

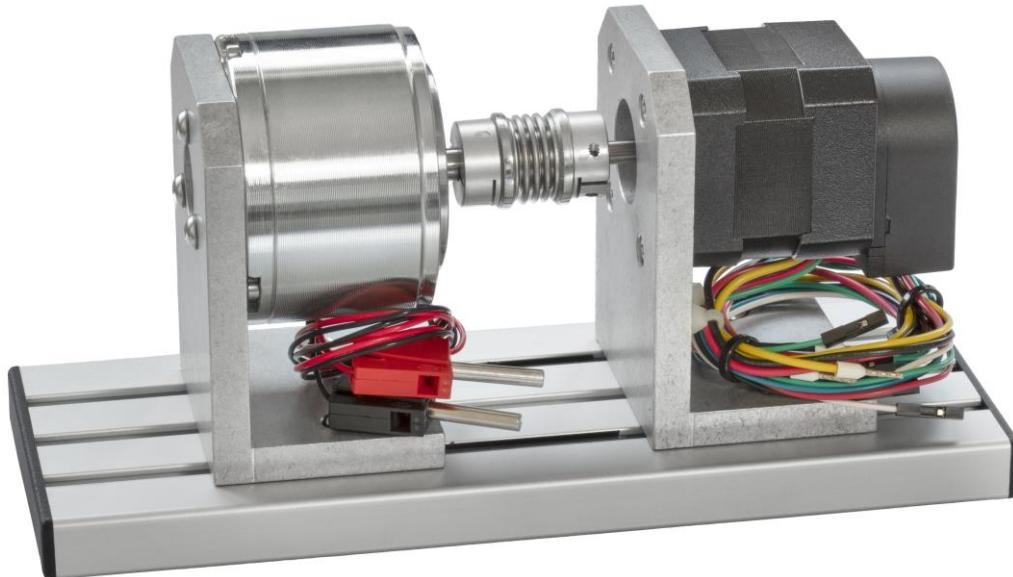
User Manual

MOTIX™ Motor Bench

About this document

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About this document

Scope and purpose

This User Manual is intended to enable users to use the MOTIX™ Motor Bench.

This document describes the MOTIX™ Motor Bench and its components.

The MOTIX™ Motor Bench can be combined with Infineon evaluation boards and reference designs for BLDC motor control evaluation. It is meant to support the motor control software development process.

The MOTIX™ Motor Bench is intended to be used with 3 phase evaluation boards of Infineon products.

For example:

- MOTIX™
- AURIX™
- TRAVEO™
- iMOTION™

Intended audience

This document is intended for anyone using the MOTIX™ Motor Bench. It is recommended for trained personnel.

