

General Description

The MAX5171/MAX5173 low-power, serial, voltage-output, 14-bit digital-to-analog converters (DACs) feature a precision output amplifier in a space-saving 16-pin QSOP package. The MAX5171 operates from a +5V single supply, and the MAX5173 operates from a +3V single supply. The output amplifier's inverting input is available to allow specific gain configurations, remote sensing, and high output current capability. This makes the MAX5171/ MAX5173 ideal for a wide range of applications, including industrial process control. Both devices draw only 260µA of supply current, which reduces to 1µA in shutdown mode. In addition, the programmable power-up reset feature allows for a user-selectable output voltage of either 0 or midscale.

The 3-wire serial interface is compatible with SPI™, QSPI™, and MICROWIRE™ standards. An input register followed by a DAC register provides a double-buffered input, allowing the input and DAC registers to be updated independently or simultaneously with a 16-bit serial word. Additional features include software and hardware shutdown, shutdown lockout, a hardware clear pin, and a reference input capable of accepting DC and offset AC signals. These devices provide a programmable digital output pin for added functionality and a serial-data output pin for daisy-chaining. All logic inputs are TTL/CMOScompatible and are internally buffered with Schmitt triggers to allow direct interfacing to optocouplers.

The MAX5171/MAX5173 incorporate a proprietary on-chip circuit that keeps the output voltage virtually "glitch free," limiting the glitches to a few millivolts during power-up.

Both devices are available in 16-pin QSOP packages and are specified for the extended (-40°C to +85°C) temperature range. The MAX5171/MAX5173 are pin-compatible upgrades to the 12-bit MAX5175/MAX5177. For 100% pincompatible DACs with an internal reference, see the 13-bit MAX5132/MAX5133 and the 12-bit MAX5122/MAX5123 data sheets.

Applications

Digitally Programmable 4-20mA Current Loops

Industrial Process Control

Digital Offset and Gain Adjustment

Motion Control

Automatic Test Equipment (ATE)

Remote Industrial Controls

μP-Controlled Systems

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MICROWIRE is a trademark of National Semiconductor Corp.

Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.

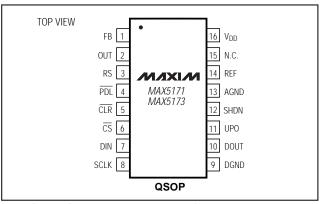
Features

- ♦ ±1 LSB INL
- ♦ 1µA Shutdown Current
- ◆ "Glitch Free" Output Voltage at Power-Up
- ♦ Single-Supply Operation: +5V (MAX5171) +3V (MAX5173)
- **♦** Full-Scale Output Range:
 - +2.048V (MAX5173, $V_{REF} = +1.25V$)
 - +4.096V (MAX5171, $V_{REF} = +2.5V$)
- ♦ Rail-to-Rail® Output Amplifier
- **♦ Low THD (-80dB) in Multiplying Operation**
- ♦ SPI/QSPI/MICROWIRE-Compatible 3-Wire **Serial Interface**
- ♦ Programmable Shutdown Mode and Power-Up
- ♦ Buffered Output Capable of Driving 5kΩ | 100pF
- **♦ User-Programmable Digital Output Pin Allows Serial Control of External Components**
- **♦** Pin-Compatible Upgrade to the 12-Bit MAX5175/MAX5177

Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE	INL (LSB)
MAX5171AEEE	-40°C to +85°C	16 QSOP	±1
MAX5171BEEE	-40°C to +85°C	16 QSOP	±2
MAX5173AEEE	-40°C to +85°C	16 QSOP	±2
MAX5173BEEE	-40°C to +85°C	16 QSOP	±4

Pin Configuration



Functional Diagram appears at end of data sheet.

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ABSOLUTE MAXIMUM RATINGS

V _{DD} to AGND, DGND	0.3V to +6.0V
AGND to DGND	0.3V to +0.3V
Digital Inputs to DGND	0.3V to +6.0V
DOUT, UPO to DGND	0.3V to $(V_{DD} + 0.3V)$
FB, OUT, REF to AGND	0.3V to $(V_{DD} + 0.3V)$
Maximum Current into Any Pin	50mA

Continuous Power Dissipation ($T_A = +70$ °C)	
16-pin QSOP (derate 8mW/°C above +70°C)	667mW
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range6	55°C to +150°C
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS—MAX5171

