

#### **General Description**

The MAX9157 is a guad bus LVDS (BLVDS) transceiver for heavily loaded, half-duplex multipoint buses. Small 32-pin QFN and TQFP packages and flow-through pinouts allow the transceiver to be placed near the connector for the shortest possible stub length. The MAX9157 drives LVDS levels into a  $27\Omega$  load (double terminated, heavily loaded LVDS bus) at up to 200Mbps. An input fail-safe circuit ensures the receiver output is high when the differential inputs are open, or undriven and shorted, or undriven and terminated. The MAX9157 differential inputs feature 52mV hysteresis for greater immunity to bus noise and reflections. The MAX9157 operates from a single 3.3V supply, consuming 80.9mA supply current with drivers enabled, and 22.7mA with drivers disabled.

The MAX9157's high-impedance I/Os (except for receiver outputs) when VCC = 0 or open, combined with glitch-free power-up and power-down, allow hot swapping of cards in multicard bus systems; 7.2pF (max) BLVDS I/O capacitances minimize bus loading.

The MAX9157 is offered in 5mm × 5mm 32-pin QFN and TQFP packages. The MAX9157 is fully specified for the -40°C to +85°C extended temperature range. Refer to the MAX9129 data sheet for a guad BLVDS driver, ideal for dual multipoint full-duplex buses.

#### **Applications**

Add/Drop Muxes Digital Cross-Connects

Network Switches/Routers Cellular Phone Base Stations **DSLAMs** 

Multipoint Buses

### **Features**

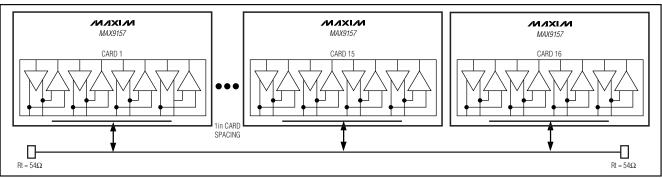
- ♦ 32-TQFP and Space-Saving 32-QFN Packages
- ♦ 52mV LVDS Input Hysteresis
- ♦ 1ns (min) Transition Time (0% to 100%) Minimizes Reflections
- ♦ Guaranteed 7.2pF (max) Bus Load Capacitance
- ♦ Glitch-Free Power-Up and Power-Down
- ♦ Hot-Swappable, High-Impedance I/O with V<sub>CC</sub> = 0 or Open
- ♦ Guaranteed 200Mbps Driver Data Rate
- ♦ Fail-Safe Circuit
- ♦ Flow-Through Pinout

#### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX9157EGJ	-40°C to +85°C	32 QFN (5mm × 5mm)
MAX9157EHJ	-40°C to +85°C	32 TQFP (5mm × 5mm)

Pin Configurations appear at end of data sheet. Functional Diagram appears at end of data sheet.

# **Typical Operating Circuit**



MIXIM

Maxim Integrated Products 1

#### **ABSOLUTE MAXIMUM RATINGS**

V <sub>CC</sub> , AV <sub>CC</sub> to GND	0.3V to +4.0V
DO_+/RIN_+, DO/RIN, to GND.	0.3V to +4.0V
DIN_, DE_, RE_ to GND	0.3V to +4.0V
RO_ to GND	0.3V to $(V_{CC} + 0.3V)$
AGND to GND	0.3V to +0.3V
Short-Circuit Duration (DO_+/RIN_+	, DO/RIN)Continuous
Continuous Power Dissipation (TA =	+70°C)
MAX9157FGJ (derate 21 2mW/°C	2 above +70°C) 1702mW

MAX9157EHJ (derate 11.1mW/°C above +70	°C)889mW
Storage Temperature Range	-65°C to +150°C
Maximum Junction Temperature	+150°C
Operating Temperature Range	40°C to +85°C
ESD Protection	
Human Body Model (DO_+/RIN_+, DO/RIN	l)±4kV
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

(VCC = 3.0V to 3.6V, R<sub>L</sub> =  $27\Omega$  ±1%, differential input voltage IV<sub>IDI</sub> = 0.1V to V<sub>CC</sub>, input common-mode voltage V<sub>CM</sub> = 0.05V to 2.4V, input voltage range = 0 to V<sub>CC</sub>, DE\_ = high,  $\overline{RE}_-$  = low, T<sub>A</sub> = -40°C to +85°C, unless otherwise noted. Typical values are at V<sub>CC</sub> = 3.3V, IV<sub>IDI</sub> = 0.2V, V<sub>CM</sub> = 1.2V, and T<sub>A</sub> = +25°C.) (Notes 1 and 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
BLVDS (DO_+/RIN_+, DO/RIN_	-)						
Differential Input High Threshold	V <sub>TH</sub>	DE_ = low			26	100	mV
Differential Input Low Threshold	V <sub>TL</sub>	DE_ = low		-100	-26		mV
Threshold Hysteresis (Note 3)	V <sub>HYST</sub>	DE_ = low	$T_A = +25$ °C, $V_{CC} = 3.3V$ , $V_{CM} = 1.2V$	12	26	43	mV
			Full operating range	9	26	78	
Input Current	las las	0.1V ≤   V <sub>ID</sub>   ≤ 0	.6V, DE_ = low	-15	±1.8	15	μΑ
input Current	I <sub>IN+</sub> , I <sub>IN-</sub>	0.6V <   VID   ≤	1.2V, DE_ = low	-20	±2.5	20	μΑ
Input Resistance	R <sub>IN1</sub>	$V_{CC} = 3.6V, 0 o$	r open, Figure 1	53			kΩ
Input nesistance	R <sub>IN2</sub>	V <sub>CC</sub> = 3.6V, 0 or open, Figure 1		148			kΩ
Power-Off Input Current	I <sub>INO+</sub> ,	$0.1V \le  V_{ID}  \le 0.6V, V_{CC} = 0 \text{ or open}$		-15	±0.9	15	μΑ
Fower-On Input Current	I <sub>INO</sub> -	$0.6V <  V_{ID}  \le 1.2V, V_{CC} = 0 \text{ or open}$		-20	±1.8	20	μΑ
Differential Output Voltage	V <sub>OD</sub>	Figure 2		250	405	460	mV
Change in Magnitude of VOD for Complementary Output States	ΔV <sub>OD</sub>	Figure 2			1	25	mV
Offset Voltage	Vos	Figure 2		1.185	1.302	1.435	V
Change in Magnitude of VOS for Complementary Output States	ΔV <sub>OS</sub>	Figure 2			3.3	25	mV
Output High Voltage	VoH	Figure 2			1.505	1.6	V
Output Low Voltage	V <sub>OL</sub>	Figure 2		0.9	1.099		V
Output Short-Circuit Current		DIN_ = high, DOVCC, DO/RIN_	D_+/RIN_+ = 0 or = 0 or VCC	-30	-14.8	30	mA
	los	DIN_ = low, DO V <sub>CC</sub> , DO_+/RIN		-30	-14.8	30	IIIA

