

General Description

The MAX5175/MAX5177 low-power, serial, voltage-output, 12-bit digital-to-analog converters (DACs) feature a precision output amplifier in a space-saving 16-pin QSOP package. The MAX5175 operates from a single +5V supply, and the MAX5177 operates from a single +3V supply. The output amplifier's inverting input is available to allow specific gain configurations, remote sensing, and high output current capability. This makes the MAX5175/MAX5177 ideal for a wide range of applications, including industrial process control. Both devices draw only 260µA of supply current, which reduces to 1µA in shutdown mode. In addition, the programmable power-up reset feature allows for a userselectable output voltage state of either 0 or midscale.

The 3-wire serial interface is compatible with SPI™, QSPI™, and MICROWIRE™ standards. An input register followed by a DAC register provides a double-buffered input, allowing the registers to be updated independently or simultaneously with a 16-bit serial word. Additional features include software and hardware shutdown, shutdown lockout, a hardware reset pin, and a reference input capable of accepting DC and offset AC signals. These devices provide a programmable digital output pin for added functionality and a serial-data output pin for daisy-chaining. All logic inputs are TTL/CMOS compatible and are internally buffered with Schmitt triggers to allow direct interfacing to optocouplers.

The MAX5175/MAX5177 incorporate a proprietary on-chip circuit that keeps the output voltage virtually "glitch free," limiting the glitches to a few millivolts during power-up.

Both devices come in 16-pin QSOP packages and are specified for the extended (-40°C to +85°C) temperature range. The MAX5171/MAX5173 are 14-bit pin-compatible upgrades to the MAX5175/MAX5177. For pin-compatible DACs with an internal reference, see the 13-bit MAX5132/MAX5133 and 12-bit MAX5122/MAX5123.

Applications

Digitally Programmable 4–20mA Current Loops **Industrial Process Controls** Digital Offset and Gain Adjustment Motion Control Automatic Test Equipment (ATE) Remote Industrial Controls µP-Controlled Systems

Functional Diagram appears at end of data sheet.

SPI and QSPI are trademarks of Motorola, Inc. MICROWIRE is a trademark of National Semiconductor Corp. Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.

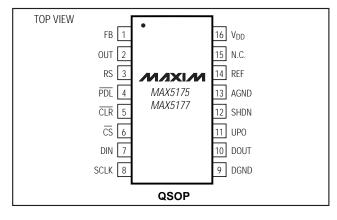
Features

- ♦ ±1 LSB INL
- ↑ 1µA Shutdown Current
- ◆ "Glitch Free" Output Voltage at Power-Up
- **♦** Single-Supply Operation
 - +5V (MAX5175)
 - +3V (MAX5177)
- **♦ Full-Scale Output Range**
 - +2.048V (MAX5177, VREF = +1.25V)
 - +4.096V (MAX5175, $V_{REF} = +2.5V$)
- **♦** Rail-to-Rail[®] Output Amplifier
- ♦ Adjustable Output Offset
- ♦ Low THD (-80dB) in Multiplying Operation
- **♦ SPI/QSPI/MICROWIRE-Compatible 3-Wire Serial Interface**
- ♦ Programmable Shutdown Mode and Power-Up Reset (0 or midscale)
- ♦ Buffered Output Capable of Driving 4-20mA or $5k\Omega \parallel 100pF Loads$
- ♦ User-Programmable Digital Output Pin Allows **Serial Control of External Components**
- ↑ 14-Bit Upgrades Available (MAX5171/MAX5173)

Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE	INL (LSB)
MAX5175AEEE	-40°C to +85°C	16 QSOP	±1
MAX5175BEEE	-40°C to +85°C	16 QSOP	±2
MAX5177AEEE	-40°C to +85°C	16 QSOP	±2
MAX5177BEEE	-40°C to +85°C	16 QSOP	±4

Pin Configuration



NIXIN

ABSOLUTE MAXIMUM RATINGS

VDD to AGND, DGND	0.3V to +6V
AGND to DGND	0.3V to +0.3V
Digital Inputs to DGND	0.3V to +6V
DOUT, UPO to DGND	0.3V to (V _{DD} + 0.3V)
FB, OUT REF to AGND	0.3V to (V _{DD} + 0.3V)
Maximum Current into Any Pin	50mA

Continuous Power Dissipation ($T_A = +70^{\circ}C$)	
16-Pin QSOP (derate 8mW/°C above +70°C).	667mW
Operating Temperature Range	40°C to +85°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS—MAX5175

 $(V_{DD} = +5V \pm 10\%, V_{REF} = 2.5V, AGND = DGND, FB = OUT, R_{L} = 5k\Omega, C_{L} = 100pF$ referenced to ground, $T_{A} = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_{A} = +25$ °C.)

PARAMETER SYM		CONDITIONS	MIN	TYP	MAX	UNITS
STATIC PERFORMANCE						
Resolution			12			Bits
Integral Nonlinearity (Note 1)	INL	MAX5175A			±1	LSB
integral Norminearity (Note 1)	IINL	MAX5175B			±2	LSD
Differential Nonlinearity	DNL				±1	LSB
Offset Error (Note 2)	Vos				±10	mV
Gain Error	GE	R _L = ∞		-0.6	±4	LSB
Gain Endi	GL	$R_L = 5k\Omega$		-1.6	±8	LJD
Power-Supply Rejection Ratio	PSRR			10	120	μV/V
Output Noise Voltage		f = 100kHz		1		LSBp-p
Output Thermal Noise Density				50		nV/√Hz
REFERENCE INPUT						
Reference Input Range	V _{REF}		0		V _{DD} - 1.4	V
Reference Input Resistance	RREF		18			kΩ
MULTIPLYING-MODE PERFOR	MANCE					
Reference -3dB Bandwidth		V _{REF} = 0.5Vp-p + 2.5V _{DC} , slew-rate limited		350		kHz
Reference Feedthrough		$V_{REF} = 3.6Vp-p + 1.8V_{DC}$, $f = 1kHz$, $code = all 0s$		-84		dB
Signal-to-Noise Plus Distortion Ratio	SINAD	V _{REF} = 1.4Vp-p + 2.5V _{DC} , f = 10kHz, code = FFF hex		84		dB
DIGITAL INPUTS						
Input High Voltage	VIH		3			V
Input Low Voltage	VIL				0.8	V
Input Hysteresis	V _H YS			200		mV
Input Leakage Current	liN	VIN = 0 or VDD		0.001	±1	μΑ
Input Capacitance	CIN			8		pF
DIGITAL OUTPUTS	-		·			
Output High Voltage	Voh	ISOURCE = 2mA	V _{DD} - 0.5			V
Output Low Voltage	VoL	I _{SINK} = 2mA		0.13	0.4	V

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ELECTRICAL CHARACTERISTICS—MAX5175 (continued)

