



**Absolute Maximum Ratings**

V <sub>CC_</sub> to GND_.....	-0.3V to +3.9V	Junction Temperature.....	+150°C
All Other Pins to GND_.....	-0.3V to V <sub>CC_</sub> + 0.3V	Operating Temperature Range.....	-40°C to +85°C
Continuous Power Dissipation (T <sub>A</sub> = +70°C)		Storage Temperature Range.....	-65°C to +150°C
TQFN-EP Multilayer Board		Lead Temperature (soldering, 10s).....	+300°C
(derate 34.5mW/°C above +70°C).....	2758.6mW	Soldering Temperature (reflow).....	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Package Thermal Characteristics (Note 1)**

TQFN

Junction-to-Ambient Thermal Resistance (θ <sub>JA</sub> ).....	29°C/W	Junction-to-Case Thermal Resistance (θ <sub>JC</sub> ).....	1.7°C/W
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**Note 1:** Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to [www.maximintegrated.com/thermal-tutorial](http://www.maximintegrated.com/thermal-tutorial).

**DC Electrical Characteristics**

(Measured using MAX2871 EV Kit. V<sub>CC\_</sub> = 3V to 3.6V, V<sub>GND\_</sub> = 0V, f<sub>REF\_IN</sub> = 50MHz, f<sub>PFD</sub> = 50MHz, T<sub>A</sub> = -40°C to +85°C. Typical values measured at V<sub>CC\_</sub> = 3.3V; T<sub>A</sub> = +25°C; register settings (Reg 0:5) 00780000, 20000141, 01005E42, 00000013, 610F423C, 01400005; unless otherwise noted.) (Note 2)

PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Supply Voltage			3	3.3	3.6	V
RFOUT_ Current Consumption	I <sub>RFOUT_</sub> , minimum output power, single channel		9			mA
	I <sub>RFOUT_</sub> , maximum output power, single channel		25			
Supply Current	Both channels enabled, maximum output power	Total, including RFOUT, both channel (Note 3)	165	200		mA
		Each output divide-by-2	8			
		I <sub>CCVCO</sub> + I <sub>CCRF</sub> (Note 3)	122			
		Low-power sleep mode	1			

**AC Electrical Characteristics**

(Measured using MAX2871 EV Kit. V<sub>CC\_</sub> = 3V to 3.6V, V<sub>GND\_</sub> = 0V, f<sub>REF\_IN</sub> = 50MHz, f<sub>PFD</sub> = 25MHz, f<sub>RFOUT\_</sub> = 6000MHz, T<sub>A</sub> = -40°C to +85°C. Typical values measured at V<sub>CC\_</sub> = 3.3V, T<sub>A</sub> = +25°C, register settings (Reg 0:5) 00780000, 20000141, 01005E42, 00000013, 610F423C, 01400005; unless otherwise noted.) (Note 2)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
<b>REFERENCE OSCILLATOR INPUT (REF_IN)</b>					
REF_IN Input Frequency Range		10		210	MHz
REF_IN Input Sensitivity		0.7		V <sub>CC_</sub>	V <sub>P-P</sub>
REF_IN Input Capacitance			2		pF
REF_IN Input Current		-60		+60	µA
<b>PHASE DETECTOR</b>					
Phase Detector Frequency	Integer-N mode	140			MHz
	Fractional-N mode	125			

**AC Electrical Characteristics (continued)**

(Measured using MAX2871 EV Kit.  $V_{CC\_} = 3V$  to  $3.6V$ ,  $V_{GND\_} = 0V$ ,  $f_{REF\_IN} = 50MHz$ ,  $f_{PFD} = 25MHz$ ,  $f_{RFOUT\_} = 6000MHz$ ,  $T_A = -40^{\circ}C$  to  $+85^{\circ}C$ . Typical values measured at  $V_{CC\_} = 3.3V$ ,  $T_A = +25^{\circ}C$ , register settings (Reg 0:5) 00780000, 20000141, 01005E42, 00000013, 610F423C, 01400005; unless otherwise noted.) (Note 2)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
<b>CHARGE PUMP</b>					
Sink/Source Current	CP[3:0] = 1111, $R_{SET} = 5.1k\Omega$		5.12		mA
	CP[3:0] = 0000, $R_{SET} = 5.1k\Omega$		0.32		
$R_{SET}$ Range		2.7		10	k $\Omega$
<b>RF OUTPUTS</b>					
Fundamental Frequency Range		3000		6000	MHz
Divided Frequency Range	With output dividers (1/2/4/8/16/32/64/128)	23.4375		6000	MHz
VCO Sensitivity			100		MHz/V
Frequency Pushing	Open loop		0.8		MHz/V
Frequency Pulling	Open loop into 2:1 VSWR		70		kHz
2nd Harmonic	Fundamental VCO output		-40		dBc
3rd Harmonic	Fundamental VCO output		-34		dBc
2nd Harmonic	VCO output divided-by-2		-25		dBc
3rd Harmonic	VCO output divided-by-2		-20		dBc
Maximum Output Power	$f_{RFOUT\_} = 3000MHz$ (Note 4)		5		dBm
Minimum Output Power	$f_{RFOUT\_} = 3000MHz$ (Note 4)		-4		dBm
Output Power Variation (Note 4)	$-40^{\circ}C \leq T_A \leq +85^{\circ}C$		1		dB
	$3V \leq V_{CC\_} \leq 3.6V$		0.2		
Muted Output Power	(Note 4)		-40		dBm
<b>VCO AND FREQUENCY SYNTHESIZER NOISE</b>					
VCO Phase Noise (Note 5)	VCO at 3000MHz	10kHz offset		-83	dBc/Hz
		100kHz offset		-111	
		1MHz offset		-136	
		5MHz offset		-149	
	VCO at 4500MHz	10kHz offset		-77	
		100kHz offset		-106	
		1MHz offset		-132	
		5MHz offset		-147	
	VCO at 6000MHz	10kHz offset		-71	
		100kHz offset		-101	
		1MHz offset		-128	
		5MHz offset		-144	
In-Band Noise Floor	Normalized (Note 6)		-230		dBc/Hz
1/f Noise	Normalized (Note 7)		-122		dBc/Hz
In-Band Phase Noise	(Note 8)		-102		dBc/Hz
Integrated RMS Jitter	(Note 9)		0.2		ps

**AC Electrical Characteristics (continued)**

(Measured using MAX2871 EV Kit.  $V_{CC\_}$  = 3V to 3.6V,  $V_{GND\_}$  = 0V,  $f_{REF\_IN}$  = 50MHz,  $f_{PFD}$  = 25MHz,  $f_{RFOUT\_}$  = 6000MHz,  $T_A$  = -40°C to +85°C. Typical values measured at  $V_{CC\_}$  = 3.3V,  $T_A$  = +25°C, register settings (Reg 0:5) 00780000, 20000141, 01005E42, 00000013, 610F423C, 01400005; unless otherwise noted.) (Note 2)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
Spurious Signals Due to PFD Frequency	50kHz loop bandwidth		-88		dBc
VCO Tune Voltage		0.5		$V_{CC\_}$ - 0.5	V
<b>TEMPERATURE SENSOR AND ADC</b>					
ADC Resolution			7		Bits
Temperature Sensor Accuracy			3		°C

**DIGITAL I/O CHARACTERISTICS**

( $V_{CC\_}$  = +3V to +3.6V,  $V_{GND\_}$  = 0V,  $T_A$  = -40°C to +85°C. Typical values at  $V_{CC\_}$  = 3.3V,  $T_A$  = +25°C.) (Note 2)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
<b>SERIAL INTERFACE INPUTS (CLK, DATA, LE, CE, RFOUT_EN)</b>					
Input Logic-Level Low	$V_{IL}$		0.4		V
Input Logic-Level High	$V_{IH}$		1.5		V
Input Current	$I_{IH}/I_{IL}$	-1		+1	μA
Input Capacitance			1		pF
<b>SERIAL INTERFACE OUTPUTS (MUX, LD)</b>					
Output Logic-Level Low	0.3mA sink current			0.4	V
Output Logic-Level High	0.3mA source current	$V_{CC\_}$ - 0.4			V
Output Current Level High			0.5		mA

**SPI TIMING CHARACTERISTICS**(V<sub>CC\_</sub> = +3V to +3.6V, V<sub>GND\_</sub> = 0V, T<sub>A</sub> = -40°C to +85°C. Typical values at V<sub>CC\_</sub> = 3.3V, T<sub>A</sub> = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CLK Clock Period	t <sub>CP</sub>	Guaranteed by CLK pulse-width low and high	50			ns
CLK Pulse-Width Low	t <sub>CL</sub>		25			ns
CLK Pulse-Width High	t <sub>CH</sub>		25			ns
LE Setup Time	t <sub>LES</sub>		20			ns
LE Hold Time	t <sub>LEH</sub>		10			ns
LE Minimum Pulse-Width High	t <sub>LEW</sub>		20			ns
DATA Setup Time	t <sub>DS</sub>		25			ns
DATA Hold Time	t <sub>DH</sub>		25			ns
MUX Valid	t <sub>DOT</sub>	MUX transition valid after CLK rise			10	ns

