TDA5150
Multichannel / Multiband Transmitter

Multichannel / Multiband RF Transmitter for 300-928 MHz bands

On-chip, high resolution fractional-N synthesizer and
Sigma-Delta modulator with ASK, FSK, GFSK options

Wireless Control

(Infineon

N e v e r   s t o p   t h i n k i n g .

TDA5150

Revision History:		**V1.1**
Previous Version:	**V1.0** issued July 2009	
433 MHz band lower limit changed	433 MHz frequency band lower limit (min), referred in several paragraphs changed from previous value of **425** MHz to **433** MHz, recent value	
Chapter 2.4.5	Detailed explanations about avoidance of fractional spurs added to **Crystal Oscillator and Clock Divider** subchapter	
Chapter 2.4.11.2	Detailed description of chip-internal synchronization mechanism added to **Synchronous Transmission** subchapter	
Table 4 four individual bits in synthesizer register bank (SFRs) reassigned to *reserved* class	Four bits (previously referenced as FRACCOMPx) reassigned to **reserved** class. **Notes**: 1. The affected bits are 0x0C.5 0x10.5 0x14.5 and 0x18.5 2. The change has no impact on chip functionality 3. After-reset state of all four above mentioned bits is 0 (i.e. no change versus previous Datasheet V1.0)	
Description of Evaluation Board V2 added to **Chapter 3.2**	Description of **Evaluation Board V2** added, see **Infineon Evaluation Board V2** Description of former board version moved to subchapter **Schematics of Infineon Evaluation board V1.1**	
Values in **Table "PLLBW TRIM" on Page 84** and associated *Note* on same page updated in accordance with the PLL settings listed in **Table 2**	Range of nominal PLL Bandwidth values (PLLBW) Listed in **Datasheet V1.0** 90 120 150 180 210 240 270 [kHz] Listed in **Datasheet V1.1** 150 175 230 270 335 375 410 [kHz] by chargepump current of 5 7.5 12.5 17.5 25 32.5 40 [µA] *Note:* 1. chargepump current values are unchanged and the same in both Datasheets. 2. no changes operated in **Table 2** regarding the PLL bandwidth or chargepump current settings.	
Data regarding load drive capability of **SDIO** pin added	Data regarding load drive capability of **SDIO** pin added to **Table 13**	

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1 Product Description

1.1 Overview

The TDA5150 is a low cost, multi-channel ASK/FSK/GFSK RF transmitter for the 300-320 MHz, 433-450 MHz, 863-928 MHz frequency bands with low power consumption and programmable RF-output power of up to +10 dBm. Radio systems built around this transmitter are easy to be designed and to be implemented.

The IC offers a high level of integration and needs only a few external components, such as a crystal, blocking capacitors and the necessary matching elements between the power amplifier output and the antenna.

An integrated high-resolution fractional-N PLL synthesizer interconnected with a sigma-delta modulator covers all of the above listed frequency bands, using the same crystal for reference frequency and Baud-rate generation.

All the major functions of the chip are controlled over SFR registers, which at their turn are accessible over a 3-wire SPI bus (Serial Peripheral Interface).

The user-configurable digital modulator allows precise settings of FSK modulation parameters and Gaussian shaping (GFSK), which directly contributes to reduction of occupied bandwidth and efficient spectrum usage.

The output power of the integrated C-class RF power amplifier is controlled over SFR registers and if necessary, the power can be downsized (reduced) in digital steps. The ASK shaping option contributes to reduced harmonics and minimized spectral splatter.

On-chip antenna tuning capacitors are available, the capacitor bank switching (for antenna tuning) is accomplished over SFR registers.

The data encoder supports NRZ, Manchester, Bi-Phase, and Miller encoding.

1.2 Features

- High resolution Sigma-Delta fractional-N PLL synthesizer (frequency step size down to 7 Hz)
- Multiband/Multichannel capability for the 300-320 MHz, 433-450 MHz and 863-928 MHz bands
- Modulation types ASK (OOK) with ASK shaping, FSK (CPFSK) and GFSK
- Multi-channel and channel hopping capability, 4 register banks for fast Tx frequency switching
- Configurable via 3-wire serial interface bus (SPI)
- Manchester, Bi-Phase, and Miller encoding, on-chip PRBS9 scrambler
- Continuous checking of chip status by Fail-Safe mechanism
- Transparent and synchronized RF modulation mode
- Programmable clock divider output
- Configurable output power level from -10 dBm to +10 dBm, in 2 dB nominal steps
- Supply voltage range 1.9 V - 3.6 V, 2 low battery detection thresholds, preset to 2.4 V and 2.1 V
- Low supply current (Sleep Mode < 0.8 µA, RF transmission 9 mA @ +5 dBm)
- ESD protection up to ± 4 kV at all pins
- Operating temperature range -40° C to +85° C
- Green Package TSSOP-10

1.3 Applications

- Short range wireless data transmission
- Remote keyless entry transmitters
- Remote control units
- Wireless alarm systems
- Remote metering
- Garage door openers

1.4 Order Information

Type	Ordering Code	Package
TDA5150	SP000300415	PG-TSSOP-10

1.5 Key Features overview

1.5.1 Typical Application Circuit
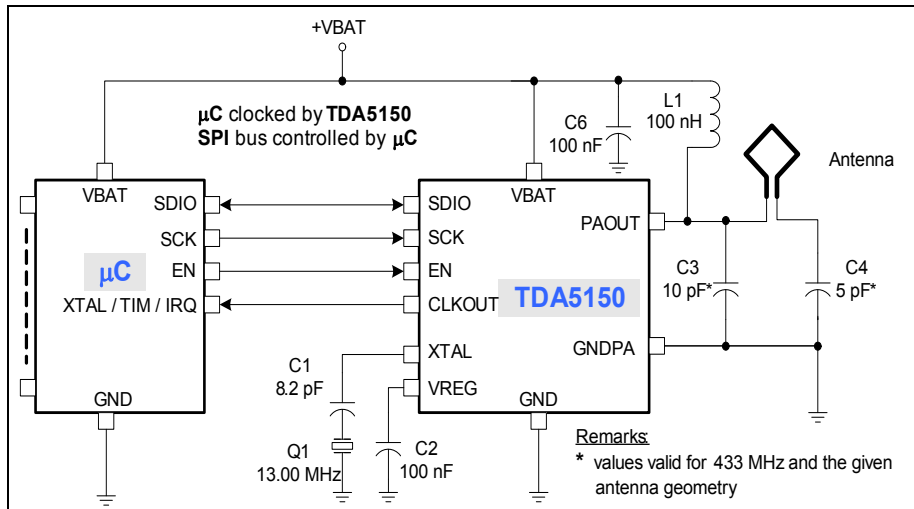
Figure 1   Minimum component count application circuit

The TDA5150 application circuit shown demonstrates the ease and simplicity of an intelligent transmitter implementation. The µC configures the TDA5150 via 3-wire SPI, the SDIO line is used at the same time to transfer data on SPI bus and as digital data input into the RF modulator. The CLKOUT line may be used as clock source for the µC or as a timer for bitrate generation.

The matching shown is an example for a loop antenna application. Different antenna types (electrical monopole or dipole, magnetic loop etc.) as well as different layout versions might require component values which can differ from those given in above example. The antenna geometry has a major influence on the antenna impedance and consequently on the component values in the matching network.

1.5.2 Sigma-Delta fractional-N PLL with High Resolution

This type of PLL offers a multitude of advantages compared to fixed, integer division ratio PLLs.

In the reference oscillator circuit the same crystal can be used for all of the RF bands and channel frequencies (for example 13 MHz and alternatively 13.56 MHz crystals are listed in the Evaluation Board descriptions **Chapter 3.2 Infineon Evaluation Board V2** and **Chapter 3.3 Infineon Evaluation board V1.1** for all versions, independently of intended operating frequency band).

Thus dedicated crystals for each carrier frequency (like by integer-N type synthesizers) are no longer required, and this is a significant advantage for systems based on the TDA5150 transmitter chip.

However by choice of crystal frequency the phenomenon known as occurrence of fractional-N spurs, shall be considered and the reference frequency selected in such way, to avoid it. The phenomenon and the countermeasures which should be taken are described in detail in **Chapter 2.4.6.1 Fractional Spurs**.

The PLL allows a direct and highly accurate (G)FSK digital modulation. This leads to reduction of spurs and harmonics versus performance of legacy transmitters, devices which are mainly using crystal frequency pulling in order to achieve FSK modulation.

Synthesizer resolution down to 7 Hz for carrier frequency generation makes possible accurate adjustments and fine tuning. It allows at least the partial correction and reduction of inherent frequency tolerances, which are due to crystal manufacturing process.

In the same way it is possible to cancel the effects of temperature dependent frequency drift (introduced by the crystal used for reference frequency generation) and a temperature-dependent retune process could be applied, by means of small frequency steps, at the carrier frequency level.

Note: the correction of the temperature related frequency drift (caused by the quartz crystal) assumes the availability of a temperature measurement sensor in the host system.

1.5.3 Reduction of Spurs and Occupied Bandwidth

The direct FSK modulation and in addition the Gaussian FSK (GFSK) reduces spurs and occupied bandwidth. Bandwidth reduction is exemplified below.
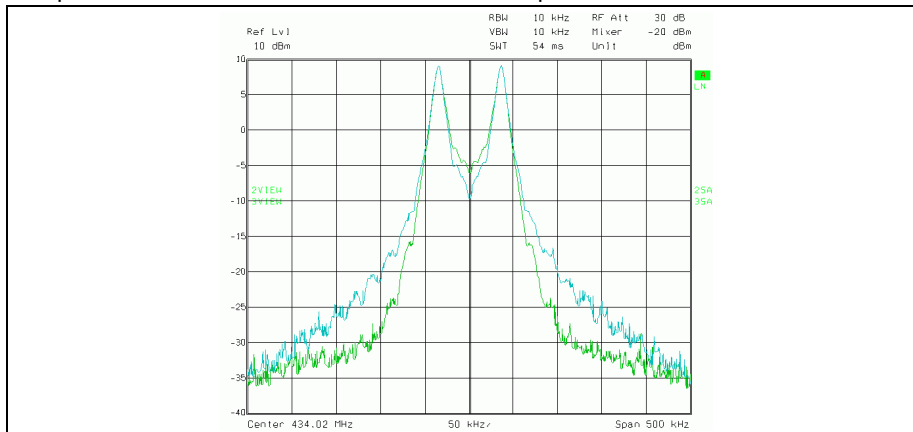
Figure 2 **Spectrum of RF-signals with equal frequency deviations ($\pm$ 35kHz), same 20 kBit/s datarate and encoding (NRZ). Blue plot corresponds to FSK modulation and green to GFSK. Observe the difference in terms of occupied bandwidth between the signals.**

1.5.4 Asynchronous and Synchronous Transmission

TDA5150 offers a simple asynchronous transmission mode (transparent modulation), whereby after the configuration word is downloaded into the transmitter's SFRs (via SPI bus) the data bitstream is output on the SDIO line and fed into the transmitter's RF modulator.

The CLKOUT signal can be used either as clock line for host µC or, alternatively, as timer base (flag) for bitrate generator (this last function have to be implemented in the µC).

In this mode, the bitrate is solely imposed and controlled by the µC software.

GFSK modulation and ASK shaping options are allowed in Asynchronous Mode.

In Synchronous Transmission Mode the bitrate is solely under the transmitter's control and fully timed by the TDA5150. The CLKOUT is used to alert the µC about the request for next data bit.

The µC may have a higher allowable processing delay tolerance, typically the duration of 1/2 bit, before sending the corresponding bit via SDIO line to transmitter.

Usage of data encoding option is allowed in Synchronous Mode.

1.5.5 Integrated Data Encoder

TDA5150 comprises a Data Encoder which automatically generates encoded data from a regular (NRZ) bitstream. The supported data encoding modes are:

- Manchester code
- Differential Manchester code
- Bi-phase space code
- Bi-phase mark code
- Miller code (Delay modulation)
- NRZ
- Scrambling (PRBS9 generator)

All the encoded bitstreams can be level inverted (as part of the encoding option). The scrambling module (PRBS9 generator) is intended to be used for generation of pseudo-random data patterns (rather for Tx test scopes) or for basic level data encryption.

1.5.6 Fail-Safe Mechanism

The Transmitter Status Register reports about failures such as: Brownout event, PLL lock error, VCO auto-calibration error and Register Parity error.

The Register Parity is a special safety feature. Each SFR (Special Function Register) has an extra parity bit which is automatically calculated and stored during a SFR write operation. During transmitter active state these parity bits, belonging to SFR content are continuously recalculated and compared against the stored values. Changes in the contents of writable SFRs without write command generate an SFR error event and an error flag is set.

To prevent erroneous transmissions (on wrong frequency or with erroneous modulation parameters) the activation of Fail-Safe mechanism is coupled with deactivation (switching off) of the RF Power Amplifier stages.

This additional feature inhibits the transmission if errors occur, thus preventing the transmission of erroneous datagrams or on false frequency

For details see the associated SFR description, and their interaction with the Fail-Safe Mechanism, as described in **Chapter 2.4.10**.

1.5.7 TESEUS - Configuration and Evaluation Tool

TESEUS for TDA5150

File   Edit   Mode   Help

General / XOSC / Encoding / SIB | PLL | PA / Modulation | Transmission

TESEUS - TDA5150 Evaluation and System EmUlation Software

XTAL Settings
Xtal Freq. [MHz]: 13.000

Encoding
Encoding Mode:
NRZ

Data Inversion:
Not Inverted 0 — 1 Inverted

PRBS Start Value: 0

Unscrambled Bit Count: 0

CLKOUT Settings
CLKOUT
Disabled 0 — 1 Enabled
CLKOUT Selection:
Prescaler Counter
☐ CLKOUT = XTAL/16

Calculator

Afterscaler CLK Div:
Prescaler CLK Div:
BDRDIV:

CLKOUT [kHz]: 812.500
Resulting Bitrate [kbps]: 3.149
Resulting Chiprate [kbps]: 6.298

TX Configuration Registers

Go2Sleep

Goto Standby
Off 0 — 1 Standby

Power Down XOSC & Bypass
Enable 0 — 1 Power Down

Failsafe Mechanism
On 0 — 1 Off

Frequency Hopping
Enabled 0 — 1 Disabled

Voltage Supply
Voltage Regulator
Vreg [V]: 2.1 V

SIB Parameters
Vbat (from SIB) [V]: 3.0
SCK Frequency [kHz]: 50.0

● Brownout Error   ● Battery Voltage Drop under 2.4V   ● PLL Lock Error
● VCO Autocalibration Failure   ● Battery Voltage Drop under 2.1V   ● Parity Error
● TDA5150 detected   ● Interface Board connected

Read Status Registers

Update Registers

Figure 3   TESEUS - First Tab of User Interface screen

TESEUS is a user-friendly, comfortable tool, suitable for generation of TDA5150 configurations and testing them using a TDA5150 Evaluation Board. Configurations can be automatically converted into register lists and implemented in C-code.

The pattern to be transmitted is written into a datagram or TX-file. A commented example TX-file can be generated by TESEUS. This file might be edited using a standard text file editor, if changes of the transmit parameters and data patterns are required.

Note: for further details please consult the TESEUS User's Manual document, downloadable from Infineon Technologies AG web-page, free of charge.

2 TDA5150 Functional Description

2.1 PIN Configuration, Pin-out


```
         EN  1              10  SDIO / DATA
       XTAL  2   TDA 5150    9  SCK
        GND  3               8  CLKOUT
       VREG  4               7  GNDPA
       VBAT  5               6  PAOUT
```
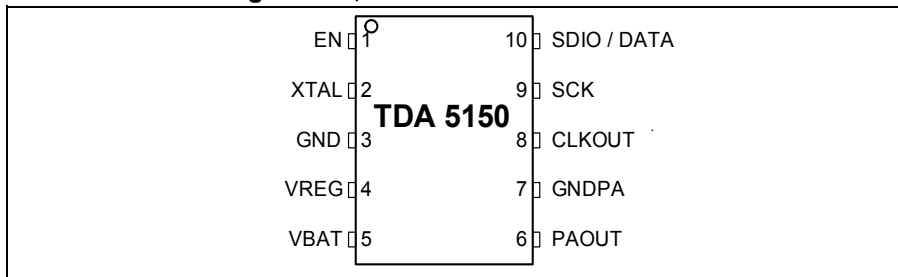
2.2 Pin Definition and Pin Functionality

Pin No.	Name	Pin Type	Equivalent I/O Schematic	Function
1	EN	Digital Input		Enable 3-wire bus
2	XTAL	Analog Input		Crystal Oscillator

Pin No.	Name	Pin Type	Equivalent I/O Schematic	Function
3	GND	Supply	XGND / GNDD / GNDA — GND Triple bond	Power supply ground
4	VREG	Analog Output	VBAT — Voltage Regulator — VREG / VDDA — VREG Double bond — GNDD / GNDA	Voltage Regulator output
5	VBAT	Supply	VBAT — Voltage Regulator — VREG	Power supply (**+**)

Pin No.	Name	Pin Type	Equivalent I/O Schematic	Function
6	PAOUT	RF-PA Output		RF Power Amplifier Output (open drain)
7	GNDPA	Analog GND		RF Power Amplifier Ground return

Pin No.	Name	Pin Type	Equivalent I/O Schematic	Function
8	CLKOUT	Digital Output		Programmable Divided Clock

Pin No.	Name	Pin Type	Equivalent I/O Schematic	Function
9	SCK	Digital Input		Clock 3-wire bus
10	SDIO	Digital Input/ Output		Data 3-wire bus

2.3 Functional Block Diagram
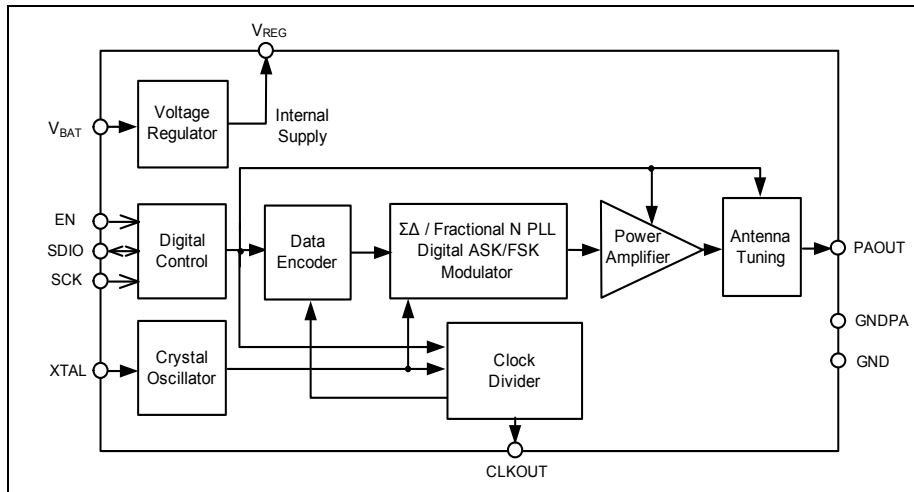
Figure 4   TDA5150 Block Diagram

TDA5150 is an SPI configurable fully integrated ASK/FSK/GFSK RF transmitter for the 300-320 MHz, 433-450 MHz and 863-928 MHz frequency bands. The input datastream, applied to the digital SDIO line is transposed and appears as modulated RF-signal, at the output of the integrated RF power amplifier. Signal encoding and spectrum is in accordance with the chosen modulation type (i.e ASK, FSK or GFSK) and encoding scheme.

TDA5150 contains following major blocks which extend the functionality compared to legacy RF transmitters:

- An on-chip voltage regulator is delivering 2.1 V nominal supply voltage for the transmitter's functional units. In addition, the battery voltage is monitored and battery low and brown out flags are set, if a critical supply voltage drop event occurs.

- For avoidance of erroneous transmissions, the brownout flag is coupled with the RF Power Amplifier state control. If a brownout or critical voltage drop event occurs, the RF Power Amplifier is automatically switched off, as part of the Fail-Safe philosophy. The mechanism is explained in detail in **Chapter 2.4.8.5**

- The crystal oscillator and the associated clock divider(s) generate the required clock signals. There is an output line (CLKOUT) which may be used to clock a host µC, or for bit rate generation.

- A digital control logic, accessible for user via the SPI bus allows flexible and fast (re)configuration. At the same time it offers a simple but powerful Fail-Safe mechanism, which enhances the reliability of the transmissions

- The data encoder synchronizes the bitstream to be transmitted with the internal bit clock. It supports different types of Manchester and Bi-Phase encodings and is able to generate PRBS9 pseudo-random patterns. The internal data encoder can be bypassed, allowing transmissions in direct (transparent) mode.

- The core element of the transmitter is the sigma-delta fractional-N PLL Synthesizer, used for carrier frequency control and as part of the digital modulator as well. It covers the frequency bands 300-320 MHz, 433-450 MHz and 863-928 MHz with outstanding frequency resolution. Only one, fixed frequency crystal (e.g. 13 MHz) is required for reference frequency generation. The synthesizer is characterized by short settling time. It is also used as direct FSK modulator, and together with a Gaussian filter, implemented by means of lookup table offers the functionality of a direct GFSK modulator.

- The integrated Power Amplifier is able to deliver up to +10 dBm output power into a 50 Ω load (usually the antenna) via an external impedance matching network. In addition there are integrated capacitors, connected between GND and the RF-PA output, over SFR controlled on/off switches. These capacitors are elements of a software controlled antenna tuner. They may be used to fine-tune (adjust) the PA-output to Load matching network impedance, and thus to maintain good VSWR values over a wider frequency band. This is particularly useful if the transmitter is operated not only on a single frequency but in multichannel mode, with considerable spread between the channels.

2.4 Functional Description

2.4.1 Special Function Registers

TDA5150 is configurable by programming the Special Function Register bank (abbreviated SFRs) via the SPI interface.

Terminology and notations related to TDA5150 SFR set, list of symbols and programming restrictions are given in **Chapter 22 Register Terminology**.

Detailed description of SFR map, programming, usage and content explanations are found in **Chapter 2.4 Functional Description** and **Chapter 2.5 Digital Control (SFR Registers)**.

2.4.2 Power Supply Circuit

An internal **voltage regulator** generates a constant supply voltage (2.1 V nominal) for most of the analog and digital blocks.

An external capacitor (100 nF nominal value) connected between VREG (pin 4) and GND (pin 3) is necessary to guarantee stable functionality of the regulator.

The regulated voltage on VREG pin is not adjustable by user and it is not allowed to connect any additional, external loads to this pin, but the above mentioned decoupling capacitor.

In **STANDBY** state, a special low-power voltage regulator is activated, which is supplying only the SPI bus interface, the SFR registers and the system controller.

In order to further reduce the current consumption, and keeping in mind that leakage currents can steeply increase by high temperatures, an additional low-power state, denoted **SLEEP** was defined. In this state most of the digital part is disconnected from the regulator (VREG). Only the SPI bus interface remains active. As a consequence, further power saving is achieved, but register content is lost by entering this mode.

See **Chapter 2.4.9 Operating Modes** for further informations.

2.4.2.1 Brownout Detector

A **Brownout Detector** (abbreviated **BOD**) is integrated into the TDA5150 transmitter.

Brownout is a condition where the supply voltage drops below a certain threshold level. By brownout events the integrity of SFRs can not be guaranteed, even if the dropout's duration is very short.

During active states, BOD monitors the VREG pin; during **STANDBY**, it monitors VBAT and VREG supply lines.

Table 1   BOD Thresholds

Description		Monitored @	min	max
Brownout Detection Level—Active State	VBDR	VREG	1.7 V	1.8 V
Brownout Detection Level—StandBy State	VPDBR	VREG & VBAT	0.7 V	1.7 V

If the BOD detects a brownout, the Power Amplifier is switched off and the SFRs are reset. The device is then forced to restart from the Power Up Reset condition. This ensures that the device is always in a well-defined logic state.
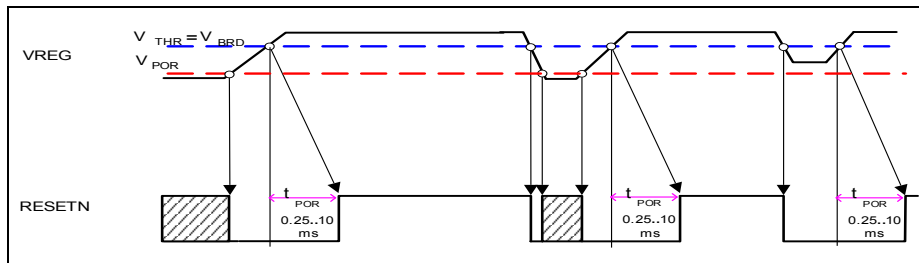
Figure 5   Power-on Reset/Brownout Detector

Brownout is indicated by bit BROUTERR (0x01.2) within SFR *TXTSTAT* (0x01).

