MAX25405 Evaluation Kit

Evaluates: MAX25405

General Description

The MAX25405 evaluation kit (EV kit) is a complete system for demonstrating the MAX25405 optical IR sensor in a typical gesture and proximity-sensing application.

The MAX25405 enables recognition of the following gestures:

- Hand Swipe Left, Right, Up, and Down
- Finger/Hand Rotation Clockwise and Counter-Clockwise
- Air Click
- Proximity Detection and Linger-to-Click

The application circuit operates by illuminating the user's hand with a precision-controlled IR light source and measuring the reflected signal with the MAX25405's 6x10 (60 pixel) IR sensor array. The four-LED IR light source is PWM controlled with external FETs from the MAX25405's onboard FET driver. The return signal is analyzed with an embedded microcontroller that interprets the gestures.

The EV kit consists of the following:

- MAX32620FTHR Microcontroller Platform
- Interface Shield Board
- MAX25405 Sensor Board
- Ribbon Cable (Connects Sensor Board to Shield Board)
- 3.3V Power Supply
- USB 2.0 Type A to Micro B Cable

Note: Plastic stand shown not included with EV kit. Check product website for CAD files.

Ordering Information **appears at end of data sheet.**

Features

- Simple yet Flexible Gesture Solution
- Lower Solution Cost than Camera-Based Systems
- Integrated Optics with ±20deg Field of View (FOV)
- Optimum Resolution for Dynamic Hand Gestures
- Built-in LED Driver with Ultra-Low-Power Operation
- 120kLux Ambient Light Performance
- Compact 20-pin, 4mm x 4mm QFN Package, Side-Wettable
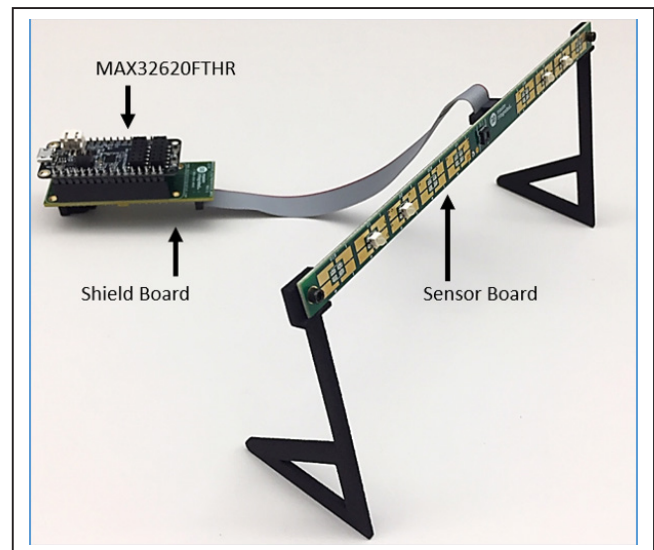- AEC-Q100
- -40°C to +85°C Operation

Figure 1. MAX25405 EV Kit

maxim integrated™

Quick Start

Required Equipment

- MAX25405 EV kit
- Included USB 2.0 Type A to Micro B cable
- Included 3.3V power supply
- Windows PC running the Maxim Gesture Sensor EV kit graphical user interface (GUI)

Note: In the following sections, software-related items are identified by bolding. Text in **bold** refers to items directly from the EV kit software. Text in **bold and underlined** refers to items from the Windows® operating system.

Procedure

The EV kit is fully assembled and tested. Follow the steps to verify board operation:

1) Install the PC EV kit software by running the installation executable: MaximGestureSensorEV-Kit_SetupVx-x-x.exe. Follow the on-screen prompts for default installation, and install the driver when prompted.
2) Connect the external 3.3V supply to the shield board (see Figure 2).
3) Connect a USB cable from the MAX32620FTHR micro-USB port to the PC's USB port (see Figure 2).
4) Launch the PC GUI software. **Start → Maxim Integrated → MaximGestureSensorEVKit**.
5) The software should auto-detect the presence of the EV kit. To verify a successful connection, the lower right of the GUI should read "Connected on COMxx at 115200." If the software fails to make a connection, the following error message is reported: "COM Port Offline." See the *Troubleshooting* section for help if this occurs.
6) Click on the **Run** button to activate the heat map. The frames-per-second (FPS) should report a non-zero value (depending on device configuration; see Figure 3). Click **Stop** when finished viewing. Now that the EV kit is operating, proceed to evaluate gesture performance.

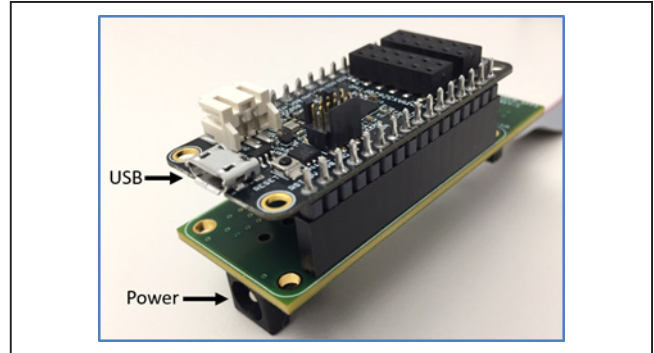*Windows is a registered trademark and registered service mark of Microsoft Corporation.*

