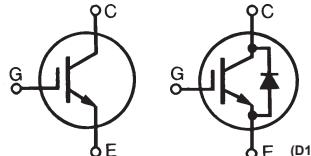


# HiPerFAST™ IGBT ISOPLUS247™ (Electrically Isolated Back Surface)

**IXGR 50N60B**      **IXGR 50N60BD1**

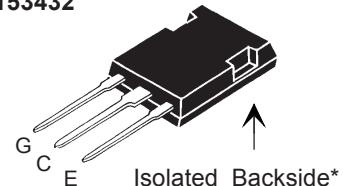
$V_{CES}$	=	600	V
$I_{C25}$	=	75	A
$V_{CE(sat)}$	=	2.5	V
$t_{fi(ty)}$	=	85	ns



Symbol	Test Conditions	Maximum Ratings		
$V_{CES}$	$T_J = 25^\circ\text{C}$ to $150^\circ\text{C}$	600	V	
$V_{CGR}$	$T_J = 25^\circ\text{C}$ to $150^\circ\text{C}$ ; $R_{GE} = 1 \text{ M}\Omega$	600	V	
$V_{GES}$	Continuous	$\pm 20$	V	
$V_{GEM}$	Transient	$\pm 30$	V	
$I_{C25}$	$T_c = 25^\circ\text{C}$	75	A	
$I_{C110}$	$T_c = 110^\circ\text{C}$	45	A	
$I_{CM}$	$T_c = 25^\circ\text{C}$ , 1 ms	200	A	
<b>SSOA (RBSOA)</b>	$V_{GE} = 15 \text{ V}$ , $T_{VJ} = 125^\circ\text{C}$ , $R_G = 10 \Omega$ Clamped inductive load, $L = 100 \mu\text{H}$	$I_{CM} = 100$ @ $0.8 V_{CES}$	A	
$P_c$	$T_c = 25^\circ\text{C}$	250	W	
$T_J$		-55 ... +150	$^\circ\text{C}$	
$T_{JM}$		150	$^\circ\text{C}$	
$T_{stg}$		-55 ... +150	$^\circ\text{C}$	
Maximum lead temperature for soldering 1.6 mm (0.062 in.) from case for 10 s		300	$^\circ\text{C}$	
$V_{ISOL}$	50/60 Hz, RMS, $t = 1$ minute leads-to-tab	2500	V	
<b>Weight</b>		5	g	

Symbol	Test Conditions	Characteristic Values		
		( $T_J = 25^\circ\text{C}$ , unless otherwise specified)		
		Min.	Typ.	Max.
$V_{GE(th)}$	$I_c = 250 \mu\text{A}$ , $V_{CE} = V_{GE}$ $I_c = 500 \mu\text{A}$	50N60B 50N60BD1	2.5 2.5	5.0 V 5.0 V
$I_{CES}$	$V_{CE} = 600 \text{ V}$ $V_{GE} = 0 \text{ V}$	50N60B 50N60BD1 50N60B $T_J = 125^\circ\text{C}$ 50N60BD1		200 $\mu\text{A}$ 650 $\mu\text{A}$ 1 mA 5 mA
$I_{GES}$	$V_{CE} = 0 \text{ V}$ , $V_{GE} = \pm 20 \text{ V}$			$\pm 100$ nA
$V_{CE(sat)}$	$I_c = I_T$ , $V_{GE} = 15 \text{ V}$			2.5 V

## ISOPLUS 247



G = Gate, C = Collector

\*

Patent pending

## Features

- DCB Isolated mounting tab
- Meets TO-247AD package Outline
- High current handling capability
- Latest generation HDMOS™ process
- MOS Gate turn-on
  - drive simplicity