### **DC ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{CC}=3.0 \text{V to } 3.6 \text{V}, R_L=27 \Omega \pm 1\%, \text{ differential input voltage } |V_{ID}|=0.1 \text{V to } V_{CC}, \text{ input common-mode voltage } V_{CM}=0.05 \text{V to } 2.4 \text{V}, \text{ input voltage range}=0 \text{ to } V_{CC}, DE_= \text{high, } \overline{RE}_= \text{low, } T_A=-40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}, \text{ unless otherwise noted.}$  Typical values are at  $V_{CC}=3.3 \text{V}, |V_{ID}|=0.2 \text{V}, V_{CM}=1.2 \text{V}, \text{ and } T_A=+25^{\circ}\text{C}.)$  (Notes 1 and 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Differential Output Short-Circuit Current (Note 3)	I <sub>OSD</sub>	DIN_ = high or le	ow, V <sub>OD</sub> = 0		14.8	30	mA
Capacitance at Bus Pins (Note 3)	Соитрит		m DO_+/RIN_+ or ND, V <sub>CC</sub> = 3.6V or 0			7.2	pF
LVCMOS/LVTTL OUTPUTS (RO_	)						
Output High Voltage	Voн	I <sub>OH</sub> = -4.0mA, DE_ = low	Open, undriven short, or undriven $27\Omega$ parallel termination	V <sub>CC</sub> - 0.3	V <sub>CC</sub> - 0.172		V
			V <sub>ID</sub> = 100mV	V <sub>CC</sub> - 0.3	V <sub>CC</sub> - 0.172		
Output Low Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 4.0mA, V <sub>I</sub> [	) = -100mV, DE_ = low		0.179	0.25	V
Dynamic Output Current	I <sub>OD</sub>	$V_{ID} = 100 \text{mV}, V$	RO_ = VCC - 1.0V, DE_ = low	-15	-22.7		mA
Dynamic Output Current	עטי	VID = -100mV, \	/ <sub>RO_</sub> = 1.0V, DE_ = low	12	19.9		mA
Output Short-Circuit Current (Note 4)	Ios	V <sub>ID</sub> = 100mV, V <sub>RO</sub> _ = 0, DE_ = low			-52	-130	mA
Output High-Impedance Current	loz	RE_ = high, V <sub>RO</sub> = 0 or V <sub>CC</sub>		-10	0.1	+10	μΑ
Capacitance at Receiver Output (Note 3)	Соитрит	Capacitance from RO_ to GND, V <sub>CC</sub> = 3.6V or 0				4.5	pF
LVCMOS/LVTTL INPUTS (DIN, D	E, RE)			•			,
Input High Voltage	VIH			2.0	1.825	Vcc	V
Input Low Voltage	V <sub>IL</sub>			GND	1.315	0.8	V
Input Current	I <sub>IN</sub>	V <sub>DE_</sub> , V <sub>RE_</sub> , V <sub>DIN</sub>	ı_ = high or low	-20	±9.2	20	μΑ
Power-Off Input Current	I <sub>INO</sub>	V <sub>DE_</sub> , V <sub>RE_</sub> , V <sub>DIN_</sub> = 3.6V or 0, V <sub>CC</sub> = 0 or open		-20	±2.4	20	μΑ
SUPPLY							
Supply Current Drivers and Receivers Enabled	Icc	DE_ = high, RE_ = low, RL = $27\Omega$			80.9	95	mA
Supply Current Drivers Enabled and Receivers Disabled	ICCD	DE_ = high, RE_ = high, R <sub>L</sub> = $27\Omega$			80.9	95	mA
Supply Current Drivers Disabled and Receivers Enabled	ICCR	DE_ = low, RE_ = low			22.7	30	mA
Supply Current Drivers Disabled and Receivers Disabled	Iccz	DE_ = low, RE_ = high			22.7	30	mA

#### **AC ELECTRICAL CHARACTERISTICS**

 $(V_{CC}=3.0V\ to\ 3.6V,\ R_L=27\Omega\ \pm 1\%,\ differential\ input\ voltage\ |V_{ID}|=0.2V\ to\ V_{CC},\ input\ frequency\ to\ LVDS\ inputs=85MHz,\ input\ frequency\ to\ LVCMOS/LVTTL\ inputs=100MHz,\ LVCMOS/LVTTL\ inputs=0\ to\ 3V\ with\ 2ns\ (10\%\ to\ 90\%)\ transition\ times. Differential\ input\ voltage\ transition\ time=1ns\ (20\%\ to\ 80\%).\ Input\ common-mode\ voltage\ V_{CM}=1.2V\ to\ 1.8V,\ DE_=\ high,\ \overline{RE}_=\ low,\ T_A=-40^{\circ}C\ to\ +85^{\circ}C,\ unless\ otherwise\ noted.\ Typical\ values\ are\ at\ V_{CC}=3.3V,\ |V_{ID}|=0.2V,\ V_{CM}=1.2V,\ and\ T_A=+25^{\circ}C.)\ (Notes\ 3\ and\ 5)$ 