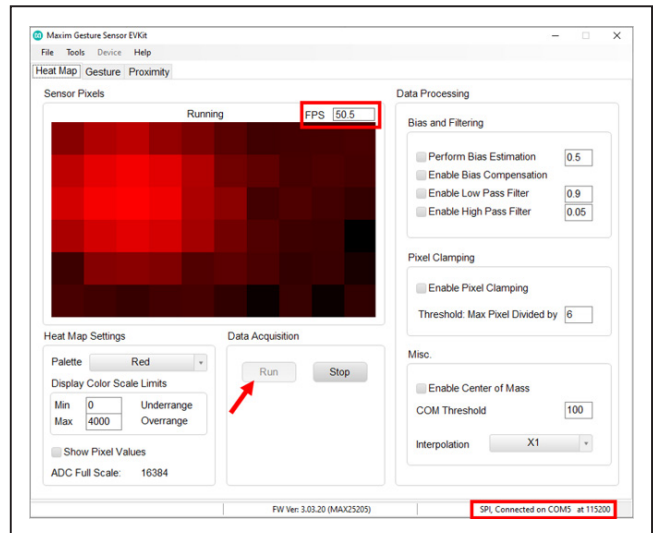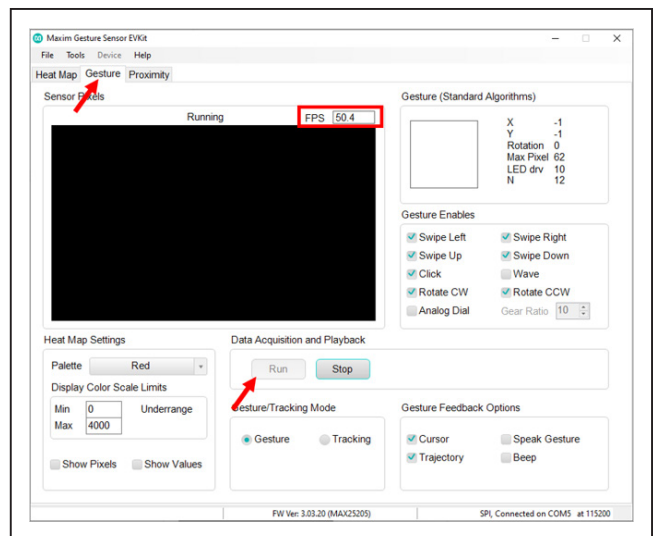Figure 2. USB and Power Connectors

Figure 3. Heat Map Tab

Figure 4. Gesture Tab

7) Click on the **Gesture** tab.
8) Click **Run**. If everything is working correctly, the GUI should report a non-zero frames-per-second (FPS) reading (see Figure 4).
9) Gestures, object position, and other gesture-related information is displayed in the **Gesture** panel in the upper right of the GUI.
10) See *Detailed Description* for proper sensor setup to achieve good gesture performance.

Detailed Description

Notes on Proper Setup for Good Gesture Performance

The sensor should be positioned so that the face of the sensor is aimed at the horizontal, or no more than 15 degrees from the horizontal. If desired, the sensor board can be attached to a stand using the mounting holes on either end of the sensor board.

The sensor should be set up so that it has an unobstructed FOV. If the sensor is set on a table, make sure that the table top is not in the sensor's field of view (check the **Heat Map** view to verify that the field of view is empty when not actively performing gestures).
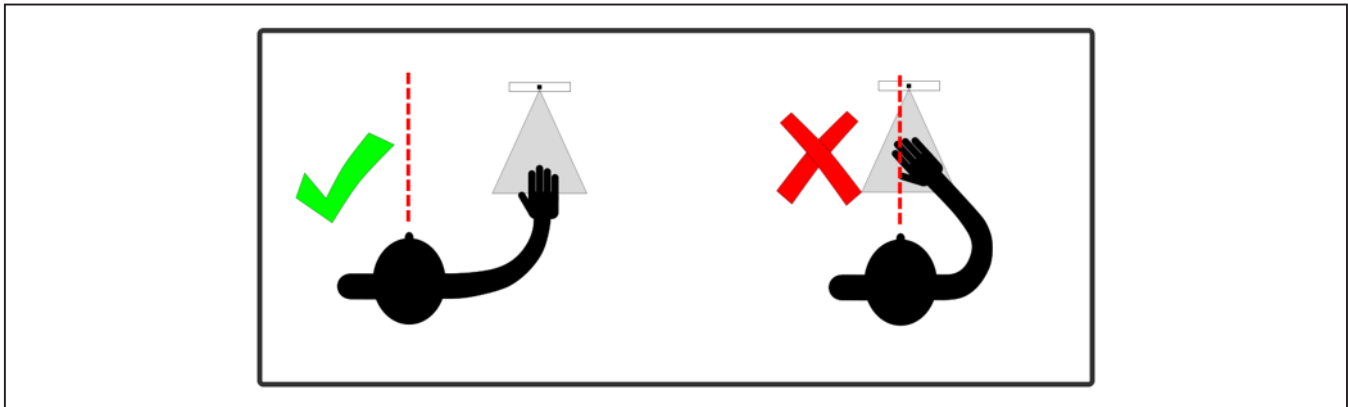

