

### **General Description**

The MAX1069 is a low-power, 14-bit successiveapproximation analog-to-digital converter (ADC). The device features automatic power-down, an on-chip 4MHz clock, a +4.096V internal reference, and an I<sup>2</sup>Ccompatible 2-wire serial interface capable of both fast and high-speed modes.

The MAX1069 operates from a single supply and consumes 5mW at the maximum conversion rate of 58.6ksps. AutoShutdown™ powers down the device between conversions, reducing supply current to less than 50µA at a 1ksps throughput rate. The option of a separate digital supply voltage allows direct interfacing with +2.7V to +5.5V digital logic.

The MAX1069 performs a unipolar conversion on its single analog input using its internal 4MHz clock. The full-scale analog input range is determined by the internal reference or by an externally applied reference voltage ranging from 1V to VAVDD.

The four address select inputs (ADD0-ADD3) allow up to 16 MAX1069 devices on the same bus.

The MAX1069 is packaged in a 14-pin TSSOP and offers both commercial and extended temperature ranges. Refer to the MAX1169 for a 16-bit device in a pin-compatible package.

### **Applications**

Hand-Held Portable Applications

Medical Instruments

Battery-Powered Test Equipment

Solar-Powered Remote Systems

Receive Signal Strength Indicators

System Supervision

AutoShutdown is a trademark of Maxim Integrated Products, Inc.

#### **Features**

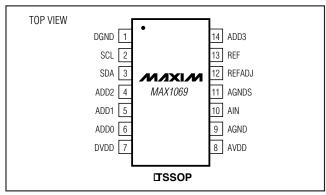
- ♦ High-Speed I<sup>2</sup>C-Compatible Serial Interface 400kHz Fast Mode 1.7MHz High-Speed Mode
- ♦ +2.7V to +5.5V Adjustable Logic Level
- ♦ Internal +4.096V Reference
- **♦ External Reference: 1V to VAVDD**
- ♦ Internal 4MHz Conversion Clock
- ♦ 58.6ksps Sampling Rate
- **♦** AutoShutdown Between Conversions
- **♦ Low Power** 
  - 5.0mW at 58.6ksps
  - 4.2mW at 50ksps
  - 2.0mW at 10ksps
  - 0.23mW at 1ksps
  - 3µW in Shutdown
- ♦ Small 14-Pin TSSOP Package

### **Ordering Information**

PART	TEMP RANGE	PIN- PACKAGE	INL (LSB)
MAX1069AEUD+	-40°C to +85°C	14 TSSOP	±1
MAX1069BEUD+	-40°C to +85°C	14 TSSOP	±2

<sup>+</sup>Denotes a lead(Pb)-free/RoHS-compliant package.

## **Pin Configuration**



#### **ABSOLUTE MAXIMUM RATINGS**

AVDD to AGND	0.3V to +6V
DVDD to DGND	0.3V to +6V
AGND to DGND	0.3V to +0.3V
AGNDS to AGND	0.3V to +0.3V
AIN, REF, REFADJ to AGND	0.3V to $(V_{AVDD} + 0.3V)$
SCL, SDA, ADD_ to DGND	
Maximum Current into Any Pin	50mA

Continuous Power Dissipation (T <sub>A</sub> =	
14-Pin TSSOP (derate 9.1mW/°C a	above +85°C)864mW
Operating Temperature Range	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Junction Temperature	
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{AVDD} = +4.75 \text{V to } +5.25 \text{V}, V_{DVDD} = +2.7 \text{V to } +5.5 \text{V}, f_{SCL} = 1.7 \text{MHz} (33\% \text{ duty cycle}), f_{SAMPLE} = 58.6 \text{ksps}, V_{REF} = +4.096 \text{V}, external reference applied to REF, REFADJ = AVDD, C_{REF} = 10 \mu\text{F}, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted}. Typical values are at <math>T_A = +25^{\circ}\text{C}$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
DC ACCURACY (Note 1)	•					•	
Resolution			14			Bits	
Relative Accuracy	INII	MAX1069A			±1	LCD	
(Note 2)	INL	MAX1069B			±2	LSB	
Differential Menlinearity	DNL	MAX1069A, no missing codes			±1	LCD	
Differential Nonlinearity	DINL	MAX1069B, no missing codes			±1	LSB	
Offset Error				2	5	mV	
Offset-Error Temperature Coefficient				1.0		ppm/°C	
Gain Error		(Note 3)		±0.25	±0.5	%FSR	
Gain Temperature Coefficient				0.1		ppm/°C	
DYNAMIC PERFORMANCE (fin(	sine wave) = 1I	(Hz, V <sub>IN</sub> = V <sub>REF(P-P)</sub> , f <sub>SAMPLE</sub> = 58.6ksps)	•				
Signal-to-Noise Plus Distortion	SINAD		81	84		dB	
Total Harmonic Distortion	THD	Up to the 5th harmonic		-99	-86	dB	
Spurious-Free Dynamic Range	SFDR		87	102		dB	
Signal-to-Noise Ratio	SNR		82	84		dB	
Full-Power Bandwidth	FPBW	-3dB point		4		MHz	
Full-Linear Bandwidth		SINAD > 81dB		20		kHz	
<b>CONVERSION RATE</b> (Figure 11)							
Conversion Time	toony	Fast mode		7.1	7.5	0	
(SCL Stretched Low)	tCONV	High-speed mode		5.8	6	μs	
Throughput Poto (Noto 4)	former	Fast mode			19		
Throughput Rate (Note 4) fSAMPLE		High-speed mode			58.6	ksps	
Internal Clock Frequency	fclk			4		MHz	
Track/Hold Acquisition Time	tACQ	(Note 5)	1100			ns	

