

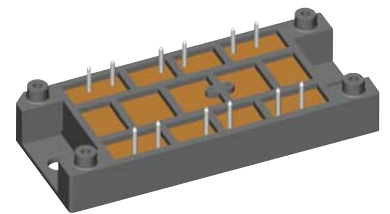
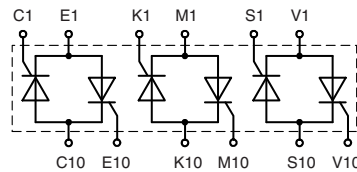
Three Phase AC Controller Modules

$$I_{RMS} = 3 \times 143 \text{ A}$$

$$V_{RRM} = 1200-1600 \text{ V}$$

Preliminary data

| V_{RSM} | V_{RRM} | Type |
|-----------|-----------|---------------|
| V_{DSM} | V_{DRM} | |
| V | V | |
| 1200 | 1200 | VWO 140-12io1 |
| 1400 | 1400 | VWO 140-14io1 |
| 1600 | 1600 | VWO 140-16io1 |



pin configuration see outlines

| Symbol | Conditions | Maximum Ratings | Features |
|----------------|--|------------------------------------|--|
| I_{RMS} | $T_C = 85^\circ\text{C}$; 50 - 400 Hz (per phase) | 101 A | <ul style="list-style-type: none"> • Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency • Package with DCB base plate • Isolation voltage 3600 V~ • Planar passivated chips • UL applied |
| I_{RMS} | $T_C = 85^\circ\text{C}$; 50 - 400 Hz (per phase) for 10 sec. | 143 A | |
| I_{TAVM} | $T_C = 85^\circ\text{C}$; (180° sine) | 46 A | |
| I_{TSM} | $T_{VJ} = 45^\circ\text{C}$ | $t = 10 \text{ ms}$ (50 Hz), sine | 1150 A |
| | $V_R = 0$ | $t = 8.3 \text{ ms}$ (60 Hz), sine | 1240 A |
| I^2t | $T_{VJ} = 45^\circ\text{C}$ | $t = 10 \text{ ms}$ (50 Hz), sine | 6610 A ² s |
| | $V_R = 0$ | $t = 8.3 \text{ ms}$ (60 Hz), sine | 6460 A ² s |
| $(di/dt)_{cr}$ | $T_{VJ} = 125^\circ\text{C}$ | $t = 10 \text{ ms}$ (50 Hz), sine | 5410 A ² s |
| | $V_R = 0$ | $t = 8.3 \text{ ms}$ (60 Hz), sine | 5270 A ² s |
| $(di/dt)_{cr}$ | $T_{VJ} = 125^\circ\text{C}$ $f = 50 \text{ Hz}$, $t_p = 200 \mu\text{s}$ $V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.45 \text{ A}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 45 \text{ A}$ | 150 A/ μs |
| | | non repetitive, $I_T = I_{TAVM}$ | 500 A/ μs |
| $(dv/dt)_{cr}$ | $T_{VJ} = 125^\circ\text{C}$; $R_{GK} = \infty$; method 1 (linear voltage rise) | $V_{DR} = \frac{2}{3} V_{DRM}$ | 1000 V/ μs |
| P_{GM} | $T_{VJ} = 125^\circ\text{C}$ $I_T = I_{TAVM}$ | $t_p = 30 \mu\text{s}$ | 10 W |
| | | $t_p = 300 \mu\text{s}$ | 5 W |
| P_{GAVM} | | | 0.5 W |
| V_{RGM} | | | 10 V |
| T_{VJ} | | | -40...+125 °C |
| T_{VJM} | for 10 sec. | | 150 °C |
| T_{stg} | | | -40...+125 °C |
| V_{ISOL} | 50/60 Hz, RMS $I_{ISOL} \leq 1 \text{ mA}$ | $t = 1 \text{ min}$ | 3000 V~ |
| | | $t = 1 \text{ s}$ | 3600 V~ |
| M_d | Mounting torque (M5) | | 2-2.5 Nm. |
| | | | 18-22 lb.in. |
| Weight | typ. | | 80 g |

Features

- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency
- Package with DCB base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- UL applied

Applications

- Switching and control of three phase AC circuits
- Softstart AC motor controller
- Solid state switches
- Light and temperature control