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
DRIVER	•			•				
Differential Propagation Delay	to	$RE_{-}$ = high, $C_{L}$ = 10pF,	MAX9157EGJ	1.2	1.96	2.5	200	
High to Low	tPHLD	Figures 3, 4	MAX9157EHJ	1.1	1.87	2.4	ns	
Differential Propagation Delay	to	$RE_{-}$ = high, $C_{L}$ = 10pF,	MAX9157EGJ	1.2	1.94	2.5	20	
Low to High	tPLHD	Figures 3, 4	MAX9157EHJ	1.1	1.84	2.4	ns	
Differential Skew   tpHLD-tpLHD   (Note 6)	tskD1	RE_ = high, C <sub>L</sub> = 10pF, Fi	gures 3, 4		33	160	ps	
Channel-to-Channel Skew (Note 7)	tccsk	RE_ = high, C <sub>L</sub> = 10pF, Fi	gures 3, 4		58	300	ps	
Chip-to-Chip Skew (Note 8)	tskD2	RE_ = high, CL = 10pF, Fi	gures 3, 4		0.38	0.8	ns	
Chip-to-Chip Skew (Note 9)	T <sub>SKD3</sub>	RE_ = high, CL = 10pF, Fi	gures 3, 4			1.3	ns	
Rise Time	t	$RE_{-}$ = high, $C_{L}$ = 10pF,	MAX9157EGJ	0.6	1.13	1.4	ns	
nise filfle	tTLH	Figures 3, 4	MAX9157EHJ	0.6	1.07	1.4	110	
Fall Time	t	$RE_{-}$ = high, $C_{L}$ = 10pF,	MAX9157EGJ	0.6	1.16	1.4	nc	
rall fille	tTHL	Figures 3, 4	MAX9157EHJ	0.6	1.11	1.4	ns	
Disable Time High to Z	to7	t <sub>PHZ</sub> $RE_{-}$ = high, $C_{L}$ = 10pF, Figures 5, 6	MAX9157EGJ		6.79	8	ns	
Disable Time High to 2	ιΡΗΖ		MAX9157EHJ		6.79	8		
Disable Time Low to Z	tou 7	tPLZ $RE_=$ high, $C_L$ = 10pF, Figures 5, 6	MAX9157EGJ		3.16	8	ns	
Disable Time Low to 2	IPLZ		MAX9157EHJ		3.48	8		
Enable Time Z to High	tpzh	$RE_{\perp} = high, C_{\perp} = 10pF,$	MAX9157EGJ		4.67	7	ns	
Litable Time 2 to Flight	чи	Figures 5, 6	MAX9157EHJ		4.71	7	115	
Enable Time Z to Low	tozi	tp71  g., og.,	MAX9157EGJ		4.36	7	ns	
Enable Time 2 to low	17ZL	Figures 5, 6	MAX9157EHJ		4.39	7	110	
Maximum Operating Frequency (Note 10)	f <sub>MAX</sub>	$RE_{\perp} = high, C_{\perp} = 10pF, Fi$	gures 5, 6	100			MHz	
RECEIVER	•							
Differential Propagation Delay	t <sub>PHLD</sub>	DE_ = low, Figures 7, 8;	MAX9157EGJ	1.8	2.58	4.1	ns	
High to Low	IPHLD	C <sub>L</sub> =15pF	MAX9157EHJ	1.8	2.61	4.1	113	
Differential Propagation Delay	tplhd	DE_ = low, Figures 7, 8;	MAX9157EGJ	1.8	2.49	4.1	ns	
Low to High	ירנחט	C <sub>L</sub> =15pF	MAX9157EHJ	1.8	2.52	4.1	113	
Differential Skew   tPHLD - tPLHD   (Note 6)	tskD1	DE_ = low, Figures 7, 8; C <sub>L</sub> = 15pF			90	450	ps	
Channel-to-Channel Skew (Note 7)	tccsk	DE_ = low, Figures 7, 8; C <sub>L</sub> = 15pF			131	580	ps	
Chip-to-Chip Skew (Note 8)	tSKD2	DE_ = low, Figures 7, 8; C	L = 15pF		0.7	1.7	ns	
Chip-to-Chip Skew (Note 9)	tskD3	DE_ = low, Figures 7, 8; C <sub>L</sub> =15pF			0.7	1.7	ns	
Rise Time	tTLH	DE_ = low, Figures 7, 8; C	 L = 15pF	0.5	1.1	1.6	ns	

#### **AC ELECTRICAL CHARACTERISTICS (continued)**

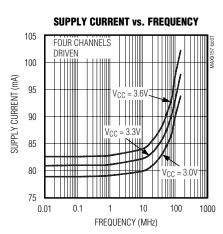
 $(V_{CC}=3.0V\ to\ 3.6V,\ R_L=27\Omega\ \pm 1\%,\ differential\ input\ voltage\ IV_{ID}I=0.2V\ to\ V_{CC},\ input\ frequency\ to\ LVDS\ inputs=85MHz,\ input\ frequency\ to\ LVCMOS/LVTTL\ inputs=100MHz,\ LVCMOS/LVTTL\ inputs=0\ to\ 3V\ with\ 2ns\ (10\%\ to\ 90\%)\ transition\ times. Differential\ input\ voltage\ transition\ time=1ns\ (20\%\ to\ 80\%).\ Input\ common-mode\ voltage\ V_{CM}=1.2V\ to\ 1.8V,\ DE_=\ high,\ \overline{RE}_=\ low,\ T_A=-40^\circ C\ to\ +85^\circ C,\ unless\ otherwise\ noted.\ Typical\ values\ are\ at\ V_{CC}=3.3V,\ |V_{ID}I=0.2V,\ V_{CM}=1.2V,\ and\ T_A=+25^\circ C.)\ (Notes\ 3\ and\ 5)$ 