 $(V_{DD}$ = +5.0V ±10%, V_{REF} = +2.5V, AGND = DGND, FB = OUT, R_L = 5k Ω , C_L = 100pF referenced to ground, T_A = T_{MIN} to T_{MAX} , unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
STATIC PERFORMANCE						l .
Resolution			14			Bits
Integral Naplinearity (Nate 1)	INL	MAX5171A			±1	LSB
Integral Nonlinearity (Note 1)	IINL	MAX5171B				LSD
Differential Nonlinearity	DNL				±1	LSB
Offset Error (Note 2)	Vos				±10	mV
Gain Error	GE	R _L = ∞		-0.6	±4	LSB
Gaiii Eii Oi	GE	$R_L = 5k\Omega$		-1.6	±8	LSD
Power-Supply Rejection Ratio	PSRR			10	120	μV/V
Output Noise Voltage		f = 100kHz		1		LSBp-p
Output Thermal Noise Density				50		nV/√Hz
REFERENCE	•					•
Reference Input Range	V _{REF}		0		V _{DD} - 1.4	V
Reference Input Resistance	R _{REF}		18			kΩ
MULTIPLYING-MODE PERFOR	RMANCE		'			
Reference -3dB Bandwidth		V _{REF} = 0.5Vp-p + 2.5V _{DC} , slew-rate limited		350		kHz
Reference Feedthrough		V _{REF} = 3.6Vp-p + 1.8V _{DC} , f = 1kHz, code = all 0s		-84		dB
Signal-to-Noise Plus Distortion Ratio		$V_{REF} = 1.4Vp-p + 2.5V_{DC}$, $f = 10kHz$, $code = 3FFF hex$		84		dB
DIGITAL INPUTS						L
Input High Voltage	VIH		3			V
Input Low Voltage	VIL				0.8	V
Input Hysteresis	VHYS			200		mV
Input Leakage Current	I _{IN}	$V_{IN} = 0$ or V_{DD}		0.001	±1	μΑ
Input Capacitance	CIN			8		pF
DIGITAL OUTPUTS						
Output High Voltage VoH Isource = 2mA VDD - 0.5				V		
Output Low Voltage	VoL	I _{SINK} = 2mA		0.13	0.4	V

ELECTRICAL CHARACTERISTICS—MAX5171 (continued)

 $(V_{DD} = +5V \pm 10\%, V_{REF} = +2.5V, AGND = DGND, FB = OUT, R_L = 5k\Omega, C_L = 100pF$ referenced to ground, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DYNAMIC PERFORMANCE						
Voltage Output Slew Rate	SR			0.6		V/µs
Output Settling Time		To ±0.5LSB, from 10mV to full scale		12		μs
Output Voltage Swing (Note 3)			0		VDD	V
Current into FB			-0.1	0	0.1	μA
Time Required to Exit Shutdown				40		μs
Digital Feedthrough		$\overline{\text{CS}} = \text{V}_{\text{DD}}; \text{f}_{\text{SCLK}} = 100 \text{kHz}, \text{V}_{\text{SCLK}} = 5 \text{Vp-p}$		1		nV-s
POWER SUPPLIES						
Positive Supply Voltage	V _{DD}		4.5		5.5	V
Power-Supply Current (Note 4)	I _{DD}			0.26	0.35	mA
Shutdown Current (Note 4)				1	10	μA
TIMING CHARACTERISTICS						
SCLK Clock Period	tcp		100			ns
SCLK Pulse Width High	tch		40			ns
SCLK Pulse Width Low	tcL		40			ns
CS Fall to SCLK Rise Setup Time	tcss		40			ns
SCLK Rise to $\overline{\text{CS}}$ Rise Hold Time	tcsh		0			ns
SDI Setup Time	t _{DS}		40			ns
SDI Hold Time	tDH		0			ns
SCLK Rise to DOUT Valid Propagation Delay	tDO1	CLOAD = 200pF			80	ns
SCLK Fall to DOUT Valid Propagation Delay	t _{DO2}	C _{LOAD} = 200pF			80	ns
SCLK Rise to CS Fall Delay	t _{CS0}		10			ns
CS Rise to SCLK Rise Hold Time	tcs1		40			ns
CS Pulse Width High	tcsw		100			ns

ELECTRICAL CHARACTERISTICS—MAX5173

 $(V_{DD}=+2.7V\ to\ +3.6V,\ V_{REF}=1.25V,\ AGND=DGND,\ FB=OUT,\ R_L=5k\Omega,\ C_L=100pF\ referenced\ to\ ground,\ T_A=T_{MIN}\ to\ T_{MAX},\ unless\ otherwise\ noted.$ Typical values are at T_A=+25°C).

