# 36V H-Bridge Transformer Driver for Isolated Supplies 

## General Description

The MAX13256 H-bridge transformer driver provides a simple solution for making isolated power supplies up to 10W. The device drives a transformer's primary coil with up to 300 mA of current from a wide 8 V to 36 V DC supply. The transformer's secondary-to-primary winding ratio defines the output voltage, allowing selection of virtually any isolated output voltage.
The device features adjustable current limiting, allowing indirect limiting of secondary-side load currents. The current limit of the MAX13256 is set by an external resistor. A $\overline{\text { FAULT }}$ output asserts when the device detects an overtemperature or overcurrent condition. In addition, the device features a low-power mode to reduce the overall supply current to 0.65 mA (typ) when the driver is not in use.
The device can be operated using the internal oscillator or driven by an external clock to synchronize multiple MAX13256 devices and precisely set the switching frequency. Internal circuitry guarantees a fixed $50 \%$ duty cycle to prevent DC current flow through the transformer, regardless of which clock source is used.
The device is available in a small 10 -pin ( $3 \mathrm{~mm} \times 3 \mathrm{~mm}$ ) TDFN package and is specified over the $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ automotive temperature range.

Benefits and Features

\author{

- Simple, Flexible Design <br> $\diamond 8 \mathrm{~V}$ to 36 V Supply Range <br> $\diamond$ Up to 90\% Efficiency <br> $\triangleleft$ Provides Up to 10W to the Transformer <br> $\diamond$ Undervoltage Lockout <br> $\triangleleft 2.5 \mathrm{~V}$ to 5 V Compatible Logic Interface <br> $\diamond$ Internal or External Clock Source <br> $\diamond$ Adjustable Overcurrent Threshold <br> - Integrated System Protection <br> $\triangleleft$ Fault Detection and Indication <br> $\diamond$ Overcurrent Limiting <br> $\triangleleft$ Overtemperature Protection <br> - Saves Space on Board <br> $\diamond$ Small 10-Pin TDFN Package ( $3 \mathrm{~mm} \times 3 \mathrm{~mm}$ )
}

Applications

> Power Meters
> Isolated Fieldbus Interfaces
> $24 V$ PLC Supply Isolation
> Medical Equipment
> Motor Controls

## Ordering Information appears at end of data sheet.

Typical Operating Circuit


For related parts and recommended products to use with this part, refer to: www.maxim-ic.com/MAX13256.related
For pricing, delivery, and ordering information, please contact Maxim Direct

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## ABSOLUTE MAXIMUM RATINGS

(Voltages referenced to GND.)


TDFN (Single-Layer Board)
(derate $18.5 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )......................... 1481.5 mW
Operating Temperature Range ........................ $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
Junction Temperature ..................................................... $+150^{\circ} \mathrm{C}$
Storage Temperature Range............................ $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Lead Temperature (soldering, 10s) ............................... $+300^{\circ} \mathrm{C}$
Soldering Temperature (reflow) ...................................... $+260^{\circ} \mathrm{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## PACKAGE THERMAL CHARACTERISTICS (Note 1)

TDFN (Four-Layer Board)
Junction-to-Ambient Thermal Resistance ( $\theta_{\mathrm{JA}}$ ) .......... $41^{\circ} \mathrm{C} / \mathrm{W}$
Junction-to-Case Thermal Resistance ( $\theta_{\mathrm{JC}}$ ) $\qquad$ $.9^{\circ} \mathrm{C} / \mathrm{W}$

TDFN (Single-Layer Board)
Junction-to-Ambient Thermal Resistance ( $\theta_{\mathrm{JA}}$ ) .......... $54^{\circ} \mathrm{C} / \mathrm{W}$ Junction-to-Case Thermal Resistance ( $\theta_{\mathrm{JC}}$ ) .................. $9^{\circ} \mathrm{C} / \mathrm{W}$

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7. For detailed information on package thermal considerations, refer to www.maxim-ic.com/thermal-tutorial.