 $(V_{DD} = +5V \pm 10\%, V_{REF} = 2.5V, AGND = DGND, FB = OUT, R_L = 5k\Omega, C_L = 100pF$ referenced to ground, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25$ °C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DYNAMIC PERFORMANCE						
Voltage Output Slew Rate	SR			0.6		V/µs
Output Settling Time		To ±0.5LSB, from 10mV to full-scale		12		μs
Output Voltage Swing (Note 3)			0		V_{DD}	V
Current into FB			-0.1	0	0.1	μΑ
Time Required to Exit Shutdown				40		μs
Digital Feedthrough		$\overline{\text{CS}}$ = V _{DD} ; f _{SCLK} = 100kHz, V _{SCLK} = 5Vp-p		1		nV-s
POWER SUPPLIES	•					
Positive Supply Voltage	V _{DD}		4.5		5.5	V
Power-Supply Current (Note 4)	IDD			0.26	0.35	mA
Shutdown Current (Note 4)				1	10	μΑ
TIMING CHARACTERISTICS	•					
SCLK Clock Period	tcp		100			ns
SCLK Pulse Width High	tсн		40			ns
SCLK Pulse Width Low	t _{CL}		40			ns
CS Fall to SCLK Rise Setup Time	tcss		40			ns
SCLK Rise to $\overline{\text{CS}}$ Rise Hold Time	tcsh		0			ns
SDI Setup Time	t _{DS}		40			ns
SDI Hold Time	tDH		0			ns
SCLK Rise to DOUT Valid Propagation Delay	t _{DO1}	C _{LOAD} = 200pF			80	ns
SCLK Fall to DOUT Valid Propagation Delay		CLOAD = 200pF			80	ns
SCLK Rise to CS Fall Delay	t _{CS0}		10			ns
CS Rise to SCLK Rise Hold Time	tcs1		40			ns
CS Pulse Width High	tcsw		100			ns

ELECTRICAL CHARACTERISTICS—MAX5177

 $(V_{DD} = +2.7V \text{ to } +3.6V, V_{REF} = 1.25V, AGND = DGND, FB = OUT, R_L = 5k\Omega, C_L = 100pF referenced to ground, T_A = T_{MIN} \text{ to } T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)$