STATIC PERFORMANCE Resolution 14 Integral Nonlinearity (Note 5) INL MAX5173A Differential Nonlinearity DNL INL Offset Error (Note 2) Vos INL Gain Error GE RL = ∞ Power-Supply Rejection Ratio PSRR INL Output Noise Voltage F = 100kHz INL Output Thermal Noise Density F = 100kHz INL Reference Reference 18 MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp·p + 1.25Vpc, slew-rate limited Reference Feedthrough VREF = 1.6Vp·p + 0.8Vpc, f = 1kHz, code = all 0s VREF = 0.9Vp·p + 1.25Vpc, f = 10kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp·p + 1.25Vpc, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS VIH 2.2 Input Low Voltage VIL Input Leakage Current Inn VIN = 0 or VDD -1 Input Leakage Current Inn VIN = 0 or VDD -1 Input Capacitance CIN DIGITAL OUTPUTS	TYP	MAX	UNITS			
$ \begin{tabular}{ c c c c } Integral Nonlinearity (Note 5) & INL & MAX5173A & MAX5173B & & & & & & & & & & & & & & & & & & &$	STATIC PERFORMANCE					
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			Bits			
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		±2	LSB			
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		±4	FSR			
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		±1	LSB			
Gain Error GE R _L = 5kΩ Power-Supply Rejection Ratio PSRR Output Noise Voltage $f = 100kHz$ Output Thermal Noise Density $f = 100kHz$ REFERENCE Reference Input Range VREF 0 Reference Input Resistance RREF 18 MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5VP-p + 1.25VDC, slew-rate limited Reference Feedthrough VREF = 1.6Vp-p + 0.8VDC, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH 2.2 Input Leakage Current IIN VIN = 0 or VDD -1 Input Capacitance CIN OIN DIGITAL OUTPUTS		±10	mV			
Power-Supply Rejection Ratio PSRR Output Noise Voltage f = 100kHz Output Thermal Noise Density reference Reference Input Range VREF 0 Reference Input Resistance RREF 18 MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25VDC, slew-rate limited Reference Feedthrough VREF = 1.6Vp-p + 0.8VDC, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex 2.2 Input High Voltage VIH 2.2 Input Low Voltage VIL VIL Input Leakage Current IIN VIN = 0 or VDD -1 Input Capacitance CIN DIGITAL OUTPUTS	-0.6	±4	- LSB			
Output Noise Voltage Output Thermal Noise Density REFERENCE Reference Input Range Reference Input Resistance Reference Input Resistance Reference -3dB Bandwidth NULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth Reference Feedthrough VREF = 0.5Vp-p + 1.25Vpc, slew-rate limited VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIL Input Low Voltage VIL Input Leakage Current IIN VIN = 0 or Vpd DIGITAL OUTPUTS	-1.6	±8	LSD			
Output Thermal Noise Density REFERENCE Reference Input Range VREF 0 Reference Input Resistance RREF 18 MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25Vpc, slew-rate limited Reference Feedthrough VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current IIN VIN = 0 or Vpd Input Capacitance CIN	10	120	μV/V			
REFERENCE Reference Input Range VREF 0 Reference Input Resistance RREF 18 MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25Vpc, slew-rate limited VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH 2.2 Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current In VIN = 0 or Vpd - 1 Input Capacitance CIN DIGITAL OUTPUTS	2		LSBp-p			
Reference Input Range VREF 18 Reference Input Resistance RREF 18 MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25VDC, slew-rate limited VREF = 1.6Vp-p + 0.8VDC, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH 2.2 Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current IIN VIN = 0 or VDD -1 Input Capacitance CIN DIGITAL OUTPUTS	50		nV/√Hz			
Reference Input Resistance RREF MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25VpC, slew-rate limited Reference Feedthrough VREF = 1.6Vp-p + 0.8VpC, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio VREF = 0.9Vp-p + 1.25VpC, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH 2.2 Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current IIN VIN = 0 or VpD - 1 Input Capacitance CIN DIGITAL OUTPUTS						
MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25VDC, slew-rate limited Reference Feedthrough VREF = 1.6Vp-p + 0.8VDC, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH 2.2 Input Low Voltage VIL Input Hysteresis Input Leakage Current IIN VIN = 0 or VDD -1 Input Capacitance CIN DIGITAL OUTPUTS		V _{DD} - 1.4	V			
Reference -3dB Bandwidth Reference Feedthrough VREF = 0.5Vp-p + 1.25VDC, slew-rate limited VREF = 1.6Vp-p + 0.8VDC, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current IIN VIN = 0 or VDD DIGITAL OUTPUTS			kΩ			
Reference Feedthrough VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current IIN VIN = 0 or Vpd DIGITAL OUTPUTS			•			
Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current Input Capacitance CIN Code = all 0s VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = 3 FFF Hex VIHZ	350		kHz			
Ratio SINAD code = 3 FFF Hex DIGITAL INPUTS Input High Voltage VIH 2.2 Input Low Voltage VIL VIL Input Hysteresis VHYS -1 Input Leakage Current IIN VIN = 0 or VDD -1 Input Capacitance CIN -1	-84		dB			
Input High Voltage	78		dB			
Input Low Voltage VIL Input Hysteresis VHYS Input Leakage Current IIN VIN = 0 or VDD -1 Input Capacitance CIN DIGITAL OUTPUTS						
Input Hysteresis Input Leakage Current Input Capacitance CIN DIGITAL OUTPUTS VHYS Input Copacitance VHYS INDUSTRIAN OUTPUTS			V			
Input Leakage Current I _{IN} V _{IN} = 0 or V _{DD} -1 Input Capacitance C _{IN}		0.8	V			
Input Capacitance C _{IN} DIGITAL OUTPUTS	200		mV			
DIGITAL OUTPUTS	0.001	±1	μΑ			
	8		pF			
Output High Voltage V_{DD} - V_{DD}).5		V			
Output Low Voltage VoL ISINK = 2mA	0.13	0.4	V			

ELECTRICAL CHARACTERISTICS—MAX5173 (continued)

 $(V_{DD} = +2.7V \text{ to } +3.6V, V_{REF} = 1.25V, \text{ AGND} = \text{DGND}, \text{ FB} = \text{OUT}, \text{ R}_{L} = 5k\Omega, \text{ C}_{L} = 100pF \text{ referenced to ground}, \text{ T}_{A} = \text{T}_{MIN} \text{ to T}_{MAX}, \text{ unless otherwise noted}.$ Typical values are at T_A = +25°C).