Note: The BOD itself can not be used to guarantee the correct operation of analog sections, where the minimum operating voltage is defined to be 1.9 V; as this is larger than the maximum BOD voltage. In other words, in case of a supply voltage drop, the voltage region which is critical for reliable operation of the analog sections (min 1.9V) is reached before the brownout detector triggers (between 1.8 - 1.7V).

See also **Chapter 4.2** for operating voltage limits.

2.4.2.2   Low Battery Detector

TDA5150 has an embedded **Low Battery Detector** (**LBD**) block. In active modes, **LBD** monitors the voltage on VBAT supply line (pin 5). **LBD** has two activation thresholds, set to 2.4 V and 2.1 V. The status regarding supply voltage below threshold events can be updated by reading from SFR *TXSTAT*, bits 4 and 5 (0x01.5:4). These LBD flags are cleared after every transmission start. The LBD might be used as early warning for low battery voltage state (but before the battery voltage is dropping below the critical value, which renders normal operation capability).

2.4.2.3   SFRs related to Supply Voltage monitoring

ADDR 0x01		**TXSTAT—Transmitter Status Register**					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
1	n.u.	LBD_2V1	LBD_2V4	VAC_FAIL	BROUTERR	PARERR	PLLLDER
/	/	r/0	r/0	c/0	c/1	c/0	c/0

Bit 7	1		Set to 1, mandatory
Bit 5	LBD_2V1		battery low detected, threshold at 2.1 V -
Bit 4	LBD_2V4		battery low detected, threshold at 2.4 V
Bit 3	reserved		reserved
Bit 2	BROUTERR		Brown out event
Bit 1	PARERR		Parity error
Bit 0	PLLLDER		PLL lock detector error
Comments			
LBD_2V1	Battery voltage drop below 2.1 V detected if **1**. In standby mode, this bit is invalid.		
LBD_2V4	Battery voltage drop below 2.4 V detected if **1**. In standby mode, this bit is invalid.		
BROUTERR	Brownout event detected if **1**.		
PARERR	Parity error detected if **1**.		
PLLLDERR	PLL lock error detected if **1**.		

2.4.3   Digital Control (3-wire SPI Bus)

The control interface is a 3-wire Serial Peripheral Interface (SPI), which is used for device control and data transmission.

2.4.3.1   SPI Pin Description

- **EN**   **- enable input** with embedded pull-down resistor. High level on EN input enables the SPI transmission. The rising edge of the EN signal triggers the selection of the active SCK edge (for the consequent data transfer, until the EN line goes again in low state) and transmission/ sampling of data between the device and the microcontroller can start. For details refer to **Figure 6** and **Figure 7**.
- **SDIO**   **- 3-state input/output** This bidirectional line is used for data transfer between the TDA5150 and external host (usually a µC). On-chip pull-down resistor is connected to this pin. The load drive capability is listed in **Table 4.3**.

- **SCK   - clock input** pin with embedded pull-down resistor. If SCK is at low level while EN goes high, the incoming SDIO data is sampled by falling edge of the SCK and the output SDIO data is set by the rising edge of SCK. Contrariwise, If SCK is at high level when EN goes high, the SDIO data is sampled with the rising edge of the SCK clock and output on SDIO by falling edge of the SCK clock. For details refer to **Figure 6** and **Figure 7**.

SPI commands are started by the rising edge on the EN line and terminated by the falling edge on EN.

The available Burst Write mode allows configuration of several SFRs within one block access, without cycling the EN line Low - High - Low for each individual byte. By keeping the EN line at High level, subsequent bytes could be sent, and the byte address counter is autoincremented, thus speeding up the transfer on the SPI bus.

A self-explaining diagram is found here: **Chapter 9 Timing Diagrams of 3-wire SPI**.

The active edge of SCK (during SPI commands) is programmable, and it is determined by the level on SCK line at the moment of activation of the EN line (rising edge on EN).

If SCK is low at that moment, the incoming SDIO data will be sampled with the falling edge of SCK, and output by rising edge of SCK (see **Figure 6** below).
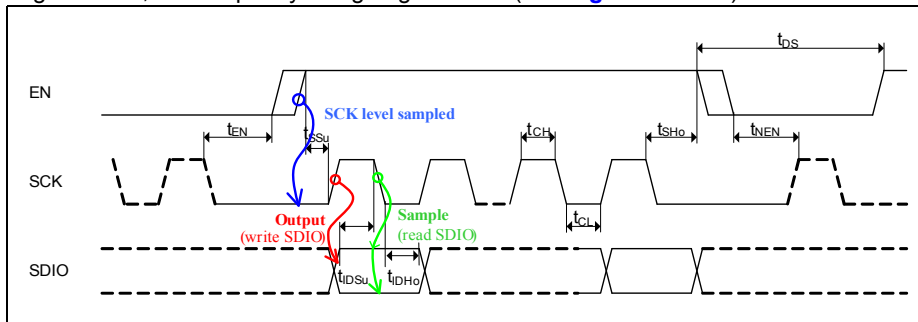
Figure 6   SPI Timing — SCK low at rising edge of EN

If SCK is high during occurrence of rising edge on EN, incoming SDIO data is sampled with the rising edge on SCK, and output by falling edge of SCK, as illustrated in **Figure 7**.
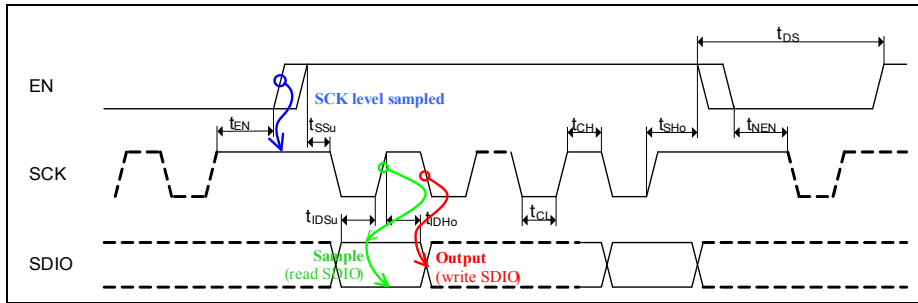
Figure 7   SPI Timing — SCK high at rising edge of EN

2.4.3.2   SPI XOR Checksum

The SPI block includes a safety feature for checksum calculation. This is achieved by means of XOR operation between the address and the data during write operation of SFR registers. The checksum is in fact the XOR of the data 8-bitwise after every 8 bits of the SPI write command. The calculated checksum value is then automatically written into SFR *SPICHKSUM* (0x00) and can be compared with the expected value. By executing a read operation of SFR *SPICHKSUM* (0x00) the register content is automatically cleared (after read). Read access to any of the other readable SFRs does not influence the SFR *SPICHKSUM*.
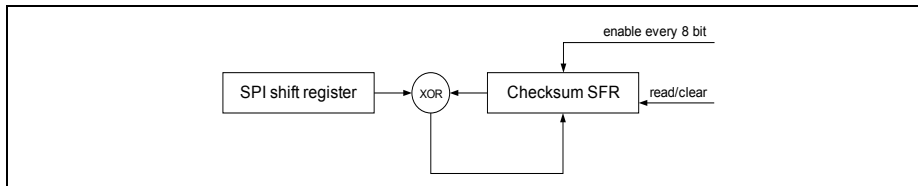
Figure 8   Generating the Checksum of SFRs, block diagram

Example:

Write to SFR address 0x04, data 0x02, address 0x05, data 0x01

Bytes transmitted via SPI	Result in Checksum Register
0000 0100	0000 0100
0000 0010	0000 0110
0000 0101	0000 0011
0000 0001	0000 0010

After writing into the registers, content of checksum SFR *SPICHKSUM* (0x00) will be 0x02.

2.4.3.3 Command Byte Structure

First byte of each SPI sequence is the **Command Byte**, with the following structure:

Function Code		Command Byte Configuration					
C1	**C0**	**Address**					
x	x	A5	A4	A3	A2	A1	A0

The first 2 bits **C1, C0** of the Command Byte are the function code field**.**

They define the command to be performed, according to the following table:

C1	C0	Function Code Configuration Bits
0	0	**Write** data into SFR register <A5:A0> field contains the SFR register's address There are 2 possible write modes (controlled by state of EN line): 1. write to a single address 2. burst mode write (with address auto increment)
0	1	**Read** data from SFR, <A5:A0> points to register address
1	0	**Reserved** (do not use)
1	1	**Transmit Command Byte** Bits <A5:A0> within this byte define the transmission parameters (see **Chapter 2.4.3.4 Transmit Command** for command fields).

The **Write / Read Command** bytes are used for device control. Bit fields <A5:A0> within **Command Byte** are used to specify the addressed SFR register. An overview and register map is given in **Chapter 2.5.1 SFR Register List**.

There are two ways to program the SFR registers:

1. by sending Write commands individually, for each register which should be written.
2. by sending a Burst Write command, which allows sequential programming (of registers found at subsequent addresses).

Attention: Writing to the address space beyond the valid SFR address range [0x04 - 0x27] is prohibited, as it may lead to system malfunction.

2.4.3.4 Transmit Command

The **Transmit Command Byte** is used for **data transmission**. It precedes the datagram to be transmitted. The Transmit Command Byte format is described in the following table:

C1	C0	Transmit Command Configuration		
		Bit	Function	Value, description
1	1	A	Data sync	0: off 1: on (at the same time Bit C - Encoding must be set also to 1 --> Int. Encoding)
1	1	B	PA mode	0: PA off at the falling edge of EN (synchronized with bit-rate if bit A is high) 1: SDIO/DATA is latched at the falling edge of EN, PA stays on, TX data are kept constant. After the time-out of 65536 / f_{sys} which is ~5 ms for a 13 MHz crystal, PA and PLL are switched off.
1	1	C	Encoding	0: off 1: on (selects SFR register for encoding Bit A must be also set to1 --> Data sync)
1	1	D	Pwr. level/ModSetting	0: selects **PowerLevel/Modulation Setting1** 1: selects **Power Level/Modulation Setting2**
1	1	<E,F>	Frequency selection	0 (00): frequency channel **A** selected 1 (01): frequency channel **B** selected 2 (10): frequency channel **C** selected 3 (11): frequency channel **D** selected (for description of programming the frequency channels **A**..**D** consult **Chapter 2.4.11.3 Channel Hopping**)

Note: After the last configuration bit for a new transmission was sent, a break of at least 100 µs must be provided in order to achieve PLL settling and lock on the selected channel frequency.

2.4.3.5 Timing Diagrams

In the following timing diagrams the 4 possible SPI commands are shown. The examples are valid for the case of SCK is low when EN line goes from Low to High (rising edge).

Therefore the incoming SDIO data is sampled at the falling edge of SCK, and data is output on SDIO line by the rising edge of SCK signal.
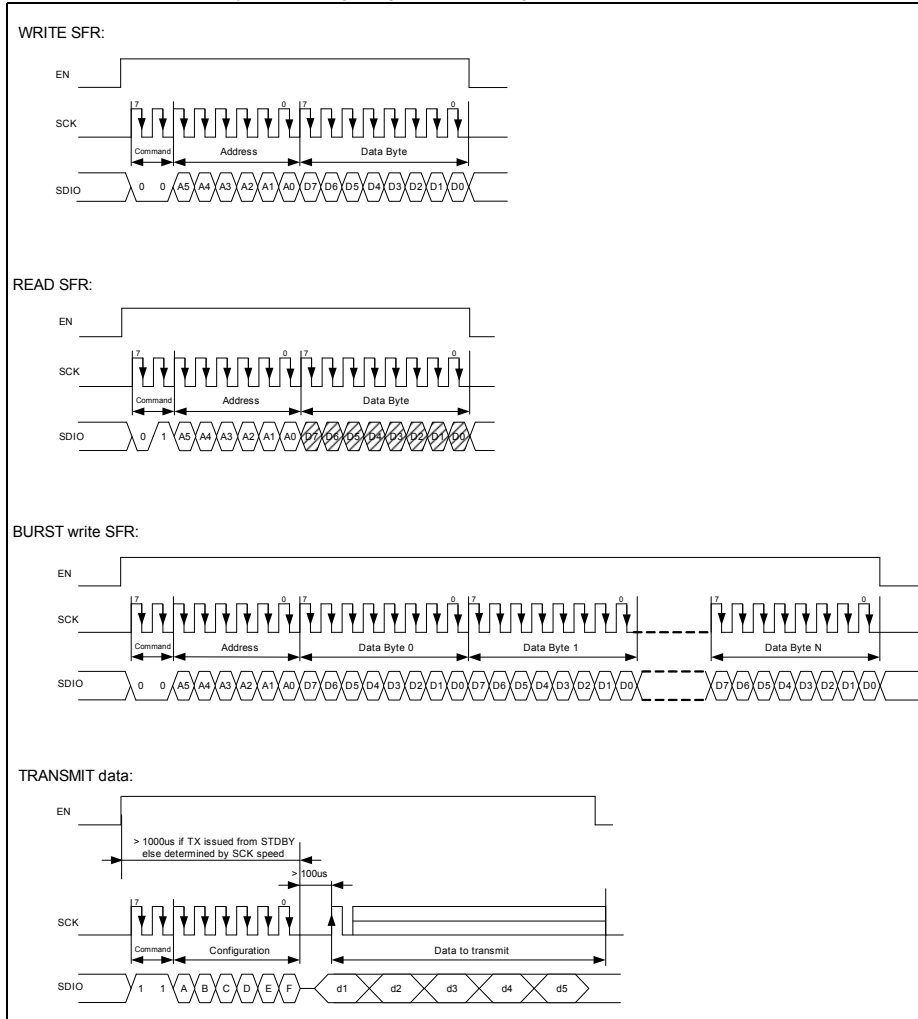
Figure 9   Timing Diagrams of 3-wire SPI

Note: In order to minimize cross-talk between SDIO and SCK lines, it is recommended to keep the SCK either Low or High, but avoid transitions during RF transmission.

Previous **Chapter 2.4.3.4 Transmit Command** gives an in-depth overview of Transmit Command structure.

2.4.4 Data Encoder

The **Data Encoder** is used in the so-called Synchronous Transmission Mode.

A description of this transmission mode is found in **Chapter 2.4.11.2 Synchronous Transmission**.

In Synchronous Transmission Mode the Encoder has to be used. If no specific encoding of SDIO data shall be done, select NRZ as encoding scheme.

Definition: ´bit-rate´ is the number of transmitted bits per second and expressed in [bits/sec]. Besides NRZ all the other implemented encoding methods split a single bit into two elementary parts, the so-called chips. Therefore we also talk about a chip-rate, which is an "n" multiple of the data-rate.

For NRZ (which means no extra encoding) n = 1 (data-rate = chip-rate), and for all other implemented encoding methods n = 2, or the chip-rate is twice the bit-rate.

The TDA5150 supports the following encoding schemes:

• Manchester code

• Differential Manchester code

• Bi-phase space code

• Bi-phase mark code

• Miller code (Delay modulation)

• NRZ

• Scrambling (PRBS9 generator)

All encoded bitstreams can be level inverted (as part of the encoding option)
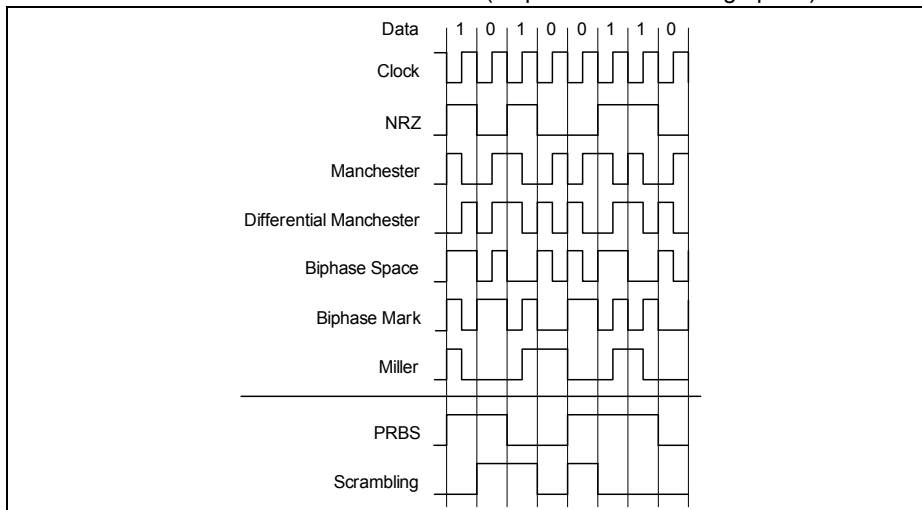
Figure 10   Coding Schemes

The Data Encoder option is enabled by bit C of Transmit Command (Data Encoder enabled if bit C = 1). See also **Chapter 2.4.3.4 Transmit Command** for command structure. If the Data Encoder is enabled, bit A must to be set for Synchronous Transmission Mode as well (Bit A = 1 and Bit C = 1, this last to enable encoding).

The selection of encoding mode is done via bits ENCODE (0x05.2:0) of SFR *TXCFG1*. (0x05). At the same time bit INVERT (0x05.3) of the same SFR enables the inversion of an already encoded bit stream.

The encoding activation entry point can be configured in SFR *ENCCNT* (0x27).

By initializing the SFR *ENCCNT* (0x27) with 0x00, already the first bit is encoded. If for example ENCCNT = 0x10, the first 16 bits should remain unencoded. This method allows to keep the first N bits unencoded within a datagram (in fact plain NRZ), followed by encoded bits (of the same datagram).The encoding scheme is selected by bit-field ENCMODE (0x05.2:0) of SFR *TXCFG1*.

2.4.4.1 PRBS9 Generator, Data Scrambler

TDA5150 contains a PRBS9 generator, suitable for generation of pseudo-random NRZ data patterns. The PRBS9 datastream satisfies (in general lines) the requirements for random distribution (even if longer PRBS polynomials come closer to "true" random distribution) and therefore it may be useful for Transmitter RF tests, for instance by measurement of the "Occupied RF Bandwidth" test case.

In addition the generated PRBS9 pattern can be XOR'ed with a real data pattern sent by the microcontroller and this way "scramble" this data pattern.

Attention: The data scrambling functionality is intended to enhance the clock recovery performance of the Receiver Station. It is not suitable, as stand-alone encryption method for security applications!

PRBS9 is a well known standard in the class of pseudo-random patterns, and is implemented within the TDA5150 by a subpart with following block diagram:
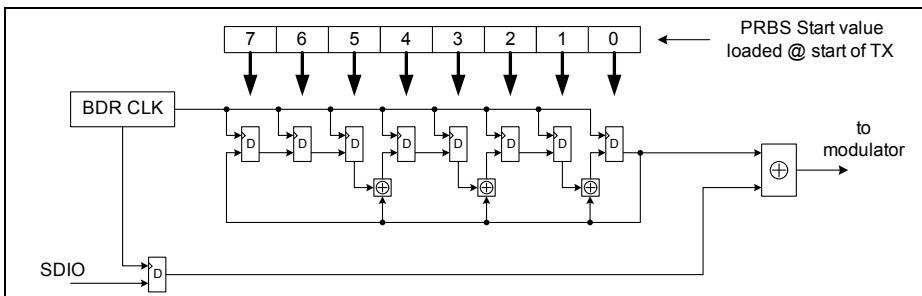
Figure 11   PRBS9 Generator and Data Scrambler

The feedback branches within the PRBS9 generator are fixed (as shown above), but the PRBS generation can be influenced by SFR configuration in the following manner:

- A start value for the PRBS9 Generator can be programmed in SFR *PRBS Start Value* (0x08). The reset value is 0xAB (10101011). Choice of 0x00 as start value is not allowed, because the output of PRBS9 Generator should "lock" and will never go to High. The PRBS Start Value is loaded into the PRBS9 Generator at the start of each transmission.

- If the Data Scrambler is used, the start of scrambling can be configured in SFR *ENCCNT* (0x27). If *ENCCNT* is 0, already the first bit is XOR'ed with PRBS9. If for example ENCCNT = 0x10, the first 16 bits stay unscrambled. This is necessary if a data frame should have always the same wake up and synchronization part, but the payload should be pseudo-random for sensitivity measurements or to enhance the clock recovery on the receiver side.

2.4.4.2 SFRs related to Transmitter Configuration and Data Encoding

ADDR 0x05		TXCFG1—Transmitter Configuration Register 1					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2SLEEP	ASKFSK2	ASKFSK1	ASKSLOPE	INVERT	ENCMODE	ENCMODE	ENCMODE
cw/0	w/0	w/1	w/0	w/0	w/1	w/0	w/1

Bit 3	INVERT		Data inversion			
Bit <2:0>	ENCMODE		Encoding mode bit <2:0>			

INVERT	Encoded data inversion enable			
	0: data not inverted		**1**: data inverted	
ENCMODE	Encoding mode, code selection (3 bits)			
	000: Manchester	**010**: Biphase Space	**100**: Miller (Delay)	**110**: Scrambling (PRBS)
	001: Differential Manchester	**011**: Biphase Mark	**101**: NRZ	**111**: not used (data = 0)

ADDR 0x08		PRBS—PRBS Start Value					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PRBS	PRBS	PRBS	PRBS	PRBS	PRBS	PRBS	PRBS
w/1	w/0	w/1	w/0	w/1	w/0	w/1	w/1

Bit <7:0>	PRBS		PRBS start value bit <7:0>

PRBS	PRBS start value (8 bits). The PRBS generator uses this value as a starting value after begin of each transmission.

ADDR 0x27		ENCCNT - Encoding start bit counter					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	ENCCNT		Encoding start bit counter bit <7:0>

ENCCNT	Sets the number of bits on start of a telegram which shall be sent unencoded or unscrambled before encoder/scrambler is switched on. This feature is used e.g. for send of unscrambled synchronization patterns first, followed by encoded payload.

2.4.5 Crystal Oscillator and Clock Divider

The Crystal Oscillator is a single pin, negative-impedance-converter type oscillator (**NIC**), and provides the reference frequency for the phase locked loop and clock signal for the sigma delta modulator.
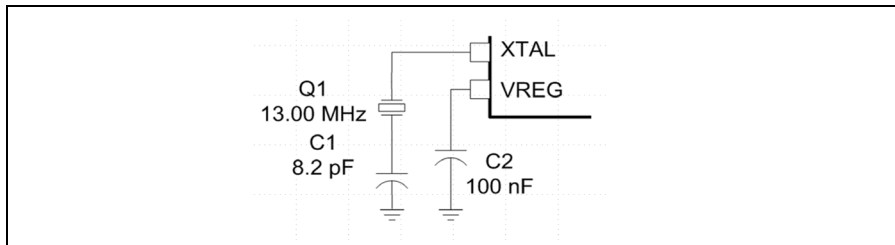
Figure 12   Oscillator Circuit

The allowed crystal frequencies are in the 12 MHz to 14 MHz range. A load capacitor (C1) is connected in series with the crystal. The value of the load capacitor depends on crystal parameters and to some extent even the parasitic capacitance of the PCB layout (track and load capacitor pad) has a slight, but measurable influence. The shown values are exemplifications, and valid for the crystal used on IFX evaluation board. Please refer also to the crystal oscillator parameters listed in **Chapter 4 Electrical Characteristics** to select a suitable crystal type.

Attention: Theoretically any crystal frequency, within the frequency range specified above, can be used. In practice this freedom is limited by the potential occurrence of so-called Fractional Spurs (see Chapter 2.4.6.1 Fractional Spurs for details).

To avoid this unwanted effect, the crystal frequency must be chosen in such way, that the division ratio:

PLL division factor = (RF carrier frequency) / (crystal frequency)

shall give a fractional part (the part behind the decimal point) between 0.1 and 0.9.