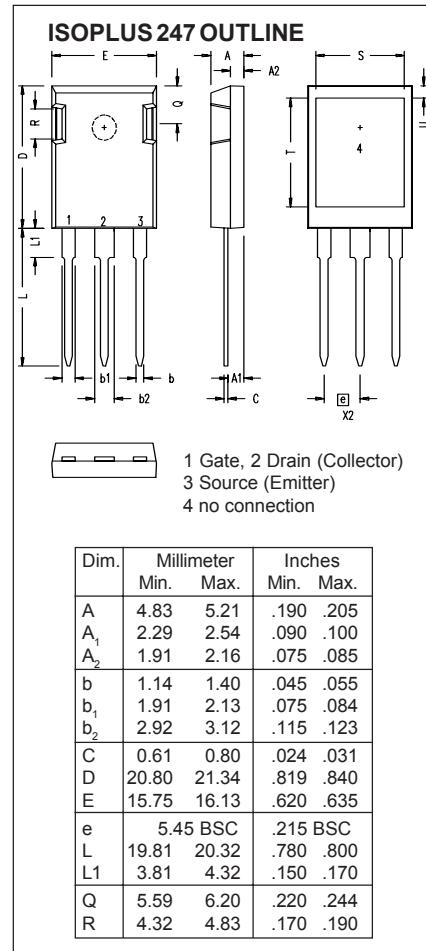
## Applications

- Uninterruptible power supplies (UPS)
- Switched-mode and resonant-mode power supplies
- AC motor speed control
- DC servo and robot drives
- DC choppers

## Advantages

- Easy assembly
- High power density
- Very fast switching speeds for high frequency applications

Symbol	Test Conditions	Characteristic Values			
		( $T_J = 25^\circ\text{C}$ , unless otherwise specified)	min.	typ.	max.
$g_{fs}$	$I_C = I_T; V_{CE} = 10 \text{ V},$ Pulse test, $t \leq 300 \mu\text{s}$ , duty cycle $\leq 2\%$	25	35	S	
$C_{ies}$	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$	4100		pF	
$C_{oes}$		300		pF	
$C_{res}$		50		pF	
$Q_g$	$I_C = I_T, V_{GE} = 15 \text{ V}, V_{CE} = 0.5 V_{CES}$	110		nC	
$Q_{ge}$		30		nC	
$Q_{gc}$		35		nC	
$t_{d(on)}$	<b>Inductive load, <math>T_J = 25^\circ\text{C}</math></b> $I_C = I_T, V_{GE} = 15 \text{ V}, L = 100\mu\text{H}$ $V_{CE} = 0.8 \cdot V_{CES}, R_G = R_{off} = 2.7 \Omega$ Remarks: Switching times may increase for $V_{CE}$ (Clamp) $> 0.8 \cdot V_{CES}$ , higher $T_J$ or increased $R_G$	50		ns	
$t_{ri}$		50		ns	
$t_{d(off)}$		110	270	ns	
$t_{fi}$		85	150	ns	
$E_{off}$		3.0	4.0	mJ	
$t_{d(on)}$	<b>Inductive load, <math>T_J = 125^\circ\text{C}</math></b> $I_C = I_T, V_{GE} = 15 \text{ V}, L = 100\mu\text{H}$ $V_{CE} = 0.8 \cdot V_{CES}, R_G = R_{off} = 2.7 \Omega$ Remarks: Switching times may increase for $V_{CE}$ (Clamp) $> 0.8 \cdot V_{CES}$ , higher $T_J$ or increased $R_G$	50		ns	
$t_{ri}$		60		ns	
$E_{on}$		3		mJ	
$t_{d(off)}$		200		ns	
$t_{fi}$		250		ns	
$E_{off}$		4.2		mJ	
$R_{thJC}$			0.5	K/W	
$R_{thCK}$			0.15	K/W	



