

# 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Internal Synchronous Rectification in TQFN Package

## General Description

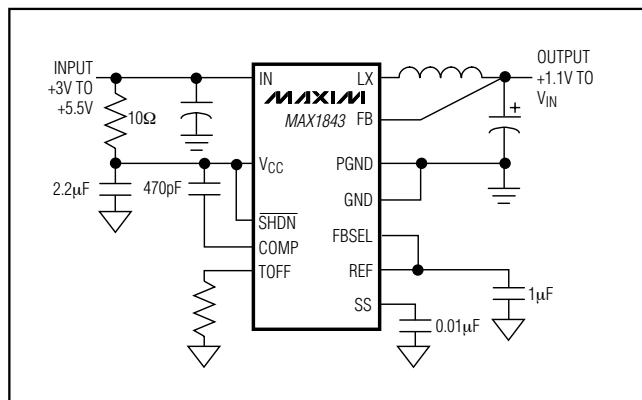
The MAX1843 constant-off-time, pulse-width modulated (PWM) step-down DC-DC converter is ideal for use in 5V and 3.3V to low-voltage conversion necessary in notebook and subnotebook computers. This device features an internal PMOS power switch and internal synchronous rectification for high efficiency and reduced component count. An external Schottky diode is not required. The internal 90mΩ power switch and 70mΩ nMOS synchronous-rectifier switch easily deliver continuous load currents up to 2.7A. The MAX1843 produces a preset +2.5V, +1.8V, or +1.5V output voltage or an adjustable output from +1.1V to  $V_{IN}$ . It achieves efficiencies as high as 95%.

The MAX1843 uses a unique current-mode, constant-off-time, PWM control scheme, which includes Idle Mode™ to maintain high efficiency during light-load operation. The programmable constant-off-time architecture sets switching frequencies up to 1MHz, allowing the user to optimize performance trade-offs between efficiency, output switching noise, component size, and cost. The MAX1843 features an adjustable soft-start to limit surge currents during startup, a 100% duty-cycle mode for low dropout operation, and a low-power shutdown mode that disconnects the input from the output and reduces supply current below 1μA. The MAX1843 is available in a 28-pin TQFN package with an exposed backside pad.

## Applications

5V or 3.3V to Low-Voltage Conversion  
CPU I/O Ring  
Chipset Supplies  
Notebook and Subnotebook Computers

## Typical Configuration



Idle Mode is a trademark of Maxim Integrated Products, Inc.

## Features

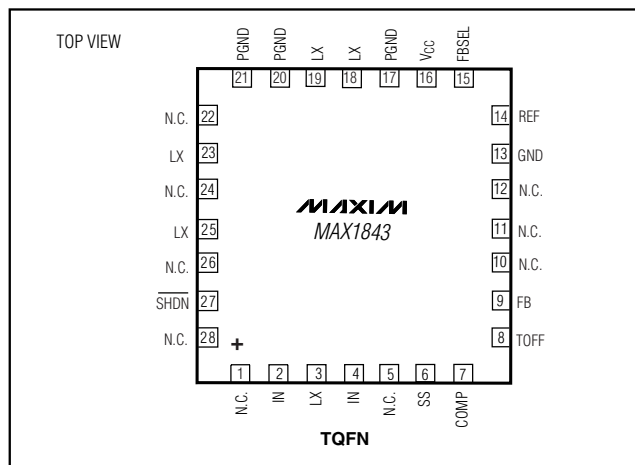
- ◆ ±1% Output Accuracy
- ◆ Up to 1MHz Switching Frequency
- ◆ 95% Efficiency
- ◆ Internal pMOS/nMOS Switches
  - 90mΩ/70mΩ On-Resistance at  $V_{IN} = +4.5V$
  - 110mΩ/80mΩ On-Resistance at  $V_{IN} = +3V$
- ◆ Output Voltage
  - +2.5V, +1.8V, or +1.5V Pin Selectable
  - +1.1V to  $V_{IN}$  Adjustable
- ◆ +3V to +5.5V Input Voltage Range
- ◆ 350μA Operating Supply Current
- ◆ < 1μA Shutdown Supply Current
- ◆ Programmable Constant-Off-Time Operation
- ◆ Idle Mode Operation at Light Loads
- ◆ Thermal Shutdown
- ◆ Adjustable Soft-Start Inrush Current Limiting
- ◆ 100% Duty Cycle During Low-Dropout Operation
- ◆ Output Short-Circuit Protection
- ◆ 28-Pin TQFN Package

## Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	PKG CODE
MAX1843ETI+	-40°C to +85°C	28 TQFN	T2855-6

+Denotes lead-free package.

## Pin Configuration



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### ABSOLUTE MAXIMUM RATINGS

V <sub>CC</sub> , IN to GND	-0.3V to +6V
IN to V <sub>CC</sub>	±0.3V
GND to PGND	±0.3V
All Other Pins to GND	-0.3V to (V <sub>CC</sub> + 0.3V)
LX Current (Note 1)	±4.7A
REF Short Circuit to GND Duration	Continuous
ESD Protection	±2kV

Continuous Power Dissipation (T <sub>A</sub> = +70°C)	
28-Pin TQFN (derate 20mW/°C above +70°C, part mounted on 1in <sup>2</sup> of 1oz copper)	1.6W
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range	-65°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C

**Note 1:** LX has internal clamp diodes to PGND and IN. Applications that forward bias these diodes should take care not to exceed the IC's package power dissipation limits.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### ELECTRICAL CHARACTERISTICS

(V<sub>IN</sub> = V<sub>CC</sub> = +3.3V, FBSEL = GND, T<sub>A</sub> = 0°C to +85°C, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)

