

DS28C50

DeepCover® I²C Secure SHA-3 Authenticator with ChipDNA PUF Protection

General Description

The DS28C50 secure authenticator combines FIPS202-compliant secure hash algorithm (SHA-3) challenge and response authentication with Maxim's patented ChipDNA™ technology, a physically unclonable function (PUF) to provide a cost-effective solution with the ultimate protection against security attacks. The ChipDNA implementation utilizes the random variation of semiconductor device characteristics that naturally occur during wafer fabrication. The ChipDNA circuit generates a unique output value that is repeatable over time, temperature, and operating voltage. Attempts to probe or observe ChipDNA operation modifies the underlying circuit characteristics, thus preventing discovery of the unique value used by the chip cryptographic functions. The DS28C50 utilizes the ChipDNA output as key content to cryptographically secure all device-stored data. With ChipDNA capability, the device provides a core set of cryptographic tools derived from integrated blocks including a SHA-3 engine, a FIPS/NIST compliant true random number generator (TRNG), 2Kb of secured EEPROM, a decrement-only counter and a unique 64-bit ROM identification number (ROM ID). The unique ROM ID is used as a fundamental input parameter for cryptographic operations and serves as an electronic serial number within the application. The DS28C50 communicates over a I²C network.

Applications

- Authentication of Medical Sensors and Tools
- Secure Management of Limited Use Consumables
- IoT Node Crypto-Protection
- Accessory and Peripheral Secure Authentication
- Printer Cartridge Identification and Authentication

Benefits and Features

- Robust Countermeasures Protect Against Security Attacks
 - Patented Physically Unclonable Function Secures Device Data
 - Actively Monitored Die Shield Detects and Reacts to Intrusion Attempts
 - All Stored Data Cryptographically Protected from Discovery
- Efficient Secure Hash Algorithm Authenticates Peripherals
 - FIPS 202-Compliant SHA-3 Algorithm for Challenge/Response Authentication
 - FIPS 198-Compliant Keyed-Hash Message Authentication Code (HMAC)
 - TRNG with NIST SP 800-90B Compliant Entropy Source
- Supplemental Features Enable Easy Integration into End Application
 - 17-Bit One-Time Settable, Nonvolatile Decrement Only Counter with Authenticated Read
 - One GPIO Pin with Optional Authentication Control
 - 2Kb of EEPROM for User Data, Key, and Control Registers
 - Unique and Unalterable Factory Programmed 64-Bit Identification Number (ROM ID)
 - Operating Range: 3.3V ±10%, -40°C to +85°C
 - 6-Pin TDFN-EP Package (3mm x 3mm)
 - I²C Communication, Up to 1MHz

Ordering Information appears at end of data sheet.

DeepCover is a registered trademark and ChipDNA is a trademark of Maxim Integrated Products, Inc.