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{AVDD} = +4.75V \text{ to } +5.25V, V_{DVDD} = +2.7V \text{ to } +5.5V, f_{SCL} = 1.7MHz (33\% \text{ duty cycle}), f_{SAMPLE} = 58.6ksps, V_{REF} = +4.096V, external reference applied to REF, REFADJ = AVDD, C_{REF} = 10\mu\text{F}, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}\text{C}$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Aperture Delay	+ 4 5	Fast mode		50		200
(Figure 11c) (Note 6)	t <sub>AD</sub>	High-speed mode		30		ns
Aperture Jitter	+	Fast mode		100		200
(Figure 11c)	taj	High-speed mode		100		ps
ANALOG INPUT (AIN)						
Input Voltage Range	V <sub>AIN</sub>		0		V <sub>REF</sub>	V
Input Leakage Current		On/off-leakage current, V <sub>AIN</sub> = 0V or V <sub>AVDD</sub> , no clock, f <sub>SCL</sub> = 0Hz		±0.01	±10	μA
Input Capacitance	CIN			35		рF
INTERNAL REFERENCE (Bypas	s REFADJ w	ith 0.1μF to AGND and REF with 10μF to AGN	D)			
REF Output Voltage	V <sub>REF</sub>		4.056	4.096	4.136	V
Reference Temperature Coefficient	TCREF	T <sub>A</sub> = -40°C to +85°C		±35		ppm/°C
Reference Short-Circuit Current	IREFSC			10	4.136	mA
REFADJ Output Voltage			4.056	4.096	4.000	V
REFADJ Input Range		For small adjustments, from 4.096V		±60		mV
EXTERNAL REFERENCE (REFA	DJ = AV <sub>DD</sub> )					
REFADJ Buffer Disable Voltage		Pull REFADJ high to disable the internal bandgap reference and reference buffer	V <sub>AVDD</sub> -	0.1		V
REFADJ Buffer Enable Voltage				VA	VDD - 0.4	V
Reference Input Voltage Range		(Note 7)	1.0		Vavdd	V
REF Input Current	I <sub>REF</sub>	VREF = +4.096V, VIN = VREF(P-P) fIN(sine wave) = 1kHz, fsample = 62.1ksps		27		μA
		V <sub>REF</sub> = +4.096V, shutdown		0.1		
DIGITAL INPUTS/OUTPUTS (SCL	., SDA)					
Input High Voltage	VIH		$0.7 \times V_{D}$	VDD		V
Input Low Voltage	VIL			0.3	$\times V_{DVDD}$	V
Input Hysteresis	VHYST		0	$1.1 \times V_{DVD}$	D	V
Input Current	I <sub>IN</sub>				±10	μΑ
Input Capacitance	CIN			15		pF
Output Low Voltage	Vol	Isink = 3mA			0.4	V
ADDRESS SELECT INPUTS (AD	D3, ADD2, A	DD1, ADD0)			<u>.</u>	
Input High Voltage			0.7 × V <sub>□</sub>			V
Input Low Voltage				0.3	$\times V_{DVDD}$	V
Input Hysteresis			0	$1.1 \times V_{DVD}$	D	V
Input Current					±10	μΑ
Input Capacitance				15		рF

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{AVDD} = +4.75V \text{ to } +5.25V, V_{DVDD} = +2.7V \text{ to } +5.5V, f_{SCL} = 1.7MHz (33\% \text{ duty cycle}), f_{SAMPLE} = 58.6ksps, V_{REF} = +4.096V, external reference applied to REF, REFADJ = AVDD, C_{REF} = 10\mu\text{F}, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted}. Typical values are at <math>T_A = +25^{\circ}\text{C}$ .)

PARAMETER	SYMBOL	COND	ITIONS	MIN	TYP	MAX	UNITS
POWER REQUIREMENTS (AVDI	, AGND, DV	DD, DGND)					
Analog Supply Voltage	VAVDD			4.75		5.25	V
Digital Supply Voltage	V <sub>D</sub> VDD			2.7		5.5	V
		Internal reference	f <sub>SAMPLE</sub> = 58.6ksps		1.8	2.5	mA
	I I	(powered down	fsample = 10ksps		0.7		11171
		between conversions,	fsample = 1ksps		40		μΑ
		$R\overline{W} = 0$	Shutdown		0.4	5.0	
			f <sub>SAMPLE</sub> = 58.6ksps		1.8	2.5	
Analog Supply Current	IA./DD	Internal reference	fsample = 10ksps		1.4		mA
Analog Supply Cullent	lavdd	(always on, $R/\overline{W} = 1$ )	fsample = 1ksps		1.1		
			Shutdown		0.4	5	μΑ
			fsample = 58.6ksps		0.90	1.8	m ^
		External reference	fsample = 10ksps		0.36		– mA
		(REFADJ = AVDD)	fsample = 1ksps		40		
			Shutdown		0.4	5	μΑ
		f <sub>SAMPLE</sub> = 58.6ksps			260	400	
District Constant Constant		f <sub>SAMPLE</sub> = 10ksps			65		]
Digital Supply Current	IDVDD	fsample = 1ksps			6		- μΑ
		Shutdown			0.2	5	]
Power-Supply Rejection Ratio	PSRR	$V_{AVDD} = 5V \pm 5\%$ , full	-scale input (Note 8)		2	6	LSB/V
TIMING CHARACTERISTICS FOR	2-WIRE FA	ST MODE (Figure 1a ai	nd Figure 2)				
Serial Clock Frequency	f <sub>SCL</sub>					400	kHz
Bus Free Time Between a STOP and a START Condition	tBUF			1.3			μs
Hold Time for Start Condition	thd,sta			0.6			μs
Low Period of the SCL Clock	t <sub>LOW</sub>			1.3			μs
High Period of the SCL Clock	tHIGH			0.6			μs
Setup Time for a Repeated START Condition (Sr)	tsu,sta			0.6			μs
Data Hold Time	thd,dat	(Note 9)		0		900	ns
Data Setup Time	tsu,dat	,		100			ns
Rise Time of Both SDA and SCL Signals, Receiving	t <sub>R</sub>	(Note 10)		20 + 0.1C <sub>B</sub>		300	ns
Fall Time of SDA Transmitting	tF	(Note 10)		20 + 0.1C <sub>B</sub>		300	ns
Setup Time for STOP Condition	tsu,sto			0.6			μs
Capacitive Load for Each Bus	CB					400	pF
Pulse Width of Spike Suppressed	tsp					50	ns