Symbol	Test Conditions	Characteristic Values			
		( $T_J = 25^\circ\text{C}$ , unless otherwise specified)	min.	typ.	max.
$V_F$	$I_F = I_T, V_{GE} = 0 \text{ V},$ Pulse test, $t \leq 300 \text{ ms}$ , duty cycle $\leq 2\%$		1.6	V	
			2.5	V	
$I_{RM}$	$I_F = I_T, V_{GE} = 0 \text{ V}, -di_F/dt = 100 \text{ A/ms}, T_J = 100^\circ\text{C}$ $V_R = 100 \text{ V}$	3.2		A	
$t_{rr}$	$I_F = 1 \text{ A}; -di/dt = 200 \text{ A/ms}; V_R = 30 \text{ V}$	35		ns	
				ns	
$R_{thJC}$			0.85	K/W	

Note:  $I_T = 50\text{A}$

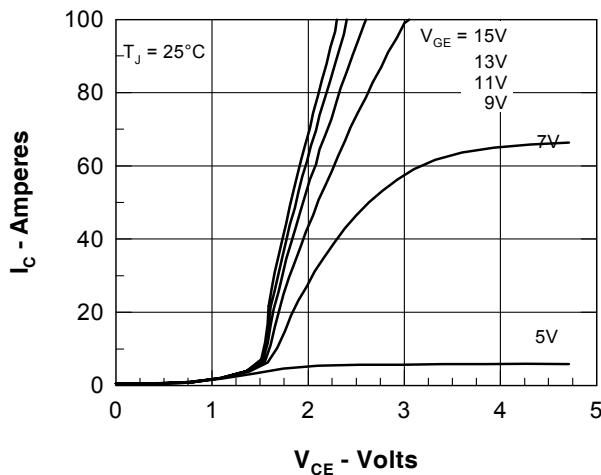