## ELECTRICAL CHARACTERISTICS

$\left(V_{D D}=8 \mathrm{~V}\right.$ to $36 \mathrm{~V}, \mathrm{~V}_{\overline{E N}}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DC CHARACTERISTICS |  |  |  |  |  |  |
| Supply Voltage Range | $V_{\text {DD }}$ | (Note 3) | 8 |  | 36 | V |
| Supply Current | IDD | $V_{\overline{E N}}=0 V, V_{C L K}=0 V, R_{\text {LIM }}=1000 \Omega,$ <br> ST1/ST2 not connected |  | 6 | 9 | mA |
| Disable Supply Current | IDIS | $V_{\text {EN }}=3.3 \mathrm{~V}, \mathrm{~V}_{\text {cLK }}=0 \mathrm{~V}$ |  | 0.65 | 1.1 | mA |
| Driver Output Resistance | $\mathrm{R}_{\mathrm{OH}}$ | $\begin{aligned} & \text { ST1 }=\text { ST2 }=\text { high, } \text { IST1, ST2 }=+300 \mathrm{~mA}, \\ & \mathrm{R}_{\text {LIM }}=1000 \Omega \end{aligned}$ |  | 1 | 1.5 | $\Omega$ |
|  | $\mathrm{R}_{\mathrm{OL}}$ | $\begin{aligned} & \text { ST1 }=\text { ST2 }=\text { low, IST1, ST2 }=-300 \mathrm{~mA}, \\ & R_{\text {LIM }}=1000 \Omega \end{aligned}$ |  | 0.6 | 1.0 |  |
| Undervoltage-Lockout Threshold | V UVLO | $\mathrm{V}_{\mathrm{DD}}$ rising | 5.9 | 6.3 | 6.9 | V |
| Undervoltage-Lockout Threshold Hysteresis | VUVLO_HYST |  |  | 300 |  | mV |

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## ELECTRICAL CHARACTERISTICS (continued)

$\left(\mathrm{V}_{\mathrm{DD}}=8 \mathrm{~V}\right.$ to $36 \mathrm{~V}, \mathrm{~V}_{\overline{E N}}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ST1, ST2 Current Limit | ILIM | $\mathrm{R}_{\text {LIM }}=1000 \Omega$ | 500 | 650 | 800 | mA |
|  |  | $\mathrm{R}_{\text {LIM }}=3010 \Omega$ | 165 | 215 | 265 |  |
| ST1, ST2 Leakage Current | ILKG | $\begin{aligned} & V_{\mathrm{EN}}=3.3 \mathrm{~V}, \mathrm{~V}_{\mathrm{CLK}}=0 \mathrm{~V}, \\ & \mathrm{~V}_{\mathrm{ST} 1}=\mathrm{V}_{\mathrm{ST} 2}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{DD}} \end{aligned}$ | -1 |  | +1 | $\mu \mathrm{A}$ |

