

# EZ430-C9

# Getting Started with Kionix EZ430-C9 Evaluation Board for the Texas Instruments MSP430 USB Stick Development Tool



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#### Contents

- 1. Kionix EZ430-C9 Evaluation board
- 2. CD containing sample firmware for reading acceleration
- 3. Application Note AN053 (this document)

#### **Overview**

The Texas Instruments (TI) eZ430-F2013 development kit with the Kionix KXTC9 Evaluation Board (EZ430-C9) provides a simple environment to quickly start sampling X, Y, and Z accelerations and create accelerometer applications using the MSP430F2012 in a convenient USB form factor.

### Hardware

#### **Development Kit Components**

#### Texas Instrument eZ430-F2013 (not included)

TI's eZ430 Development Tool consists of a MSP-EZ430U Debugging Interface, which connects to a detachable eZ430-T2012 target board all housed inside a plastic enclosure. The enclosure can be opened to attach/detach different target boards. It is to the eZ430-T2012 target board that the Kionix accelerometer evaluation board can be attached.



The MSP-EZ430U debugging interface may come with Spy Bi-Wire Interfaces supplied through either a 4-pin connector (Figure 2) or a 6-pin connector (Figure 3).



Figure 2: eZ430-F2013 development kit with 4-pin target board connector



**Figure 3:** eZ430-F2013 development kit with 4-pin target board connector Since the detachable eZ430-T2012 target board comes with a 4-pin connector, it should be placed on the <u>middle</u> 4-pins of the eZ430-F2013 development kit if it comes with 6-pin connector.

The eZ430 Development Tool provides a real-time debugging and programming interface for the MSP430F2012 on the target board, and comes with the easy-to-use IAR Embedded Workbench Integrated Development Environment (IDE). The T2012 can be used to develop your personal project or to evaluate the MSP430 MCU. The latest product information and ordering information about the ez430 Development Tool can be found at: <u>http://www.ti.com/tool/ez430-f2013</u>. The latest product information and ordering about the eZ430-T2012 target board can be found at: <u>http://www.ti.com/tool/ez430-f2013</u>.



#### Kionix EZ430-C9 Evaluation Board

The Kionix EZ430-C9 Evaluation Board provides the connection between the KXTC9-2050 accelerometer and the MCU. The two boards (Kionix EZ430-C9 and the TI eZ430-T2012 target board) connect to each other through the 14-pin configuration (Figure 4). The pin configuration of both boards are compatible with each other, meaning pin 1 through pin 14 of the eZ430-T2012 connect to pin 1 through pin 14 of the EZ430-C9 respectively.



**Figure 4:** Kionix EZ430-7 Evaluation Board Mounted on TI eZ430-T2012

Power to the EZ430-C9 is provided through the target board. If the target board along with the EZ430-C9 is to function as a standalone unit, then an external power supply can be connected appropriately to the 14-pin connection.



AN053

PCB board schematic is shown in Figure 5, and board layout, pin description, and accelerometer axis orientation are shown in Figure 6.







J1 Connector Pin			
Description			
pin 1	VDD		
pin 2	GND		
pin 3	P2		
pin 4	P13		
pin 5	P3		
pin 6	P12		
pin 7	P4		
pin 8	P11		
pin 9	P5		
pin 10	P10		
pin 11	X		
pin 12	P9		
pin 13	Y		
pin 14	Z		

Outer Dimensions: 1.9cm x 1.6cm





The product specifications for the KXTC9-2050 accelerometer can be found at: <a href="http://www.kionix.com/product/KXTC9-2050">http://www.kionix.com/product/KXTC9-2050</a>

#### Software

#### **Getting Started**

Install the IAR Workbench. The IDE can be obtained from TI's website. <u>http://www.ti.com/tool/iar-kickstart</u>. More information about the IDE is available on the website as well.

#### **Reading Acceleration Data Demo**

A sample C file has been provided to help you get started in reading X, Y, and Z acceleration data. You will need to set up a project for the eZ430-T2012, and download the application onto the MSP430F2012. The following steps will guide you through the process:

- Start the Workbench. (Start -> All Programs -> IAR Systems -> IAR Embedded Workbench for MSP430 6.30 -> IAR Embedded Workbench).
- Click on the File tab -> Open Workspace ->. Select the directory where you have unzipped the 'AccelDemoKXTC9.zip'.
- 3. Select the 'KXTC9\_F2012.eww' workspace.
- Set the correct device by clicking on Projects -> Options -> General Options select 'Target' tab and select MSP430F2012 from the list (Figure 4).



### AN053

Category: General Options Static Analysis	<u>+</u>	
C/C++ Compiler Assembler	Target Output Library Configuration Lib	brary Options Stack/Heap
Custom Build Build Actions Linker TI ULP Advisor Debugger FET Debugger Simulator	Device MSP430F2012 Development mode © Normal mode BOM mode	Code Model     Data Model       Small     Small       Large     Medium       Large     Large
	Position-independence	32 bits     64 bits
	No dynamic read/write initialization	Hardware multiplier
	Exclude RESET vector	<ul> <li>Allow direct access</li> <li>Use only library calls</li> </ul>

Figure 7: Select MSP430F2012 Device

 Still in the Options window, select 'Debugger' category, select 'Setup' tab, and choose FET Debugger under **Driver** window (**Figure 8**).

