## Current Sensors MR, Zero-Phase Current Transformers



#### **Overview**

The MR series are compact, molded-type, zero-phase current transformers. They are ideal for improving the sensitivity, compactness, and weight of electric shock prevention.

#### **Applications**

Typical applications include electric shock prevention from earth leakage breakers, short-circuit relays, and ground fault circuit interrupters.

#### **Benefits**

- · High sensitivity
- · Compact and lightweight
- Laminated iron core
- RoHS compliant

### **Ordering Information**

MR	/C	-01
Series	Height	Shape Classification
MR	Blank = Standard /C = Compact	-1 -2 -3 -4 -1-P5 -01 -01B



**MR** Type

MR/C Types

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### **Dimensions in mm**

#### MR-1, 2, 3, 4





MR/C-01



MR/C-01B

MR-1-P5



Part Number	D1 (Minimum)	D2 (Maximum)	D3 (Maximum)	D4	H (Maximum)	L (±3.0)
MR-1	7.2	19.3	22.4	(5.0)	8.3	45.0
MR-2	8.9	21.8	24.7	(5.0)	8.3	80.0
MR-3	11.0	28.0	30.5	(6.0)	10.5	67.0
MR-4	16.5	32.0	34.5	(7.0)	10.8	67.0
MR-1-P5	7.4	19.3	21.8	(8.0)	8.5	_
MR/C-01	6.0	17.5	19.0	_	6.7	_
MR/C-01B	6.0	17.5	19.0	_	7.9	_

Pin:  $\varphi 0.8$  mm pin connectors.

\* Pin root diameter.



## **AC Output Characteristics**

#### Output Voltage Example MR-1



## **Environmental Compliance**

All MR sensors are RoHS compliant.



## **Specifications**

ltem	Performance Characteristics	
Rated Current	15 – 125 A	
Output Voltage	8.0 – 12.5 V Minimum	
DC Resistance	25 - 30 Ω	
Operating Temperature Range	-20°C to +80°C	
Temperature Characteristics	±10%	
Storage Temperature Range	-5°C to +40°C	



### Table 1 – Ratings & Part Number Reference

Dent	Electrical			Measurement Conditions from Output Voltage			Wataba	
Number	Rated Current (A)	Output Voltage (mV) Minimum	Overinput Characteristics (After DC5A Input) Maximum	DC Resistance (Ω)	Frequency (Hz)	Load Resistance (Ω)	Detection Current (mA)	(g)
MR-1	30	8.0	±10%	(30)	60	300	22.5	4.1
MR-2	30	8.0	±10%	(30)	60	300	22.5	5.9
MR-3	60	8.0	±10%	(30)	60	300	22.5	11.9
MR-4	125	8.0	±10%	(30)	60	300	22.5	16.5
MR-1-P5	30	8.0	±10%	(25)	60	300	22.5	4.3
MR/C-01	15	12.5	±10%	(30)	60	1,000	15.0	2.3
MR/C-01B	15	12.5	±10%	(30)	60	1,000	15.0	2.7

### **Soldering Process**

#### MR-1, MR-2, MR-3, & MR-4

Iron Coldering	Temperature of tip	350°C or lower	
non soldering	Worktime	within 3 seconds	

#### MR/C-01 & MR/C-01B

Flow Soldering	Preheating temperature	90 – 150°C	
	Preheating time	within 90 seconds	
	Heating temperature	260°C	
	Heating time	within 5 seconds	
Iron Soldering	Temperature of tip	350°C or lower	
	Worktime	within 3 seconds	

## Packaging

Part Number	Packaging Type	Pieces Per Box
MR-1		560
MR-2	Тгау	480
MR-3		200
MR-4		300
MR-1-P5		1,050
MR/C-01		1,200
MR/C-01B		960

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### **Handling Precautions**

#### **Precautions for Product Storage**

Current sensors should be stored in normal working environments. While the sensors are quite robust in other environments, exposure to high temperatures, high humidity, corrosive atmospheres, and long-term storage degrade solderability.

KEMET recommends that maximum storage temperature not exceed 40°C and maximum storage humidity not exceed 70% relative humidity. Atmospheres should be free of chlorine and sulfur-bearing compounds. Temperature fluctuations should be minimized to avoid condensation on the parts. Avoid storage near strong magnetic fields, as they can magnetize the product and cause its characteristics to change.

For optimized solderability, the stock of current sensors should be used within 12 months of receipt.

#### **Before Using Zero-Phase Current Transformers**

- Do NOT drop or apply any other mechanical stress, as such stresses may change performance characteristics.
- Do NOT use current transformers opened between secondary output terminals. Heat build-up in the magnetic core may
  occur, resulting in damage to the parts by coil melting.
- If the MR series is used as a current transformer, contact KEMET for more information.



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