# **LED**riv**IR**<sup>™</sup>

### IRS29831PBF

### LED FLYBACK CONTROL IC

#### Features

• Flyback LED Driver

International

**ICR** Rectifier

- Integrated 700 V MOSFET
- Critical-conduction / Transition mode operation
- Primary constant power control
- Burst mode operation at light load
- Over-current protection
- Micro power startup (150 µA)
- Low quiescent current (2.5 mA)
- Latch immunity and ESD protection
- Open load / Over voltage protection
- Compatible with Triac Dimmers
- High Power Factor / Low THD

#### **Typical Applications**

• LED Drivers

#### Product Summary

Topology	Flyback
Drain Source Voltage	700 V
Max Drain Current	0.65 A
Max Converter Power	25 W

#### Package



8-Lead DIP

#### **Ordering Information**

Dece Dect Newslaw		Standard Pack		
Base Part Number	Package Type	Form	Quantity	Complete Part Number
IRS29831PBF	DIP8	Tube/Bulk	50	IRS29831PBF

# **I** R

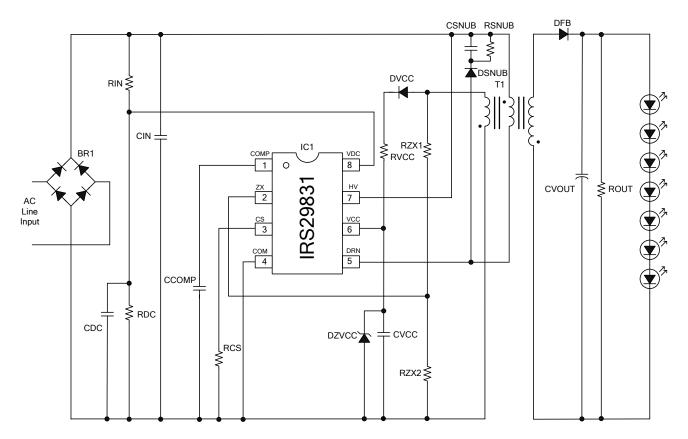
## IRS29831PBF

Table of Contents	Page
Ordering Information	1
Description	3
Absolute Maximum Ratings	4
Recommended Operating Conditions	4
Electrical Characteristics	5
Functional Block Diagram	7
State Diagram	8
Input/Output Pin Equivalent Circuit Diagram	9
Lead Definitions	10
Lead Assignments	10
Application Information and Additional Details	11
Package Details	15
Part Marking Information	16
Qualification Information	



#### Description

The IRS29831 is an integrated LED driver control IC and power MOSFET designed to drive Flyback and Buck-Boost converter based LED drivers. The IRS29831 includes primary side power regulation allowing a low cost isolated or non-isolated LED driver to be implemented without the need for an opto-isolator for a fixed LED load. The IRS29831 is also compatible with converters that include secondary feedback circuitry. Other features of the IRS29831 include a high voltage startup enabling VCC supply to be derived initially from the high voltage DC bus until the auxiliary Flyback inductor winding takes over for rapid startup. The IRS29831 typically operates in critical conduction (CrCM) with full protection against open and short circuit as well as inductor saturation. The IRS29831 may be used in single stage LED drivers with no DC bus smoothing capacitor enabling high power factor and low THD with minimal component count.



#### Typical Connection Diagram (non-dimming)



#### **Absolute Maximum Ratings**

Absolute maximum ratings indicate sustained limits beyond which damage to the device may occur. All voltage parameters are absolute voltages referenced to COM; all currents are defined positive into any lead. The thermal resistance and power dissipation ratings are measured under board mounted and still air conditions.

