
#### Abstract

General Description The MAX1002 is a dual, 6-bit analog-to-digital converter (ADC) that combines high-speed, low-power operation with a user-selectable input range, an internal reference, and a clock oscillator. The dual, parallel ADCs are designed to convert in-phase (I) and quadrature (Q) analog signals into two 6-bit offset-binary-coded digital outputs at sampling rates up to 60Msps while achieving typical integral nonlinearity (INL) and differential nonlinearity (DNL) of $\pm 1 / 4 \mathrm{LSB}$. The ability to interface directly with baseband I and Q signals makes the MAX1002 ideal for use in direct-broadcast satellite, VSAT, and QAM16 demodulation applications. The MAX1002 input amplifiers feature true differential inputs, a $55 \mathrm{MHz}-0.5 \mathrm{~dB}$ analog bandwidth, and userprogrammable input full-scale ranges of $125 \mathrm{mVp}-\mathrm{p}$, $250 \mathrm{mVp}-\mathrm{p}$, or $500 \mathrm{mVp}-\mathrm{p}$. With an AC-coupled input signal, matching performance between input channels is typically 0.1 dB gain, $1 / 4 \mathrm{LSB}$ offset, and $0.5^{\circ}$ phase. Dynamic performance is 5.85 effective number of bits (ENOB) with a 20 MHz analog input signal, or 5.78 ENOB with a 50 MHz input signal. The MAX1002 operates with a single +5 V power supply and provides TTL-compatible digital outputs. The device is available in the commercial temperature range $\left(0^{\circ} \mathrm{C}\right.$ to $+70^{\circ} \mathrm{C}$ ) and comes in a 36-pin SSOP package.


## Applications

Direct Broadcast Satellite (DBS) Receivers VSAT Receivers
Wide Local Area Networks (WLAN)
Cable Television Set-Top Boxes

Features

\author{

- $\pm 1 / 4 L S B$ INL and DNL, Typical <br> - 1/4LSB (typ) Channel-to-Channel Offset Matching <br> - 0.1dB Gain and $0.5^{\circ}$ Phase Matching, Typical <br> - Internal Bandgap Voltage Reference <br> - Two Matched 6-Bit, 60Msps ADCs <br> - Excellent Dynamic Performance: <br> 5.85 ENOB with 20MHz Analog Input 5.7 ENOB with 50MHz Analog Input <br> - Internal Oscillator with Overdrive Capability <br> - 55MHz (-0.5dB) Bandwidth Input Amplifiers with True Differential Inputs <br> - User-Selectable Input Full-Scale Range ( 125 mV p-p, 250 mV p-p, or 500 mVp -p) <br> - Single-Ended or Differential Input Drive <br> - +5V Single Supply <br> - TTL Outputs <br> - 90Msps Upgrade with +3.3V CMOS-Compatible Output Available (MAX1003)
}

Ordering Information

| PART | TEMP. RANGE | PIN-PACKAGE |
| :---: | :---: | :--- |
| MAX1002CAX | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 36 SSOP |

Pin Configuration appears at end of data sheet.


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## Low-Power, 60Msps, Dual, 6-Bit ADC

## ABSOLUTE MAXIMUM RATINGS

VCC to GND ............................................................................................................................................................................................................-0.3V, VCC
VCCO to OGND.

Continuous Power Dissipation ( $\mathrm{T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ ) SSOP (derate $45 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) 941 mW Operating Temperature Range.............................. $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ Storage Temperature Range ............................. $65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ Lead Temperature (soldering, <10sec)........................... $300^{\circ} \mathrm{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS