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{AVDD} = +4.75V \text{ to } +5.25V, V_{DVDD} = +2.7V \text{ to } +5.5V, f_{SCL} = 1.7MHz (33\% \text{ duty cycle}), f_{SAMPLE} = 58.6ksps, V_{REF} = +4.096V, external reference applied to REF, REFADJ = AVDD, C_{REF} = 10 \mu F, T_A = T_{MIN} \text{ to } T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
TIMING CHARACTERISTICS FOR	2-WIRE HIG	GH-SPEED MODE (Figure 1b and Figure 2)				
Serial Clock Frequency	fsclh	(Note 11)			1.7	MHz
Hold Time, (Repeated) Start Condition	<sup>†</sup> HD,STA		160			ns
Low Period of the SCL Clock	tLOW		320			ns
High Period of the SCL Clock	thigh		120			ns
Setup Time for a Repeated START Condition	tsu,sta		160			ns
Data Hold Time	thd,dat	(Note 9)	0		150	ns
Data Setup Time	t <sub>SU,DAT</sub>		10			ns
Rise Time of SCL Signal (Current Source Enabled)	tRCL	(Note 10)	10		80	ns
Rise Time of SCL Signal After Acknowledge Bit	<sup>t</sup> RCL1	(Note 10)	20		160	ns
Fall Time of SCL Signal	tFCL	(Note 10)	20		80	ns
Rise Time of SDA Signal	t <sub>RDA</sub>	(Note 10)	20		160	ns
Fall Time of SDA Signal	tFDA	(Note 10)	20		160	ns
Setup Time for STOP Condition	tsu,sto		160			ns
Capacitive Load for Each Bus	C <sub>B</sub>				400	pF
Pulse Width of Spike Suppressed	tsp				10	ns

- **Note 1:** DC accuracy is tested at V<sub>AVDD</sub> = +5.0V and V<sub>DVDD</sub> = +3.0V. Performance at power-supply tolerance limits is guaranteed by power-supply rejection test.
- Note 2: Relative accuracy is the deviation of the analog value at any code from its theoretical value after the full-scale range and offset have been calibrated.
- Note 3: Offset nullified.
- Note 4: One sample is achieved every 18 clocks in continuous conversion mode.

$$f_{SAMPLE} = \left(\frac{18 \text{ clocks}}{f_{SCL}} + t_{CONV}\right)^{-1}$$

Note 5: The track/hold acquisition time is two SCL cycles as illustrated in Figure 11.

$$t_{ACQ} = 2 \times \left(\frac{1}{f_{SCL}}\right)$$

- **Note 6:** A filter on SDA and SCL delays the sampling instant and suppresses noise spikes less than 10ns in high-speed mode and 50ns in fast mode.
- Note 7: ADC performance is limited by the converter's noise floor, typically  $480\mu V_{P-P}$ .
- Note 8:

$$PSRR = \frac{\left[V_{FS}(5.25V) - V_{FS}(4.75V)\right] \times \frac{2^N}{V_{REF}}}{5.25V - 4.75V}$$
 where N is the number of bits (14).

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{AVDD} = +4.75V \text{ to } +5.25V, V_{DVDD} = +2.7V \text{ to } +5.5V, f_{SCL} = 1.7MHz (33\% \text{ duty cycle}), f_{SAMPLE} = 58.6ksps, V_{REF} = +4.096V, external reference applied to REF, REFADJ = AVDD, C_{REF} = 10\mu\text{F}, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C}.)$ 

- Note 9: A master device must provide a data hold time for SDA (referred to V<sub>IL</sub> of SCL) in order to bridge the undefined region of SCL's falling edge (see Figure 1).
- Note 10:  $C_B$  = total capacitance of one bus line in pF.  $t_B$  and  $t_F$  measured between  $0.3 \times V_{DVDD}$  and  $0.7 \times V_{DVDD}$ .
- Note 11: fSCL must meet the minimum clock low time plus the rise/fall times.

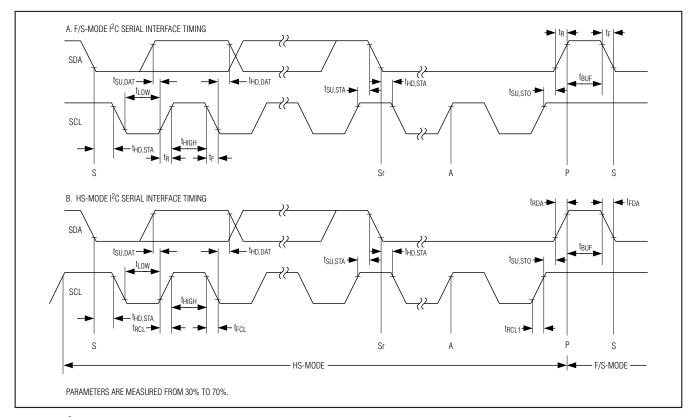


Figure 1. I<sup>2</sup>C Serial Interface Timing

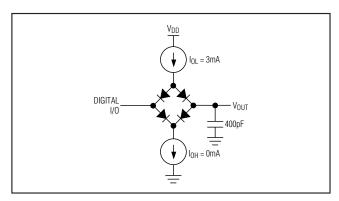
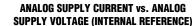
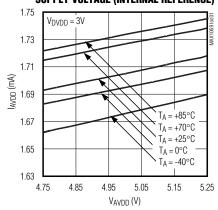


Figure 2. Load Circuit

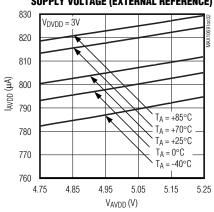
### **Typical Operating Characteristics**

 $(V_{DVDD} = +3.0V, V_{AVDD} = +5.0V, f_{SCL} = 1.7MHz$  (33% duty cycle),  $f_{SAMPLE} = 58.6ksps$ ,  $V_{REF} = +4.096V$ , external reference applied to REF, REFADJ = AVDD,  $C_{REF} = 10\mu F$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

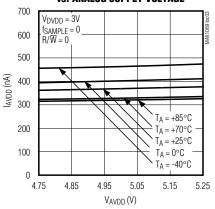




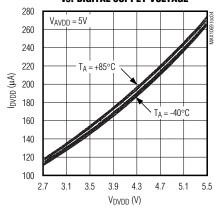




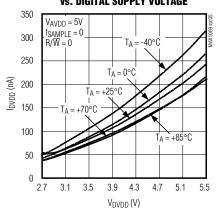
ANALOG SHUTDOWN CURRENT vs. Analog Supply Voltage



