## MAX20029/MAX20029B/ MAX20029C/MAX20029D

## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Benefits and Features

- Quad Step-Down DC-DC Converters with Integrated FETs
- Operate from 3.0V to 5.5V Supply Voltage
- 0.7 V to 4.0 V Fixed or Adjustable Output Voltage
- 2.2MHz Switching Frequency
- MAX20029/MAX20029C: Up to Four 1.5A Channels
- MAX20029B/MAX20029D: Up to One 3A + Two 1.5A Channels
- Designed to Improve Automotive EMI Performance
- Forced-PWM Operation
- Two Channels $180^{\circ}$ Out-of-Phase
- SYNC Input
- Spread-Spectrum Option
- Soft-Start and Supply Sequencing Reduces Inrush Current
- Individual Enable Inputs and Power-Good Outputs to Simplify Sequencing
- OV Input-Voltage Monitoring
- Overtemperature and Short-Circuit Protection
- 28-Pin ( $5 \mathrm{~mm} \times 5 \mathrm{~mm} \times 0.8 \mathrm{~mm}$ ) TQFN-EP Package
- $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ Operating Temperature Range

Ordering Information appears at end of data sheet.

## Simplified Block Diagram



## MAX20029/MAX20029B/ MAX20029C/MAX20029D

## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

Absolute Maximum Ratings<br>PV_ to PGND<br>$\qquad$<br>-0.3 V to +6.0 V<br>$\mathrm{V}_{\mathrm{A}}$ to GND...........................................................-0.3V to +6.0 V<br>OUTS_, EN_, PG_, SYNC to GND...............-0.3V to VA + 0.3V<br>PV_ to PV<br>$\qquad$<br>$\qquad$ -0.3 V to +0.3 V<br>PGND_ to GND ....................................................-0.3V to +0.3 V<br>LX_ to PGND..............................................-1.0V to PV_ + 0.3 V<br>LX_ Continuous RMS Current<br>$\qquad$<br>2.0A<br>Output Short-Circuit Duration.<br>$\qquad$<br>Continuous

| Continuous Power Dissipation $\left(\mathrm{TA}=+70^{\circ} \mathrm{C}\right)$ |
| :--- |
| 28-pin TQFN (derate $28.6 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )....... 2285 mW |
| Operating Temperature Range..........................................................................................................$~$ |

Continuous Power Dissipation ( $\mathrm{TA}=+70^{\circ} \mathrm{C}$ )
28-pin TQFN (derate $28.6 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )....... 2285 mW
Operating Temperature Range.......................... $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
Junction Temperature..................................................... $+150^{\circ} \mathrm{C}$
Storage Temperature Range ............................. $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Soldering Temperature (reflow)....................................... $+260^{\circ} \mathrm{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## Package Thermal Characteristics (Note 1)

28 TQFN


Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

## Package Information

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a " + ", "\#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

| PACKAGE TYPE | PACKAGE CODE | OUTLINE NO. | LAND PATTERN NO. |
| :---: | :---: | :---: | :---: |
| 28 TQFN-EP | T2855+5 | $\underline{21-0140}$ | $\underline{90-0025}$ |

## Electrical Characteristics

$\left(\mathrm{V}_{\mathrm{A}}=\mathrm{V}_{\mathrm{PV} 1}=\mathrm{V}_{\mathrm{PV} 2}=\mathrm{V}_{\mathrm{PV} 3}=\mathrm{V}_{\mathrm{PV} 4}=5.0 \mathrm{~V} ; \mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{J}}=-40^{\circ} \mathrm{C}\right.$ to $+125^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ under normal conditions, unless otherwise noted.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GENERAL |  |  |  |  |  |  |  |
| Supply Voltage Range | $\mathrm{V}_{\mathrm{PV}}$ | Fully operational |  | 3.0 |  | 5.5 | V |
| Supply Current | IPVO | No load, no switching,$V_{E N 1}=V_{E N 2}=V_{E N 3}=V_{E N 4}=V_{P V}$ |  | 2.5 | 3.8 | 5 | mA |
| Shut-Off Current | IVPSD | $\begin{aligned} & V_{\mathrm{EN} 1}=\mathrm{V}_{\mathrm{EN} 2}= \\ & \mathrm{V}_{\mathrm{EN} 3}=\mathrm{V}_{\mathrm{EN} 4}= \\ & \mathrm{V}_{\mathrm{GND}} \end{aligned}$ | $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ |  | 0.1 | 2 | $\mu \mathrm{A}$ |
|  |  |  | $\mathrm{T}_{\mathrm{A}}=+125^{\circ} \mathrm{C}$ |  | 2 |  |  |
| Overvoltage Threshold |  | Rising |  | 5.6 | 5.8 | 6 | V |
|  |  | Hysteresis |  | 0.1 |  |  |  |
| UVLO Threshold |  | $\mathrm{V}_{P V_{-}}$falling |  | 2.68 |  |  | V |
|  |  | VPV_falling (MAX20029D) |  | 2.6 |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{PV}}$ _rising |  | 3.0 |  |  |  |
| PWM Switching Frequency | fsw |  |  | 2.0 | 2.2 | 2.4 | MHz |

