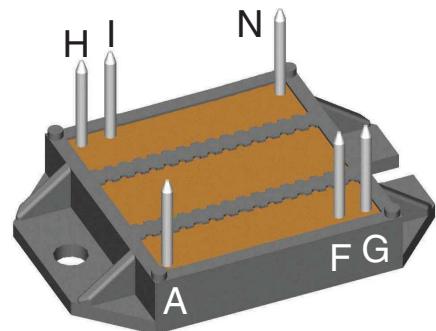
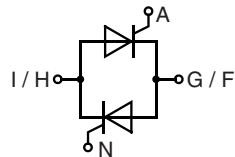


AC Controller Modules

I_{RMS} = **140 A**
I_{TAVM} = **58 A**
V_{RRM} = **1200/1600 V**

V _{RSM}	V _{RRM}	
V _{DSM}	V _{DRM}	Typ
V	V	
1300	1200	MMO 140-12io7
1700	1600	MMO 140-16io7



Preliminary Data

Symbol	Conditions	Maximum Ratings		
I _{RMS}	T _C = 85°C; 50-400 Hz (per single controller)	130	A	
I _{TRMS}		90	A	
I _{TAVM}	T _C = 85°C; 180° sine, per Thyristor	58	A	
I _{TSM}	T _{VJ} = 45°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	1150	A	
	T _{VJ} = 125°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	1230	A	
		1000	A	
		1070	A	
I ² t	T _{VJ} = 45°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	6600	A ² s	
	T _{VJ} = 125°C; t = 10 ms (50 Hz) V _R = 0 t = 8.3 ms (60 Hz)	6280	A ² s	
		5000	A ² s	
		4750	A ² s	
(di/dt) _{cr}	T _{VJ} = 125°C; repetitive, I _T = 60 A f = 50 Hz; t _p = 200 µs; V _D = $\frac{2}{3}$ V _{DRM} ;	150	A/µs	
	I _G = 0.45 A; non repetitive, I _T = I _{TAVM} di _G /dt = 0.45 A/µs	500	A/µs	
(dv/dt) _{cr}	T _{VJ} = 125°C; V _D = $\frac{2}{3}$ V _{DRM} ; R _{GK} = ∞ ; method 1 (linear voltage rise)	1000	V/µs	
P _{GM}	T _{VJ} = 125°C; t _p = 30 ms I _T = I _{T(AV)M} ; t _p = 300 ms	10	W	
		5	W	
P _{GAVM}		0.5	W	
V _{RGM}		10	V	
T _{VJ}		-40...+150	°C	
T _{VJM}		150	°C	
T _{stg}		-40...+125	°C	
V _{ISOL}	50/60 Hz, RMS t = 1 min	2500	V~	
	I _{ISOL} ≤ 1 mA t = 1 s	3000	V~	
M _d	Mounting torque (M4)	1.5 - 2.0	Nm	
		14 - 18	lb.in.	
Weight	Typical including screws	18	g	

Features

- Thyristor controller for AC (circuit W1C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glass passivated chips
- Low forward voltage drop
- Leads suitable for PC board soldering

Applications

- Switching and control of single and three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density
- Small and light weight

Data according to IEC 60747 and refer to a single diode unless otherwise stated.