## LOGIC SIGNALS (CLK, $\overline{E N}, \overline{\text { FAULT }})$

| Input Logic-High Voltage | $\mathrm{V}_{\mathrm{IH}}$ |  | 2 |  |  | V |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input Logic-Low Voltage | $\mathrm{V}_{\text {IL }}$ |  |  |  | 0.8 | V |
| Input Leakage Current | IIL | $\mathrm{V}_{\mathrm{CLK}}=\mathrm{V}_{\text {EN }}=5.5 \mathrm{~V}$ or 0 V | -1 |  | +1 | $\mu \mathrm{A}$ |
| FAULT Output Logic-Low Voltage | V OL | $\left.\right\|^{\text {FAULT }}=10 \mathrm{~mA}$ |  |  | 1 | V |
| $\overline{\text { FAULT Leakage Current }}$ | ILKGF | $V_{\overline{\text { FAULT }}}=36 \mathrm{~V}, \overline{\text { FAULT }}$ deasserted |  |  | 10 | $\mu \mathrm{A}$ |
| AC CHARACTERISTICS |  |  |  |  |  |  |
| Switching Frequency | $\mathrm{f}_{\text {SW }}$ | $\mathrm{V}_{\mathrm{CLK}}=0 \mathrm{~V}$, measured at ST1/ST2 outputs | 255 | 425 | 700 | kHz |
| CLK Input Frequency | ${ }_{\text {f EXT }}$ | External clocking | 200 |  | 2000 | kHz |
| ST1/ST2 Duty Cycle | DTC | Internal or external clocking | 49 | 50 | 51 | \% |
| ST1/ST2 Rise Time | $t_{\text {RISE }}$ | $\begin{aligned} & S_{1} 1 / \mathrm{ST} 2=20 \% \text { to } 80 \% \text { of } V_{D D}, R_{L}=1 \mathrm{k} \Omega \text {, } \\ & C_{L}=50 \mathrm{pF} \text {, Figure } 1 \mathrm{a} \end{aligned}$ |  |  | 100 | ns |
| ST1/ST2 Fall Time | $t_{\text {FALL }}$ | ST1/ST2 $=80 \%$ to $20 \%$ of $V_{D D}, R_{L}=1 \mathrm{k} \Omega$, $C_{L}=50 p F$, Figure 1a |  |  | 100 | ns |
| Crossover Dead Time | $t_{\text {DEAD }}$ | $R_{L}=200 \Omega$, Figure 1b |  | 30 |  | ns |
| Watchdog Timeout | ${ }^{\text {twDOG }}$ | (Note 4) | 20 | 32 | 55 | $\mu \mathrm{s}$ |
| Current-Limit Blanking Time | $t_{\text {BLANK }}$ | Figure 2 | 0.73 | 1.2 | 2.0 | ms |
| Current-Limit Autoretry Time | $t_{\text {RETRY }}$ | Figure 2 | 23.4 | 38.4 | 64.0 | ms |
| PROTECTION |  |  |  |  |  |  |
| Thermal-Shutdown Threshold | TSHDN |  |  | +160 |  | ${ }^{\circ} \mathrm{C}$ |
| Thermal-Shutdown Hysteresis | TSHDN_HYS |  |  | 10 |  | ${ }^{\circ} \mathrm{C}$ |

Note 2: All units are production tested at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$. Specifications over temperature are guaranteed by design.
Note 3: If $V_{D D}$ is greater than 27 V , see the Snubber section.
Note 4: See the Watchdog section.

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Test Circuits/Timing Diagrams


Figure 1. Test Circuits (A and B) and Timing Diagram (C) for Rise, Fall, and Dead Times


Figure 2. Timing Diagram for Current Limiting

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Typical Operating Characteristics
$\left(\mathrm{V}_{\mathrm{DD}}=24 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted. $)$


FAULT OUTPUT-VOLTAGE LOW
vs. SINK CURRENT



ST1/ST2 OUTPUT-VOLTAGE HIGH vs. SOURCE CURRENT


ISOLATED OUTPUT VOLTAGE
vs. LOAD CURRENT


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## Typical Operating Characteristics (continued)

$\left(\mathrm{V}_{\mathrm{DD}}=24 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted.)


MAXIMUM OUTPUT CURRENT
vs. TEMPERATURE



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*EXPOSED PAD—CONNECT TO GND

Pin Description

| PIN | NAME | FUNCTION |
| :---: | :---: | :--- |
| 1,2 | $V_{D D}$ | Power Supply. Bypass V$V_{D D}$ to ground with a 1 $\mu$ F capacitor as close as possible to the device. |
| 3 | CLK | Clock Input. Connect CLK to GND to enable internal clocking. Apply a clock signal to CLK to enable exter- <br> nal clocking. |
| 4 | $\overline{\mathrm{EN}}$ | Enable Input. Drive $\overline{\mathrm{EN}}$ low to enable the device. Drive $\overline{\mathrm{EN}}$ high to disable the device. |
| 5 | ITH | Overcurrent Threshold Adjustment Input. Connect a resistor (RLIM) from ITH to GND to set the overcurrent <br> threshold for the ST1 and ST2 outputs. Do not exceed 10pF of capacitance to GND on ITH. |
| 6 | $\overline{\text { FAULT }}$ | Fault Open-Drain Output. The fault open-drain transistor turns on when there is either an overtemperature or <br> overcurrent condition. |
| 7,9 | GND | Ground |
| 8 | ST2 | Transformer Drive Output 2 |
| 10 | ST1 | Transformer Drive Output 1 |
| - | EP | Exposed Pad. Internally connected to GND. Connect EP to a large ground plane to maximize thermal perfor- <br> mance; not intended as an electrical connection point. |