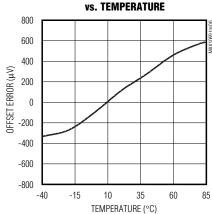
## DIGITAL SUPPLY CURRENT vs. DIGITAL SUPPLY VOLTAGE



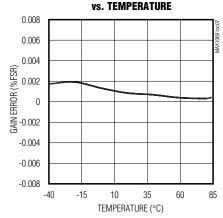
## DIGITAL SHUTDOWN CURRENT vs. DIGITAL SUPPLY VOLTAGE



## OFFSET ERROR



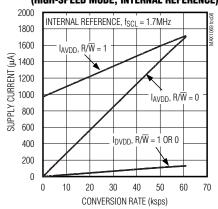
### GAIN ERROR



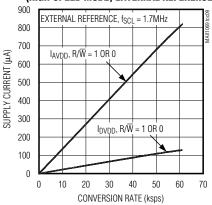
### Typical Operating Characteristics (continued)

 $(V_{DVDD} = +3.0V, V_{AVDD} = +5.0V, f_{SCL} = 1.7MHz (33\% duty cycle), f_{SAMPLE} = 58.6ksps, V_{REF} = +4.096V, external reference applied to REF, REFADJ = AVDD, C_{REF} = 10\mu F, T_A = +25°C, unless otherwise noted.)$ 

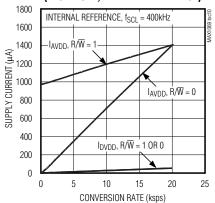
## SUPPLY CURRENT vs. CONVERSION RATE (HIGH-SPEED MODE, INTERNAL REFERENCE)



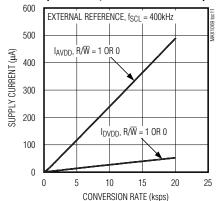
## SUPPLY CURRENT vs. CONVERSION RATE (HIGH-SPEED MODE, EXTERNAL REFERENCE)



## SUPPLY CURRENT vs. CONVERSION RATE (FAST MODE, INTERNAL REFERENCE)



## SUPPLY CURRENT vs. CONVERSION RATE (FAST MODE, EXTERNAL REFERENCE)

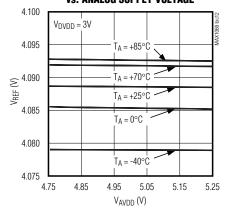


.\_\_\_\_\_ /N/XI/N

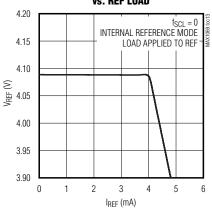
### Typical Operating Characteristics (continued)

 $(V_{DVDD} = +3.0V, V_{AVDD} = +5.0V, f_{SCL} = 1.7MHz$  (33% duty cycle),  $f_{SAMPLE} = 58.6ksps$ ,  $V_{REF} = +4.096V$ , external reference applied to REF, REFADJ = AVDD,  $C_{REF} = 10\mu F$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

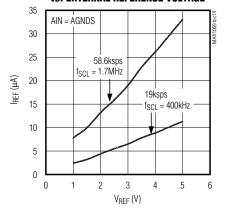
#### INTERNAL +4.096V REFERENCE VOLTAGE vs. analog supply voltage



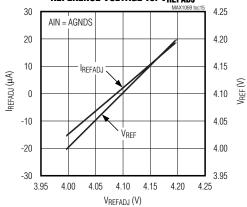
# INTERNAL REFERENCE VOLTAGE vs. REF LOAD



## EXTERNAL REFERENCE CURRENT vs. EXTERNAL REFERENCE VOLTAGE

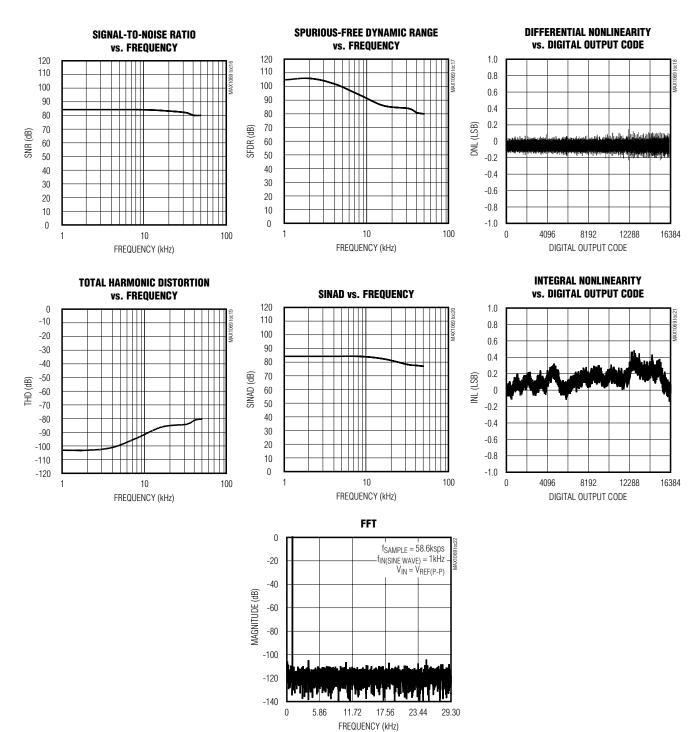


## EXTERNAL REFERENCE CURRENT AND REFERENCE VOLTAGE vs. V<sub>REFADJ</sub>



### Typical Operating Characteristics (continued)

 $(V_{DVDD} = +3.0V, V_{AVDD} = +5.0V, f_{SCL} = 1.7MHz (33\% duty cycle), f_{SAMPLE} = 58.6ksps, V_{REF} = +4.096V, external reference applied to REF, REFADJ = AVDD, C_{REF} = 10\mu F, T_A = +25°C, unless otherwise noted.)$ 



### **Pin Description**

PIN	NAME	FUNCTION
1	DGND	Digital Ground
2	SCL	Clock Input
3	SDA	Data Input/Output
4	ADD2	Address Select Input 2
5	ADD1	Address Select Input 1
6	ADD0	Address Select Input 0
7	DVDD	Digital Power Input. Bypass to DGND with a 0.1µF capacitor.
8	AVDD	Analog Power Input. Bypass to AGND with a 0.1µF capacitor.
9	AGND	Analog Ground
10	AIN	Analog Input
11	AGNDS	Analog Signal Ground. Negative reference for analog input. Connect to AGND.
12	REFADJ	Internal Reference Output and Reference Buffer Input. Bypass to AGND with a 0.1µF capacitor. Connect REFADJ to AVDD to disable the internal bandgap reference and reference-buffer amplifier.
13	REF	Reference Buffer Output and External Reference Input. Bypass to AGND with a 10µF capacitor when using the internal reference.
14	ADD3	Address Select Input 3

### Detailed Description

The MAX1069 analog-to-digital converter (ADC) uses successive-approximation conversion (SAR) techniques and on-chip track-and-hold (T/H) circuitry to capture and convert an analog signal to a serial 14-bit digital output.