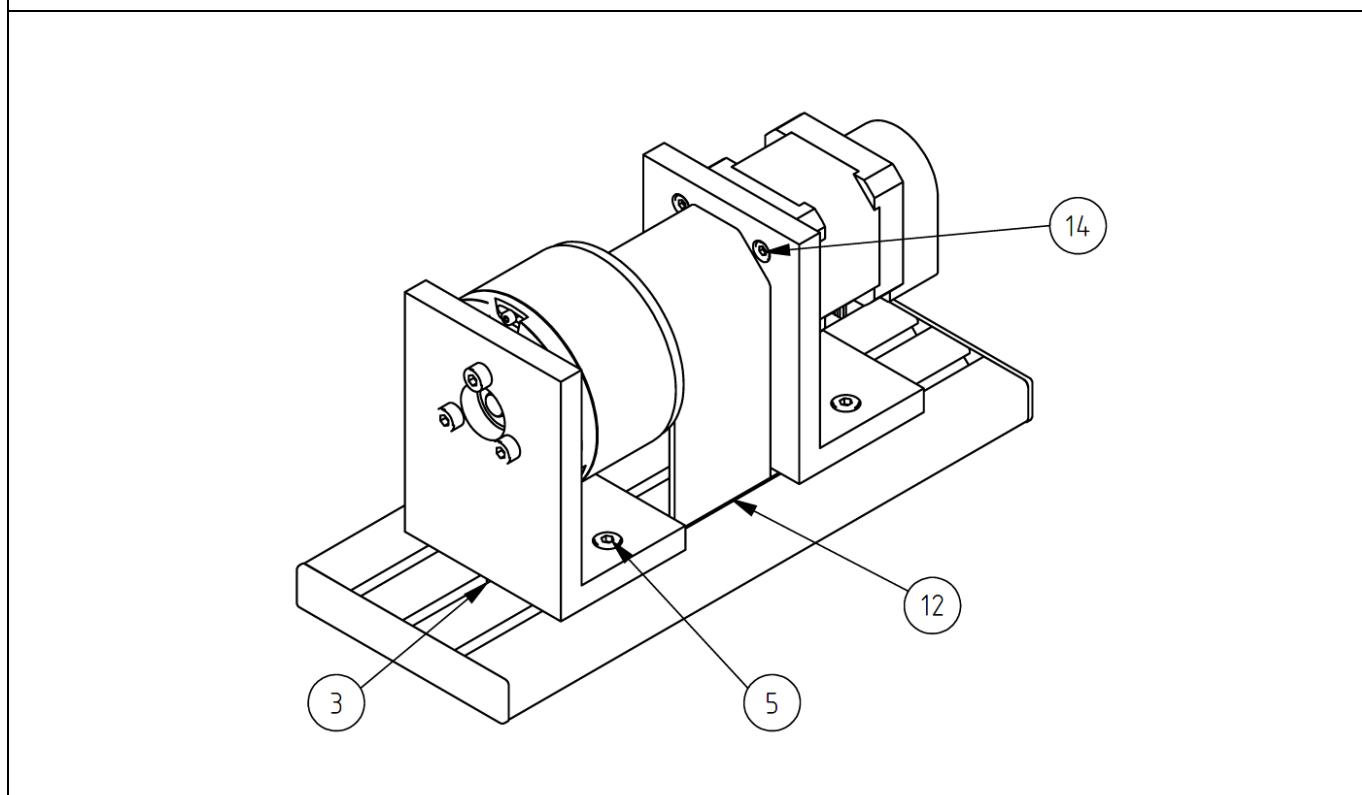
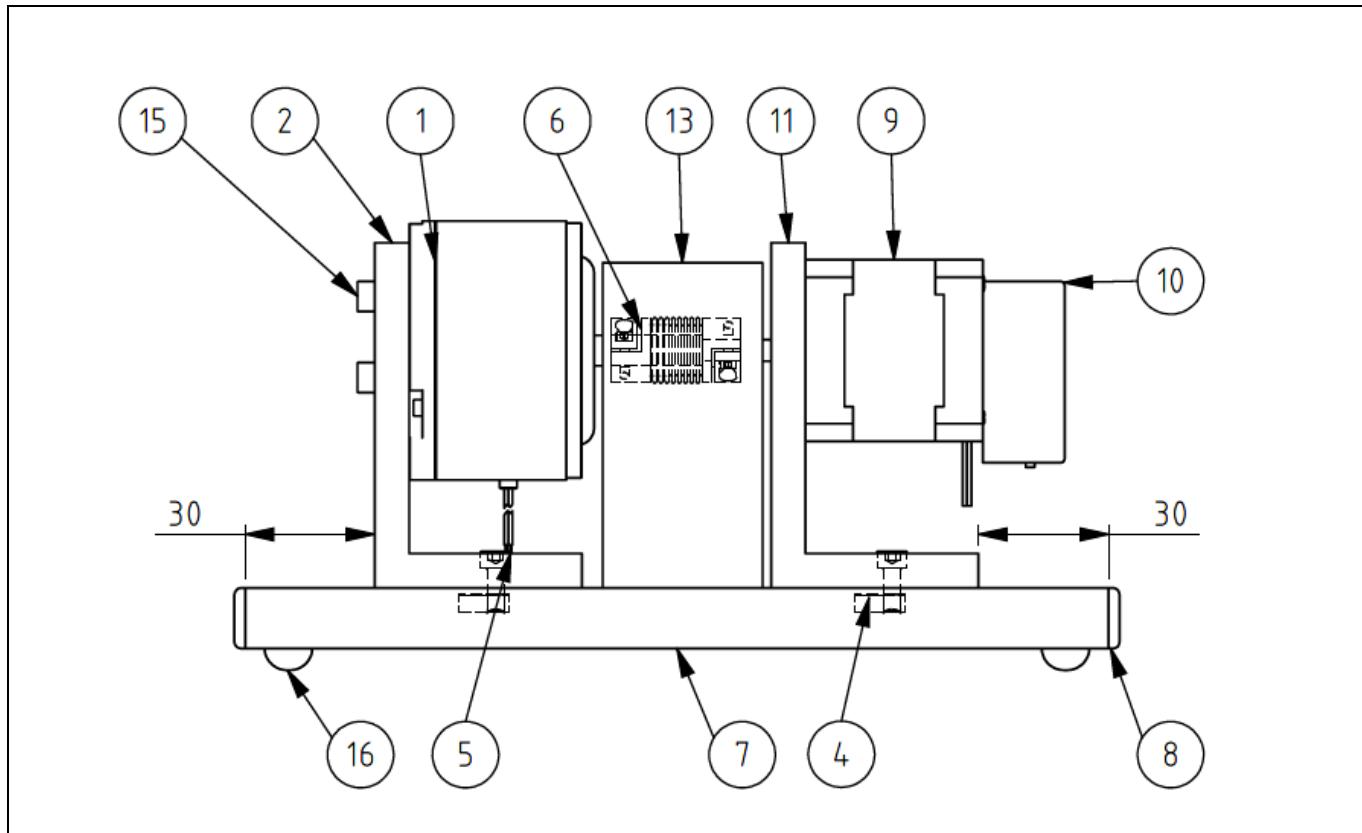
Note: The MOTIX™ Motor Bench contains spinning components while operational. Always keep the acrylic cover closed. Check all screws and achsle alignment frequently.