# 36V H-Bridge Transformer Driver for Isolated Supplies 

Functional Diagram


## Detailed Description

The MAX13256 is an integrated primary-side controller and H -bridge driver for isolated power-supply circuits. The device contains an on-board oscillator, protection circuitry, and internal MOSFETs to provide up to 300 mA of current to the primary winding of a transformer. The device can be operated using the internal oscillator or driven by an external clock to synchronize multiple MAX13256 devices and control EMI behavior. Regardless of the clock source being used, an internal flip-flop stage guarantees a fixed $50 \%$ duty cycle to prevent DC current flow in the transformer as long as the period of the clock is constant.
The device operates from a wide single-supply voltage of 8 V to 36 V , and includes undervoltage lockout for controlled startup. The device features break-before-make
switching to prevent cross conduction of the H -bridge MOSFETs. An external resistor sets an overcurrent limit, allowing primary-side limiting of load currents on the transformer's secondary side. Thermal-shutdown circuitry provides additional protection against excessive power dissipation.

Isolated Power Supply
The MAX13256 allows a versatile range of secondaryside rectification circuits (see Figure 3). The primary-tosecondary transformer winding ratio can be chosen to adjust the isolated output voltage. The device delivers up to 300 mA of current to the transformer with a supply up to +36 V .
The MAX13256 provides the advantages of the H -bridge converter topology, including multiple isolated outputs, step-up/step-down or inverted output, relaxed filtering requirements, and low output ripple.

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#### Abstract

Clock Source Either the internal oscillator or an external clock provides the switching signal for the MAX13256. Connect CLK to ground to select the internal oscillator. Provide a clock signal to CLK to automatically select external clocking.


Internal Oscillator Mode The MAX13256 includes an internal oscillator that drives the H -bridge when a watchdog timeout is detected on CLK. The outputs switch at 425 kHz (typ) with a guaranteed $50 \%$ duty cycle in the internal oscillator mode.

## External Clock Mode

The MAX13256 provides an external clock mode. When an external clock source is applied to CLK, the external clock drives the H-bridge. An internal flip-flop divides the external clock by two in order to generate a switching signal with a guaranteed $50 \%$ duty cycle. As a result, the device outputs switch at one-half of the external clock frequency. The device switches on the rising edge of the external clock signal.

## Watchdog

A stalled clock could cause excessive DC current to flow through the primary winding of the transformer. The MAX13256 features an internal watchdog circuit to prevent damage from this condition. The internal oscillator provides the switching signal to the H-bridge whenever the period between edges on CLK exceeds the watchdog timeout period of $20 \mu \mathrm{~s}(\mathrm{~min})$.

Transients on ST1/ST2 During tDEAD
When the MAX13256 switches, there is a period of time when both ST1 and ST2 are high impedance to ensure that there are no shoot-through currents in the H -bridge. During this dead time, the voltage at these pins may temporarily exceed the absolute maximum ratings due to the inductive load presented by the transformer. This transient voltage will not damage the device.

## Disable Mode

The MAX13256 provides a disable mode to reduce current consumption. The ST1 and ST2 outputs are high impedance in disable mode.

Power-Up and Undervoltage Lockout
The MAX13256 provides an undervoltage-lockout feature to both ensure a controlled power-up state and prevent operation before the oscillator has stabilized. On powerup and during normal operation if the supply voltage drops below VUVLO, the undervoltage-lockout circuit forces the device into disable mode. The ST1 and ST2 outputs are high impedance in disable mode.