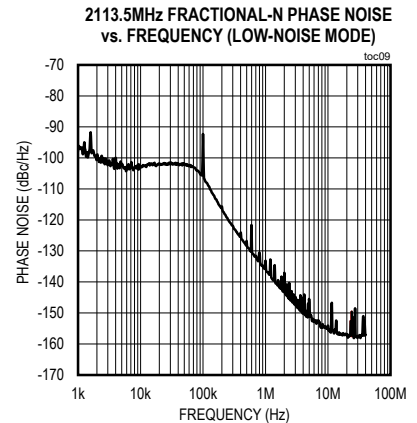
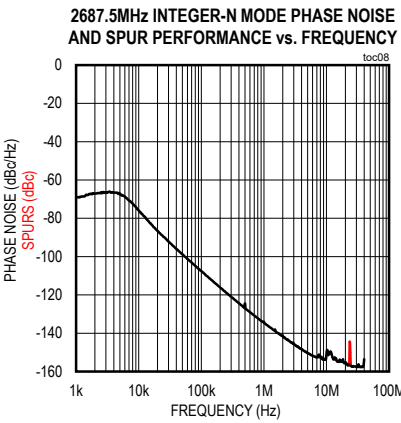
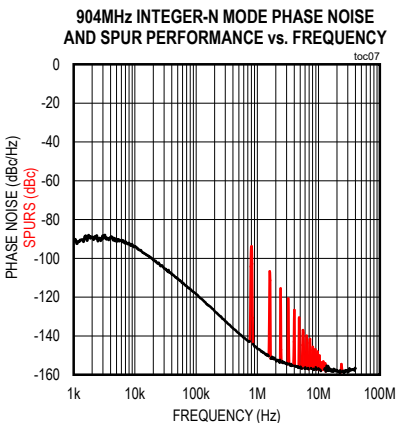
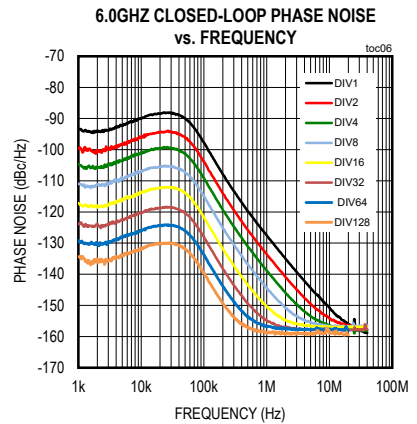
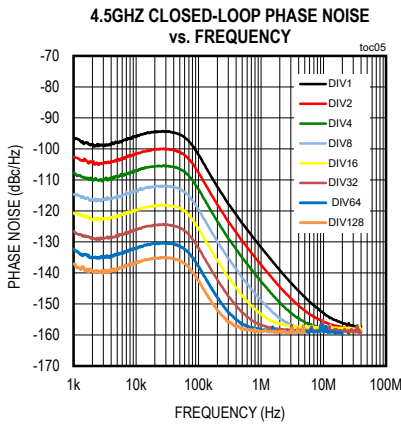
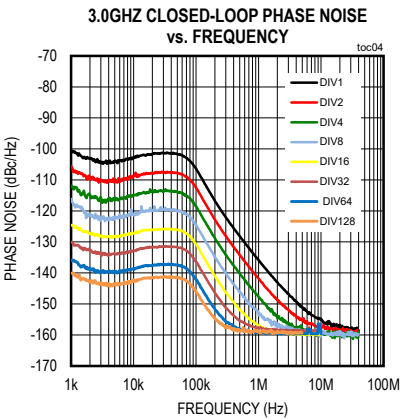
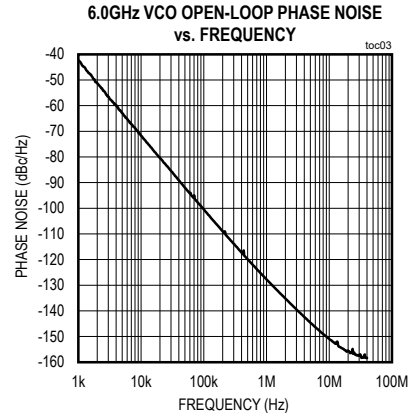
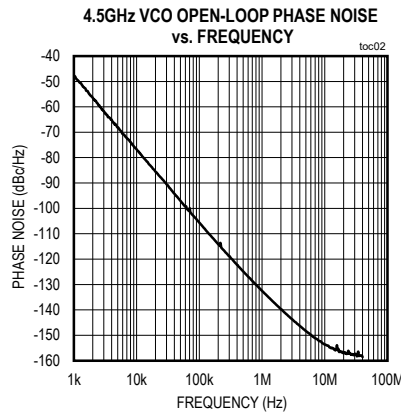
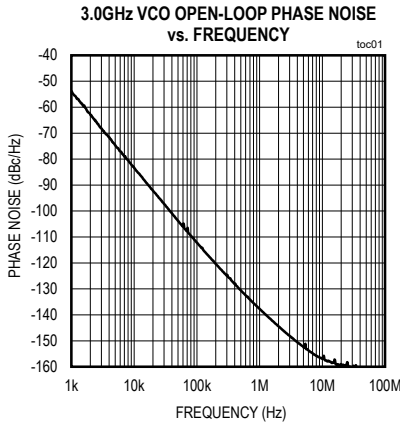
**Note 2:** Production tested at T<sub>A</sub> = +25°C. Cold and hot are guaranteed by design and characterization.**Note 3:** f<sub>REF\_IN</sub> = 100MHz, phase detector frequency = 25MHz, RF output = 6000MHz.

Register setting: 00780000, 00400061, 34011242, F8010003, 638FF1FC, 80400005.

**Note 4:** Measured single ended with 27nH to V<sub>CC\_RF</sub> into 50Ω load. Power measured with single output enabled. Unused output has 27nH to V<sub>CC\_RF</sub> with 50Ω termination.**Note 5:** VCO phase noise is measured open loop.**Note 6:** Measured at 200kHz using a 50MHz Billely NV108C19554 OCVCXO with 2MHz loop bandwidth. Register setting 801E0000, 8000FFF9, 80005FC2, 6C10000B, 638E80FC, 400005. EV kit loop filter: C2 = 1500pF, C1 = 33pF, R2A = 0Ω, R2B = 1100Ω, R3 = 0Ω, C3 = open.**Note 7:** 1/f noise contribution to the in-band phase noise is computed by using 1/f noise + 10log(10kHz/f<sub>OFFSET</sub>) + 20log(f<sub>RF</sub>/1GHz). Register setting: 803A0000, 8000FFF9, 81005F42, F4000013, 6384803C, 001500005.**Note 8:** f<sub>REF\_IN</sub> = 50MHz; f<sub>PFD</sub> = 25MHz; offset frequency = 10kHz; VCO frequency = 4227MHz, output divide-by-2 enabled. RFOUT = 2113.5MHz; N = 169; loop BW = 40kHz, CP[3:0] = 1111; integer mode.**Note 9:** f<sub>REF\_IN</sub> = 50MHz; f<sub>PFD</sub> = 50MHz; VCO frequency = 4400MHz, f<sub>RFOUT</sub> = 4400MHz; loop BW = 65kHz. Register setting: 002C0000, 200303E9, 80005642, 00000133, 638E82FC, 01400005. EV kit loop filter: C2 = 0.1μF, C1 = 0.012μF, R2A = 0Ω, R2B = 120Ω, R3 = 250Ω, C3 = 820pF.

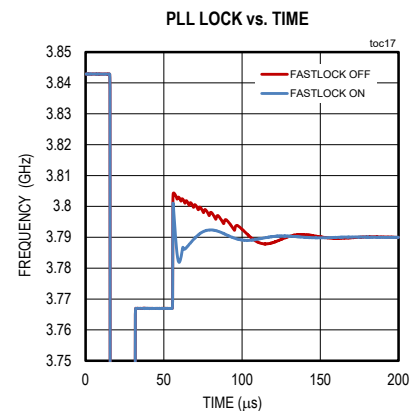
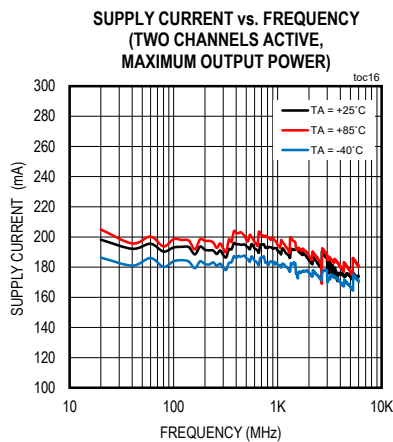
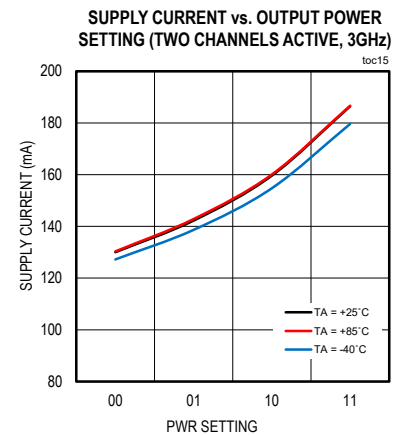
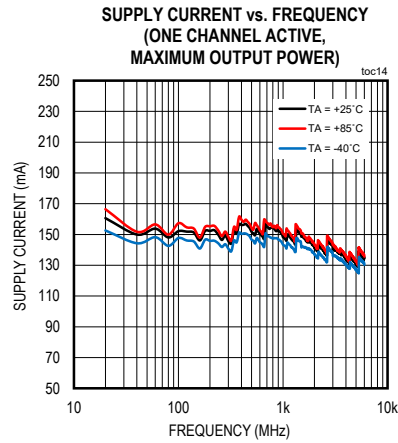
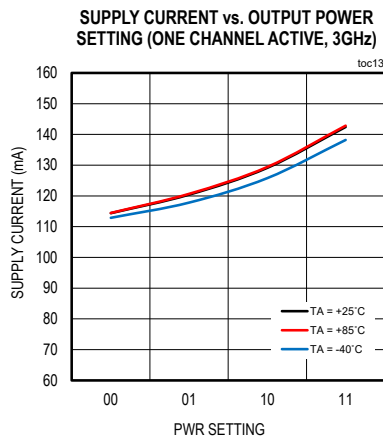
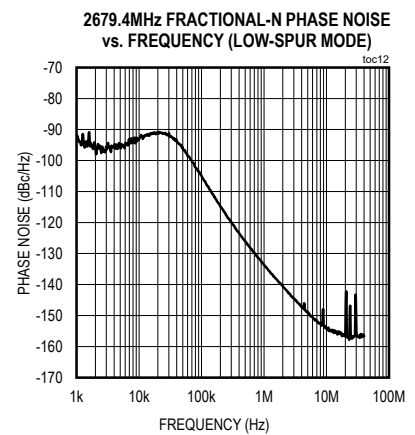
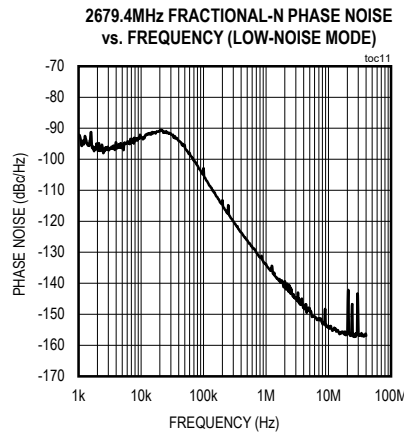
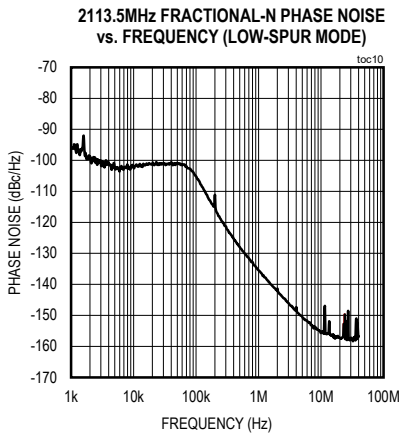
Typical Operating Characteristics

(Measured with MAX2871 EV Kit.  $V_{CC\_} = 3.3V$ ,  $V_{GND\_} = 0V$ ,  $f_{REF\_IN} = 50MHz$ ,  $T_A = +25^\circ C$ , see the [Typical Operating Characteristics Testing Conditions Table](#) Table.)