Typical Application Circuit

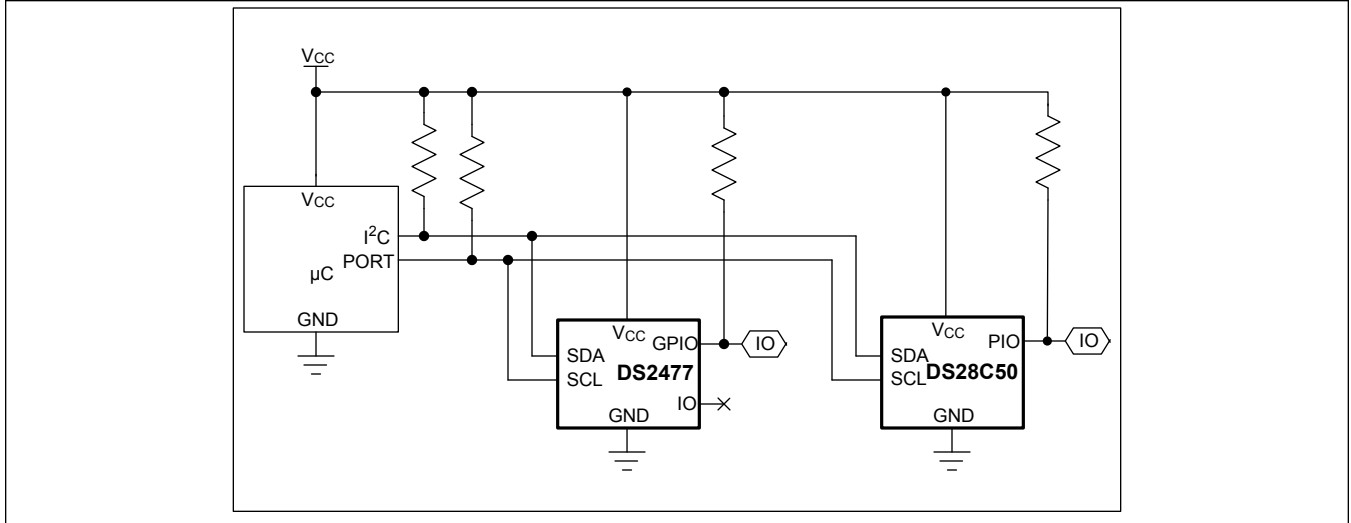


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Absolute Maximum Ratings

Voltage Range on Any Pin Relative to GND -0.5V to 4.0V Operating Temperature Range -40°C to 85°C
Maximum Current into Any Pin -20mA to 20mA Lead Temperature (soldering, 10s) +300°C

Package Information

6 TDFN-EP

Package Code	T633+2
Outline Number	21-0137
Land Pattern Number	90-0058
Thermal Resistance, Single-Layer Board:	
Junction to Ambient (θ_{JA})	55°C/W
Junction to Case (θ_{JC})	9°C/W
Thermal Resistance, Four-Layer Board:	
Junction to Ambient (θ_{JA})	42°C/W
Junction to Case (θ_{JC})	9°C/W

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

Electrical Characteristics

(Limits are 100% production tested at $T_A = +25^\circ\text{C}$ and/or $T_A = +85^\circ\text{C}$. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Typical values are not guaranteed.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Supply Voltage	V_{CC}	(Note 1)	2.97	3.3	3.63	V
Supply Current	I_{CC}	Standby			400	μA
		Communicating/Active			10	mA
I²C SCL AND SDA PINS (Note 2)						
Low-Level Input Voltage	V_{IL}		-0.3		$0.2 \times V_{CC}$	V
High-Level Input Voltage	V_{IH}		$0.7 \times V_{CC}$		$V_{CC} + 0.3\text{V}$	V
Hysteresis of Schmitt Trigger Inputs	V_{HYS}	(Note 3)		$0.05 \times V_{CC}$		V
Low-Level Output Voltage at 4mA Sink Current	V_{OL}	(Note 4)			0.4	V
Output Fall Time from $V_{IH(MIN)}$ to $V_{IL(MAX)}$ with a Bus Capacitance from 10pF to 400pF	t_{OF}	(Note 3)		30		ns
Pulse Width of Spikes that are Suppressed by the Input Filter	t_{SP}	(Note 3)			50	ns

Electrical Characteristics (continued)