## Overcurrent Limiting

The MAX13256 limits the ST1/ST2 output current. Connect an external resistor ( $\mathrm{R}_{\mathrm{LIM}}$ ) to ITH to set the current limit. When the current reaches the limit for longer than the blanking time of 1.2 ms (typ), the drivers are disabled and FAULT is asserted low. The drivers are reenabled after the autoretry time of 38.4 ms (typ). If a continuous fault condition is present, the duty cycle of the fault current is approximately $3 \%$.
To set the current-limit threshold, use the following equation:

$$
R_{\mathrm{LIM}}(\mathrm{k} \Omega)=\frac{650}{\mathrm{ILIM}^{(\mathrm{mA})}}
$$

where LIIM $_{\text {Lis }}$ the desired current threshold in the range of $215 \mathrm{~mA}<\mathrm{l}$ LIM $<650 \mathrm{~mA}$ (typ). For example, a $1 \mathrm{k} \Omega$ resistor sets the current limit to 650 mA . Use a $1 \%$ resistor for $R_{\text {LIM }}$ for increased accuracy.
Ensure that the overcurrent threshold is set to at least twice the expected maximum operating current. For an expected maximum operating current of 300 mA , set the ILIM to 650 mA . For an expected operating current of 100 mA , set the $\mathrm{I}_{\text {LIM }}$ to 215 mA .

FAULT Output
The $\overline{\text { FAULT }}$ output is asserted low whenever the device is disabled due to a fault condition. $\overline{\mathrm{FAULT}}$ is automatically deasserted when the device is enabled after the autoretry time following an overcurrent fault, resulting in FAULT toggling during a continuous overcurrent condition. $\overline{\text { FAULT }}$ is asserted for the entire duration of an overtemperature fault. $\overline{F A U L T}$ is an open-drain output.

## Thermal Shutdown

The MAX13256 is protected from overtemperature damage by a thermal-shutdown circuit. When the junction temperature $\left(\mathrm{T}_{\mathrm{J}}\right)$ exceeds $+160^{\circ} \mathrm{C}$, the device is disabled and $\overline{\mathrm{FAULT}}$ is asserted low. $\overline{\mathrm{FAULT}}$ stays low for the duration of an overtemperature fault. The device resumes normal operation when $T_{J}$ falls below $+150^{\circ} \mathrm{C}$.

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Figure 3. Secondary-Side Rectification Topologies


Figure 4. Output Snubber


## Applications Information

## Snubber

For $V_{D D}$ greater than 27 V , use a simple RC snubber circuit on ST1 and ST2 to ensure that the peak voltage is less than 40V during switching (Figure 4). Recommended values for the snubber are $R=91 \Omega$ and $C=330 \mathrm{pF}$.

Power Dissipation
The power dissipation of the device is approximated by:

$$
\mathrm{P}_{\mathrm{D}}=\left(\mathrm{R}_{\mathrm{OHL}} \times \mathrm{I}_{\mathrm{PRI}}{ }^{2}\right)+\left(\mathrm{I}_{\mathrm{DD}} \times \mathrm{V}_{\mathrm{DD}}\right)
$$

where $\mathrm{R}_{\mathrm{OHL}}$ is the combined high-side and low-side onresistance of the internal FET drivers, and IPRI is the load current flowing through ST1 and ST2.

## High-Temperature Operation

When the MAX13256 is operated under high ambient temperatures, the power dissipated in the package can raise the junction temperature close to thermal shutdown. Under such temperature conditions, the power dissipation should be held low enough so that that junction temperature observes a factor of safety margin. The maximum junction temperature should be held below $+140^{\circ} \mathrm{C}$. Use the package's thermal resistances to calculate the junction temperature. Alternatively use the Maximum Output Current vs. Temperature curves shown in the Typical Operating Characteristics section to determine the maximum ST1/ST2 load currents.