Resolution 12	PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Integral Nonlinearity (Note 5) INL MAX5177A ±2 LSB MAX5177B ±4 ±4 LSB MAX5177B ±1 MV MAX5177B ±1 MV MAX5177B ±1 MV MAX5177B ±1 MV MAX5177B ±1 MX MX5177B ±1 MX517TB ±1 MX51	STATIC PERFORMANCE						
Integral Nonlinearity (Note 5) INL MAX5177B ±4 LSB	Resolution			12			Bits
MAX5177B	Integral Nonlinearity (Note E)	INII	MAX5177A			±2	LCD
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Integral Northhearty (Note 5)	IIVL	MAX5177B			±4	LSD
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Differential Nonlinearity	DNL				±1	LSB
Gain Error GE RL = 5kΩ -1.6 ±8 LSB Power-Supply Rejection Ratio PSRR 10 120 μ/V/V Output Noise Voltage f = 100kHz 2 LSBp-p Output Thermal Noise Density 50 nV/NEZ REFERENCE 50 VDD - 1.4 V Reference Input Range NREF 0 VDD - 1.4 V Reference Input Resistance RREF 18 × kΩ MULTIPLYING-MODE PERFORMANCE 18 × kΩ Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25Vpc, slew-rate limited 350 kHz Reference Feedthrough VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s -84 dB Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = FFF hex 78 dB DIGITAL INPUTS VII 0.8 V Input High Voltage VIL 0.8 V Input Hysteresis VHys 200 mV Input Leakage Current Inp VIN	Offset Error (Note 2)	Vos				±10	mV
Power-Supply Rejection Ratio PSRR Power-Supply Po	Gain Error	GE	R _L = ∞		-0.6	±4	LCB
Output Noise Voltagef = 100kHz2LSBp-pOutput Thermal Noise Density50nV/NHZREFERENCEReference Input RangeVREF0VDD - 1.4VReference Input ResistanceRREF18kΩMULTIPLYING-MODE PERFORMANCEReference -3dB BandwidthVREF = 0.5Vp-p + 1.25VDC, slew-rate limited350kHzReference FeedthroughVREF = 1.6Vp-p + 0.8VDC, f = 1kHz, code = all 0s-84dBSignal-to-Noise Plus Distortion RatioSINADVREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = FFF hex78dBDIGITAL INPUTSInput High VoltageVIH2.2VInput Low VoltageVIL2.2VInput HysteresisVHYS200mVInput Leakage CurrentInnVIN = 0 or VDD0.001±1μAInput CapacitanceCINN150URCE = 2mAVDD - 0.5V	Gairr Error	GL	$R_L = 5k\Omega$		-1.6	±8	LJD
Output Thermal Noise Density 50 nV/NHZ REFERENCE Reference Input Range VREF 0 VDD - 1.4 V Reference Input Resistance RREF 18 kΩ kΩ MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5VP-p + 1.25VDC, slew-rate limited 350 kHz Reference Feedthrough VREF = 1.6Vp-p + 0.8VDC, f = 1kHz, code = all 0s -84 dB Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25VDC, f = 10kHz, code = FFF hex 78 dB DIGITAL INPUTS Input High Voltage VIH 2.2 V Input Low Voltage VIL 2.2 V Input Hysteresis VHYS 200 mV Input Leakage Current I _{IN} VIN = 0 or VDD 0.001 ±1 μA Input Capacitance C _{IN} VOH 8 pF	Power-Supply Rejection Ratio	PSRR			10	120	μV/V
REFERENCE Reference Input Range VREF 0 VDD - 1.4 V Reference Input Resistance RREF 18 kΩ MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25Vpc, slew-rate limited 350 kHz Reference Feedthrough VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s -84 dB Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = FFF hex 78 dB DIGITAL INPUTS Input High Voltage VIH 2.2 V Input Low Voltage VIL 0.8 V Input Hysteresis VHYS 200 mV Input Leakage Current In VIN = 0 or VpD 0.001 ±1 μA Input Capacitance CIN 8 pF DIGITAL OUTPUTS Output High Voltage Voh Isource = 2mA Vpp - 0.5 V	Output Noise Voltage		f = 100kHz		2		LSBp-p
Reference Input Range VREF 0 VDD - 1.4 V Reference Input Resistance RREF 18 kΩ MULTIPLYING-MODE PERFORMANCE Reference -3dB Bandwidth VREF = 0.5Vp-p + 1.25Vpc, slew-rate limited 350 kHz Reference Feedthrough VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s -84 dB Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = FFF hex 78 dB DIGITAL INPUTS Input High Voltage VIH 2.2 V Input Low Voltage VIL 0.8 V Input Hysteresis VHYS 200 mV Input Leakage Current Input Vin = 0 or Vpd 0.001 ±1 μA Input Capacitance Cin 8 pF DIGITAL OUTPUTS Output High Voltage VOH Isource = 2mA VDD - 0.5 V	Output Thermal Noise Density				50		nV/√Hz
Reference Input Resistance RREF 18 kΩ MULTIPLYING-MODE PERFORMANCE Reference - 3dB Bandwidth VREF = 0.5Vp-p + 1.25Vpc, slew-rate limited 350 kHz Reference Feedthrough VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s -84 dB Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = FFF hex 78 dB DIGITAL INPUTS Input High Voltage VIH 2.2 V Input Low Voltage VIL 0.8 V Input Hysteresis VHYS 200 mV Input Leakage Current Ilin VIN = 0 or VDD 0.001 ±1 μΑ DIGITAL OUTPUTS Output High Voltage VOH Isource = 2mA VDIS NOTE = 2mA	REFERENCE						
MULTIPLYING-MODE PERFORMANCEReference -3dB BandwidthVREF = 0.5Vp-p + 1.25Vpc, slew-rate limited350kHzReference FeedthroughVREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s-84dBSignal-to-Noise Plus Distortion RatioSINADVREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = FFF hex78dBDIGITAL INPUTSInput High VoltageVIH2.2VInput Low VoltageVIL0.8VInput HysteresisVHYS200mVInput Leakage CurrentInnut VIN = 0 or VDD0.001±1μAInput CapacitanceCIN8pFDIGITAL OUTPUTSOutput High VoltageVOHIsource = 2mAVDD - 0.5V	Reference Input Range	VREF		0		V _{DD} - 1.4	V
Reference -3dB BandwidthVREF = 0.5Vp-p + 1.25VpC, slew-rate limited350kHzReference FeedthroughVREF = 1.6Vp-p + 0.8VpC, f = 1kHz, code = all 0s-84dBSignal-to-Noise Plus Distortion RatioSINADVREF = 0.9Vp-p + 1.25VpC, f = 10kHz, code = FFF hex78dBDIGITAL INPUTSInput High VoltageVIH2.2VInput Low VoltageVIL0.8VInput HysteresisVHYS200mVInput Leakage CurrentIINVIN = 0 or VpD0.001±1μAInput CapacitanceCIN8pFDIGITAL OUTPUTSOutput High VoltageVohIsource = 2mAVpp - 0.5V	Reference Input Resistance	R _{REF}		18			kΩ
Reference Feedthrough VREF = 1.6Vp-p + 0.8Vpc, f = 1kHz, code = all 0s -84 dB Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = FFF hex 78 dB DIGITAL INPUTS Input High Voltage VIH 2.2 V Input Low Voltage VIL 0.8 V Input Hysteresis VHYS 200 mV Input Leakage Current IIN VIN = 0 or Vpd 0.001 ±1 μA Input Capacitance CIN 8 pF DIGITAL OUTPUTS Output High Voltage Voh Isource = 2mA Vpd - 0.5 V	MULTIPLYING-MODE PERFOR	MANCE					
Signal-to-Noise Plus Distortion Ratio SINAD VREF = 0.9Vp-p + 1.25Vpc, f = 10kHz, code = FFF hex 78 dB DIGITAL INPUTS Input High Voltage VIH 2.2 V Input Low Voltage VIL 0.8 V Input Hysteresis VHYS 200 mV Input Leakage Current IIN VIN = 0 or VDD 0.001 ±1 µA Input Capacitance CIN 8 pF DIGITAL OUTPUTS Output High Voltage VOH Isource = 2mA VDD - 0.5 V	Reference -3dB Bandwidth		V _{REF} = 0.5Vp-p + 1.25V _{DC} , slew-rate limited		350		kHz
Ratio SINAD code = FFF hex 78 dB DIGITAL INPUTS Input High Voltage VIH 2.2 V Input Low Voltage VIL 0.8 V Input Hysteresis VHYS 200 mV Input Leakage Current IIN VIN = 0 or VDD 0.001 ±1 μA Input Capacitance CIN 8 pF DIGITAL OUTPUTS Output High Voltage VOH Isource = 2mA VDD - 0.5 V	Reference Feedthrough				-84		dB
Input High Voltage V _{IH} 2.2 V Input Low Voltage V _{IL} 0.8 V Input Hysteresis V _{HYS} 200 mV Input Leakage Current I _{IN} V _{IN} = 0 or V _{DD} 0.001 ±1 μA Input Capacitance C _{IN} 8 pF DIGITAL OUTPUTS Output High Voltage V _{OH} I _{SOURCE} = 2mA V _{DD} - 0.5 V		SINAD			78		dB
Input Low Voltage	DIGITAL INPUTS	'					
Input Hysteresis VHYS 200 mV Input Leakage Current I _{IN} V _{IN} = 0 or V _{DD} 0.001 ±1 μA Input Capacitance C _{IN} 8 pF DIGITAL OUTPUTS Output High Voltage V _{OH} I _{SOURCE} = 2mA V _{DD} - 0.5 V	Input High Voltage	V _{IH}		2.2			V
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Input Low Voltage	VIL				0.8	V
Input Capacitance C _{IN} 8 pF DIGITAL OUTPUTS Output High Voltage V _{OH} Isource = 2mA V _{DD} - 0.5 V	Input Hysteresis	VHYS			200		mV
DIGITAL OUTPUTS Output High Voltage Voh Isource = 2mA VDD - 0.5 V	Input Leakage Current	I _{IN}	V _{IN} = 0 or V _{DD}		0.001	±1	μΑ
Output High Voltage VoH Isource = 2mA VDD - 0.5 V	Input Capacitance	CIN			8		рF
	DIGITAL OUTPUTS	•		•			
Output Low Voltage VoL ISINK = 2mA 0.13 0.4 V	Output High Voltage	VoH	ISOURCE = 2mA	V _{DD} - 0.5			V
	Output Low Voltage	Vol	I _{SINK} = 2mA		0.13	0.4	V

ELECTRICAL CHARACTERISTICS—MAX5177 (continued)

 $(V_{DD} = +2.7V \text{ to } +3.6V, V_{REF} = 1.25V, AGND = DGND, FB = OUT, R_L = 5k\Omega, C_L = 100pF referenced to ground, T_A = T_{MIN} \text{ to } T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)$