The MAX1069 performs a unipolar conversion on its single analog input using its internal 4MHz clock. The full-scale analog input range is determined by the internal reference or by an externally applied reference voltage ranging from 1V to  $V_{AVDD}$ .

The flexible 2-wire serial interface provides easy connection to microcontrollers ( $\mu$ Cs) and supports data rates up to 1.7MHz. Figure 3 shows the simplified functional diagram for the MAX1069 and Figure 4 shows the typical application circuit.

#### **Power Supply**

To maintain a low-noise environment, the MAX1069 provides separate analog and digital power-supply inputs. The analog circuitry requires a +5V supply and consumes only 900µA at sampling rates up to 58.6ksps. The digital supply voltage accepts voltages

from +2.7V to +5.5V to ensure compatibility with low-voltage ASICs. The MAX1069 wakes up in shutdown mode when power is applied irrespective of the VAVDD and VDVDD sequence.

#### Analog Input and Track/Hold

The MAX1069 analog input contains a track-and-hold (T/H) capacitor, T/H switches, comparator, and a switched capacitor digital-to-analog converter (DAC) (Figure 5).

As shown in Figure 11c, the MAX1069 acquisition period is the two clock cycles prior to the conversion period. The T/H switches are normally in the hold position. During the acquisition period the T/H switches are in the track position and  $C_{T/H}$  charges to the analog input signal. Before a conversion begins, the T/H switches move to the hold position retaining the charge on  $C_{T/H}$  as a sample of the analog input signal.

During the conversion interval, the switched capacitive DAC adjusts to restore the comparator input voltage to zero within the limits of 14-bit resolution. This is equivalent to transferring a charge of 35pF  $\times$  (VaIN - VagNDS) from CT/H to the binary-weighted capacitive DAC,

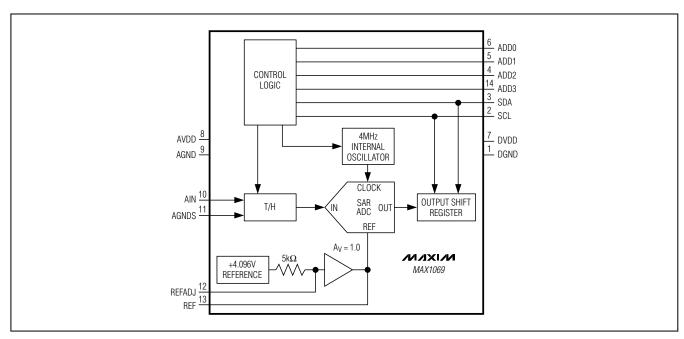


Figure 3. MAX1069 Simplified Functional Diagram

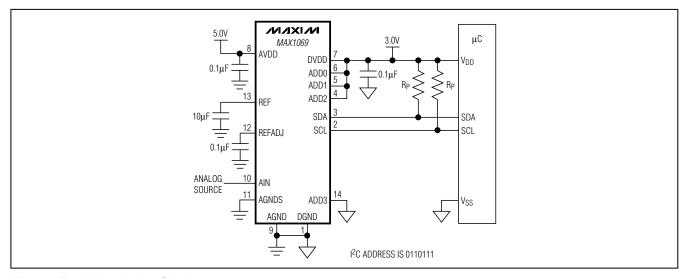


Figure 4. Typical Application Circuit

forming a digital representation of the analog input signal. During the conversion period, the MAX1069 holds SCL low (clock stretching).

The time required for the T/H to acquire an input signal is a function of the analog input source impedance. If the input signal source impedance is high, lengthen the

acquisition time by reducing f<sub>SCL</sub>. The MAX1069 provides two SCL cycles (t<sub>ACQ</sub>), in which the track-and-hold capacitance must acquire a charge representing the input signal. Minimize the input source impedance (RSOURCE) to allow the track-and-hold capacitance to charge within the allotted time. RSOURCE should be less than 12.9k $\Omega$  for f<sub>SCL</sub> = 400kHz and less than 2.4k $\Omega$ 

for fSCL = 1.7MHz. RSOURCE is calculated with the following equation:

$$R_{SOURCE} \le \frac{2}{f_{SCI} \times In(2 \times 2^N) \times C_{IN}} - R_{IN}$$

where RSOURCE is the analog input source impedance, fSCL is the maximum system SCL frequency, N is 14 (the number of bits of resolution), CIN is 35pF (the sum of CT/H and input stray capacitance), and RIN is  $800\Omega$  (the T/H switch resistances).

To improve the input-signal bandwidth under AC conditions, drive AIN with a wideband buffer (> 4MHz) that can drive the ADC's input capacitance and settle quickly (see the *Input Buffer* section).

An RC filter at AIN reduces the input track-and-hold switching transient by providing charge for CT/H.

#### **Analog Input Bandwidth**

The MAX1069 features input-tracking circuitry with a 4MHz small-signal bandwidth. The 4MHz input bandwidth makes it possible to digitize high-speed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. Use anti-alias filtering to avoid high-frequency signals being aliased into the frequency band of interest.

#### **Analog Input Range and Protection**

Internal ESD (electrostatic discharge) protection diodes clamp AIN, REF, and REFADJ to AVDD and AGNDS/AGND (Figure 6). These diodes allow the analog inputs to swing from (VAGND - 0.3V) to (VAVDD + 0.3V) without causing damage to the device. For accurate conversions, the inputs must not go more than 50mV beyond their rails.