Fig. 1. Saturation Voltage Characteristics

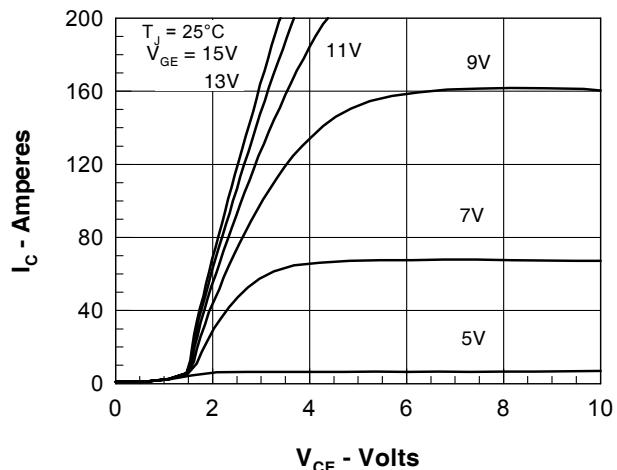


Fig. 2. Extended Output Characteristics

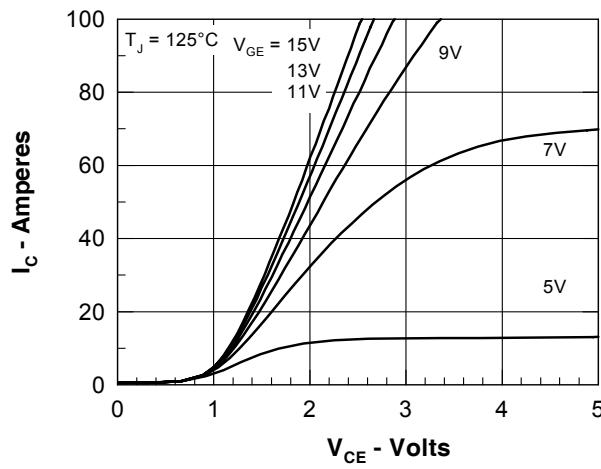


Fig. 3. Saturation Voltage Characteristics

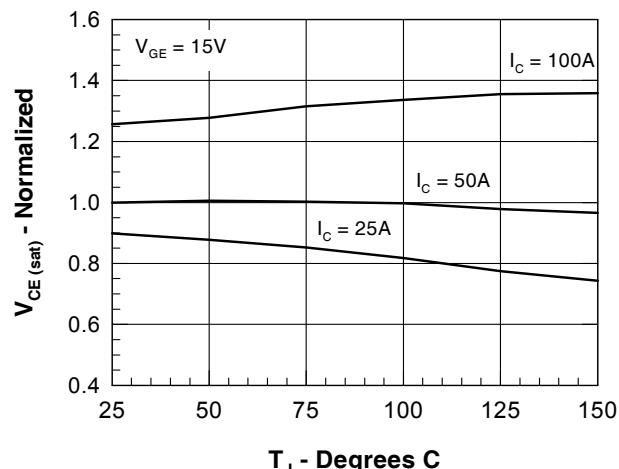


Fig. 4. Temperature Dependence of  $V_{CE(sat)}$

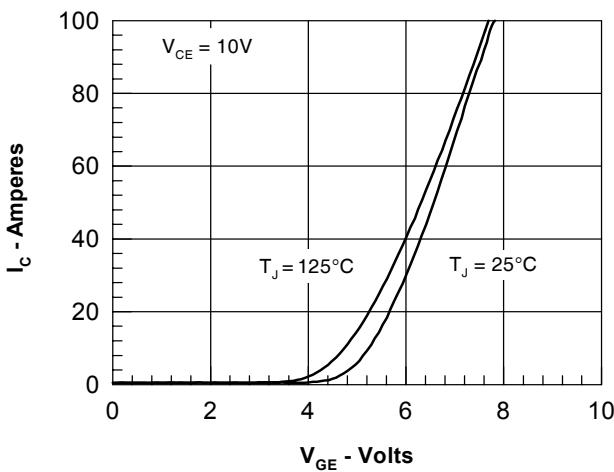


Fig. 5. Saturation Voltage Characteristics

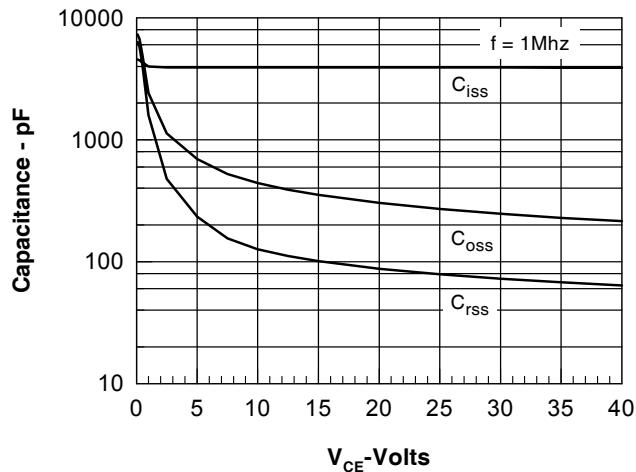


Fig. 6. Junction Capacitance Curves

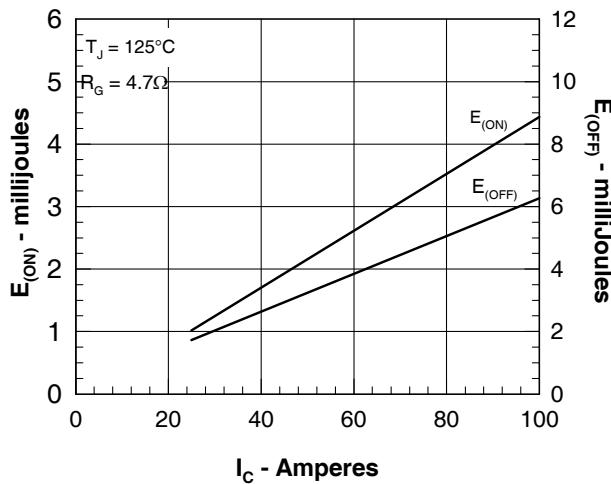


Fig. 7. Dependence of  $E_{(ON)}$  and  $E_{(OFF)}$  on  $I_C$ .