## Electrical Characteristics (continued)

$\left(\mathrm{V}_{\mathrm{A}}=\mathrm{V}_{\mathrm{PV} 1}=\mathrm{V}_{\mathrm{PV} 2}=\mathrm{V}_{\mathrm{PV} 3}=\mathrm{V}_{\mathrm{PV} 4}=5.0 \mathrm{~V} ; \mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{J}}=-40^{\circ} \mathrm{C}\right.$ to $+125^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ under normal conditions, unless otherwise noted.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Spread Spectrum | Df/f | Spread-spectrum option = enabled (see the Selector Guide) |  | +3 |  |  | \% |
| SYNC Input Frequency Range | $\mathrm{f}_{\text {SYNC }}$ |  |  | 1.7 |  | 2.5 | MHz |
| SYNCHRONOUS STEP-DOWN DC-DC CONVERTERS (OUT1-OUT4) MAX20029D |  |  |  |  |  |  |  |
| Fixed DC Output Accuracy |  | $\mathrm{I}_{\text {LOAD }}=0 \mathrm{~mA}$ |  | +1.5 |  |  | \% |
|  |  | $\mathrm{I}_{\text {LOAD }}=0 \mathrm{~mA}$ to $\mathrm{I}_{\mathrm{MAX}}$ |  | -3 |  | +3 |  |
|  |  | $\begin{aligned} & \text { ILOAD }=0 \mathrm{~mA} \text { to } 1.0 \mathrm{~A}(\mathrm{MAX} 20029 \mathrm{C} / \\ & \text { MAX20029D) } \end{aligned}$ |  | -3 |  | +3 |  |
|  |  | $I_{\text {LOAD }}=0 \mathrm{~mA}$ to 1.0 A at $125^{\circ} \mathrm{C}$ (MAX20029C/MAX20029D) |  | -3 |  | +3.2 |  |
|  |  | $\begin{aligned} & \text { ILOAD }=0 \mathrm{~mA} \text { to } 1.5 \mathrm{~A}(\mathrm{MAX} 20029 \mathrm{C} / \\ & \text { MAX20029D) } \end{aligned}$ |  | -3.75 |  | +3 |  |
|  |  | $\begin{aligned} & \text { ILOAD }=0 \mathrm{~mA} \text { to } 1.5 \mathrm{~A} \text { at } 125^{\circ} \mathrm{C} \\ & \text { (MAX20029C) } \end{aligned}$ |  | -3.75 |  | +3.2 |  |
| FB DC Set-Point Accuracy | $\mathrm{V}_{\text {SFB }}$ | $\begin{aligned} & \text { ILOAD }=0 \mathrm{~mA}(\text { MAX20029/ } \\ & \text { MAX20029B) } \end{aligned}$ |  | 1015 |  |  | mV |
|  |  | ILOAD $=0 \mathrm{~mA}$ to IMAX (MAX20029/ MAX20029B) |  | 970 |  | 1030 |  |
| Load Regulation |  | MAX20029  <br> MAX20029B/  <br> MAX20029D Per 1A of load <br> (OUT3, OUT4)  <br> MAX20029C  |  | -1.5 |  |  | \% |
|  |  | MAX20029B/ MAX20029D (OUT1) | Per 2A of load | -1.5 |  |  |  |
| Line Regulation |  | $\mathrm{I}_{\text {LOAD }}=\mathrm{IMAX} / 2, \mathrm{~V}_{\mathrm{PV}}^{-}$= 4.5 V to 5.5 V |  | +0.3 |  |  | \% |
| pMOS On-Resistance |  | $\mathrm{V}_{P \mathrm{~V}_{-}}=5.0 \mathrm{~V}, \mathrm{I}_{\mathrm{LX}}=0.2 \mathrm{~A}$ |  |  | 125 | 250 | $\mathrm{m} \Omega$ |
| nMOS On-Resistance |  | $\mathrm{VPV}_{-}=5.0 \mathrm{~V}, \mathrm{ILX}_{\text {L }}=0.2 \mathrm{~A}$ |  |  | 100 | 200 | $\mathrm{m} \Omega$ |

## Automotive Quad／Triple Low－Voltage Step－Down DC－DC Converters

## Electrical Characteristics（continued）

$\left(\mathrm{V}_{\mathrm{A}}=\mathrm{V}_{\mathrm{PV} 1}=\mathrm{V}_{\mathrm{PV} 2}=\mathrm{V}_{\mathrm{PV} 3}=\mathrm{V}_{\mathrm{PV} 4}=5.0 \mathrm{~V} ; \mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{J}}=-40^{\circ} \mathrm{C}\right.$ to $+125^{\circ} \mathrm{C}$ ，unless otherwise noted．Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ under normal conditions，unless otherwise noted．）（Note 2）