Advantages

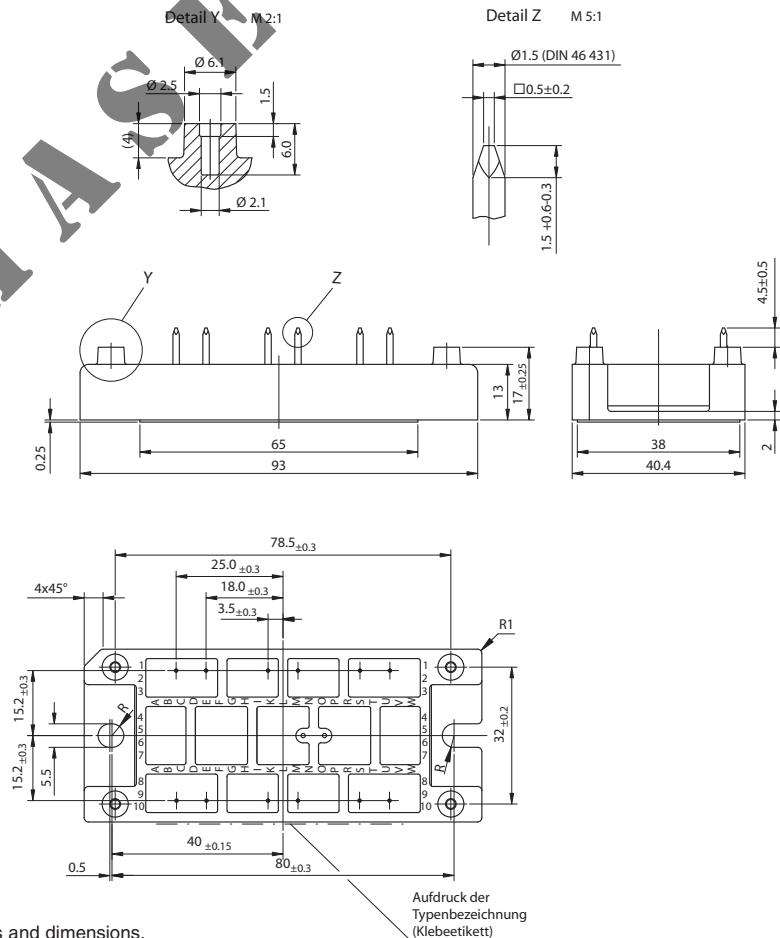
- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density

Recommended replacement:
 3x MMO90-12/14/16 io6
 3x CLA110MB1200NA

Data according to IEC 60747 refer to a single thyristor unless otherwise stated.

| Symbol | Conditions | Characteristic Values | |
|------------|---|-----------------------|---------------------|
| I_D, I_R | $T_{VJ} = 125^\circ\text{C}; V_R = V_{RRM}; V_D = V_{DRM}$ | \leq | 5 mA |
| V_T | $I_T = 140 \text{ A}; T_{VJ} = 25^\circ\text{C}$ | \leq | 1.5 V |
| V_{T0} | For power-loss calculations only | | 0.85 V |
| r_T | | | 5.2 m Ω |
| V_{GT} | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$ | \leq | 1.5 V |
| | $T_{VJ} = -40^\circ\text{C}$ | \leq | 1.6 V |
| I_{GT} | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$ | \leq | 100 mA |
| | $T_{VJ} = -40^\circ\text{C}$ | \leq | 200 mA |
| V_{GD} | $T_{VJ} = 125^\circ\text{C}; V_D = \frac{2}{3} V_{DRM}$ | \leq | 0.2 V |
| I_{GD} | | \leq | 5 mA |
| I_L | $T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | \leq | 450 mA |
| I_H | $T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$ | \leq | 200 mA |
| t_{gd} | $T_{VJ} = 25^\circ\text{C}; V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | \leq | 2 μs |
| t_q | $T_{VJ} = 125^\circ\text{C}; I_T = 20 \text{ A}, t_p = 200 \mu\text{s}; di/dt = -10 \text{ A}/\mu\text{s}$ typ. $V_R = 100 \text{ V}; dv/dt = 15 \text{ V}/\mu\text{s}; V_D = \frac{2}{3} V_{DRM}$ | | 150 μs |
| R_{thJC} | per thyristor; sine 180°el | | 0.6 K/W |
| | per module | | 0.1 K/W |
| R_{thJK} | per thyristor; sine 180°el | | 0.7 K/W |
| | per module | | 0.117 K/W |
| d_s | Creeping distance on surface | | 12.7 mm |
| d_A | Creepage distance in air | | 9.4 mm |
| a | Max. allowable acceleration | | 50 m/s ² |

Dimensions in mm (1 mm = 0.0394")



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