## Hot Insertion

If the MAX13256 is inserted into a live backplane, it is possible to damage the device. Damage is caused by overshoot on $\mathrm{V}_{\mathrm{DD}}$ exceeding the absolute maximum rating. Limit the transient input voltage to the MAX13256 with an external protection device.

## Output-Ripple Filtering

Output-voltage ripple can be reduced with a lowpass LC filter (see Figure 5). The component values shown give a cutoff frequency of 21.5 kHz by the equation:

$$
f_{3 \mathrm{~dB}}=\frac{1}{2 \pi \sqrt{\mathrm{LC}}}
$$

Use an inductor with low DC resistance and sufficient saturation current rating to minimize filter power dissipation.

Power-Supply Decoupling
Bypass $V_{D D}$ to ground with a $1 \mu F$ ceramic capacitor as close as possible to the device.

Figure 5. Output Ripple Filtering

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## Output-Voltage Regulation

For many applications, the unregulated output of the MAX13256 meets the output-voltage tolerances. This configuration represents the highest efficiency possible with the device.
For applications requiring a regulated output voltage, Maxim provides several solutions. In the following examples, assume a tolerance of $\pm 10 \%$ for the input voltage.
When the load currents on the transformer's secondary side are low, the output voltage can strongly increase. If operation under low load currents is expected, outputvoltage limiting should be used to keep the voltage within the tolerance range of the subsequent circuitry. If the minimum output load current is less than approximately 5 mA ,
connect a zener diode from the output node to ground as shown in Figure 6 to limit the output voltage to a safe value.

Example 1: $\mathbf{+ 2 4 V}$ to Isolated, Regulated $+\mathbf{3 . 3 V}$
In Figure 6, the MAX13256 feeds approximately +4.4 V to the input of an LDO through a TGMR-502V6LF 4:1 transformer and 4-diode bridge rectifier (see Figure 3C). From this, a MAX604 LDO produces a regulated +3.3 V output at up to 500 mA .

Example 2: $\mathbf{+ 2 4 V}$ to Isolated, Regulated $+\mathbf{1 2 V}$ In the circuit of Figure 7, the MAX13256 feeds approximately +14.2 V through a 1.5:1 transformer and a 4-diode bridge rectifier (see Figure 3C). From this, a MAX1659 LDO produces a regulated +12 V output at up to 350 mA .


Figure 6. +24 V to Isolated, Regulated +3.3 V


Figure 7. +24 V to Isolated, Regulated +12 V

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Example 3: $\mathbf{+ 2 4 V}$ to Isolated, Regulated $\pm 15 \mathrm{~V}$
In Figure 8, the MAX13256 is used with a 1:1.5 center tapped transformer and a 4-diode bridge rectifier network (see Figure 3C) to supply $\pm 17.1 \mathrm{~V}$ to a MAX8719 LDO and a 7915 LDO. The circuit produces regulated $\pm 15 \mathrm{~V}$ outputs at up to 100 mA .

Isolated DAC/ADC Interface for Industrial Process Control
The MAX13256 provides isolated power for data converters in industrial process control applications (see Figure 9). The 300 mA output current capability allows for multiple data converters operating across an isolation barrier. The power output capability also supports circuitry for signal conditioning and multiplexing.


Figure 8. +24 V to Isolated, Regulated $\pm 15 \mathrm{~V}$

MAX13256

## 36V H-Bridge Transformer Driver for Isolated Supplies



Figure 9. Isolated Power Supply for Industrial Control Applications

# 36V H-Bridge Transformer Driver for Isolated Supplies 


#### Abstract

Isolated RS-485/RS-232 Data Interfaces The MAX13256 provides power for multiple transceivers in isolated RS-485/RS-232 data interface applications. The 300 mA output current capability of the MAX13256 allows multiple RS-485/RS-232 transceivers to operate simultaneously.