PARAMETER	SYMBOL	CONDITIONS			MIN	TYP	MAX	UNITS
Input Voltage	V <sub>IN</sub> , V <sub>CC</sub>				3.0		5.5	V
Preset Output Voltage	V <sub>OUT</sub>	V <sub>IN</sub> = +3V to +5.5V	FBSEL = V <sub>CC</sub>	T <sub>A</sub> = +25°C to +85°C	2.500	2.525	2.550	V
				T <sub>A</sub> = 0°C to +85°C	2.487	2.525	2.563	
			FBSEL = unconnected	T <sub>A</sub> = +25°C to +85°C	1.500	1.515	1.530	
				T <sub>A</sub> = 0°C to +85°C	1.492	1.515	1.538	
		I <sub>LOAD</sub> = 0 to 2.5A	FBSEL = REF	T <sub>A</sub> = +25°C to +85°C	1.800	1.818	1.836	
				T <sub>A</sub> = 0°C to +85°C	1.791	1.818	1.845	
		V <sub>FB</sub> = V <sub>OUT</sub>	FBSEL = GND	T <sub>A</sub> = +25°C to +85°C	1.089	1.100	1.111	
				T <sub>A</sub> = 0°C to +85°C	1.084	1.100	1.117	
Adjustable Output Voltage Range		V <sub>IN</sub> = V <sub>CC</sub> = +3V to +5.5V, FBSEL = GND			V <sub>REF</sub>		V <sub>IN</sub>	V
AC-Load Regulation Error						2		%
DC-Load Regulation Error						0.4		%
Dropout Voltage	V <sub>DO</sub>	V <sub>IN</sub> = V <sub>CC</sub> = +3V, I <sub>LOAD</sub> = 1A					250	mV
Reference Voltage	V <sub>REF</sub>	T <sub>A</sub> = +25°C to +85°C			1.089	1.100	1.111	V
		T <sub>A</sub> = 0°C to +85°C			1.084	1.100	1.117	
Reference Load Regulation	ΔV <sub>REF</sub>	I <sub>REF</sub> = -1μA to +10μA				0.5	2	mV
pMOS Switch On-Resistance	R <sub>ON,P</sub>	I <sub>LX</sub> = 0.5A	V <sub>IN</sub> = +4.5V			90	200	mΩ
			V <sub>IN</sub> = +3V			110	250	
nMOS Switch On-Resistance	R <sub>ON,N</sub>	I <sub>LX</sub> = 0.5A	V <sub>IN</sub> = +4.5V			70	150	mΩ
			V <sub>IN</sub> = +3V			80	200	
Current-Limit Threshold	I <sub>LIMIT</sub>				3.1	3.6	4.1	A
RMS LX Output Current							3.1	A

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## ELECTRICAL CHARACTERISTICS (continued)

( $V_{IN} = V_{CC} = +3.3V$ ,  $FBSEL = GND$ ,  $T_A = 0^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Idle-Mode Current Threshold			0.3	0.6	0.9	A
Switching Frequency	f	(Note 2)			1	MHz
No-Load Supply Current	$I_{IN} + I_{CC}$	$V_{FB} = 1.2V$		350	600	$\mu A$
Shutdown Supply Current	$I_{IN} + I_{CC}$	$\overline{SHDN} = GND$ , includes pMOS leakage		<1	15	$\mu A$
Thermal Shutdown Threshold	$T_{SHDN}$	Hysteresis = $15^{\circ}C$		160		$^{\circ}C$
Undervoltage Lockout	$V_{UVLO}$	$V_{IN}$ falling, hysteresis = $90mV$	2.5	2.6	2.7	V
FB Input Bias Current		$V_{FB} = 1.2V$	0	60	250	nA
Off-Time	$t_{OFF}$	$R_{TOFF} = 110k\Omega$	0.9	1.00	1.1	$\mu s$
		$R_{TOFF} = 30.1k\Omega$	0.24	0.30	0.37	
		$R_{TOFF} = 499k\Omega$	3.8	4.5	5.2	
Off-Time Startup Period		$FB = GND$		4 $t_{OFF}$		$\mu s$
On-Time	$t_{ON}$	(Note 2)	0.4			$\mu s$
SS Source Current	$I_{SS}$		4	5	6	$\mu A$
SS Sink Current	$I_{SS}$	$V_{SS} = 1V$	100			$\mu A$
$\overline{SHDN}$ Input Current	$I_{\overline{SHDN}}$	$V_{SHDN} = 0$ to $V_{CC}$	-1		1	$\mu A$
$\overline{SHDN}$ Logic Input Low Voltage	$V_{IL}$				0.8	V
$\overline{SHDN}$ Logic Input High Voltage	$V_{IH}$		2.0			V
FBSEL Input Current	$I_{FB}$	$V_{FBSEL} = 0$ to $V_{CC}$	-4		4	$\mu A$
FBSEL Logic Thresholds		$FBSEL = GND$			0.2	V
		$FBSEL = REF$	0.9		1.3	
		$FBSEL = unconnected$	$0.7V_{CC} - 0.2$		$0.7V_{CC} + 0.2$	
		$FBSEL = V_{CC}$	$V_{CC} - 0.2$			
Maximum Output RMS Current					3.1	ARMS

## ELECTRICAL CHARACTERISTICS

( $V_{IN} = V_{CC} = +3.3V$ ,  $FBSEL = GND$ ,  $T_A = -40^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .) (Note 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	MAX	UNITS	
Input Voltage	$V_{IN}, V_{CC}$		3.0	5.5	V	
Preset Output Voltage	$V_{OUT}$	$V_{IN} = +3V$ to $+5.5V$ , $I_{LOAD} = 0$ to $2.5A$ , $V_{FB} = V_{OUT}$	$FBSEL = V_{CC}$	2.475	2.576	V
			$FBSEL = unconnected$	1.485	1.545	
			$FBSEL = REF$	1.782	1.854	
			$FBSEL = GND$	1.078	1.122	
Adjustable Output Voltage Range		$V_{IN} = V_{CC} = +3V$ to $+5.5V$ , $FBSEL = GND$	$V_{REF}$	$V_{IN}$	V	
Reference Voltage	$V_{REF}$		1.078	1.122	V	
pMOS Switch On-Resistance	$R_{ON,P}$	$I_{LX} = 0.5A$	$V_{IN} = +4.5V$		200	m $\Omega$
			$V_{IN} = +3V$		250	

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## ELECTRICAL CHARACTERISTICS (continued)

( $V_{IN} = V_{CC} = +3.3V$ , FBSEL = GND,  $T_A = -40^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .) (Note 3)