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DYNAMIC PERFORMANCE						
Voltage Output Slew Rate	SR			0.6		V/µs
Output Settling Time		To ±0.5LSB, from 10mV to full-scale		12		μs
Output Voltage Swing (Note 3)			0		V_{DD}	V
Current into FB			-0.1	0	0.1	μΑ
Time Required to Exit Shutdown				40		μs
Digital Feedthrough		$\overline{\text{CS}}$ = V _{DD} , DIN = 50kHz; f _{SCLK} = 100kHz, V _{SCLK} = 3Vp-p		1		nV-s
POWER SUPPLIES	,		"			
Positive Supply Voltage	V _{DD}		2.7		3.6	V
Power-Supply Current (Note 4)	I _{DD}			0.26	0.35	mA
Shutdown Current (Note 4)				1	10	μΑ
TIMING CHARACTERISTICS	•					
SCLK Clock Period	tcp		150			ns
SCLK Pulse Width High	tch		75			ns
SCLK Pulse Width Low	tcL		75			ns
CS Fall to SCLK Rise Setup Time	tcss		60			ns
SCLK Rise to $\overline{\text{CS}}$ Rise Hold Time	tcss		0			ns
SDI Setup Time	t _{DS}		60			ns
SDI Hold Time	tDH		0			ns
SCLK Rise to DOUT Valid Propagation Delay	t _{DO1}	CLOAD = 200pF			200	ns
SCLK Fall to DOUT Valid Propagation Delay	t _{DO2}	C _{LOAD} = 200pF			200	ns
SCLK Rise to CS Fall Delay tcso			10			ns
CS Rise to SCLK Rise Hold Time	t _{CS1}		75			ns
CS Pulse Width High	tcsw		150			ns
		<u>I</u>				1

Note 1: INL guaranteed between codes 64 and 16383.

Note 2: Offset is measured at the code that comes closest to 10mV.

Note 3: Accuracy is better than 1.0 LSB for $V_{OUT} = 10 \text{mV}$ to V_{DD} - 180 mV. Guaranteed by PSR test on end points.

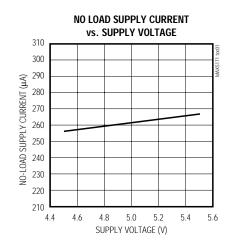
Note 4: R_L = open and digital inputs are either V_{DD} or DGND.

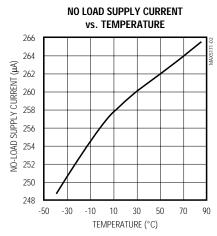
Note 5: INL guaranteed between codes 128 and 16383.

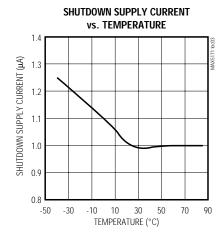
Typical Operating Characteristics

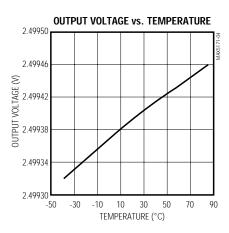
(MAX5171: $V_{DD} = +5V$, $V_{REF} = 2.5V$; MAX5173: $V_{DD} = +3V$, $V_{REF} = 1.25V$; $C_L = 100$ pF, FB = OUT, code = 3FFF hex, $T_A = +25$ °C, unless otherwise noted.)

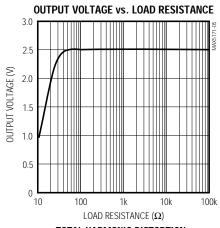
MAX5171

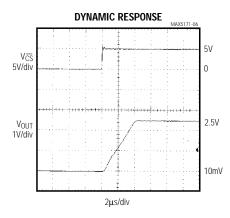


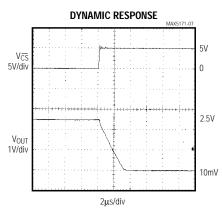


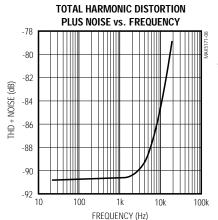


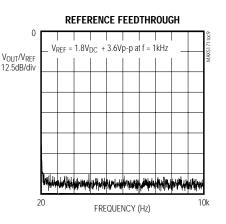








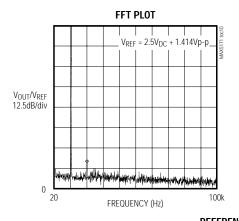


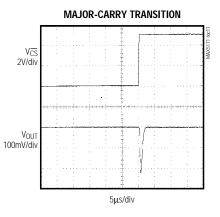


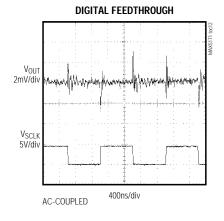
Typical Operating Characteristics (continued)

(MAX5171: V_{DD} = +5V, V_{REF} = 2.5V; MAX5173: V_{DD} = +3V, V_{REF} = 1.25V; C_L = 100pF, FB = OUT, code = 3FFF hex, T_A = +25°C, unless otherwise noted.)

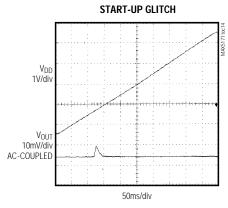
MAX5171



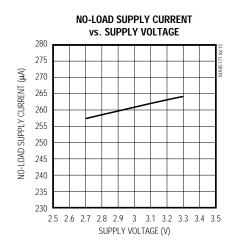


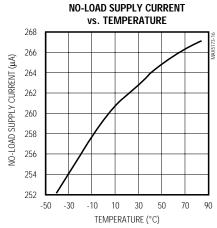


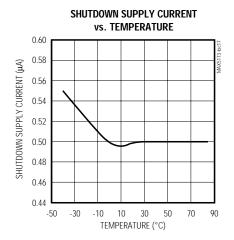
REFERENCE VOLTAGE INPUT FREQUENCY RESPONSE 0 -5 -5 -15 -20 -25 0 500 1000 1500 2000 2500 3000 FREQUENCY (kHz)