For example a 13.56 MHz crystal should not be used for the carrier frequency of 868 MHz (resulting PLL division factor is 64.012 and the fractional part, of 0.012 is smaller than 0.1).

Note: In multichannel systems prior to settling for a reference oscillator frequency, each individual transmit frequency shall be checked for the PLL division factor (which must be within the 0.1 - 0.9 range) in order to avoid the occurrence of fractional spurs.

In addition the RF frequencies used for the FSK deviation are not allowed to cross the PLL division factor integer line (as in this case the lower and the higher FSK frequencies would have different integer part of PLL division ratio). However this 2nd criterion is automatically fulfilled if the rule for the fractional part range (stated above) is fulfilled.

2.4.5.1 The Bit-Rate Generator

The TDA5150 is able to generate a bit (or chip) clock by dividing the signal frequency output by the crystal oscillator.
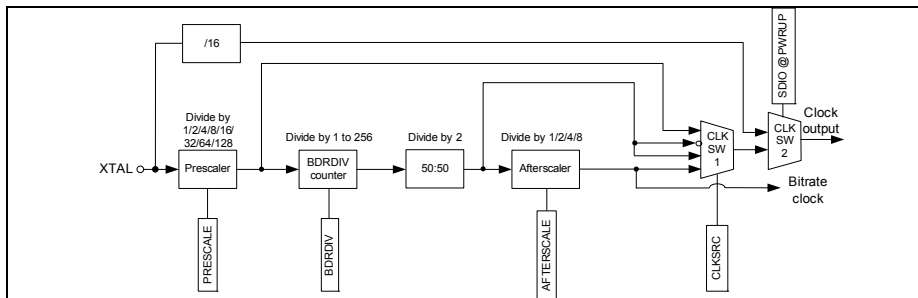
Figure 13   Bit-Rate Divider

In Asynchronous Transmission Mode the bitrate clock can be routed to CLKOUT pin and used by the µC as timer signal for bitrate generation.

In Synchronous Transmission Mode the bitrate clock is in addition used internally, for synchronization of the incoming bitstream.

The bitrate or chiprate is calculated according to the formula:

$$bitrate = \frac{f_{XOSC}}{PRESCALE \times (BDRDIV + 1) \times 2 \times AFTERSCALE}$$

2.4.5.2 The Clock Output

The TDA5150 offers a **clock output** signal **(CLKOUT)**, derived from the crystal frequency. It can be used as source for system clock of a µC or as bit (chip) clock to control the data rate as already described.

Different stages of the bit-rate divider can be routed to CLKOUT, as well as the output of the XTAL / 16 divider according to following rules:

• If SDIO = 0 when EN goes High, the output clock chosen as XTAL/16 by default.

• If SDIO = 1 when EN goes High, the output clock is selected as imposed by settings of SFR *CLKOUTCFG* (0x06). This is the configurator register for Clock pre- and afterscaler. Detailed description of the bit-fields is given in next **Chapter 2.4.5.3 SFRs related to Crystal Oscillator and Clock Divide**

If enabled, the CLKOUT starts toggling when the swing amplitude on crystal oscillator output reaches a certain threshold. This small delay is related to the oscillator startup time.

If disabled, no clock signal is output on CLKOUT, but it delivers a rising edge pulse after a reset event and stays high, signalizing that the crystal oscillator output already reached a stable level.

Note: If the CLKOUT line is used as system clock for a µC, keep in mind that in Synchronous Transmission Mode the delivered frequency is not highly stable in phase (it is affected by jitter), due to the fact that the related counters are synchronized with each Transmit Command. The reasons for this and the synchronization procedure itself are explained in **Chapter 2.4.11.2 Synchronous Transmission**.

2.4.5.3   SFRs related to Crystal Oscillator and Clock Divide

ADDR 0x06		CLKOUTCFG - Clock Pre- and Post-scaler					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CLKSRC	CLKSRC	AFTERSCAIE	AFTERSCALE	PRESCALE	PRESCALE	PRESCALE	CLKOUTENA
w/0	w/0	w/0	w/0	w/1	w/0	w/0	w/1

Bit <7:6>	CLKSRC		Clock source selection bit <1:0> 00: after prescaler, 01: after BRDIV counter 10: after BRDIV counter inverted, 11: after afterscaler
Bit <5:4>	AFTERSCALE		Afterscaler selection bit <1:0> divide by 2^AFTERSCALE
Bit <3:1>	PRESCALE		Prescaler selection bit <2:0> divide by 2^PRESCALE
Bit 0	CLKOUTENA		0 if CLKOUT disabled. In this case CLKOUT goes High after crystal oscillator achieves stable level 1 if clock output enabled

ADDR 0x07		BDRDIV—Bit-rate Divider					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV
w/1	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	BDRDIV		BDRDIV divider bit <7:0>

2.4.6   Sigma-Delta fractional-N PLL Block

The **Sigma-Delta fractional-N PLL** contained on-chip is the key piece for the transmitter's RF functionality.

The advantage of a fractional-N PLL is that not only integer multiples of the crystal frequencies can be generated (N * f_{XTAL}) but also values of N-multiples plus a fractional part, yielding significantly more freedom in terms of reference frequency choice.

Part of the PLL is a VCO (Voltage Controlled Oscillator) operating at a center frequency of around 1.8 GHz. The VCO frequency is divided at first by 2 in a prescaler block with fixed division ratio. It is then further either divided by 1, 2 or 3 in the band select divider block, the resulting frequency at this block's output equaling the transmitter's RF operating frequency.

This RF signal is then further divided by a multimodulus divider block, down to a frequency which is in same range as that of the reference signal's. This last is input from the reference oscillator (i.e. generated by the crystal oscillator block).

The reference oscillator's frequency and the VCO's subdivided frequency, input from multimodulus divider are compared in a phase detector. At the output of the phase detector an error signal, proportional to the phase difference of the two, above mentioned signals is obtained. The phase-error signal is converted to a bipolar current by the charge pump and then fed into the loop filter (integrator).

The output of this integrator controls the VCO frequency via the tuning voltage and so closing the loop.

The multimodulus divider is able to switch between different dividing factors. Thus it is possible e.g. to divide by 2.5 by first dividing by 2, than by 3, followed by 2 again, and so on. The dividing factor is defined by the Sigma-Delta Modulator.

2.4.6.1 Fractional Spurs

Due to the behavior of Sigma-Delta PLLs, spurs are generated at frequencies close to the integer multiples of the reference frequency. These spurs are named **Fractional Spurs**. It is therefore recommended to use PLL division ratios (output RF frequency divided by crystal oscillator frequency) with fractional parts between 0.1 and 0.9, or in other words, the crystal frequency should be chosen in such way to yield for fractional part of the PLL division ratio values between 0.1 and 0.9.

2.4.6.2 Voltage Controlled Oscillator (VCO)

The Voltage Controlled Oscillator runs at approximately 1.8 GHz. This is 2, 4, or 6 times the desired RF output frequency, dependent on the frequency band settings.

To trim out production tolerances of the VCO, a VCO Auto Calibration mechanism (VAC) is implemented and runs automatically during each start up of the PLL. First a fixed, internal voltage is applied to the VCO, and the generated RF frequency is divided by 4 (or 8 for 868/915 MHz bands). The positive transitions are then counted during 32 system clock cycles. The result is compared to a configured number, derived from the desired RF frequency value (as the formula shows). The VCO is then automatically fine-tuned, before an RF transmission starts.

$$VAC\_CTR{<}8{:}0{>} \ = \ \frac{PLLINT{<}6{:}0{>} + \dfrac{PLLFRAC{<}20{:}0{>}+0.5}{2^{21} - 0.5}}{(ISMB{<}1{>} + 1) \times 4} \times VAC\_NXOSC{<}5{:}0{>}$$

where:

- VAC_CTR<8:0> has to be calculated according the formula above. It contains the optimal number of positive transitions to which the VAC-counter result is compared.

- PLLINT <6:0> and PLLFRAC <20:0> PLL divider SFRs used to define the desired RF frequency.
- ISMB<1> MSB of SFR register ISMB<1:0>, for band selection.
- VAC_NXOSC<5:0> always set to 32 decimal or 0x20, number of elapsed system clocks cycles used for VAC counting (i.e. total duration of counting).

2.4.6.3 Loop Filter Bandwidth

In order to provide a high grade of flexibility by choice of modulation parameters, a PLL with programable bandwidth have been implemented in the TDA5150.

The damping resistor(s), part of the active Loop Filter in the PLL can be selected by means of a 3 bit control field designated PLLBWTRIM in the SFR register *PLLBW (0x25.6:4)*.

Aiming the minima of RF-energy leaking into the adjacent channel(s) and/or out of band transmissions, the PLL bandwidth should be set as narrow as possible, but not less then 1.5 - 2 times the chip rate, if FSK or GFSK modulation is used.

For NRZ encoding the chip rate and data and bit rate are the same. For all other encoding schemes like Manchester or Bi-Phase etc. each bit is represented by two chips. Therefore the chip rate is the double of the bit rate for all encoding schemes, implemented in the TDA5150 encoder, excepting NRZ. The chip rate is not influenced by the fact whether the encoding is done by the on-chip Data Encoder or is realized externally. In order to maintain the PLL loop stability and for optimum performance, the chargepump and loop filter settings as listed in **Table 2** have to be used.

Note: current settings and associated loop filter damping factors are correlated.

Table 2			PLL recommended settings						
Loop filter damping resistor selection			Chargepump settings and resulting current					Resulting nominal PLL BW	Notes
PLLBW TRIM			**CPTRIM**				CP_current	[kHz]	
Bit2	Bit1	Bit0	Bit3	Bit2	Bit1	Bit0	[uA]		
0	0	0	*	*	*	*	*	*	not recommended
0	0	1	1	1	1	1	40	410	
0	1	0	1	1	0	0	32.5	375	
0	1	1	1	0	0	1	25	335	
1	0	0	0	1	1	0	17.5	270	
1	0	1	0	1	0	0	12.5	230	
1	1	0	0	0	1	0	7.5	175	
1	1	1	0	0	0	1	5	150	

2.4.6.4 PLL Dividers, RF Carrier Frequency

The divider chain contains a fixed divider by 2 (prescaler), a band select divider, dividing by 1 for the 915 and 868 MHz bands, by 2 for the 434 MHz band, and by 3 for the 315 MHz band. The divider ratio of this block is controlled by the field SMB0/1 of SFR *TXCFG0* (0x04.3:2).This band selection block is followed by the Multi-Modulus Divider, which is controlled by the Sigma-Delta Modulator. The RF frequency is set in the PLL Integer and PLL Fractional SFRs. Up to 4 different frequencies may be preconfigured in the same band (Frequency Registers A, B, C, D) and finally the active channel selected through the Transmit Command. This allows fast channel switching or hopping, without the need of downloading the complete reconfiguration data content into the corresponding SFRs (i.e the new PLL settings).

The RF frequency f_{RF} is derived from the crystal frequency.

$$f_{RF} = f_{XOSC} \times \left(PLLINT<6:0> + \frac{PLLFRAC<20:0> + \mathbf{0.5}}{2^{21} - \mathbf{0.5}} \right)$$

For the 315 MHz and 433 MHz bands (ISMB<1> = 0) PLLINT bit 6 is not used and only values from 15 to 43 are valid.

For the 868 MHz and 915 MHz bands (ISMB<1> = 1) all PLLINT bits are used and values between 54 and 84 are valid.

2.4.6.5 SFRs related to Sigma-Delta fractional-N PLL Block

ADDR 0x04		**TXCFG0—Transmitter Configuration Register 0**					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2STDBY	reserved	reserved	FSOFF	ISMB	ISMB	reserved	reserved
cw/0	w/0	w/0	w/0	w/0	w/1	w/1	w/0

Bit 7	GO2STDBY	**1:** activate STANDBY			
Bit 4	FSOFF	**0:** activate FAILSAFE			
Bit <3:2>	ISMB		RF frequency band bits		
ISMB		ISM band selection (2-bits)			
		00: MHz 300-320	**01**: MHz 433-450	**10**: MHz 863-870	**11**: MHz 902-928

ADDR 0x09, 0x0D, 0x11, 0x15	PLLINT*n*—PLL MM Integer Value Channel A, B, C, D						
	n: Channel A, B, C, D						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	PLLINT*n*	PLLINT*n*	PLLINT*n*	PLLINT*n*	PLLINT*n*	PLLINT*n*	PLLINT*n*
/	w/1	w/0	w/0	w/0	w/0	w/0	w/0
Bit <6:0>	PLLINT*n*			Integer division ratio bit <6:0>			
PLLINT*n*	Multi-modulus divider integer offset value (7 bits) for Channel **A**, **B**, **C**, and **D**						

ADDR 0x0A, 0x0E, 0x12, 0x16	PLLFRAC*n*0—PLL Fractional Division Ratio						
	n: Channel A, B, C, D (byte 0)						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRAC*n*0	PLLFRAC*n*0	PLLFRAC*n*0	PLLFRAC*n*0	PLLFRAC*n*0	PLLFRAC*n*0	PLLFRAC*n*0	PLLFRAC*n*0
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0
Bit <7:0>	PLLFRAC*n*0			Fractional division ratio bit <7:0>			
PLLFRAC*n*0	Synthesizer channel frequency value (21 bits, bits < 7:0 >), Fractional division ratio for Channel **A**, **B**, **C**, and **D**						

ADDR 0x0B, 0x0F, 0x13, 0x17	PLLFRAC*n*1—PLL Fractional Division Ratio						
	n: Channel A, B, C, D (byte 1)						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRAC*n*1	PLLFRAC*n*1	PLLFRAC*n*1	PLLFRAC*n*1	PLLFRAC*n*1	PLLFRAC*n*1	PLLFRAC*n*1	PLLFRAC*n*1
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0
Bit <7:0>	PLLFRAC*n*1			Fractional division ratio bit <15:8>			
PLLFRAC*n*1	Synthesizer channel frequency value (21 bits, bits < 15:8 >), fractional division ratio for Channel **A**, **B**, **C**, and **D**						

ADDR 0x0C, 0x10, 0x14, 0x18	PLLFRAC*n*2—PLL Fractional Division Ratio *n*: Channel A, B, C, D (byte 2)						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	n.u.	reserved	PLLFRAC*n*2	PLLFRAC*n*2	PLLFRAC*n*2	PLLFRAC*n*2	PLLFRAC*n*2
/	/	w/0	w/1	w/0	w/0	w/0	w/0

Bit 5	reserved		Set to 0. Users are advised to leave the state of this bit unchanged.
Bit <4:0>	PLLFRAC*n*2		Fractional division ratio bit <20:16>

PLLFRAC*n*2	Synthesizer channel frequency value (21 bits, bits < 20:16 >), fractional division ratio for Channel **A**, **B**, **C**, and **D**

2.4.7 Digital FSK/GFSK Modulator

The TDA5150 uses an integrated **direct FSK Modulator** for generation of RF-signals. By this method, and assuming NRZ data encoding, a positive frequency deviation (relative to nominal carrier frequency) occurs for a logical "1" of the already encoded data, and a negative frequency deviation for a logical "0" if the data inversion bit INVERT in SFR *TXCFG1* (0x05.3) is 0 (inversion OFF).

If the inversion function is active (INVERT bit is set to 1), the frequency shift directions are inverted (i.e. negative frequency deviation for logical "1" of input data and positive deviation for "0") for the same NRZ data stream.

*Note: If an encoding scheme other then NRZ is chosen, then data bits are decomposed in elementary chips, as shown in **Figure 10** and above two statements regarding input data inversion state (on/off) versus frequency shift direction are true, but apply instead of input data bit, to the resulting chips.*

The two frequencies, corresponding to positive and negative frequency shift are directly associated with specific divider numbers.

The modulation is achieved by switching between these two divider numbers and it takes effect under the control of data signal state (and encoding scheme, if other then NRZ).

The above described (divider ratio switching) method is called direct FSK modulation.

With direct FSK modulation a well controlled frequency shift can be achieved and the pullability of the crystal in the reference frequency oscillator circuit is no issue anymore, like by the classical FSK, where usually a reactance does "pull" the crystal frequency.

Data shaping is realized in the digital domain, as Gaussian filtered FSK (GFSK). It can be enabled by setting the GFBYP bit of SFR *GFXOSC* (0x1E.3) to 0.

The GFSK modulation scheme can further reduce the occupied RF bandwidth versus FSK modulation.

The ASK or FSK modulation type is selected by a bit-field in SFR *TXCFG1* (0x05). There are two possible setups, denoted **ModulationSetting1** and **ModulationSetting2**. A field within **Transmit Command** byte (referenced as bit D in **Transmit Command** byte) selects one of the two settings as active. This allows for fast commutation between modulation parameters without additional (re)configuration and repeated register downloads. See also **Chapter 2.4.3.4 Transmit Command** for details.
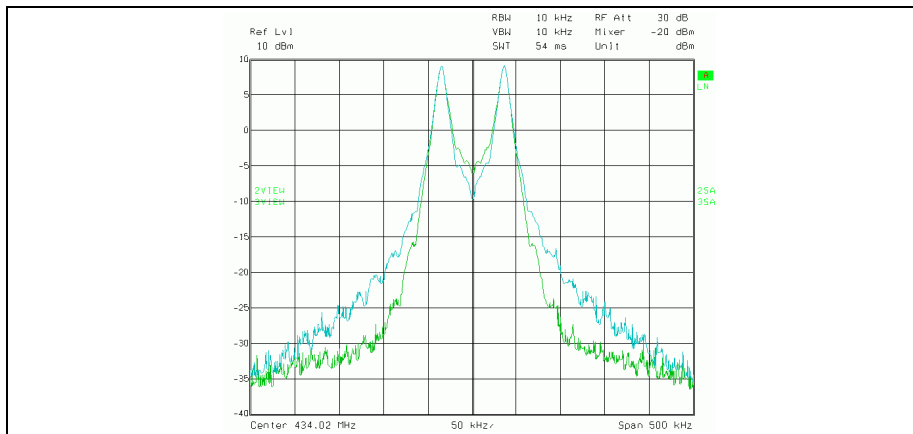
Figure 14   Spectrum for FSK and Gaussian FSK (GFSK) modulated RF-signals, both with 20 kbit/s datarate and ± 35 kHz FSK deviation. Blue plot corresponds to FSK and green plot to GFSK modulation.

The **frequency deviation** is configured using the bits FDEF<4:0> and FDEVSCALE<2:0> in the SFR *FDEV*(0x1C.7:0) and is calculated as follows:

$$\Delta f_{RF} = f_{XOSC} \times \frac{190 \times FDEV<4:0> \times 2^{\frac{FDEVSCALE<2:0>}{64}} + 0.5}{2^{21} - 0.5}$$

Note that the FSK deviation is referenced to the center frequency. This means, that the spacing between the two FSK frequencies, is twice the FSK deviation.

The pulse-shaping Gaussian Filter used for GFSK can be disabled if regular FSK is used. In ASK mode the filter is always switched off. For ASK mode a power-sloping mechanism is available and described in detail in **Chapter 2.4.8 Power Amplifier, ASK Modulator**.

The Gaussian shaping is defined as a number of fixed frequency steps (transitions) between the 2 FSK frequencies, corresponding to Low and High, or 0 and 1 on the modulator input. It is understood that the steps are counted over one edge of the data chip. Ideally these 16 steps are distributed over the complete data chip length, which means there are 16 gaussian filter steps per chip or N_{GF} = 16. Selecting N_{GF} > 16 will reduce the shaping effect and selecting N_{GF} < 16 will cause a reduction of signal information, with minimal positive effect on the obtained RF spectrum.
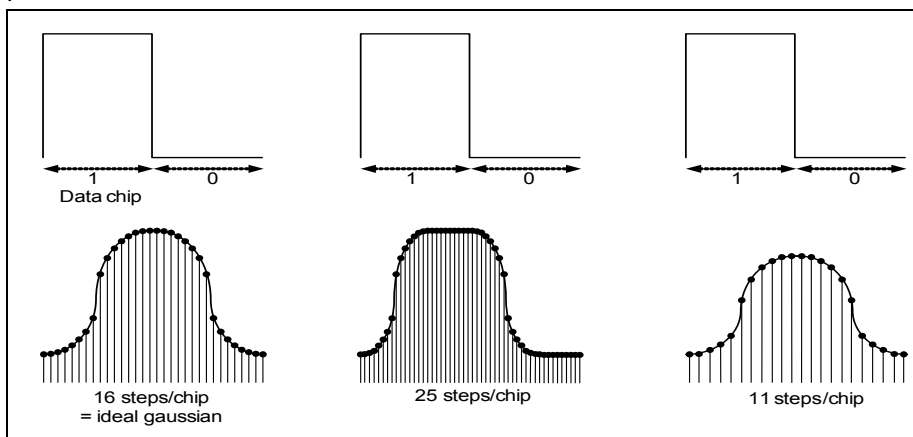
Figure 15   Influence of the Gaussian Divider on Data Shaping

The content of GFDIV is calculated as follows:

$$GFDIV = \frac{f_{XOSC}}{chiprate \times N_{GF}} - 1$$

It is recommended to program the **GFDIV** register in such way, that the GF divider N_{GF} is 16 times the chip-rate. This allows optimum Gaussian filtering.

2.4.7.1   SFRs related to digital FSK / GFSK Modulator

ADDR 0x1C		FDEV—Frequency Deviation					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FDEVSCALE	FDEVSCALE	FDEVSCALE	FDEV	FDEV	FDEV	FDEV	FDEV
w/1	w/1	w/0	w/1	w/1	w/1	w/1	w/1

Bit <7:5>	FDEVSCALE		Frequency deviation scaling bit <2:0>
Bit <4:0>	FDEV		Frequency deviation bit <4:0>

FDEVSCALE	Scaling of the frequency deviation (3 bits)				
	000: divide by 64	**001**: divide by 32	**010**: divide by 16	**011**: divide by 8	
	100: divide by 4	**101**: divide by 2	**110**: divide by 1	**111**: multiply by2	
FDEV	Frequency deviation value (5 bits), defines the multiplication value for the output data from the Gaussian filter (0-31).				

ADDR 0x1D		GFDIV—Gaussian Filter Divider Value					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV
w/0	w/0	w/0	w/0	w/1	w/0	w/0	w/0

Bit <7:0>	GFDIV		Gaussian filter divider bit <7:0>

GFDIV	Gaussian filter clock divider value (11 bits, bits < 7:0 >), defines the sampling ratio of the Gaussian filter; typically this value is set such that the GF divider N_{GF} is 16 x chip-rate (for ideal Gaussian filtering). **Note:** bits < 10:8> are contained in **GFXOSC** register **(0x1E)**

ADDR 0x1E		GFXOSC—Gaussian Filter Configuration					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FHBLANK	reserved	reserved	reserved	GFBYP	GFDIV	GFDIV	GFDIV
w/0	w/1	w/1	w/1	w/1	w/0	w/0	w/0

Bit 7	FHBLANK						
Bit 3	GFBYP			Gaussian filter bypass			
Bit <2:0>	GFDIV			Gaussian filter divider bit <10:8>			

FHBLANK	Frequency Hopping disable (defines the jump from the TX_TIMEOUT state)		
	0: enable (jump to TX_ON state) see also GFXOSC register description (**0x1E**) **1**: disable (jump to PLL_ON state)		
GFBYP	Gaussian filter bypass: **0**: GF enabled **1**: GF bypassed		
GFDIV		Gaussian filter clock divider value (11 bits, bits < 10:8 >), defines the sampling ratio of the Gaussian filter, typically this value is set such that the GF divider is 16 x chip-rate (for ideal Gaussian filtering) **Note:** bits < 7:0> are contained in **GFDIV** register **(0x1D)**	

2.4.8 Power Amplifier, ASK Modulator

The RF signal generated by VCO and under the control of the Sigma-Delta fractional-N PLL is fed to a group of class-C Power Amplifier stages, and amplified before being transmitted. The Power Amplifier (PA) includes an output power control, ASK sloping, switchable capacitors for antenna fine tuning and an auto switch-off mechanism, as part of the Fail-Safe system. If critical supply voltage drop or frequency error events occur, the Fail-Safe mechanism switches the PA off, thus preventing erroneous transmissions.
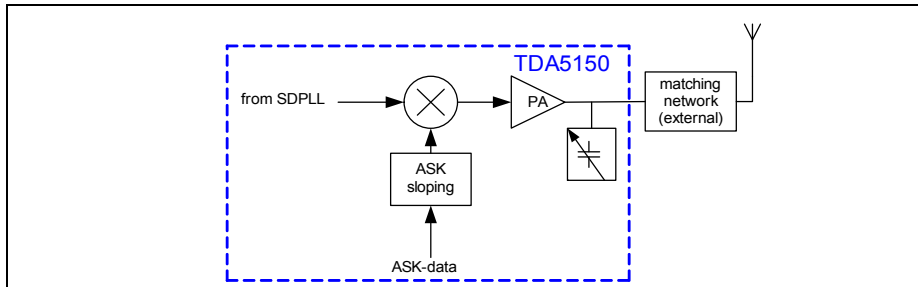
Figure 16   Transmitter Blocks

In FSK or GFSK mode, the PA is always ON during the transmission's duration.
By ASK mode, the SDPLL delivers a continuous RF signal to the PA. The PA is switched ON and OFF, according to the data signal to be transmitted. Additionally there is an ASK sloping mechanism, which switches the different power stages ON (and OFF) in a well determined sequence, correlated with the transitions on data signal line. This power ramping procedure minimizes out-of band transients and spectral splatter.