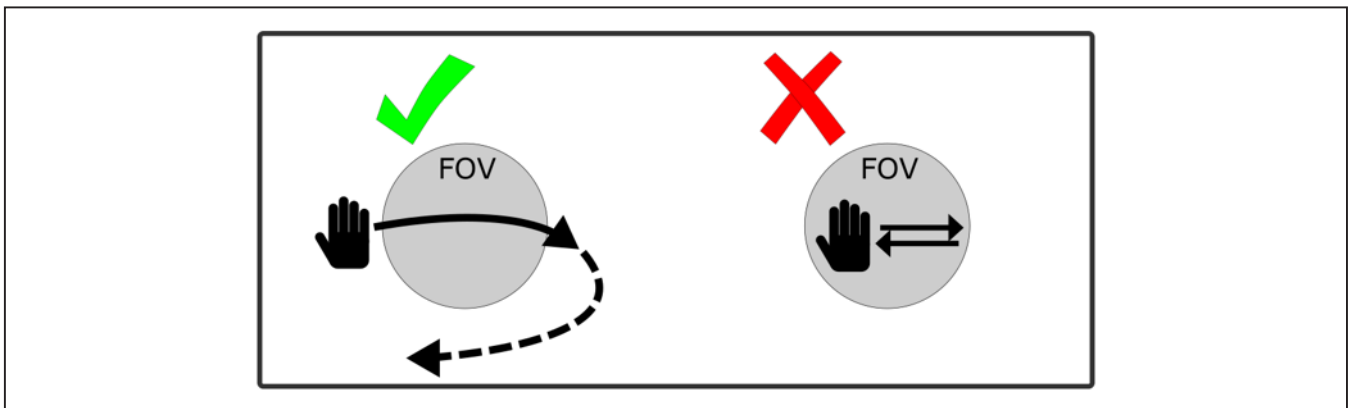*Figure 5. Correct Sensor Position, Directed to Side of Body*

Figure 6. Horizontal Swipes

The sensor should be positioned to the right of the body, not aimed directly at the torso. This allows gestures to be made naturally with the hand positioned off to the side. The sensor position with respect to the body should be similar to how it would be configured in the car, with the sensor mounted just above the infotainment display in the center console, to the right of the driver (see Figure 5).

Gestures should be made in a single, smooth motion, with the hand entering the field of view at the beginning of the gesture and exiting the field of view at completion of the gesture.

Figure 6 shows the correct way to perform left/right swipe gestures. The palm should be perpendicular to the sensor.

Figure 7 shows the correct way to perform up/down swipe gestures. The hand must enter and then exit the field of view and then not re-enter the field of view, to indicate completion of the gesture. The palm or the back of the hand should be perpendicular to the sensor.

Figure 8 shows the correct way to perform rotations. The rotation should be drawn with at least two fingers. The circle of rotation should be about 10cm in diameter, with the entire circle gesture performed within the field of view.
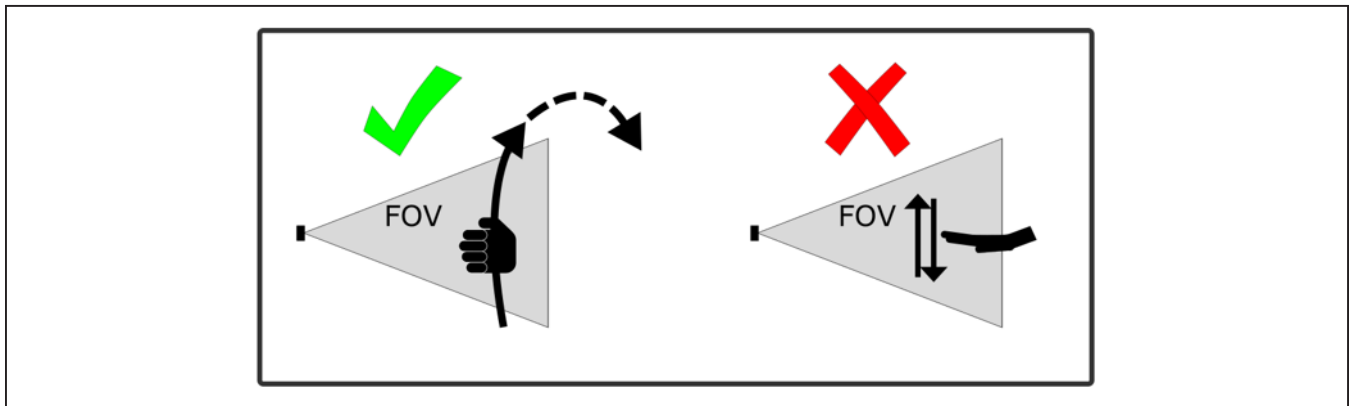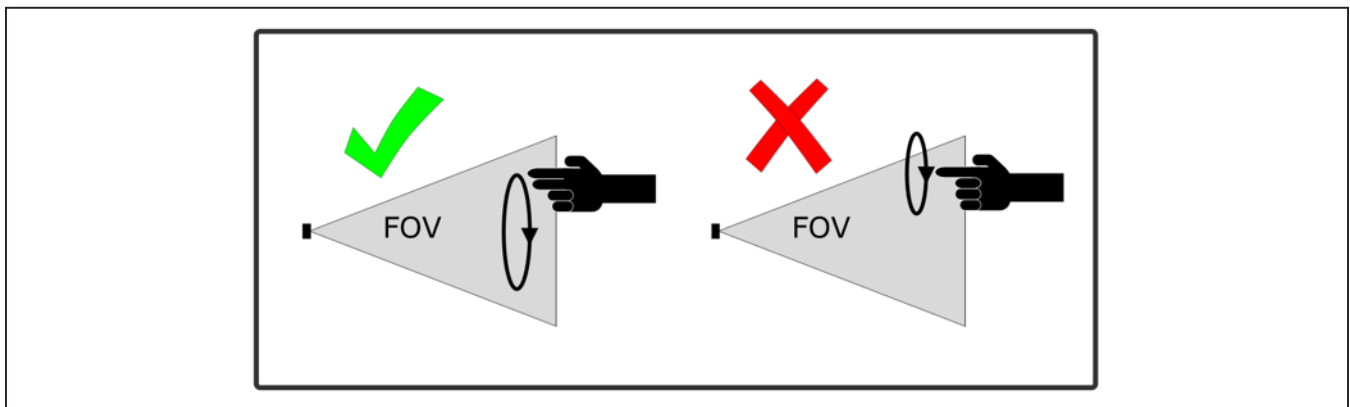