If the analog inputs exceed 300mV beyond their rails, limit the current to 2mA.

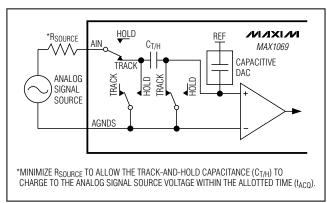


Figure 5. Equivalent Input Circuit

#### Internal Clock

The MAX1069 contains an internal 4MHz oscillator that drives the SAR conversion clock. During conversion, SCL is held low (clock stretching). An internal register stores data when the conversion is in progress. When the MAX1069 releases SCL, the master reads the conversion results at any clock rate up to 1.7MHz (Figure 11).

#### **Digital Interface**

The MAX1069 features an I<sup>2</sup>C-compatible, 2-wire serial interface consisting of a bidirectional serial data line (SDA) and a serial clock line (SCL). SDA and SCL facilitate bidirectional communication between the MAX1069 and the master at rates up to 1.7MHz. The master (typically a microcontroller) initiates data transfer on the bus and generates SCL.

SDA and SCL require pullup resistors ( $500\Omega$  or greater, Figure 4). Optional resistors ( $24\Omega$ ) in series with SDA and SCL protect the device inputs from high-voltage spikes on the bus lines. Series resistors also minimize crosstalk and undershoot of the bus signals.

#### Bit Transfer

One data bit is transferred during each SCL clock cycle. Nine clock cycles are required to transfer the data into or out of the MAX1069. The data on SDA must remain stable during the high period of the SCL clock pulse as changes in SDA while SCL is high are control signals (see the *START and STOP Conditions* section). Both SDA and SCL idle high.

#### START and STOP Conditions

The master initiates a transmission with a START condition (S), a high-to-low transition on SDA with SCL high. The master terminates a transmission with a STOP condition (P), a low-to-high transition on SDA while SCL is high (Figure 7). The STOP condition frees the bus and places all devices in F/S mode (see the *Bus Timing* section). Use a repeated START condition (Sr) in place

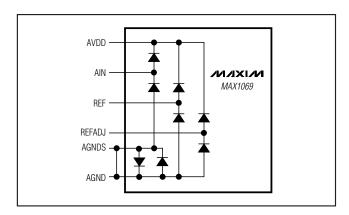


Figure 6. Internal Protection Diodes

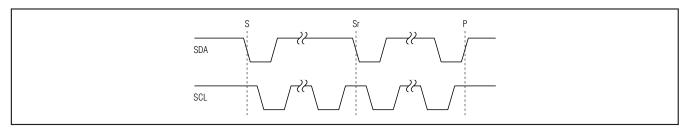


Figure 7. START and STOP Conditions

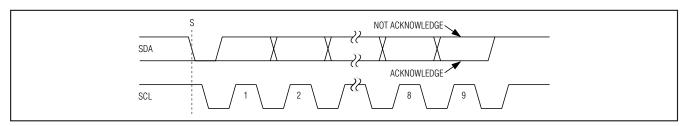


Figure 8. Acknowledge Bits

of a STOP condition to leave the bus active and in its current timing mode (see the *HS-Mode* section).

#### Acknowledge Bits

Successful data transfers are acknowledged with an acknowledge bit (A) or a not-acknowledge bit ( $\overline{A}$ ). Both the master and the MAX1069 (slave) generate acknowledge bits. To generate an acknowledge, the receiving device must pull SDA low before the rising edge of the acknowledge-related clock pulse (ninth pulse) and keep it low during the high period of the clock pulse (Figure 8). To generate a not acknowledge, the receiver allows SDA to be pulled high before the rising edge of the acknowledge-related clock pulse and leaves it high during the high period of the clock pulse.

Monitoring the acknowledge bits allows for detection of unsuccessful data transfers. An unsuccessful data transfer happens if a receiving device is busy or if a system fault has occurred. In the event of an unsuccessful data transfer, the master should reattempt communication at a later time.

#### Slave Address

A master initiates communication with a slave device by issuing a START condition followed by a slave address byte. As shown in Figure 9, the slave address byte consists of 7 address bits and a read/write bit (R/W). When idle, the MAX1069 continuously waits for a START condition followed by its slave address. When the MAX1069 recognizes its slave address, it acquires the analog input signal and prepares for conversion. The

first three bits (MSBs) of the slave address have been factory programmed and are always **011**. Connecting ADD3–ADD0 to DVDD or DGND, programs the last four bits (LSBs) of the slave address high or low.

Since the MAX1069 does not require setup or configuration, the least significant bit (LSB) of the address byte ( $R\overline{W}$ ) controls power-down. In external reference mode (REFADJ = AVDD),  $R\overline{W}$  is a don't care. In internal reference mode, setting  $R\overline{W} = 1$  places the device in normal operation and setting  $R\overline{W} = 0$  powers down the internal reference following the conversion (see the *Internal Reference Shutdown* section).

After receiving the address, the MAX1069 (slave) issues an acknowledge by pulling SDA low for one clock cycle.

#### **Bus Timing**

At power-up, the MAX1069 bus timing defaults to fast mode (F/S-mode), allowing conversion rates up to 19ksps. The MAX1069 must operate in high-speed mode (HS-mode) to achieve conversion rates up to 58.6ksps. Figure 1 shows the bus timing for the MAX1069 2-wire interface.

#### **HS-Mode**

At power-up, the MAX1069 bus timing is set for F/S-mode. The master selects HS-mode by addressing all devices on the bus with the HS-mode master code 0000 1XXX (X = don't care). After successfully receiving the HS-mode master code, the MAX1069 issues a not acknowledge allowing SDA to be pulled high for one

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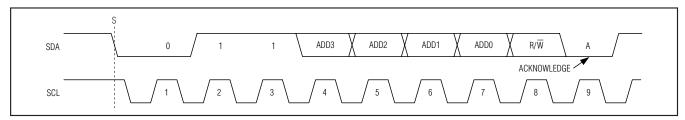


Figure 9. MAX1069 Slave Address Byte

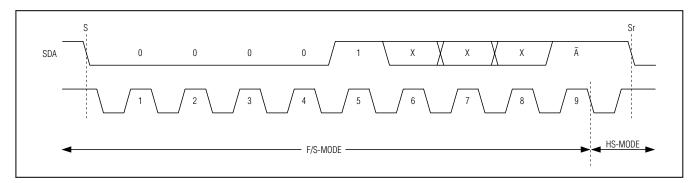


Figure 10. F/S-Mode to HS-Mode Transfer

clock cycle (Figure 10). After the not acknowledge, the MAX1069 is in HS-mode. The master must then send a repeated START followed by a slave address to initiate HS-mode communication. If the master generates a STOP condition, the MAX1069 returns to F/S-mode.