PCB Layout Guidelines As with all power-supply circuits, careful $\operatorname{PCB}$ layout is important to achieve low switching losses and stable operation. For thermal performance, connect the exposed pad to a solid copper ground plane.
The traces from ST1 and ST2 to the transformer must be low resistance and inductance paths. Place the transformer as close as possible to the MAX13256 using short, wide traces.
When the device is operating with the internal oscillator, it is possible for high-frequency switching components on ST1 and ST2 to couple into the CLK circuitry through PCB parasitic capacitance. This capacitive coupling can induce duty-cycle errors in the oscillator, resulting in a DC current through the transformer. To ensure proper operation, ensure that CLK has a solid ground connection.

## Exposed Pad

Ensure that the exposed pad has a solid connection to the ground plane for best thermal performance. Failure to provide a low thermal impedance path to the ground plane results in excessive junction temperatures when delivering maximum output power.

## Component Selection

## Transformer Selection

Transformer selection for the MAX13256 can be simplified by the use of a design metric, the ET product. The ET product relates the maximum allowable magnetic flux density in a transformer core to the voltage across a winding and switching period. Inductor magnetizing current in the primary winding changes linearly with time during the switching period of the device. Transformer manufacturers specify a minimum ET product for each transformer. The transformer's ET product must be larger than:

$$
E T=V_{D D} /(2 \times f s w)
$$

where f W is the minimum switching frequency of the ST1/ST2 outputs ( $255 \mathrm{kHz}(\mathrm{min})$ ) when the internal oscillator is used or one-half of the clock frequency when an external clock source is used.

Choose a transformer with sufficient ET product in the primary winding to ensure that the transformer does not saturate during operation. Saturation of the magnetic core results in significantly reduced inductance of the primary, and therefore a large increase in current flow. This can cause the current limit to be reached even when the load is not high.
For example, when the internal oscillator is used to drive the H -bridge, the required transformer ET product for an application with $\mathrm{V}_{\mathrm{DD}}(\max )=36 \mathrm{~V}$ is 70.6 V us. An application with $\mathrm{V}_{\mathrm{DD}}(\max )=8.8 \mathrm{~V}$ has a transformer ET product requirement of $17.3 \mathrm{~V} \mu \mathrm{~s}$.
In addition to the constraint on ET product, choose a transformer with a low DC-winding resistance. Power dissipation of the transformer due to the copper loss is approximated as:

$$
P_{D_{-} T X}=I_{L O A D}{ }^{2} \times\left(R_{P R I} / \mathrm{N}^{2}+R_{S E C}\right)
$$

where RPRI is the DC winding resistance of the primary, and $\mathrm{R}_{\text {SEC }}$ is the DC winding resistance of the secondary. In most cases, an optimum is reached when RSEC $=$ RPRI/ $\mathrm{N}^{2}$. For this condition, the power dissipation is equal for the primary and secondary windings.
As with all power-supply designs, it is important to optimize efficiency. In designs incorporating small transformers, the possibility of thermal runaway makes low transformer efficiencies problematic. Transformer losses produce a temperature rise that reduces the efficiency of the transformer. The lower efficiency, in turn, produces an even larger temperature rise.
To ensure that the transformer meets these requirements under all operating conditions, the design should focus on the worst-case conditions. The most stringent demands on ET product arise for minimum input voltage, switching frequency, and maximum temperature and load current. Additionally, the worst-case values for transformer and rectifier losses should be considered.
The primary should be a single winding; however, the secondary can be center-tapped, depending on the desired rectifier topology. In most applications, the phasing between primary and secondary windings is not significant. Half-wave rectification architectures are possible with the MAX13256; however, these are discouraged. If a net DC current results due to an imbalanced load, the average magnetic flux in the core is increased. This reduces the effective ET product and can lead to saturation of the transformer core.

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Transformers for use with the device are typically wound on a high-permeability magnetic core. To minimize radiated electromagnetic emissions, select a toroid, pot core, E/I/U core, or equivalent.