2.4.8.1   PA Output Power Programming

The PA comprises 11 elementary cells in parallel. Each one is a class-C amplifier.

The cells are grouped in three PA blocks.

PA Block 0 is composed of 9 stages, PA Block 1 and PA Block 2 are strong single stages. Each PA Block can be individually enabled and disabled to optimize power consumption and efficiency in an output power subrange. The overall 11 PA stages allow control of the RF output power in 11 steps over a range of 20 dB. The PA can be switched OFF by disabling all the 11 stages.
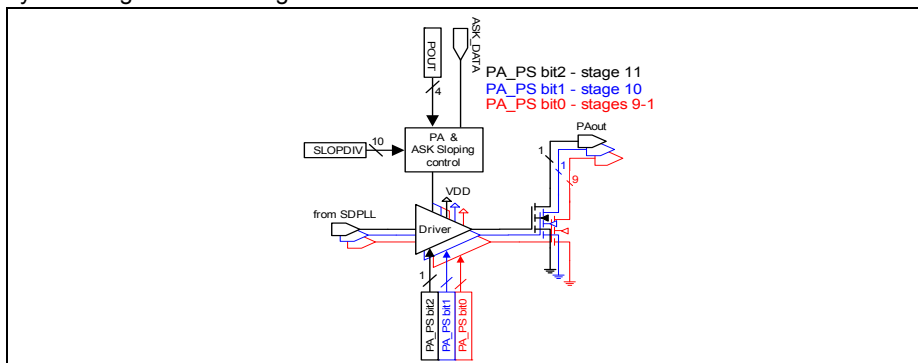
Figure 17   PA Core with Output Power Control

Two independent PA power level settings can be configured. With the Transmit Command the PA power level is selected together with the modulation setting. This means, either power level 1 AND modulation type 1 or power level 2 AND modulation type 2 are selected, according to Modulation Setting 1 or Modulation Setting 2 field in the Transmit Configuration byte.

The 3 PA Blocks are enabled by PA_PS1 and PA_PS2 bits within SFR *POWCFG0* (0x1A). The bits PA_PS1 do enable the PA blocks for power level 1 and bits PA_PS2 are used for power level 2.

Enabling the 3 PA Blocks offers following typical PA ranges (note that the PA output power depends also on the external matching circuit, at a quite large extent):

- PA_PS bit0=1: +5 dBm matched; Pout = +5 dBm down to -10 dBm, 9 PA Stages
- PA_PS bit1=1: +8 dBm matched; Pout = +8 dBm down to -10 dBm, 10 PA Stages
- PA_PS bit2=1: +10 dBm matched; Pout = +10 dBm down to -10 dBm, 11 PA Stages

In addition to enabling the PA Blocks, the 11 PA stages have to be configured. This is achieved by setting the bit-fields POUT1 (0x1B.3:0) for power level 1 and POUT2 (0x1B.7:4) for power level 2 in SFR *POWCFG1* (0x1B) (POUTn=0 means that the PA is effectively OFF).

The output impedance of the PA depends on the number of PA stages used. The external antenna matching must be done for the impedance related to the highest number of used PA stages, or in other words, for the use-case of highest RF output power.If the desired output power is +10 dBm for instance, the antenna should be matched for the case of all the11 PA Stages active. In the same way, if the output power requirement is for +5 dBm, the antenna should be matched assuming that 9 PA Stages are used and active. Supposed the matching network have been set up for the PA impedance bound to +10 dBm output power (all 11 PA Stages active), it is reasonable to expect some degree of mismatch and efficiency loss by operation in +5 dBm RF power mode.

2.4.8.2   ASK Modulation and ASK Sloping

The ASK or FSK modulation is selected by SFR *TXCFG1* (0x05). There are two possible setups, designated **ModulationSetting1**, and **ModulationSetting2**. The bit D of Transmit Command Byte selects the active setting. This allows switching between the two modulation setups, without any further register configuration. See also

Chapter 2.4.3.4 Transmit Command

ASK modulation is realized by switching the PA Stages ON and OFF in accordance with data signal to be transmitted.

On-chip ASK Sloping capability is provided within TDA5150. This means that instead of switching all PA Stages at the same time, they are switched ON one after the other in a configurable time sequence.

The power sloping is controlled by SFR SLOPDIV register (0x19.7:0).

The register content is equal with the number of reference oscillator cycles elapsed until the next PA stage is switched ON or OFF.

Note: For optimum shaping effect, it is recommended to match the number of sloping steps to the required maximum output power and consequently to the maximum number of stages which might be used.

2.4.8.3 Duty Cycle Control

The control of Duty Cycle leads to control of the averaged RF output power (by changing the conductive angle of the RF power amplifier) and contributes to further reduction of the current consumption. It is worth to be noted, that decreasing conduction angle values lead to decrease of power consumption, but at the same time due to the short and high-amplitude current pulses the level of RF harmonics (on $n* f_{carrier}$ frequencies) will tend to rise. An adequate lowpass or bandpass filter is required therefore between the power amplifier and the load, and quite often this filter is merged into one block with the impedance matching network (i.e. the impedance matching network is able to reject some harmonics of the carrier frequency, especially those with potentially high level).

If Duty Cycle control option is enabled, nominal values of 31 %, 35 %, 39 % and 43 % can be programmed. If disabled, the default value of 50% applies for Duty Cycle.

The Duty Cycle Control is accessible through the DCCCONF bits (0x1F.5:4) of SFR *ANTTDCC* (0x1F) (see **DCCCONF** paragraph for details).

In the 315 MHz band the DCCCONF and DCCDISABLE bits are ignored. A predefined (and optimized) value of 33% is superimposed instead of a programable Duty Cycle.

2.4.8.4 Antenna Tuning

A block of 4 switchable capacitors connected in parallel with the PA output may be used for antenna tuning. This option may be useful for fine-tuning the RF PA to Load matching network, and thus to obtain enhanced radiated power performance in a wider frequency band. However retuning is required only in those multichannel applications, where the channels are at considerable frequency offset one from the other (i.e not for ISM bands).

The tuning capacitors can be switched ON / OFF individually, the control of the respective switches is implemented in SFR *TUNETOP* (0x1F).

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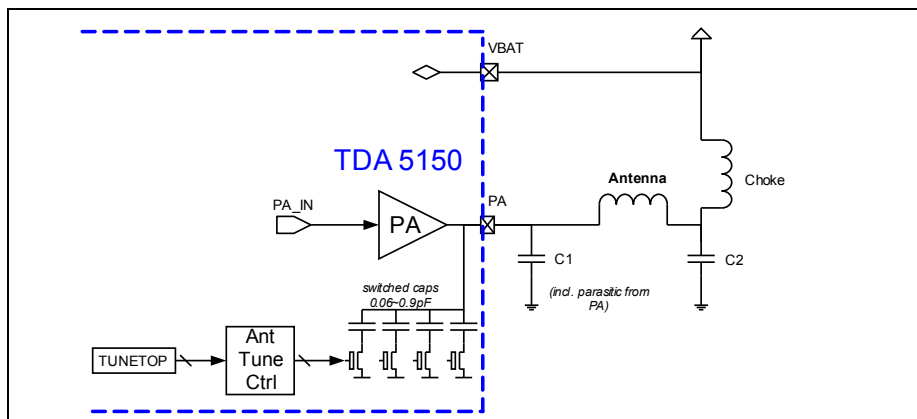
Figure 18   PA Antenna Tuning and Matching

The 4 switched capacitors have different values of typically 60 fF, 120 fF, 240 fF and 480 fF, giving an overall maximum capacitance of about 0.9 pF.

Note: Due to the low Q Factor of the switched capacitors at the higher frequencies, the current consumption of the device tends to increase if this tuning option is used in the higher frequency bands (868 MHz and 915 MHz).

2.4.8.5 Fail-Safe PA Switch Off

To prevent erroneous transmissions (on wrong frequency or with erroneous modulation parameters, altered payload etc.) the activation of Fail-Safe mechanism is coupled with deactivation (switching off) of the RF Power Amplifier stages. If critical errors occur, the Fail-Safe mechanism incorporated in the TDA5150 is activated, provided the detection enable bit is armed (i.e. bit FSOFF in SFR *TXCFG0* (0x04.4) is 0).

Observe that this corresponds to the after-reset state. In other words, by exiting the reset state, the Fail-Safe detection is already armed, but it can be deactivated anytime by

changing its control bit state to High (bit FSOFF=1 (0x04.4)) or rearmed, by setting it to Low.

If the detection is armed, RF Power Amplifier drivers are automatically switched OFF in case of an error, to prevent erroneous transmissions.

This happens if at least one of the following events occurs:

• Parity error in the SFRs
• Brownout event (event sensed by the brown-out detector BOD)
• PLL lock failure is detected (event sensed by the lock detector LD)

If the detection is disabled, the error flags in *Transmitter Status Register* (0x01) still keep track of error status (i.e. they are set, if an error occurs) but the RF Power Amplifier is not switched off by the error flag(s) set condition (i.e. the RF-PA continues to transmit despite error until the transmission is terminated as a normal, error-free one).

Refer to *Transmitter Status Register* (0x01) description and Fail-Safe Flags, explained in next **Chapter 2.4.8.6 SFRs related to RF Power Amplifier and ASK Modulator**.

2.4.8.6   SFRs related to RF Power Amplifier and ASK Modulator

ADDR 0x04		TXCFG0—Transmitter Configuration Register 0					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2STDBY	reserved	reserved	FSOFF	ISMB	ISMB	reserved	reserved
cw/0	w/0	w/0	w/0	w/0	w/1	w/1	w/0
Bit 4	FSOFF			Fail-Safe mechanism: 0 enabled, 1 turned off			

ADDR 0x05		TXCFG1—Transmitter Configuration Register 1					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2SLEEP	ASKFSK2	ASKFSK1	ASKSLOPE	INVERT	ENCMODE	ENCMODE	ENCMODE
cw/0	w/0	w/1	w/0	w/0	w/1	w/0	w/1
Bit 4	ASKSLOPE			ASK sloping: 0 disable, 1 enable			

ADDR 0x19		SLOPEDIV —ASK Sloping Clock Divider					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV
w/1	w/0	w/0	w/0	w/0	w/0	w/0	w/0
Bit <7:0>	SLOPEDIV			ASK sloping clock divider bit <7:0>			

SLOPEDIV	ASK sloping clock division ratio (10 bits, bits < 7:0 >), defines the timing of the ASK signal shaping using PA power stage switching		
	Range:	from **0x000**: SLOPEDIV = 1	to **0x3FF**: SLOPEDIV = 1024

ADDR 0x1A		POWCFG0—PA Output Power Configuration Register 0					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PA_PS2	PA_PS2	PA_PS2	PA_PS1	PA_PS1	PA_PS1	SLOPEDIV	SLOPEDIV
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:5>	PA_PS2		PA output blocks setting 2 bit <2:0>		
Bit <4:2>	PA_PS1		PA output blocks setting 1 bit <2:0>		
Bit <1:0>	SLOPEDIV		ASK sloping clock divider bit <9:8>		

PA_PS2	Individual control of the 3 PA blocks, setting 2 (3-bits)				
	0: disabled	**1**: enabled	Bit(0) ==> PA block 0	Bit(1) ==> PA block 1	Bit(2) ==> PA block 2
PA_PS1	Individual control of the 3 PA blocks, setting 1(3-bits)				
	0: disabled	**1**: enabled	Bit(0) ==> PA block 0	Bit(1) ==> PA block 1	Bit(2) ==> PA block 2
SLOPEDIV	ASK sloping clock division ratio (10 bits, bits < 9:8 >), defines the frequency of the ASK signal shaping using PA power stage switching				
	Range:		from **0x000**: SLOPEDIV = 1	to **0x3FF**: SLOPEDIV = 1024	

ADDR 0x1B		POWCFG1—PA Output Power Configuration Register 1					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
POUT2	POUT2	POUT2	POUT2	POUT1	POUT1	POUT1	POUT1
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:4>	POUT2		Output power setting 2 bit <3:0>
Bit <3:0>	POUT1		Output power setting 1 bit <3:0>

POUT2	PA output power setting 2 (4 bits), defines the number of enabled PA stages		
	Range:	from **0x0**: POUT2 = 0	to **0xB**: POUT2 = 11 > **0xB**: POUT2 = 11
POUT1	PA output power setting 1 (4 bits), defines the number of enabled PA stages		
	Range:	from **0x0**: POUT1 = 0	to **0xB**: POUT1 = 11 > **0xB**: POUT1 = 11

ADDR 0x1F		ANTTDCC—Antenna Tuning and Duty Cycle Configurations					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	DCC DISABLE	DCCCONF	DCCCONF	TUNETOP	TUNETOP	TUNETOP	TUNETOP
w/0	w/0	w/1	w/0	w/0	w/0	w/0	w/0

Bit 7	reserved		Always use 0
Bit 6	DCCDISABLE		Duty cycle control disable
Bit <5:4>	DCCCONF		Duty cycle control delay configuration bit <1:0>
Bit 3:0	TUNETOP		Antenna tuning top capacitor bit <3:0>

DCCDISABLE	Duty cycle control disable (must be 0 for ISMB=0)			
	0 enabled		1 disabled (delay = 0ps)	
DCCCONF	Duty cycle control delay configuration (ISMB = 1/2/3, for ISMB = 0 => delay = 0 ps)			
	00: 43% (69/35/33 ps)	01: 39% (207/104/98 ps)	10: 35% (346/173/164 ps)	11: 31% (484/242/230 ps)
TUNETOP	Antenna tuning top capacitor selection (4-bits):			
	Individual switch of capacitor banks	**0**: switched off	**1**: switched on	
	Bit(0) ==> 60 fF	Bit(1) ==> 120 fF	Bit(2) ==> 240 fF	Bit(3) ==> 480 fF

2.4.9 Operating Modes

TDA5150 has 3 main operating modes: **SLEEP**, **STANDBY**, **TRANSMIT**

and 2 temporary modes: **XOSC_ENABLE** and **PLL_ENABLE**.

2.4.9.1 SLEEP Mode

SLEEP is the lowest power consumption mode. Most of the internal blocks, excepting the SPI interface are powered down and consequently the content of SFRs is going lost. Therefore the SFR bank requires a full reprogramming after exiting SLEEP mode.

The SPI interface stays active and is supplied via the Low Power Voltage Regulator while in SLEEP mode.

The SPI interface is able to detect bus non-idle conditions and it will wake up the transmitter if the EN pin is taken high and at least 3 pulses are applied to SCK pin.

Observe that this last wake-up condition is automatically fulfilled during communication over the transmitter's SPI-bus, assuming a standard, SPI-bus protocol is used.

SLEEP mode is entered:

- after a GO2SLEEP command execution, i.e by taking the EN pin to Low preceded by setting of the GO2SLEEP bit in SFR *TXCFG1* (0x05.7) to 1. This bit will be cleared automatically on WAKEUP (i.e. on exiting the SLEEP state). There is a small latency after the trailing edge of signal on EN pin (of 2 f_{sys} cycles) the time taken to close down internal blocks.

SLEEP mode is left if the EN line is set to High level and there is clock activity (at least 3 pulses) on the SCK line. The conjunction of these 2 conditions will wake up the transmitter and thus SLEEP Mode will be exited.

In SLEEP mode:

- Only the low power voltage regulator is ON
- Only the SPI interface is powered
- POR is ON
- BOD is in low power mode (inaccurate threshold)
- All other blocks are OFF
- Power supply for digital core and SFR data is disconnected. As a consequence, SFR register content is lost.

2.4.9.2 STANDBY Mode (Data Retention Mode)

STANDBY is a low power mode, but with higher consumption as SLEEP mode, due to the fact that the SFRs are still supplied in this mode.

STANDBY is entered:

- whenever the EN line is low (no SPI communication), and the time-out count of 65536/ f_{sys} periods have been elapsed
- after a GO2STANDBY command execution (setting the GO2STANDBY bit in SFR *TXCFG0* (0x04.7) followed by taking the EN pin to Low (EN=0).

In STANDBY Mode:

- Only the low power voltage regulator is ON
- SPI, SFR container, and System Controller are supplied - data can be read into and from the chip.
- POR is ON
- BOD is in low-power mode (inaccurate threshold)
- Data consistency of SFR container is monitored by means of parity bits

All other blocks are OFF.

2.4.9.3 TRANSMIT Mode

This mode is automatically entered during a transmit command. PLL and PA are active in this mode. TRANSMIT is left, with the falling edge of the EN line, when bit B in the Transmit Command is 0. Otherwise TDA5150 remains in the transmit mode with PA and PLL in ON state, until the time-out of 65536 / f_{sys} occurs (around ~5 ms for a 13 MHz reference clock).

- Normal voltage regulator is ON
- POR is ON
- BOD is ON
- XOSC is ON
- PLL is ON
- PA is ON

2.4.9.4 XOSC_ENABLE Mode

This is a temporary mode after power up, entered whenever SLEEP or STANDBY mode is left (by a rising edge of the EN line). This mode is automatically entered while SFRs are programmed. XOSC_ENABLE is left by GO2SLEEP, GO2STANDBY commands, by the ~5 ms time-out to enter automatically STANDBY, or by a transmit command.

- Normal voltage regulator is ON
- POR is ON
- BOD is ON
- XOSC is ON
- Clock divider is ON
- PLL and PA are OFF

2.4.9.5 PLL_ENABLE Mode

This is a temporary mode during a transmit command, when the PLL is already activated, but the PA is not switched ON yet.

- Normal voltage regulator is ON
- POR is ON
- BOD is ON
- XOSC is ON
- PLL is ON, PA is OFF
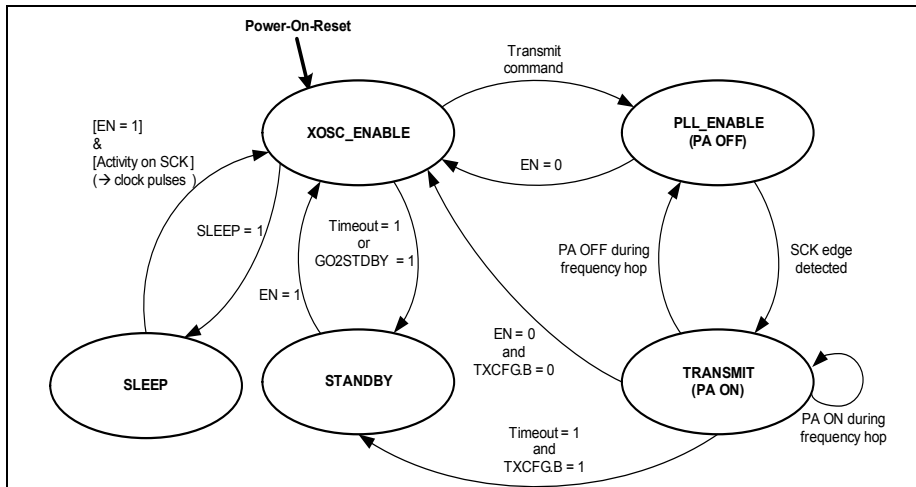
Figure 19   Simplified State Diagram of the TDA5150

2.4.9.6   SFRs related to Operating Modes

ADDR 0x04		TXCFG0—Transmitter Configuration Register 0					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2STDBY	reserved	reserved	FSOFF	ISMB	ISMB	reserved	reserved
cw/0	w/0	w/0	w/0	w/0	w/1	w/1	w/0
Bit 7	GO2STDBY			**1:** go to StandBy (cleared after 1 is written)			

ADDR 0x05		TXCFG1—Transmitter Configuration Register 1					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2SLEEP	ASKFSK2	ASKFSK1	ASKSLOPE	INVERT	ENCMODE	ENCMODE	ENCMODE
cw/0	w/0	w/1	w/0	w/0	w/1	w/0	w/1
Bit 7	GO2SLEEP			**1:** go to Sleep **Note:** after execution of this command all SFR content is lost			

2.4.10 Fail-Safe Mechanism and Status Register

2.4.10.1 Fail-Safe Flags

The status of the TDA5150 is continuously monitored during active state by the integrated Fail-Safe mechanism, which includes:

- Brownout Error—generates an internal reset, whenever the voltage drops below the specific threshold. The brownout error flag is set, to allow recognition of a brownout event. The flag can be read via SPI bus.
- Parity Error— There is a single parity bit for each SFR register, which is updated each time the SFR register is written. Following this update, the parity for each register is calculated and checked against this bit continuously. If there is a mismatch in any of the registers, the error flag is set. The content of all SFRs is monitored and the parity checked even during **STANDBY** state.
- PLL Lock Error—is monitored after the transmission start. If the PLL loses the phase-locked state during transmission, the related flag is set.

The Fail-Safe status of the chip is stored and available via the SFR *Transmitter Status Register* (0x01). If a failure condition occurs, a flag is set and latched via previously mentioned SFR. Even if the condition which led to the event occurrence is no longer true, the "set" state of the Fail-Safe bits is kept, and cleared only by the Transmitter Status Register read operation. See also **Chapter 2.5.2** for detailed SFR register map.

Preservation of above described Fail-Safe Flag bits in SFR Transmitter Status Register provides a feedback to user about the failure root cause - if any error occurred.

If the Transmit Fail-Safe bit FSOFF in SFR *TXCFG0* (0x04) is enabled (set to 0) and one of the Fail-Safe flags goes in active state, the PA is disabled thus preventing further transmission. The after-reset state for Fail-Safe is active (bit FSOFF set to 0).

It is highly recommended to read the SFR *Transmitter Status Register* (0x01) before- and after a transmission (clear error flags, if any and check for error-free transmission).

2.4.10.2 Low Battery Monitor

The low-battery detector monitors the supply voltage on Pin 5 (VBAT). If the voltage drops below 2.4 V, a corresponding flag is set and the threshold is switched automatically to 2.1 V. If this new threshold is also reached due to further voltage drop, the 2.1 V flag bit is set in addition to the 2.4 V flag. These Fail-Safe flags are automatically cleared after each transmission start, and content is not preserved like for Brownout Error, Parity Error and PLL Lock Error bits.

Summary:

- LBD_2V4 set if battery voltage drops below 2.4 V
- LBD_2V1 set if battery voltage drops below 2.1 V

2.4.10.3 SFRs related to Supply Voltage monitoring

ADDR 0x01		TXSTAT—Transmitter Status Register					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
1	n.u.	LBD_2V1	LBD_2V4	VAC_FAIL	BROUTERR	PARERR	PLLLDER
/	/	r/0	r/0	c/0	c/1	c/0	c/0

Bit 7	1		Set to 1, mandatory
Bit 5	LBD_2V1		Low battery detected at 2.1 V
Bit 4	LBD_2V4		Low battery detected at 2.4 V
Bit 3	reserved		Don't care
Bit 2	BROUTERR		Brown out event
Bit 1	PARERR		Parity error
Bit 0	PLLLDER		PLL lock detector error

LBD_2V1	Battery voltage drop below 2.1 V detected if **1**. In standby mode, this bit is invalid.
LBD_2V4	Battery voltage drop below 2.4 V detected if **1**. In standby mode, this bit is invalid.
BROUTERR	Brownout event detected if **1**.
PARERR	Parity error detected if **1**.
PLLLDERR	PLL lock error detected if **1**.