( $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{\mathrm{CCO}}=+5 \mathrm{~V} \pm 5 \% ; \mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$; unless otherwise noted.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DC ACCURACY (Note 1) |  |  |  |  |  |  |
| Resolution | RES |  | 6 |  |  | Bits |
| Integral Nonlinearity | INL |  | -0.5 | $\pm 0.25$ | 0.5 | LSB |
| Differential Nonlinearity | DNL | No missing codes over temperature | -0.5 | $\pm 0.25$ | 0.5 | LSB |
| Full-Scale Input Range | VFSH | GAIN = VCC (high gain) | 118.75 | 125 | 131.25 | $m V p-p$ |
|  | VFSM | GAIN = open (mid gain) | 237.5 | 250 | 262.5 |  |
|  | $\mathrm{V}_{\text {FSL }}$ | GAIN = GND (low gain) | 475 | 500 | 525 |  |
| INVERTING AND NONINVERTING ANALOG INPUTS |  |  |  |  |  |  |
| Input Open-Circuit Voltage | VAOC |  | 2.25 | 2.35 | 2.45 | V |
| Input Resistance | RIN |  | 13 | 20 | 29 | $\mathrm{k} \Omega$ |
| Input Capacitance | Cin | Guaranteed by design |  | 3 | 5 | pF |
| Common-Mode Voltage Range | Vсм | Other analog input driven with external source (Note 2) | 1.75 |  | 2.75 | V |
| OSCILLATOR INPUTS |  |  |  |  |  |  |
| Oscillator Input Resistance | Rosc | Other oscillator input tied to $\mathrm{V}_{\mathrm{CC}}+0.3 \mathrm{~V}$ | 4.8 | 8 | 12.1 | $\mathrm{k} \Omega$ |
| DIGITAL OUTPUTS (DI0-DI5, DQ0-DQ5) |  |  |  |  |  |  |
| Digital Outputs Logic-High Voltage | Voh | ISOURCE $=50 \mu \mathrm{~A}$ | 2.4 |  |  | V |
| Digital Outputs Logic-Low Voltage | VOL | ISINK $=400 \mu \mathrm{~A}$ |  |  | 0.5 | V |
| POWER SUPPLY |  |  |  |  |  |  |
| Supply Current | IcC |  |  | 63 | 104 | mA |
| Power-Supply Rejection Ratio | PSRR | $\mathrm{V}_{\mathrm{CC}}=4.75 \mathrm{~V}$ to 5.25 V (Note 3) |  | -75 | -40 | dB |
| Digital Outputs Supply Current | Icco | 20 MHz , FS I \& Q analog inputs, Cload $=15 p F($ Note 4$)$ |  |  | 24 | mA |
| Power Dissipation | PD |  |  | 380 |  | mW |

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## AC ELECTRICAL CHARACTERISTICS

( $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{\mathrm{CCO}}=+5 \mathrm{~V} \pm 5 \% ; \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$; unless otherwise noted.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DYNAMIC PERFORMANCE (GAIN = open; external 60 MHz clock (Figure 7); VINI, VINIQ $=20 \mathrm{MHz}$ sine; amplitude -1dB below FS; unless otherwise noted.) |  |  |  |  |  |  |
| Maximum Sample Rate | fmax |  | 60 |  |  | Msps |
| Analog Input -0.5dB Bandwidth | BW | Gain = GND, open, Vcc | 55 |  |  | MHz |
| Effective Number of Bits | ENOBM | GAIN = open (mid gain) | 5.6 | 5.85 |  | Bits |
|  |  | GAIN = open (mid gain), $\mathrm{V}_{\mathrm{IN}}=50 \mathrm{MHz},-1 \mathrm{~dB}$ below FS | 5.7 |  |  |  |
|  | ENOBH | Gain = VCC (high gain) | 5.8 |  |  |  |
|  | ENOBL | Gain = VCC (low gain) | 5.85 |  |  |  |
| Signal-to-Noise and Distortion Ratio | SINAD | Gain = open (mid gain) | 35.4 | 37 |  | dB |
| Input Offset (Note 5) | OFF | I channel | -0.5 |  | 0.5 | LSB |
|  |  | Q channel | -0.5 |  | 0.5 |  |
| Crosstalk Between ADCs | XTLK |  | -55 |  |  | dB |
| Offset Mismatch Between ADCs | OMM2 | (Note 5) | -0.5 | $\pm 0.25$ | 0.5 | LSB |
| Amplitude Match Between ADCs | AM |  | -0.2 | $\pm 0.1$ | 0.2 | dB |
| Phase Match Between ADCs | PM |  | -2 | $\pm 0.5$ | 2 | degrees |
| TIMING CHARACTERISTICS (data outputs: $\mathrm{R}_{\mathrm{L}}=1 \mathrm{M} \Omega, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$, Figure 8) |  |  |  |  |  |  |
| DCLK to Data-Propagation Delay | tPD | (Note 6) |  | 7.1 |  | ns |
| Data Valid Skew | tskew | (Note 6) |  | 3.6 |  | ns |
| Input to DCLK Delay | tDCLK | TNK+ to DCLK (Note 6) |  | 5.3 |  | ns |
| Aperture Delay | tAP |  |  | 5.5 |  | ns |
| Pipeline Delay | PD |  |  | 1 |  | clock cycle |