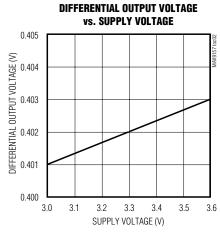
PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Fall Time	tTHL	DE_ = low, Figures 7, 8; CL	= 15pF	0.7	1.2	1.8	ns
Disable Time Llighte 7	to	DE_ = low, R <sub>L</sub> = $500\Omega$ , C <sub>L</sub>	MAX9157EGJ		6.74	8	20
Disable Time High to Z	tPHZ	= 15pF, Figures 9, 10	MAX9157EHJ		6.82	8	ns
Disable Time Laurte 7	4	$DE_{\perp} = low, R_{\perp} = 500\Omega, C_{\perp}$ = 15pF, Figures 9, 10	MAX9157EGJ		6.49	8	
Disable Time Low to Z	t <sub>PLZ</sub>		MAX9157EHJ		6.79	8	ns
Facilia Tima 7 to High		$t_{PZH}$ DE_ = low, R <sub>L</sub> = 500 $\Omega$ , C <sub>L</sub> MAX9157EGJ = 15pF, Figures 9, 10 MAX9157EHJ	MAX9157EGJ		4.67	7	
Enable Time Z to High	IPZH		MAX9157EHJ		4.57	7	ns
Finale La Time 2 And Laws		$DE_{-} = low, R_{L} = 500\Omega, C_{-}$	MAX9157EGJ		5.43	7	
Enable Time Z to Low	ΓPZL	t <sub>PZL</sub> = 15pF, Figures 9, 10	MAX9157EHJ		4.71	7	ns
Maximum Operating Frequency (Note 10)	f <sub>MAX</sub>	$DE_{-} = low, C_{L} = 15pF$		85			MHz

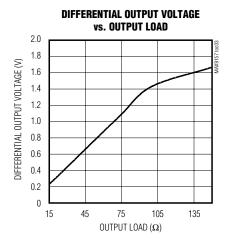
- Note 1: Current into a pin is defined as positive. Current out of a pin is defined as negative. All voltages are referenced to ground except V<sub>TH</sub>, V<sub>TL</sub>, V<sub>ID</sub>, V<sub>HYST</sub>, V<sub>OD</sub>, and ΔV<sub>OD</sub>.
- Note 2: Maximum and minimum limits over temperature are guaranteed by design and characterization. Devices are production tested at T<sub>A</sub> = +25°C.
- Note 3: Guaranteed by design and characterization.
- Note 4: Short only one output at a time. Do not exceed the absolute maximum junction temperature specification.
- Note 5: CL includes scope probe and test jig capacitance.
- Note 6: tskD1 is the magnitude difference of differential propagation delays in a channel. tskD1 = I tpHLD tpLHD I.
- Note 7: t<sub>CCSK</sub> is the magnitude difference of the t<sub>PLHD</sub> or t<sub>PHLD</sub> of one channel and the t<sub>PLHD</sub> or t<sub>PHLD</sub> of any other channel on the same part.
- Note 8: t<sub>SKD2</sub> is the magnitude difference of any differential propagation delays between parts operating over rated conditions at the same V<sub>CC</sub> and within 5°C of each other.
- Note 9: tskp3 is the magnitude difference of any differential propagation delays between parts operating over rated conditions.
- Note 10: Meets data sheet specifications while operating at minimum f<sub>MAX</sub> rating.

## Typical Operating Characteristics

 $(V_{CC} = 3.3V, R_L = 27\Omega, driver C_L = 10pF, receiver C_L = 15pF, IV_{ID}I = 200mV, V_{CM} = 1.2V, f_{IN} = 20MHz, T_A = +25^{\circ}C, unless otherwise noted.)$ 

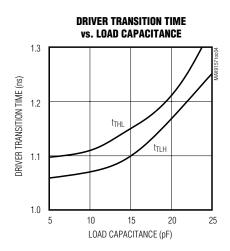


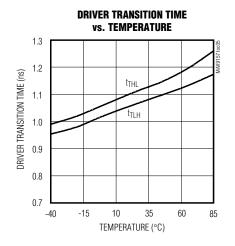


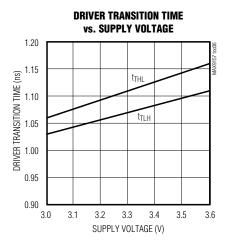


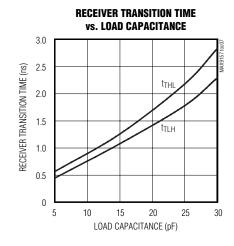
### Typical Operating Characteristics (continued)

 $(V_{CC}=3.3V, R_L=27\Omega, driver\ C_L=10pF, receiver\ C_L=15pF,\ IV_{ID}I=200mV,\ V_{CM}=1.2V,\ f_{IN}=20MHz,\ T_A=+25^{\circ}C,\ unless\ otherwise\ noted.)$ 









# Pin Description

PIN	NAME	FUNCTION
1, 2, 22, 23, 24	N.C.	No Connection. Not internally connected.
3	VCC	Digital Power Supply
4, 21	GND	Digital Ground
5	RE34	Receiver Channels 3 and 4 Enable (Enable Low). Drive RE34 low to enable receiver channels 3 and 4.
6	DE34	Driver Channels 3 and 4 Enable (Enable High). Drive DE34 high to enable driver channels 3 and 4.
7, 17	AGND	Analog Ground
8, 19	AVCC	Analog Power Supply
9	DO4-/RIN4-	Channel 4 Inverting BLVDS Input/Output
10	DO4+/RIN4+	Channel 4 Noninverting BLVDS Input/Output
11	DO3-/RIN3-	Channel 3 Inverting BLVDS Input/Output
12	DO3+/RIN3+	Channel 3 Noninverting BLVDS Input/Output
13	DO2-/RIN2-	Channel 2 Inverting BLVDS Input/Output
14	DO2+/RIN2+	Channel 2 Noninverting BLVDS Input/Output
15	DO1-/RIN1-	Channel 1 Inverting BLVDS Input/Output
16	DO1+/RIN1+	Channel 1 Noninverting BLVDS Input/Output
18	DE12	Driver Channels 1 and 2 Enable (Enable High). Drive DE12 high to enable driver channels 1 and 2.
20	RE12	Receiver Channels 1 and 2 Enable (Enable Low). Drive RE12 low to enable receiver channels 1 and 2.
25	DIN1	Driver Channel 1 Input
26	RO1	Receiver Channel 1 Output
27	DIN2	Driver Channel 2 Input
28	RO2	Receiver Channel 2 Output
29	DIN3	Driver Channel 3 Input
30	RO3	Receiver Channel 3 Output
31	DIN4	Driver Channel 4 Input
32	RO4	Receiver Channel 4 Output
EP*	EXPOSED PAD	Exposed Pad. Solder exposed pad to GND.