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| pMOS Current－Limit Threshold |  | $\begin{aligned} & \text { MAX20029 } \\ & \text { MAX20029C } \end{aligned}$ | OUT1／OUT2，Opt 1 （0．5A channel） | 0.8 | 1.1 | 1.5 | A |
|  |  |  | OUT1／OUT2，Opt 2 <br> （1A channel） | 1.4 | 1.65 | 2 |  |
|  |  |  | OUT1／OUT2，Opt 3 （1．5A channel） | 1.85 | 2.2 | 2.75 |  |
|  |  | MAX20029B／ <br> MAX20029D <br> （OUT1，2A <br> channel，per <br> LX＿pin） | （see Selector Guide） | 1.4 | 1.65 | 2 |  |
|  |  | MAX20029B／ MAX20029D （OUT1，3A channel，per LX＿）pin |  | 1.85 | 2.2 | 2.75 |  |
|  |  | OUT3／OUT4 <br> （0．5A channel） | （see Selector Guide） | 0.8 | 1.1 | 1.5 |  |
|  |  | OUT3／OUT4 <br> （1．5A channel） |  | 1.85 | 2.2 | 2.75 |  |
| Soft－Start Ramp Time |  |  |  |  | 3272 |  | Cycles |
| OUTS Leakage Current | $\mathrm{I}_{\mathrm{B}}$ OUTS | Externally adjustable output |  |  | 20 |  | nA |
| LX Leakage Current |  | $\mathrm{V}_{\mathrm{PV}}^{-}$＝ $5.0 \mathrm{~V}, \mathrm{LX}_{-}=\mathrm{V}_{\mathrm{PGND}}$ or $\mathrm{V}_{\mathrm{PV}}$ |  |  | 0.1 |  | $\mu \mathrm{A}$ |
| Minimum On－Time |  |  |  |  | 45 | 66 | ns |
| LX Rise／Fall Time |  |  |  |  | 4 |  | ns |
| Duty－Cycle Range |  |  |  |  |  | 100 | \％ |
| OUTS＿Discharge Resistance |  | $\mathrm{V}_{\mathrm{EN}}=\mathrm{V}_{\mathrm{GND}}$ |  |  | 35 |  | $\Omega$ |
| OUT1，OUT2 Phasing |  | （Note 3） |  |  | 0 |  | Degrees |
| OUT3，OUT4 Phasing |  | （Note 3） |  |  | 180 |  | Degrees |
| THERMAL OVERLOAD |  |  |  |  |  |  |  |
| Thermal－Shutdown Temperature |  | $\mathrm{T}_{\mathrm{J}}$ rising（Note 4） |  |  | ＋185 |  | ${ }^{\circ} \mathrm{C}$ |
| Hysteresis |  | （Note 4） |  |  | 15 |  | ${ }^{\circ} \mathrm{C}$ |
| OUTPUT POWER－GOOD INDICATORS（PG1－PG4） |  |  |  |  |  |  |  |
| Output Overvoltage Threshold |  | $\mathrm{V}_{\text {OUT }}$ rising（percentage of nominal output） |  | 106 | 110 | 114 | \％ |

## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Electrical Characteristics (continued)

$\left(\mathrm{V}_{\mathrm{A}}=\mathrm{V}_{\mathrm{PV} 1}=\mathrm{V}_{\mathrm{PV} 2}=\mathrm{V}_{\mathrm{PV} 3}=\mathrm{V}_{\mathrm{PV} 4}=5.0 \mathrm{~V} ; \mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{J}}=-40^{\circ} \mathrm{C}\right.$ to $+125^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ under normal conditions, unless otherwise noted.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Output Undervoltage Threshold |  | $\mathrm{V}_{\text {OUT }}$ falling (percentage of nominal output) | 92.5 | 94 | 96 | \% |
|  |  | $\mathrm{V}_{\text {OUT }}$ rising (percentage of nominal output) | 93.5 | 95 | 97 |  |
|  |  | $\mathrm{V}_{\text {OUT }}$ falling (percentage of nominal output), MAX20029C/MAX20029D | 90 | 94 | 96 |  |
|  |  | $\mathrm{V}_{\text {OUT }}$ rising (percentage of nominal output), MAX20029C/MAX20029D | 90.5 | 95 | 96.5 |  |
| UV/OV Propagation Delay |  |  |  | 15 |  | $\mu \mathrm{s}$ |
| PG_Output High Leakage Current |  |  |  | 0.1 |  | $\mu \mathrm{A}$ |
| PG_Output Low Level |  | $\mathrm{V}_{\mathrm{PV}}=3.0 \mathrm{~V}$, sinking 3mA |  |  | 0.22 | V |
| Active Timeout Period |  | Option 1 |  | 256 |  | Cycles |
|  |  | Option 2 |  | 20480 |  | Cycles |
| ENABLE INPUTS (EN1-EN4) |  |  |  |  |  |  |
| Input High Level |  | $\mathrm{V}_{\text {PV_ }}=5.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{EN}}$ _rising | 0.7 | 1.0 | 1.3 | V |
| Hysteresis |  | $V_{P V}=5.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{EN}}$ falling |  | 50 |  | mV |
| Pulldown Resistance |  |  |  | 100 |  | $\mathrm{k} \Omega$ |
| DIGITAL INTERFACE (SYNC) |  |  |  |  |  |  |
| Input Voltage High | $\mathrm{V}_{\text {INH }}$ |  | 1.5 |  |  | V |
| Input Voltage Low | $\mathrm{V}_{\text {INL }}$ |  |  |  | 0.5 | V |
| Input Voltage Hysteresis |  |  |  | 70 |  | mV |
| Pulldown Resistance |  |  |  | 100 |  | k $\Omega$ |