(Limits are 100% production tested at T_A = +25°C and/or T_A = +85°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Typical values are not guaranteed.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Current with an Input Voltage Between 0.1V _{CCmax} and 0.9V _{CCmax}	I _I	(Note 3 , Note 5)	-1		+1	μA
Input Capacitance	C _I	(Note 3)		10		pF
SCL Clock Frequency	f _{SCL}	(Note 1)	0		1	MHz
Hold Time (Repeated) START Condition	t _{HD:STA}		0.45			μs
Low Period of the SCL Clock	t _{LOW}	(Note 6)	0.65			μs
High Period of the SCL Clock	t _{HIGH}	(Note 3)	0.35			μs
Setup Time for a Repeated START Condition	t _{SU:STA}	(Note 3)	0.35			μs
Data Hold Time	t _{HD:DAT}	(Note 3 , Note 6 , Note 7)			0.35	μs
Data Setup Time	t _{SU:DAT}	(Note 3 , Note 6 , Note 8)	100			ns
Setup Time for STOP Condition	t _{SU:STO}	(Note 3)	0.35			μs
Bus Free Time Between a STOP and START Condition	t _{BUF}	(Note 3)	0.6			μs
Capacitive Load for Each Bus Line	C _B	(Note 1 , Note 9)			400	pF
Warm-Up Time	t _{OSCWUP}	(Note 1 , Note 10)			1	ms
GPIO PIN						
GPIO Output Low	PIOV _{OL}	PIOI _{OL} = 4mA (Note 4)			0.4	V
GPIO Input Low	PIOV _{IL}		-0.3		0.2 x V _{CC}	V
GPIO Master Sample	PIOV _{IH}		0.70 x V _{CC}		V _{CC} + 0.3	V
GPIO Switching Hysteresis	PIOV _{HY}			0.05 x V _{CC}		V
GPIO Leakage Current	PIOI _L		-1		+1	μA
CRYPTO FUNCTIONS						
Computation Current	I _{CMP}				10	mA
Read Memory	t _{RM}				50	ms
Write Memory	t _{WM}				100	ms
Blockwise Write Memory	t _{WM_BL}	Page data changes limited to one of four 8-byte blocks (refer to <i>DS28C50 Security User Guide</i>)			60	ms
Write State	t _{WS}				60	ms

Electrical Characteristics (continued)

(Limits are 100% production tested at $T_A = +25^\circ\text{C}$ and/or $T_A = +85^\circ\text{C}$. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Typical values are not guaranteed.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Computation Time (HMAC)	t_{CMP}				5	ms
TRNG Generation	t_{RNG}				25	ms
TRNG On-Demand Check	t_{ODC}				50	ms
EEPROM						
Write/Erase Cycles (Endurance)	N_{CY}	(Note 11)	100K			
Data Retention	t_{DR}	$T_A = +85^\circ\text{C}$ (Note 12)	10			Years

Note 1: System requirement.

Note 2: All I²C timing values are referred to $V_{\text{IH(MIN)}}$ and $V_{\text{IL(MAX)}}$ levels.

Note 3: Guaranteed by design and/or characterization only. Not production tested.

Note 4: The I-V characteristic is linear for voltages less than 1V.

Note 5: I/O pins of the DS28C50 do not obstruct the SDA and SCL lines if V_{CC} is switched off.

Note 6: $t_{\text{LOW min}} = t_{\text{HD:DAT max}} + 200\text{ns}$ for rise or fall time + $t_{\text{SU:DAT min}}$. Values greater than these can be accommodated by extending t_{LOW} accordingly.

Note 7: The DS28C50 provides a hold time of at least 100ns for the SDA signal (referenced to the $V_{\text{IH(MIN)}}$ of the SCL signal) to bridge the undefined region of the falling edge of SCL.

Note 8: The DS28C50 can be used in a standard-mode I²C-bus system, but the requirement $t_{\text{SU:DAT}} \geq 250\text{ns}$ must then be met. Also the acknowledge timing must meet this setup time (I²C bus specification Rev. 03, 19 June 2007).

Note 9: C_B = Total capacitance of one bus line in pF. The maximum bus capacitance allowable may vary from this value depending on the actual operating voltage and frequency of the application (I²C bus specification Rev. 03, 19 June 2007).