Symbol	Definition			Max.	Units
V <sub>DS</sub>	Drain-Source Voltage			700.0	V
I <sub>DS</sub>	Drain Current at 25°C <sup>†</sup>			0.65	Α
I <sub>DS</sub>	Drain Current at 100°C <sup>†</sup>			0.4	A
V <sub>CC</sub>	IC Low Voltage Supply <sup>††</sup>		-0.3	20.8	V
I <sub>cc</sub>	VCC current		0	25.0	mA
V <sub>HV</sub>	HV Pin Voltage		-0.3	600	V
I <sub>HV</sub>	HV Pin Current		0	5.0	mA
$V_{DS}$	Drain Pin Voltage		-0.3	700	V
V <sub>COMP</sub>	COMP Pin Voltage				
V <sub>DC</sub> VDC Pin Voltage				V <sub>cc</sub> +0.3	v
V <sub>ZX</sub> ZX Pin Voltage		-0.3	V <sub>CC</sub> +0.5	v	
V <sub>CS</sub>	VCS Pin Voltage	1			
I <sub>COMP</sub>	I <sub>COMP</sub> COMP Pin Current				
I <sub>DC</sub> VDC Pin Current		-5	F		
I <sub>ZX</sub>	ZX Pin Current		-5	5	mA
I <sub>cs</sub>					
$P_D$	$ \begin{array}{ l l l l l l l l l l l l l l l l l l l$			1	W
$R_{ ext{ heta}JA}$	Thermal Resistance, Junction to Ambient (8-Pin DIP)			125	°C/W
Τ <sub>J</sub>	T <sub>J</sub> Junction Temperature		-55	125	
Τ <sub>s</sub>	T <sub>s</sub> Storage Temperature		-55	125	°C
Τ <sub>L</sub>				300	

#### **Recommended Operating Conditions**

For proper operation the device should be used within recommended conditions.

Symbol	Definition	Min.	Max.	Units
V <sub>cc</sub>	Supply Voltage	V <sub>CCUV+</sub>	18	V
I <sub>cc</sub>	V <sub>CC</sub> Supply Current	Note 2	10	
I <sub>cs</sub>	CS Pin Current			
I <sub>DC</sub>	V <sub>DC</sub> Pin Current	-1 1		mA
I <sub>ZX</sub>	ZX Pin Current			
I <sub>COMP</sub>	COMP Pin Current			
$V_{DC}$	V <sub>DC</sub> Pin Voltage	0 6.0		v
V <sub>CS</sub>	V <sub>CS</sub> Pin Voltage	0.1	2.0	V
TJ	Junction Temperature	-25	100	٥C

**†:** The MOSFET device used in this product is rated to 4A. It has been de-rated to conform to the thermal limits of the DIP8 package assuming no heat sink is attached.

††: This IC contains a zener clamp structure between the chip VCC and COM which has a nominal breakdown voltage of 20V. This supply pin should not be driven by a DC, low impedance power source greater than the VCLAMP specified in the Electrical Characteristics section.

#### **Electrical Characteristics**

$$\label{eq:V_CC} \begin{split} V_{CC} &= V_{BIAS} {=} 14V \ {+}{-}\ 0.25V, \ C_{OUT} {=}\ 1000 pF, \\ V_{COMP} &= V_{OC} {=}\ V_{DC} {=}\ V_{ZX} {=}\ 0V, \ T_A {=} 25^{\circ}C \ \text{unless otherwise specified} \end{split}$$

Symbol	Definition	Min	Тур	Мах	Units	Test Conditions
<b>MOSFET Cha</b>	racteristics					
V <sub>DSMAX</sub>	Maximum Drain-Source Voltage	700.0			V	
I <sub>DMAX</sub>	Maximum Continuous Drain Current			0.65	А	
Source-Drain	Diode Characteristics					
V <sub>SD</sub>	Diode Forward Voltage			1.4	V	
T <sub>rr</sub>	Reverse Recovery Time		437.0		ns	
Q <sub>rr</sub>	Reverse Recovery Charge		2.2		μC	
Supply Chara	cteristics					
V <sub>CCUV+</sub>	V <sub>cc</sub> Supply Under Voltage Positive Going Threshold	11.5	12.5	13.5		
V <sub>CCUV</sub> -	V <sub>CC</sub> Supply Under Voltage Negative Going Threshold	9.5	10.5	11.5	V	
V <sub>UVHYS</sub>	V <sub>cc</sub> Supply Under Voltage Lockout Hysteresis	1.5	2.0	3.0		
IQCCUV	UVLO Mode V <sub>cc</sub> Quiescent Current		150		μA	$V_{CC} = 6V$
I <sub>CC</sub>	V <sub>CC</sub> Supply Current		2.5	5.0	mA	
$V_{CLAMP}$	V <sub>CC</sub> Zener Clamp Voltage	19.8	20.8	21.8	V	$I_{CC} = 10 \text{mA}$
	Startup Characteristics					
V <sub>HVSMIN</sub>	Minimum Startup Voltage	30.0			V	
I <sub>HV_CHARGE</sub>	V <sub>cc</sub> Charge Current	1	2		mA	V <sub>CC</sub> < V <sub>CCUV-</sub> HV=100V~400V
HVS_OFF	High Voltage Start-Up Circuit OFF State Leakage Current			50	μA	HV=400V
Error Amplifie	er Characteristics					
	COMP Pin Error Amplifier Output Current Sourcing		30		-μA	
I <sub>COMPSINK</sub>	COMP Pin Error Amplifier Output Current Sinking		30		μΑ	
V <sub>COMPOH</sub>	Error Amplifier Output Voltage Swing (high state)		13.5			
V <sub>COMPOL</sub>	Error Amplifier Output Voltage Swing (low state)		2.5		V	GBD
V <sub>COMPFLT</sub>	Error Amplifier Output Voltage in Fault Mode		0			
I <sub>VDC</sub>	Input bias current		-1		μA	V <sub>DC</sub> =0 to 3V
<b>Control Chara</b>	acteristics					
V <sub>ZX+</sub>	ZX Pin Threshold Voltage (Arm)	1.40	1.54	1.68		
V <sub>ZX-</sub>	ZX Pin Threshold Voltage (Trigger)	0.52	0.6	0.68	V	
V <sub>PREF</sub>	Power Regulation Reference		1.00			
K <sub>MULT</sub>	Multiplier Gain	1.90	2.00	2.10		V <sub>CS</sub> =0.5V
t <sub>BLANK</sub>	OC pin current-sensing blank time	160	200	264	ns	V <sub>DC</sub> =2.5V COMP=4.0V CS=1.5V