Typical Operating Characteristics (continued)

(Measured with MAX2871 EV Kit.  $V_{CC\_} = 3.3V$ ,  $V_{GND\_} = 0V$ ,  $f_{REF\_IN} = 50MHz$ ,  $T_A = +25^{\circ}C$ , see the [Typical Operating Characteristics Testing Conditions Table](#) Table.)



## Typical Operating Characteristics Testing Conditions Table

TOC TITLE	f <sub>REF</sub> (MHz)	f <sub>PPD</sub> (MHz)	REGISTER SETTINGS (hex)	LOOP FILTER BW (Hz)	MAX2871 EV KIT COMPONENT VALUES					COMMENTS
					C2 (F)	R2A + R2B (Ω)	C1 (F)	R3 (Ω)	C3 (F)	
3.0GHz VCO OPEN-LOOP PHASE NOISE vs. FREQUENCY	N/A	N/A	80B40000, 80000141, 0000405A, XX00013, 648020FC, 00000005	N/A	N/A	N/A	N/A	N/A	N/A	VCO bits set for 3GHz output, VAS_SHDN = 1
4.5GHz VCO OPEN-LOOP PHASE NOISE vs. FREQUENCY	N/A	N/A	80B40000, 80000141, 0000405A, XX00013, 648020FC, 00000005	N/A	N/A	N/A	N/A	N/A	N/A	VCO bits set for 4.5GHz output, VAS_SHDN = 1
6.0GHz VCO OPEN-LOOP PHASE NOISE vs. FREQUENCY	N/A	N/A	80B40000, 80000141 0000405A XX00013, 648020FC 00000005	N/A	N/A	N/A	N/A	N/A	N/A	VCO bits set for 6.0GHz output, VAS_SHDN = 1
3.0GHz CLOSED-LOOP PHASE NOISE vs. FREQUENCY	50	25	803C0000 80000141 00009E42, E8000013, 618160FC, 00400005	40k	0.1μ	120	0.012μ	250	820p	
4.5GHz CLOSED-LOOP PHASE NOISE vs. FREQUENCY	50	25	805A0000, 80000141, 00009E42, E8000013, 618160FC, 00400005	40k	0.1μ	120	0.012μ	250	820p	
6.0GHz CLOSED-LOOP PHASE NOISE vs. FREQUENCY	50	25	80780000, 80000141, 00009E42, EA000013, 608C80FC, 00400005	40k	0.1μ	120	0.012μ	250	820p	



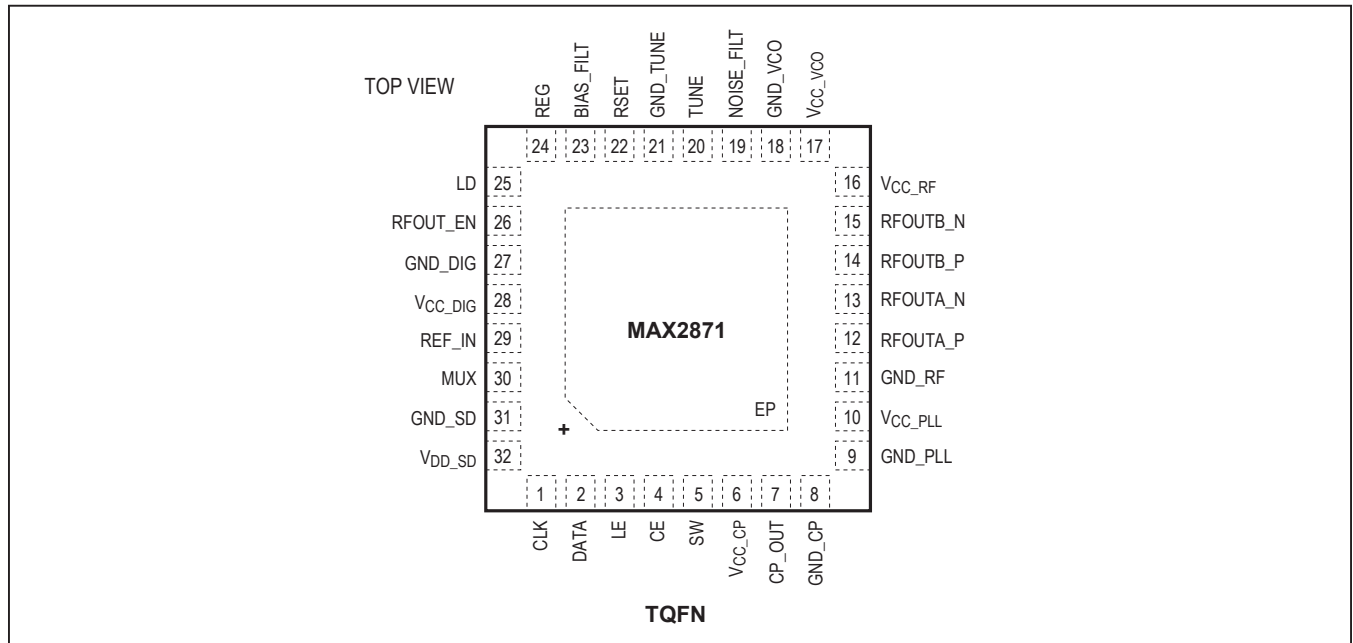
Typical Operating Characteristics Testing Conditions Table (continued)

TOC TITLE	f <sub>REF</sub> (MHz)	f <sub>PFD</sub> (MHz)	REGISTER SETTINGS (hex)	LOOP FILTER BW (Hz)	MAX2871 EV KIT COMPONENT VALUES S					COMMENTS
					C2 (F)	R2A + R2B (Ω)	C1 (F)	R3 (Ω)	C3 (F)	
904MHz INTEGER-N MODE PHASE NOISE AND SPUR PERFORMANCE vs. FREQUENCY	40	0.8	82350000, 800007D1 E1065FC2, 2C000013 6020803C 00400005	16k	0.1μ	806	3300p	1201	470p	
2687.5MHz INTEGER-N PHASE NOISE AND SPUR PERFORMANCE vs. FREQUENCY	40	0.5	94FF0000, 803207D1, 010A1E42, B00000A3, 6090803C, 00400005	5k	0.1μ	1000	6800p	300	0.01μ	
2113.5MHz FRACTIONAL-N PHASE NOISE (LOW-NOISE MODE) vs. FREQUENCY	50	25	00548050, 400003E9, 81005FC2, E8000013, 609C80FC, 00400005	40k	0.1μ	120	0.012μ	250	820p	
2113.5MHz FRACTIONAL-N PHASE NOISE vs. FREQUENCY (LOW-SPUR MODE)	50	25	00548050, 400003E9, E1005FC2, E8000013, 609C80FC, 00400005	40k	0.1μ	120	0.012μ	250	820p	
2679.4MHz FRACTIONAL-N PHASE NOISE vs. FREQUENCY (LOW-NOISE MODE)	50	25	00358160, 203207D1, 01005E42, B20000A3, 6010003C, 00400005	40k	0.1μ	120	0.012μ	250	820p	
2679.4MHz FRACTIONAL-N PHASE NOISE vs. FREQUENCY (LOW-SPUR MODE)	50	25	00358160, 203207D1, 41005E42, B20000A3, 6010003C, 00400005	40k	0.1μ	120	0.012μ	250	820p	
SUPPLY CURRENT vs. OUTPUT POWER SETTING (ONE CHANNEL ACTIVE, 3GHz)	50	25	003C0000, 20000321, 01005E42, 00000013, 610F423C, 01400005,							APWR swept from 00 to 11

## Typical Operating Characteristics Testing Conditions Table (continued)

TOC TITLE	f <sub>REF</sub> (MHz)	f <sub>PDF</sub> (MHz)	REGISTER SETTINGS (hex)	LOOP FILTER BW (Hz)	MAX2871 EV KIT COMPONENT VALUES					COMMENTS
					C2 (F)	R2A + R2B (Ω)	C1 (F)	R3 (Ω)	C3 (F)	
SUPPLY CURRENT vs. FREQUENCY (ONE CHANNEL ACTIVE, MAXIMUM OUTPUT POWER)	50	25	003C0000, 20000321, 01005E42, 00000013, 610F423C, 01400005							N and F values changed for each frequency
SUPPLY CURRENT vs. OUTPUT POWER SETTING (TWO CHANNELS ACTIVE)	50	25	003C0000, 20000321, 01005E42, 00000013, 610F43FC, 01400005							APWR and BPWR swept from 00 to 11
SUPPLY CURRENT vs. FREQUENCY (TWO CHANNELS ACTIVE MAXIMUM OUTPUT POWER)	50	25	003C0000, 20000321, 01005E42, 00000013, 610F43FC, 01400005							N and F values swept for each frequency
PLL LOCK vs. TIME	40	40	00250120, 20320141, 00004042, 000000A3, 0184023C, 01400005	40k	0.1μ	120	0.012μ	250	820p	CDM changed from 00 to 01

Pin Configuration



Pin Description

PIN	NAME	FUNCTION
1	CLK	Serial Clock Input. The data is latched into the 32-bit shift register on the rising edge of the CLK line.
2	DATA	Serial Data Input. The serial data is loaded MSB first. The 3 LSBs identify the register address.
3	LE	Load Enable Input. When LE goes high the data stored in the shift register is loaded into the appropriate latches.
4	CE	Chip Enable. A logic-low powers the part down and the charge pump becomes high impedance.
5	SW	Fast-Lock Switch. Connect to the loop filter when using the fast-lock mode. No connect in Normal mode
6	V <sub>CC_CP</sub>	Power Supply for Charge Pump. Place decoupling capacitors as close as possible to the pin.
7	CP_OUT	Charge-Pump Output. Connect to external loop filter input.
8	GND_CP	Ground for Charge-Pump. Connect to board ground, not to the paddle.
9	GND_PLL	Ground for PLL. Connect to board ground, not to the paddle.
10	V <sub>CC_PLL</sub>	Power Supply for PLL. Place decoupling capacitors as close as possible to the pin.
11	GND_RF	Ground for RF Outputs. Connect to board ground plane, not to the paddle.
12	RFOUTA_P	Open Collector Positive RF Output A. See RFOUTA± and RFOUTB± section in <a href="#">Detailed Description</a> .
13	RFOUTA_N	Open Collector Negative RF Output A. See RFOUTA± and RFOUTB± section in <a href="#">Detailed Description</a> .