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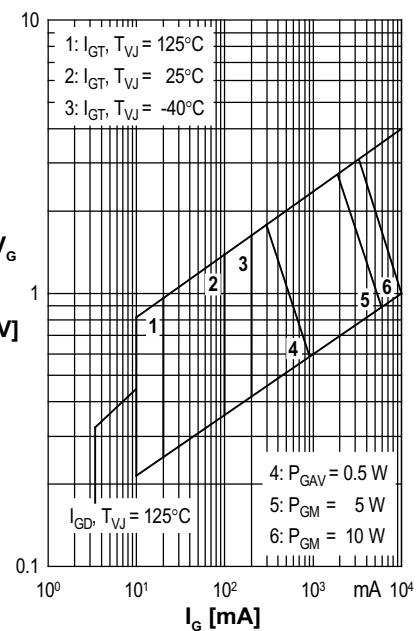
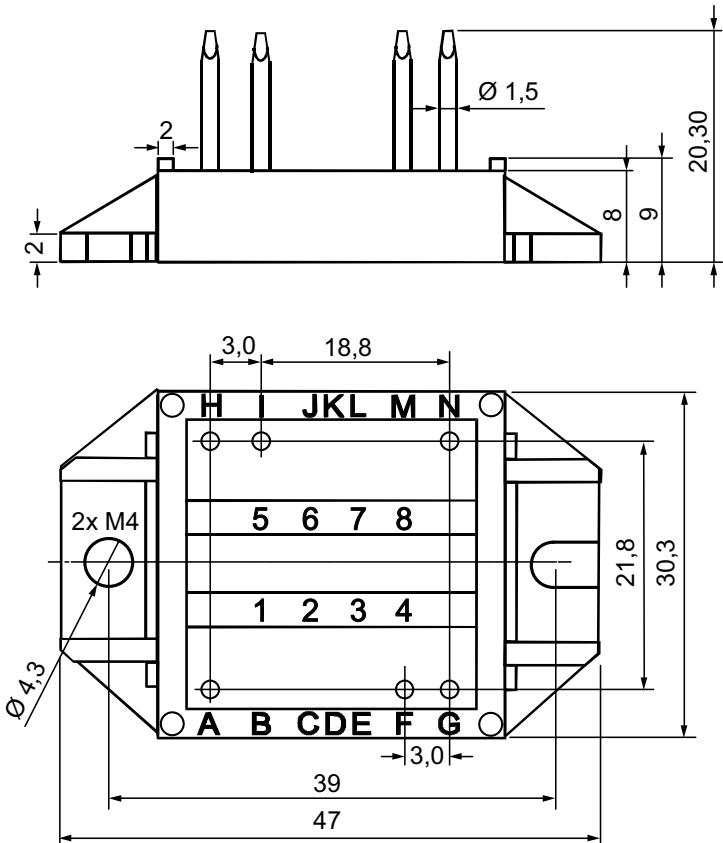
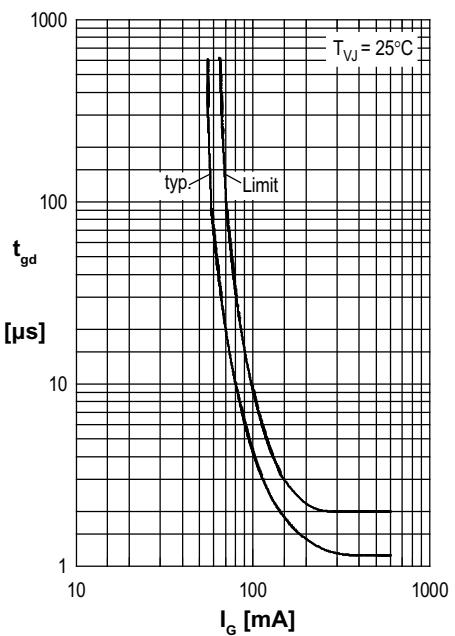
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1 - 2

Symbol	Conditions	Characteristic Values	
		typ.	max.
I_D, I_R	$V_R / V_D = V_{RRM} / V_{DRM}$	$T_{VJ} = 125^\circ\text{C}$	5 mA
V_T	$I_T = 200 \text{ A}$	$T_{VJ} = 25^\circ\text{C}$	1.75 V
V_{TO}	For power-loss calculations only	0.85 V	
r_t		5.20 mΩ	
V_{GT}	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$	1.5 V
		$T_{VJ} = -40^\circ\text{C}$	1.6 V
I_{GT}	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$	100 mA
		$T_{VJ} = -40^\circ\text{C}$	200 mA
V_{GD}	$V_D = \frac{2}{3} V_{DRM};$	$T_{VJ} = 125^\circ\text{C}$	0.2 V
I_{GD}			10 mA
I_L	$t_p = 10 \mu\text{s};$ $I_G = 0.45 \text{ A}; dI_G/dt = 0.45 \text{ A}/\mu\text{s}$	$T_{VJ} = 25^\circ\text{C}$	450 mA
I_H	$V_D = 6 \text{ V}; R_{GK} = \infty;$	$T_{VJ} = 25^\circ\text{C}$	200 mA
t_{gd}	$V_D = \frac{1}{2} V_{DRM}$	$T_{VJ} = 25^\circ\text{C}$	2 μs
	$I_G = 0.45 \text{ A}; dI_G/dt = 0.45 \text{ A}/\mu\text{s}$		
R_{thJC}	per thyristor; DC current	0.70 K/W	
R_{thCH}		0.12 K/W	
R_{thJC}	per module	0.35 K/W	
R_{thCH}		0.06 K/W	
d_s	Creeping distance on surface	11.2 mm	
d_A	Creepage distance in air	17.0 mm	
a	Maximum allowable acceleration	50 m/s²	

Dimensions in mm (1 mm = 0.0394")

Fig. 1 Gate trigger characteristics

Fig. 2 Gate trigger delay time

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