#### **Electrical Characteristics (cont'd)**

 $V_{CC} = V_{BIAS} = 14V + 0.25V, C_{OUT} = 1000pF,$  $V_{COMP} = V_{OC} = V_{DC} = V_{ZX} = 0V, T_A = 25^{\circ}C \text{ unless otherwise specified.}$ 

T <sub>WD</sub>	PFC Watch-dog Pulse Interval		100	135	μs	ZX = 0 COMP = 4.0V
t <sub>onmin</sub>	PWM Minimum ON time	220	280	340	ns	††
t <sub>onmax</sub>	PWM Maximum ON Time 22 32 42 µs		PWM Maximum ON Time		ZX = 0 COMP = 13V	
t <sub>OFFMIN</sub>	PWM Minimum OFF Time	2.7	3.0	3.3		††
V <sub>DCMAX</sub>	Maximum voltage for multiplier input <sup>†</sup>			7.0	V	GBD
V <sub>CSPKMAX</sub>	Maximum peak voltage for multiplier input <sup>†</sup>			1.0	V	Signal is averaged before entering multiplier input. GBD
<b>Protection Cir</b>	cuitry Characteristics					
V <sub>CSTH</sub>	CS Pin Over-current Sense Threshold	1.19	1.25	1.31		
V <sub>COMPOFF</sub>	Cut off voltage below which gate drive output is disabled	1.12	1.40	1.68	V	
$V_{\text{COMPOFF}_\text{HYS}}$	Cut off voltage hysteresis		40		mV	
V <sub>OVTH</sub>	ZX Pin Over-voltage Comparator Threshold	4.90	5.15	5.40	V	
V <sub>OVHYS</sub>	ZX Pin Over-voltage Comparator Hysteresis		200		mV	

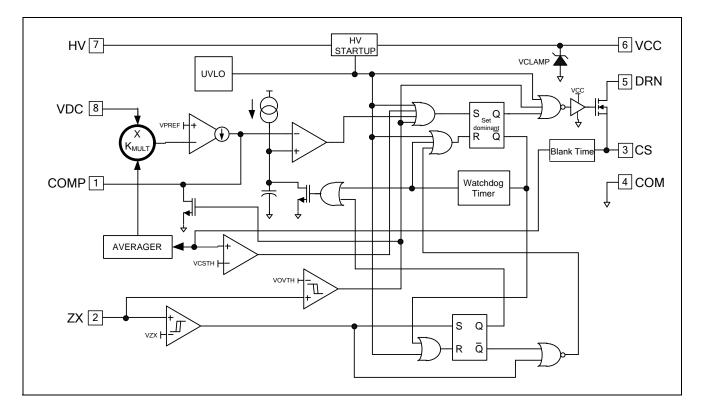
**†**: Multiplier operates accurately from zero to the maximum input specified.

††: Measured at the Drain with MOSFET switching delay also included.

GBD: Guaranteed by design.