## Pin Description (continued)

PIN	NAME	FUNCTION
14	RFOUTB_P	Open Collector Positive RF Output B. See RFOUTA± and RFOUTB± section in <a href="#">Detailed Description</a> .
15	RFOUTB_N	Open Collector Negative RF Output B. See RFOUTA± and RFOUTB± section in <a href="#">Detailed Description</a> .
16	V <sub>CC_RF</sub>	Power Supply for RF Output and Dividers. Place decoupling capacitors as close as possible to the pin.
17	V <sub>CC_VCO</sub>	VCO Power Supply. Place decoupling capacitors to the analog ground plane.
18	GND_VCO	Ground for VCO. Connect to main board ground plane, not directly to the paddle.
19	NOISE_FILT	VCO Noise Decoupling. Place a 1µF capacitor to ground.
20	TUNE	Control Input to the VCO. Connect to external loop filter.
21	GND_TUNE	Ground for Control Input to the VCO. Connect to main board ground plane, not directly to the paddle.
22	RSET	Charge-Pump Current Range Input. Connect an external resistor to ground to set the minimum CP current. $I_{CP} = 1.63/R_{SET} \times (1 + CP[3:0])$
23	BIAS_FILT	VCO Noise Decoupling. Place a 1µF capacitor to ground.
24	REG	Reference Voltage Compensation. Place a 1µF capacitor to ground.
25	LD	Lock Detect Output. Logic-high when locked, and logic-low when unlocked. See register description for more details ( <a href="#">Table 9</a> ).
26	RFOUT_EN	RF Output Enable. A logic-low disables the RF outputs.
27	GND_DIG	Ground for Digital Circuitry. Connect to main board ground plane, not directly to the paddle.
28	V <sub>CC_DIG</sub>	Power Supply for Digital Circuitry. Place decoupling capacitors as close as possible to pin.
29	REF_IN	Reference Frequency Input. This is a high-impedance input with a nominal bias voltage of $V_{CC\_DIG}/2$ . AC-couple to reference signal.
30	MUX	Multiplexed I/Os. See <a href="#">Table 5</a> .
31	GND_SD	Ground for Sigma-Delta Modulator. Connect to main board ground plane, not directly to the paddle.
32	V <sub>CC_SD</sub>	Power Supply for Sigma-Delta Modulator. Place decoupling capacitors as close as possible to the pin.
—	EP	Exposed Pad. Connect to board ground.

## Detailed Description

### 4-Wire Serial Interface

The MAX2871 can be controlled by 3-wire SPI for write operation using CLK, DATA, LE pins, refer [Figure 1](#). For read operation, in addition to the above 3 pins, MUX pin can be used to access Reg, 0x06, refer [Figure 2](#). The MAX2871 serial interface contains six write-only and one read-only 32-bit registers. The 29 most-significant bits (MSBs) are data, and the three least-significant bits (LSBs) are the register address. Register data is loaded MSB first through the 4-wire serial interface (SPI). When LE is logic-low, the logic level at DATA is shifted at the rising edge of CLK. At the rising edge of LE, the 29 data bits are latched into the register selected by the address bits. The user must program all register values after power-up.

Upon power-up, the registers should be programmed twice with at least a 20ms pause between cycle of write. The first write ensures that the device is enabled, and the second write starts the VCO selection process. Recommended to turn-off the outputs during this sequence and then turn-on the outputs using RFA\_EN, RFB\_EN.

For a clean clock at start up, after power on, follow this sequence of programming:

- Register 5, Address 0X05. Wait 20ms
- Register 4, set bit 5 and 8 to 0 to keep RFOUT disable.
- Register 3, Address 0X03
- Register 2, Address 0X02
- Register 1, Address 0X01
- Register 0, Address 0X00
- Register 5, Address 0X05

- Register 4, set bit 5 and 8 to 0 to keep RFOUT disable.
- Register 3, Address 0X03
- Register 2, Address 0X02
- Register 1, Address 0X01
- Register 0, Address 0X00

To enable RFOUT, Register 4, Address 0X04, set bit 5 and 8 to 1.

Register programming order should be address 0x05, 0x04, 0x03, 0x02, 0x01, and 0x00. Several bits are double buffered to update the settings at the same time. See the register descriptions for double buffered settings.

### Read Sequence

Register 0x06 can be read back through the MUX pin. The user must set MUX (register 5, bit 18 and register 2, bits 28:26) = 1100. To begin the read sequence, set LE to logic-low, send 32 periods of CLK, and set LE to logic-high. While the CLK is running, the DATA pin can be held at logic-high or logic-low for 29 clocks, but the last 3 bits must be 110 to indicate register 6, then set LE back to logic-high after the 32nd clock. Finally, send 1 period of the clock. The MSB of register 0x06 appears after the rising edge of the next clock and continues to shift out for the next 29 clock cycles ([Figure 2](#)). After the LSB of register 0x06 has been read, the user can reset MUX register = 0000.

### Power Modes

The MAX2871 can be put into low-power mode by setting SHDN = 1 (register 2, bit 5) or by setting the CE pin to logic-low. In low-power mode, all blocks except SPI are off.

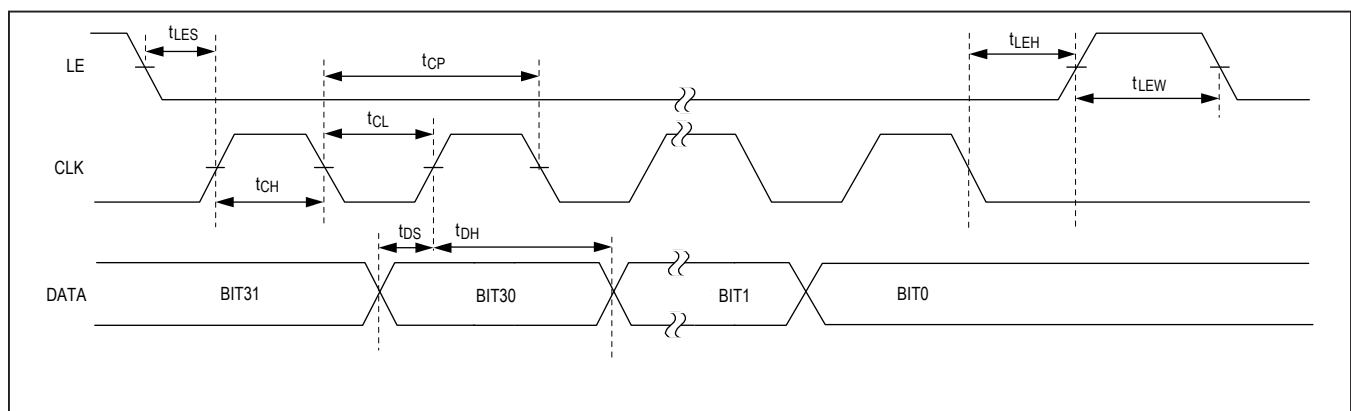


Figure 1. SPI Timing Diagram

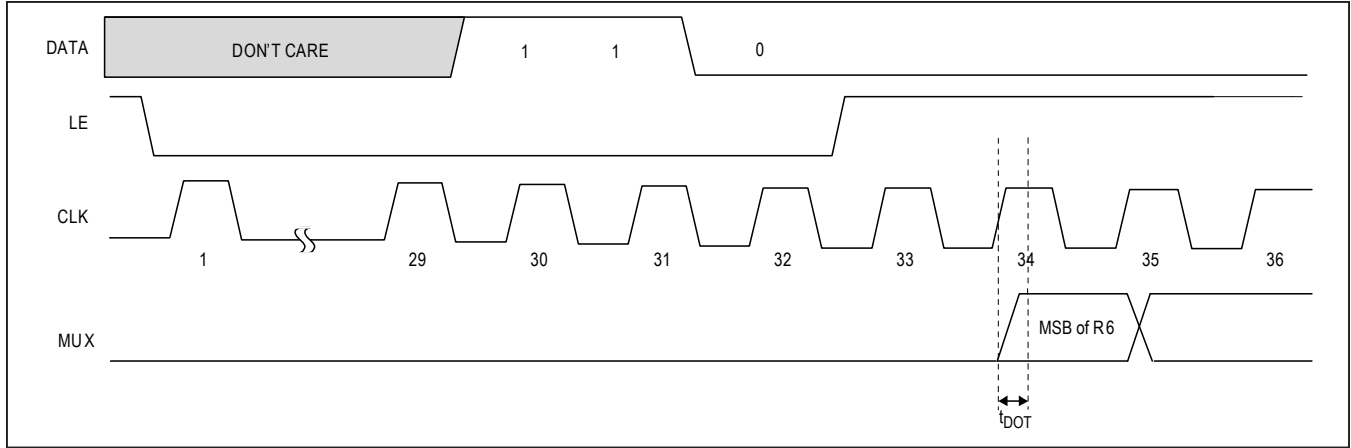


Figure 2. Initiating Readback

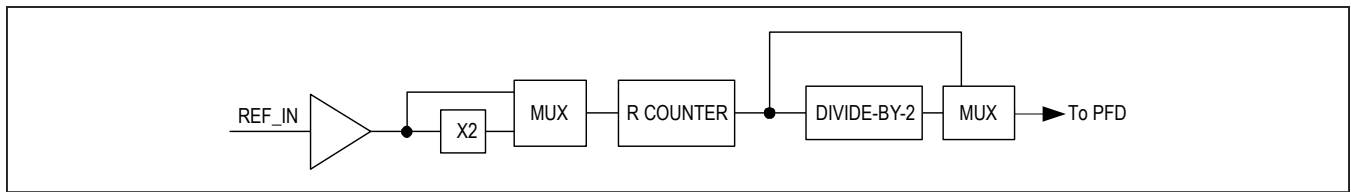


Figure 3. Reference Input

After exiting low-power mode, allow at least 20ms for external capacitors to charge to their final values before programming the final VCO frequency.

**Reference Input**

The reference input stage is configured as a CMOS inverter with shunt resistance from input to output. In shut-down mode this input is set to high impedance to prevent loading of the reference source.

The reference input signal path also includes optional x2 and ÷2 blocks. When the reference doubler is enabled (DBR = 1), the maximum reference input frequency is limited to 105MHz. When the doubler is disabled, the reference input frequency is limited to 210MHz. The minimum reference frequency is 10MHz. The minimum R counter divide ratio is 1, and the maximum divide ratio is 1023.