Voltage Output Slew Rate SR Output Slew Rate To ±0.5LSB, from 10mV to full-scale 12	PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Settling Time To ±0.5LSB, from 10mV to full-scale 12 μs Output Voltage Swing (Note 3) 0 VDD V Current Info FB 0.0.1 0 0.1 μA Time Required to Exit Shutdown 40 μs μs Digital Feedthrough 25 = VDD, DIN = 50kHz, fscLK = 100kHz, fscLK = 100kHz, fscLK = 100kHz, fscLK = 100kHz, fscLK = 3VD-D 1 nV-s POWER SUPPLIES Post SUPPLIES 2.7 3.6 V Power-Supply Current (Note 4) Ibp 0.26 0.35 mA Year Supply Current (Note 4) Ibp 0.26 0.35 mA TMIMING CHARACTERISTICS SCLK Clock Period 1 1 0 μA TMIMING CHARACTERISTICS SCLK Pulse Width High 1 1 1 ns SCLK Pulse Width Low 1cL 75 ns ns SCLK Rise Setup Time 1cSs 60 ns SCLK Rise to CS Rise Hold Time 1 1 1 ns SCLK Rise to DOUT Valid Propagation Delay	DYNAMIC PERFORMANCE	•		<u> </u>			
Output Voltage Swing (Note 3) 0 VDD V Current into FB -0.1 0 0.1 μA Time Required to Exit Shutdown 40 μs Digital Feedthrough ∇SC = VDD, DIN = 50kHz, fSCLK = 100kHz, fSCLK = 10	Voltage Output Slew Rate	SR			0.6		V/µs
Current into FB Current into FB City	Output Settling Time		To ±0.5LSB, from 10mV to full-scale		12		μs
Time Required to Exit Shutdown CS = VDD, DIN = 50kHz, fSCLK = 100kHz, VSCLK = 3VP-P	Output Voltage Swing (Note 3)			0		V _{DD}	V
Digital Feedthrough SCS = VDD, DIN = 50kHz, fSCLK = 100kHz, VSCLK = 3Vp-p 1	Current into FB			-0.1	0	0.1	μA
No Scitive Supply Voltage VDD Supply VDD	Time Required to Exit Shutdown				40		μs
Positive Supply Voltage VDD 2.7 3.6 V	Digital Feedthrough				1		nV-s
Power-Supply Current (Note 4) IDD	POWER SUPPLIES	'		<u>'</u>			
Shutdown Current (Note 4) 1 10 μA TIMING CHARACTERISTICS SCLK Clock Period tcp 150 ns SCLK Pulse Width High tch 75 ns SCLK Pulse Width Low tcl 75 ns CS Fall to SCLK Rise Setup Time tcss 60 ns SCLK Rise to CS Rise Hold Time tcsh 0 ns SDI Setup Time tbs 60 ns SDI Hold Time tbH 0 ns SCLK Rise to DOUT Valid Propagation Delay tbO1 CLOAD = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay tbO2 CLOAD = 200pF 200 ns SCLK Rise to CS Fall Delay tcso 10 ns SCLK Rise to SCLK Rise Hold Time tcsi 75 ns	Positive Supply Voltage	V _{DD}		2.7		3.6	V
TIMING CHARACTERISTICS SCLK Clock Period tcp 150 ns	Power-Supply Current (Note 4)	IDD			0.26	0.35	mA
SCLK Clock Period tcP 150 ns SCLK Pulse Width High tCH 75 ns SCLK Pulse Width Low tCL 75 ns CS Fall to SCLK Rise Setup Time tCSS 60 ns SCLK Rise to CS Rise Hold Time tCSH 0 ns SDI Setup Time tDS 60 ns SDI Hold Time tDH 0 ns SCLK Rise to DOUT Valid Propagation Delay tDO1 CLOAD = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay tDO2 CLOAD = 200pF 200 ns SCLK Rise to CS Fall Delay tCS0 10 ns CS Rise to SCLK Rise Hold Time tCS1 75 ns	Shutdown Current (Note 4)				1	10	μΑ
SCLK Pulse Width High tCH 75 ns SCLK Pulse Width Low tcL 75 ns CS Fall to SCLK Rise Setup Time tcss 60 ns SCLK Rise to CS Rise Hold Time tcsh 0 ns SDI Setup Time tbs 60 ns SDI Hold Time tbh 0 ns SCLK Rise to DOUT Valid Propagation Delay tbo1 CLOAD = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay tbo2 CLOAD = 200pF 200 ns SCLK Rise to CS Fall Delay tcso 10 ns CS Rise to SCLK Rise Hold Time tcsi 75 ns	TIMING CHARACTERISTICS	•					
SCLK Pulse Width Low t _{CL} 75 ns \$\overline{\text{CS}}\$ Fall to SCLK Rise Setup Time t _{CSS} 60 ns SCLK Rise to \$\overline{\text{CS}}\$ Rise Hold Time t _{CSH} 0 ns SDI Setup Time t _{DS} 60 ns SDI Hold Time t _{DH} 0 ns SCLK Rise to DOUT Valid Propagation Delay t _{DO1} C _{LOAD} = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay t _{DO2} C _{LOAD} = 200pF 200 ns SCLK Rise to \$\overline{\text{CS}}\$ Fall Delay t _{CSO} 10 ns \$\overline{\text{CS}}\$ Rise to SCLK Rise Hold Time t _{CS1} 75 ns	SCLK Clock Period	tcp		150			ns
CS Fall to SCLK Rise Setup Time tCSS 60 ns SCLK Rise to CS Rise Hold Time tCSH 0 ns SDI Setup Time tDS 60 ns SDI Hold Time tDH 0 ns SCLK Rise to DOUT Valid Propagation Delay tD01 CLOAD = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay tD02 CLOAD = 200pF 200 ns SCLK Rise to CS Fall Delay tCS0 10 ns CS Rise to SCLK Rise Hold Time tCS1 75 ns	SCLK Pulse Width High	tсн		75			ns
Time ICSS 60 IIS SCLK Rise to \overline{CS} Rise Hold Time tCSH 0 ns SDI Setup Time tDS 60 ns SDI Hold Time tDH 0 ns SCLK Rise to DOUT Valid Propagation Delay tDO1 CLOAD = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay tDO2 CLOAD = 200pF 200 ns SCLK Rise to \overline{CS} Fall Delay tCSO 10 ns \overline{CS} Rise to SCLK Rise Hold Time tCS1 75 ns	SCLK Pulse Width Low	tcL		75			ns
Time tCSH 0 ns SDI Setup Time tDS 60 ns SDI Hold Time tDH 0 ns SCLK Rise to DOUT Valid Propagation Delay tDO1 CLOAD = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay tDO2 CLOAD = 200pF 200 ns SCLK Rise to CS Fall Delay tCS0 10 ns CS Rise to SCLK Rise Hold Time tCS1 75 ns	CS Fall to SCLK Rise Setup Time	t _{CSS}		60			ns
SDI Hold TimetDH0nsSCLK Rise to DOUT Valid Propagation DelaytDO1 $C_{LOAD} = 200pF$ 200nsSCLK Fall to DOUT Valid Propagation DelaytDO2 $C_{LOAD} = 200pF$ 200nsSCLK Rise to \overline{CS} Fall DelaytCS010ns \overline{CS} Rise to SCLK Rise Hold TimetCS175ns		tcsh		0			ns
SCLK Rise to DOUT Valid Propagation Delay \$\text{SCLK Rise to DOUT Valid Propagation Delay} \text{ tDO1} \text{ \$CLOAD} = 200pF \text{ 200} \text{ ns} \text{ SCLK Fall to DOUT Valid Propagation Delay} \text{ tDO2} \text{ \$CLOAD} = 200pF \text{ 200} \text{ ns} \text{ SCLK Rise to \$\overline{\text{CS}}\$ Fall Delay \text{ tcs0} \text{ 10} \text{ ns} \text{ ns} \text{ T5} \text{ ns} \text{ ns} \text{ ns} \text{ T5} \text{ ns} \text{ ns} \text{ ns} \text{ ns} \text{ T5} \text{ ns} \text{ ns} \text{ ns} \text{ T5} \text{ ns} \t	SDI Setup Time	t _{DS}		60			ns
Propagation Delay tDO1 CLOAD = 200pF 200 ns SCLK Fall to DOUT Valid Propagation Delay tDO2 CLOAD = 200pF 200 ns SCLK Rise to CS Fall Delay tcso 10 ns CS Rise to SCLK Rise Hold Time tcso 75 ns	SDI Hold Time	tDH		0			ns
Propagation Delay $tDO2$ CLOAD = 200pF200nsSCLK Rise to \overline{CS} Fall Delay $tcso$ 10ns \overline{CS} Rise to SCLK Rise Hold Time $tcso$ 75ns		t _{DO1}	C _{LOAD} = 200pF			200	ns
CS Rise to SCLK Rise Hold Time tos1 75 ns		tDO2	CLOAD = 200pF			200	ns
	SCLK Rise to CS Fall Delay	t _{CS0}		10			ns
CS Pulse Width High t _{CSW} 150 ns	CS Rise to SCLK Rise Hold Time	tcs1		75			ns
	CS Pulse Width High	tcsw		150			ns