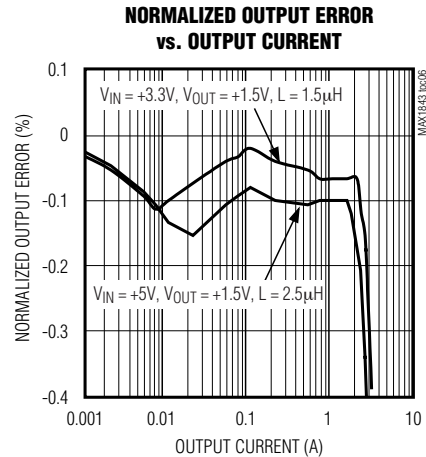
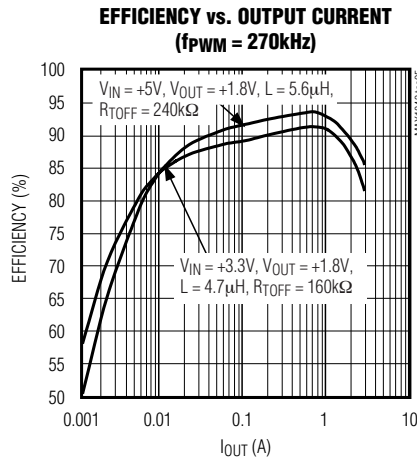
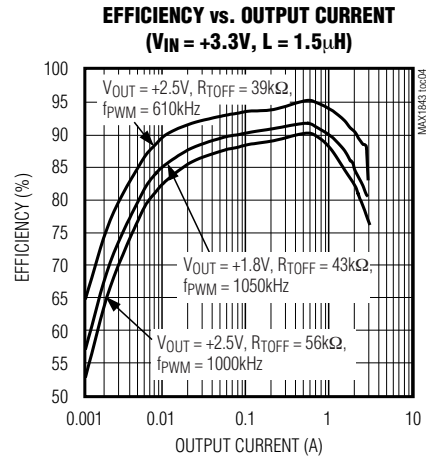
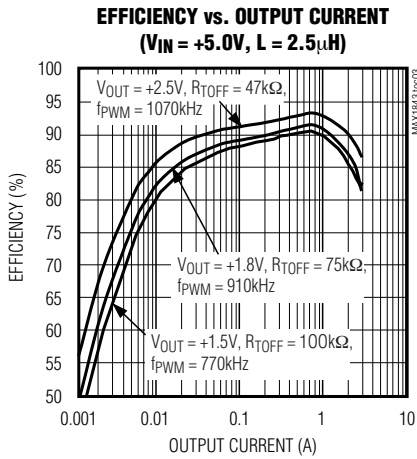
PARAMETER	SYMBOL	CONDITIONS	MIN	MAX	UNITS
nMOS Switch On-Resistance	$R_{ON,N}$	$I_{LX} = 0.5A$	$V_{IN} = +4.5V$	150	m $\Omega$
			$V_{IN} = +3V$	200	
Current-Limit Threshold	$I_{LIMIT}$		2.9	4.3	A
Idle-Mode Current Threshold			0.2	1.0	A
No-Load Supply Current	$I_{IN} + I_{CC}$	$V_{FB} = 1.2V$		600	$\mu A$
FB Input Bias Current	$I_{FB}$	$V_{FB} = 1.2V$	0	300	nA
Off-Time	$t_{OFF}$	$R_{TOFF} = 110k\Omega$	0.85	1.15	$\mu s$

**Note 2:** Recommended operating frequency, not production tested.

**Note 3:** Specifications from  $0^{\circ}C$  to  $-40^{\circ}C$  are guaranteed by design, not production tested.

## Typical Operating Characteristics

(Circuit of Figure 1,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

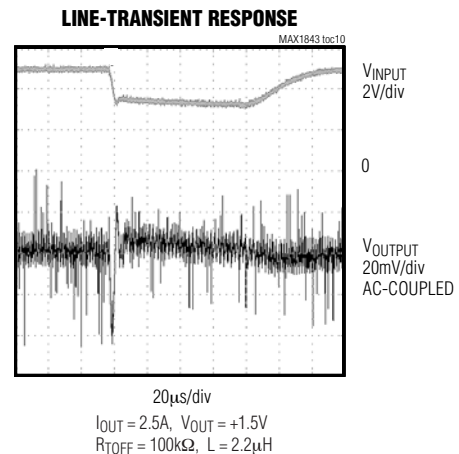
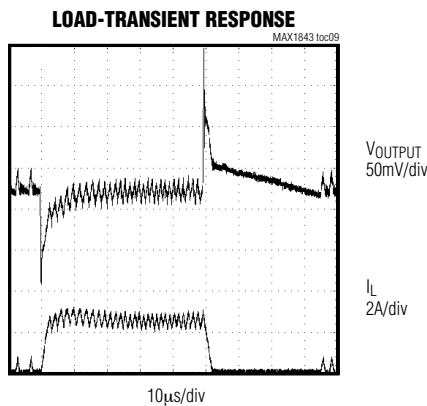
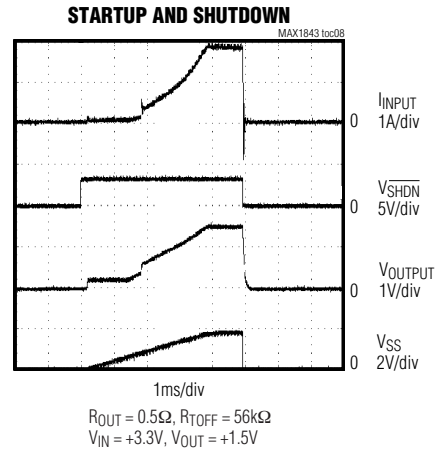
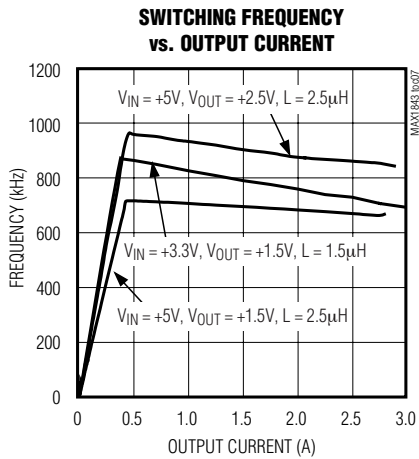
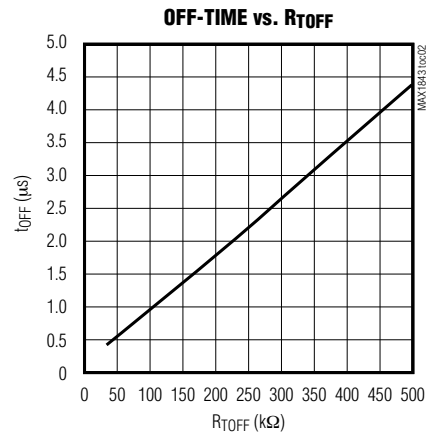
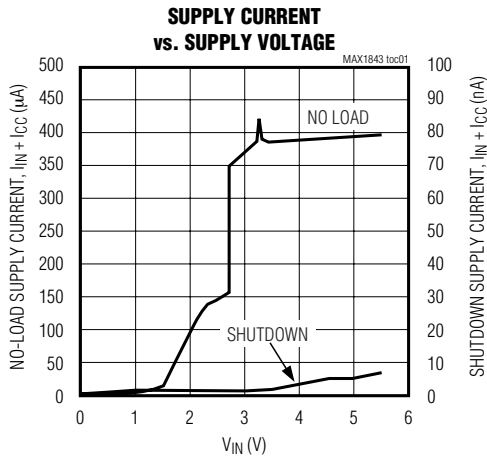


# 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Synchronous Rectification in TQFN Package

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## Typical Operating Characteristics (continued)

(Circuit of Figure 1,  $T_A = +25^\circ\text{C}$ , unless otherwise noted.)