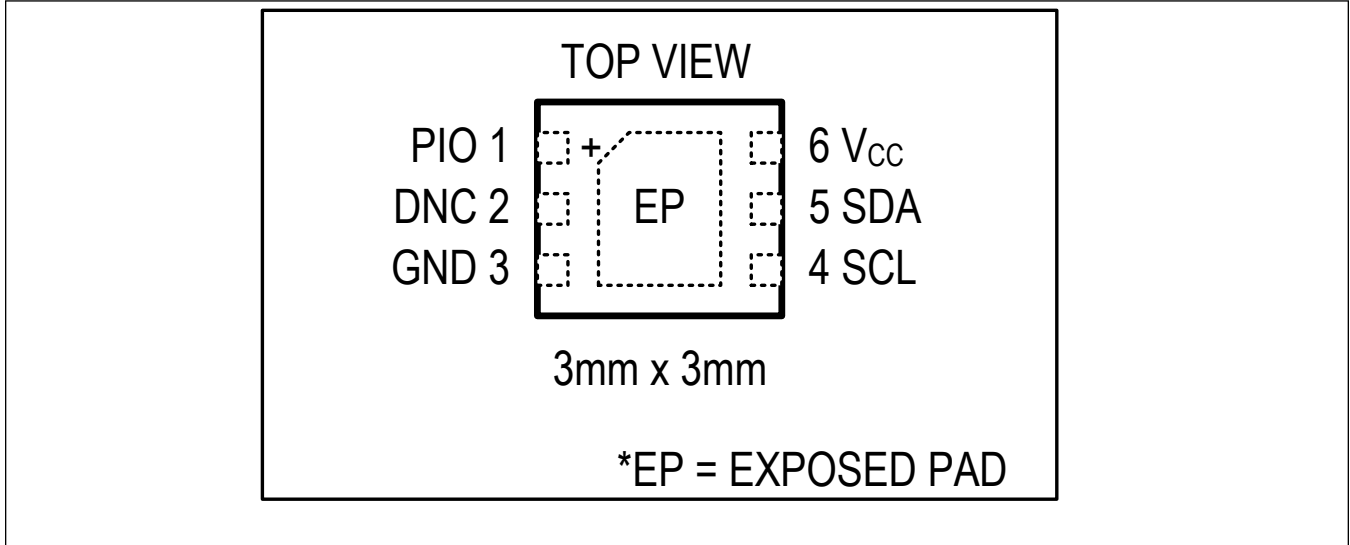
Note 10: I²C communication should not take place for the max t_{OSCWUP} time following a power-on reset.

Note 11: Write-cycle endurance is tested in compliance with JESD47G.

Note 12: Data retention is tested in compliance with JESD47G.

Pin Configuration

6 TDFN-EP



Pin Description

PIN	NAME	FUNCTION
1	PIO	General-Purpose IO
2	DNC	Do Not Connect
3	GND	Ground
4	SCL	I ² C Clock. Connect to V _{CC} with pullup resistor.
5	SDA	I ² C Data. Connect to V _{CC} with pullup resistor.
6	V _{CC}	Supply Voltage
—	EP	Exposed Pad (TDFN Only). Solder evenly to the board's ground plane for proper operation. Refer to Application Note 3273: Exposed Pads: A Brief Introduction for additional information.

Decrement Counter

The optional 17-bit decrement counter can be written one time on a dual-purpose page of memory. A dedicated command is used to decrement the count value by one with each call. Once the count value reaches a value of 0, no additional decrements are possible.

I²C

General Characteristics

The I²C bus uses a data line (SDA) plus a clock signal (SCL) for communication. Both SDA and SCL are bidirectional lines, connected to a positive supply voltage through a pullup resistor. When there is no communication, both lines are high. The output stages of devices connected to the bus must have an open drain or open collector to perform the wired-AND function. Data on the I²C bus can be transferred at rates of up to 100kbps in standard mode and up to 400kbps in fast mode. The DS28C50 works in both modes or up to a clock rate of 1MHz. A device that sends data on the bus is defined as a transmitter, and a device receiving data is defined as a receiver. The device that controls the communication is called a master. The devices that are controlled by the master are slaves. To be individually accessed, each device must have a slave address that does not conflict with other devices on the bus. Data transfers can be initiated only when the bus is not busy. The master generates the serial clock (SCL), controls the bus access, generates the START and STOP conditions, and determines the number of data bytes transferred between START and STOP (Figure 2). Data is transferred in bytes with the most significant bit being transmitted first. After each byte follows an acknowledge bit to allow synchronization between master and slave.

Slave Address

The slave address to which the DS28C50 responds is shown in Figure 3. The slave address is part of the slave address/control byte. The last bit of the slave address/control byte (R/W) defines the data direction. When set to 0, subsequent data flows from master to slave (write access); when set to 1, data flows from slave to master (read access).