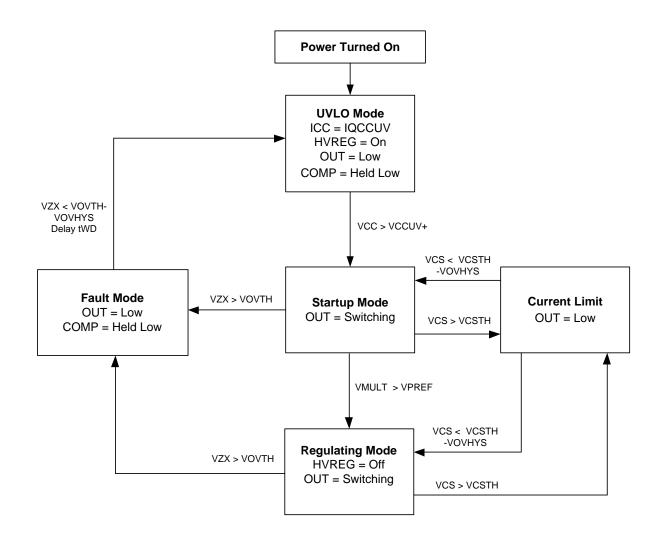


#### **Functional Block Diagram**



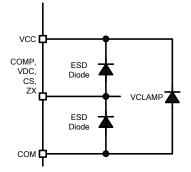


#### State Diagram





#### Input/Output Pin Equivalent Circuit Diagrams

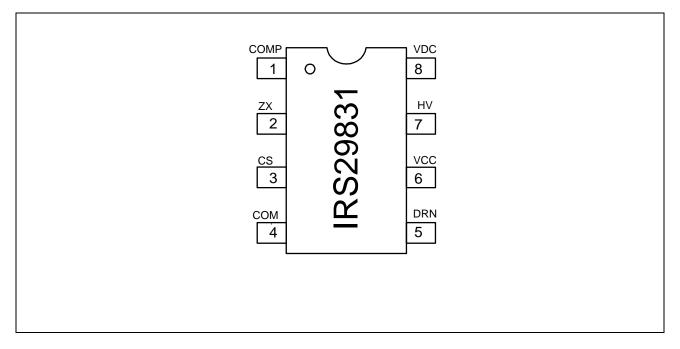




#### Lead Definitions

Symbol	Description	
COMP	Compensation and averaging capacitor input	
ZX	PFC Zero-Crossing & Over-Voltage Detection	
CS	PFC Current Sensing Input	
СОМ	IC Power & Signal Ground	
DRN	MOSFET Drain	
VCC	Logic & Low-Side Gate Driver Supply	
HV	High Voltage Startup Input	
VDC	DC Bus Voltage Input	

#### Lead Assignments



# Application Information and Additional Details

The IRS29831 is a switched mode controller IC with an integrated high voltage MOSFET designed for use in Flyback and Buck-Boost converters. An internal high voltage regulator is included to supply the IC low voltage VCC supply allowing operation directly from a DC input voltage up to 600V with rapid startup at low and high AC line inputs.

#### Internal high voltage startup

In order to begin operating, the IRS29831 requires its VCC supply to be raised above the under voltage lockout positive threshold (VCCUV+) and to continue operating requires VCC to be maintained above the under voltage lockout negative threshold (VCCUV-).

The internal high voltage start up circuit provides the initial VCC voltage until an auxiliary winding from the converter transformer takes over. A series resistor RVCC and 18V zener clamp DZVCC or other voltage limiting scheme is necessary in line with VCC to prevent damage to the IRS29831 if the auxiliary winding voltage exceeds the internal clamp voltage (VCLAMP).

The HV regulator enables the IRS29831 based LED driver to start up very rapidly and deliver light within 0.5s of switch on at any line input voltage. When the converter reaches steady state and VCC can be supplied through the auxiliary winding the HV regulator switches off for zero power dissipation.

The IRS29831 is primarily targeted at LED driver applications up to 25W using isolated or non-Flvback isolated converter or Buck-Boost topologies. The auxiliary winding is also used to detect output voltage and zero-crossing point. In the event of a short circuit at the output, the VCC supply from the auxiliary winding collapses causing the IRS29831 to enter under voltage lockout and shut down. The startup sequence is then re-initialized continuing in "hiccup" mode until the short circuit is removed. Short circuit protection is therefore auto-recovering enabling the driver to tolerate the condition without damage to the components. A capacitor in the order of 10pF at the ZX may be required for correct operation.