2.4.11 RF Data Transmission

The procedure of RF Transmission is started by the rising edge of the control signal applied to the chip-enable pin (EN; pin 1). Thus STANDBY or SLEEP Mode are exited followed by start of the crystal oscillator, which would require maximum 1 ms to start up, if the crystal types indicated in **Table 5** and **Table 7** or similar models are used.

Note: the startup time of an oscillator using a quartz crystal as frequency stabilizing element is at great extent a function of oscillator gain and the crystal's equivalent motional parameters (L_1, C_1, R_s and C_0). Especially motional inductance (L_1) has a high degree of influence, but also (R_s), the equivalent series resistance and those parameter have to be carefully examined during crystal selection.

During this time the TDA5150 can be already reconfigured, because the SPI block does not require the system clock.

Before start of a transmission the *Transmitter Status Register* (0x01) should be read, in order to clear bits set by previous errors (if any).

Every transmission starts with a Transmit Command:

C1	C0	Transmit Command Configuration		
		Bit	**Function**	**Value, description**
1	1	A	Data sync	0: off 1: on (at the same time Bit C - Encoding must be set also to 1 --> Int. Encoding)
1	1	B	PA mode	0: PA off at the falling edge of EN (synchronized with bit-rate if bit A is high) 1: SDIO/DATA is latched at the falling edge of EN, PA stays on, TX data are kept constant. After the time-out of 65536 / f_{sys} which is ~5 ms for a 13 MHz crystal, PA and PLL are switched off.
1	1	C	Encoding	0: off 1: on (selects SFR register for encoding Bit A must be also set to1 -->Data sync)
1	1	D	Pwr. level/ModSetting	0: selects **PowerLevel/Modulation Setting1** 1: selects **Power Level/Modulation Setting2**
1	1	<E,F>	Frequency selection	0 (00): selects frequency channel **A** 1 (01): selects frequency channel **B** 2 (10): selects frequency channel **C** 3 (11): selects frequency channel **D** For description of frequency channels **A**..**D** programming procedure please see **Chapter 2.4.11.3 Channel Hopping**

The Transmit Command byte is sent via SPI, and identified by the first two bits, designated C0 and C1. These two bits are mandatory set to 1.

The following 6 bits, designated *bit A - bit F*, specify the transmission details.

- A: Synchronous (1) or asynchronous (0) transmission, details are described later in this chapter.
- B: If 0, the PA is switched off by the falling edge of the EN line. If 1, the SDIO line is latched with the falling edge of EN, the PA stays active, continuing to transmit according to the latched SDIO state. After a time-out duration of 65536 / f_{sys} (~5 ms for a 13 MHz reference clock), both the PA and PLL are switched off if no other SPI command starts a new transmission. This feature helps to keep the transmitter

sending, despite the fact that the EN line is pulled to Low state, normally a stop condition for Transmitter. Pulling the EN line to (Low) in between SPI command blocks is required by SPI protocol, if commands are not sent in burst mode.

- C: If C = 0, the Encoder is not used. If C = 1, the Encoder is used as configured in the *Transmitter Configuration Register 1,* bits ENCMODE (0x05.2:0).

- D: Switch between two subsets of transmission parameters, referenced as **PowerLevel/Modulation Setting *n***. Each subset contains 3 bit-fields for control of:
  - modulation type (ASK or FSK)
  - RF-PA block activation (3 blocks are available, may be switched ON/OFF individually)
  - RF-PA output power

- Modulation type (ASK or FSK) is controlled by bit-field ASKFSK1:2 (0x05.6:5) of the SFR *Transmitter Configuration Register 1* (0x05). The modulation mode selection is done individually for each of the two transmission settings (steered by bit field value D = 0 or D= 1), with choice between ASK and FSK modulation. The settings are not coupled, i.e one bank could be set for ASK modulation and the other for FSK for example. Further, if FSK is chosen as modulation type, enabling of Gaussian filtering is another option - but not mandatory. See also **Chapter 2.4.4.2 SFRs related to Transmitter Configuration and Data Encoding**.

- RF-PA block activation, controlled by bit-fields PA_PS1 (0x1A.4:2) respectively PA_PS2 (0x1A.7:5) of the SFR *Output Power Configuration Register 0*, (0x1A) for the two transmission settings

- RF-PA output power selection, controlled by the bit-fields POUT1 (0x1B.3:0) respectively POUT2 (0x1B.7:4) of the SFR *Output Power Configuration Register 1*, (0x1B) for the two transmission settings

- If D = 0, following fields are selected: [ASKFSK1, together with PA_PS1 and POUT1]. If D = 1, following fields are selected: [ASKFSK2, together with PA_PS2 and POUT2].

- E, F RF Frequency selection as configured in PLL MM Integer Value registers A/B/C/D (0x09/0x0D/0x11/0x15) and the PLL Fractional Division Ratio registers A/B/C/D (0x0A:0x0C:0x0E:0x10/0x12:0x14/0x16:0x18.

After the transmit command have been sent, the SCLK line has to stay low for at least 100 µs (i.e settling time of the PLL). A rising edge of the SCLK line after this break activates the PA and starts the transmission. The digital data is input into the transmitter via the SDIO line and transposed into modulated RF signal, without regard on the state of SCLK line (which could be Low or High).

To keep crosstalk between SCLK and SDIO at minimum level, it is recommended to keep SCLK at a steady level, instead of toggling it (usually by the uC).

2.4.11.1 Asynchronous Transmission

In Asynchronous Transmission Mode (also referred as Transparent Mode), the data on SDIO is directly input into modulator and converted into RF carrier. There is no internal

synchronization with the bit-rate clock. The CLKOUT programmed to the proper bit-rate (or a multiple of it) may be used by the host to time and shift (into SDIO line) the bits to be transmitted.

The Encoder and Scrambler can not be used and are automatically bypassed.

It is not recommended to use GFSK in conjunction with Asynchronous Transmission Mode, as the frequency steps are timed with 1/16 of the bit-rate (chip-rate) clock. Timing differences between the internal bit-rate clock and the µC clock may cause unwanted jitter in the transmission.

GFSK modulation is intended to be used rather in conjunction with Synchronous Transmission Mode.
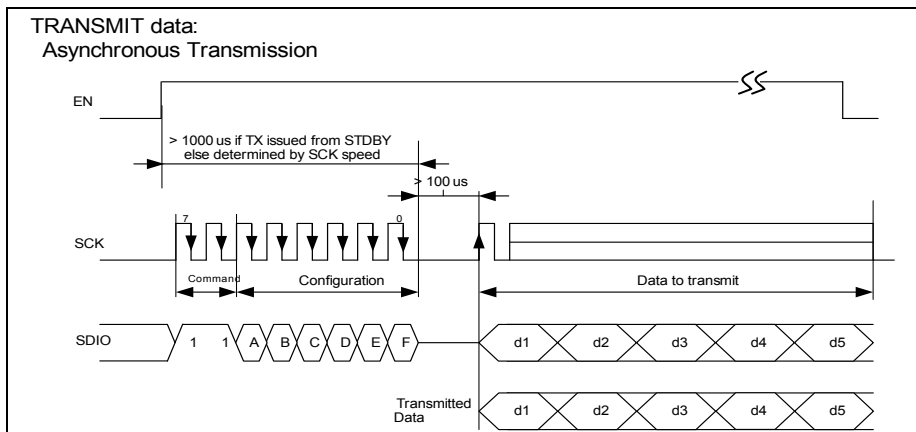
Figure 20   Asynchronous Transmission

Setting the EN line (pin 1) to low terminates the RF-transmission.

2.4.11.2 Synchronous Transmission

In the Synchronous Transmission Mode the transmit data is latched with the falling edge of the internal bit clock, and thus synchronized. The bit clock at the CLKOUT has to be used by the µC to time the bits which are transmitted, e.g. on interrupt basis.

The Encoder has to be enabled. If the bits shall not be encoded, select NRZ as generic Encoder scheme. See **Chapter 2.4.4 Data Encoder**.
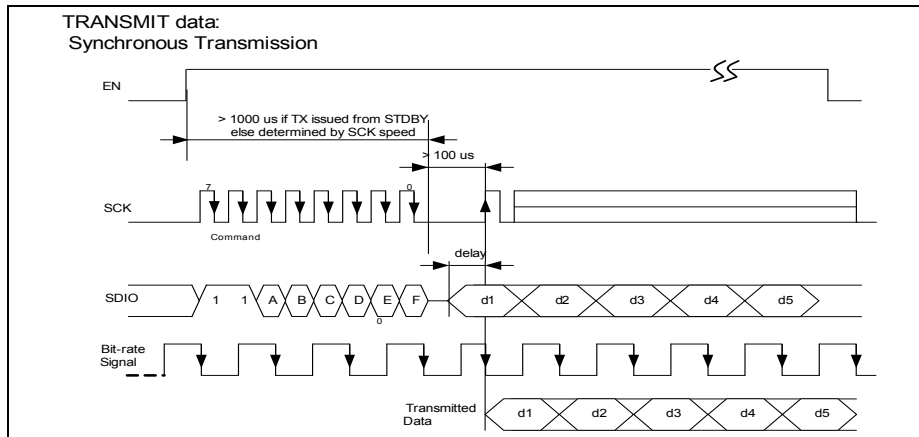
Figure 21   Synchronous Transmission

Synchronous transmission is the recommended user mode. Encoding can be used, and this mode is preferred especially for GFSK. At the same time SW implementation is easier, because the delivery of the next data bit (over the SDIO line) is triggered by interrupt (mapped to CLKOUT line) and timing inaccuracies caused for example by interrupt reaction latency are compensated / neutralized by the synchronization.

If Synchronous Mode will be used, the following aspects have to be kept in mind:

• The data sampling is being done always on the falling edge of the internal baudrate clock

• The initialization of the internal baudrate clock at the SCLK edge is working properly (starting with '0') only if the prescaler is set to "division by 1"; in all other cases the baudrate clock begins with the opposite phase ('1') and therefore there is a half bit delay caused by data sampled on falling edge

• The initial phase of the CLKOUT is determined by the CLKOUT state and internal baudrate clock at SCLK edge (invert CLKOUT @ SCLK)

• If the prescaler is not set to "division by 1", the initial CLKOUT phase is additionally depending on the timing between the clock generated by the prescaler and SCLK edge (if prescaler clock generated @ SCLK edge, additional CLKOUT inversion is done)

This means that the minimum baudrate with prescaler ratio at "division by 1" at which the baudrate clock is generated properly is

BDR = f_xosc / 256 * 2 * 8 which yields for 13 MHz reference frequency~ 3,173 kB/s,

where PRESCALE = 1, BDRDIV = 255 and AFTERSCALE = 8.

Therefore it is advisable to avoid lower datarates in this mode. A workaround is described in the Application Note **AN_Programming_the_TDA5150_V2.0.pdf**

2.4.11.3 Channel Hopping

TDA5150 offers the possibility for usage of up to 4 preconfigured RF channels, designated as frequency channel A, B, C, and D.

The preconfiguration assumes the proper programming of the following PLL registers:

- Multi-Modulus Integer Value registers A/B/C/D (0x09; 0x0D; 0x11; 0x15) and
- Fractional Division Ratio registers A/B/C/D (0x0A:0x0C; 0x0E:0x10; 0x12:0x14; 0x16:0x18.

Bit-fieled <E:F> in Transmit Command is used for frequency channel selection.

Thus it is possible to switch quickly between RF frequency channels, without time consuming reconfiguration, assuming that the channels intended for transmission have been preconfigured in advance.

Any frequency hop within the frequency band requires a new Transmit Command and up to 100 µs idle time for the PLL to perform the VCO Auto Calibration and to settle (i.e. to achieve phase locked state).

For hops to new frequencies less then1 MHz apart from the frequency on which the VCO Auto Calibration was performed, it is possible to skip the VCO Auto Calibration process and thus to reduce the PLL settling time to around 20 µs (instead of 100 µs). In this case it is allowed to start the transmission, triggered by the rising edge of signal on the SCK line, by waiting for only 20 µs after the Transmit Command have been completed.

The VCO Auto Calibration process can be skipped by setting the FHBLANK bit (0x1E.7) in SFR *GFXOSC* (0x1E) to 1.

Attention: There should be no more than 4 consecutive channel hops without VCO Auto Calibration during transmissions.

If bit B of the Transmit Command is set, the RF power amplifier will stay active, until the time-out condition is reached (i.e. for a duration of 65536 / f_{sys} corresponding to ~5 ms for a 13 MHz reference clock).

2.4.11.4 SFRs related to Channel Hopping

ADDR 0x1E		GFXOSC—Gaussian Filter Configuration					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FHBLANK	reserved	reserved	reserved	GFBYP	GFDIV	GFDIV	GFDIV
w/0	w/1	w/1	w/1	w/1	w/0	w/0	w/0
Bit 7	FHBLANK			Frequency Hopping VAC Disable			
FHBLANK		Frequency Hopping, enable/disable VCO Auto Calibration for Channel Hopping					
		0: enable VCO Auto Calibration (default)			**1**: Skip VCO Auto Calibration for frequency hops <1 MHz		

2.5 Digital Control (SFR Registers)

2.5.1 SFR Register List

The SFRs (Special Function Registers) are used to configure TDA5150 and to read out certain information e.g. the transmitter status.

There are complete SFRs, as well as register bits in SFRs, called "Reserved". These SFRs and register bits used in the production process. The SFRs and bits have to be configured with their default value as shown in the **Chapter 2.5.2 SFR Detailed Descriptions**

Table 3   SFR Register List

Register Name	Register Description	Address
SPICHKSUM	SPI Checksum register	**0x00**
TXSTAT	Transmitter status register	**0x01**
TXCFG0	Transmitter configuration register 0	**0x04**
TXCFG1	Transmitter configuration register 1	**0x05**
CLKOUTCFG	Clock pre- and after-scaler	**0x06**
BDRDIV	BDRDIV divider	**0x07**
PRBS	PRBS start value	**0x08**
PLLINTA	PLL MM integer value Channel A	**0x09**
PLLFRACA0	PLL fractional division ratio Channel A (byte 0)	**0x0A**

PLLFRACA1	PLL fractional division ratio Channel A (byte 1)	**0x0B**
PLLFRACA2	PLL fractional division ratio Channel A (byte 2)	**0x0C**
PLLINTB	PLL MM integer value Channel B	**0x0D**
PLLFRACB0	PLL fractional division ratio Channel B (byte 0)	**0x0E**
PLLFRACB1	PLL fractional division ratio Channel B (byte 1)	**0x0F**
PLLFRACB2	PLL fractional division ratio Channel B (byte 2)	**0x10**
PLLINTC	PLL MM integer value Channel C	**0x11**
PLLFRACC0	PLL fractional division ratio Channel C (byte 0)	**0x12**
PLLFRACC1	PLL fractional division ratio Channel C (byte 1)	**0x13**
PLLFRACC2	PLL fractional division ratio Channel C (byte 2)	**0x14**
PLLINTD	PLL MM integer value Channel D	**0x15**
PLLFRACD0	PLL fractional division ratio Channel D (byte 0)	**0x16**
PLLFRACD1	PLL fractional division ratio Channel D (byte 1)	**0x17**
PLLFRACD2	PLL fractional division ratio Channel D (byte 2)	**0x18**
SLOPEDIV	ASK sloping clock divider low	**0x19**
POWCFG0	PA output power configuration register 0	**0x1A**
POWCFG1	PA output power configuration register 1	**0x1B**
FDEV	Frequency deviation	**0x1C**
GFDIV	Gaussian filter divider value	**0x1D**
GFXOSC	Gaussian filter configuration	**0x1E**
ANTTDCC	Antenna tuning and Duty Cycle configurations	**0x1F**
RES1	Reserved	**0x20**
VAC0	VAC configuration 0	**0x21**
VAC1	VAC configuration 1	**0x22**
VACERRTH	VCA error threshold	**0x23**
CPCFG	Charge pump configuration	**0x24**
PLLBW	PLL bandwidth configuration	**0x25**
RES2	Reserved	**0x26**
ENCCNT	Encoding start bit counter	**0x27**

Figure 22   Register Terminology

Register-bit command terminology

r	read register	\0	default to 0	\1	default to 1
w	write register	\0	default to 0	\1	default to 1
c	clear-after-write register	\0	default to 0 after clear	\1	default to 1 after clear

Important notice: It is mandatory to maintain the default values, as specified in the respective register tables for all

• reserved Special Function Registers (SFR)
• reserved bits
• reserved bit fields

Table 4   Register Bit Map Configuration

Register	Addr	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SPICHKSUM	0x00	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM
TXSTAT	0x01	1	n.u.	LBD_2V1	LBD_2V4	VAC_FAIL	BROUTERR	PARERR	PLLLDERR
TXCFG0	0x04	GO2STDBY	reserved	reserved	FSOFF	ISMB	ISMB	reserved	reserved
TXCFG1	0x05	GO2SLEEP	ASKFSK2	ASKFSK1	ASKSLOPE	INVERT	ENCMODE	ENCMODE	ENCMODE
CLKOUTCFG	0x06	CLKSRC	CLKSRC	AFTERSCALE	AFTERSCALE	PRESCALE	PRESCALE	PRESCALE	CLKOUTENA
BDRDIV	0x07	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV
PRBS	0x08	PRBS	PRBS	PRBS	PRBS	PRBS	PRBS	PRBS	PRBS
PLLINTA	0x09	n.u.	PLLINTA	PLLINTA	PLLINTA	PLLINTA	PLLINTA	PLLINTA	PLLINTA
PLLFRACA0	0x0A	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0
PLLFRACA1	0x0B	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1
PLLFRACA2	0x0C	n.u.	n.u.	reserved	PLLFRACA2	PLLFRACA2	PLLFRACA2	PLLFRACA2	PLLFRACA2
PLLINTB	0x0D	n.u.	PLLINTB	PLLINTB	PLLINTB	PLLINTB	PLLINTB	PLLINTB	PLLINTB
PLLFRACB0	0x0E	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0
PLLFRACB1	0x0F	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1
PLLFRACB2	0x10	n.u.	n.u.	reserved	PLLFRACB2	PLLFRACB2	PLLFRACB2	PLLFRACB2	PLLFRACB2
PLLINTC	0x11	n.u.	PLLINTC	PLLINTC	PLLINTC	PLLINTC	PLLINTC	PLLINTC	PLLINTC
PLLFRACC0	0x12	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0
PLLFRACC1	0x13	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1
PLLFRACC2	0x14	n.u.	n.u.	reserved	PLLFRACC2	PLLFRACC2	PLLFRACC2	PLLFRACC2	PLLFRACC2
PLLINTD	0x15	n.u.	PLLINTD	PLLINTD	PLLINTD	PLLINTD	PLLINTD	PLLINTD	PLLINTD
PLLFRACD0	0x16	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0
PLLFRACD1	0x17	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1
PLLFRACD2	0x18	n.u.	n.u.	reserved	PLLFRACD2	PLLFRACD2	PLLFRACD2	PLLFRACD2	PLLFRACD2
SLOPEDIV	0x19	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV
POWCFG0	0x1A	PA_PS2	PA_PS2	PA_PS2	PA_PS1	PA_PS1	PA_PS1	SLOPEDIV	SLOPEDIV
POWCFG1	0x1B	POUT2	POUT2	POUT2	POUT2	POUT1	POUT1	POUT1	POUT1
FDEV	0x1C	FDEVSCALE	FDEVSCALE	FDEVSCALE	FDEV	FDEV	FDEV	FDEV	FDEV
GFDIV	0x1D	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV
GFXOSC	0x1E	FHBLANK	reserved	reserved	reserved	GFBYP	GFDIV	GFDIV	GFDIV
ANTTDCC	0x1F	DCCVBYP	DCCDISABLE	DCCCONF	DCCCONF	TUNETOP	TUNETOP	TUNETOP	TUNETOP
RES1	0x20	n.u.	reserved	reserved	reserved	reserved	reserved	reserved	reserved
VAC0	0x21	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR
VAC1	0x22	n.u.	VAC_NXOSC	VAC_NXOSC	VAC_NXOSC	VAC_NXOSC	VAC_NXOSC	VAC_NXOSC	VAC_CTR
RES2	0x23	reserved	reserved	reserved	reserved	reserved	reserved	reserved	reserved
CPCFG	0x24	n.u.	reserved	reserved	reserved	CPTRIM	CPTRIM	CPTRIM	CPTRIM
PLLBW	0x25	reserved	PLLBWTRIM	PLLBWTRIM	PLLBWTRIM	reserved	reserved	reserved	reserved
RES3	0x26	reserved	reserved	reserved	reserved	reserved	reserved	reserved	reserved
ENCCNT	0x27	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT

2.5.2   SFR Detailed Descriptions

ADDR 0x00		SPICHKSUM—SPI Checksum Register					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM	SPICHKSUM
c/0	c/0	c/0	c/0	c/0	c/0	c/0	c/0
Bit <7:0>	SPICHKSUM		SPI checksum bit <7:0>				
SPICHKSUM	Readout and clear the SPI checksum (8-bits), generated by each write to SFR register						

ADDR 0x01		TXSTAT—Transmitter Status Register					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
1	n.u.	LBD_2V1	LBD_2V4	VAC_FAIL	BROUTERR	PARERR	PLLLDER
/	/	r/0	r/0	c/0	c/1	c/0	c/0
Bit 7	1		Mandatory to keep set (1)				
Bit 5	LBD_2V1		battery low detected at 2.1 V				
Bit 4	LBD_2V4		battery low detected at 2.4 V				
Bit 3	reserved		Don't care				
Bit 2	BROUTERR		Brown out detector error				
Bit 1	PARERR		Parity error				
Bit 0	PLLLDER		PLL lock detector error				
LBD_2V1	Battery voltage drop below 2.1 V detected if **1** NOTE: bit invalid in standby mode.						
LBD_2V4	Battery voltage drop below 2.4 V detected if **1** NOTE: bit invalid in standby mode						
BROUTERR	Brownout error detected if **1**						
PARERR	Parity error detected if **1**						
PLLLDERR	PLL lock error detected if **1**						

ADDR 0x04			TXCFG0—Transmitter Configuration Register 0				
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2STDBY	reserved	reserved	FSOFF	ISMB	ISMB	reserved	reserved
cw/0	w/0	w/0	w/0	w/0	w/1	w/1	w/0

Bit 7	GO2STDBY		Go to StandBy
Bit 6	reserved		Reserved, set 0
Bit 5	reserved		Reserved, set to 0
Bit 4	FSOFF		Fail-Safe mechanism turned off
Bit <3:2>	ISMB		RF frequency band bit <1:0>
Bit 1	reserved		Reserved, set to 1
Bit 0	reserved		Reserved, set to 0

GO2STDBY	Put the chip in STDBY mode (look at the detailed state diagram), cleared after 1 is written			
FSOFF	Fail-Safe mechanism			
	0: on		**1**:off	
ISMB	ISM band selection (2-bits)			
	00: MHz 300-320	**01**: MHz 433-450	**10**: MHz 863-870	**11**: MHz 902-928

Important notice: It is mandatory to maintain the default values, as specified in the respective register tables for all

• reserved Special Function Registers (SFR)
• reserved bits
• reserved bit fields

ADDR 0x05	TXCFG1—Transmitter Configuration Register 1						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GO2SLEEP	ASKFSK2	ASKFSK1	ASKSLOPE	INVERT	ENCMODE	ENCMODE	ENCMODE
cw/0	w/0	w/1	w/0	w/0	w/1	w/0	w/1

Bit 7	GO2SLEEP		Go to Sleep
Bit <6:5>	ASKFSK2:1		[ASK / FSK setting 2] and [ASK / FSK setting 1]
Bit 4	ASKSLOPE		ASK sloping enable
Bit 3	INVERT		Data inversion
Bit <2:0>	ENCMODE		Encoding mode bit <2:0>

GO2SLEEP	Set the chip into SLEEP mode (look at the detailed state diagram), cleared after 1 is written	
ASKFSK2:1	[ASK / FSK modulation switch setting 2] and [ASK / FSK modulation switch setting 1]	
	0: ASK	**1**: FSK
ASKSLOPE	ASK sloping enable	
	0: disable	**1**: enable
INVERT	Encoded data inversion enable	
	0: data not inverted	**1**: data inverted
ENCMODE	Encoding mode, code selection (3 bits)	