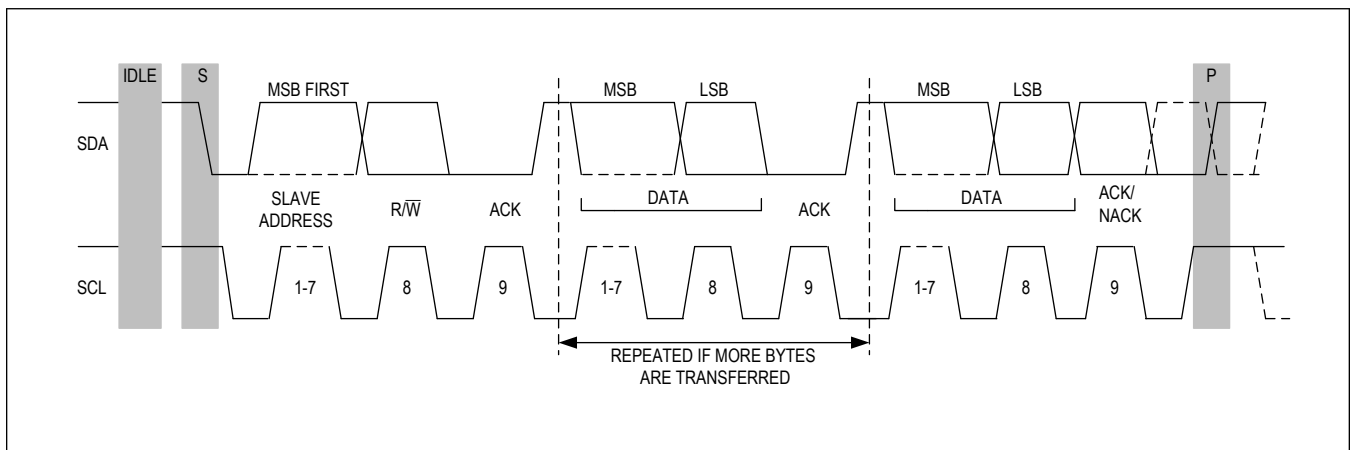


Figure 2. I²C Protocol Overview

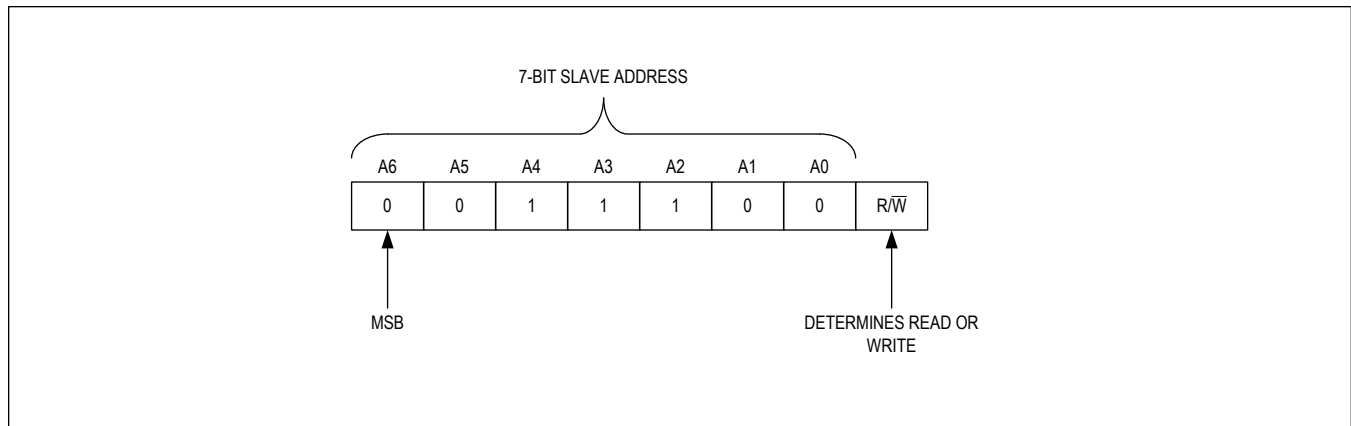


Figure 3. I²C Slave Address

I²C Definitions

The following terminology is commonly used to describe I²C data transfers. The timing references are defined in [Figure 4](#).