**PFD Frequency**

The phase-detector frequency is determined as follows:

$$f_{PFD} = f_{REF} \times [(1 + DBR)/(R \times (1 + RDIV2))]$$

$f_{REF}$  represents the external reference input frequency. DBR (register 2, bit 25) sets the  $f_{REF}$  input frequency doubler mode (0 or 1). RDIV2 (register 2, bit 24) sets the  $f_{REF}$  divide-by-2 mode (0 or 1). R (register 2, bits 23:14) is the value of the 10-bit programmable reference counter (1 to 1023). The maximum  $f_{PFD}$  is 125MHz for frac-N mode and

140MHz for int-N mode. The R-divider can be held in reset when RST (register 2, bit 3) = 1.

**Int, Frac, Mod, and R Counter Relationship**

The VCO frequency ( $f_{VCO}$ ), N, F, and M can be determined based on desired RF output frequency ( $f_{RFOUTA}$ ) as follows:

Set DIVA value property based on  $f_{RFOUTA}$  and [Table 4](#) (register 4, bits 22:20)

$$f_{VCO} = f_{RFOUTA} \times DIVA$$

If bit FB = 1, (DIVA is not in PLL feedback loop):

$$N + (F/M) = f_{VCO}/f_{PFD}$$

If bit FB = 0, (DIVA is in PLL feedback loop) and DIVA ≤ 16:

$$N + (F/M) = (f_{VCO}/f_{PFD})/DIVA$$

If bit FB = 0, (DIVA is in PLL feedback loop) and DIVA > 16:

$$N + (F/M) = (f_{VCO}/f_{PFD})/16$$

N is the value of the 16-bit N counter (16 to 65535), programmable through bits 30:15 of register 0. M is the fractional modulus value (2 to 4095), programmable through bits 14:3 of register 1. F is the fractional division value (0 to MOD - 1), programmable through bits 14:3 of register 0. In frac-N mode, the minimum N value is 19 and maximum

N value is 4091. The N counter is held in reset when RST = 1 (register 2, bit 3). DIVA is the RF output divider setting (0 to 7), programmable through bits 22:20 of register 4. The division ratio is set by  $2^{DIVA}$ .

The RF B output frequency is determined as follows:

If BDIV = 0 (register 4, bit 9),  $f_{RFOUTB} = f_{RFOUTA}$ .

If BDIV = 1,  $f_{RFOUTB} = f_{VCO}$ .

### Int-N/Frac-N Modes

Integer-N mode is selected by setting bit INT = 1 (register 0, bit 31). When operating in integer-N mode, it is also necessary to set bit LDF (register 2, bit 8) to set the lock detect to integer-N mode.

The device's frac-N mode is selected by setting bit INT = 0 (register 0, bit 31). Additionally, set bit LDF = 0 (register 2, bit 8) for frac-N lock-detect mode.

If the device is in frac-N mode, it will remain in frac-N mode when fractional division value F = 0, which can result in unwanted spurs. To avoid this condition, the device can automatically switch to integer-N mode when F = 0 if the bit F01 = 1 (register 5, bit 24).

### Phase Detector and Charge Pump

The device's charge-pump current is determined by the value of the resistor from pin RSET to ground and the value of bits CP (register 2, bits 12:9) as follows:

$$I_{CP} = 1.63/R_{SET} \times (1 + CP_{<3:0>})$$

To reduce spurious in frac-N mode, set charge-pump linearity bits CPL = 00/01/10/11 (register 1, bits 30:29). The user can determine which mode works best for their application. For int-N mode, set CPL = 00.

The charge-pump output can be put into high-impedance mode when TRI = 1 (register 2, bit 4). The output is in normal mode when TRI = 0.

The phase detector polarity can be changed if an active inverting loop filter topology is used. For noninverting loop filters, set PDP = 1 (register 2, bit 6). For inverting loop filters, set PDP = 0.

### MUX

MUX is a multipurpose input/output for observing and controlling various internal functions of the MAX2871. MUX can also be configured as serial data output. Bits MUX (register 5, bit 18 and register 2, bit 28:26) are used to select the desired MUX function (see [Table 5](#)).

### Lock Detect

Lock detect can be monitored through the LD output by setting the LD bits (register 5, bits 23:22). For digital lock detect, set LD = 01. The digital lock detect is dependent on the mode of the synthesizer. In frac-N mode set LDF = 0, and in int-N mode set LDF = 1. To set the accuracy of the digital lock detect, see [Table 1](#) and [Table 2](#).

Analog lock detect can be set with LD = 10. In this mode, LD is an open-drain output and requires an external pullup resistor of 10kΩ typical value.

The lock detect output validity is dependent on many factors. The lock detect output is not valid during VCO auto selection process. After the VCO auto selection process has completed, the lock detect output is not valid until the TUNE voltage has settled. TUNE voltage settling time is dependent on loop filter bandwidth, and can be calculated using EE-Sim Simulation tool found at [www.maximintegrated.com](http://www.maximintegrated.com).

**Table 1. Frac-N Digital Lock-Detect Settings**

PFD FREQUENCY	LDS	LDP	LOCKED UP/DOWN TIME SKEW (ns)	NUMBER OF LOCKED CYCLES TO SET LD	UP/DOWN TIME SKEW TO UNSET LD (ns)
≤ 32MHz	0	0	10	40	15
≤ 32MHz	0	1	6	40	15
> 32MHz	1	X	4	40	4

**Table 2. Int-N Digital Lock-Detect Settings**

PFD FREQUENCY	LDS	LDP	LOCKED UP/DOWN TIME SKEW (ns)	NUMBER OF LOCKED CYCLES TO SET LD	UP/DOWN TIME SKEW TO UNSET LD (ns)
≤ 32MHz	0	0	10	5	15
≤ 32MHz	0	1	6	5	15
> 32MHz	1	X	4	5	4

### Cycle Slip Reduction

Cycle slip reduction is one of the two methods available to improve lock time. It is enabled by setting CSM bit (register 3, bit 18) to 1. In this mode, the charge pump must be set to its minimum value.

### Fast-Lock

Another method to decrease lock time is to use a fast-lock mode. This mode requires that CP = 0000 (register 2, bits 12:9) and that the shunt resistive portion of the loop filter be segmented into two parts, where one resistor (R2A) is 1/4 of the total resistance, and the other resistor (R2B) is 3/4 of the total resistance. The larger resistor (R2B) should be connected from SW to Ground, and the smaller resistor (R2A) from SW to the loop filter capacitor (see Figure 4). When CDM = 01 (register 3, bits 16:15), fast-lock is active after the VAS has completed. During fast-lock, the charge pump is increased to CP = 1111 and the shunt loop filter resistance is set to 1/4 of the total resistance by changing pin SW from high impedance to ground. Fast-lock deactivates after a timeout set by the user. This timeout is loop filter dependent, and is set by:

$$t_{\text{FAST-LOCK}} = M \times \text{CDIV} / f_{\text{PFD}}$$

where M is the modulus setting and CDIV is the clock divider setting. The user must determine the CDIV setting based on their loop filter time constant. The SW pin can be left open/ no connect when fast lock mode is not used.

### RFOUTA± and RFOUTB±

The device has dual differential open-collector RF outputs that require an external RF choke or a 50Ω resistor to supply for each output. Each differential output can be independently enabled or disabled by setting bits RFA\_EN (register 4, bit 5) and RFB\_EN (register 4, bit 8). Both outputs are also controlled by applying a logic-high (enabled) or logic-low (disabled) to pin RFOUT\_EN.

The output power of each output can be individually controlled with APWR (register 4, bits 4:3) for RFOUTA and BPWR (register 4, bits 7:6) for RFOUTB. The available differential output power settings are from -4dBm to +5dBm, in 3dB steps with 50Ω pullup to supply. The available single-ended output power ranges from -4dBm to +5dBm in 3dB steps with a RF choke to supply. Across the entire frequency range different pullup elements (L or R) are required for optimal output power. If single-ended output is used, the unused output should be supplied and terminated in the same manner as the corresponding load. If a differential output is unused then those RFOUT pins should be directly connected to VCC\_RF (pin 16).

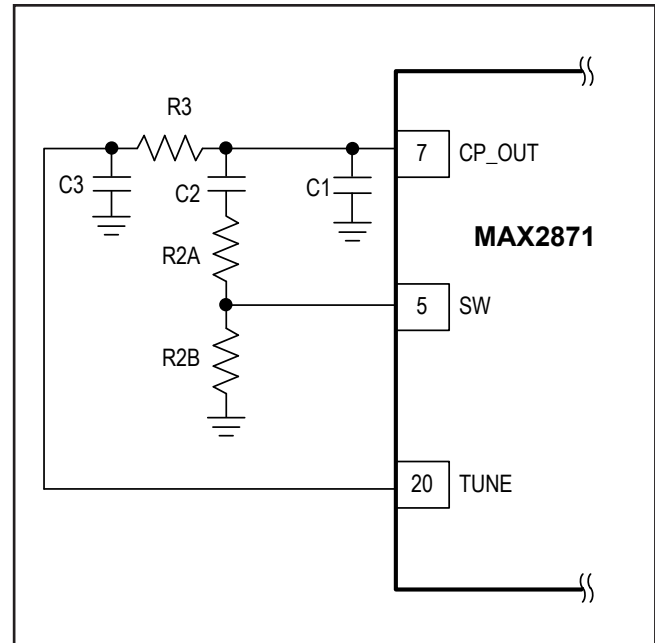


Figure 4. Fast Lock Filter Topology

To prevent undesired frequencies from being output while acquiring lock, the output power can be disabled when the PLL is unlocked by using MTLD (register 4, bit 10). A logic 1 will disable the outputs when the digital lock detect is logic low. When acquiring lock the output can overshoot and pass through the desired frequency. In some circumstances, the digital lock detect will flicker high during these periods. To prevent this from happening, a timer can be used to delay the output from enabling after losing lock. Enable MUTEDEL (register 3, bit 17) with MTLD enabled to use this function. The delay for enabling the output is set by:

$$\text{Delay} = \text{CDIV} \times M / f_{\text{PFD}}$$

where CDIV (register 3, bits 14:3) is the clock divider, M (register 1, bits 14:3) is the variable modulus for the fractional N modulator, and  $f_{\text{PFD}}$  is the phase detector frequency.

### Voltage-Controlled Oscillator

The fundamental VCO frequency of the device guarantees gap-free coverage from 3.0GHz to 6.0GHz using four individual VCO core blocks with 16 sub-bands within each block. Connect the output of the loop filter to the TUNE input. The TUNE input is used to control the VCO.