Note 1: INL guaranteed between codes 16 and 4095.

Note 2: Offset is measured at the code that comes closest to 10mV.

Note 3: Accuracy is better than 1LSB for Vout = 10mV to VDD - 180mV. Guaranteed by PSR test on end points.

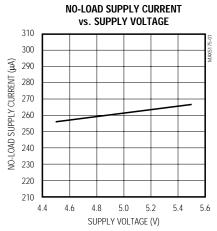
Note 4: R_L = open and digital inputs are either V_{DD} or DGND.

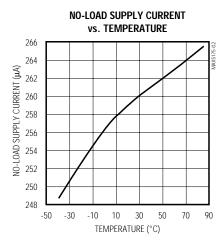
Note 5: INL guaranteed between codes 32 and 4095.

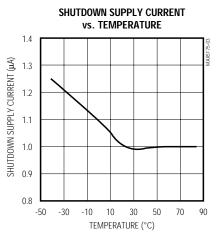
Typical Operating Characteristics

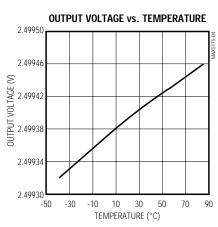
 $(MAX5175: V_{DD} = +5V, V_{REF} = 2.5V; MAX5177: V_{DD} = +3V, V_{REF} = 1.25V; C_L = 100pF, FB = OUT, code = FFF hex, T_A = +25^{\circ}C, unless otherwise noted.)$

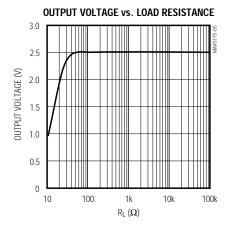
MAX5175

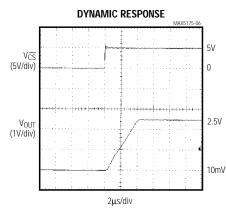


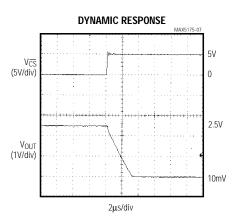


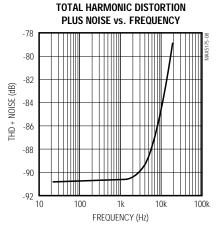


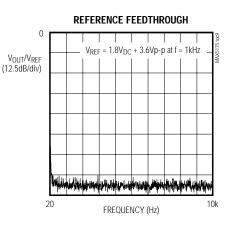








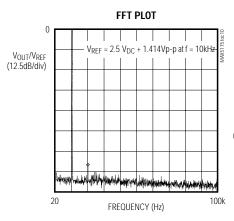


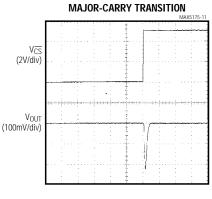


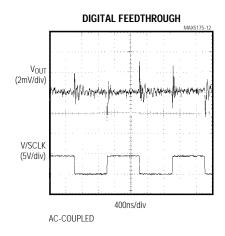
Typical Operating Characteristics (continued)

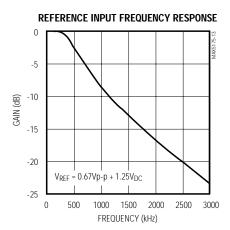
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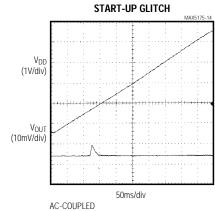
MAX5175



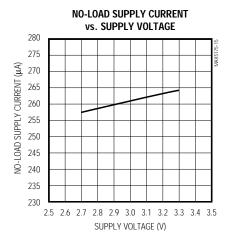


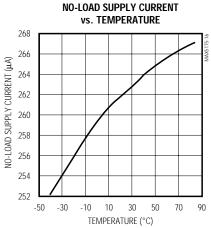


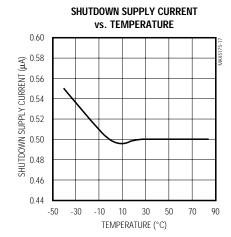




MAX5177



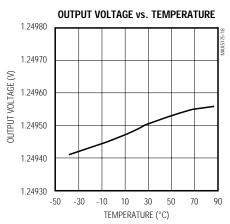


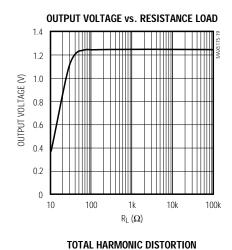


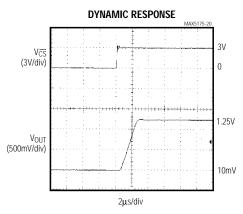
Typical Operating Characteristics (continued)

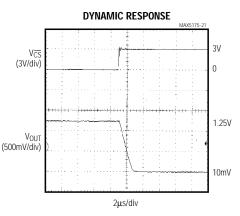
(MAX5175: V_{DD} = +5V, V_{REF} = 2.5V; MAX5177: V_{DD} = +3V, V_{REF} = 1.25V; C_L = 100pF, FB = OUT, code = FFF hex, T_A = +25°C, unless otherwise noted.)