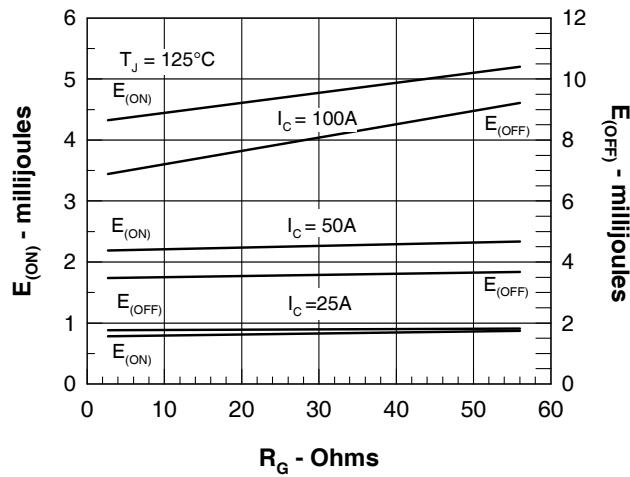


Fig. 8. Dependence of t<sub>fi</sub> and  $E_{(OFF)}$  on  $R_G$ .

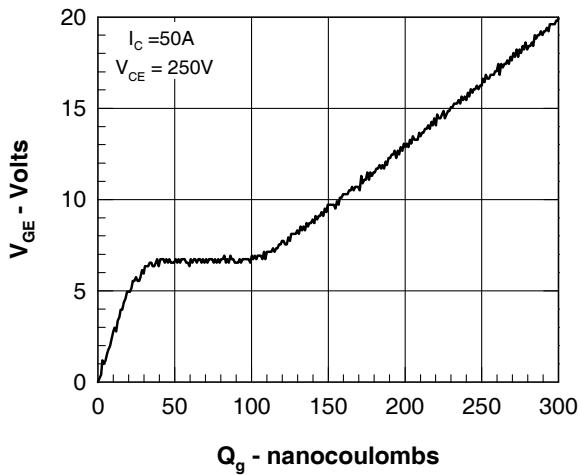


Fig. 9. Gate Charge

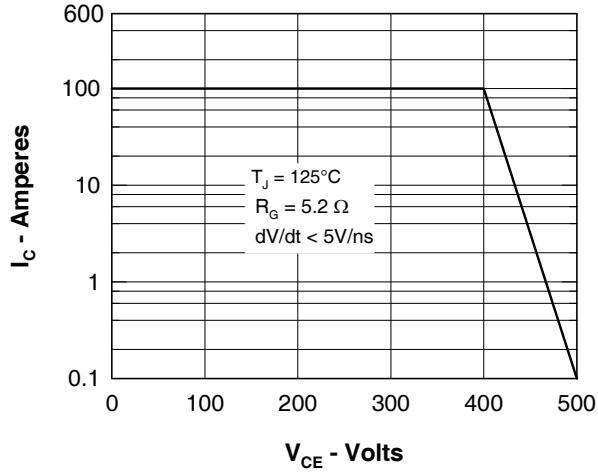


Fig. 10. Turn-off Safe Operating Area

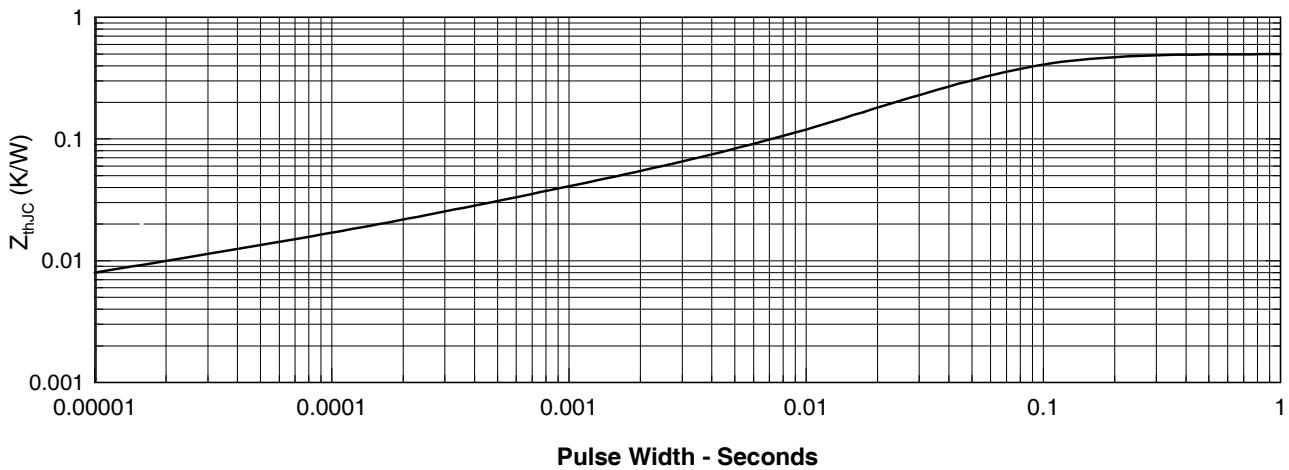


Figure 11. IGBT Transient Thermal Resistance

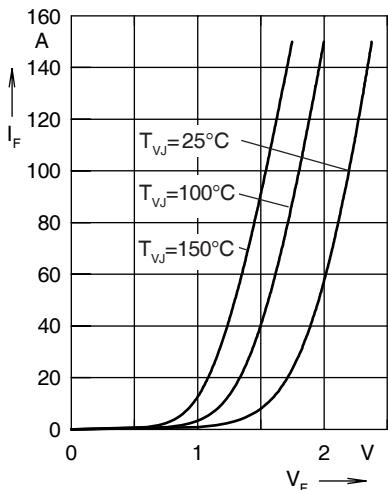


Fig. 12 Forward current  $I_F$  versus  $V_F$