MAX5173

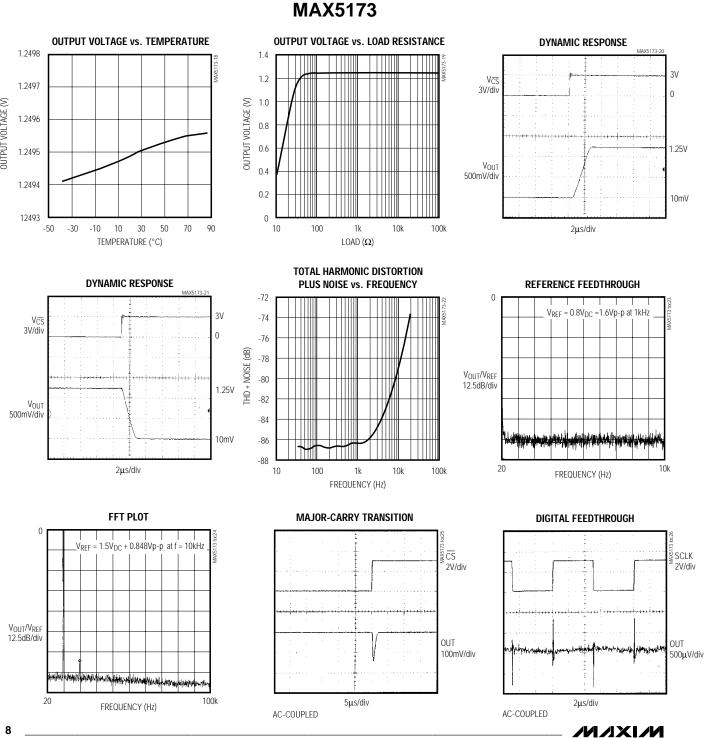






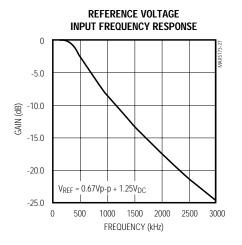
Typical Operating Characteristics (continued)

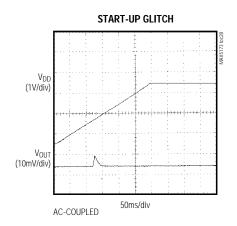
 $(MAX5171: V_{DD} = +5V, V_{REF} = 2.5V; MAX5173: V_{DD} = +3V, V_{REF} = 1.25V; C_{L} = 100pF, FB = OUT, code = 3FFF hex, T_{A} = +25^{\circ}C, T_{A} = +25^{\circ$ unless otherwise noted.)



Typical Operating Characteristics (continued)

(MAX5171: V_{DD} = +5V, V_{REF} = 2.5V; MAX5173: V_{DD} = +3V, V_{REF} = 1.25V; C_L = 100pF, FB = OUT, code = 3FFF hex, T_A = +25°C, unless otherwise noted.)





Pin Description

PIN	NAME	FUNCTION	
1	FB	Feedback Input	
2	OUT	Voltage Output. High impedance in shutdown. Output voltage is limited to V _{DD} .	
3	RS	Reset Mode Select (digital input). Connect to V _{DD} to select midscale reset output value. Connect to DGND o select 0 reset output value.	
4	PDL	Power-Down Lockout (digital input). Connect to $V_{\mbox{\scriptsize DD}}$ to allow shutdown. Connect to DGND to disable shutdown.	
5	CLR	Clear DAC (digital input). Clears the DAC to its predetermined output state as set by RS.	
6	CS	Chip-Select Input (digital input)	
7	DIN	Serial-Data Input (digital input). Data is clocked in on the rising edge of SCLK.	
8	SCLK	Serial Clock Input (digital input)	
9	DGND	Digital Ground	
10	DOUT	Serial-Data Output	
11	UPO	User-Programmable Output. State is set by serial input.	
12	SHDN	Shutdown (digital input). Pulling SHDN high when $\overline{PDL} = V_{DD}$ places the chip in shutdown mode with a maximum shutdown current 0f 10 μ A.	
13	AGND	Analog Ground	
14	REF	Reference Input. Maximum V _{REF} is V _{DD} - 1.4V.	
15	N.C.	No Connection	
16	V _{DD}	Positive Supply. Bypass to AGND with a 4.7μF capacitor in parallel with a 0.1μF capacitor.	

Detailed Description

The MAX5171/MAX5173 14-bit, serial, voltage-output DACs operate with a 3-wire serial interface. These devices include a 16-bit shift register and a double-buffered input composed of an input register and a DAC register (see *Functional Diagram*). In addition, the negative terminal of the output amplifier is available. The DACs are designed with an inverted R-2R ladder network (Figure 1), which produces a weighted voltage proportional to the reference voltage.

Reference Input

The reference input accepts both AC and DC values with a voltage range extending from 0 to V_{DD} - 1.4V. The following equation represents the resulting output voltage:

$$V_{OUT} = \frac{V_{REF} \cdot N \cdot Gain}{16384}$$

where N is the numeric value of the DAC's binary input code (0 to 16383), VREF is the reference voltage, and Gain is the externally set voltage gain. The maximum output voltage is VDD. The reference pin has a minimum impedance of $18k\Omega$ and is code dependent.

Output Amplifier

The MAX5171/MAX5173's DAC output is internally buffered by a precision amplifier with a typical slew rate of 0.6V/µs. Access to the output amplifier's inverting input provides flexibility in output gain setting and signal conditioning (see *Applications Information*).