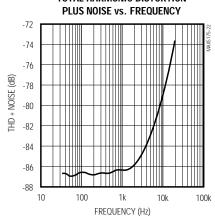
MAX5177

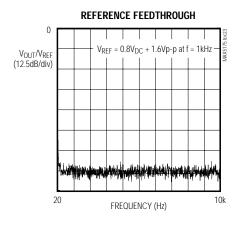


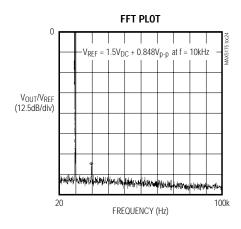


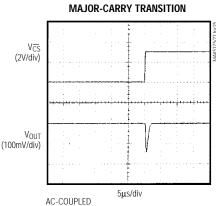


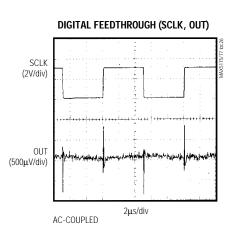








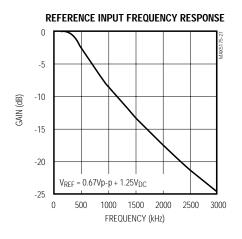


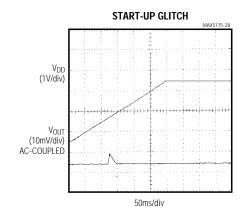


Typical Operating Characteristics (continued)

(MAX5175: $V_{DD} = +5V$, $V_{REF} = 2.5V$; MAX5177: $V_{DD} = +3V$, $V_{REF} = 1.25V$; $C_L = 100pF$, FB = OUT, code = FFF hex, $T_A = +25$ °C, unless otherwise noted.)

MAX5177





Pin Description

PIN	NAME	FUNCTION
1	FB	Feedback Input
2	OUT	Voltage Output. High impedance in shutdown. Output voltage is limited to V _{DD} .
3	RS	Reset Mode Select (digital input). Connect to V _{DD} to select midscale reset output value. Connect to DGND to select 0 reset output value.
4	PDL	Power-Down Lockout (digital input). Connect to V _{DD} to allow shutdown. Connect to DGND to disable shutdown.
5	CLR	Clear DAC (digital input). Clears the DAC to its predetermined output state as set by RS.
6	CS	Chip-Select Input (digital input). DIN is ignored when $\overline{\text{CS}}$ is high.
7	DIN	Serial-Data Input (digital input). Data is clocked in on the rising edge of SCLK.
8	SCLK	Serial Clock Input (digital input)
9	DGND	Digital Ground
10	DOUT	Serial-Data Output
11	UPO	User-Programmable Output. State is set by the serial input.
12	SHDN	Shutdown (digital input). Pulling SHDN high when $\overline{PDL} = V_{DD}$ places the chip in shutdown with a maximum shutdown current of 10 μ A.
13	AGND	Analog Ground
14	REF	Reference Input. Maximum V _{REF} is V _{DD} - 1.4V.
15	N.C.	No Connect
16	V _{DD}	Positive Supply. Bypass to AGND with a 4.7µF capacitor in parallel with a 0.1µF capacitor.

Detailed Description

The MAX5175/MAX5177 12-bit, serial, voltage-output DACs operate with a 3-wire serial interface. These devices include a 16-bit shift register and a double-buffered input composed of an input register and a DAC register (see *Functional Diagram*). In addition, the negative terminal of the output amplifier is available. The DACs are designed with an inverted R-2R ladder network (Figure 1) that produces a weighted voltage proportional to the reference voltage.

Reference Inputs

The reference input accepts both AC and DC values with a voltage range extending from 0 to V_{DD} - 1.4V. The following equation represents the resulting output voltage:

$$V_{OUT} = \frac{V_{REF} \cdot N \cdot GAIN}{4096}$$

where N is the numeric value of the DAC's binary input code (0 to 4095), V_{REF} is the reference voltage, and Gain is the externally set voltage gain. The maximum output voltage is V_{DD}. The reference pin has a minimum impedance of $18k\Omega$ and is code dependent.

Output Amplifier

The MAX5175/MAX5177's DAC output is internally buffered by a precision amplifier with a typical slew rate of 0.6V/µs. Access to the output amplifier's inverting input provides flexibility in output gain setting and signal conditioning (see *Applications Information*).

The output amplifier settles to $\pm 0.5 LSB$ from a full-scale transition within 12µs, when loaded with 5k Ω in parallel with 100pF. Loads less than 2k Ω degrade performance.

Shutdown Mode

The MAX5175/MAX5177 feature a software- and hardware-programmable shutdown mode that reduces the typical supply current to 1µA. Enter shutdown by writing the appropriate input-control word as shown in Table 1 or by using the hardware shutdown function. In shutdown mode, the reference input and the amplifier output become high impedance and the serial interface remains active. Data in the input register is saved, allowing the MAX5175/MAX5177 to recall the prior output state when returning to normal operation. Exit shutdown by reloading the DAC register from the shift register, by simultaneously loading the input and DAC registers, or by toggling PDL. When returning from shutdown, wait 40µs for the output to settle.

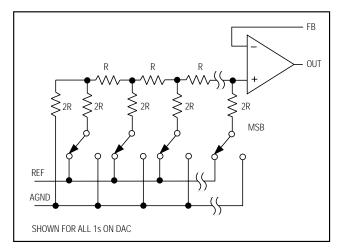


Figure 1. Simplified DAC Circuit Diagram

Power-Down Lockout

Power-down lockout disables the software/hardware shutdown mode. A high-to-low transition on PDL brings the device out of shutdown, returning the output to its previous state.

Shutdown

Pulling SHDN high while PDL is high places the MAX5175/MAX5177 in shutdown. Pulling SHDN low does not take the device out of shutdown. A high-to-low transition on PDL or an appropriate command from the serial data line (see Table 1 for commands) is required to exit shutdown.

Serial Interface

The 3-wire serial interface is compatible with SPI, QSPI (Figure 2), and MICROWIRE (Figure 3) interface standards. The 16-bit serial input word consists of two control bits, 12 bits of data (MSB to LSB), and two sub-bits.

The control bits determine the MAX5175/MAX5177's response as outlined in Table 1. The digital inputs are double buffered, which allows any of the following:

- Loading the input register without updating the DAC register
- Updating the DAC register from the input register
- Updating the input and DAC registers simultaneously.

The MAX5175/MAX5177 accept one 16-bit packet or two 8-bit packets sent while \overline{CS} remains low. The devices allow the following to be configured:

- Clock edge on which serial data output (DOUT) is clocked out
- State of the user-programmable logic output
- · Reset state.

Specific commands for setting these are shown in Table 1.