Figure 7. Vertical Swipes

Figure 8. Rotations

Supported Gestures

GESTURE	DESCRIPTION	ICON
Swipes	Swipe gestures can be made in four directions: right, left, up, and down. Swipes are indicated by a chevron pointed in the direction of the swipe.	
Rotation	Rotations can be made in the clockwise or counter-clockwise direction. Rotation is indicated by a dial graphic. A full rotation event is indicated by incrementing or decrementing the number shown on the dial. In addition, continuous rotation is indicated by the status bar going around the dial. By selecting the **Analog Dial** checkbox, the displayed rotation amount is scaled by the gear ratio value, which allows fine control over the dial setting.	
Air Click	An air-click gesture is performed by bringing the palm of the hand directly toward the sensor and then directly away from the sensor in one quick smooth motion. The air click is indicated by a small filled circle.	
Wave	A wave gesture is performed by swiping to the right across at least half of the FOV, then left at least 10cm, then right again to exit the FOV.	

Error Events

EVENT	DESCRIPTION	ICON
Gesture Error	An unresolved or ambiguous gesture that remains in the field of view beyond the specified maximum gesture duration is indicated by the X icon. To clear the error, simply remove the hand from the field of view.	
Sunlight Rejection	This fault state occurs when intense direct sunlight is detected on the sensor. The algorithm rejects sensor frames while this fault state is active. This capability reduces the possibility of false positives due to invalid pixel readings. The fault state is automatically cleared after direct sunlight is no longer detected.	

EV Kit System Functionality and Block Diagram

The EV kit uses a MAX32620FTHR (ARM Cortex-M4F) microcontroller platform to perform the following functions:

- Serial communications to the MAX25405 to configure the sensor and read back sensor data.

- Monitor interrupts from the MAX25405.

- Run the gesture recognition algorithm.

- Packetize the sensor data and gesture results, and stream data to the PC over the USB serial port.

The interface board connects the MCU and the sensor board and provides power to the MAX25405 and external LEDs.
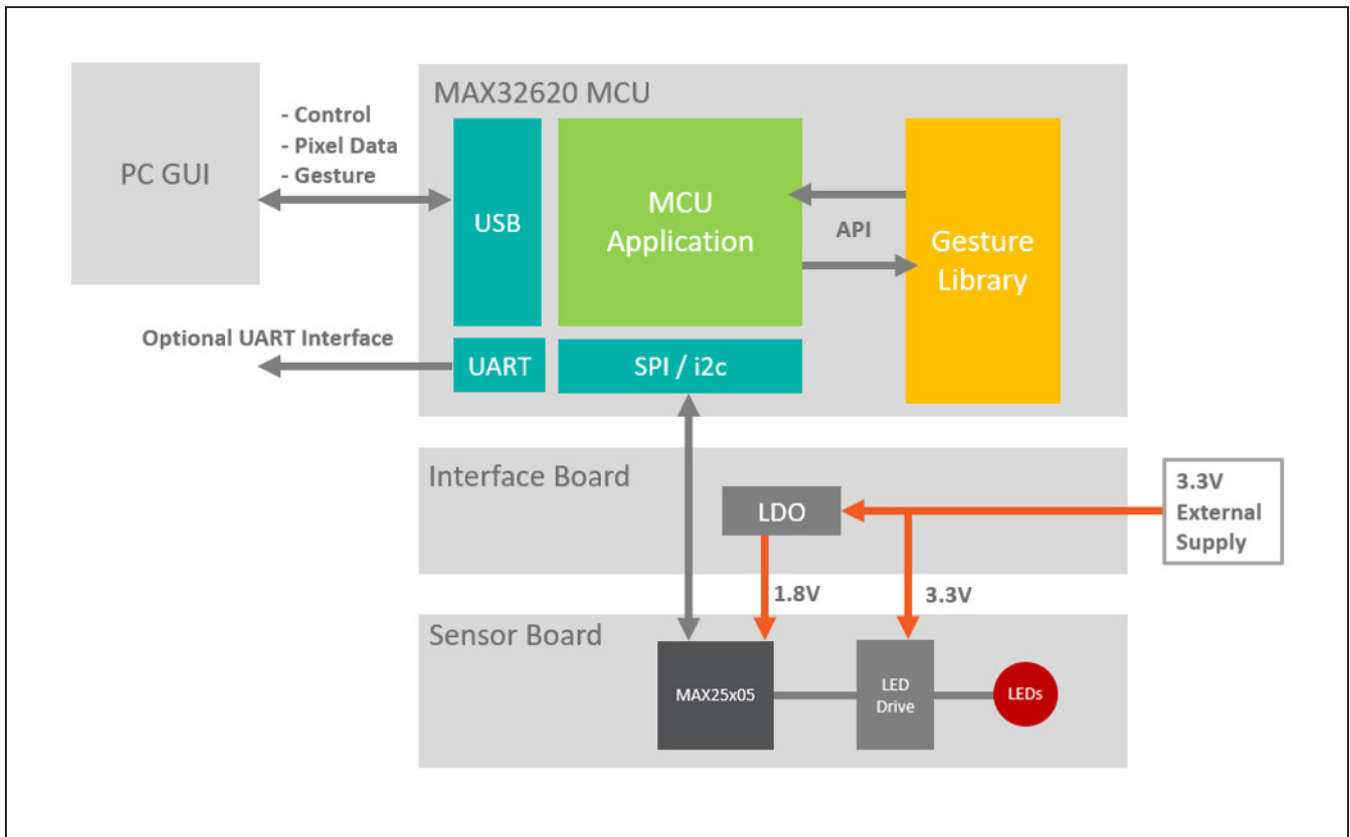