ENCMODE	Encoding mode, code selection (3 bits)				
	000: Manchester	**010**: Biphase Space	**100**: Miller (Delay)	**110**: Scrambling (PRBS)	
	001: Differential Manchester	**011**: Biphase Mark	**101**: NRZ	**111**: not used (data =0)	

ADDR 0x06		CLKOUTCFG - Clock Pre- and Post-scaler					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CLKSRC	CLKSRC	AFTERSCALE	AFTERSCALE	PRESCALE	PRESCALE	PRESCALE	CLKOUTENA
w/0	w/0	w/0	w/0	w/1	w/0	w/0	w/1

Bit <7:6>	CLKSRC		Clock source selection bit <1:0>
Bit <5:4>	AFTERSCALE		Post scaler selection bit <1:0>
Bit <3:1>	PRESCALE		Pre scaler selection bit <2:0>
Bit 0	CLKOUTENA		Enable clock output

CLKSRC	Clock output selection (2-bits)			
	00: prescaler clock	**01**: BDRDIV counter clock	**10**: inverted BDRDIV counter clock	**11**: afterscaler clock
AFTERSCALE	Post-scaler clock divider selection (2 bits)			
	00: divide by 1	**01**: divide by 2	**10**: divide by 4	**11**: divide by 8
PRESCALE	Pre-scaler clock divider selection (3-bits)			
	000: divide by 1	**001**: divide by 2	**010**: divide by 4	**011**: divide by 8
	100: divide by 16	**101**: divide by 32	**110**: divide by 64	**111**: divide by 128
CLKOUTENA	Clock output enable			
	0: disable, instead of clock, the Crystal Oscillator stable signal causes a rising edge on CLKOUT	**1**: enabled		
	Enabled also automatically, when default clocking (f_{SYS}/16) is used, when the SDI input is low at the rising edge of the EN after power up			

ADDR 0x07		BDRDIV—Bit-rate Divider					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV	BDRDIV
w/1	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	BDRDIV		BDRDIV divider bit <7:0>

BRDRDIV	Along with the pre-scaler and the post-scaler, Bitrate clock divider value (8 bits), defines the data bit-rate, according to following formula.		
	Range:	from **0x00**: BDRDIV = 0	to **0xFF**: BDRDIV = 255
	Formula to calculate the bitrate: $$bitrate = \frac{f_{XOSC}}{PRESCALE \times (BDRDIV + \mathbf{1}) \times \mathbf{2} \times AFTERSCALE}$$		

ADDR 0x08		PRBS—PRBS Start Value					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PRBS	PRBS	PRBS	PRBS	PRBS	PRBS	PRBS	PRBS
w/1	w/0	w/1	w/0	w/1	w/0	w/1	w/1

Bit <7:0>	PRBS		PRBS start value bit <7:0>

PRBS	PRBS start value (8 bits), the PRBS generator uses this as a starting value after each transmission beginning

ADDR 0x09	PLLINTA—PLL MM Integer Value Channel A						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	PLLINTA	PLLINTA	PLLINTA	PLLINTA	PLLINTA	PLLINTA	PLLINTA
/	w/1	w/0	w/0	w/0	w/0	w/0	w/0
Bit <6:0>	PLLINTA			Integer division ratio bit <6:0>			
PLLINTA	Multi-modulus divider integer offset value (7 bits) for **Channel A**						

ADDR 0x0A	PLLFRACA0—PLL Fractional Division Ratio Channel A (byte 0)						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0	PLLFRACA0
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0
Bit <7:0>	PLLFRACA0			Fractional division ratio bit <7:0>			
PLLFRACA0	Synthesizer channel frequency value (21 bits, bits < 7:0 >), fractional division ratio for **Channel A**						

ADDR 0x0B	PLLFRACA1—PLL Fractional Division Ratio Channel A (byte 1)						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1	PLLFRACA1
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0
Bit <7:0>	PLLFRACA1			Fractional division ratio bit <15:8>			
PLLFRACA1	Synthesizer channel frequency value (21 bits, bits < 15:8 >), fractional division ratio for **Channel A**						

ADDR 0x0C		PLLFRACA2—PLL Fractional Division Ratio Channel A (byte 2)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	n.u.	reserved	PLLFRACA2	PLLFRACA2	PLLFRACA2	PLLFRACA2	PLLFRACA2
/	/	w/0	w/1	w/0	w/0	w/0	w/0

Bit 5	reserved		Set to 0. Users are advised to leave the state of this bit unchanged.
Bit <4:0>	PLLFRACA2		Fractional division ratio bit <20:16>

PLLFRACA2	Synthesizer channel frequency value (21 bits, bits < 20:16 >), fractional division ratio for **Channel A**

ADDR 0x0D		PLLINTB—PLL MM Integer Value Channel B					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	PLLINTB	PLLINTB	PLLINTB	PLLINTB	PLLINTB	PLLINTB	PLLINTB
/	w/1	w/0	w/0	w/0	w/0	w/0	w/0

Bit <6:0>	PLLINTB		Integer division ratio bit <6:0>

PLLINTB	Multi-modulus divider integer offset value (7 bits) for **Channel B**

ADDR 0x0E		PLLFRACB0—PLL Fractional Division Ratio Channel B (byte 0)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0	PLLFRACB0
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	PLLFRACB0		Fractional division ratio bit <7:0>

PLLFRACB0	Synthesizer channel frequency value (21 bits, bits < 7:0 >), fractional division ratio for **Channel B**

ADDR 0x0F		PLLFRACB1—PLL Fractional Division Ratio Channel B (byte 1)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1	PLLFRACB1
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	PLLFRACB1		Fractional division ratio bit <15:8>
PLLFRACB1	Synthesizer channel frequency value (21 bits, bits < 15:8 >), fractional division ratio for **Channel B**		

ADDR 0x10		PLLFRACB2—PLL Fractional Division Ratio Channel B (byte 2)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	n.u.	reserved	PLLFRACB2	PLLFRACB2	PLLFRACB2	PLLFRACB2	PLLFRACB2
/	/	w/0	w/1	w/0	w/0	w/0	w/0

Bit 5	reserved		Set to 0. Users are advised to leave the state of this bit unchanged.
Bit <4:0>	PLLFRACB2		Fractional division ratio bit <20:16>
PLLFRACB2	Synthesizer channel frequency value (21 bits, bits < 20:16 >), fractional division ratio for **Channel B**		

ADDR 0x11		PLLINTC—PLL MM Integer Value Channel C					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	PLLINTC	PLLINTC	PLLINTC	PLLINTC	PLLINTC	PLLINTC	PLLINTC
/	w/1	w/0	w/0	w/0	w/0	w/0	w/0

Bit <6:0>	PLLINTC		Integer division ratio bit <6:0>
PLLINTC	Multi-modulus divider integer offset value (7 bits) for **Channel C**		

ADDR 0x12		PLLFRACC0—PLL Fractional Division Ratio Channel C (byte 0)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0	PLLFRACC0
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	PLLFRACC0		Fractional division ratio bit <7:0>

PLLFRACC0	Synthesizer channel frequency value (21 bits, bits < 7:0 >), fractional division ratio for **Channel C**

ADDR 0x13		PLLFRACC1—PLL Fractional Division Ratio Channel C (byte 1)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1	PLLFRACC1
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	PLLFRACC1		Factional division ratio bit <15:8>

PLLFRACC1	Synthesizer channel frequency value (21 bits, bits < 15:8 >), fractional division ratio for **Channel C**

ADDR 0x14		PLLFRACC2—PLL Fractional Division Ratio Channel C (byte 2)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	n.u.	reserved	PLLFRACC2	PLLFRACC2	PLLFRACC2	PLLFRACC2	PLLFRACC2
/	/	w/0	w/1	w/0	w/0	w/0	w/0

Bit 5	reserved		Set to 0. Users are advised to leave the state of this bit unchanged.
Bit <4:0>	PLLFRACC2		Factional division ratio bit <20:16>

PLLFRACC2	Synthesizer channel frequency value (21 bits, bits < 20:16 >), fractional division ratio for **Channel C**

ADDR 0x15		PLLINTD—PLL MM Integer Value Channel D					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	PLLINTD	PLLINTD	PLLINTD	PLLINTD	PLLINTD	PLLINTD	PLLINTD
/	w/1	w/0	w/0	w/0	w/0	w/0	w/0

Bit <6:0>	PLLINTD		Integer division ratio bit <6:0>

PLLINTD	Multi-modulus divider integer offset value (7 bits) for **Channel D**

ADDR 0x16		PLLFRACD0—PLL Fractional Division Ratio Channel D (byte 0)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0	PLLFRACD0
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	PLLFRACD0		Fractional division ratio bit <7:0>

PLLFRACD0	Synthesizer channel frequency value (21 bits, bits < 7:0 >), fractional division ratio for **Channel D**

ADDR 0x17		PLLFRACD1—PLL Fractional Division Ratio Channel D (byte 1)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1	PLLFRACD1
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	PLLFRACD1		Fractional division ratio bit <15:8>

PLLFRACD1	Synthesizer channel frequency value (21 bits, bits < 15:8 >), fractional division ratio for **Channel D**

ADDR 0x18		PLLFRACD2—PLL Fractional Division Ratio Channel D (byte 2)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	n.u.	reserved	PLLFRACD2	PLLFRACD2	PLLFRACD2	PLLFRACD2	PLLFRACD2
/	/	w/0	w/1	w/0	w/0	w/0	w/0

Bit 5	reserved		Set to 0. Users are advised to leave the state of this bit unchanged.
Bit <4:0>	PLLFRACD2		Fractional division ratio bit <20:16>

PLLFRACD2	Synthesizer channel frequency value (21 bits, bits < 20:16 >), fractional division ratio for **Channel D**

ADDR 0x19		SLOPEDIV—ASK Sloping Clock Divider					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV	SLOPEDIV
w/1	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	SLOPEDIV		ASK sloping clock divider bit <7:0>

SLOPEDIV	ASK sloping clock division ratio (10 bits, bits < 7:0 >), defines the slope of the ASK signal shaping using PA power stage switching		
	Range:	from **0x000**: SLOPEDIV = 1	to **0x3FF**: SLOPEDIV = 1024

ADDR 0x1A		POWCFG0—PA Output Power Configuration Register 0					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PA_PS2	PA_PS2	PA_PS2	PA_PS1	PA_PS1	PA_PS1	SLOPEDIV	SLOPEDIV
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:5>	PA_PS2		PA output blocks setting 2 bit <2:0>
Bit <4:2>	PA_PS1		PA output blocks setting 1 bit <2:0>
Bit <1:0>	SLOPEDIV		ASK sloping clock divider bit <9:8>

PA_PS2	Individual control of the 3 PA blocks, setting 2 (3-bits)			
	0: disabled	**1**: enabled	Bit(0) ==> PA block 0	Bit(1) ==> PA block 1	Bit(2) ==> PA block 2
PA_PS1	Individual control of the 3 PA blocks, setting 1(3-bits)			
	0: disabled	**1**: enabled	Bit(0) ==> PA block 0	Bit(1) ==> PA block 1	Bit(2) ==> PA block 2
SLOPEDIV	ASK sloping clock division ratio (10 bits, bits < 9:8 >), defines the frequency of the ASK signal shaping using PA power stage switching			
	Range:	from **0x000**: SLOPEDIV = 1	to **0x3FF**: SLOPEDIV = 1024	

ADDR 0x1B		POWCFG1—PA Output Power Configuration Register 1					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
POUT2	POUT2	POUT2	POUT2	POUT1	POUT1	POUT1	POUT1
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:4>	POUT2		Output power setting 2 bit <3:0>
Bit <3:0>	POUT1		Output power setting 1 bit <3:0>

POUT2	PA output power setting 2 (4 bits), defines the number of enabled PA stages		
	Range:	from **0x0**: POUT2 = 0	to **0xB**: POUT2 = 11 > **0xB**: POUT2 = 11
POUT1	PA output power setting 1 (4 bits), defines the number of enabled PA stages		
	Range:	from **0x0**: POUT1 = 0	to **0xB**: POUT1 = 11 > **0xB**: POUT1 = 11

ADDR 0x1C		FDEV—Frequency Deviation					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FDEVSCALE	FDEVSCALE	FDEVSCALE	FDEV	FDEV	FDEV	FDEV	FDEV
w/1	w/1	w/0	w/1	w/1	w/1	w/1	w/1

Bit <7:5>	FDEVSCALE		Frequency deviation scaling bit <2:0>
Bit <4:0>	FDEV		Frequency deviation bit <4:0>

FDEVSCALE	Scaling of the frequency deviation (3 bits)				
	000: divide by 64	**001**: divide by 32	**010**: divide by 16	**011**: divide by 8	
	100: divide by 4	**101**: divide by 2	**110**: divide by 1	**111**: multiply by2	$value = \dfrac{2^{FDEVSCALE}}{64}$
FDEV	Frequency deviation value (5 bits), defines the multiplication value for the output data from the Gaussian filter (0-31)				

ADDR 0x1D		GFDIV—Gaussian Filter Divider Value					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV	GFDIV
w/0	w/0	w/0	w/0	w/1	w/0	w/0	w/0

Bit <7:0>	GFDIV		Gaussian filter divider bit <7:0>

GFDIV	Gaussian filter clock divider value (11 bits, bits < 7:0 >), defines the sampling ratio of the Gaussian filter; typically this value is set such that the GF divider N_{GF} is 16 x chip-rate (for ideal Gaussian filtering) $$GFDIV = \frac{f_{XOSC}}{chiprate \times NGF} - 1$$

Note: it is recommended to program the **GFDIV** register in such way, that the GF divider N_{GF} is 16 times the chip-rate. This allows optimum Gaussian filtering.

ADDR 0x1E		GFXOSC—Gaussian Filter Configuration					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FHBLANK	reserved	reserved	reserved	GFBYP	GFDIV	GFDIV	GFDIV
w/0	w/1	w/1	w/1	w/1	w/0	w/0	w/0

Bit 7	FHBLANK		Frequency Hopping VAC Disable
Bit <6:4>	reserved		Reserved, set all bits to 1
Bit 3	GFBYP		Gaussian filter bypass
Bit <2:0>	GFDIV		Gaussian filter divider bits <10:8>

FHBLANK	Frequency Hopping, enable/disable VCO Auto Calibration for Channel Hopping		
	0: enable VCO Auto Calibration (default)		**1**: Skip VCO Auto Calibration for frequency hops <1MHz
GFBYP	Gaussian filter bypass:	**0**: GF enabled	**1**: GF bypassed
GFDIV		Gaussian filter clock divider value (11 bits, bits < 10:8 >), defines the sampling ratio of the Gaussian filter, typically this value is set such that the GF divider is 16 x chiprate (for ideal Gaussian filtering) $$GFDIV = \frac{f_{XOSC}}{chiprate \times \mathbf{16}} - \mathbf{1}$$	

ADDR 0x1F		ANTTDCC—Antenna Tuning and Duty Cycle Configurations					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	DCC DISABLE	DCCCONF	DCCCONF	TUNETOP	TUNETOP	TUNETOP	TUNETOP
w/0	w/0	w/1	w/0	w/0	w/0	w/0	w/0

Bit 7	reserved		Reserved, set to 0
Bit 6	DCCDISABLE		Duty cycle control disable
Bit <5:4>	DCCCONF		Duty cycle control delay configuration bit <1:0>
Bit 3:0	TUNETOP		Antenna tuning top (PAOUT pin) bit <3:0>

DCCDISABLE	Duty cycle control disable (must be 0 for ISMB=0)			
	0 enabled		1 disabled (delay = 0ps)	
DCCCONF	Duty cycle control delay configuration (ISMB = 1/2/3, for ISMB = 0 => delay = 0 ps)			
	00: 43% (69/ 35/ 33 ps)	01: 39% (207/ 104/ 98 ps)	10: 35% (346/ 173/ 164 ps)	11: 31% (484/ 242/ 230 ps)
TUNETOP	Antenna tuning top capacitor selection (4-bits):			
	Individual switch of capacitor banks	**0**: switched off	**1**: switched on	
	Bit(0) ==> 60 fF	Bit(1) ==> 120 fF	Bit(2) ==> 240 fF	Bit(3) ==> 480 fF

ADDR 0x20		RES1—Reserved					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	reserved	reserved	reserved	reserved	reserved	reserved	reserved
/	w/1	w/0	w/0	w/1	w/1	w/0	w/0

Bit <7:0>	reserved		Reserved, set bits <6,3,2> to 1 and bits <5, 4, 1, 0> to 0

.

ADDR 0x21		VAC0—VAC Configuration 0					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR	VAC_CTR
w/1	w/1	w/0	w/0	w/1	w/0	w/0	w/0

Bit <7:0>	VAC_CTR		VAC frequency counter value bit <7:0>

VAC_CTR	VCO autocalibration FAST counter (~100 MHz) compare value (9 bits, bits< 7:0 >)

ADDR 0x22		VAC1—VAC Configuration 1					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	reserved	reserved	reserved	reserved	reserved	reserved	VAC_CTR
/	w/1	w/0	w/0	w/0	w/0	w/0	w/0

Bit 7	n.u.		Not used
Bit <6:1>	reserved		Reserved, set bit 6 to 1, bits <5:1> to 0
Bit 0	VAC_CTR		VAC frequency counter value bit 8

VAC_CTR	VCO autocalibration FAST counter (~100 MHz) compare value (9 bits, bit 8)

.

ADDR 0x23		RES2					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	reserved	reserved	reserved	reserved	reserved	reserved	reserved
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0

Bit <7:0>	reserved		Reserved, set to 0

ADDR 0x24		CPCFG—Charge Pump Configurations					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n.u.	reserved	reserved	reserved	CPTRIM	CPTRIM	CPTRIM	CPTRIM
/	w/0	w/1	w/0	w/0	w/1	w/0	w/0

Bit <6:4>	reserved		Reserved
Bit <3:0>	CPTRIM		Charge pump current trimming bit <3:0>

CPTRIM	Charge pump current trimming (4-bits):			
	Range:	from **0x0**: current = 2.5 µA	to **0xF**. current = 40 µA	step: 2.5 µA

*Note: **CPTRIM** bits must be set correlated with PLLBW bits, otherwise loop instability may occur*

ADDR 0x25		PLLBW— PLL Bandwidth Configuration					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	PLLBW TRIM	PLLBW TRIM	PLLBW TRIM	reserved	reserved	reserved	reserved
w/1	w/1	w/0	w/1	w/1	w/0	w/0	w/0

Bit 7	reserved		reserved
Bit <6:4>	PLLBWTRIM		Trim bandwidth of the PLL loop filter bit <2:0>
Bit <3:0>	reserved		reserved

PLLBWTRIM	Trim bandwidth of the PLL loop filter (3 bits):			
	Range:	from **0x1**: BW = 410 kHz	to **0x7**: BW = 150 kHz	Typical step: ~43 kHz

Note: PLLBW must be set together with CPTRIM according to following table:

PLLBWTRIM [kHz]	150	175	230	270	335	375	410
CPTRIM [µA]	5	7.5	12.5	17.5	25	32.5	40

.

ADDR 0x26		RES3—Reserved					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	reserved	reserved	reserved	reserved	reserved	reserved	reserved
w/1	w/1	w/0	w/0	w/0	w/0	w/0	w/0
Bit <7:0>	reserved			Reserved, set bits <7:6> to 1, and bits <5:0> to 0			

.

ADDR 0x27		ENCCNT - Encoding start bit counter					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT	ENCCNT
w/0	w/0	w/0	w/0	w/0	w/0	w/0	w/0
Bit <7:0>	ENCCNT			Encoding start bit counter bit <7:0>			
ENCCNT		Sets the number of bits on start of a telegram which shall be sent unencoded or unscrambled before encoder/scrambler is switched on. This feature is used e.g. to be able to send unscrambled synchronization patterns first.					

3 Applications

In this chapter 3 application examples are listed. The first one is a basic version, demonstrating in terms of simplicity the advantages of transmitter systems built around the TDA5150. The second and third examples are the more elaborate Evaluation Board versions (V2 and V1.1) allowing a higher degree of flexibility and freedom in setup and configuration, if used as evaluation or reference system by customers.
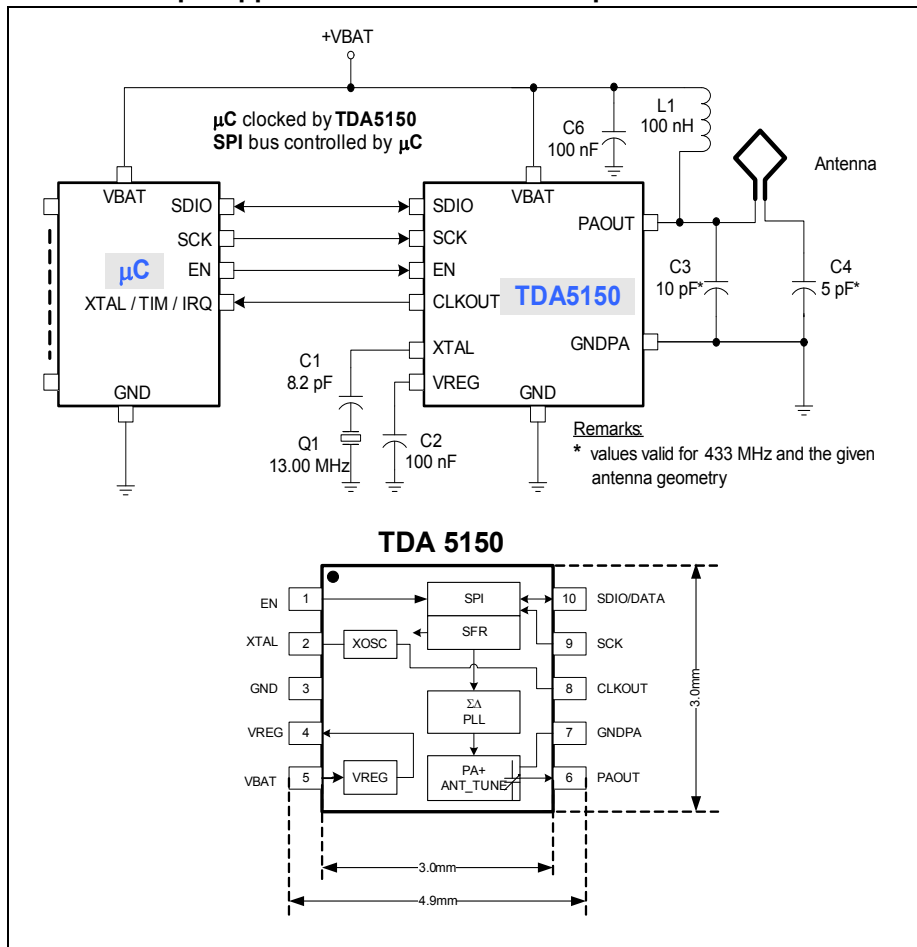
3.1 Simple application schematics example

Figure 23   Simple application example with reduced Bill of Materials list
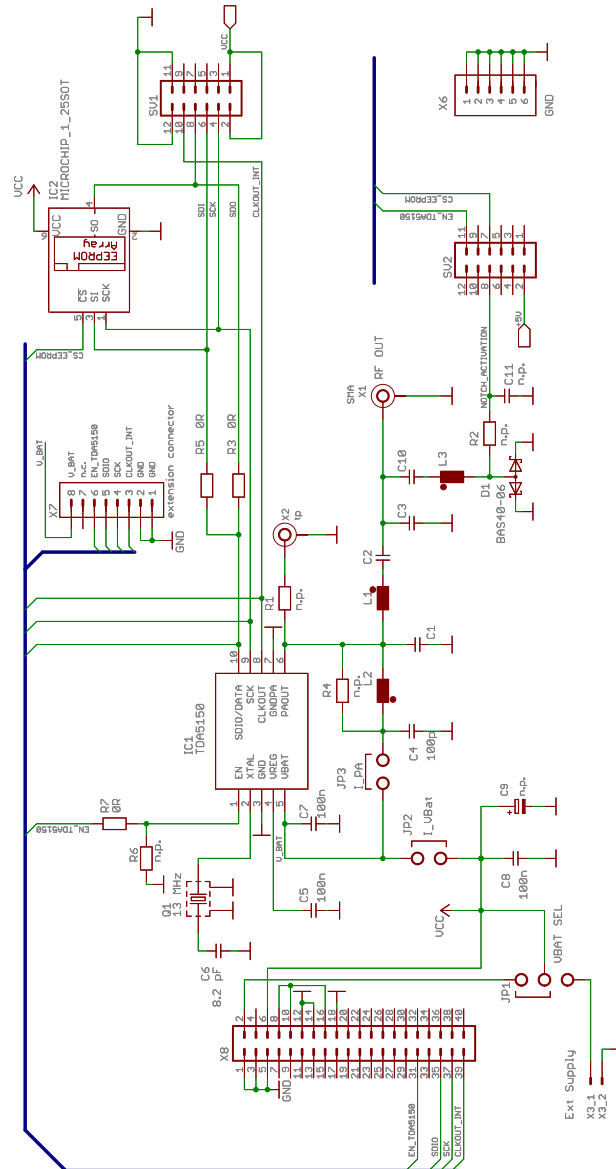
3.2   Infineon Evaluation Board V2

Figure 24   Infineon Evaluation Board V2 schematics

The schematics of a more elaborate solution, the **TDA5150 Evaluation Board V2** is shown in **Figure 24**.