Bus Idle or Not Busy

Both SDA and SCL are inactive and in their logic-high states.

START Condition

To initiate communication with a slave, the master must generate a START condition. A START condition is defined as a change in state of SDA from high to low while SCL remains high.

STOP Condition

To end communication with a slave, the master must generate a STOP condition. A STOP condition is defined as a change in state of SDA from low to high while SCL remains high.

Repeated START Condition

Repeated STARTs are commonly used for read accesses after having specified a memory address to read from in a preceding write access. The master can use a repeated START condition at the end of a data transfer to immediately initiate a new data transfer following the current one. A repeated START condition is generated the same way as a normal START condition, but without leaving the bus idle after a STOP condition.

Data Valid

With the exception of the START and STOP condition, transitions of SDA can occur only during the low state of SCL. The data on SDA must remain valid and unchanged during the entire high pulse of SCL plus the required setup and hold time ($t_{HD:DAT}$ after the falling edge of SCL and $t_{SU:DAT}$ before the rising edge of SCL; see [Figure 4](#)). There is one clock pulse per bit of data. Data is shifted into the receiving device during the rising edge of the SCL pulse.

When finished with writing, the master must release the SDA line for a sufficient amount of setup time (minimum $t_{SU:DAT}$ + t_R in [Figure 4](#)) before the next rising edge of SCL to start reading. The slave shifts out each data bit on SDA at the falling edge of the previous SCL pulse and the data bit is valid at the rising edge of the current SCL pulse. The master generates all SCL clock pulses, including those needed to read from a slave.

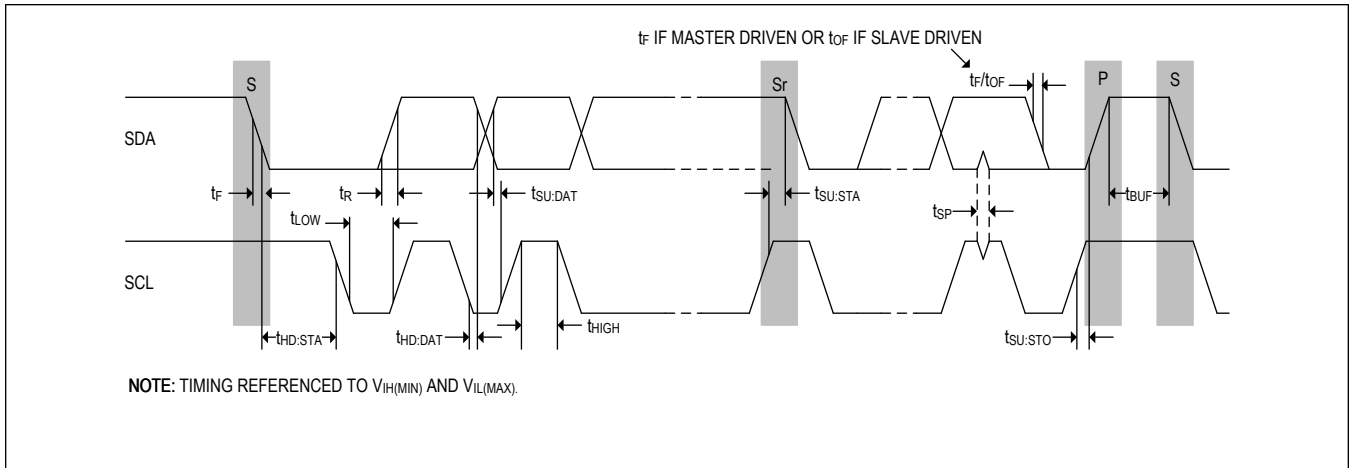


Figure 4. I²C Timing Diagram

DS28C50

DeepCover® I²C Secure SHA-3 Authenticator with
ChipDNA PUF Protection

Ordering Information

PART NUMBER	TEMP RANGE	PIN-PACKAGE
DS28C50Q+T	-40°C to +85°C	6 TDFN (2.5k pcs reel)

+Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape and reel.

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	9/19	Initial release	—

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