## 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Synchronous Rectification in TQFN Package

### Pin Description

PIN	NAME	FUNCTION
1, 5, 10, 11, 12, 22, 24, 26, 28	N.C.	Not Internally Connected
2, 4	IN	Supply Voltage Input—for the Internal pMOS Power Switch
3, 18, 19, 23, 25	LX	Connection for the Drains of the pMOS Power Switch and nMOS Synchronous-Rectifier Switch. Connect the inductor from this node to the output filter capacitor and load.
6	SS	Soft-Start. Connect a capacitor from SS to GND to limit inrush current during startup.
7	COMP	Integrator Compensation. Connect a capacitor from COMP to $V_{CC}$ for integrator compensation. See <i>Integrator Amplifier</i> section.
8	TOFF	Off-Time Select Input. Sets the pMOS power switch off-time during constant-off-time operation. Connect a resistor from TOFF to GND to adjust the PMOS switch off-time.
9	FB	Feedback Input—for Both Preset-Output and Adjustable-Output Operating Modes. Connect directly to output for fixed-voltage operation or to a resistive divider for adjustable operating modes.
13, back-side pad	GND	Analog Ground. Connect exposed backside pad to pin 13.
14	REF	Reference Output. Bypass REF to GND with a 1 $\mu$ F capacitor.
15	FBSEL	Feedback Select Input. Selects output voltage. See Table 2 for programming instructions.
16	$V_{CC}$	Analog Supply Voltage Input. Supplies internal analog circuitry. Bypass $V_{CC}$ with a 10 $\Omega$ and 2.2 $\mu$ F lowpass filter. See Figure 1.
17, 20, 21	PGND	Power Ground. Internally connected to the internal nMOS synchronous-rectifier switch.
27	$\overline{\text{SHDN}}$	Shutdown Control Input. Drive $\overline{\text{SHDN}}$ low to disable the reference, control circuitry, and internal MOSFETs. Drive high or connect to $V_{CC}$ for normal operation.

### Detailed Description

The MAX1843 synchronous, current-mode, constant-off-time, PWM DC-DC converter steps down input voltages of +3V to +5.5V to a preset output voltage of +2.5V, +1.8V, or +1.5V, or to an adjustable output voltage from +1.1V to  $V_{IN}$ . It delivers up to 2.7A of output current. Internal switches composed of a 0.09 $\Omega$  pMOS power switch and a 0.07 $\Omega$  nMOS synchronous-rectifier switch improve efficiency, reduce component count, and eliminate the need for an external Schottky diode.

The MAX1843 optimizes efficiency by operating in constant-off-time mode under heavy loads and in Maxim's proprietary idle mode under light loads. A single resistor-programmable constant-off-time control sets switching frequencies up to 1MHz, allowing the user to optimize performance trade-offs in efficiency, switching noise, component size, and cost. Under low-dropout conditions, the device operates in a 100% duty-cycle mode, where the pMOS switch remains continuously on. Idle mode enhances light-load efficiency by skipping cycles, thus reducing transition and gate-charge losses.

When power is drawn from a regulated supply, constant-off-time PWM architecture essentially provides constant-frequency operation. This architecture has the inherent advantage of quick response to line-and-load transients.

The MAX1843's current-mode, constant-off-time PWM architecture regulates the output voltage by changing the pMOS switch on-time relative to the constant off-time. Increasing the on-time increases the peak inductor current and the amount of energy transferred to the load per pulse.

### Modes of Operation

The current through the pMOS switch determines the mode of operation: constant-off-time mode (for load currents greater than half the Idle Mode threshold, of idle mode), or idle mode (for load currents less than half the Idle-Mode threshold). Current sense is achieved through a proprietary architecture that eliminates current-sensing  $I^2R$  losses.