The output amplifier settles to ± 0.5 LSB from a full-scale transition within 12 μ s, when loaded with 5k Ω in parallel with 100pF. Loads less than 2k Ω degrade performance.

Shutdown Mode

The MAX5171/MAX5173 feature a software- and hardware-programmable shutdown mode that reduces the typical supply current to 1µA. Enter shutdown by writing the appropriate input-control word as shown in Table 1, or by using the hardware shutdown. In shutdown mode, the reference input and amplifier output become high-impedance, and the serial interface remains active. Data in the input register is saved, allowing the MAX5171/MAX5173 to recall the prior output state when returning to normal operation. To exit shutdown, reload the DAC register from the shift register by simultaneously loading the input and DAC registers or by toggling PDL. When returning from shutdown, wait 40µs for the output to settle.

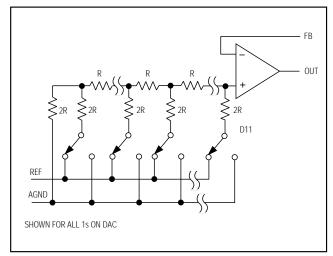


Figure 1. Simplified DAC Circuit Diagram

Power-Down Lockout

Power-down lockout disables the software/hardware shutdown mode. A high-to-low transition on PDL brings the device out of shutdown, returning the output to its previous state.

Shutdown

Pulling SHDN high while \overline{PDL} is high places the MAX5171/MAX5173 in shutdown mode. Pulling SHDN low does not return the device to normal operation. A high-to-low transition on \overline{PDL} or an appropriate command from the serial data line is required to exit shutdown (see Table 1 for commands).

Serial Interface

The MAX5171/MAX5173 3-wire serial interface is compatible with SPI/QSPI (Figure 2) and MICROWIRE (Figure 3) interface standards. The 16-bit serial input word consists of two control bits and 14 bits of data (MSB to LSB).

The control bits determine the MAX5171/MAX5173's response as outlined in Table 1. The MAX5171/MAX5173's digital inputs are double buffered, which allows any of the following:

- Loading the input register without updating the DAC register.
- Updating the DAC register from the input register.
- Updating the input and DAC registers simultaneously.

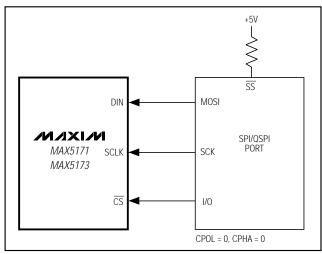


Figure 2. Connections for SPI/QSPI

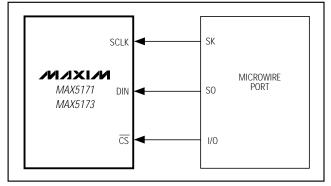


Figure 3. Connections for MICROWIRE

The MAX5171/MAX5173 accepts one 16-bit packet or two 8-bit packets sent while $\overline{\text{CS}}$ remains low. The MAX5171/MAX5173 allow the following to be configured:

- Clock edge on which serial data output (DOUT) is clocked.
- State of the user-programmable logic output.
- Configuration of the reset state.

Specific commands for setting these are shown in Table 1.

The general timing diagram in Figure 4 illustrates how the MAX5171/MAX5173 acquire data. \overline{CS} must go low at least tcss before the rising edge of the serial clock (SCLK). With \overline{CS} low, data is clocked into the register on the rising edge of SCLK. The maximum serial clock frequency guaranteed for proper operation is 10MHz for the MAX5171 and 6MHz for the MAX5173. See Figure 5 for a detailed timing diagram of the serial interface.

Serial Data Output (DOUT)

The serial-data output, DOUT, is the internal shift register's output; it allows for daisy-chaining of multiple devices as well as data readback (see *Applications Information*). By default upon start-up, data shifts out of DOUT on the serial clock's rising edge (Mode 0) and provides a lag of 16 clock cycles, thus maintaining SPI, QSPI, and MICROWIRE compatibility. However, if the device is programmed for Mode 1, then the output data lags DIN by 16.5 clock cycles and is clocked out on the serial clock's rising edge. During shutdown, DOUT retains its last digital state prior to shutdown.

User-Programmable Logic Output (UPO)

The UPO allows control of an external device through the serial interface, thereby reducing the number of

Table 1. Serial-Interface Programming Commands

16-BIT SERIAL WORD		FUNCTION
C0	D13D0	FUNCTION
0	14-bit DAC data	Load input register; DAC registers are unchanged.
1	14-bit DAC data	Load input register; DAC registers are updated (start up DAC with new data).
0	x x x xxx xxxx xxxx	Update DAC register from input register (start up DAC with data previously stored in the input registers).
1	0 0 x xxx xxxx xxxx	No operation (NOP).
1	0 1 x xxx xxxx xxxx	Shut down DAC (provided PDL = 1).
1	1 0 0 xxx xxxx xxxx	UPO goes low (default).
1	1 0 1 xxx xxxx xxxx	UPO goes high.
1	1 1 0 xxx xxxx xxxx	Mode 1, DOUT clocked out on SCLK's rising edge.
1	1 1 1 xxx xxxx xxxx	Mode 0, DOUT clocked out on SCLK's falling edge (default).
	C0 0 1	C0 D13D0 0 14-bit DAC data 1 14-bit DAC data 0 x x x xxx xxxx xxxx 1 0 0 x xxx xxxx xxxx 1 0 1 x xxx xxxx xxxx 1 1 0 0 xxx xxxx xxxx 1 1 0 1 xxx xxxx xxxx 1 1 1 0 xxx xxxx xxxx