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1 Mechanical Setup

1.1 Main Assembly



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1.2 Bill of Material

Table 1 Bill of Material

No.	Qty.	Title	Comp. / Manuf.	Draw. / Manuf. No.	Rev. / Note
1	1	hysteresis brake	Mobac	HB-50M-2	-
2	1	brake bracket	MOTEON (MTN)	PMTN19-MTN-P002 / Alu-Winkel EN-AW 6060 80x80x8 mm	Rev.1.0
3	4	parallel pin ISO 2338 - 5 m8 x 10	-	-	Toolbox Part
4	4	slot nut M4	item	0037006	-
5	4	Screw SO 4762 M4 x 10 - 10N	-	-	Toolbox Part
6	1	miniature bellows coupling MK2	R+W	MK2/15/30/5/7	-
7	1	profile 5 80x14 L=200	item	0037085	3m length item 0044813
8	2	cover cap 5 80x14	item	0037091	-
9	1	brushless DC motor DB42S03	nanotec	DB42S03	-
10	1	encoder WEDL5541-B14	nanotec	WEDL5541-B14	-
11	1	motor bracket	MOTEON (MTN)	PMTN19-MTN-P001 / Alu-Winkel EN-AW 6060 80x80x8 mm	Rev.1.0
12	2	cover profile 5 L=40 mm	item	0039174	only orderable in 2m length
13	1	shaft cover	MOTEON (MTN)	PMTN19-MTN-P003 / 2mm transparent acrylic	Rev.1.0
14	4	Screw ISO 4762 M3 x 10 - 10N	-	-	Toolbox Part
15	3	Screw ISO 4762 M4 x 16 - 16N	-	-	Toolbox Part
16	4	Buffer D11x5	item	0.0.667.78	Set of 4