<sup>\*</sup>MAX9157EGJ only.

#### **Detailed Description**

The MAX9157 is a four-channel, 200Mbps, 3.3V BLVDS transceiver in 32-lead TQFP and QFN packages, ideal for driving heavily loaded multipoint buses, typically 16 to 20 cards plugged into a backplane. The MAX9157 receivers accept a differential input and have a fail-safe input circuit. The devices detect differential signals as low as 100mV and as high as VCC.

The MAX9157 driver outputs use a current-steering configuration to generate a 9.25mA to 17mA output current. This current-steering approach induces less ground bounce and no shoot-through current, enhancing noise margin and system speed performance. The outputs are short-circuit current limited.

The MAX9157 current-steering output requires a resistive load to terminate the signal and complete the transmission loop. Because the devices switch the direction of current flow and not voltage levels, the output voltage swing is determined by the value of the termination resistor multiplied by the output current. With a typical 15mA output current, the MAX9157 produces a 405mV output voltage when driving a bus terminated with two  $54\Omega$  resistors (15mA  $\times$  27 $\Omega$  = 405mV). Logic states are determined by the direction of current flow through the termination resistor.

#### Fail-Safe Receiver Inputs

The fail-safe feature of the MAX9157 sets the output high when the differential input is:

- Open
- Undriven and shorted
- · Undriven and terminated

Without a fail-safe circuit, when the input is undriven, noise at the input may switch the outputs and it may appear to the system that data is being sent. Open or undriven terminated input conditions can occur when a cable is disconnected or cut, or when driver output is in high impedance. A shorted input can occur because of a cable failure.

When the input is driven with a differential signal with a common-mode voltage of 0.05V to 2.4V, the fail-safe circuit is not activated. If the input is open, undriven and shorted, or undriven and parallel terminated, an internal resistor in the fail-safe circuit pulls both inputs above  $V_{CC}$  - 0.3V, activating the fail-safe circuit and forcing the outputs high (Figure 1).

#### **Effect of Capacitive Loading**

The characteristic impedance of a differential PC board trace is uniformly reduced when equal capacitive loads are attached at equal intervals (provided the transition time of the signal being driven on the trace is longer than the delay between loads). This kind of loading is typical of multipoint buses where cards are attached at 1 in or 0.8 in intervals along the length of a backplane.

The reduction in characteristic impedance is approximated by the following formula:

 $Z_{DIFF}$ -loaded =  $Z_{DIFF}$ -unloaded  $\times$  SQRT [Co / (Co + N  $\times$  C<sub>L</sub> / L)]

where:

Z<sub>DIFF</sub>-unloaded = unloaded differential characteristic impedance

Co = unloaded trace capacitance (pF/unit length)

 $C_L$  = value of each capacitive load (pF)

N = number of capacitive loads

L = trace length

For example, if Co = 2.5pF/in,  $C_L$  = 10pF, N = 18, L = 18in, and  $Z_{DIFF}$ -unloaded = 120 $\Omega$ , the loaded differential impedance is:

ZDIFF-loaded =  $120\Omega \times$  SQRT [2.5pF / (2.5pF + 18 x 10pF / 18in)] ZDIFF-loaded =  $54\Omega$ 

In this example, capacitive loading reduces the characteristic impedance from  $120\Omega$  to  $54\Omega$ . The load seen by

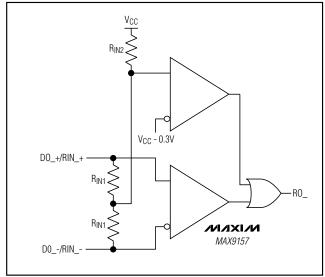


Figure 1. Internal Fail-Safe Circuit

a driver located on a card in the middle of the bus is  $27\Omega$  because the driver sees two  $54\Omega$  loads in parallel. A typical LVDS driver (rated for a  $100\Omega$  load) would not develop a large enough differential signal to be reliably detected by an LVDS receiver. The MAX9157 BLVDS drivers are designed and specified to drive a  $27\Omega$  load to differential voltage levels of 250mV to 460mV. A standard LVDS receiver is able to detect this level of differential signal. Short extensions off the bus, called stubs, contribute to capacitive loading. Keep stubs less than 1 in for a good balance between ease of component placement and good signal integrity.

The MAX9157 driver outputs are current-source drivers and drive larger differential signal levels into loads lighter than  $27\Omega$  and smaller levels into loads heavier than  $27\Omega$  (see  $Typical\ Operating\ Characteristics\ curves). To keep loading from reducing bus impedance below the rated <math display="inline">27\Omega$  load, PC board traces can be designed for higher unloaded characteristic impedance.

#### **Effect of Transition Times**

For transition times (measured from 0% to 100%) shorter than the delay between capacitive loads, the loads are seen as low-impedance discontinuities from which the driven signal is reflected. Reflections add and subtract from the signal being driven and cause decreased noise margin and jitter. The MAX9157 output drivers are designed for a minimum transition time of 1ns (rated 0.6ns from 20% to 80%, or about 1ns from 0% to 100%) to reduce reflections while being fast enough for high-speed backplane data transmission.