Category: General Options Static Analysis C/C++ Compiler Assembler Custom Build Build Actions Linker TI ULP Advisor Debugger FET Debugger Simulator	Setup       Images       Extra Options       Plugins         Driver       Imain       Imain         Setup       macros       Use macro file
	Device description file
	OK Cancel





Still in the Options window, under 'Debugger' category, select 'FET Debugger' sub-category, select 'Setup' tab, and choose 'Texas Instrument USB-IF' in the 'Connection' window to use the USB interface (Figure 9).

Options for node "KXTC	9_F2012"	
Category: General Options Static Analysis C/C++ Compiler Assembler	Setup Download Breakpoint:	Factory Settings
Custom Build Build Actions Linker TI ULP Advisor Debugger EET Debugger	Connection Texas Instrument USB-IF ▼	Automatic Jtag speed © East © Medium © Slow
EET Debugger Simulator	Debug grotocol <ul> <li>Automatic selection</li> <li>Manual selection</li> <li>Spy-Bi-Wire</li> <li>4-Wire JTAG</li> </ul>	Target VCC       Ovemide default       Target VCC (in Volt):       3.3       Settling time (in ms):
	Disable memory cache	Enable ULP/LPMx.5 debug
		OK Cancel

Figure 9: Select Texas Instrument USB-IF Connection Type

- Use Project -> Rebuild All to build and link the source code. You can view the source code by double clicking on the project, and then double-clicking on the displayed source file.
- Use Project -> Download and Debug to start the C-SPY debugger. C-SPY will erase the device Flash, and then download the application object file to the device Flash.

9. Place the cursor on the Zout variable. Press Run to cursor button to refresh the view of the Xout, Yout, and Zout (X, Y, and Z acceleration) variables in the watch window (Figure 10).

File Edit View Project Debug Emulator	Tools Window Help			
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Workspace Run to Cursor	main.c	main() 👻 🗙	Watch 1	×
Debug 🗸	// 06 NOV 2015		Expression	Value
Files 😤 🛤		<b>^</b>	Xaxis	532
□ 🗊 KXTC9_F2012 - Debug 🗸	///**********************************		Yaxis Zavis	497
E main.c			<click edi<="" td="" to=""><td></td></click>	
	unsigned int Xout();			
	unsigned int Zout();			
	unsigned int Varias			
	unsigned int Yaxis;			
	unsigned int Zaxis;			
	void main (void)			
1				1
Run to cursor	WDTCTL = WDTPW + WDTHOLD; // Stop WDT		Accelerat	ion
button	ADC10CTL0 = ADC10SHT_2 + ADC100N + ADC10IE; // ADC100N, interrupt enabled PIDTP = 0x01: // Set Pl 0 to output direction	=	Variables	
	//get acceleration data		-	
	<pre>Xaxis = Xout();</pre>			
	<pre>Yaxis = Yout(); Qaxis = Zout(); Place cursor here</pre>			
	// ADC10 interrupt service routine			
	interrupt void ADC10_ISR(void)			
KXTC9 F2012	unsigned int Xout()		4	
×		, v		
Log				^
Fri Nov 06, 2015 16:12:40: VCC voltage Fri Nov 06, 2015 16:12:40: Invalid param	3.5 V istor(s) : (Configure) - modo-Byb velue-ByD			
Fri Nov 06, 2015 16:12:41: Download co	mplete.			_
Fri Nov 06, 2015 16:12:41: Loaded debu	igee: C:\Users\achernyakov\Documents\Install Software\Kionix\EZ430\AccelDemoKXTC9\Debug\Exe\K	XTC9_F2012.d43	3	_
Fri Nov 06, 2015 16:12:41: Larget reset Fri Nov 06, 2015 16:12:41: No state store	age buffer implemented on connected device : (EnableEnergyTrace)			=
3	ge sere ingrementes en composed device . (Enderenning mater)			-
6nq	III			•
Z Debug Log Build				×
Execute to the current cursor position	Lr	49. Col 11	System	NUM ::

Figure 10: Operation in Debug Mode

Congratulations, you have successfully built and tested the AccelDemoKXTC9 application



#### **Technical Support**

If you experience technical difficulties with the EZ430-C9 evaluation board, please contact your local Kionix Sales Office for technical support information.

#### The Kionix Advantage

Kionix technology provides for X, Y, and Z-axis sensing on a single, silicon chip. One accelerometer can be used to enable a variety of simultaneous features including, but not limited to:

Hard Disk Drive protection Vibration analysis Tilt screen navigation Sports modeling Theft, man-down, accident alarm Image stability, screen orientation & scrolling Computer pointer Navigation, mapping Game playing Automatic sleep mode

### **Theory of Operation**

Kionix MEMS linear tri-axis accelerometers function on the principle of differential capacitance. Acceleration causes displacement of a silicon structure resulting in a change in capacitance. A signal-conditioning CMOS technology ASIC detects and transforms changes in capacitance into an analog output voltage, which is proportional to acceleration. These outputs can then be sent to a micro-controller for integration into various applications. For product summaries, specifications, and schematics, please refer to the Kionix MEMS accelerometer product catalog at: <a href="http://www.kionix.com/parametric/Accelerometers">http://www.kionix.com/parametric/Accelerometers</a>



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