**Tune ADC**

A 7-bit ADC is used to read back the VCO tuning voltage. The ADC value can be read back through register 6, bits 22:16. To digitize the tuning voltage, do the following:

- 1) Set bits CDIV (register 3, bits 14:3) =  $f_{\text{PFD}}/100\text{kHz}$  to set the clock speed for the ADC.
- 2) Set bits ADCM (register 5, bits 5:3) = 100 to enable the ADC to read the TUNE pin voltage.
- 3) Set bit ADCS (register 5, bit 6) = 1 to start the ADC conversion process.
- 4) Wait 100 $\mu\text{s}$  for the conversion process to finalize.
- 5) Read back register 6. The ADC value is located in bits 22:16.
- 6) Reset bits ADCM = 0 and ADCS = 0.

The voltage on the TUNE pin can be calculated as:

$$V = 0.315 + \text{ADC} \times 0.0165$$

**VCO Autoselect (VAS) State Machine**

An internal VCO autoselect state machine is initiated when register 0 is programmed to automatically select the correct VCO if bit VAS\_SHDN = 0 (register 3, bit 25).

The state machine clock,  $f_{\text{BS}}$ , must be set to 50kHz. This is set by the BS bits (register 4, bits 25:24, 19:12). The formula for setting BS is:

$$\text{BS} = f_{\text{PFD}}/50\text{kHz}$$

where  $f_{\text{PFD}}$  is the phase-detector frequency. The BS value should be rounded to the nearest integer. If the calculated BS is higher than 1023, then set BS = 1023. If  $f_{\text{PFD}}$  is lower than 50kHz, then set BS = 1. The time needed to select the correct VCO is  $10/f_{\text{BS}}$ .

The VAS\_TEMP bit (register 3, bit 24) can be used to select the best VCO for the given ambient temperature to ensure that the VCO will not drift out of lock if the temperature changes within  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ . Bits RFA\_EN (register 4, bit 5) and RFB\_EN (register 4, bit 8) must be 0, and bits 30:29 of register 5 must be set to 11 during VCO acquisition. Setting VAS\_TEMP = 1 will increase the time needed to achieve lock from  $10/f_{\text{BS}}$  to approximately 100ms.

If VAS\_SHDN = 1, then the VCO can be manually selected by bits VCO (register 3, bits 31:26). Refer to [Applications Information](#) for detailed implementation of VCO manual selection.

**Phase Adjustment**

After achieving lock, the phase of the single MAX2871 device's RF output can be changed in increments of P (register 1, bits 26:15) / M (register 1, bits 14:3)  $\times 360^{\circ}$ .

Also, multiple MAX2871 devices' RF Outputs can be phase synchronized with a single reference input. See [Applications Information](#) for detailed implementation.

**Low-Spur Mode**

The device offers three modes for the sigma-delta modulator. Low-noise mode offers lower in-band noise at the expense of spurs. The spurs can be reduced by setting SDN = 10 (register 2, bits 30:29) or SDN = 11 for different modes of dithering. The user can determine which mode works best for their application.

**Temperature Sensor**

The device is equipped with an on-chip temperature sensor and 7-bit ADC.

To read the digitized output of the temperature sensor:

- 1) Set bits CDIV (register 3, bits 14:3) =  $f_{\text{PFD}}/100\text{kHz}$  to set the clock speed for the ADC.
- 2) Set bits ADCM (register 5, bits 5:3) = 001 to enable the ADC to read the temperature.
- 3) Set bit ADCS (register 5, bit 6) = 1 to start the ADC conversion process.
- 4) Wait 100 $\mu\text{s}$  for the conversion process to finalize.
- 5) Read back register 6. The ADC value is located in bits 22:16.
- 6) Reset bits ADCM=0 and ADCS=0.

The approximate ambient temperature can be converted as:

$$t = 95 - 1.14 \times \text{ADC}$$

This formula is most accurate when the VCO is enabled and RFOUTA is enabled at full output power. The temperature can vary based on output power and if one or both outputs are enabled.

### Register and Bit Descriptions

The operating mode of the device is controlled by six on-chip registers.

Defaults are not guaranteed upon power-up and are provided for reference only. All reserved bits should only

be written with default values. In low-power mode, the register values are retained. Upon power-up, the registers should be programmed twice with at least a 20ms pause between writes. The first write ensures that the device is enabled, and the second write starts the VCO selection process.

**Table 3. Register 0 (Address: 000, Default: 007D0000<sub>HEX</sub>)**

BIT LOCATION	BIT ID	NAME	DEFINITION
31	INT	Int-N or Frac-N Mode Control	0 = Enables the fractional-N mode 1 = Enables the integer-N mode The LDF bit must also be set to the appropriate mode.
30:15	N[15:0]	Integer Division Value	Sets integer part (N-divider) of the feedback divider factor. All integer values from 16 to 65,535 are allowed for integer mode. Integer values from 0 to 15 are not allowed. Integer values from 19 to 4091 are allowed for fractional mode.
14:3	FRAC[11:0]	Fractional Division Value	Sets fractional value: 000000000000 = 0 (see F0I bit description) 000000000001 = 1 ---- 111111111110 = 4094 111111111111 = 4095
2:0	ADDR[2:0]	Address Bits	Control Register address bits, 000

**Table 4. Register 1 (Address: 001, Default: 2000FFF9<sub>HEX</sub>)**

BIT LOCATION	BIT ID	NAME	DEFINITION
31	Reserved	Reserved	Reserved. Program to 0.
30:29	CPL[1:0]	CP Linearity	Sets CP linearity mode. 00 = Disables the CP linearity mode (integer-N mode) 01 = CP linearity 10% mode (frac-N mode) 10 = CP linearity 20% mode (frac-N mode) 11 = CP linearity 30% mode (frac-N mode)
28:27	CPT[1:0]	Charge Pump Test	Sets charge-pump test modes. 00 = Normal mode 01 = Long Reset mode 10 = Force CP into source mode 11 = Force CP into sink mode
26:15	P[11:0]	Phase Value	Sets phase value. See the <a href="#">Phase Adjustment</a> section. 000000000000 = 0 000000000001 = 1 (recommended) ----- 111111111111 = 4095
14:3	M[11:0]	Modulus Value (M)	Fractional modulus value used to program $f_{VCO}$ . See the <a href="#">Int, Frac, Mod and R Counter Relationship</a> section. Double buffered by register 0. 000000000000 = Not Valid 000000000001 = Not Valid 000000000010 = 2 ----- 111111111111 = 4095
2:0	ADDR[2:0]	Address Bits	Control Register address bits, 001

**Table 5. Register 2 (Address: 010, Default: 00004042<sub>HEX</sub>)**

BIT LOCATION	BIT ID	NAME	DEFINITION
31	LDS	Lock-Detect Speed	Lock-detect speed adjustment. 0 = $f_{PFD} \leq 32\text{MHz}$ 1 = $f_{PFD} > 32\text{MHz}$
30:29	SDN[1:0]	Frac-N Sigma Delta Noise Mode	Sets noise mode (see the Low-Spur Mode section.) 00 = Low-noise mode 01 = Reserved 10 = Low-spur mode 1 11 = Low-spur mode 2
28:26	MUX[2:0]	MUX Configuration	Sets MUX pin configuration (MSB bit located register 05). 0000 = Three-state output 0001 = D_VDD 0010 = D_GND 0011 = R-divider output 0100 = N-divider output/2 0101 = Analog lock detect 0110 = Digital lock detect 0111 = Sync Input 1000 : 1011 = Reserved 1100 = Read SPI registers 06 1101 : 1111 = Reserved
25	DBR	Reference Doubler Mode	Sets reference doubler mode. 0 = Disable reference doubler 1 = Enable reference doubler
24	RDIV2	Reference Div2 Mode	Sets reference divide-by-2 mode. 0 = Disable reference divide-by-2 1 = Enable reference divide-by-2
23:14	R[9:0]	Reference Divider Mode	Sets reference divide value (R). Double buffered by register 0. 0000000000 = 0 (unused) 0000000001 = 1 ----- 1111111111 = 1023

**Table 5. Register 2 (Address: 010, Default: 00004042<sub>HEX</sub>) (continued)**

BIT LOCATION	BIT ID	NAME	DEFINITION
13	REG4DB	Double Buffer	Sets double buffer mode. 0 = Disabled 1 = Enabled
12:9	CP[3:0]	Charge-Pump Current	Sets charge-pump current in mA ( $R_{SET} = 5.1k\Omega$ ). Double buffered by register 0. $ICP = 1.63/R_{SET} \times (1+CP[3:0])$
8	LDF	Lock-Detect Function	Sets lock-detect function. 0 = Frac-N lock detect 1 = Int-N lock detect
7	LDP	Lock-Detect Precision	Sets lock-detect precision. 0 = 10ns 1 = 6ns
6	PDP	Phase Detector Polarity	Sets phase detector polarity. 0 = Negative 1 = Positive (default)
5	SHDN	Shutdown Mode	Sets power-down mode. 0 = Normal mode 1 = Device shutdown
4	TRI	Charge Pump Output High-Impedance Mode	Sets charge-pump output high-impedance mode. 0 = Disabled 1 = Enabled
3	RST	Counter Reset	Sets counter reset mode. 0 = Normal operation 1 = R and N counters reset
2:0	ADDR[2:0]	Address Bits	Control Register address bits, 010

**Table 6. Register 3 (Address: 011, Default: 000000B<sub>HEX</sub>)**

BIT LOCATION	BIT ID	NAME	DEFINITION
31:26	VCO[5:0]	VCO	Manual selection of VCO and VCO sub-band when VAS is disabled. 000000 = VCO0 ..... 111111 = VCO63
25	VAS_SHDN	VAS_SHDN	Sets VAS shutdown mode. 0 = VAS enabled 1 = VAS disabled
24	VAS_TEMP	VAS_TEMP	Sets VAS response to temperature drift. 0 = VAS temperature compensation disabled 1 = VAS temperature compensation enabled
23:19	Reserved	Reserved	Reserved.
18	CSM	Cycle Slip Mode	Cycle Slip Mode 0 = Disable Cycle Slip Reduction 1 = Enable Cycle Slip Reduction
17	MUTEDEL	Mute Delay Mode	Mute Delay 0 = Do not delay LD to MTLTD function to prevent flickering 1 = Delay LD to MTLTD function to prevent flickering
16:15	CDM[1:0]	Clock Divider Mode	Sets clock divider mode. 00 = Mute until Lock Delay 01 = Fast-lock enabled 10 = Phase Adjustment mode 11 = Reserved
14:3	CDIV[11:0]	Clock Divider Value	Sets 12-bit clock divider value. 000000000000 = Unused 000000000001 = 1 000000000010 = 2 ----- 111111111111 = 4095
2:0	ADDR[2:0]	Address Bits	Control Register address bits, 011