1.3 Electric connections**Table 2 Electric Connections**

Component	Wire	Function	Wire termination
hysteresis brake	red	DC+	Wago 215-212
hysteresis brake	black	DC-	Wago 215-311
motor phase	AWG20 yellow	U	crimped ferrule
motor phase	AWG20 red	V	crimped ferrule
motor phase	AWG20 black	W	crimped ferrule
motor Hall sensor	AWG26 red	+5V	Dupont female 1-pin
motor Hall sensor	AWG26 black	GND	Dupont female 1-pin
motor Hall sensor	AWG26 blue	H1	Dupont female 1-pin
motor Hall sensor	AWG26 white	H2	Dupont female 1-pin
motor Hall sensor	AWG26 green	H3	Dupont female 1-pin

Note: It is recommended to use pull-up resistors on the H1, H2 and H3 connections to +5V.

1.4 Motor

The MOTIX™ Motor Bench is equipped with a Nanotec DB42S03 BLDC motor. The latest specification can be found on the manufacturer's website.

Table 3 Motor Parameters copied from DB42S03 Datasheet

No. of Pol./Phases	8/3		
Voltage Rated (VDC)	24		
Current (AMP)	No load [A]	Rated [A]	Peak [A]
	0.2	1.79	5.4
Resistance / phase to phase [Ohms] @ 25°C	1.5 ± 15%		
Inductance / phase to phase [mH] @ 1kHz	2.1 ± 20%		
Tourque Rated / Peak	Constant [Nm/A]	Rated [Nm]	Peak [Nm]
	0.035	0.0625	0.19
Power Rated [W]	26		
Speed	Rated [RPM]		No Load [RPM]
	4000		6200
Rotor Inertia [Kg-m ²]	2.4x10 ⁻⁶		
Weight [Kg]	0.3		

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1.5 Hysteresis Brake

The MOTIX™ Motor Bench is equipped with a Mobac HB-50M-2 hysteresis brake. The latest specification can be found on the manufacturer's website.

Table 4 Brake Parameters copied from Mobac HB-50M-2 Datasheet

Torque at working current [Nm]	0.38	
Working current [mA]	270	
Resistance at 25°C ± 10% [Ohm]	95	
DC Voltage [V]	24	
Rpm max. 25°C ± 10% [min ⁻¹]	15000	
Power dissipation [Watt]	Peak	continuous
	90	23
Residual torque without current [Nm]	1.55×10^{-3}	
Rotor inertia [kgcm ²]	0.1670	
Weight [kg]	0.755	

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1.6 Couplings

The coupling creates the mechanical link between the motor and the hysteresis brake. It also compensates mechanical inaccuracies in the setup. It is mandatory to realign the setup frequently.

Note: Couplings may vary in model and manufacturer due to allocation.

Table 5 **Couplings variations**

	
Motor axle diameter (rated) [mm]	5
Brake axle diameter (rated) [mm]	7

2 Hardware and Software Support

2.1 MOTIX™ MCUs

Table 6 Evaluation Hardware

Name	Order No.	Example Software
TLE9879 Evalkit	SP001389172	<ul style="list-style-type: none">- Sensor-less FOC
TLE987X EVALB_VQFN	SP005421934	<ul style="list-style-type: none">- Block commutation, Hall sensor based
TLE987X EVALB_TQFP	SP005421936	<ul style="list-style-type: none">- Block commutation with BEMF

