(\mathrm{~L})} \\ & \hline \end{aligned}$ | 1.1 | 1.4 | - | V | - |
| 6.4.3 | Input voltage hysteresis | $V_{\text {INHHY }}, V_{\text {INHY }}$ | - | 200 | - | mV | 1) |
| 6.4.4 | Input current | $\begin{aligned} & I_{I_{\mathrm{NH}(\mathrm{H})},} \\ & I_{\mathrm{IN}_{\mathrm{N}(\mathrm{H})},}, I_{\mathrm{N} 2(\mathrm{H})} \end{aligned}$ | - | 30 | 200 | $\mu \mathrm{A}$ |  |
| 6.4.5 | Input current | $\begin{array}{\|l} I_{I_{\mathrm{NH}(\mathrm{~L})}} \\ I_{\mathrm{N} 1(\mathrm{~L})}, \\ I_{\mathrm{N} 2(\mathrm{~L})} \end{array}$ | - | 25 | 125 | $\mu \mathrm{A}$ | $V_{\mathrm{IN} 1}, V_{\mathrm{IN} 2}, V_{\mathrm{INH}}=0.4 \mathrm{~V}$ |

## Status Signal

| 6.4 .6 | Status Low output voltage | $V_{S T(L O W)}$ | - | - | 0.4 | V | $I_{\mathrm{ST}}=1.6 \mathrm{~mA}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 6.4 .7 | Status leakage current | $I_{S T(L K)}$ | - | - | 1 | $\mu \mathrm{~A}$ | $V_{S T}=0 . . .28 \mathrm{~V}$ |

1) Not subject to production test, specified by design.

## 7 Application Information

Note: The following information is given as a hint for the implementation of the device only and shall not be regarded as a description or warranty of a certain functionality, condition or quality of the device.


Figure 13 Application Diagram
Note: This is a very simplified example of an application circuit. The function must be verified in the real application.

### 7.1 Application and Layout Considerations

Due to the fast switching times for high currents, special care has to be taken during the PCB layout. Stray inductances have to be minimized in the power bridge design as it is necessary in all switched high power bridges. The BTM7745G has no separate pin for power ground and logic ground. Therefore it is recommended to assure that the offset between power ground and logic ground pins of the device is minimized. It is also necessary to ensure that all VS pins are at the same voltage level. Therefore the VS pins need to be shorted together. Voltage differences between the VS pins may cause parameter deviations (such as reduced current limits) up to a latched shutdown of the device with error signal on the ST pin, similar to overtemperature shutdown.
Due to the fast switching behavior of the device in current limitation mode or overvoltage lock out a low ESR electrolytic capacitor $C_{\mathrm{s}}$ of at least $100 \mu \mathrm{~F}$ from VS to GND is recommended. This prevents destructive voltage peaks and drops on VS. This is recommended for both PWM and non PWM controlled applications. The value of the capacitor must be verified in the real application.
In addition a ceramic capacitor $C_{\text {sc }}$ from VS to GND close to each device is recommended to provide current for the switching phase via a low inductance path and therefore reducing noise and ground bounce. A reasonable value for this capacitor would be about 470 nF .

## Application Information

It is recommended to do the freewheeling in the low side path to ensure a proper function and avoid unintended overtemperature detection and shutdown. For proper operation it is also recommended to put a pull-down resistor $R_{\mathrm{Dx}}$ on each output OUTx to GND with a value in the range of e.g. $1 . . .10 \mathrm{k} \Omega$. These resistors can also be used for open load detection.

## Considerations for Open Load Detection Mode

As mentioned in Chapter 6.4.1 both high side switches can be switched on independently while all other switches are off. This will be realized by setting the corresponding IN signal to high while INH and the other IN are low.

| Device State | Inputs |  |  | Outputs |  |  |  |  | Mode |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | INH | IN1 | IN2 | HS1 | LS1 | HS2 | LS2 | ST |  |
| Open-Load detection mode | 0 | 0 | 1 | OFF | OFF | ON | OFF | 1 | HS2 active |
|  | 0 | 1 | 0 | ON | OFF | OFF | OFF | 1 | HS1 active |
|  | 0 | 1 | 1 | ON | OFF | ON | OFF | 1 | both HSx are active |

Together with the recommended pull-down resistors on the outputs OUTx to GND this provides the possibility to do an open load detection in H-bridge configuration.

In case of one high side is active while the other half bridge is off (HS off and LS off) a current of up to 2 mA will be sourced out of the OUT of the high ohmic half bridge. This has to be considered while choosing the right value of the pull-down resistor.

## 8 Package Outlines



1) Does not include plastic or metal protrusion of 0.15 max. per side
2) Does not include dambar protrusion of 0.05 max. per side

PG-DSO-36-20, -29, -34, -43, -44-PO V05
Footprint


Figure 14 PG-DSO-36-29 (Plastic Green Dual Small Outline Package)

## Green Product (RoHS compliant)

To meet the world-wide customer requirements for environmentally friendly products and to be compliant with government regulations the device is available as a green product. Green products are RoHS-Compliant (i.e Pb-free finish on leads and suitable for Pb-free soldering according to IPC/JEDEC J-STD-020).

For further information on alternative packages, please visit our website:
http://www.infineon.com/packages.

High Current H-Bridge
BTM7745G

## 9 Revision History

| Revision | Date | Changes |
| :--- | :--- | :--- |
| 1.0 | $2010-05-28$ | Initial version Data Sheet |

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