The board can be steered by the System Interface Board (**TDA5150 SIB V1.2**) just in the same way as the **TDA5150 Evaluation Board V1.1**, with the control signals and voltage supply lines applied over connector **X8**, or by an **uW-Link Motherboard**, which is a general propose interface device, used in conjunction with Infineon Technologies AG products. The control and supply lines are applied in this case over the connectors designated as **SV1** and **SV2**.

An on-board serial EEPROM device (IC2) is used for module recognition and parameter storage.

All of the control and supply lines are routed to **X7**, a 100mil pitch standard connector. The user may dock on this connector for signal visualization, bus traffic monitoring or for taking control of an external system, built around a TDA5150 transmitter and using the **uW-Link Motherboard** or **TDA5150 SIB V1.2** interface the as a Host.

This is a really practical solution in early development state of customer projects, as the hardware platform may be developed and the transmitter part tested, under control of software provided by Infineon Technologies AG while the firmware for the final application Host is still in development.

Total current consumption of the transmitter may be monitored by replacing the jumper **JP2** with a milliampermeter. The current drained by the RF power amplifier stage can be measured in a similar manner, if jumper **JP3** is replaced with a milliampermeter.

Infineon Technologies AG delivers a software tool designated TESEUS, which may be used in conjunction with TDA5150 systems for initialization, transmission parameter setup (frequency, modulation mode, transmission speed, encoding etc) and generation of data frames. The specific settings may be stored, retrieved and exported in several formats (C-header or Special Function Register list as text-file) and are displayed in a user-friendly Graphical User Interface (GUI) module.

For details about TESEUS tool please refer to **Chapter 1.5.7**.

The complete documentation of the **TDA5150 Evaluation Board V2** including schematics and layout (as .pdf file), eBOM (spreadsheet) and Gerber files of the printed circuit board can be downloaded, free of charge from the following link **http://www.infineon.com/TDA5150**.

Note: the layout of components and tracks included in reference oscillator block and RF matching network is practically the same on the two Evaluation Board versions (V2 and V1.1). At the same time the nominal value of the components included in the mentioned blocks is the same. Therefore minimum deviation is expected between the performance figures of the two mentioned boards and both may be regarded as equivalents in terms of RF performance.
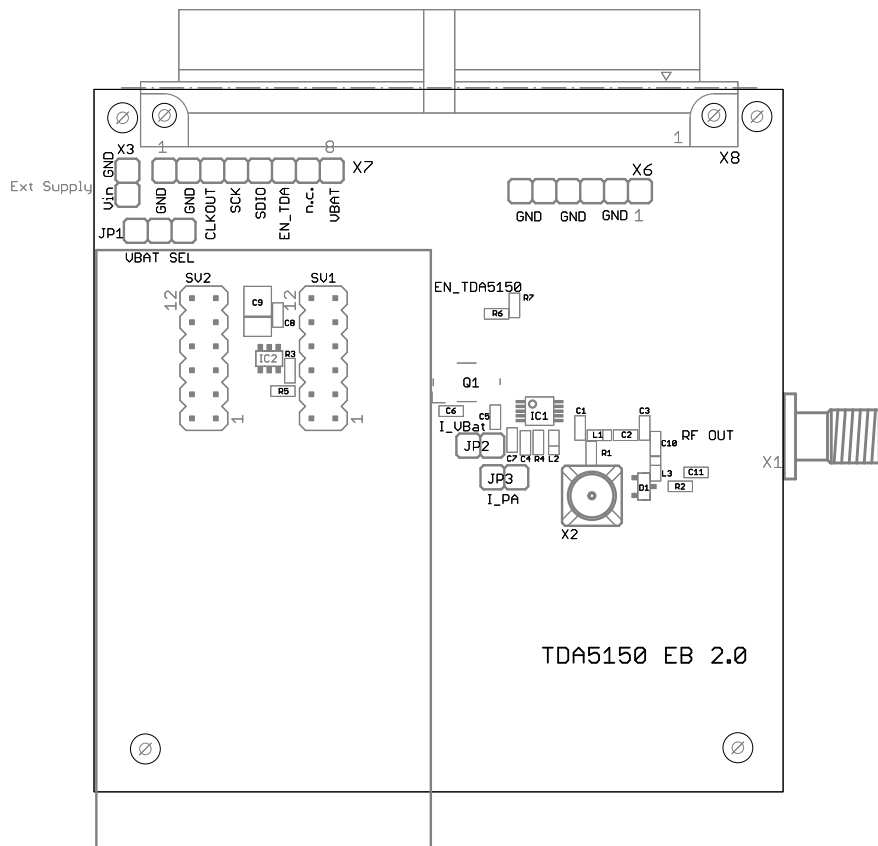
Figure 25   Component placement on Infineon Evaluation Board V2, top side. At bottom left corner the contour of the uW-Link Motherboard is drawn.
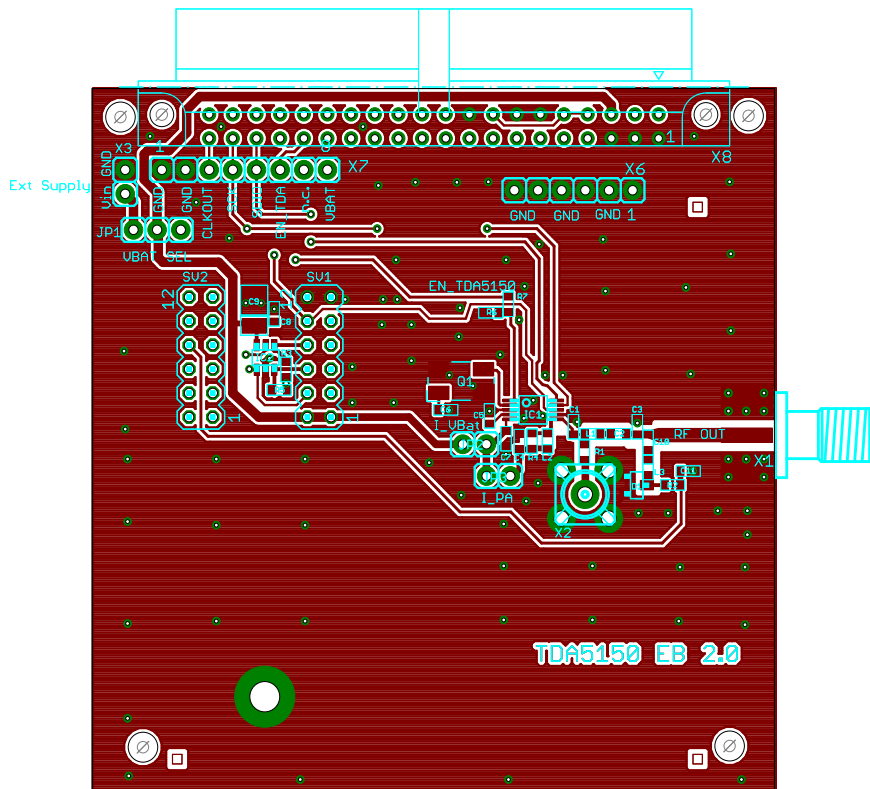
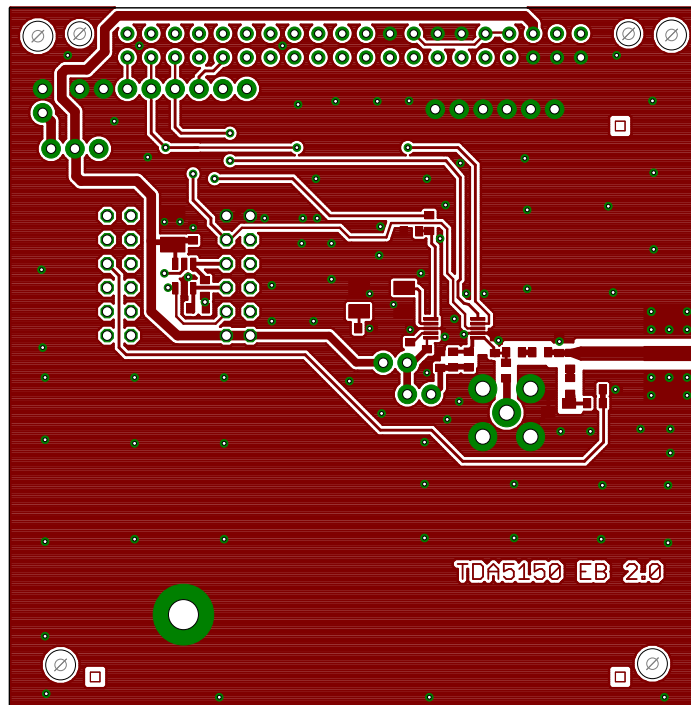**Figure 26   Infineon Evaluation Board V2, top side assembly**

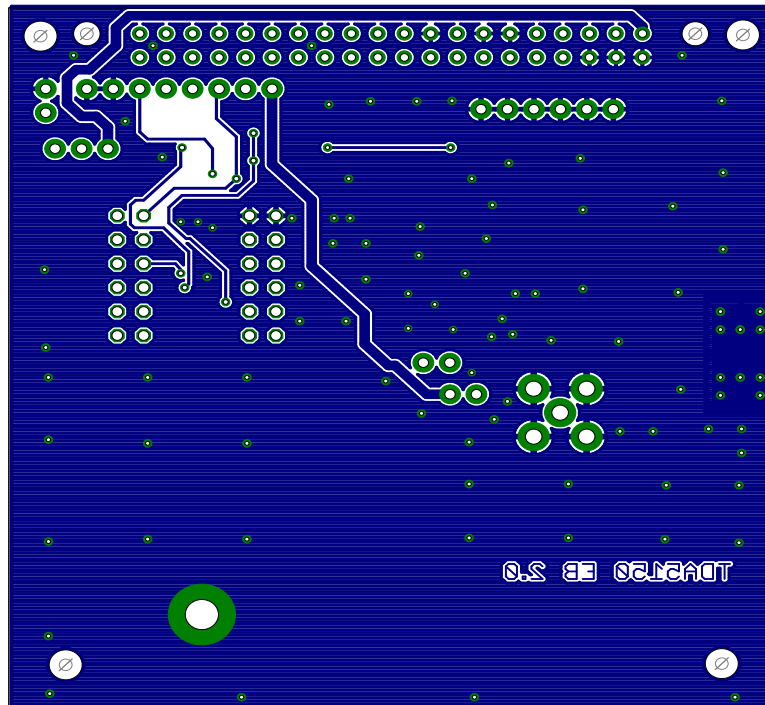**Figure 27   Infineon Evaluation Board V2, top side metal**

Figure 28   Infineon Evaluation Board V2, bottom side metal

Table 5   Bill of Materials, Infineon Evaluation Board V2

| Position	ID	Value	Package	Tol. [%]	Type	Manufacturer	Notes
1	**C1**	see **Table 6**	0603	**Table 6**		Johanson Technology	
2	**C2**	see **Table 6**	0603	**Table 6**		Johanson Technology	
3	**C3**	see **Table 6**	0603	**Table 6**		Johanson Technology	
4	**C4**	100 pF	0603	20		Johanson Technology	
5	**C5**	100 nF	0603	20			
6	**C6**	8.2 pF	0603	see crystal manufacturer specifications for load capacitor value			
7	**C7**	100 nF	0603	20			
8	**C8**	100 nF	0603	20			
9	**C9**	10 uF	0603	20			not placed
10	**C10**		notch filter, value depends on harmonics order				not placed
11	**C11**	100 pF	0603	20			not placed
12	**D1**	BAS 40-06	SOT 23	Low/High band switch		Infineon Technologies	not placed
13	**IC1**	TDA5150	10 pin TSSOP		Tx-chip	Infineon Technologies	
14	**IC2**	25AA04A	6 pin SOT23		SPI 4Kbit EEPROM	Microchip Ltd	
15	**JP1**	jumper	100 mil				
16	**JP2**	jumper	100 mil				
17	**JP3**	jumper	100 mil				
18	**L1**	see **Table 6**	0603	**Table 6**	0603CS	Coilcraft	
19	**L2**	see **Table 6**	0603	**Table 6**	0603CS	Coilcraft	
20	**L3**		0603	notch filter, value depends on harmonics order			not placed
21	**Q1**	13.000 MHz	TSS-5032	10 ppm [1]	EXS00A-CS01623 [2]	NDK model ID NX5032SD for 13 MHz	1) recommended value 2)NDK specification nmb
22	**R1**		0603			not placed, used only for system tests	
23	**R2**	560 Ohm	0603	10			not placed
24	**R3**	0 R	0603				
25	**R4**		0603				not placed
26	**R5**	0 R	0603				
27	**R6**		0603				not placed
28	**R7**	0 R	0603				
29	**SV 1**	connector	100 mil		12 pin	connection to uW-Link Motherboard	
30	**SV 2**	connector	100 mil		12 pin	connection to uW-Link Motherboard	
31	**X1**	connector			SMA		RF port
32	**X2**	connector			SMA	not placed, used only for system tests	
33	**X3**	connector	100 mil		2 pins		External supply
34	**X6**	connector	100 mil		6 pins		GND for probes
35	**X7**	connector	100 mil		8 pins		Test points
36	**X8**	connector			2x20 pin		SIB connector

Note: RF output power and frequency band dependent component values are listed in **Table 6**.

Table 6   Frequency and RF output power dependent component values, Infineon Evaluation Board V2

Frequency band and RF output power	C_1	C_2	C_3	L_1	L_2	Note
315 MHz band						
315_5_dBm	2.7 pF	100 pF	15 pF	72 nH	100 nH	▪ Board version orderable over ISAR
315_8_dBm	2.7 pF	100 pF	10 pF	72 nH	100 nH	
315_10_dBm	2.7 pF	100 pF	5.6 pF	72 nH	100 nH	
434 MHz band						
434_5_dBm	1.5 pF	33 pF	12 pF	51 nH	51 nH	▪ Board version orderable over ISAR
434_8_dBm	1.5 pF	33 pF	6.8 pF	51 nH	51 nH	
434_10_dBm	1.5 pF	33 pF	4.7 pF	51 nH	51 nH	▪ Board version orderable over ISAR
868 MHz band						
868_5_dBm						
868_8_dBm						
868_10_dBm	2.2 pF	68 pF	5.6 pF	10 nH	9.5 nH	▪ Board version orderable over ISAR
915 MHz band						
915_5_dBm						
915_8_dBm						
915_10_dBm	1.5 pF	68 pF	4.7 pF	9.5 nH	8.7 nH	▪ Board version orderable over ISAR
Tolerance	±0.1 pF	2%	2% or ±0.1 pF	2%	2%	

Attention: for the capacitors listed in Table 6 the COG type is recommended. Avoid the usage of XR7 type for those components, as the tolerances and value of thermal coefficient may be rather high.

3.3 Infineon Evaluation board V1.1
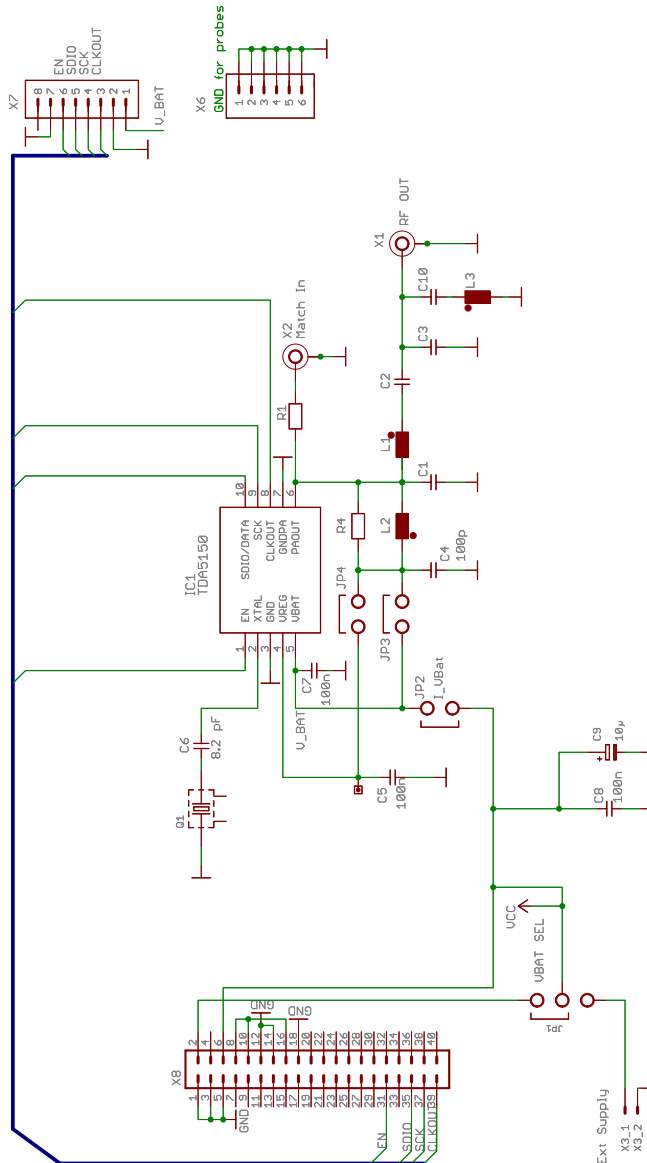
Figure 29 **Schematics of Infineon Evaluation board V1.1**
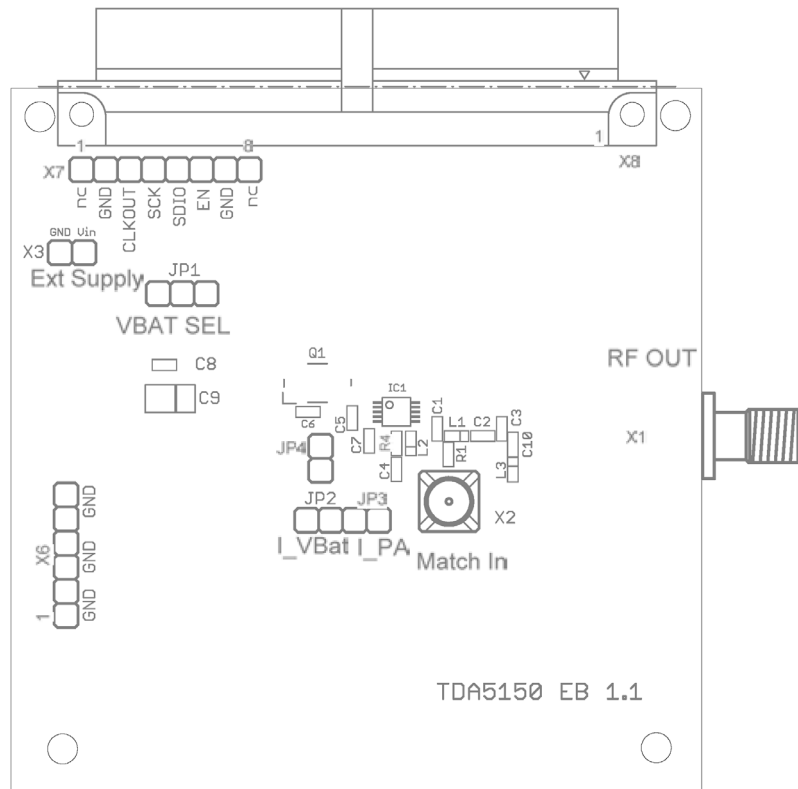
Figure 30   Component placement on Infineon Evaluation Board V1.1, top side)
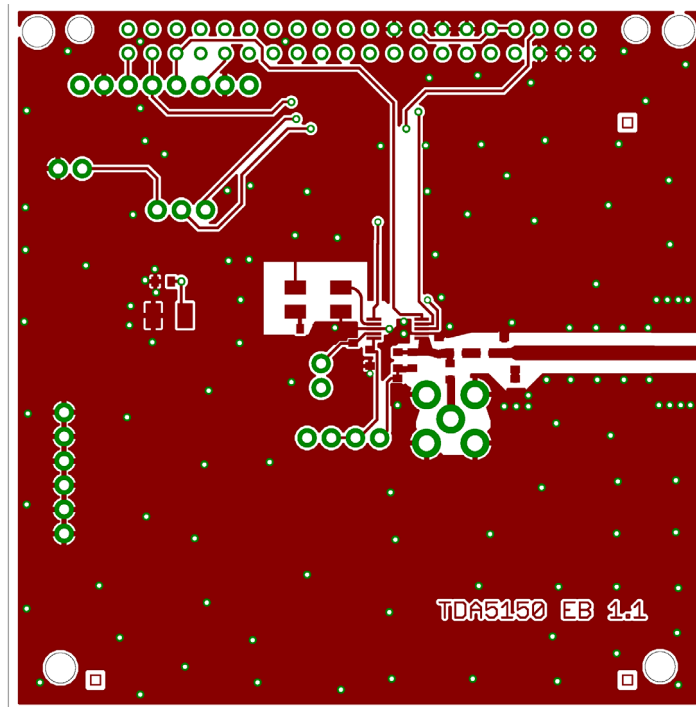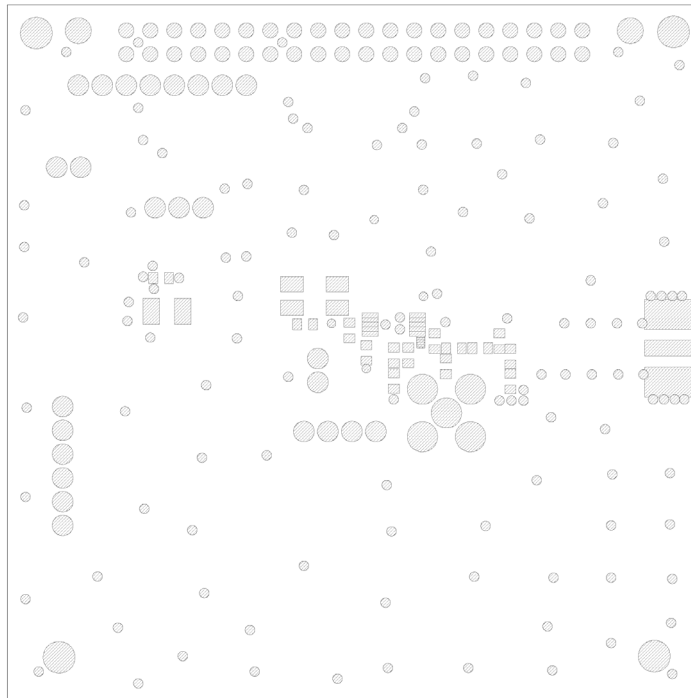
Figure 31   Infineon Evaluation Board V1.1, copper layer on top side