Figure 9. System Diagram

Updating Firmware

The gesture firmware on the MAX32620FTHR can be updated with the following procedure.

1) Connect the MAX32620FTHR to the PC with a USB cable.

2) Open a **File Explorer** window on the PC.

3) Enter the bootloader mode on the MAX32620FTHR by holding the BOOT button down and simultaneously pressing and releasing the RESET button. Release the BOOT button to complete the operation.

4) The MAX32620FTHR appears as **BOOTLOADER** drive in the **File Explorer** directory heirarchy.

5) Drag and drop the firmware .bin file into the **BOOTLOADER** drive. The MAX32620FTHR blinks its LEDs while it updates the firmware.

6) Once the blinking stops, press the RESET button or disconnect and reconnect the USB to restart the MCU.

Troubleshooting

If the software fails to connect to the sensor, check the **Device Manager** to determine if the driver was installed properly. When the EV kit is connected to the PC, the device should show up under the **Ports** section as **Maxim Serial Port**.

Manual connection to the EV kit can be performed under the **Device Menu**.
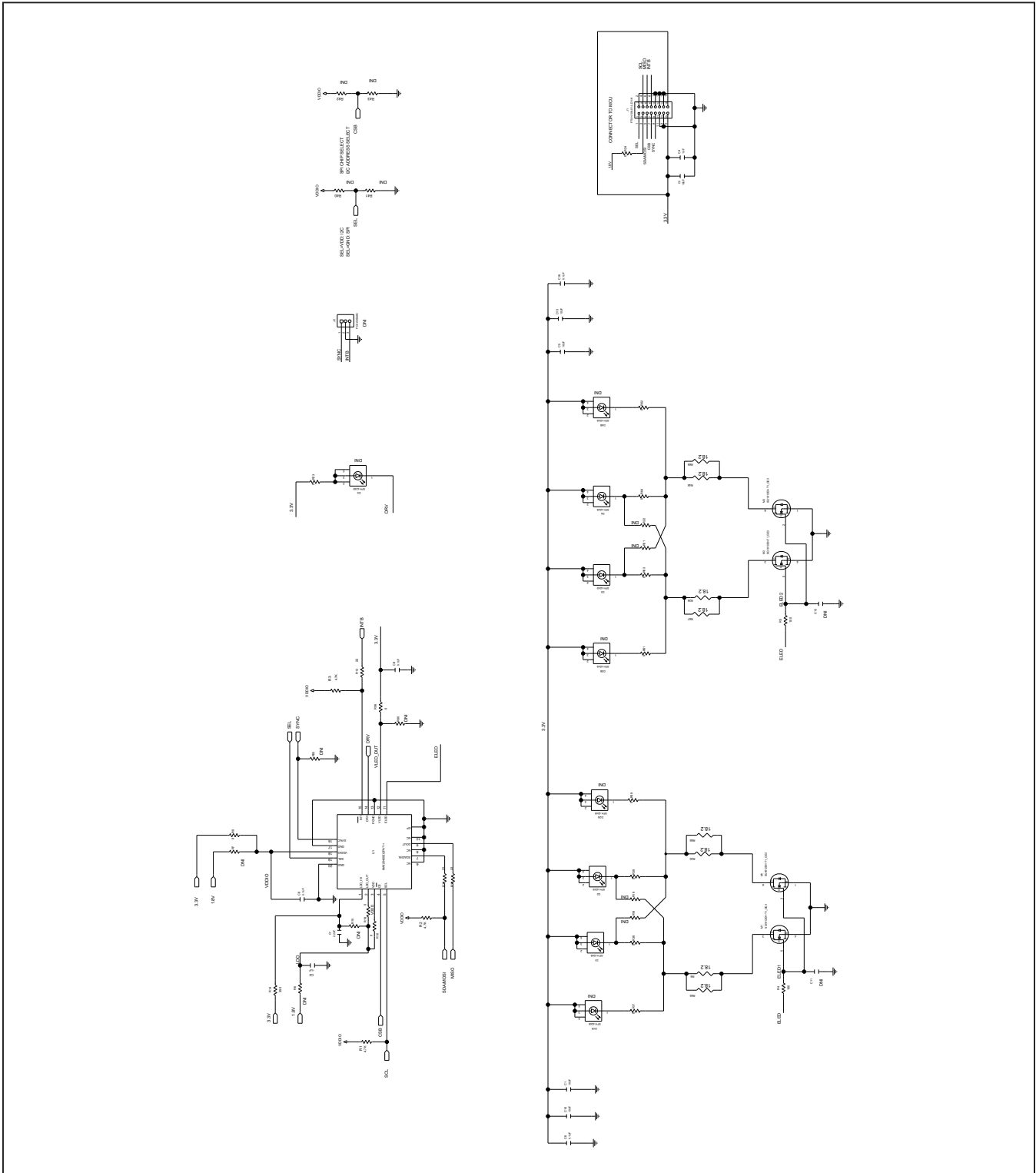
Ordering Information

PART	TYPE
MAX25405EVKIT#	EV Kit

#Denotes RoHS compliance.