## 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Synchronous Rectification in TQFN Package

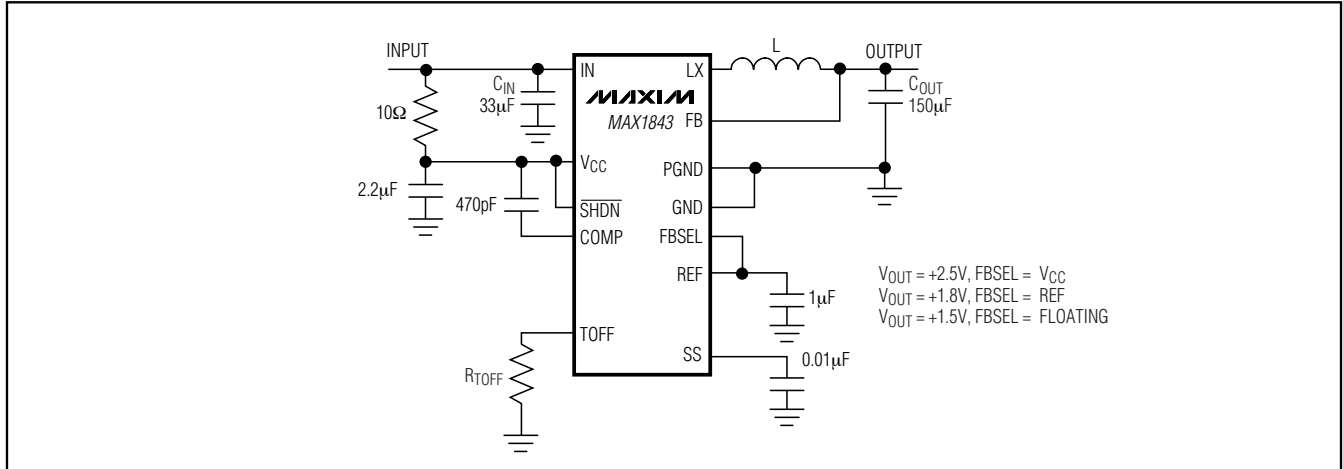


Figure 1. Typical Circuit

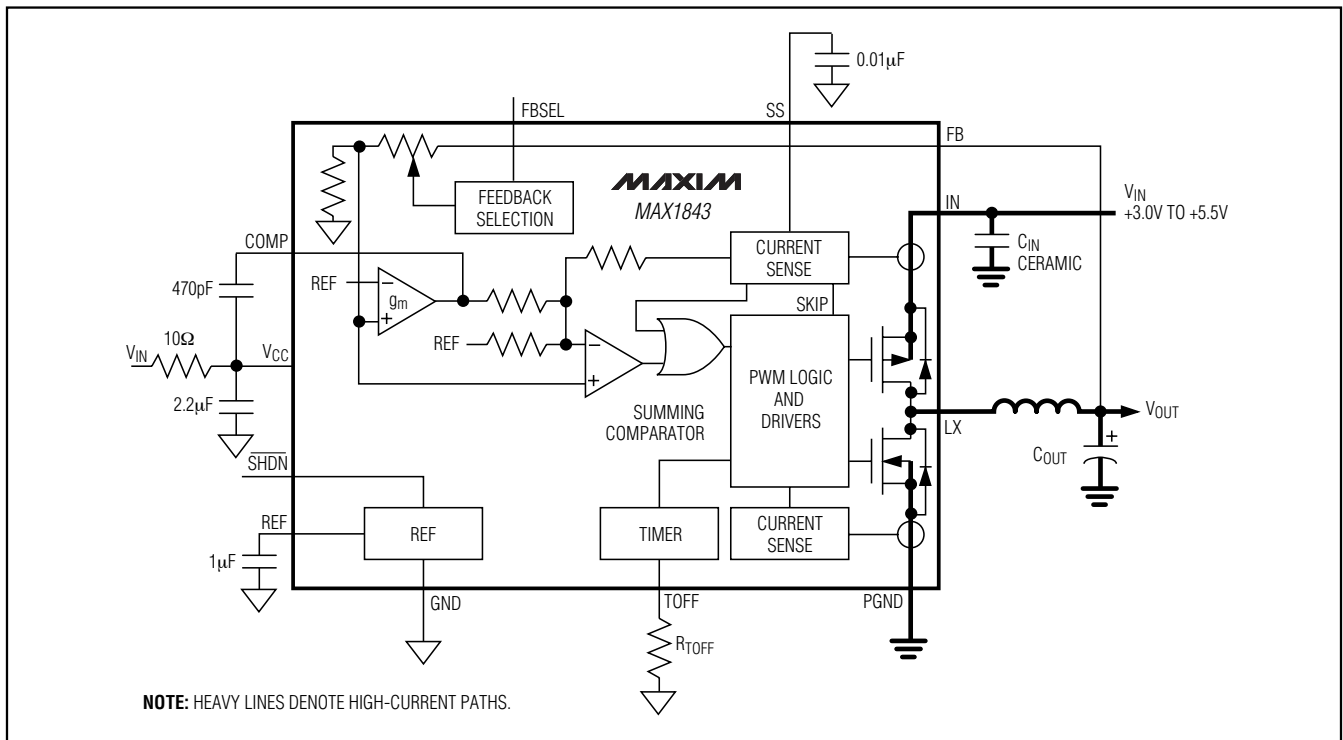


Figure 2. Functional Diagram

### Constant-Off-Time Mode

Constant-off-time operation occurs when the current through the pMOS switch is greater than the idle-mode threshold current (which corresponds to a load current of half the idle mode threshold). In this mode, the regulation comparator turns the pMOS switch on at the end of each off-time, keeping the device in continuous-conduction

mode. The pMOS switch remains on until the output is in regulation or the current limit is reached. When the pMOS switch turns off, it remains off for the programmed off-time ( $t_{OFF}$ ). To control the current under short-circuit conditions, the pMOS switch remains off for approximately  $4 \times t_{OFF}$  when  $V_{OUT} < V_{OUT(NOM)} / 4$ .



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### Idle Mode

Under light loads, this device improves efficiency by switching to a pulse-skipping idle mode. Idle-mode operation occurs when the current through the pMOS switch is less than the idle-mode threshold current. Idle mode forces the pMOS to remain on until the current through the switch reaches the idle mode threshold, thus minimizing the unnecessary switching that degrades efficiency under light loads. In idle mode, the device operates in discontinuous conduction. Current-sense circuitry monitors the current through the nMOS synchronous switch, turning it off before the current reverses. This prevents current from being pulled from the output filter through the inductor and nMOS switch to ground. As the device switches between operating modes, no major shift in circuit behavior occurs.

### 100% Duty-Cycle Operation

When the input voltage drops near the output voltage, the duty cycle increases until the pMOS MOSFET is on continuously. The dropout voltage in 100% duty cycle is the output current multiplied by the on-resistance of the internal pMOS switch and parasitic resistance in the inductor. The pMOS switch remains on continuously as long as the current limit is not reached.

### Shutdown

Drive  $\overline{\text{SHDN}}$  to a logic-level low to place the MAX1843 in low-power shutdown mode and reduce supply current to less than 1 $\mu\text{A}$ . In shutdown, all circuitry and internal MOSFETs turn off, and the LX node becomes high impedance. Drive  $\overline{\text{SHDN}}$  to a logic-level high or connect to  $V_{\text{CC}}$  for normal operation.

### Summing Comparator

Three signals are added together at the input of the summing comparator (Figure 2): an output voltage error signal relative to the reference voltage, an integrated output voltage error correction signal, and the sensed PMOS switch current. The integrated error signal is provided by a transconductance amplifier with an external capacitor at COMP. This integrator provides high DC accuracy without the need for a high-gain amplifier. Connecting a capacitor at COMP modifies the overall loop response (see the *Integrator Amplifier* section).

### Synchronous Rectification

In a step-down regulator without synchronous rectification, an external Schottky diode provides a path for current to flow when the inductor is discharging. Replacing the Schottky diode with a low-resistance NMOS synchronous switch reduces conduction losses and improves efficiency.

The nMOS synchronous-rectifier switch turns on following a short delay after the pMOS power switch turns off, thus preventing cross-conduction or “shoot through.” In constant-off-time mode, the synchronous-rectifier switch turns off just prior to the pMOS power switch turning on. While both switches are off, inductor current flows through the internal body diode of the nMOS switch. The internal body diode’s forward voltage is relatively high.

### Thermal Resistance

Junction-to-ambient thermal resistance,  $\theta_{\text{JA}}$ , is highly dependent on the amount of copper area immediately surrounding the IC leads. The MAX1843 EV kit has 1in<sup>2</sup> of copper area and a thermal resistance of 50°C/W with no forced airflow. Airflow over the board significantly reduces the junction-to-ambient thermal resistance. For heatsinking purposes, it is essential to connect the exposed backside pad to a large analog ground plane.

### Power Dissipation

Power dissipation in the MAX1843 is dominated by conduction losses in the two internal power switches. Power dissipation due to supply current in the control section and average current used to charge and discharge the gate capacitance of the internal switches (i.e., switching losses) is approximately:

$$P_{\text{DS}} = C \times V_{\text{IN}}^2 \times f_{\text{PWM}}$$

where  $C = 2.5\text{nF}$  and  $f_{\text{PWM}}$  is the switching frequency in PWM mode.