Figure 32   Infineon Evaluation Board V1.1, top side solder mask
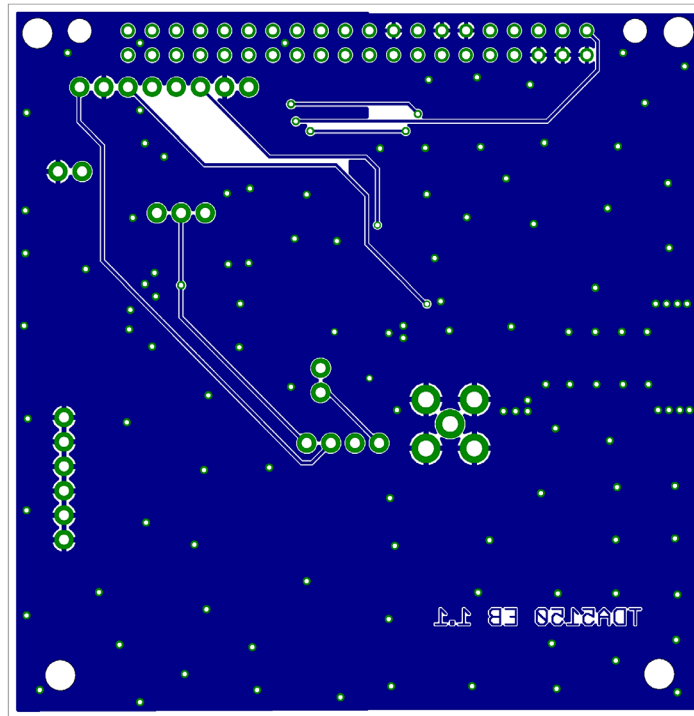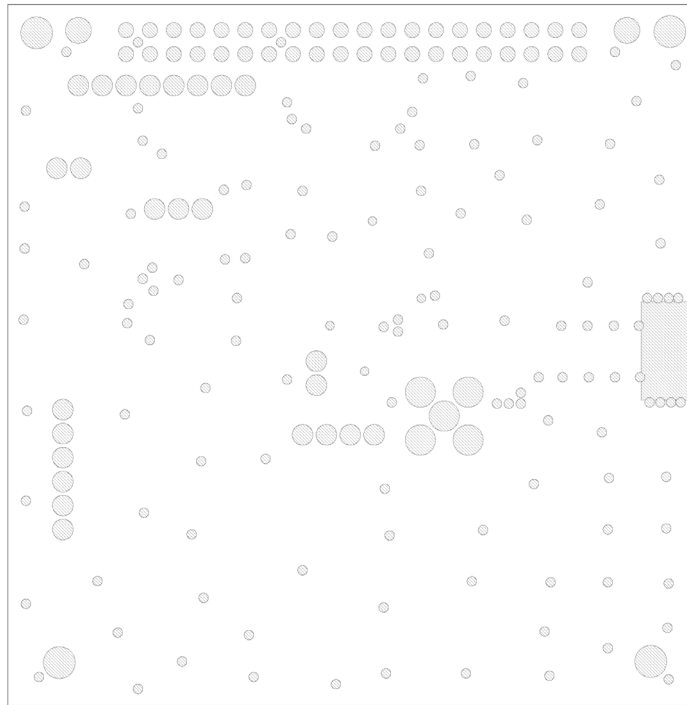
Figure 33   Infineon Evaluation Board V1.1, copper layer on bottom side

Figure 34   Infineon Evaluation Board V1.1, bottom side solder mask
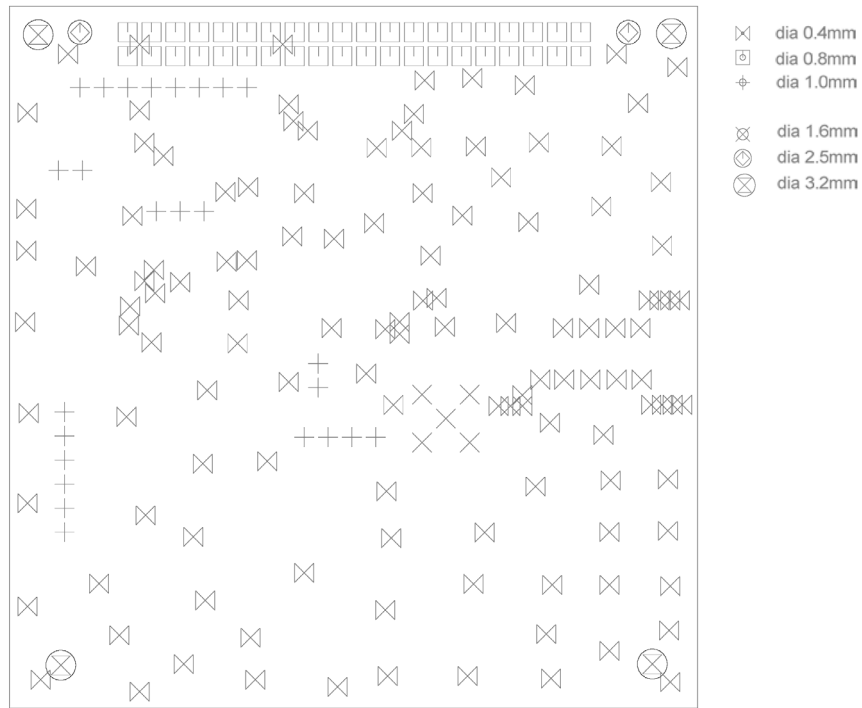
Figure 35   Infineon Evaluation Board V1.1 drill map and tool list

Table 7   Bill of Materials, Infineon Evaluation Board V1.1

Position	ID	Value	Package	Tol. [%]	Type	Manufacturer	Notes
1	C1	see **Table 8**	0603	**Table 8**		Johanson Technology	
2	C2	see **Table 8**	0603	**Table 8**		Johanson Technology	
3	C3	see **Table 8**	0603	**Table 8**		Johanson Technology	
4	C4	100 pF	0603	20		Johanson Technology	
5	C5	100 nF	0603	20			
6	C6	8.2 pF	0603		see crystal manufacturer specifications for load capacitor		
7	C7	100 nF	0603	20			
8	C8	100 nF	0603	20			
9	C9	10 uF	0603	20			not placed
10	C10		0603	notch filter, value depends on harmonics order			not placed
11	IC1	TDA5150	10 pin TSSOP		Tx-chip	Infineon Technologies	
12	JP1	jumper	100 mil				
13	JP2	jumper	100 mil				Test Bridge for TDA5150 current
14	JP3	jumper	100 mil				Test Bridge for RF PA current
15	L1	see **Table 8**	0603	**Table 8**	0603CS	Coilcraft	
16	L2	see **Table 8**	0603	**Table 8**	0603CS	Coilcraft	
17	L3		0603	notch filter, value depends on harmonics order			not placed
18	Q1	13.000 MHz (only for system test, not distribution version 13.560 MHz)	TSS-5032	10 ppm [1]	EXS00A-CS01623 [2] EXS00A-CS0264 [2]	NDK model ID NX5032SD for 13 MHz NX5032SA for 13.56 MHz	1) recommended value 2) NDK specification nmb
19	R1		0603				not placed, only for system test
20	R4		0603				not placed
21	X1	connector			SMA		RF port
22	X2	connector			SMA		not placed, only for system test
23	X3	connector	100 mil		2 pins		External supply
24	X6	connector	100 mil		6 pins		GND for probes
25	X7	connector	100 mil		8 pins		Test points
26	X8	connector			2x20 pin		SIB connector

Note: RF output power and frequency band dependent component values are listed in **Table 8***.*

Table 8 **Frequency and RF output power dependent component values, Infineon Evaluation Board V1.1**

Frequency band and RF output power	C_1	C_2	C_3	L_1	L_2	Note
315 MHz band						
315_5_dBm	2.7 pF	100 pF	15 pF	72 nH	100 nH	■ Board version orderable over ISAR
315_8_dBm	2.7 pF	100 pF	10 pF	72 nH	100 nH	
315_10_dBm	2.7 pF	100 pF	5.6 pF	72 nH	100 nH	
434 MHz band						
434_5_dBm	1.5 pF	33 pF	12 pF	51 nH	51 nH	■ Board version orderable over ISAR
434_8_dBm	1.5 pF	33 pF	6.8 pF	51 nH	51 nH	
434_10_dBm	1.5 pF	33 pF	4.7 pF	51 nH	51 nH	■ Board version orderable over ISAR
868 MHz band						
868_5_dBm						
868_8_dBm						
868_10_dBm	2.2 pF	68 pF	5.6 pF	10 nH	9.5 nH	■ Board version orderable over ISAR
915 MHz band						
915_5_dBm						
915_8_dBm						
915_10_dBm	1.5 pF	68 pF	4.7 pF	9.5 nH	8.7 nH	■ Board version orderable over ISAR
Tolerance	$\pm$0.1 pF	2%	2% or $\pm$0.1 pF	2%	2%	

Attention: for the capacitors listed in Table 8 the COG type is recommended. Avoid the usage of XR7 type for those components, as the tolerances and value of thermal coefficient may be rather high.

Note: the layout of components and tracks included in reference oscillator block and RF matching network is practically the same on the two Evaluation Board versions (V2 and V1.1). At the same time the nominal value of the components included in the mentioned blocks is the same. Therefore minimum deviation is expected between the performance figures of the two mentioned boards and both may be regarded as equivalents in terms of RF performance.

4 Electrical Characteristics

4.1 Absolute Maximum Ratings

Attention: Stresses above the maximum values listed below may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Maximum ratings are absolute ratings; exceeding even one single of the values may cause irreversible damage to the integrated circuit.

Table 9 Absolute Maximum Ratings

	Parameter	Symbol	Values			Unit	Note/ Test Condition
			min.		max.		
A1	Supply voltage	V_{BAT}	-0.3	-	+4	V	
A2	Junction Temperature	T_j	-40		+125	°C	
			-40	-	+150		1) Max. 24 hrs. by T_{max} accumulated over lifetime 2)V_{BAT} =3.6 V
A3	Storage Temperature	T_s	-50	-	+150	°C	Max 1000 hours by Tmax or Tmin
A4	Transient Temperature	T_{tran}		-	+175	°C	Max 180 sec, 10 x Tcycles over lifetime.
A5	ESD HBM integrity (all pins except pin 6, RF-PA output)	V_{HBM}	-4	-	+4	kV	Acc. to JEDEC EIA /JESD22-A114-B
A6	ESD HBM integrity (pin 6)	V_{HBMRF}	-4	-	+4	kV	Acc. to JEDEC EIA /JESD22-A114-B
A7	ESD SDM integrity	V_{SDM}	-500	-	+500	V	All pins except corner pins
			-750	-	+750	V	All corner pins
A8	Latch up	I_{LU}	100	-		mA	AEC-Q100 (transient current)
A9	Maximum Input Voltage @ digital input pins	V_{in}	-0.3	-	V_{BAT} + 0.3	V	

	Parameter	Symbol	Values		Unit	Note/
			min.	max.		Test Condition
A10	Maximum Current into digital input and output pins	I_{IOmax}	-	4	mA	Note 1
A11	Maximum Input Voltage @ XTAL pin (pin 2)	$V_{In,XTAL}$	-0.3	V_{REG} + 0.3		Note 2

Attention: It is not allowed to apply higher voltages than specified by *A9*, even if the current is limited to values below threshold listed in line *A10*. The voltage limiting effect of the internal ESD structures shall not be used as "level shifter" by interconnection(s) to digital logic with higher output voltage!

Note: V_{REG} is the output voltage of the internal voltage regulator, accessible on pin 4, (designated as VREG).

4.2 Operating Range

Table 10 Supply Voltage Operating Range and Temperature Operating Range

	Parameter	Symbol	Values			Unit	Note/
			min.	typ	max.		Test Condition
B1	Supply Voltage	V_{BAT}	1.9	-	3.6	V	[-40..+85] °C
B2	Operating Temperature	T_{amb}	-40	-	+85	°C	

4.2.1 AC/DC Characteristics

Supply voltage V_{BAT} = 1.9 V ... 3.6 V; Ambient temperature T_{amb} =[-40...+85] ^{o}C, unless otherwise specified. Maximum 10 pF capacitive load at CLKOUT (pin 8).

Clock frequency on CLKOUT (pin 8) is f_{CLKOUT} = f_{XTAL} / 16 (as specified by after reset state).

Attention: Test Status ■ denotes that the parameter is not subject to production test. It was verified by design and/or characterization.

Table 11   AC/DC Characteristics

	Parameter	Symbol	Limit Values			Unit	Test Status	Test Conditions Remarks
			min	typ	max			
C1	Transmit Frequency Bands	f_{TX}	300 433 863		320 450 928	MHz MHz MHz		
C2	Modulation Types		ASK (OOK); FSK(CPFSK); GFSK					
C3	Encoding Modes		Manchester, differential Manchester, Miller, Biphase-mark, Biphase-space, scrambled NRZ					
C4	Chip Rate		0.5		100	kchip/s	■	See **Chapter 2.4.4** for chip rate definition
C5	Carrier Frequency Step	f_{step}			7	Hz	■	$f_{crystal}$ / 2exp(21)
C6	Frequency Deviation	f_{dev}	1		64	kHz	■	See **Chapter 2.4.7** for frequency shift programming and calculations
C7	Crystal Frequency Range	f_{XTAL}	12		14	MHz	■	Total max. capacity (incl. parasitics) between XTAL and GND pins max. 4 pF
C8	Crystal Osc Margin	R_{START} [1]	|-500|			Ohm		1)$f_{crystal}$ = 13.56 MHz T_{amb} = 25 °C
		L_{OSC}	3.85	5.5	7.15	µH	■	

	Parameter	Symbol	Limit Values			Unit	Test Status	Test Conditions Remarks
			min	typ	max			
C9	XTAL Startup Time	t_{XTAL}			1	ms		with crystal NDK NX5032SA on TDA5150 Evaluation Board
C10	CLKOUT Output Frequency	f_{CLKOUT}			14	MHz		For divider ratio calculations see **Chapter 2.4.5.1**
C11	Voltage Regulator Output Voltage	V_{REG}		2.1[1] [2]		V		100 nF decoupling on VREG pin. No external DC load allowed [1]V_{BAT} = 3V@27°C [2]$V_{BAT} \geq 2.2$ V for effective regulator operation
C12	Supply Current Sleep Mode	I_{sleep}		0.4[1]	2.5[2]	µA		[1]by T = 27 °C [2]by Tmax = 85 °C
C13	Supply Current Standby Mode	$I_{standby}$		0.5[1]	6[2]	µA		[1]by T = 27 °C [2]by Tmax = 85 °C
C14	Low-Battery Detector Threshold	$V_{LBD\_2.1}$	2.0	-	2.2	V		monitored @V_{BAT}
		$V_{LBD\_2.4}$	2.3	-	2.5	V		
C15	Brownout Detector Voltage Threshold	V_{BOD}	1.7	-	1.8	V		in Active Mode monitored @V_{REG}
		V_{BOD}	0.7	-	1.7	V		in Standby Mode monitored @V_{REG} and @V_{BAT}
C16	Supply Current PLL is ON PA is OFF @315/434 MHz	$I_{pllenable}$		6.3	8	mA		V_{BAT} =3 V

	Parameter	Symbol	Limit Values			Unit	Test Status	Test Conditions Remarks
			min	typ	max			
C17	Supply Current PLL is ON PA is OFF @868/915 MHz	$I_{pllenable}$		6.6	8.5	mA		V_{BAT} =3 V
C18	Supply Current Transmit Mode @315/434 MHz	I_{T5dbm}		9	12	mA	1)	1)@P_{out} = +5/8/10 dBm measured with 50 Ohms load 2)V_{BAT} =3 V
		I_{T8dbm}		11	14	mA		
		I_{T10dbm}		13	16	mA	2)	
C19	Supply Current Transmit Mode @868/915 MHz	I_{T5dbm}		11	14	mA	1)	1)@P_{out}= + 5/8/10 dBm measured with 50 Ohms load 2) V_{BAT} = 3V
		I_{T8dbm}		13	16	mA		
		I_{T10dbm}		16	19	mA	2)	
C20	Power Level Tolerance vs. nominal value	$P_{var5dbm}$	-1.5		+1.5	dB	1)	Referenced to V_{BAT} = 3V @27°C (not including matching network comp. tolerance) 1)315 & 434 MHz band 2)868 & 915 MHz band
		$P_{var8dbm}$					1)	
		$P_{var10dbm}$					1)	
		$P_{var5dbm}$	-2		+2	dB	2)	
		$P_{var8dbm}$					2)	
		$P_{var10dbm}$					2)	
C21	Power Level Variation vs. temperature	$P_{var5dbm}$	-1.5		+1.5	dB	■	T_{amb} =[-40..+85] °C V_{BAT}= 3 Volt RF P_o measured on Evaluation Board
		$P_{var8dbm}$	-1.5		+1.5	dB	■	
		$P_{var10dbm}$	-1.5		+1.5	dB	■	
C22	Power Level Variation vs. battery voltage	$P_{var5dbm}$		5.5	7	dB		V_{BAT}=[1.9...3.6] V RF P_o measured on IFX Evaluation Boards
		$P_{var8dbm}$		5.5	7	dB		
		$P_{var10dbm}$		5.5	7	dB		
C23	Power Level Step Size	$P_{delta step}$	1	2	3	dB		maximum 10 steps

	Parameter	Symbol	Limit Values			Unit	Test Status	Test Conditions Remarks
			min	typ	max			
C24	PLL bandwidth		150[1]		410[1]	kHz	■	1) the PLL bandwidth is programable.SFR **CPTRIM** (0x24.3:0) controls the chargepump current and SFR **PLLBW TRIM** (0x25.6:4)fis the selector for loop filter damping resistor value

150 kHz is the smallest and 410 kHz the largest **nominal** PLL BW. See **Table2** for **PLL recommended settings** |
C25	Band Switching Time	$t_{bandswitch}$			100	us		jump between band end frequencies $[f_{min .. } f_{max}]$
C26	Channel Switching Time	$t_{chswitch}$		20		us	■	1 MHz hop away from adj. channel
C27	SSB Phase Noise @ 315/434 MHz PLLBW = 150 kHz			-86	-80	dBc/Hz		@ 10 kHz offset, +27 °C
				-86	-80	dBc/Hz		@ 100 kHz offset, +27 °C
				-105	-100	dBc/Hz	■	@ 1 MHz offset, +27 °C
				-135	120	dBc/Hz	■	@ 10 MHz offset, +27°C

	Parameter	Symbol	Limit Values			Unit	Test Status	Test Conditions Remarks
			min	typ	max			
C28	SSB Phase Noise @ 868/915MHz PLLBW = 150 kHz			-80	-75	dBc/Hz		@ 10 kHz offset, +27 °C
				-80	-75	dBc/Hz		@ 100 kHz offset, +27 °C
				-105	-100	dBc/Hz	■	@ 1 MHz offset, +27 °C
				-135	-120	dBc/Hz	■	@ 10 MHz offset, +27 °C

4.3 SPI Characteristics

Attention: Test Status ■ denotes that the parameter is not subject to production test. It was verified by design and/or characterization.

Table 12 SPI Timing Characteristics

	Parameter	Symbol	Values			Unit	Test Status	Note/ Test Condition
			min	typ	max			
D1	Clock Frequency	f_c			2	MHz	■	
D2	Clock High Time	t_{CH}	150			ns	■	
D3	Clock Low Time	t_{CL}	150			ns	■	
D4	Active SetUp Time	t_{SSu}	20			ns	■	
D5	Not Active Hold Time	t_{EN}	20			ns	■	
D6	Active Hold Time	t_{SHo}	20			ns	■	
D7	Not Active SetUp Time	t_{NEN}	20			ns	■	
D8	Deselect Time	t_{DS}	150			ns	■	
D9	Input Data SetUp Time	t_{IDSu}	50			ns	■	
D10	Input Data Hold Time	t_{IDHo}	50			ns	■	
D11	Clock to Output Data Valid @ 20pF Load	t_{CODV}			150	ns	■	
D12	Output Data Rise Time @ 20pF Load	t_{ODri}			25	ns	■	
D13	Output Data Fall Time @ 20pF Load	t_{ODfa}			25	ns	■	

	Parameter	Symbol	Values			Unit	Test Status	Note/ Test Condition
			min	typ	max			
D14	Input Data Tristate Setup Time	t_{IDZSu}	0			ns	■	
D15	Output Data Disable Time	t_{NODZ}			150	ns	■	

Table 13   SPI Electrical Characteristics

|	Parameter	Symbol	Values min	typ	max	Unit	Test Status	Note/Test Condition
E1	Input Low Voltage	V_{IL}	-0.2	-	0.4	V		Pins EN, SCK, SDIO
E2	Input High Voltage	V_{IH}	$V_{BAT}-0.4$	-	$V_{BAT}+0.2$	V		Pins EN, SCK, SDIO
E3	Output Low Voltage	V_{OH}			0.5	V		Pins SDIO, CLKOUT
E4	Output High Voltage	V_{OH}	$V_{BAT}-0.5$			V		Pins SDIO, CLKOUT
E5	SPIO pin drive capability	V_{OH}	750			Ohm	■	current source V_{BAT} @3.6 V and +85 °C T_{amb}
E6	SPIO pin drive capability	V_{OL}	500			Ohm	■	current sink V_{BAT} @3.6 V and +85 °C T_{amb}
E7	Parasitic capacitance	C_{pad}			5	pF	■	
E8	Internal Pull-down Resistor	R_{down}	175	250	360	kOhm	■	

5 Package Outline
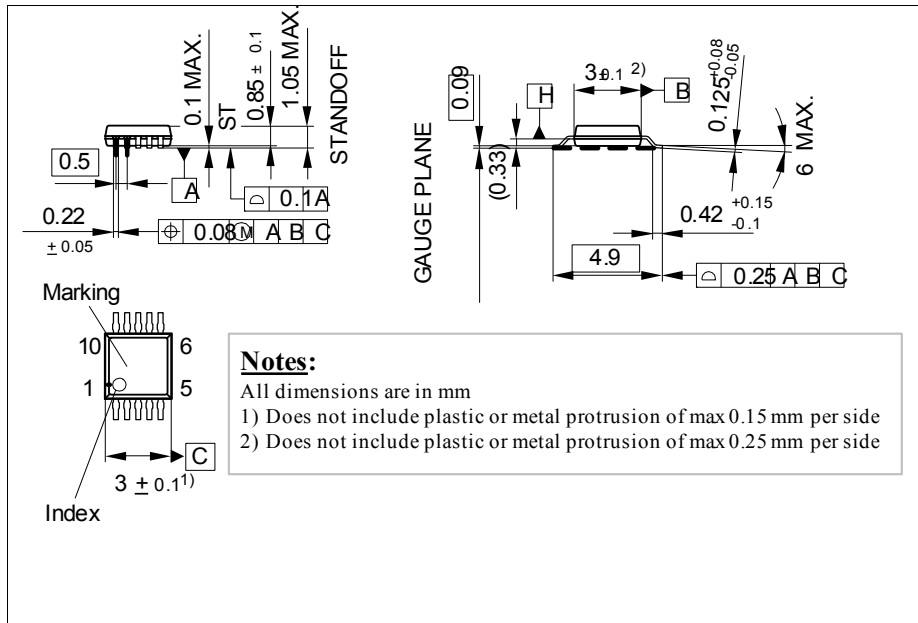
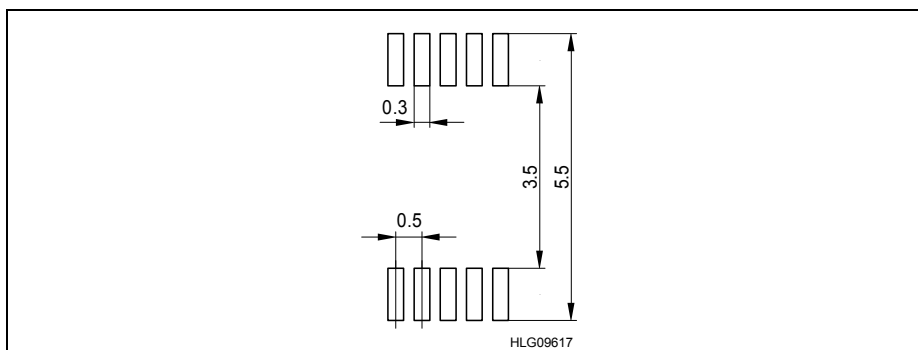**Figure 36   Green Package TSSOP-10 outline**

Figure 37   Footprint TSSOP-10 package

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