#### Primary power regulation

To eliminate feedback circuitry and opto-isolators where the load consists of a fixed number of

LEDs, the IRS29831 is capable of regulating the output current indirectly by calculating and controlling the input power of the converter. Since an LED load has an approximately fixed voltage the power consumed is proportional to the current. In practice there are variations in LED forward voltage drop due to tolerance and temperature, however perfect accuracy is not usually required in such applications. For a fixed number of LEDs the current will be approximately proportional to the input power allowing output current regulation of +/-5% over line input from 120VAC to 230VAC. Power regulation has been shown to provide slightly less Lumen output variation than current regulation.

The IRS29831 senses input voltage and current then averages and multiplies these quantities to determine the input power. This is then regulated against an accurate fixed reference to control the LED current.

The line input voltage is sensed through a resistor divider (RIN and RDC) to provide a voltage within the range from 0V to VDCMAX. Primary current is sensed through shunt resistor (RCS) connected from the source of the Flyback MOSFET switch to the DC bus return. This waveform is a high frequency ramp rising from zero at the beginning of each switching cycle to reach a peak level at the point the MOSFET is switched off, remaining at zero during the off time.

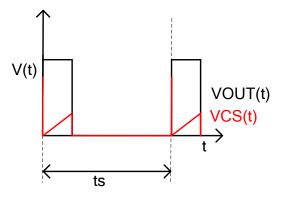


Figure 1: Current sense waveform

A transconductance error amplifier (OTA) uses an external capacitor (CCOMP) referenced to 0V to realize an integrator that provides a stable error voltage used to control the PWM on time. A response time of several AC line cycles is normally used as in typical power factor correction circuits to enable high power factor and low THD. LED output current typically increases gradually as the input voltage is increased. At light loads the IRS29831 operates in burst mode to minimize losses and maintain a stable output when the COMP output voltage drops below the VCOMPOFF threshold.

#### Primary current limiting

At low line input voltages the power regulation loop demands a high peak current which can cause saturation of the primary inductor. In order to prevent this from occurring, the IRS29831 includes cycle by cycle primary current limiting with a fixed threshold VCSTH at the CS pin input. Under low line or fault conditions where the MOSFET current is abnormally high, the gate drive switches off as the current ramps up above VCSTH with a leading edge blanking period of tBLANK. Leading edge blanking avoids false tripping due to the fast high current switch on transient caused by parasitic capacitances in the internal MOSFET. This transient is also blanked from the averaging input that feeds the power regulation multiplier to prevent inaccuracies.

The IRS29831 normally operates in critical conduction mode (CrCM), also known as transition or boundary mode. The Flyback transformer auxiliary winding used to supply VCC is also used to provide the zero crossing or demagnetization signal to the IRS29831. This indicates when all of the energy stored in the inductor has been transferred to the output to trigger the next switching cycle.

The auxiliary winding voltage is divided through RZX1 and RZX2 to provide the ZX pin input signal.

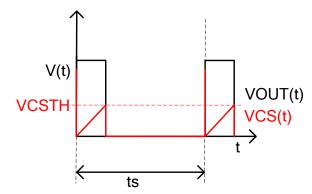


Figure 2: Cycle by cycle current limiting

The pulse appearing at ZX has an amplitude proportional to the secondary output voltage and therefore the DC output voltage:

$$VZX = \frac{N_A \cdot RZX \, 2 \cdot VOUT}{N_S \cdot (RZX1 + RZX2)}$$
[1]

Where,

 $N_A$  = Number of turns on the auxiliary winding  $N_S$  = Number of turns on the secondary winding VOUT = DC Output Voltage (LED voltage)

When the IRS29831 integrated MOSFET switches off the voltage VZX transitions high. The values of RZX1 and RZX2 must be selected so that this voltage always exceeds the VZX+ threshold. It should be noted that if the IRS29831 is used in a converter that is required to drive loads with

different numbers of LEDs with a range of voltage, an additional feedback circuit is needed to regulate the output current. In this case the VZX voltage needs to exceed VZX+ at the minimum load voltage. If VZX does not exceed VZX+ the IRS29831 will operate in discontinuous mode (DCM) with a fixed time of tWD.

When the voltage at VZX exceeds VZX+ the IRS29831 is armed. It then waits until VZX drops below VZX- again to trigger the next switching cycle.