This number is reduced when the switching frequency decreases as the part enters idle mode. Combined conduction losses in the two power switches are approximated by:

$$P_{\text{D}} = I_{\text{OUT}}^2 \times R_{\text{PMOS}}$$

where  $R_{\text{PMOS}}$  is the on-resistance of the pMOS switch.

The junction-to-ambient thermal resistance required to dissipate this amount of power is calculated by:

$$\theta_{\text{JA}} = (T_{\text{J,MAX}} - T_{\text{A,MAX}}) / P_{\text{D(TOT)}}$$

where:  $\theta_{\text{JA}}$  = junction-to-ambient thermal resistance

$T_{\text{J(MAX)}}$  = maximum junction temperature

$T_{\text{A(MAX)}}$  = maximum ambient temperature

$P_{\text{D(TOT)}}$  = total losses



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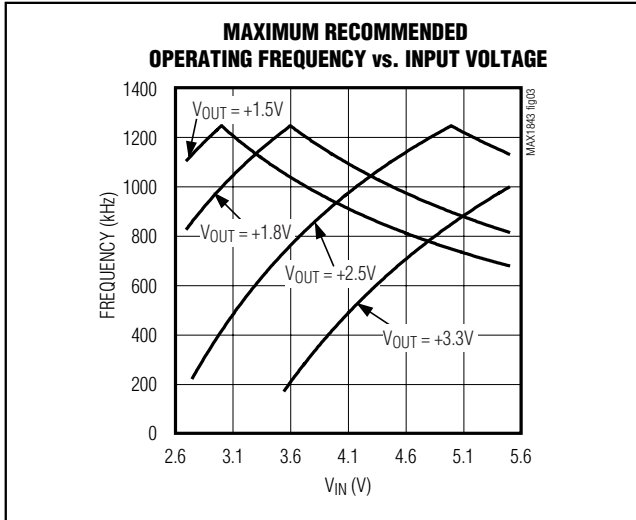


Figure 3. Maximum Recommended Operating Frequency vs. Input Voltage

**Table 1. Recommended Component Values (I<sub>OUT</sub> = 2.7A)**

V <sub>IN</sub> (V)	V <sub>OUT</sub> (V)	f <sub>PWM</sub> (kHz)	L (μH)	R <sub>TOFF</sub> (kΩ)
5	3.3	800	2.2	39
5	2.5	1180	2.2	47
5	1.8	850	2.2	75
5	1.5	715	2.2	100
3.3	2.5	570	1.5	39
3.3	1.8	985	1.5	43
3.3	1.5	940	1.5	56

### Design Procedure

For typical applications, use the recommended component values in Table 1. For other applications, take the following steps:

- 1) Select the desired PWM-mode switching frequency. See Figure 3 for maximum operating frequency.
- 2) Select the constant off-time as a function of input voltage, output voltage, and switching frequency.
- 3) Select R<sub>TOFF</sub> as a function of off-time.
- 4) Select the inductor as a function of output voltage, off-time, and peak-to-peak inductor current.

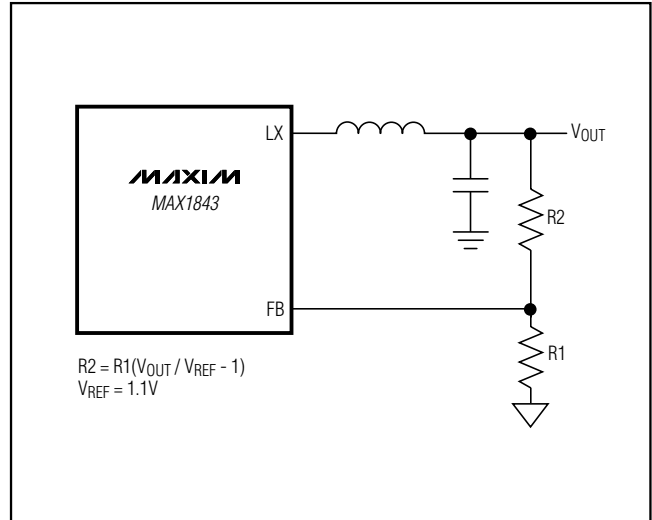


Figure 4. Adjustable Output Voltage

**Table 2. Output Voltage Programming**

PIN		OUTPUT VOLTAGE (V)
FBSEL	FB	
VCC	Output voltage	2.5
Unconnected	Output voltage	1.5
REF	Output voltage	1.8
GND	Resistive divider	Adjustable

### Setting the Output Voltage

The output of the MAX1843 is selectable between one of three preset output voltages: +2.5V, +1.8V, and +1.5V. For a preset output voltage, connect FB to the output voltage, and connect FBSEL as indicated in Table 2. For an adjustable output voltage, connect FBSEL to GND, and connect FB to a resistive divider between the output voltage and ground (Figure 4). Regulation is maintained for adjustable output voltages when V<sub>FB</sub> = V<sub>REF</sub>. Use a resistor in the 10kΩ to 50kΩ range for R1. R2 is given by the equation:

$$R2 = R1 \left( \frac{V_{OUT}}{V_{REF}} - 1 \right)$$

where V<sub>REF</sub> is typically 1.1V.

## 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Synchronous Rectification in TQFN Package

### Programming the Switching Frequency and Off-Time

The MAX1843 features a programmable PWM mode switching frequency, which is set by the input and output voltage and the value of  $R_{TOFF}$ , connected from  $TOFF$  to GND.  $R_{TOFF}$  sets the pMOS power switch off-time in PWM mode. Use the following equation to select the off-time according to the desired switching frequency in PWM mode:

$$t_{OFF} = \frac{(V_{IN} - V_{OUT} - V_{PMOS})}{f_{PWM}(V_{IN} - V_{PMOS} + V_{NMOS})}$$

where:  $t_{OFF}$  = the programmed off-time  
 $V_{IN}$  = the input voltage  
 $V_{OUT}$  = the output voltage  
 $V_{PMOS}$  = the voltage drop across the internal pMOS power switch  
 $V_{NMOS}$  = the voltage drop across the internal nMOS synchronous-rectifier switch  
 $f_{PWM}$  = switching frequency in PWM mode

Select  $R_{TOFF}$  according to the formula:

$$R_{TOFF} = (t_{OFF} - 0.07\mu s) (110k\Omega / 1.00\mu s)$$

Recommended values for  $R_{TOFF}$  range from 36k $\Omega$  to 430k $\Omega$  for off-times of 0.4 $\mu s$  to 4 $\mu s$ .