#### **Power-On Reset**

The power-on reset voltage of the MAX9157 is typically 2.25V. When the supply falls below this voltage, the devices are disabled and the receiver inputs/driver outputs are in high impedance. The power-on reset ensures glitch-free power-up and power-down, allowing hot swapping of cards in a multicard bus system without disrupting communications.

#### **Receiver Input Hysteresis**

The MAX9157 receiver inputs feature 52mV hysteresis to increase noise immunity for low-differential input signals.

#### **Operating Modes**

The MAX9157 features driver/receiver enable inputs that select the bus I/O function (Table 1). Tables 2 and 3 show the driver and receiver truth tables.

#### Input Internal Pullup/Pulldown Resistors

The MAX9157 includes pullup or pulldown resistors (300k $\Omega$ ) to ensure that unconnected inputs are defined (Table 4).

#### **Applications Information**

#### Supply Bypassing

Bypass each supply pin with high-frequency surface-mount ceramic  $0.1\mu F$  and 1nF capacitors in parallel as close to the device as possible, with the smaller value capacitor closest to the device.

#### **Termination**

In the example given in the Effect of Capacitive Loading section, the loaded differential impedance of a bus is reduced to  $54\Omega$ . Since the bus can be driven from any card position, the bus must be terminated at each end. A parallel termination of  $54\Omega$  at each end of the bus placed across the traces that make up the differential pair provides a proper termination. The total load seen by the driver is  $27\Omega$ . The MAX9157 drives higher differential signal levels into lighter loads. (See Differential Output Voltage vs. Output Load graph in the Typical Operating Characteristics section). A multidrop bus with the driver at one end and receivers connected at regular intervals along the bus has a lowered impedance due to capacitive loading. Assuming a  $54\Omega$  impedance, the multidrop bus can be terminated with a single, parallel-connected  $54\Omega$  resistor at the far end from the driver. Only a single resistor is required because the driver sees one  $54\Omega$  differential trace. The signal swing is larger with a  $54\Omega$  load. In general, parallel terminate each end of the bus with a resistor

Table 1. I/O Enable Functional Table

MODE SELECTED	DE_	RE_
Driver Mode	Н	Η
Receiver Mode	L	L
High-Impedance Mode	L	Н
Loopback Mode	Н	L

**Table 2. Driver Mode** 

INPUTS		OUTPU	TS
DE_	DIN_	DO_+/RIN_+	DO/RIN
Н	L	L	Н
Н	Н	Н	L
L	Χ	Z	Z

#### **Table 3. Receiver Mode**

	INPUTS			
RE_	$V_{ID} = (V_{DO_+}/R_{IN_+}) - (V_{DO}/R_{IN})$	RO_		
L	V <sub>ID</sub> < -100mV	Ш		
L	V <sub>ID</sub> > 100mV	Н		
L	Fail-safe operation guaranteed when DO_+/RIN_+ and DO/RIN are open, undriven and shorted, or undriven and parallel terminated	н		
Н	X	Z		

# Table 4. Input Internal Pullup/Pulldown Resistors

PIN	INTERNAL RESISTOR
DE12	Pulldown to GND
DE34	Pulldown to GND
RE12	Pullup to V <sub>CC</sub>
RE34	Pullup to V <sub>CC</sub>
DIN_	Pullup to V <sub>CC</sub>

matching the differential impedance of the bus (taking into account any reduced impedance due to loading).

#### Traces, Cables, and Connectors

The characteristics of input and output connections affect the performance of the MAX9157. Use controlled-impedance traces, cables, and connectors with matched characteristic impedance.

Ensure that noise couples as common mode by running the traces of a differential pair close together. Reduce within-pair skew by matching the electrical length of the traces of a differential pair. Excessive skew can result in a degradation of magnetic field cancellation. Maintain the distance between traces of a differential pair to avoid discontinuities in differential impedance. Minimize the number of vias to further prevent impedance discontinuities.

Avoid the use of unbalanced cables, such as ribbon cable. Balanced cables, such as twisted pair, offer superior signal quality and tend to generate less EMI due to canceling effects. Balanced cables tend to pick up noise as common mode, which is rejected by the receiver.

#### **Board Layout**

A four-layer PC board that provides separate power, ground, input, and output signals is recommended. Keep the LVTTL/LVCMOS and BLVDS signals separated to prevent coupling.