The IRS29831 includes a minimum off time function so that if the ZX pin input transitions high and low before tOFFMIN the gate drive output will not go high again until after this period. This prevents false tripping at the ZX input and also limits the maximum switching frequency of the converter by entering discontinuous mode (DCM) under conditions where the off time would otherwise be very short. This reduces switching losses and prevents transformer overheating.

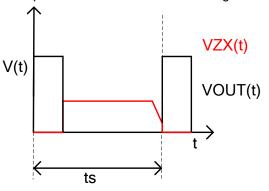


Figure 3: Zero crossing detection

### IRS29831PBF

#### Integrated MOSFET

The IRS29831 includes an internal 700V rated MOSFET with low RDSon to enable driver operation up to 25W with minimal temperature rise. A snubber network consisting of DSNUB, CSNUB and RSNUB is required in Flyback converters to limit the peak ringing transient. In a typical circuit with appropriate snubber values the transient will not exceed 650V at maximum line input.

#### Over voltage protection

The ZX input is also used for output over voltage protection. If the load becomes disconnected the output voltage could potentially rise very high damaging components as well as presenting an electric shock hazard. In order to protect against this the IRS29831 is able to detect the output voltage indirectly through the proportional ZX input. If the ZX input voltage exceeds VOVTH when the MOSFET switches off, the gate drive switches off and remains off for a period of tWD before beginning the next cycle irrespective of when the ZX voltage transitions low. In this case the IRS29831 discharges the COMP capacitor so that the next cycle will begin at reduced duty cycle. When the open circuit is removed the converter recovers with a soft start. This protection scheme allows the LED load to be "hot" connected and disconnected from the converter output without risk of damaging the circuit or of high voltages appearing at the output.

The overvoltage threshold is set by choosing the values of RZX1 and RZX2 appropriately, according to the formula:

$$VOUT_{OV} = \frac{VOVTH \cdot N_{s} \cdot (RZX1 + RZX2)}{N_{A} \cdot RZX2}$$
[2]

The recommended over voltage threshold is 20-25% above the normal operating voltage of the LED load. This is important since re-connecting an LED load with the output capacitor charged to a higher voltage causes a high current discharge that can cause severe damage to LEDs. A bleed resistor is also recommended to discharge the output capacitor.

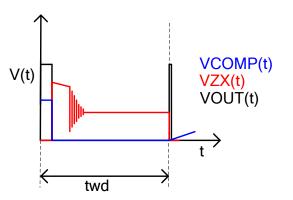


Figure 4: Overvoltage protection

#### Operating with a secondary feedback circuit

In applications where more accurate current regulation over a wide input and/or output voltage range required the IRS29831 can be used in conjunction with a secondary sensing and feedback circuit. This technique is also applied in designs where dimming to low levels is required for example in a 0-10V controlled dimmable LED driver.

The feedback circuit can be fed through an optoisolator or from the output of an operational amplifier if isolation is not required.

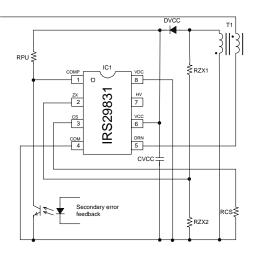


Figure 5: Secondary feedback circuit

A simple output voltage feedback scheme is shown in figure 5 to demonstrate how the optoisolator can be connected to the IRS29831 to create a feedback circuit. The VDC input is tied to COM leaving the multiplier output at zero with the COMP output pulled up to maximum by the internal error amplifier. The opto-isolator feedback

pulls down on the COMP voltage to reduce the on time as the opto-diode current is increased driven by a secondary error amplifier circuit. A pull up resistor (RPU) may be added to improve stability.

#### **Triac Dimming**

A triac dimming LED driver can be easily implemented with the IRS29831 using a small number of additional components. The dimming design should be optimized to work in either the 120VAC or 220VAC range. It is not practical to create a design with good dimming performance and efficiency for both input voltages.