Note 2: All units are $100 \%$ production tested at $+25^{\circ} \mathrm{C}$. All temperature limits are guaranteed by design.
Note 3: Phase measurement is in relation to the rising edge of $\mathrm{V}_{\mathrm{LX}}$.
Note 4: Guaranteed by design. Not production tested.

Typical Operating Characteristics
$\left(\mathrm{V}_{\mathrm{A}}=\mathrm{V}_{\mathrm{PV} 1}=\mathrm{V}_{\mathrm{PV} 2}=\mathrm{V}_{\mathrm{PV} 3}=\mathrm{V}_{\mathrm{PV} 4}=5.0 \mathrm{~V} ; \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted. $)$




SUPPLY CURRENT


LINE REGULATION



## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Pin Configuration



## Pin Description

| PIN | NAME |  |
| :---: | :---: | :--- |
| 1 | EN1 | Active-High Digital Enable Input for Buck 1. Driving EN1 high enables Buck 1. |
| 2 | PV1 | Buck 1 Voltage Input. Connect a 2.2 F F or larger ceramic capacitor from PV1 to PGND1 as close <br> as possible to the device. |
| 3 | LX1 | Buck 1 Switching Node. LX1 is high impedance when the device is off. |
| 4 | PGND1 | Power Ground for Buck 1 |
| 5 | PGND2 | Power Ground for Buck 2 |
| 6 | LX2 | Buck 2 Switching Node. LX2 is high impedance when the device is off. Connect to LX1 for the <br> MAX20029B/MAX20029D. |
| 7 | PV2 | Buck 2 Voltage Input. Connect a 2.2 <br> as por larger ceramic capacitor from PV2 to PGND2 as close <br> as possible to the device. |
| 8 | EN2 | Buck 2 Voltage-Sense Input. Connect to output capacitor. Connect to ground for the <br> MAX20029B/MAX20029D. |
| 10 | PG2 | Active-High Digital Enable Input for Buck 2. Driving EN2 high enables Buck 2. Connect to ground <br> for the MAX20029B/MAX20029D. |
| 11 | GND | Open-Drain, Active-High, Power-Good Output for Buck 2. To obtain a logic signal, pull up PG2 <br> with an external resistor connected to a positive voltage equal to or lower than VA. Connect to <br> ground for the MAX20029B/MAX20029D. |
| 12 | PG3 | Opound <br> with an external resistor connected to a positive voltage equal to or lower than VA. |
| 13 | EN3 | Active-High Digital Enable Input for Buck 3. Driving EN3 high enables Buck 3. |

## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Pin Description (continued)

| PIN | NAME | FUNCTION |
| :---: | :---: | :---: |
| 14 | OUTS3 | Buck 3 Voltage Sense Input |
| 15 | PV3 | Buck 3 Voltage Input. Connect a $2.2 \mu \mathrm{~F}$ or larger ceramic capacitor from PV3 to PGND3 as close as possible to the device. |
| 16 | LX3 | Buck 3 Switching Node. LX3 is high impedance when the device is off. |
| 17 | PGND3 | Power Ground for Buck 3 |
| 18 | PGND4 | Power Ground for Buck 4 |
| 19 | LX4 | Buck 4 Switching Node. LX4 is high impedance when the device is off. |
| 20 | PV4 | Buck 4 Voltage Input. Connect a $2.2 \mu \mathrm{~F}$ or larger ceramic capacitor from PV4 to PGND4 as close as possible to the device. |
| 21 | EN4 | Active-High Digital Enable Input for Buck 4. Driving EN4 high enables Buck 4. |
| 22 | OUTS4 | Buck 4 Voltage Sense Input |
| 23 | PG4 | Open-Drain, Active-High, Power-Good Output for Buck 4. To obtain a logic signal, pull up PG4 with an external resistor connected to a positive voltage equal to or lower than VA. |
| 24 | GND | Analog Ground |
| 25 | SYNC | SYNC Input. Supply an external clock to control the switching frequency. Connect SYNC to PGND_ to use the default switching frequency. |
| 26 | VA | Analog Voltage Supply. Connect a $1 \mu \mathrm{~F}$ or larger ceramic capacitor from VA to GND as close as possible to the device. Connect to the same supply as PV_ inputs. |
| 27 | PG1 | Open-Drain, Active-High, Power-Good Output for Buck 1. To obtain a logic signal, pull up PG1 with an external resistor connected to a positive voltage equal to or lower than VA. |
| 28 | OUTS1 | Buck 1 Voltage Sense Input |
| - | EP | Exposed Pad. Connect the exposed pad to ground. Connecting the exposed pad to ground does not remove the requirement for proper ground connections to PGND1-PGND4 and GND. The exposed pad is attached with epoxy to the substrate of the die, making it an excellent path to remove heat from the IC. |