Note 1: Best straight-line linearity method.
Note 2: A typical application will AC couple the analog input to the DC bias level present at the analog inputs (typically 2.35V). However, it is also possible to DC couple the analog input (using differential or single-ended drive) within this commonmode input range (Figures 4, 5).
Note 3: PSSR is defined as the change in the mid-gain, full-scale range as a function of the variation in VCC supply voltage (expressed in decibels).
Note 4: The current in the $\mathrm{V}_{\mathrm{CCO}}$ supply is a strong function of the capacitive loading on the digital outputs. To minimize supply transients and achieve the best dynamic performance, reduce the capacitive loading effects by keeping line lengths on the digital outputs to a minimum.
Note 5: Offset-correction compensation enabled, $0.22 \mu \mathrm{~F}$ at Q and I compensation inputs (Figures 2, 3).
Note 6: tpD and tSKEw are measured from the 1.4 V level of the output clock, to the 1.4 V level of either the rising or falling edge of a data bit. tDCLK is measured from the $50 \%$ level of the clock overdrive signal on TNK+ to the 1.4 V level of DCLK. The capacitive load on the outputs is 15 pF .

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Typical Operating Characteristics





DIFFERENTIAL NONLINEARITY
vs. CODE



DIFFERENTIAL NONLINEARITY vs. CODE


## Low-Power, 60Msps, Dual, 6-Bit ADC

| PIN | NAME | FUNCTION |
| :---: | :---: | :---: |
| 1 | GAIN | Gain-Select Input. Sets input full-scale range: $125 / 250 / 500 \mathrm{mVp}-\mathrm{p}$ (Table 1). |
| 2 | IOCC+ | Positive I-Channel Offset-Correction Compensation. Connect $0.22 \mu \mathrm{~F}$ capacitor for AC-coupled inputs (Figures 2, 3). Ground for DC-coupled inputs (Figures 4, 5). |
| 3 | IOCC- | Negative I-Channel Offset-Correction Compensation. Connect $0.22 \mu \mathrm{~F}$ capacitor for AC-coupled inputs (Figures 2, 3). Ground for DC-coupled inputs (Figures 4, 5). |
| 4 | IIN+ | I-Channel Noninverting Analog Input |
| 5 | IIN- | I-Channel Inverting Analog Input |
| 6 | Vcc | $+5 \mathrm{~V} \pm 5 \%$ Supply. Bypass with $0.01 \mu \mathrm{~F}$ capacitor to GND (Pin 7 ). |
| $\begin{gathered} 7,11,12, \\ 18,19 \end{gathered}$ | GND | Analog Ground |
| 8 | VCC | $+5 \mathrm{~V} \pm 5 \%$ Supply. Bypass with $0.01 \mu \mathrm{~F}$ capacitor to GND (Pin 11). |
| 9 | TNK+ | Positive Oscillator/Clock Input |
| 10 | TNK- | Negative Oscillator/Clock Input |
| 13 | VCC | $+5 \mathrm{~V} \pm 5 \%$ Supply. Bypass with $0.01 \mu \mathrm{~F}$ capacitor to GND (Pin 12). |
| 14 | QIN- | Q-Channel Inverting Analog Input |
| 15 | QIN+ | Q-Channel Noninverting Analog Input |
| 16 | QOCC- | Negative Q-Channel Offset-Correction Compensation. Connect $0.22 \mu \mathrm{~F}$ capacitor for AC-coupled inputs (Figures 2, 3). Ground for DC-coupled inputs (Figures 4, 5). |
| 17 | QOCC+ | Positive Q-Channel Offset-Correction Compensation. Connect $0.22 \mu \mathrm{~F}$ capacitor for AC-coupled inputs (Figures 2, 3). Ground for DC-coupled inputs (Figures 4, 5). |
| 20-25 | DQ5-DQ0 | Q-Channel Digital Outputs 0-5. DQ5 is the most significant bit (MSB). |
| 26, 28 | Vcco | $+5 \mathrm{~V} \pm 5 \%$ Digital Supply. Bypass each with 47pF to OGND (Pin 27). |
| 27 | OGND | Digital Output Ground |
| 29 | DCLK | Digital Clock Output. Frames the output data. |
| 30-35 | DIO-DI5 | I-Channel Digital Outputs 0-5. DI5 is the most significant bit (MSB). |
| 36 | VCC | $+5 \mathrm{~V} \pm 5 \%$ Supply. Bypass with $0.01 \mu \mathrm{~F}$ to GND (Pin 19). |

## Detailed Description

## Converter Operation

The MAX1002 contains two 6-bit analog-to-digital converters (ADCs), a buffered voltage reference, and oscillator circuitry. The ADCs use a flash-conversion technique to convert an analog input signal into a 6-bit parallel digital output code. The MAX1002's unique design includes 63 fully differential comparators and a proprietary encoding scheme that ensures no more than 1LSB dynamic encoding error. The control logic interfaces easily to most digital signal processors (DSPs) and microprocessors ( $\mu \mathrm{Ps}$ ) with +5 V CMOScompatible logic interfaces. Figure 1 shows the MAX1002 in a typical application.