#### Data Byte (Read Cycle)

Initiate a read cycle to begin a conversion. A read cycle begins with the master issuing a START condition followed by seven address bits and a read bit (R/W). The standard I<sup>2</sup>C-compatible interface requires that  $R/\overline{W}=1$  to read from a device, however, since the MAX1069 does not require setup or configuration, the read mode is inherent and R/W controls power-down (see the *Internal Reference Shutdown* section). If the address byte is successfully received, the MAX1069 (slave) issues an acknowledge and begins conversion.

As seen in Figure 11, the MAX1069 holds SCL low during conversion. When the conversion is complete, SCL is released and the master can clock data out of the device. The most significant byte of the conversion is available first and contains D13 to D6. The least significant byte contains D5 to D0 plus two trailing sub bits S1 and S0. Data can be continuously converted as long as the master acknowledges the conversion results. Issuing a not acknowledge frees the bus allowing the master to generate a STOP or repeated START.

### **Applications Information**

#### **Power-On Reset**

When power is first applied, internal power-on reset circuitry activates the MAX1069 in shutdown. When the internal reference is used, allow 12ms for the reference to settle when  $C_{REF} = 10 \mu F$  and  $C_{REFADJ} = 0.1 \mu F$ .

#### **Automatic Shutdown**

The MAX1069 automatic shutdown reduces the supply current to less than 0.6µA between conversions. The MAX1069 I<sup>2</sup>C-compatible interface is always active. When the MAX1069 receives a valid slave address the device powers up. The device is then powered down again when the conversion is complete. The automatic shutdown function does not change with internal or external reference. When the internal reference is chosen, the internal reference remains active between conversions unless internal reference shutdown is requested (see the *Internal Reference Shutdown* section).

#### **Internal Reference Shutdown**

The R/ $\overline{W}$  bit of the slave address controls the MAX1069 internal reference shutdown. In external reference mode (REFADJ = AVDD), R/ $\overline{W}$  is a don't care. In internal reference mode, setting R/ $\overline{W}$  = 1 places the device in normal operation and setting R/ $\overline{W}$  = 0 prepares the internal reference for shutdown.

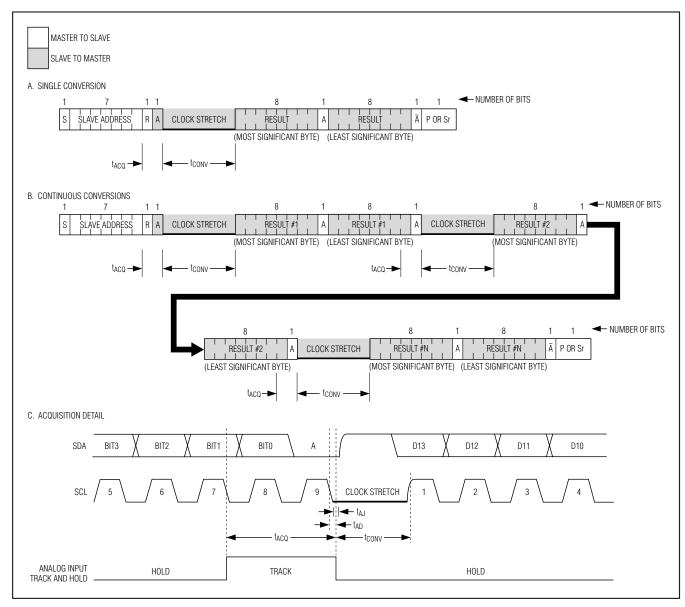


Figure 11. Read Cycle

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If the internal reference is used and  $R\overline{W}=0,$  shutdown occurs when the master issues a not-acknowledge bit while reading the conversion results. The internal reference and internal reference buffer are disabled during shutdown, reducing the analog supply current to less than  $1\mu A.$ 

A dummy conversion is required to power up the internal reference. The MAX1069 internal reference begins powering up from shutdown on the 9th falling edge of a

valid address byte. Allow 12ms for the internal reference to settle before obtaining valid conversion results.

#### Reference Voltage

The MAX1069 provides an internal or accepts an external reference voltage. The ADC input range is from VAGNDS to VREF (see the *Transfer Function* section).

#### Internal Reference

The MAX1069 contains an internal 4.096V bandgap reference. This bandgap reference is connected to REFADJ through a  $5k\Omega$  resistor. Bypass REFADJ with a 0.1 $\mu$ F capacitor to AGND. The MAX1069 reference buffer has a unity gain to provide +4.096V at REF. Bypass REF with a 10 $\mu$ F capacitor to AGND when the internal reference is used (Figure 12).

The internal reference is adjustable to  $\pm 1.5\%$  using the Figure 13 circuit.

#### External Reference

For external reference operation, disable the internal reference by connecting REFADJ to AVDD. During conversion, an external reference at REF must deliver up to  $100\mu A$  of DC load current and have an output impedance of less than  $10\Omega$ .

For optimal performance, buffer the reference through an op amp and bypass REF with a  $10\mu\text{F}$  capacitor. Consider the MAX1069's equivalent input noise ( $80\mu\text{V}_{RMS}$ ) when choosing a reference.

#### **Transfer Function**

The MAX1069 has a standard unipolar transfer function with a valid analog input voltage range from  $V_{AGNDS}$  to  $V_{REF}$ . Output data coding is binary with 1LSB =  $(V_{REF}/2^N)$  where 'N' is the number of bits (14). Code transitions occur halfway between successive-integer

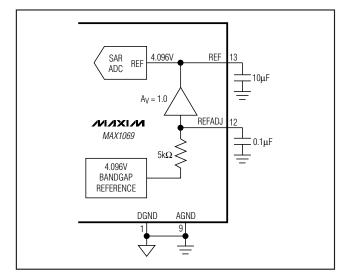


Figure 12. Internal Reference

LSB values. Figure 14 shows the MAX1069 input/output (I/O) transfer function.