The general timing diagram in Figure 4 illustrates how the MAX5175/MAX5177 acquire data. \overline{CS} must go low at least tcss before the rising edge of the serial clock (SCLK). With \overline{CS} low, data is clocked into the register on the rising edge of SCLK. The maximum serial clock frequency guaranteed for proper operation is 10MHz for the MAX5175 and 6MHz for the MAX5177. See Figure 5 for a detailed timing diagram of the serial interface.

Table 1. Serial-Interface Programming Commands

	•	16-BIT SERIAL WORD		FUNCTION
C1	C0	D11D0	S1, S0	FUNCTION
0	0	12-bit DAC data	00	Load input register; DAC registers are unchanged.
0	1	12-bit DAC data	00	Load input register; DAC registers are updated (start up DAC with new data).
1	0	XXXX XXXX XXXX	xx	Update DAC register from input register (start up DAC with data previously stored in the input registers).
1	1	0 0 x x xxxx xxxx	XX	No operation (NOP).
1	1	0 1 x x xxxx xxxx	XX	Shut down DAC (provided PDL = 1).
1	1	1 0 0 x xxxx xxxx	XX	UPO goes low (default).
1	1	1 0 1 x xxxx xxxx	XX	UPO goes high.
1	1	1 1 0 x xxxx xxxx	XX	Mode 1, DOUT clocked out on SCLK's rising edge.
1	1	1 1 1 x xxxx xxxx	XX	Mode 0, DOUT clocked out on SCLK's falling edge (default).

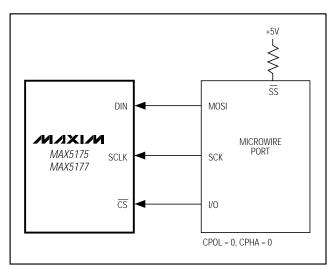


Figure 2. Connections for SPI/QSPI Standards

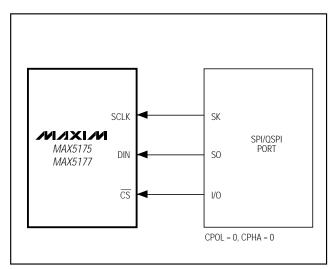


Figure 3. Connections for MICROWIRE

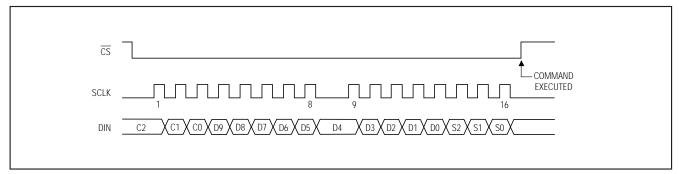


Figure 4. Serial-Interface Timing Diagram

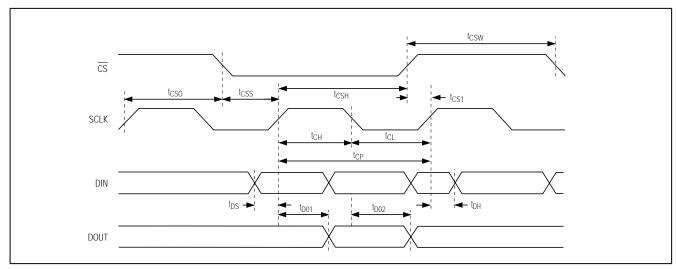


Figure 5. Detailed Serial-Interface Timing Diagram

Serial-Data Output (DOUT)

The serial-data output (DOUT) is the internal shift register's output and allows for daisy-chaining of multiple devices as well as data readback (see *Applications Information*). By default upon start-up, data shifts out of DOUT on the serial clock's rising edge (Mode 0) and provides a lag of 16 clock cycles, thus maintaining SPI, QSPI, and MICROWIRE compatibility. However, if the device is programmed for Mode 1, then the output data lags DIN by 16.5 clock cycles and is clocked out on the serial clock's rising edge. During shutdown, DOUT retains its last digital state prior to shutdown.

User-Programmable Logic Output (UPO)

The UPO allows control of an external device through the serial interface, thereby reducing the number of microcontroller I/O pins required. During power-down, this output will retain its digital state prior to shutdown. When $\overline{\text{CLR}}$ is pulled low, UPO will reset to its programmed default state. See Table 1 for specific commands to control the UPO.

Reset (RS) and Clear (CLR)

The MAX5175/MAX5177 offers a clear pin (CLR) which resets the output voltage. If RST = DGND, then CLR resets the output voltage to the minimum voltage (0 if no offset is introduced). If RST = VDD, then CLR resets the output voltage to midscale. In either case, CLR will reset UPO to its programmed default state.

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Applications Information

Unipolar Output

Figure 6 shows the MAX5175/MAX5177 configured for unipolar, rail-to-rail operation with a gain of +2V/V. Table 2 lists the codes for unipolar output voltages. The output voltage is limited to V_{DD}.

Bipolar Output

Figure 7 shows the MAX5175/MAX5177 configured for bipolar output operation. The output voltage is given by the following equation (FB = OUT):

$$V_{OUT} = V_{REF} \left(\frac{2N}{4096} - 1 \right)$$

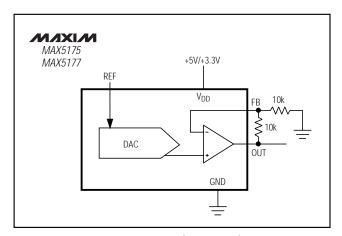


Figure 6. Unipolar Output Circuit (Rail-to-Rail)

Table 2. Unipolar Code Table (Circuit of Figure 6)

DAC CONTENTS MSB LSB	ANALOG OUTPUT
11 1111 1111 11 (00)	2 • V _{REF} (4095/4096)
10 0000 0000 01 (00)	2 • V _{REF} (2049/4096)
10 0000 0000 00 (00)	2 • V _{REF} (2048/4096)
01 1111 1111 11 (00)	2 • V _{REF} (2047/4096)
00 0000 0000 01 (00)	2 · V _{REF} (1/4096)
00 0000 0000 00 (00)	0

where N represents the numeric value of the DAC's binary input code and V_{REF} is the voltage of the external reference. Table 3 shows digital codes and the corresponding output voltage for Figure 7's circuit.

Daisy-Chaining Devices

The serial data output pin (DOUT) allows multiple MAX5175/MAX5177s to be daisy-chained together as shown in Figure 8. The advantage of this is that only two lines are needed to control all of the DACs on the line. The disadvantage is that it takes *n* commands to program the DACs. Figure 9 shows several MAX5175/MAX5177s sharing one common DIN signal line. In this configuration the data bus is common to all devices; however, more I/O lines are required because each device needs a dedicated $\overline{\text{CS}}$ line. The advantage of this configuration is that only one command is needed to program any DAC.