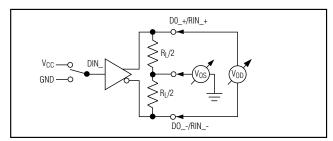


Figure 2. Driver VoD and Vos Test Circuit

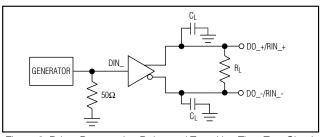


Figure 3. Driver Propagation Delay and Transition Time Test Circuit

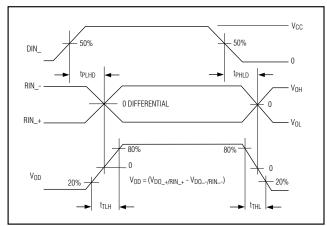


Figure 4. Driver Propagation Delay and Transition Time Waveforms

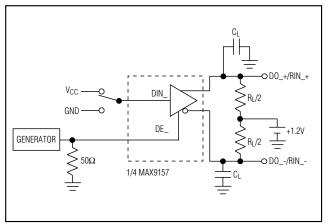


Figure 5. Driver High-Impedance Delay Test Circuit

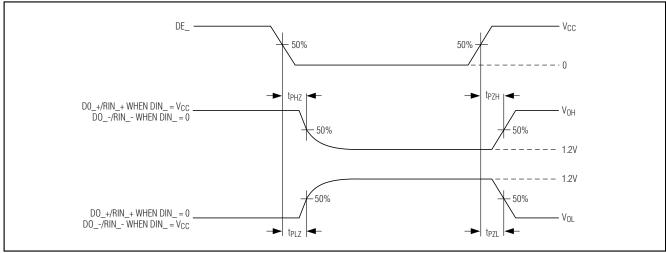


Figure 6. Driver High-Impedance Delay Waveform

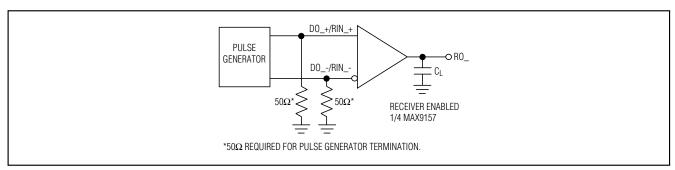


Figure 7. Receiver Transition Time and Propagation Delay Test Circuit

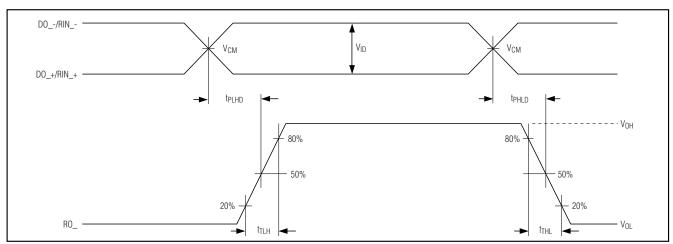


Figure 8. Receiver Transition Time and Propagation Delay Timing Diagram

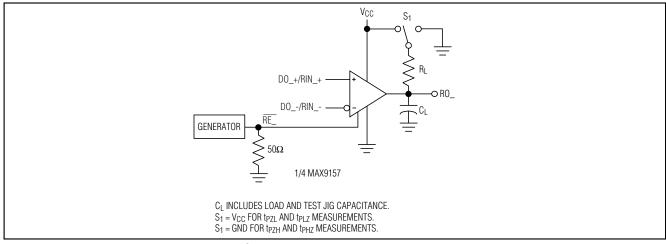


Figure 9. Receiver High-Impedance Delay Test Circuit

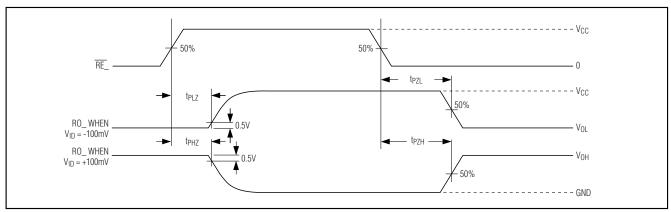
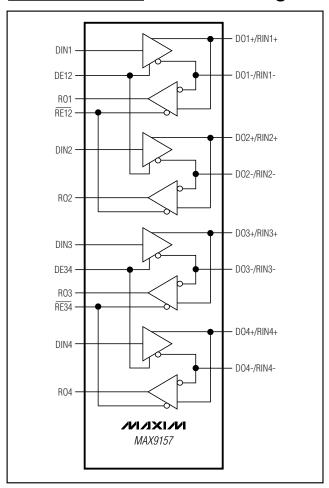


Figure 10. Receiver High-Impedance Waveforms

### **Functional Diagram**

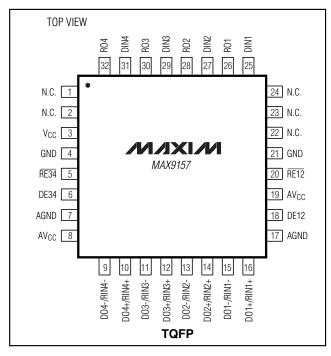


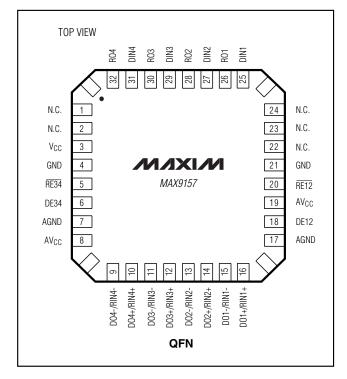
## **Chip Information**

TRANSISTOR COUNT: 1826

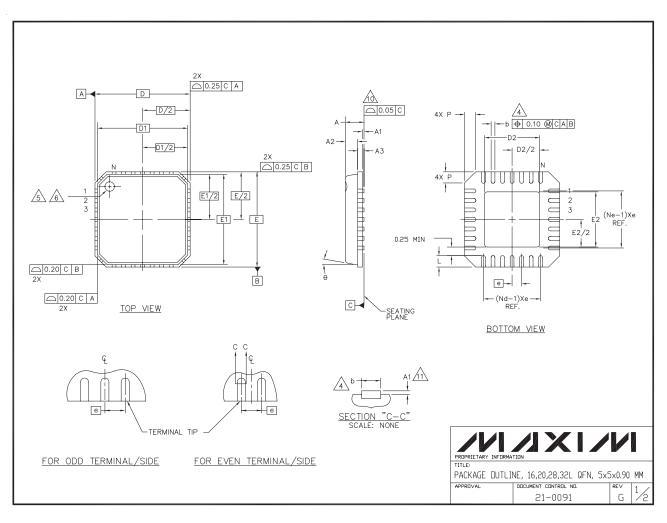
PROCESS: CMOS

## Pin Configurations





# Package Information



### Package Information (continued)

#### NOTES:

- 1. DIE THICKNESS ALLOWABLE IS 0.305mm MAXIMUM (.012 INCHES MAXIMUM)
- 2. DIMENSIONING & TOLERANCES CONFORM TO ASME Y14.5M. 1994.
- N IS THE NUMBER OF TERMINALS.

  No IS THE NUMBER OF TERMINALS IN X-DIRECTION &

  No IS THE NUMBER OF TERMINALS IN Y-DIRECTION.
- DIMENSION 6 APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN 0.20 AND 0.25mm FROM TERMINAL TIP.
- THE PIN #1 IDENTIFIER MUST BE EXISTED ON THE TOP SURFACE OF THE PACKAGE BY USING INDENTATION MARK OR INK/ LASER MARKED.
- 6. EXACT SHAPE AND SIZE OF THIS FEATURE IS OPTIONAL.
- 7. ALL DIMENSIONS ARE IN MILLIMETERS.
- 8. PACKAGE WARPAGE MAX 0.05mm.
- APPLIED FOR EXPOSED PAD AND TERMINALS.