MAX25405 EV Kit Bill of Materials

| ITEM	REF_DES	DNI/DNP	QTY	MFG PART #	MANUFACTURER	VALUE	DESCRIPTION	COMMENTS
1	C1, C3, C5, C10, C15	-	5	CL21B106KOQNNN; GRM21BZ71C106KE15; GMC21X7R106K16NT	SAMSUNG;MURATA;CAL-CHIP	10UF	CAP; SMT (0805); 10UF; 10%; 16V; X7R; CERAMIC	
2	C2, C4	-	2	UMK107BJ105KA; C1608X5R1H105K080AB; CL10A105KB8NNN; GRM188R61H105KAAL	TAIYO YUDEN;TDK; SAMSUNG;MURATA	1UF	CAP; SMT (0603); 1UF; 10%; 50V; X5R; CERAMIC	
3	C6, C8, C9, C16	-	4	885012206071; C1608X7R1E104K080AA; C0603C104K3RAC; GRM188R71E104KA01; C1608X7R1E104K; 06033C104KAT2A	WURTH ELECTRONICS INC; TDK;KEMET;MURATA;TDK;AVX	0.1UF	CAP; SMT (0603); 0.1UF; 10%; 25V; X7R; CERAMIC	
4	C7	-	1	C1608X5R1E225K; TMK107ABJ225KA; TMK107BJ225KA; GRM188R61E225KA12	TDK;TAIYO YUDEN;TAIYO YUDEN;MURATA	2.2UF	CAP; SMT (0603); 2.2UF; 10%; 25V; X5R; CERAMIC	
5	D1, D4	-	2	SFH 4248	OSRAM	SFH 4248	DIODE; LED; INFRARED EMITTER; INFRARED; SMT; PIV=1.5V; IF=0.1A; -40 DEGC TO +100 DEGC	
6	D2, D3	-	2	SFH 4249	OSRAM	SFH 4249	DIODE; LED; INFRARED EMITTER; INFRARED; SMT; PIV=5.0V; IF=0.1A; -40 DEGC TO +100 DEGC	
7	J1	-	1	FTSH-108-01-L-DV-K	SAMTEC	FTSH-108-01-L-DV-K	CONNECTOR; MALE; SMT; MICRO HEADER; STRAIGHT; 16PINS	
8	M1, M2	-	2	SQ1912EH-T1_GE3	VISHAY SILICONIX	SQ1912EH-T1_GE3	TRAN; NCH; SC70-6; PD-(1.5W); I-(0.8A); V-(20V)	
9	MISC1	-	1	KTPS12-03320WA-VI-P1	VOLGEN	KTPS12-03320WA-VI-P1	ACCESSORY; ADAPTER; UNIVERSAL INPUT; WALL MOUNT ADAPTER	
10	MISC2	-	1	FFSD-08-D-06.00-01-N	SAMTEC	FFSD-08-D-06.00-01-N	CONNECTOR; FEMALE; TIGER EYE FLAT IDC WIRE CABLE; WIREMOUNT; 16PINS	
11	R1-R3	-	3	CRCW06034K70FK	VISHAY DALE	4.7K	RES; SMT (0603); 4.7K; 1%; +/-100PPM/DEGC; 0.1000W	
12	R4, R5	-	2	CRCW0603100RJN; ERJ-3GEYJ101	VISHAY DALE;PANASONIC	100	RES; SMT (0603); 100; 5%; +/-200PPM/DEGK; 0.1000W	
13	R8, R10, R17, R18, R23, R24, R38, R58, R59, R61-R64	-	13	CRCW06030000Z0	VISHAY DALE	0	RES; SMT (0603); 0; JUMPER; JUMPER; 0.1000W	
14	R9, R20, R28, R48, R65-R68	-	8	ERJ-8ENF18R2	PANASONIC	18.2	RES; SMT (1206); 18.2; 1%; +/-100PPM/DEGK; 0.2500W	
15	R11-R13	-	3	CRCW060322R0FK	VISHAY	22	RES; SMT (0603); 22; 1%; +/-100PPM/DEGC; 0.1000W	
16	R14	-	1	CRCW0603390RFK	VISHAY DALE	390	RES; SMT (0603); 390; 1%; +/-100PPM/DEGC; 0.1000W	
17	R56	-	1	CRCW08050000Z0EAHP; HCJ0805ZT0R00	VISHAY;STACKPOLE ELECTRONICS INC.	0	RES; SMT (0805); 0; JUMPER; JUMPER; 0.5000W	
18	U1	-	1	MAX25405EQP/VY+	MAXIM	MAX25405EQP/VY+	EVKIT PART - IC; GESTURE SENSOR FOR AUTOMOTIVE APPLICATIONS; OCQFN20-EP 4MM X 4MM X 1.40MM; 0.5MM PITCH; PACKAGE OUTLINE DRAWING: 21-100404; PACKAGE LAND PATTERN: 90-100083; PACKAGE CODE: Q2044Y+2	
19	PCB	-	1	MAX25405_SENSORBOARD_APPS_A	MAXIM	PCB	PCB:MAX25405_SENSORBOARD_APPS_A	-
20	C11, C13	DNP	0	C0402C100J5GAC; GRM1555C1H100JA01	KEMET;MURATA	10PF	CAP; SMT (0402); 10PF; 5%; 50V; C0G; CERAMIC	DNI
21	D1B, D4B	DNP	0	SFH 4248	OSRAM	SFH 4248	DIODE; LED; INFRARED EMITTER; INFRARED; SMT; PIV=1.5V; IF=0.1A; -40 DEGC TO +100 DEGC	DNI
22	D2B, D3B, D5	DNP	0	SFH 4249	OSRAM	SFH 4249	DIODE; LED; INFRARED EMITTER; INFRARED; SMT; PIV=5.0V; IF=0.1A; -40 DEGC TO +100 DEGC	DNI
23	J2	DNP	0	PCC03SAAN	SULLINS	PCC03SAAN	CONNECTOR; MALE; THROUGH HOLE; BREAKAWAY; STRAIGHT THROUGH; 3PINS; -65 DEGC TO +125 DEGC	DNI
24	R6, R7, R15, R16, R19, R21, R22, R40-R43, R60	DNP	0	CRCW06030000Z0	VISHAY DALE	0	RES; SMT (0603); 0; JUMPER; JUMPER; 0.1000W	DNI
25	R55	DNP	0	CRCW06031K00FK; ERJ-3EKF1001; CR0603AFX-1001ELF	VISHAY; PANASONIC;BOURNS	1K	RES; SMT (0603); 1K; 1%; +/-100PPM/DEGC; 0.1000W	DNI
TOTAL			54					