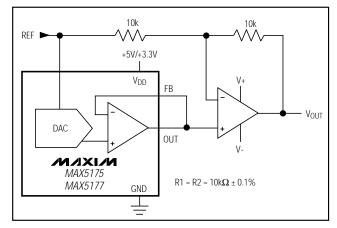


Figure 7. Bipolar Output Circuit

Table 3. Bipolar Code Table (Circuit of Figure 7)

DAC CONTENTS MSB LSB	ANALOG OUTPUT
11 1111 1111 11 (00)	+V _{REF} [(2 • 4095/4096) - 1]
10 0000 0000 01 (00)	+V _{REF} [(2 • 2049/4096) - 1]
10 0000 0000 00 (00)	+VREF [(2 • 2048/4096) - 1]
01 1111 1111 11 (00)	+V _{REF} [(2 • 2047/4096) - 1]
00 0000 0000 01 (00)	+V _{REF} [(2 • 1/4096) - 1]
00 0000 0000 00 (00)	-V _{REF}

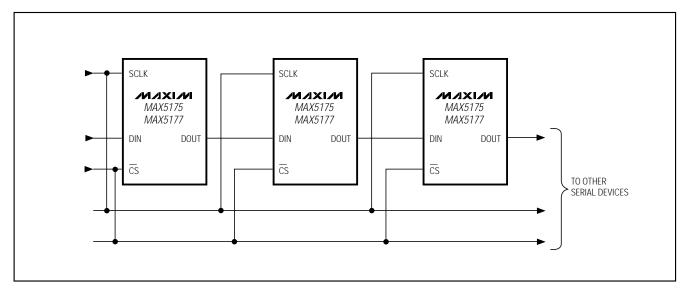


Figure 8. Daisy-Chaining MAX5175/MAX5177s

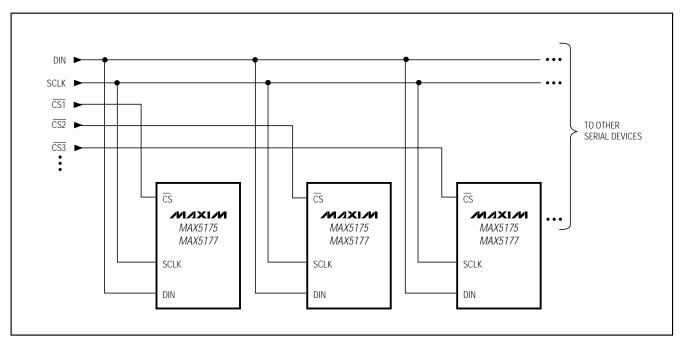


Figure 9. Multiple MAX5175/MAX5177s Sharing Common DIN and SCLK Lines

Using an AC Reference

The MAX5175/MAX5177 accept reference voltages containing AC components, as long as the reference voltage remains between 0 and V_{DD} - 1.4V. Figure 10 shows a technique for applying a sine-wave signal to REF. The reference voltage must remain above AGND.

Digitally Programmable Current Source

The circuit of Figure 11 places an NPN transistor (2N3904 or similar) within the op amp feedback loop to implement a digitally programmable, unidirectional current source. The output current is calculated with the following equation:

$$I_{OUT} = \frac{V_{REF} \cdot N}{R \cdot 4096}$$

where N is the numeric value of the DAC's binary input code and R is the sense resistor shown in Figure 11.

Power-Supply and Layout Considerations

Wire-wrap boards are not recommended. For optimum system performance, use printed circuit boards with separate analog and digital ground planes. Connect the two ground planes together at the low-impedance

power-supply source. Connect DGND and AGND pins together at the IC. The best ground connection is achieved by connecting the DAC's DGND and AGND pins together and connecting that point to the system analog ground plane. If the DAC's DGND is connected to the system digital ground, digital noise may infiltrate the DAC's analog portion.

Bypass the power supply with a $4.7\mu F$ capacitor in parallel with a $0.1\mu F$ capacitor to AGND. Minimize capacitor lead lengths to reduce inductance. If noise becomes an issue, use shielding and/or ferrite beads to increase isolation.

In order to maintain INL and DNL performance, as well as gain drift, it is extremely important to provide the lowest possible reference output impedance at the DAC reference input pin. INL degrades if the series resistance on the REF pin exceeds 0.1Ω . The same consideration must be made for the AGND pin.

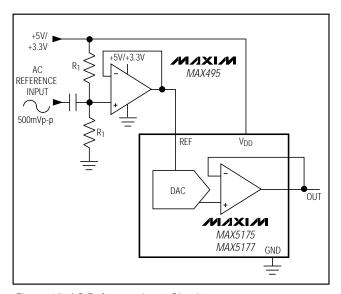


Figure 10. AC Reference Input Circuit

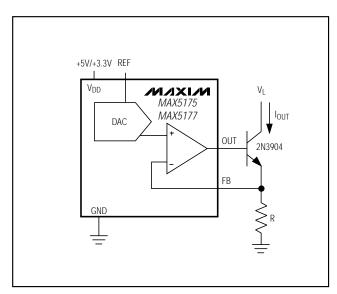
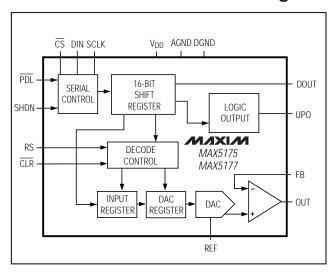


Figure 11. Digitally Programmable Current Source

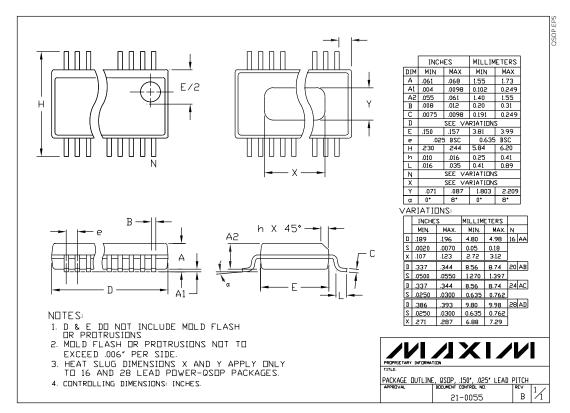
Functional Diagram

Chip Information

TRANSISTOR COUNT: 3457



Package Information



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MCP47FVB04T-E/MQ MCP48FEB28T-E/MQ MCP48FVB28T-20E/ST MCP47FVB28T-20E/ST MCP47FEB24T-E/MQ MCP48FVB18T
20E/ST MCP47FEB14T-E/MQ MCP47FEB08T-E/MQ MCP48FVB08T-20E/ST MCP47FEB04T-E/MQ MCP47FVB04T-20E/ST

AD7524JRZ-REEL LTC1664CGN LTC1664IGN LTC7545ACSW MCP47DA1T-A1E/OT MCP4921-E/MC UC3910D DAC39J84IAAV

DAC8218SPAG DAC8562TDGSR MAX551ACUB+ MAX545BCPD+ MAX531BCPD+ DAC7641YB/250 DAC7611PB DAC0800LCM

TLV5638CDR