Figure 1. Internal Block Diagram

## Automotive Quad／Triple Low－Voltage Step－Down DC－DC Converters

## Detailed Description

The MAX20029／MAX20029B／MAX20029C／MAX20029D PMICs offer four high－efficiency，synchronous step－down converters that operate with a 3.0 V to 5.5 V input voltage range and provide a 0.7 V to 4.0 V output voltage range． The PMICs deliver up to 1．5A of load current per output， and achieve $\pm 3 \%$ output error over load，line，and tem－ perature ranges．
The PMICs feature fixed－frequency PWM－mode operation with a 2.2 MHz switching frequency．An optional spread－ spectrum frequency modulation minimizes radiated electromagnetic emissions due to the switching frequency， while a factory－programmable synchronization input（SYNC） allows the device to synchronize to an external clock．
Integrated low $R_{D S(O N)}$ switches help minimize efficiency losses at heavy loads and reduce critical／parasitic inductance，making the layout a much simpler task with respect to discrete solutions．
The PMICs are offered in factory－preset output voltages to allow customers to achieve $\pm 3 \%$ output－voltage accuracy， without using expensive $0.1 \%$ resistors．In addition， adjustable output－voltage versions can be set to any desired values between 1.0 V and 4.0 V using an external resistive divider．See the Selector Guide for available options．
Additionally，each converter features soft－start，PG＿ output，overcurrent，and overtemperature protections （see Figure 1）．

## Control Scheme

The PMICs use peak current－mode control，and feature internal slope compensation and loop compensation，both of which reduce board space and allow a very compact solution．

## Hybrid Load－Line Architecture

The PMICs feature hybrid load－line architecture to reduce the output capacitance needed，potentially saving system cost and size．This results in a measurable load－transient response．

## Input Overvoltage Monitoring（OV）

The PMICs feature an input overvoltage－monitoring circuit on the input supply．When the input exceeds 5.8 V （typ） all power－good indicators（PG＿）go low．When the input
supply returns to within the operating range of 5.7 V （typ）or less during the timeout period，the power－good indicators go high．

## Input Undervoltage Lockout（UVLO）

The PMICs feature an undervoltage lockout on the PV＿ inputs set at 2.77 V （typ）falling．This prevents loss of control of the device by shutting down all outputs．This circuit is only active when at least one buck converter is enabled．

## Power－Good Outputs（PG＿）

The PMICs feature an open－drain power－good output for each of the four buck regulators．PG＿asserts low when the output voltage drops $6 \%$ below the regulated voltage or $10 \%$ above the regulated voltage for approximately $15 \mu \mathrm{~s}$ ．PG＿remains asserted for a fixed number of switching cycles after the output returns to its regulated voltage．See the Selector Guide for available options． PG＿asserts low during soft－start and in shutdown．PG＿ becomes high impedance when Buck＿is in regulation． Connect PG＿to a logic supply with a $10 \mathrm{k} \Omega$ resistor．

## Soft－Start

The soft－start time limits startup inrush current by forc－ ing the output voltage to ramp up towards its regulation point．During soft－start，the converters operate in skip mode to prevent the outputs from discharging．Expected soft－start time for MAX20029 and MAX20029B is approxi－ mately 1.5 ms ，and approximately 1 ms for MAX20029C／ MAX20029D（scaling factor is applied due to internal volt－ age reference difference）．

Figure 2．Load－Transient Response


## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Spread-Spectrum Option

The PMICs feature a linear spread-spectrum (SS) operation, which varies the internal operating frequency between fSW and (fSW + 3\%). The internal oscillator is frequency modulated at a rate of 1.5 kHz with a frequency deviation of $3 \%$ (see Figure 3). This function does not apply to an oscillation frequency applied externally through the SYNC pin. Spread spectrum is a factoryselectable option. See the Selector Guide for available options.

## Synchronization (SYNC)

The PMICs feature a SYNC input to allow the internal oscillator to synchronize with an external clock. SYNC accepts signal frequencies in the range of $1.7 \mathrm{MHz}<$ $f_{S Y N C}<2.5 \mathrm{MHz}$. Connect to PGND_if the SYNC feature is not used.

## Current-Limit/Short-Circuit Protection

The PMICs offer a current-limit feature that protects the devices against short-circuit and overload conditions on each output. In the event of a short-circuit or overload condition at an output, the high-side MOSFET remains on until the inductor current reaches the high-side MOSFET's current-limit threshold. The converter then turns on the low-side MOSFET and the inductor current ramps down. The converter allows the high-side MOSFET to turn on only when the inductor current ramps down to the lowside MOSFET's current threshold. This cycle repeats until the short or overload condition is removed.