### Inductor Selection

The key inductor parameters must be specified: inductor value ( $L$ ) and peak current ( $I_{PEAK}$ ). The following equation includes a constant, denoted as LIR, which is the ratio of peak-to-peak inductor AC current (ripple current) to maximum DC load current. A higher value of LIR allows smaller inductance but results in higher losses and ripple. A good compromise between size and losses is found at approximately a 25% ripple-current to load-current ratio (LIR = 0.25), which corresponds to a peak inductor current 1.125 times the DC load current:

$$L = \frac{V_{OUT} \times t_{OFF}}{I_{OUT} \times LIR}$$

where:  $I_{OUT}$  = maximum DC load current  
 LIR = ratio of peak-to-peak AC inductor current to DC load current, typically 0.25

The peak inductor current at full load is  $1.125 \times I_{OUT}$  if the above equation is used; otherwise, the peak current is calculated by:

$$I_{PEAK} = I_{OUT} + \frac{V_{OUT} \times t_{OFF}}{2 \times L}$$

Choose an inductor with a saturation current at least as high as the peak inductor current. The inductor you select should exhibit low losses at your chosen operating frequency.

### Capacitor Selection

The input filter capacitor reduces peak currents and noise at the voltage source. Use a low-ESR and low-ESL capacitor located no further than 5mm from IN. Select the input capacitor according to the RMS input ripple-current requirements and voltage rating:

$$I_{RIPPLE} = I_{LOAD} \frac{\sqrt{V_{OUT}(V_{IN} - V_{OUT})}}{V_{IN}}$$

where  $I_{RIPPLE}$  = input RMS current ripple.

The output filter capacitor affects the output voltage ripple, output load-transient response, and feedback-loop stability. For stable operation, the MAX1843 requires a minimum output ripple voltage of  $V_{RIPPLE} \geq 1\% \times V_{OUT}$ .

The minimum ESR of the output capacitor should be:

$$ESR > 1\% \times \frac{L}{t_{OFF}}$$

Stable operation requires the correct output filter capacitor. When choosing the output capacitor, ensure that:

$$C_{OUT} \geq \frac{t_{OFF}}{V_{OUT}} 79\mu FV / \mu s$$

### Integrator Amplifier

An internal transconductance amplifier fine tunes the output DC accuracy. A capacitor,  $C_{COMP}$ , from COMP to  $V_{CC}$  compensates the transconductance amplifier. For stability, choose  $C_{COMP} = 470pF$ .

A large capacitor value maintains a constant average output voltage but slows the loop response to changes in output voltage. A small capacitor value speeds up the loop response to changes in output voltage but decreases stability. Choose the capacitor values that result in optimal performance.

## 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Synchronous Rectification in TQFN Package

### Soft-Start

Soft-start allows a gradual increase of the internal current limit to reduce input surge currents at startup and at exit from shutdown. A timing capacitor,  $C_{SS}$ , placed from SS to GND sets the rate at which the internal current limit is changed. Upon power-up, when the device comes out of undervoltage lockout (2.6V typ) or after the  $\overline{SHDN}$  pin is pulled high, a  $4\mu\text{A}$  constant-current source charges the soft-start capacitor and the voltage on SS increases. When the voltage on SS is less than approximately 0.7V, the current limit is set to zero. As the voltage increases from 0.7V to approximately 1.8V, the current limit is adjusted from 0 to the current-limit threshold (see the *Electrical Characteristics*). The voltage across the soft-start capacitor changes with time according to the equation:

$$V_{SS} = \frac{4\mu\text{A} \times t}{C_{SS}}$$

The soft-start current limit varies with the voltage on the soft-start pin, SS, according to the equation:

$$SS I_{LIMIT} = \frac{V_{SS} - 0.7\text{V}}{1.1\text{V}} \times I_{LIMIT}$$

where  $I_{LIMIT}$  is the current threshold from the *Electrical Characteristics*.

The constant-current source stops charging once the voltage across the soft-start capacitor reaches 1.8V (Figure 5).

### Frequency Variation with Output Current

The operating frequency of the MAX1843 is determined primarily by  $t_{OFF}$  (set by  $R_{TOFF}$ ),  $V_{IN}$ , and  $V_{OUT}$  as shown in the following formula:

$$f_{PWM} = (V_{IN} - V_{OUT} - V_{PMOS}) / [t_{OFF} (V_{IN} - V_{PMOS} + V_{NMOS})]$$

However, as the output current increases, the voltage drop across the nMOS and pMOS switches increases and the voltage across the inductor decreases. This causes the frequency to drop. The change in frequency can be approximated with the following formula:

$$\Delta f_{PWM} = -I_{OUT} \times R_{PMOS} / (V_{IN} \times t_{OFF})$$

where  $R_{PMOS}$  is the resistance of the internal MOSFETs (90m $\Omega$  typ).

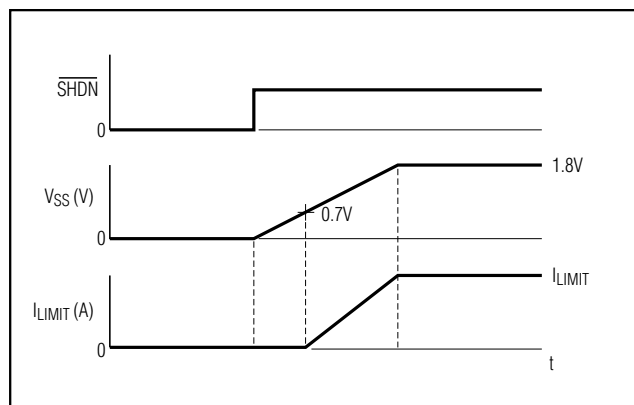


Figure 5. Soft-Start Current-Limit Over Time

### Circuit Layout and Grounding

Good layout is necessary to achieve the MAX1843's intended output power level, high efficiency, and low noise. Good layout includes the use of ground planes, careful component placement, and correct routing of traces using appropriate trace widths. The following points are in order of decreasing importance:

- 1) Minimize switched-current and high-current ground loops. Connect the input capacitor's ground, the output capacitor's ground, and PGND. Connect the resulting island to GND at only one point.
- 2) Connect the input filter capacitor less than 5mm away from IN. The connecting copper trace carries large currents and must be at least 1mm wide, preferably 2.5mm.
- 3) Place the LX node components as close together and as near to the device as possible. This reduces resistive and switching losses as well as noise.
- 4) Ground planes are essential for optimum performance. In most applications, the circuit is located on a multilayer board and full use of the four or more layers is recommended. For heat dissipation, connect the exposed backside pad to a large analog ground plane, preferably on a surface of the board that receives good airflow. If the ground plane is located on the IC surface, make use of the N.C. pins adjacent to GND to lower thermal resistance to the ground plane. If the ground is located elsewhere, use several vias to lower thermal resistance. Typical applications use multiple ground planes to minimize thermal resistance. Avoid large AC currents through the analog ground plane.