Programmable Input Amplifiers
The MAX1002 has in-phase (I) and quadrature (Q) pro-grammable-gain input amplifiers with a 55 MHz -0.5 dB bandwidth and true differential inputs. To maximize performance in high-speed systems, each amplifier has less than 5 pF of input capacitance. The input amplifier gain is programmed via the GAIN pin to provide three possible input full-scale ranges (FSR) (Table 1).

Table 1. Input Amplifier Programming

| GAIN | INPUT FULL-SCALE RANGE <br> (mVp-p) |
| :---: | :---: |
| GND | 500 |
| Open | 250 |
| $\mathrm{~V}_{\mathrm{CC}}$ | 125 |

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Figures 2 and 3 show single-ended and differential ACcoupled input circuits. Each of the amplifier inputs is internally biased to a 2.35 V reference through a $20 \mathrm{k} \Omega$ resistor, eliminating external DC bias circuits. A series $0.1 \mu \mathrm{~F}$ capacitor is required at each amplifier input for AC-coupled signals.
When operating with AC-coupled inputs, the input amplifiers' DC offset voltage is nulled to within $\pm 1 / 2$ LSB by an on-chip offset-correction amplifier. An external
compensation capacitor is required to set the dominant pole of the offset-correction amplifier's frequency response (Figures 2 and 3). The compensation capacitor determines the low-frequency corner of the analog input response according to the following formula:

$$
f_{c}=1 /(0.1 \times C)
$$

where $C$ is the value of the compensation capacitor in $\mu \mathrm{F}$, and fc is the corner frequency in Hz .


Figure 1. Commercial Satellite Receiver System

## Low-Power, 60Msps, Dual, 6-Bit ADC

Figures 4 and 5 show single-ended and differential DCcoupled input circuits for applications where a DC component of the input signal is present. The amplifiers' input common-mode voltage range extends from 1.75 V to 2.75 V . To prevent attenuation of the input signal's DC component when operating in this mode, disable the off-set-correction amplifier by grounding the _OCC+ and _OCC- pins for the I and Q blocks (Figures $\overline{4}$ and 5).


Figure 2. Single-Ended AC-Coupled Input


Figure 4. Single-Ended DC-Coupled Input

ADCs
The I and Q ADC blocks receive the analog signals from the respective I and Q input amplifiers. The ADCs use flash conversion with 63 fully differential comparators to digitize the analog input signal into a 6-bit output in offset binary format.


Figure 3. Differential AC-Coupled Input

Figure 5. Differential DC-Coupled Input


## Low-Power, 60Msps, Dual, 6-Bit ADC

The MAX1002 features a proprietary encoding scheme that ensures no more than 1LSB dynamic encoding error. Dynamic encoding errors resulting from metastable states may occur when the analog input voltage, at the time the sample is taken, falls close to the decision point for any one of the input comparators. The resulting output code for typical converters can be incorrect, including false full- or zero-scale outputs. The MAX1002's unique design reduces the magnitude of this type of error to 1LSB.

## Internal Voltage Reference

An internal buffered bandgap reference is included on the MAX1002 to drive the ADC's reference ladders. The on-chip reference and buffer eliminate any external (high-impedance) connections to the reference ladder, minimizing the potential for noise coupling from external circuitry while ensuring that the voltage reference, input amplifier, and reference ladder track well with variations in temperature and power supplies.

## Oscillator Circ uit

The MAX1002 includes a differential oscillator, which is controlled by an external parallel resonant (tank) network (Figure 6). As an alternative, the oscillator may be overdriven with an external clock source (Figure 7).

Internal-Clock Operation (Tank)
If the tank circuit is used, the resonant inductor should have a sufficiently high $Q$ and a self-resonant frequency (SRF) of at least twice the intended oscillator frequency. Coilcraft's $1008 \mathrm{HS}-221$, with a 700 MHz SRF and a Q of 45, works well for this application. Generate different clock-frequency ranges by adjusting varactor and tank elements.
An internal-clock-driver buffer is included to provide sharp clock edges to the internal flash comparators. The buffer ensures that the comparators are simultaneously clocked, maximizing the ADC's effective number of bits of performance.