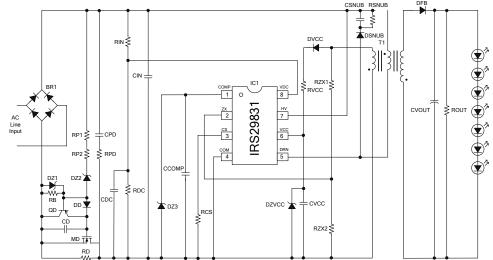
The dimming driver implementation consists of a single stage high power factor converter previously described with anti-ringing and active damping circuits added to the input to provide triac stability. The COMP output is also clamped to a maximum level by adding an external zener diode DZ3 referenced to COM. This prevents the primary side regulation circuit from attempting to compensate for the reduced AC input voltage detected during dimming. During dimming the converter operates with the on time determined by the voltage at which COMP is limited by the zener diode. A value of 6.8V typically provides good results for a 120VAC system. The schematic below shows a full implementation of a 120VAC triac dimmable LED driver.

RPD and CPD for the anti-ringing network to suppress high frequency oscillations that typically occur when the dimmer triac fires caused by the interaction of the dimmer with the LED driver input filter. Typical values for RPD and CPD are 470Ohms (1W) and 100nF to 220nF (250V).

The active damping circuit based around a low voltage MOSFET MD is used to limit the inrush current when the triac fires. At the start of each line cycle the triac is in the off state and during this time MD is turned off while QD holds the gate low. This means that when the triac fires the series damping resistor RD limits the input current for a period of time until MD switches on. Zener diode DZ2 normally rated at 10V prevents MD from switching on due to residual leakage voltages that appear on the DC bus during the period before the triac fires. After the triac fires a voltage appears at DZ1 which is typically rated at 16V. This causes QD to switch off and CD to charge through RP1, RP2 and DD. After the delay determined by these components, MD switches on shorting out RD to remove the damping resistance when it is no longer necessary. Typical values for RP1, RP2 are 680K and CD is 4.7nF. DD can be a typical small diode such as a 1N4148.

The active circuit is designed to provide input resistance to damp the circuit at the firing point without incurring unnecessary power losses in the damping resistor RD. A typical value for RD is 1000hms rated at 2W.

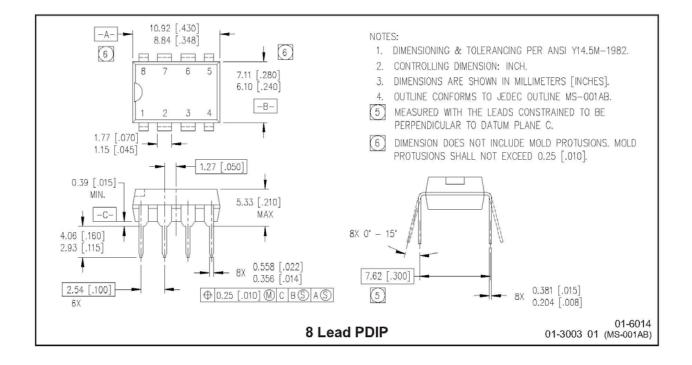
If some power loss can be tolerated in the interests of saving component cost RD can be reduced in value and MD and the components driving its gate can be removed. This low cost approach can still provide acceptable dimming performance with a small loss in converter efficiency.



#### Triac Dimmable LED Driver

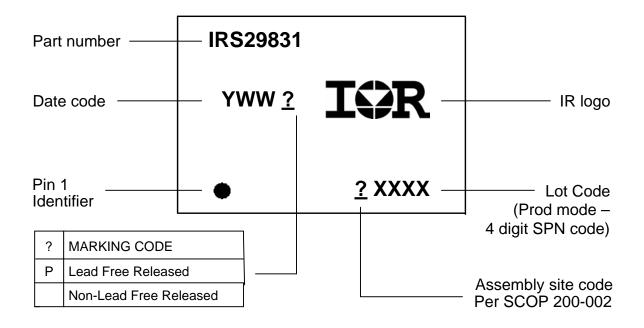


#### Package Details





#### **Part Marking Information**





#### **Qualification Information<sup>†</sup>**

Qualification Level		Industrial <sup>††</sup>
		Comments: This family of ICs has passed JEDEC's Industrial
		qualification. IR's Consumer qualification level is granted by
		extension of the higher Industrial level.
Machine Model		Class B
ESD		(per JEDEC standard JESD22-A115)
Human Body Model		Class 1C
		(per ANSI/ESDA/JEDEC standard JS-001-2012)
IC Latch-Up Test		Class I, Level A
		(per JESD78)
RoHS Compliant		Yes

† Qualification standards can be found at International Rectifier's web site http://www.irf.com/

- + Higher qualification ratings may be available should the user have such requirements. Please contact your International Rectifier sales representative for further information.
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