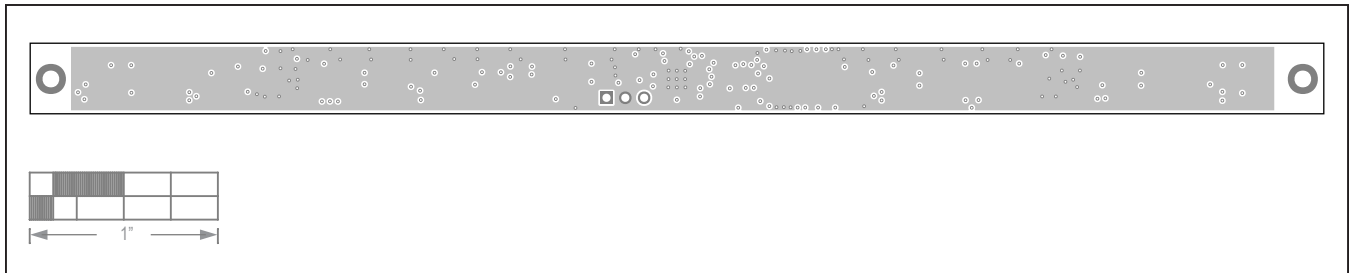## MAX25405 EV Kit Schematic

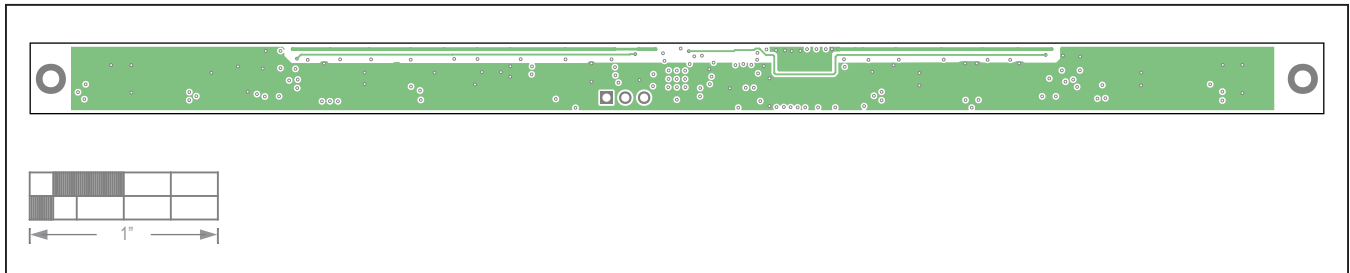## MAX25405 EV Kit PCB Layout Diagrams
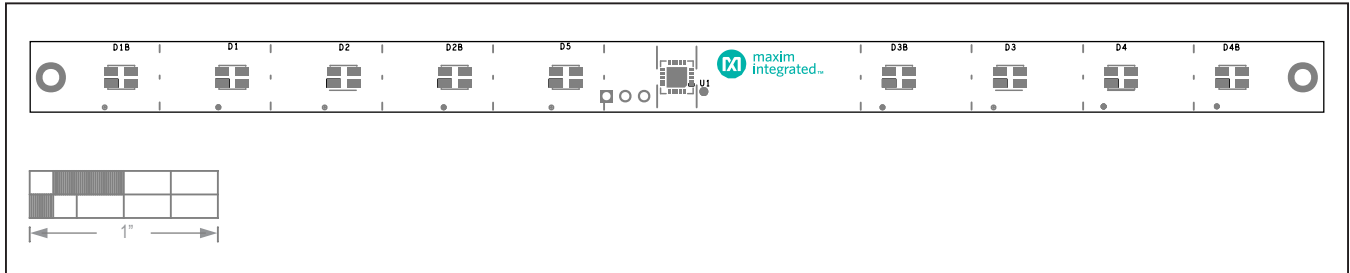
MAX25405 EV Kit PCB Layout—Silk Top
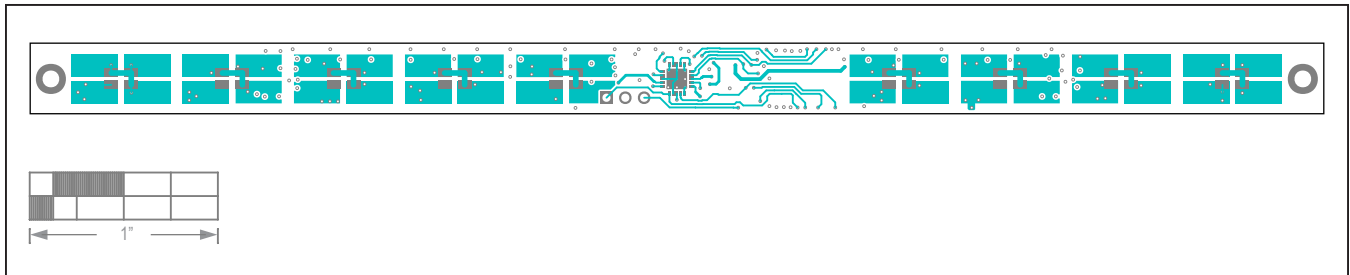
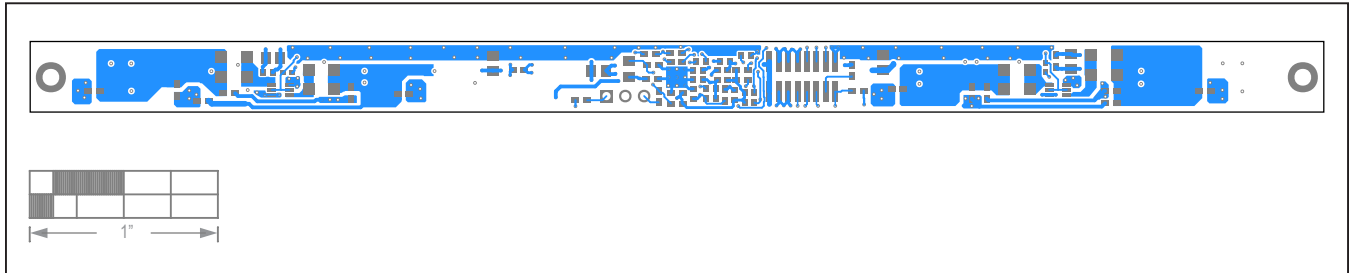*MAX25405 EV Kit PCB Layout—Top*

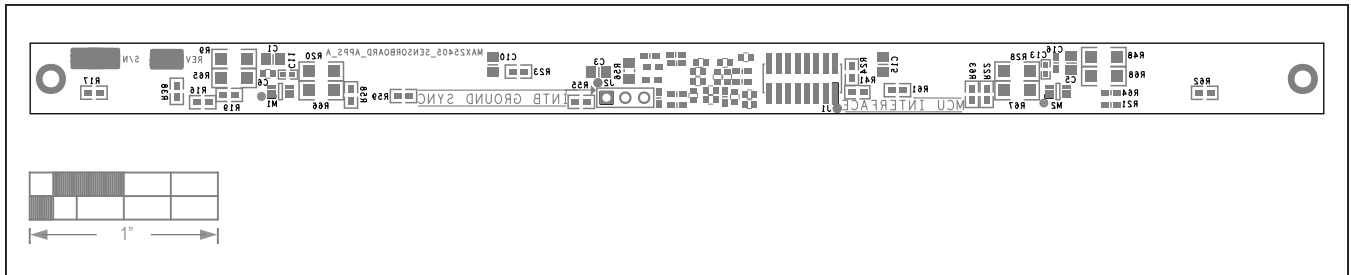*MAX25405 EV Kit PCB Layout—Layer1*

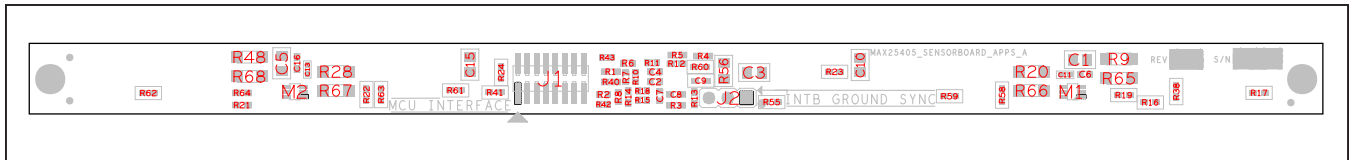

MAX25405 EV Kit PCB Layout—Layer2

MAX25405 EV Kit PCB Layout Diagrams (continued)

MAX25405 EV Kit PCB Layout—Bottom

MAX25405 EV Kit PCB Layout—Silk Bottom

MAX25405 EV Kit—Assembly Bottom

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	4/21	Initial release	—

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