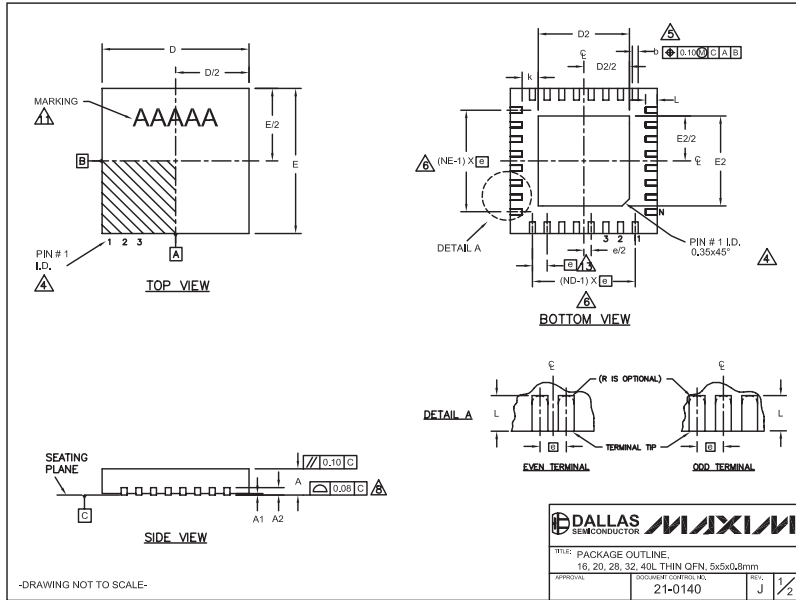
### Chip Information

TRANSISTOR COUNT: 3662

# 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Synchronous Rectification in TQFN Package

## Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to [www.maxim-ic.com/packages.](http://www.maxim-ic.com/packages.))



COMMON DIMENSIONS												
PKG. SYMBOL	16L 5x5		20L 5x5		28L 5x5		32L 5x5		40L 5x5		MIN.	MAX.
	MIN.	NOM.	MIN.	NOM.	MIN.	NOM.	MIN.	NOM.	MIN.	NOM.		
A	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80
A1	0	0.02	0.05	0	0.02	0.05	0	0.02	0.05	0	0.02	0.05
A2	0.20 REF.		0.20 REF.		0.20 REF.		0.20 REF.		0.20 REF.			
b	0.25	0.30	0.35	0.25	0.30	0.35	0.20	0.25	0.30	0.15	0.20	0.25
D	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10
E	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10
e	0.80 BSC.		0.65 BSC.		0.50 BSC.		0.50 BSC.		0.40 BSC.			
k	0.25	-	-	0.25	-	-	0.25	-	0.25	-	-	-
L	0.30	0.40	0.50	0.45	0.55	0.65	0.30	0.40	0.50	0.30	0.40	0.50
N	16		20		28		32		40			
ND	4		5		7		8		10			
NE	4		5		7		8		10			
JEDEC	WHHB		WHHC		WHHD-1		WHHD-2		---			

- NOTES:
1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
  2. ALL DIMENSIONS ARE IN MILLIMETERS, ANGLES ARE IN DEGREES.
  3. N IS THE TOTAL NUMBER OF TERMINALS.

PKG. CODES	D2			E2		
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
T1655-2	3.00	3.10	3.20	3.00	3.10	3.20
T1655-3	3.00	3.10	3.20	3.00	3.10	3.20
T1655N-1	3.00	3.10	3.20	3.00	3.10	3.20
T2055-3	3.00	3.10	3.20	3.00	3.10	3.20
T2055-4	3.00	3.10	3.20	3.00	3.10	3.20
T2055-5	3.15	3.25	3.35	3.15	3.25	3.35
T2855-3	3.15	3.25	3.35	3.15	3.25	3.35
T2855-4	2.60	2.70	2.80	2.60	2.70	2.80
T2855-5	2.60	2.70	2.80	2.60	2.70	2.80
T2855-6	3.15	3.25	3.35	3.15	3.25	3.35
T2855-7	2.60	2.70	2.80	2.60	2.70	2.80
T2855-8	3.15	3.25	3.35	3.15	3.25	3.35
T2855N-1	3.15	3.25	3.35	3.15	3.25	3.35
T3255-3	3.00	3.10	3.20	3.00	3.10	3.20
T3255-4	3.00	3.10	3.20	3.00	3.10	3.20
T3255-5	3.00	3.10	3.20	3.00	3.10	3.20
T3255N-1	3.00	3.10	3.20	3.00	3.10	3.20
T4055-1	3.40	3.50	3.60	3.40	3.50	3.60

# 2.7A, 1MHz, Low-Voltage, Step-Down Regulator with Internal Synchronous Rectification in QFN Package

## Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)

<p>4. **SEE COMMON DIMENSIONS TABLE</p> <p>5. THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JEDEC SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.</p> <p>6. DIMENSION 5 APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm FROM TERMINAL TP.</p> <p>7. NO AND HE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.</p> <p>8. DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.</p> <p>9. COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.</p> <p>10. DRAWING CONFORMS TO JEDEC MO220, EXCEPT EXPOSED PAD DIMENSION FOR T2855-3 AND T2855-4.</p> <p>11. WARRPAGE SHALL NOT EXCEED 0.10 mm.</p> <p>12. MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY.</p> <p>13. NUMBER OF LEADS SHOWN ARE FOR REFERENCE ONLY.</p> <p>14. LEAD CENTERLINES TO BE AT TRUE POSITION AS DEFINED BY BASIC DIMENSION "e", ±0.05.</p>	<table border="1"> <tr> <td>T4055-2</td> <td>3.40</td> <td>3.50</td> <td>3.60</td> <td>3.40</td> <td>3.50</td> <td>3.60</td> </tr> </table>	T4055-2	3.40	3.50	3.60	3.40	3.50	3.60
T4055-2	3.40	3.50	3.60	3.40	3.50	3.60		
<p>15. PACKAGE OUTLINE</p> <p>16, 20, 26, 32, 40, THIN QFN, 6x5x0.8mm</p> <p>17. DALLAS SEMICONDUCTOR</p> <p>18. MAXIM</p>	<p>19. DRAWING TITLE</p> <p>21-0140</p> <p>22. REV. J</p> <p>23. 2/2</p>							

-DRAWING NOT TO SCALE-

MAX1843

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