### **Input Buffer**

Most applications require an input buffer amplifier to achieve 14-bit accuracy. If the input signal is multiplexed, the input channel should be switched immediately after acquisition, rather than near the end of or

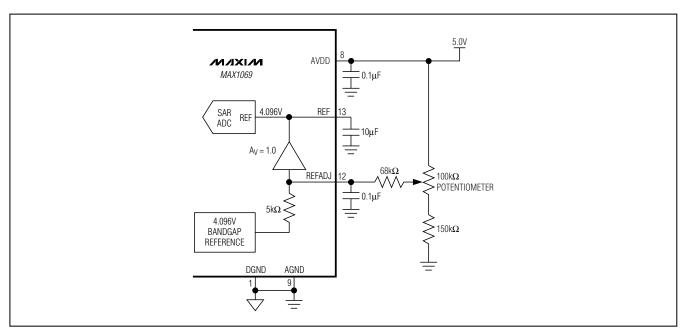


Figure 13. Adjusting the Internal Reference

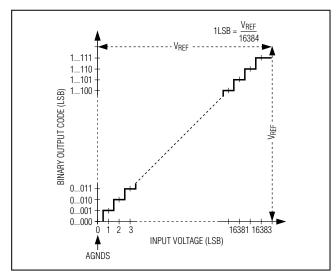


Figure 14. Unipolar Transfer Function

after a conversion. This allows more time for the input buffer amplifier to respond to a large step-change in input signal. The input amplifier must have a high enough slew rate to complete the required output voltage change before the beginning of the acquisition time. At the beginning of acquisition, the internal sampling capacitor array connects to AIN (the amplifier output), causing some output disturbance.

Ensure that the sampled voltage has settled to within the required limits before the end of the acquisition time. If the frequency of interest is low, AIN can be bypassed with a large enough capacitor to charge the internal sampling capacitor with very little ripple. However, for AC use, AIN must be driven by a wideband buffer (at least 4MHz), which must be stable with the ADC's capacitive load (in parallel with any AIN bypass capacitor used) and also settle quickly. Refer to Maxim's website at www.maxim-ic.com for application notes on how to choose the optimum buffer amplifier for your ADC application.

#### Layout, Grounding, and Bypassing

Careful printed circuit (PC) layout is essential for the best system performance. Boards should have separate analog and digital ground planes and ensure that digital and analog signals are separated from each other. Do not run analog and digital (especially clock) lines parallel to one another, or digital lines underneath the device package.

Figure 4 shows the recommended system ground connections. Establish an analog ground point at AGND and a digital ground point at DGND. Connect all analog

grounds to the star analog ground. Connect the digital grounds to the star digital ground. Connect the digital ground plane to the analog ground plane at one point. For lowest-noise operation, make the ground return to the star ground's power-supply low impedance and make it as short as possible.

High-frequency noise in the AVDD power supply degrades the ADC's high-speed comparator performance. Bypass AVDD to AGND with a 0.1µF ceramic surface-mount capacitor. Make bypass capacitor connections as short as possible. If the power supply is very noisy, connect a  $10\Omega$  resistor in series with AVDD and a  $4.7\mu\text{F}$  capacitor from AVDD to AGND to create a lowpass RC filter.

#### **Definitions**

#### **Integral Nonlinearity**

Integral nonlinearity (INL) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit or a line drawn between the end points of the transfer function once offset and gain errors have been nullified. The MAX1069 INL is measured using the endpoint method.

#### **Differential Nonlinearity**

Differential nonlinearity (DNL) is the difference between an actual step width and the ideal value of 1LSB. A DNL error specification of less than 1LSB guarantees no missing codes and a monotonic transfer function.

#### **Aperture Jitter**

Aperture jitter  $(t_{AJ})$  is the sample-to-sample variation in the time between the samples (Figure 11).

#### **Aperture Delay**

Aperture delay (t<sub>AD</sub>) is the time from the falling edge of SCL to the instant when an actual sample is taken (Figure 11).

#### Signal-to-Noise Ratio

For a waveform perfectly reconstructed from digital samples, signal-to-noise ratio (SNR) is the ratio of full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

$$SNR = ((6.02 \times N) + 1.76)dB$$

In reality, noise sources besides quantization noise exist, including thermal noise, reference noise, clock jitter, etc. Therefore, SNR is computed by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first five harmonics, and the DC offset.

#### Signal-to-Noise Plus Distortion

Signal-to-noise plus distortion (SINAD) is the ratio of the fundamental input frequency's RMS amplitude to RMS equivalent of all other ADC output signals.

$$SINAD(db) = 20 \times log \left( \frac{Signal_{RMS}}{Noise_{RMS}} \right)$$

#### **Effective Number of Bits**

Effective number of bits (ENOB) indicates the global accuracy of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. With an input range equal to the ADC's full-scale range, calculate the ENOB as follows:

$$ENOB = \left(\frac{SINAD - 1.76}{6.02}\right)$$

#### **Total Harmonic Distortion**

Total harmonic distortion (THD) is the RMS sum ratio of the input signal's first five harmonics to the fundamental itself, expressed as:

THD = 
$$20 \times \log \left( \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2}}{V_1} \right)$$

where  $V_1$  is the fundamental amplitude, and  $V_2$  through  $V_5$  are the amplitudes of the 2nd- through 5th-order harmonics.

#### Spurious-Free Dynamic Range

Spurious-free dynamic range (SFDR) is the ratio of RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest distortion component.

**Chip Information** 

PROCESS: BiCMOS

### \_Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
14 TSSOP	U14+1	21-0066	90-0113

### **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	10/02	Initial release	_
1	11/09	Remove the grade C devices from the <i>Ordering Information</i> and <i>Electrical Characteristics</i> tables	
2	12/10	Add lead-free, remove 0 to +70 temp range parts, update pin names for AVDD and DVDD, style edits	1–15, 17–20

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