**Table 7. Register 4 (Address: 100, Default: 6180B23C<sub>HEX</sub>)**

BIT LOCATION	BIT ID	NAME	DEFINITION
31:29	Reserved	Reserved	Reserved. Program to 011.
28	SDLDO	Shutdown VCO LDO	Sets Shutdown VCO LDO mode. 0 = Enables LDO 1 = Disables LDO
27	SDDIV	Shutdown VCO Divider	Sets Shutdown VCO Divider mode. 0 = Enables VCO Divider 1 = Disables VCO Divider
26	SDREF	Shutdown Reference Input	Sets Shutdown Reference input mode. 0 = Enables Reference Input 1 = Disables Reference Input
25:24	BS[9:8]	Band-Select MSBs	Sets Band-Select clock divider MSBs. See bits[19:12].
23	FB	VCO Feedback Mode	Sets VCO to N counter feedback mode. 0 = Divided 1 = Fundamental
22:20	DIVA[2:0]	RFOUT_ Output Divider Mode	Sets RFOUT_ output divider mode. Double buffered by register 0 when REG4DB = 1. 000 = Divide by 1, if $3000\text{MHz} \leq f_{\text{RFOUTA}} \leq 6000\text{MHz}$ 001 = Divide by 2, if $1500\text{MHz} \leq f_{\text{RFOUTA}} < 3000\text{MHz}$ 010 = Divide by 4, if $750\text{MHz} \leq f_{\text{RFOUTA}} < 1500\text{MHz}$ 011 = Divide by 8, if $375\text{MHz} \leq f_{\text{RFOUTA}} < 750\text{MHz}$ 100 = Divide by 16, if $187.5\text{MHz} \leq f_{\text{RFOUTA}} < 375\text{MHz}$ 101 = Divide by 32, if $93.75\text{MHz} \leq f_{\text{RFOUTA}} < 187.5\text{MHz}$ 110 = Divide by 64, if $46.875\text{MHz} \leq f_{\text{RFOUTA}} < 93.75\text{MHz}$ 111 = Divide by 128, if $23.5\text{MHz} \leq f_{\text{RFOUTA}} < 46.875\text{MHz}$
19:12	BS[7:0]	Band Select	Sets band select clock divider value. MSB are located in bits [25:24]. 000000000 = Reserved 000000001 = 1 000000010 = 2 ---- 111111111 = 1023
11	SDVCO	VCO Shutdown	Sets VCO Shutdown mode. 0 = Enables VCO 1 = Disables VCO
10	MTLD	RFOUT Mute until Lock Detect	Sets RFOUT Mute until Lock Detect Mode 0 = Disables RFOUT Mute until Lock Detect Mode 1 = Enables RFOUT Mute until Lock Detect Mode
9	BDIV	RFOUTB Output Path Select	Sets RFOUTB output path select. 0 = VCO divided output 1 = VCO fundamental frequency
8	RFB_EN	RFOUTB Output Mode	Sets RFOUTB output mode. 0 = Disabled 1 = Enabled
7:6	BPWR[1:0]	RFOUTB Output Power	Sets RFOUTB single-ended output power. See the <a href="#">RFOUTA± and RFOUTB±</a> section. 00 = -4dBm 01 = -1dBm 10 = +2dBm 11 = +5dBm

**Table 7. Register 4 (Address: 100, Default: 6180B23C<sub>HEX</sub>) (continued)**

BIT LOCATION	BIT ID	NAME	DEFINITION
5	RFA_EN	RFOUTA Output Mode	Sets RFOUTA output mode. 0 = Disabled 1 = Enabled
4:3	APWR[1:0]	RFOUTA Output Power	Sets RFOUTA single-ended output power. See the <a href="#">RFOUTA± and RFOUTB±</a> section. 00 = -4dBm 01 = -1dBm 10 = +2dBm 11 = +5dBm
2:0	C[2:0]	Register Address	Control Register address bits, 100

**Table 8. Register 5 (Address: 101, Default: 00400005<sub>HEX</sub>)**

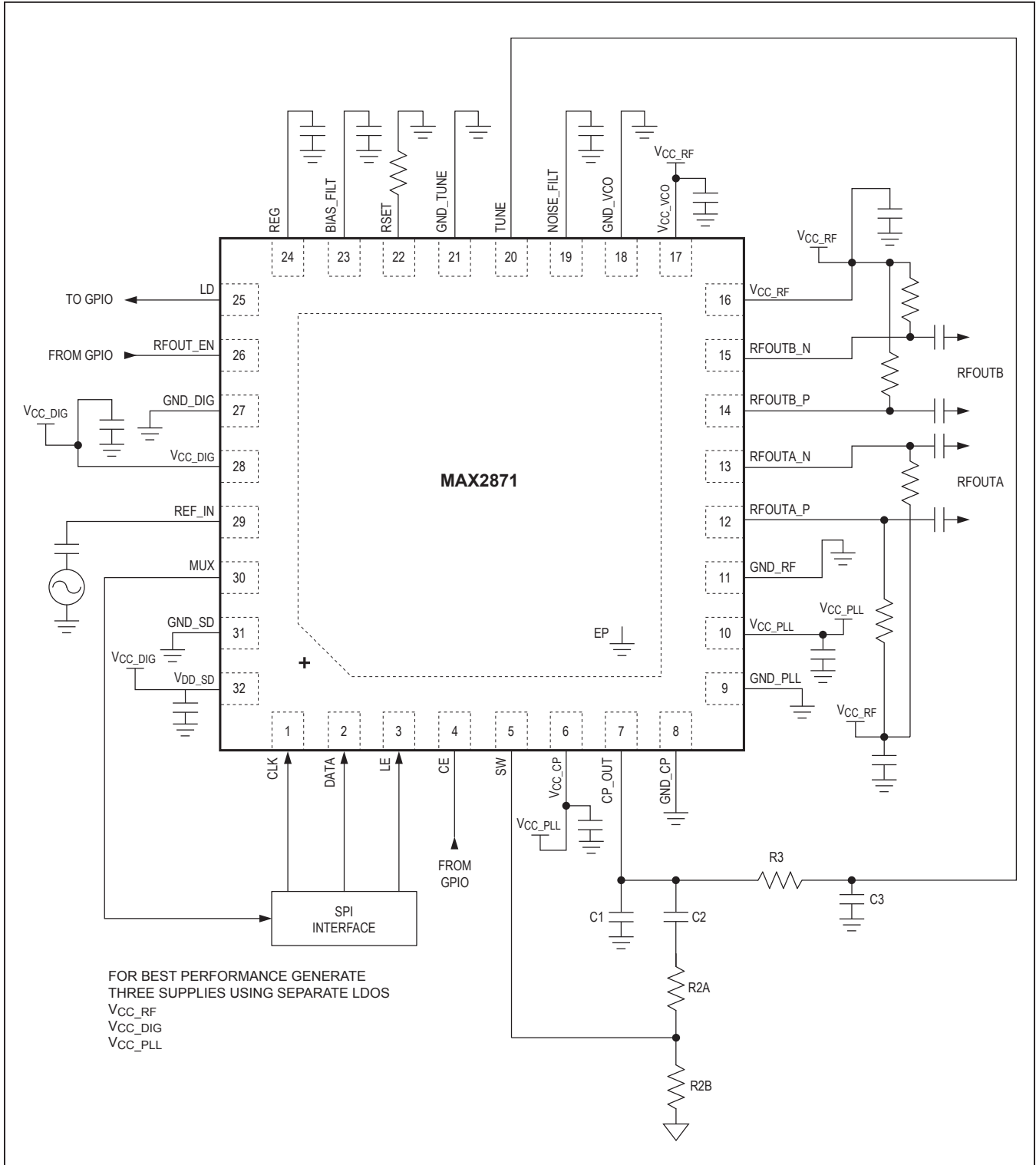
BIT LOCATION	BIT ID	NAME	DEFINITION
31	Reserved	Reserved	Reserved. Program to 0.
30:29	VAS_DLY	VAS_DLY	VCO Autoselect Delay. Program to 11 when VAS_TEMP=1 Program to 00 when VAS_TEMP=0
28:26	Reserved	Reserved	Reserved. Program to 000.
25	SDPLL	Shutdown PLL	Sets Shutdown PLL mode. 0 = Enables PLL 1 = Disables PLL
24	F01	F01	Sets integer mode for F = 0. 0 = If F[11:0] = 0, then fractional-N mode is set 1 = If F[11:0] = 0, then integer-N mode is auto set
23:22	LD[1:0]	Lock-Detect Pin Function	Sets lock-detect pin function. 00 = Low 01 = Digital lock detect 10 = Analog lock detect 11 = High
21:19	Reserved	Reserved	Reserved. Program to 000.
18	MUX[3]	MUX MSB	Sets mode at MUX pin (see register 2 [28:26])
17:7	Reserved	Reserved	Reserved. Program to 0000000000.
6	ADCS	ADC Start	Sets ADC Start mode. 0 = ADC normal operation 1 = Start ADC conversion process
5:3	ADCM[2:0]	ADC Mode	Sets ADC mode. 000 = Disabled 001 = Temperature sensor 010 = Reserved 011 = Reserved 100 = Tune pin 101 = Reserved 110 = Reserved 111 = Reserved
2:0	ADDR[2:0]	Register Address	Control Register address bits, 101



**Table 9. Register 6 (Address: 110, Read-Only Register)**

BIT LOCATION	BIT ID	NAME	DEFINITION
31:28	DIE[3:0]	Die ID	Die ID. 0110 = MAX2870 0111 = MAX2871
27:24	Reserved	Reserved	Reserved.
23	POR	Power On Reset	Power-On-Reset 0 = Power has not been cycled since last read 1 = Power has not been cycled since last read. All registers have been reset to default values.
22:16	ADC[6:0]	ADC Code	ADC Code.
15	ADCV	ADC Valid	Determines ADC code validity. 0 = Invalid ADC code 1 = Valid ADC code
14:10	Reserved	Reserved	Reserved.
9	VASA	VAS Active	Determines if VAS is Active. 0 = VCO Autoselect complete 1 = VCO Autoselect searching for correct VCO
8:3	V[5:0]	Current VCO	Current VCO.
2:0	ADDR[2:0]	Register Address	Control Register address bits, 110

Typical Application Circuit



### Applications Information

#### VCO Manual Selection Operation

VCO manual selection operation (VAS\_SHDN = 1) allows shorter lock time, typically 200µS saving. It is also required that multiple MAX2871 devices phase synchronization.