## Low-Voltage Operation

The MAX13256 can be operated from an +8V supply by decreasing the turns ratio of the transformer, or by designing a voltage doubler circuit as shown in Figure 3B.
Optimum performance at +8 V is obtained with fewer turns on the primary winding since the ET product requirement is lower than for $\mathrm{a}+24 \mathrm{~V}$ supply. However, any of the transformers for use with $\mathrm{a}+24 \mathrm{~V}$ supply can operate properly with $\mathrm{a}+8 \mathrm{~V}$ supply. For a given power level, the transformer currents are higher with a +8 V supply than with a +24 V supply. Therefore, the DC resistance of the transformer windings has a larger impact on the circuit efficiency.

## Diode Selection

The high switching speed of the MAX13256 necessitates high-speed rectifiers. Ordinary silicon signal diodes such as 1 N 914 or 1 N 4148 can be used for low-output current levels (less than 50mA.) But at higher output current levels, their reverse recovery times might degrade efficiency. At higher output currents, select low forwardvoltage Schottky diodes to improve efficiency. Ensure
that the average forward current rating for the rectifier diodes exceeds the maximum load current of the circuit. For surface-mount applications, Schottky diodes such as the BAT54, MBRS140, and MBRS340 are recommended.

Capacitor Selection
Input Bypass Capacitor
Bypass the supply pin to GND with a $1 \mu \mathrm{~F}$ ceramic capacitor as close as possible to the device. The equivalent series resistance (ESR) of the input capacitors is not as critical as for the output filter capacitors. Typically ceramic $X 7 \mathrm{R}$ capacitors are adequate.

Output Filter Capacitor
In most applications, the actual capacitance rating of the output filter capacitors is less critical than the capacitor's ESR. In applications sensitive to output-voltage ripple, the output filter capacitor must have low ESR. For optimal performance, the capacitance should meet or exceed the specified value over the entire operating temperature range. Capacitor ESR typically rises at low temperatures; however, OS-CON capacitors can be used at temperatures below $0^{\circ} \mathrm{C}$ to help reduce output-voltage ripple in sensitive applications. In applications where low outputvoltage ripple is not critical, standard ceramic $0.1 \mu \mathrm{~F}$ capacitors are sufficient.

Suggested External Component Manufacturers

## Table 1. Component Manufacturers

| MANUFACTURER | COMPONENT | WEBSITE |
| :--- | :---: | :--- |
| Central Semiconductor | Diodes | www.centralsemi.com |
| Halo Electronics | Transformers | www.haloelectronics.com |
| Kemet | Capacitors | www.kemet.com |
| Sanyo | Capacitors | www.sanyo.com |
| Taiyo Yuden | Capacitors | www.t-yuden.com |
| TDK | Capacitors | www.component.tdk.com |

## MAX13256

## 36V H-Bridge Transformer Driver for Isolated Supplies

## Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE |
| :---: | :---: | :--- |
| MAX13256ATB + | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 10 TDFN-EP* |

+ Denotes a lead(Pb)-free/RoHS-compliant package.
${ }^{*} E P=$ Exposed Pad

Chip Information
PROCESS: BiCMOS

## Package Information

For the latest package outline information and land patterns (footprints), go to www.maxim-ic.com/packages. Note that a "+", "\#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

| PACKAGE <br> TYPE | PACKAGE <br> CODE | OUTLINE <br> NO. | LAND <br> PATTERN NO. |
| :---: | :---: | :---: | :---: |
| 10 TDFN-EP | $\mathrm{T} 1033+1$ | $\underline{21-0137}$ | $\underline{90-0003}$ |

MAX13256

# 36V H-Bridge Transformer Driver for Isolated Supplies 

Revision History

| REVISION <br> NUMBER | REVISION <br> DATE | DESCRIPTION | PAGES <br> CHANGED |
| :---: | :---: | :--- | :---: | :---: |
| 0 | $6 / 11$ | Initial release | - |
| 1 | $8 / 11$ | Added Note 4 to Watchdog Timeout section in the Electrical Characteristics. <br> Updated text and formula in Overcurrent Limiting section. | 3,9 |

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integrated $_{\text {m }}$

[^0]
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[^0]:    Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time. The parametric values (min and max limits) shown in the Electrical Characteristics table are guaranteed. Other parametric values quoted in this data sheet are provided for guidance.