## Overtemperature Protection

Thermal-overload protection limits the total power dissipation in the PMICs. When the junction temperature exceeds $185^{\circ} \mathrm{C}$ (typ), an internal thermal sensor shuts down the step-down converters, allowing the IC to cool. The thermal sensor turns on the IC again after the junction temperature


Figure 3. Effect of Spread Spectrum on Internal Oscillator
cools by $15^{\circ} \mathrm{C}$. The IC goes through a standard power-up sequence as defined in the Soft-Start section.

## Applications Information

## Adjustable Output-Voltage Option

The MAX20029/MAX20029B PMICs feature adjustable output voltages (see the Selector Guide for more details), which allows the customer to set the outputs to any voltage between 1.0 V and $\mathrm{V}_{\mathrm{PV}}-0.5 \mathrm{~V}$ (up to 4.0 V ). Connect a resistive divider from outpūt (VOUT ) to OUTS_ to GND to set the output voltage (see Figure 4). Select R2 (OUTS_ to the GND resistor) $\leq 100 \mathrm{k} \Omega$. Calculate R1 ( $\mathrm{V}_{\mathrm{OUT}}$ _ to the OUTS_resistor) with the following equation:

$$
\mathrm{R} 1=\mathrm{R} 2\left[\left(\frac{\mathrm{~V}_{\text {OUT_- }}}{\mathrm{V}_{\mathrm{OUTS}_{-}}}\right)-1\right]
$$

where $\mathrm{V}_{\text {OUTS }}=1.0 \mathrm{~V}$ (see the Electrical Characteristics table). The output voltage is nominal at $50 \%$ load current.
The external feedback resistive divider must be frequency compensated for proper operation. Place a capacitor across R1 in the resistive divider network. Use the following equation to determine the value of the capacitor:

$$
\begin{aligned}
& \text { If } \frac{R 2}{R 1}>1, C 1=C\left(\frac{R 2}{R 1}\right) \\
& \text { else } C 1=C \text {, where } C=15 p F
\end{aligned}
$$



Figure 4. Adjustable Output-Voltage Configuration

Connect OUTS_ to VOUT_ for a fixed 1.0 V output voltage.

## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Inductor Selection

The PMICs are optimized for use with a $1.5 \mu \mathrm{H}$ inductor on outputs configured for $0.5 \mathrm{~A}, 1 \mathrm{~A}$, or 1.5 A , and a $1.0 \mu \mathrm{H}$ inductor for an output configured for 2 A or 3 A . For output voltages less than $0.9 \mathrm{~V}, 0.47 \mu \mathrm{H}$ is recommended.

## Input Capacitor

The PMICs are designed to operate with a single $2.2 \mu \mathrm{~F}$ ceramic bypass capacitor on each PV_ input. Phase interleaving of the four buck converters contributes to a lower required input capacitance by canceling input ripple currents. Place the bypass capacitors as close as possible to their corresponding $\mathrm{PV}_{\mathbf{\prime}}$ input to ensure the best EMI and jitter performance.

## Output Capacitor

All outputs of the PMICs are optimized for use with ceramic capacitors.
For $\mathrm{V}_{\mathrm{OUT}} / \mathrm{V}_{\text {IN }}>0.2$ :

$$
\begin{aligned}
& \text { CoUT_MIN }=\frac{20}{V_{\text {OUT }}} \mu \mathrm{F} \\
& \text { C OUT_NOM }=\frac{33}{V_{\text {OUT }}} \mu \mathrm{F}
\end{aligned}
$$

For $V_{\text {OUT }} V_{\text {IN }} \leq 0.2$ :

$$
\begin{aligned}
& \text { COUT_MIN }=\frac{40}{V_{\text {OUT }}} \mu \mathrm{F} \\
& \text { C OUT_NOM }=\frac{60}{V_{\text {OUT }}} \mu \mathrm{F}
\end{aligned}
$$

Additional output capacitance can be used if better voltage ripple or load-transient response is required (see Figure 2). To guarantee stability, it is recommended that the phase margin be measured under the worst-case deration of the output capacitor(s). Due to the soft-start sequence, the PMICs are unable to drive arbitrarily large output capacitors.