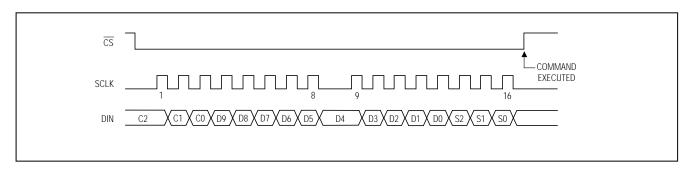


Figure 4. Serial-Interface Timing Diagram

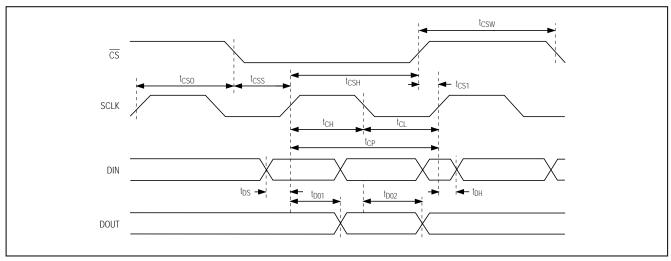


Figure 5. Detailed Serial-Interface Timing Diagram

microcontroller I/O pins required. During power-down, this output will retain its digital state prior to shutdown. When CLR is pulled low, UPO will reset to its programmed default state. See Table 1 for specific commands to control the UPO.

Reset (RS) and Clear (CLR)

The MAX5171/MAX5173 offers a clear pin which resets the output voltage. If RST = DGND, then $\overline{\text{CLR}}$ resets the output voltage to the minimum voltage (0 if no offset is introduced). If RST = VDD, then $\overline{\text{CLR}}$ resets the output voltage to midscale. In either case, $\overline{\text{CLR}}$ resets UPO to its programmed default state.

Applications Information

Unipolar Output

Figure 6 shows the MAX5171/MAX5173 configured for unipolar, rail-to-rail operation with a gain of +2V/V. Table 2 lists the codes for unipolar output voltages. The output voltage is limited to V_{DD} .

Bipolar Output

Figure 7 shows the MAX5171/MAX5173 configured for bipolar output operation. The output voltage is given by the following equation (FB = OUT):

$$V_{OUT} = V_{REF} \left(\frac{2 \cdot N}{16384} - 1 \right)$$

where N represents the numeric value of the DAC's binary input code and VREF is the voltage of the external reference. Table 3 shows digital codes and the corresponding output voltage for Figure 7's circuit.

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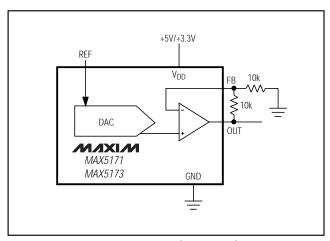


Figure 6. Unipolar Output Circuit (Rail-to-Rail)

Table 2. Unipolar Code Table (Circuit of Figure 6)

DAC CONTENTS MSB LSB	ANALOG OUTPUT
11 1111 1111 1111	2 • V _{REF} (16383/16384)
10 0000 0000 0001	2 • V _{REF} (8193/16384)
10 0000 0000 0000	2 • V _{REF} (8192/16384)
01 1111 1111 1111	2 • V _{REF} (8191/16384)
00 0000 0000 0001	2 • V _{REF} (1/16384)
00 0000 0000 0000	0

Daisy-Chaining Devices

The serial data output pin (DOUT) allows multiple MAX5171/MAX5173s to be daisy-chained together, as shown in Figure 8. The advantage of this is that only two lines are needed to control all of the DACs on the line. The disadvantage is that it takes *n* commands to program the DACs. Figure 9 shows several MAX5171/MAX5173s sharing one common DIN signal line. In this configuration, the data bus is common to all devices. However, this configuration uses more I/O lines because each device requires a dedicated $\overline{\text{CS}}$ line. The benefit is that only one command is needed to program any DAC.

Using an AC Reference

The MAX5171/MAX5173 accepts reference voltages with AC components as long as the reference voltage remains between 0 and V_{DD} - 1.4V. Figure 10 shows a technique for applying a sine-wave signal to the REF. The reference voltage must remain above AGND.

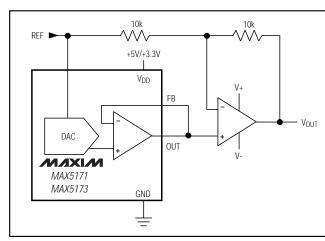


Figure 7. Bipolar Output Circuit

Table 3. Bipolar Code Table (Circuit of Figure 7)

DAC CONTENTS MSB LSB	ANALOG OUTPUT
11 1111 1111 1111	+V _{REF} [(2 • 16383/16384) - 1]
10 0000 0000 0001	+V _{REF} [(2 • 8193/16384) - 1]
10 0000 0000 0000	+V _{REF} [(2 • 8192/16384) - 1]
01 1111 1111 1111	+VREF [(2 • 8191/16384) - 1]
00 0000 0000 0001	+V _{REF} [(2 • 1/16384) - 1]
00 0000 0000 0000	-V _{REF}

Digitally Programmable Current Source

The circuit of Figure 11 places an NPN transistor (2N3904 or similar) within the op amp feedback loop to implement a digitally programmable, unidirectional current source. The output current is calculated with the following equation:

$$I_{OUT} = \frac{V_{REF} \cdot N}{R \cdot 16384}$$

where N is the numeric value of the DAC's binary input code and R is the sense resistor shown in Figure 11.