## External-Clock Operation

To accommodate designs that use an external clock, the MAX1002's internal oscillator can be overdriven by an external clock source (Figure 7). The external clock source should be a sinusoid to minimize clock-phase noise and jitter, which can degrade the ADC's effective bits performance. AC couple the clock source (recommended voltage level is approximately $1 \mathrm{Vp}-\mathrm{p}$ ) to the oscillator inputs (Figure 7).


Figure 7. External-Clock-Drive Circuit

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Figure 8. MAX1002 Timing Diagram

## Output Data Format

The conversion results are output on a dual 6 -bit-wide data bus. Data is latched into the ADC output latch following a pipeline delay of one clock cycle (Figure 8). Output data is clocked out of the respective ADC's dataoutput pins ( $\mathrm{D}-0$ through D_5) on the rising edge of the clock output (DCLK), with a DCLK-to-data propagation delay (tpD) of 7.1 ns . The MAX1002 outputs are TL compatible.

Transfer Function
Figure 9 shows the MAX1002's nominal transfer function. Output coding is offset binary with 1 LSB $=$ FSR $/ 63$.


Figure 9. Ideal Transfer Function

## Low-Power, 60Msps, Dual, 6-Bit ADC

## Applications Information

## Layout, Grounding, and Bypassing

The MAX1002 is designed with separate analog and digital power-supply and ground connections to isolate high-current digital noise spikes from the more sensitive analog circuitry. The high-current digital output ground (OGND) and analog ground (GND) should be at the same DC level, connected at only one location on the board. This provides best noise immunity and improved conversion accuracy. Use of separate ground planes is strongly recommended.
The entire board requires good DC bypassing for both analog and digital supplies. Place the bypass capacitors close to where the power is routed onto the board, i.e., close to the connector. $10 \mu \mathrm{~F}$ electrolytic capacitors with low ESR-ratings are recommended. For best effective bits performance, minimize capacitive loading at the digital outputs. Keep the digital output traces as short as possible.
The MAX1002 can operate with one +5 V supply. For optimum performance, separate $+5 \mathrm{~V} \pm 5 \%$ supplies and bypassing are recommended. Bypass each of the Vcc supply pins to its respective GND with highquality ceramic capacitors located as close to the package as possible (Table 2). Consult the evaluation kit for a suggested layout and bypassing scheme.

Table 2. Bypassing

| SUPPLY <br> FUNCTION | Vcc / <br> Vcco | BYPASS TO <br> GND/OGND | CAPACITOR <br> VALUE |
| :--- | :---: | :---: | :---: |
| Analog Inputs | 6 | 7 | $0.01 \mu \mathrm{~F}$ |
| Oscillator/Clock | 8 | 11 | $0.01 \mu \mathrm{~F}$ |
| Converter | 13 | 12 | $0.01 \mu \mathrm{~F}$ |
| Digital Q Output | 26 | 27 | 47 pF |
| Digital I Output | 28 | 27 | 47 pF |
| Buffer | 36 | 19 | $0.01 \mu \mathrm{~F}$ |

## Dynamic Performance

Signal-to-noise plus distortion (SINAD) is the ratio of the fundamental input frequency's RMS amplitude to all other ADC output signals. The output spectrum is limited to frequencies above DC and below one-half the ADC sample rate.
The theoretical minimum A/D noise is caused by quantization error, and results directly from the ADC's resolution: $\mathrm{SNR}=(6.02 \mathrm{~N}+1.76) \mathrm{dB}$, where N is the number of bits of resolution. Therefore, a perfect 6-bit ADC can do no better than 38 dB .
The FFT Plot (see Typical Operating Characteristics) shows the result of sampling a pure 20 MHz sinusoid at a 60 MHz clock rate. This FFT plot of the output shows the output level in various spectral bands. The plot has been averaged to reduce the quantization noise floor and reveal the low-amplitude spurs. This emphasizes the excellent spurious-free dynamic range of the MAX1002.
The effective resolution (or ENOB) the ADC provides can be measured by transposing the equation that converts resolution to SNR: $\mathrm{N}=($ SINAD - 1.76) / 6.02 (see Typical Operating Characteristics).

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TRANSISTOR COUNT: 6097

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ADS7955QDBTRQ1 ADS7807UB ADS7805UB ADS1220IPWR MCP3426A0-E/MS MCP3422A0-E/MC AD9220AR MAX11212AEUB+
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