## Thermal Considerations

How much power the package can dissipate strongly depends on the mounting method of the IC to the PCB and the copper area for cooling. Using the JEDEC test standard, the maximum power dissipation allowed is 2285 mW in the TQFN package. More power dissipation can be handled by the package if great attention is given during PCB layout. For example, using the top and bottom copper as a heatsink and connecting the thermal vias to one of the middle layers (GND) transfers the heat from the package into the board more efficiently, resulting in lower
junction temperature at high power dissipation in some PMIC applications. Furthermore, the solder mask around the IC area on both top and bottom layers can be removed to radiate the heat directly into the air. The maximum allowable power dissipation in the IC is as follows:

$$
\mathrm{P}_{\mathrm{MAX}}=\frac{\left(\mathrm{T}_{\mathrm{J}(\mathrm{MAX})}-\mathrm{T}_{\mathrm{A}}\right)}{\theta_{\mathrm{JC}}+\theta_{\mathrm{CA}}}
$$

where $T_{J(M A X)}$ is the maximum junction temperature $\left(+150^{\circ} \mathrm{C}\right), \mathrm{T}_{\mathrm{A}}$ is the ambient air temperature, $\theta_{\mathrm{JC}}\left(3^{\circ} \mathrm{C} / \mathrm{W}\right.$ for the 28-pin TQFN) is the thermal resistance from the junction to the case, and $\theta_{\mathrm{CA}}$ is the thermal resistance from the case to the surrounding air through the PCB, copper traces, and the package materials. $\theta_{\mathrm{CA}}$ is directly related to system-level variables and can be modified to increase the maximum power dissipation.
The TQFN package has an exposed thermal pad on its underside. This pad provides a low thermal-resistance path for heat transfer into the PCB. This low thermally resistive path carries a majority of the heat away from the IC. The PCB is effectively a heatsink for the IC. The exposed pad should be connected to a large ground plane for proper thermal and electrical performance. The minimum size of the ground plane is dependent upon many system variables. To create an efficient path, the exposed pad should be soldered to a thermal landing, which is connected to the ground plane by thermal vias. The thermal landing should be at least as large as the exposed pad and can be made larger depending on the amount of free space from the exposed pad to the other pin landings. A sample layout is available on the evaluation kit to speed designs.

## PCB Layout Guidelines

Careful PCB layout is critical to achieve low switching losses and clean, stable operation. Use a multilayer board whenever possible for better noise immunity and power dissipation. Follow these guidelines for good PCB layout:

1) Use a large contiguous copper plane under the PMIC packages. Ensure that all heat-dissipating components have adequate cooling.
2) Keep the high-current paths short, especially at the ground terminals. This practice is essential for stable, jitter-free operation. The high current path comprising of input capacitor, inductor, and the output capacitor should be as short as possible.
3) Keep the power traces and load connections short. This practice is essential for high efficiency. Use thick copper PCBs (2oz vs. 1oz) to enhance full-load efficiency.
4) Use a single ground plane to reduce the chance of ground potential differences. With a single ground plane, enough isolation between analog return signals and high-power signals must be maintained.

## Typical Operating Circuits



## Typical Operating Circuits (continued)



## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Selector Guide

| PART | Iout <br> (A) |  |  |  | VOUT <br> (V) |  |  |  | SPREAD SPECTRUM | PG_ TIMEOUT (CYCLES) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | CH1 | CH2 | CH3 | CH4 | CH1 | CH2 | CH3 | CH4 |  |  |
| MAX20029 |  |  |  |  |  |  |  |  |  |  |
| MAX20029ATIA/V+ | 1.5 | 1.5 | 1.5 | 1.5 | ADJ | ADJ | ADJ | ADJ | Off | 256 |
| MAX20029ATIB/V+ | 1.0 | 1.0 | 1.5 | 1.5 | 1.5 | 1.8 | 1.15 | 1.4 | +3\% | 256 |
| MAX20029ATIC/V+ | 1.0 | 1.0 | 1.5 | 1.5 | 1.8 | 1.35 | 3.3 | 1.2 | +3\% | 256 |
| MAX20029ATID/V+ | 1.0 | 1.0 | 1.5 | 0.5 | 1.0 | 1.8 | ADJ | 3.3 | +3\% | 256 |
| MAX20029ATIF/V+ | 1.5 | 1.5 | 1.5 | 1.5 | 1.0 | 1.8 | ADJ | 3.3 | +3\% | 256 |
| MAX20029B |  |  |  |  |  |  |  |  |  |  |
| MAX20029BATIA/V+ | 3.0 | - | 1.5 | 1.5 | ADJ | - | ADJ | ADJ | Off | 20,480 |
| MAX20029BATIB/V+ | 3.0 | - | 1.5 | 1.5 | 1 | - | 1.8 | 1.5 | +3\% | 20,480 |
| MAX20029BATIC/V+ | 3.0 | - | 1.5 | 1.5 | 1.1 | - | 1.8 | 1.0 | Off | 256 |
| MAX20029BATID/V+ | 3.0 | - | 1.5 | 0.5 | 1.0 | - | 1.8 | 1.2 | +3\% | 256 |
| MAX20029BATIE/V+** | 3.0 | - | 1.5 | 1.5 | 1.5 | - | 1.8 | 3.3 | +3\% | 256 |
| MAX20029C |  |  |  |  |  |  |  |  |  |  |
| MAX20029CATIA/V+ | 1.5 | 1.5 | 1.5 | 1.5 | 3.3 | 1.8 | 1.0 | 0.7 | Off | 256 |
| MAX20029CATIB/V+ | 1.0 | 1.0 | 0.5 | 1.5 | 1.5 | 0.9 | 1.1 | 0.7 | +3\% | 256 |
| MAX20029CATIC/V+** | 1.5 | 1.5 | 1.5 | 1.5 | 1.8 | 3.3 | 0.85 | 1.8 | +3\% | 256 |
| MAX20029D |  |  |  |  |  |  |  |  |  |  |
| MAX20029DATIA/V+ | 3.0 | - | 1.5 | 1.5 | 1.1 | - | 0.7 | 1.8 | Off | 20,480 |