Power-Supply and Layout Considerations

Wire-wrap boards are not recommended. For optimum system performance, use PC boards with separate analog and digital ground planes. Connect the two ground planes together at the low-impedance power-supply source. Connect the DGND and AGND pins together at the IC. The best ground connection is achieved by connecting the DAC's DGND and AGND pins together and connecting that point to the system analog ground plane. If the DAC's DGND is connected to the system digital ground, digital noise may get through to the DAC's analog portion.

Bypass the power supply with a $4.7\mu F$ capacitor in parallel with a $0.1\mu F$ capacitor to AGND. Minimize the capacitor lead lengths to reduce inductance. If noise becomes an issue, use shielding and/or ferrite beads to increase isolation.

To maintain INL and DNL performance, as well as gain drift, it is extremely important to provide the lowest possible reference output impedance at the DAC reference input pin. INL degrades if the series resistance on the REF pin exceeds 0.1Ω . The same consideration must be made for the AGND pin.

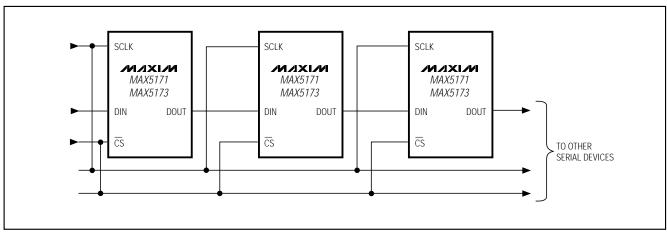


Figure 8. Daisy-Chaining MAX5171/MAX5173 Devices

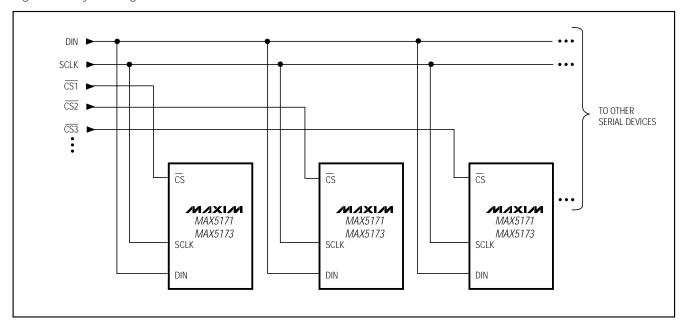
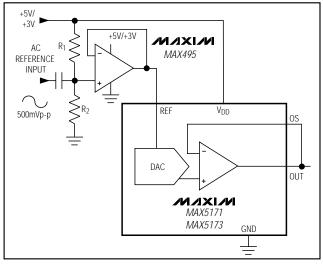


Figure 9. Multiple MAX5171/MAX5173s Sharing Common DIN and SCLK Lines



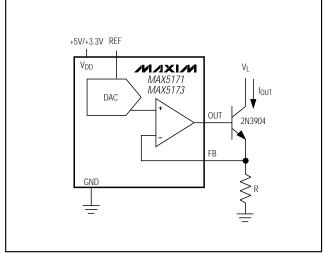
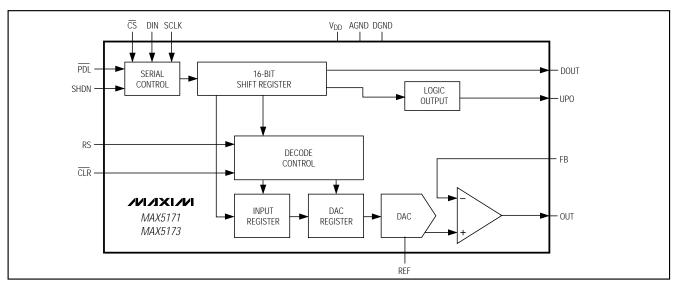


Figure 10. AC Reference Input Circuit

Figure 11. Digitally Programmable Current Source

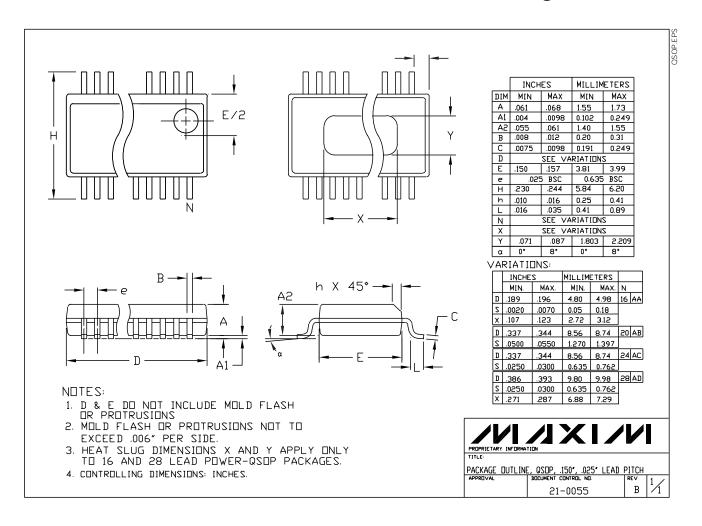
Functional Diagram



Chip Information

TRANSISTOR COUNT: 3457

Package Information



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