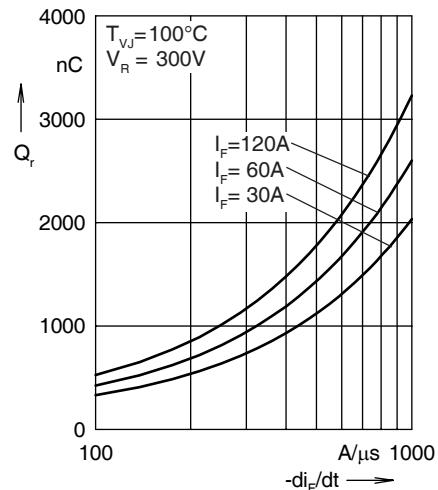


Fig. 13 Reverse recovery charge  $Q_r$  versus  $-di_F/dt$

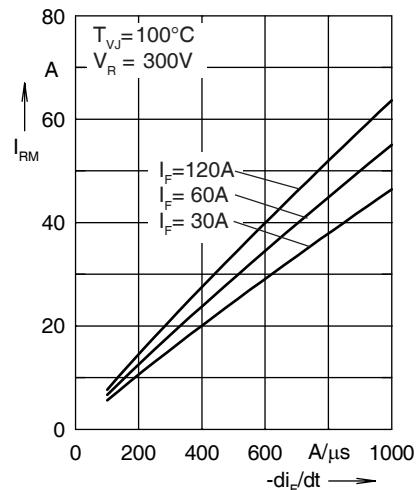


Fig. 14 Peak reverse current  $I_{RM}$  versus  $-di_F/dt$

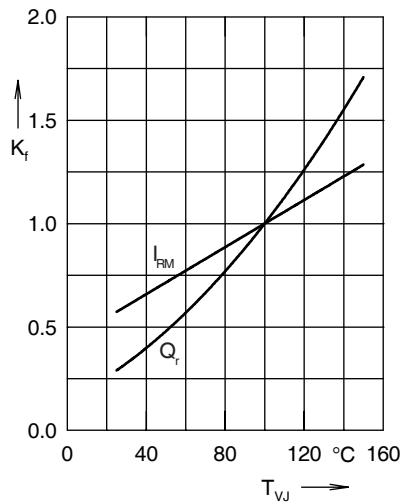


Fig. 15 Dynamic parameters  $Q_r$ ,  $I_{RM}$  versus  $T_{VJ}$

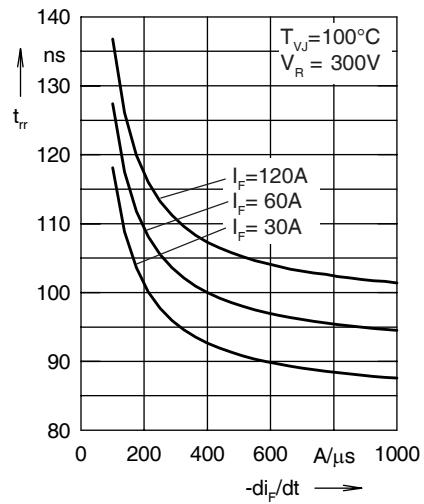


Fig. 16 Recovery time  $t_{rr}$  versus  $-di_F/dt$