The following steps need to be implemented:

1. Building VCO lookup table (Required ONLY once after each power cycle)
  - Set VAS\_SHDN = 0, follow “VCO Autoselect (VAS) State Machine” section to set BS bits properly
  - Write proper N and Frac value to Reg 0, triggering MAX2871 to first desired frequency point, i.e freq1. Wait for PLL to lock
  - Read back register 6[8:3] from MUX pin and save the value to memory as vco1, see detail at 4-Wire Serial Interface section about register readback
  - Repeat above steps for all desired frequency points
2. VCO manual selection normal operation
  - Set VAS\_SHDN = 1
  - Based on the VCO lookup table obtained from step 1, write desired frequency’s corresponding VCO value to reg3[31:26]
  - Write proper N and Frac value to reg0, triggering MAX2871 to desired frequency

#### Phase synchronization of multiple MAX2871 devices

Multiple MAX2871 devices can be phase synchronized. This feature works in the frequency range of 187.5MHz to 6000 MHz and in Fractional-N mode ONLY.

Proper hardware/register guidelines MUST be followed:

#### Hardware Design Guidelines

1. Connect all MAX2871 to same reference source. Refer, [Figure 5](#)
2. Connect MUX pins of all MAX2871 to 4 wire interface’s readback
3. Connect MUX pins of all MAX2871 to same sync pulse source
4. The relative delay of reference signal at each MAX2871s reference pin can **NOT** be random. Refer [Figure 6](#).

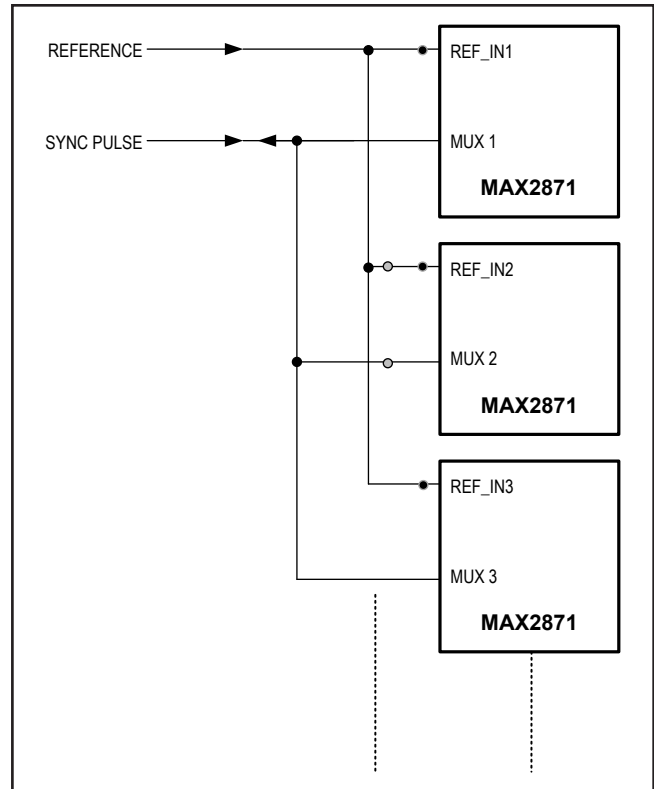


Figure 5. Phase Synchronization Application Setup

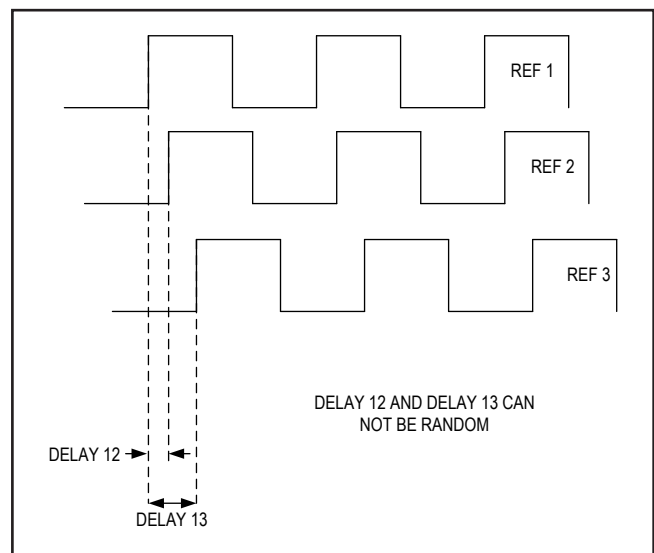


Figure 6. Reference Signal Relative Delay

5. At each MAX2871 REF\_IN pin and MUX pin, the sync rising edge can **NOT** occur inside the setup hold time window around reference signal rising edge. Refer to [Figure 7](#).

$$t_{\text{SETUP}} = (4/N) \times t_{\text{PFD}} + 2.6\text{nS}$$

$$t_{\text{HOLD}} = (4/N) \times t_{\text{PFD}}$$

where: N is MAX2871's N counter ratio, reg0[30:15]

$$t_{\text{PFD}} = 1/(\text{PFD frequency})$$

### Register Design Guidelines

- The reference doubler and reference divide-by-2 must be disabled.  
DBR (reg2[25]) = 0  
RDIV2 (reg2[24]) = 0
- R divider ratio must be set to 1  
R (register 2, bits 23:14) = 1.
- Set MAX2871 in Fractional mode  
INT (reg0[31]) = 0  
F01 (reg5[24]) = 0
- Output divider has to be inside the PLL loop  
FBMUX (reg4[23]) = 0.
- If OUTPUT B is used, it has to be set to "VCO divided output" mode  
BDIV (reg4[9]) = 0
- Sigma delta modulator has to be in low noise mode  
SDN (reg2[30:29]) = 00.
- N counter ratio has to be in allowable range  
 $19 < N$  (reg0[30:15]) < 4091
- DIVA (register 4, bits 22:20)  $\leq 100_{\text{binary}}$  (less than or equal to divide-by-16, which limits the minimum output frequency to 187.5MHz)
- Set VAS\_SHDN = 1, for normal operation

### Steps to Execute Phase Sync

- Follow "VCO Manual Selection Operation" section to build VCO lookup table for each MAX2871 devices in the system, only required once after each power cycle
- Force the voltage on the MUX pin to VIL
- Set MUX (reg5[18] & reg2[28:26]) = 0111 which allows MUX to take external 'SYNC INPUT'
- Program the MAX2871s for the desired frequency and allow them to lock. Ensure to use "VCO Manual selection Operation"

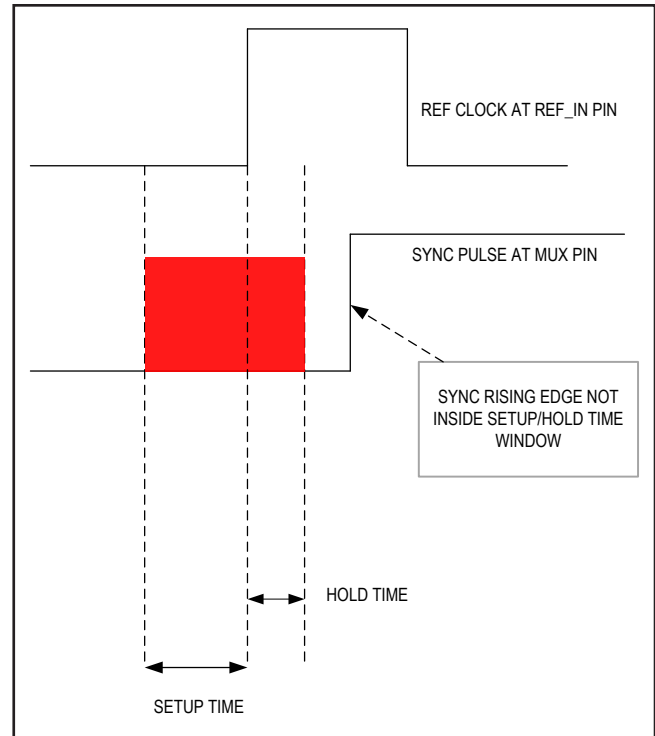


Figure 7. Setup Time/ Hold Time Window

- Force the voltage on the MUX pins to VIH. This resets the MAX2871s so they are synchronous. The MUX sync pulse rising edge cannot occur inside setup/hold time window around the reference signal rising edge.
- (Optional) If the user plans to use MUX pin's other function (i.e., register readback, follow steps below):
  - Force the voltage on the MUX pins back to VIL
  - Set MUX (reg5[18] and reg2[28:26]) = 0000 (HiZ mode)
  - Remove the forced voltage from the MUX pin
  - Now the MUX pin is ready for other functions
- Set ONLY P(reg1[26:15]) for the desired amount of phase shift for each part.
- Set CDM (reg3[16:15]) = 10
- Reset CDM (reg3[16:15]) = 00. All MAX2871s are frequency synchronized with phase difference defined in step 7. The initial phase sync is completed
- Repeat step 2-10 for new frequency points

### Layout Issues

The MAX2871 EV kit can be used as a starting point for layout. For best performance, take into consideration grounding and routing of RF, baseband, and power supply PCB proper line. Make connections from vias to the ground plane as short as possible. On the high impedance ports, keep traces short to minimize shunt capacitance. EV kit Gerber files can be requested/ downloaded at [www.maximintegrated.com](http://www.maximintegrated.com).

### Power-Supply Layout

To minimize coupling between different sections of the IC, a star power-supply routing configuration with a large decoupling capacitor at a central VCC\_ node is recommended. The VCC\_ traces branch out from this node, each going to a separate VCC\_ node in the circuit. Place a bypass capacitor as close as possible to each supply pin. This arrangement provides local decoupling at each VCC\_ pin. Use at least one via per bypass capacitor for a low-inductance ground connection. Do not share the capacitor ground vias with any other branch.

### Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX2871ETJ+	-40°C to +85°C	32 TQFN-EP*

+Denotes lead(Pb)-free/RoHS-compliant package.

\*EP = Exposed pad.

### Package Information

For the latest package outline information and land patterns (footprints), go to [www.maximintegrated.com/packages](http://www.maximintegrated.com/packages). Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
32 TQFN-EP	T3255+5	<a href="#">21-0140</a>	<a href="#">90-0013</a>

## Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	9/14	Initial release	—
1	4/15	Updated <i>Phase Adjustment</i> section and other minor updates to data sheet	1, 13, 17, 19, 24
2	5/16	Updated <i>Phase Adjustment</i> section, Register 6 readout timing, other general updates	3, 5, 11–13, 15, 18, 19, 21, 22, 24,
3	4/17	Added <i>VCO Manual Selection</i> and <i>Phase Sync</i> sections, as well as other general updates/corrections	1–4, 11, 13–19, 21, 22, 24, 25, 27
4	6/20	Updated <i>Detailed Description</i> section	13

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at [www.maximintegrated.com](http://www.maximintegrated.com).

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