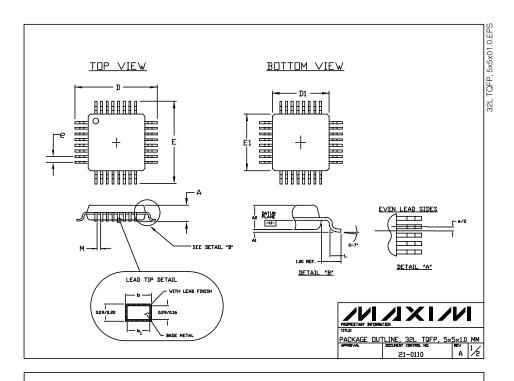
  EXCLUDE EMBEDDED PART OF EXPOSED PAD FROM MEASURING.
- 10. MEETS JEDEC MO220.
- 11. THIS PACKAGE OUTLINE APPLIES TO ANVIL SINGULATION (STEPPED SIDES) AND TO SAW SINGULATION (STRAIGHT SIDES) QFN STYLES.

S		COMMON	l			
S M B O L	DII	MENSION	IS	No.		
°L	MIN.	NOM.	MAX.	T <sub>E</sub>		
Α	0.80	0.90	1.00			
A1	0.00	0.01	0.05			
A2	0.00	0.65	1.00			
А3		0.20 REF.				
D		5.00 BSC				
D1		4.75 BSC				
E E1		5.00 BSC				
E1		4.75 BSC				
θ	0°	_	12°			
Р	0		0.60			
D2	1.25	_	3.25			
E2	1.25	_	3.25			

Y M	PITCH	VARIAT	ION B	N <sub>O</sub>	Y M M	PITCH	VARIAT	ION B	N_	Y <sub>M</sub>	PITCH	I VARIAT	ION C	N <sub>0</sub>	¥   M	PITCH	VARIAT	ION D	N <sub>O</sub>
ို	MIN.	NOM.	MAX.	Υ <sub>E</sub>	ို	MIN.	NOM.	MAX.	Ϋ́E	ို	MIN.	NOM.	MAX.	Ŭ <sub>τ</sub> <sub>E</sub>	ို	MIN.	NOM.	MAX.	Ϋ́E
e		0.80 BSC			e		0.65 BSC			e l		0.50 BSC			e		0.50 BSC		
N		16		3	N		20		3	N		28		3	N		32		3
Nd		4		3	Nd		5		3	Nd		7		3	Nd		8		3
Ne		4		3	Ne		5		3	Ne		7		3	Ne		8		3
L	0.35	0.55	0.75		L	0.35	0.55	0.75		L	0.35	0.55	0.75		L	0.30	0.40	0.50	
Ь	0.28	0.33	0.40	4	b	0.23	0.28	0.35	4	Ь	0.18	0.23	0.30	4	b	0.18	0.23	0.30	4



### Package Information (continued)



- NOTES:

  1. ALL DIMENSIONING AND TOLERANCING CONFORM TO ANSI Y14.5-1982.

  2. DATUM PLANE EMED IS LOCATED AT MOLD PARTING LINE AND COUNCIDENT WITH LEAD, WHERE LEAD EXITS PLASTIC BODY AT BOTTOM OF PARTING LINE.

  3. DIMENSIONS DI AND EL DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE MOLD PROTRUSION IS 0.254 MM ON DI AND EL DIMENSIONS.

  4. THE TOP OF PACKAGE IS SMALLER THAN THE BOTTOM OF PACKAGE BY 0.15 MILLIMETERS.

  5. DIMENSION 5 DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 MM TOTAL IN EXCESS OF THE 5 DIMENSION AT MAXIMUM MATERIAL CONDITION.

  6. CONTROLLING DIMENSION MILLIMETER.

  7. THIS OUTLINE CONFORMS TO JEDEC PUBLICATION 95, REGISTRATION MO-136.

  LEADS SHALL BE COPLANAR WITHIN .004 TNCH.
- MD-136. 8. LEADS SHALL BE COPLANAR WITHIN .004 INCH.

	JEDEC \	√ARIATI⊡NS	1			
	DIMENSIONS					
	А					
	5×5×1	I.O MM				
	MIN.	MAX.				
Α	14	1.20				
A <sub>1</sub>	0.05	0.15				
Az	0.95	1.05				
D	7.00	BSC.				
D <sub>1</sub>	5.00	BSC.				
E	7.00 BSC.					
E1	5.00 BSC.					
L	0.45	0.75				
м	0.15	N/L				
N	32					
e	0.50 BSC.					
ь	0.17	0.27				
ы	0.17	0.23				
NOTES THE DEPOSITION TITLE						
PACKAGE DUTLINE, 32L TQFP, 5x5x1.0 MM						

₽ ₹ 21-0110

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ADN4665ARUZ ADN4666ARUZ ADN4666ARZ-REEL7 ADN4693EBRZ ADN4697EBRZ ADN4695EBRZ ADN4666ARZ

ADN4667ARZ ADN4667ARZ-REEL7 ADN4668ARZ ADN4670BSTZ ADN4670BCPZ ADN4661BRZ ADN4663BRZ-REEL7

ADN4694EBRZ-RL7 ADN4662BRZ-REEL7 ADN4662BRZ ADN4691EBRZ ADN4694EBRZ ADN4690EBRZ GM8285BGA

MAX9113ESA+T MAX9122EUE+T MAX9174EUB+T FIN1031MX MAX9121EUE+T MAX9111ESA+ MAX9112ESA+

THC63LVDM87 NB3N4666CDTR2G MAX9179EUE+ MAX9129EUE+ MAX9121EUE+ MAX9157EHJ+ FIN1017MX FIN1027AMX