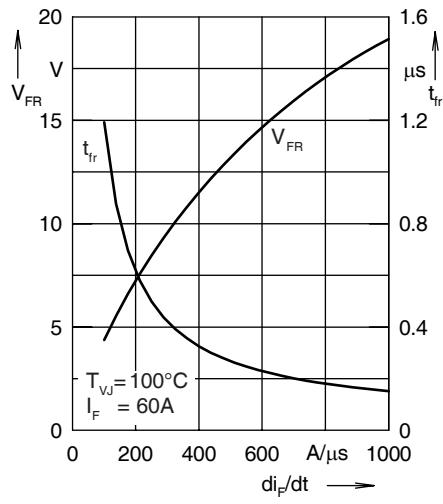


Fig. 17 Peak forward voltage  $V_{FR}$  and  $t_{tr}$  versus  $di_F/dt$

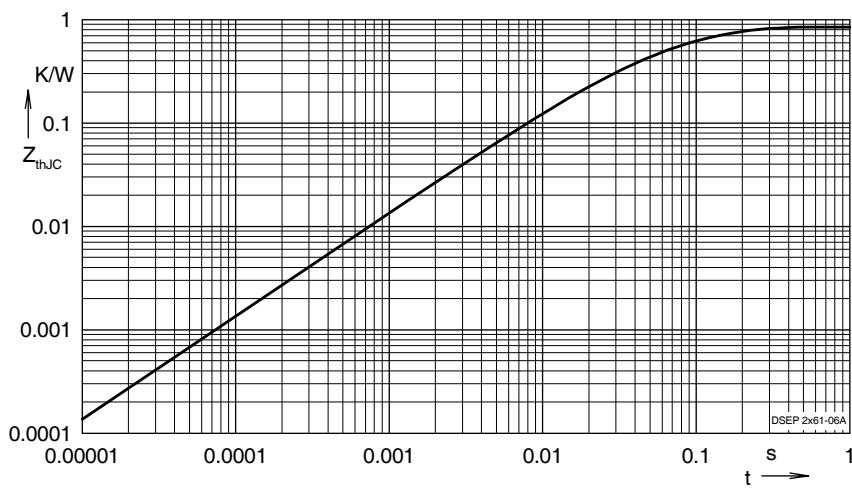


Fig. 18 Transient thermal resistance junction to case

Constants for  $Z_{thJC}$  calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.3073	0.0055
2	0.3533	0.0092
3	0.0887	0.0007
4	0.1008	0.0399

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