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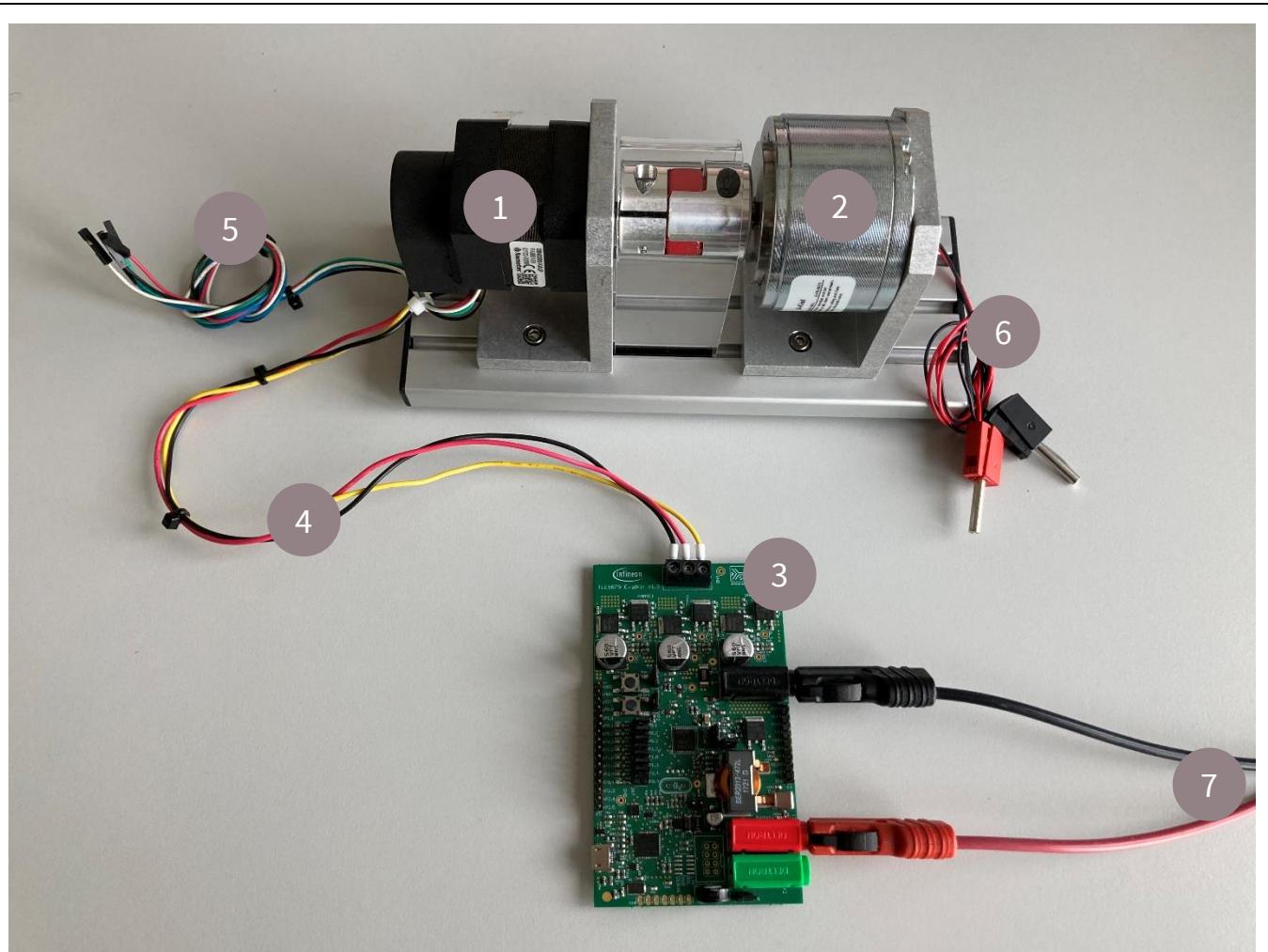
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3 Example Setup

The MOTIX™ Motor Bench can be used with several Evaluation Boards from Infineon Technologies. This chapter describes an example setup.

Table 7 Example Setup



1	DB42S03 BLDC motor
2	Mobac HB-50M-2 hysteresis brake
3	TLE9879 Evalkit
4	BLDC motor phase wires
5	Hall sensor wires
6	Hysteresis brake connectors
7	12V Power Supply

4 Revision History

Table 8 Revision History

Page or Item	Subjects (major changes since previous revision)
Rev. 1.0, 2022-10-11	
All	Initial release.

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