Note: Contact factory for custom configuration. Factory-selectable features include:
CH1/CH2 Current Configuration: 0.5A, 1.0A, or 1.5A (both channels have the same current level)
CH3, CH4 Current Configuration: 0.5 A or 1.5 A
DC-DC Voltages:

- (MAX20029/MAX20029B) Adjustable, or a fixed voltage between 1.0 V and 4.0 V in 50 mV steps
- (MAX20029C) Fixed voltages between 0.7 V and 3.8 V in 50 mV steps

Spread Spectrum: Off, $+3 \%$, or $+6 \%$
PG_Active Timeout Period: 256 or 20,480 clock cycles
CH1 Current Configuration: 2.0A or 3.0A
**Future product-contact factory for availability
See the Ordering Information table for other options.

## Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE |
| :---: | :--- | :--- |
| MAX20029ATI_/V+ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 TQFN-EP* |
| MAX20029BATI_/V+ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 TQFN-EP* |
| MAX20029CATI_/V+ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 TQFN-EP* |
| MAX20029DATI_/V+ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 TQFN-EP* |

Note: Insert the desired suffix letter (from the Selector Guide) into the blank area "_" to indicate factory-selectable features.
/V denotes an automotive qualified part that conforms to
AEC-Q100.
+Denotes a lead(Pb)-free/RoHS-compliant package.
*EP = Exposed pad.
**Future part—contact factory for availability.

## Automotive Quad/Triple Low-Voltage Step-Down DC-DC Converters

## Revision History

| REVISION NUMBER | REVISION <br> DATE | DESCRIPTION | PAGES CHANGED |
| :---: | :---: | :---: | :---: |
| 0 | 6/17 | Initial release | - |
| 1 | 9/17 | Replaced TOCs 1, 2, 3, 4 deleted TOCs 6-9, and renumbered TOC10 to TOC05 and TOC12 to TOC06; added MAX20029ATIC/V+ (as a future product) and MAX20029BATIB/V+ to the Selector Guide | 6, 7, 16 |
| 2 | 10/17 | Removed future product status from MAX20029ATIC/V+ and added future product status on MAX20029BATIB/V+ in the Selector Guide | 15 |
| 3 | 7/18 | Updated title, General Description, Benefits and Features, and Detailed Description; updated Electrical Characteristic table, Figure 1, Typical Operating Circuits; added MAX20029BATIC/V+ and MAX20029CATIA/V+ to the Selector Guide and Ordering Information tables as future parts | 1-16 |
| 4 | 9/18 | Updated General Description, Electrical Characteristics table, Soft-Start, and Output Capacitor. Added MAX20029ATID/V+**, MAX20029BATID/V+**, MAX20029CATIB/ $\mathrm{V}+{ }^{* *}$ with the accompanying ordering information to the Selector Guide | $\begin{gathered} 1,4,5,10,12 \\ 15 \end{gathered}$ |
| 5 | 9/18 | Updated Electrical Characteristics table | 4 |
| 5.1 |  | Replaced missing rows from bottom of Electrical Characteristics table and future product and Ordering Information footnotes under the Selector Guide, which were omitted in error | 5,16 |
| 6 | 10/18 | Added MAX20029BATIE/V+** with the accompanying ordering information and removed future product status from MAX20029CATIA/V+ in the Selector Guide | 16 |
| 7 | 1/19 | Removed future product status from MAX20029BATID/V+ and MAX20029CATIB/V+, updated CH1 for MAX20029CATIB/V+, and corrected DC-DC Voltages note in the Selector Guide | 16 |
| 8 | 2/19 | Removed future product status from MAX20029ATID/V+, MAX20029BATIB/V+ and MAX20029BATIC/V+ in the Selector Guide | 16 |
| 9 | 3/19 | Added MAX20029ATIF/V+ in the Selector Guide | 16 |
| 10 | 12/19 | Added MAX20029D in the General Description and Benefits and Features, updated Electrical Characteristics table, added MAX20029D in the Pin Description table, Detailed Description and Soft-Start section, updated Inductor Selection, added MAX20029D in the Typical Operating Circuits diagram, Updated Selector Guide and Ordering Information tables by adding new row for MAX20029D | $\begin{gathered} 1,3-6,8,11 \\ 13,15-16 \end{gathered}$ |
| 11 | 2/20 | Added MAX20029CATIC/V+** and updated MAX20029DATIA/V+ in Ordering Information | 16 |

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[^0]:    For pricing, delivery, and ordering information, please visit Maxim Integrated's online storefront at https://www.maximintegrated.com/en/storefront/storefront.html.

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