## **MIC2776**



### Micro-Power Low Voltage Supervisor

### **General Description**

The MIC2776 is a power supply supervisor which provides under-voltage monitoring and power-on reset generation in a compact 5-pin SOT package. Features include an adjustable under-voltage detector, a delay-generator, a manual reset input, and a choice of active-high, active-low, or open-drain active-low reset output. The user-adjustable monitoring input is compared against a 300mV reference. This low reference voltage allows monitoring voltages lower than those supported by previous supervisor ICs.

The reset output is asserted for no less than 140ms at poweron and any time the input voltage drops below the reference voltage. It remains asserted for the timeout period after the input voltage subsequently rises back above the threshold boundary. A reset can be generated at any time by asserting the manual reset input, /MR. The reset output will remain active at least 140ms after the release of /MR. The /MR input can also be used to daisy-chain the MIC2776 onto existing power monitoring circuitry or other supervisors. Hysteresis is included to prevent chattering due to noise. Typical supply current is a low 3.0µA.

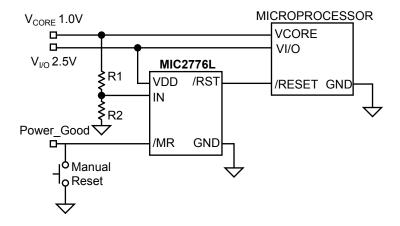
#### **Features**

- User-adjustable input can monitor supplies as low as 0.3V
- · ±1.5% threshold accuracy
- Separate V<sub>DD</sub> input
- Generates power-on reset pulse (140ms min.)
- Manual reset input
- Choice of active-high, active-low or open-drain activelow reset output
- Inputs can be pulled above V<sub>DD</sub> (7V abs. max.)
- Open-drain output can be pulled above V<sub>DD</sub> (7V abs. max.)
- Ultra-low supply current, 3.0µA typical
- Rejects brief input transients
- IttyBitty™ SOT-23-5 package

## **Applications**

- · Monitoring processor, ASIC, or FPGA core voltage
- Computer systems
- PDAs/Hand-held PCs
- · Embedded controllers
- · Telecommunications systems
- Power supplies
- · Wireless / cellular systems
- Networking hardware

# **Typical Application**



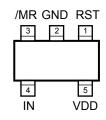
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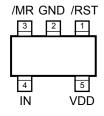
# **Ordering Information**

Part Number			Donat Output	Tomporatura Danga	Dookogo		
Standard	Marking	Pb-Free	Marking	Reset Output	Temperature Range	Package	
MIC2776N-BM5	UKAA	MIC2776N-YM5	<u>UK</u> AA	Open-Drain, Active-Low / RST	-40°C to +85°C	SOT-23-5	
MIC2776H-BM5	ULAA	MIC2776H-YM5	<u>UL</u> AA	Active-High, Complementary RST	-40°C to +85°C	SOT-23-5	
MIC2776L-BM5	UMAA	MIC2776L-YM5	<u>UM</u> AA	Active-Low, Complementary /RST	-40°C to +85°C	SOT-23-5	

# **Pin Configuration**



SOT-23-5 (M5) "H" Version



SOT-23-5 (M5) "L" and "N" Version

# **Pin Description**

Pin Number MIC2776H	Pin Number MIC2776L MIC2776N	Pin Name	Pin Function
1	1 F		Digital (Output): Asserted high whenever V <sub>IN</sub> falls below the reference voltage. It will remain asserted for no less than 140ms after V <sub>IN</sub> returns above the threshold limit.
	1	/RST	Digital (Output): Asserted low whenever $V_{\rm IN}$ falls below the reference voltage. It will remain asserted for no less than 140ms after $V_{\rm IN}$ returns above the threshold limit. (open-drain for "N" version)
2	2	GND	Ground
3	3	/MR	Digital (Input): Driving this pin low initiates an immediate and unconditional reset. Assuming IN is above the threshold when /MR is released (returns high), the reset output will be de-asserted no less than 140ms later. /MR may be driven by a logic signal or a mechanical switch. /MR has an internal pull-up to V <sub>DD</sub> and may be left open if unused.
4	4	IN	Analog (Input): The voltage on this pin is compared to the internal 300mV reference. An under-voltage condition will trigger a reset sequence.
5	5	VDD	Analog (Input): Independent supply input for internal circuitry.

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## **Absolute Maximum Ratings (Note 1)**

## 

## **Operating Ratings** (Note 2)

Supply Voltage (V <sub>DD</sub> )	+1.5V to +5.5V
Input Voltages (V <sub>IN</sub> , V <sub>/MR</sub> )	0.3V to +6.0V
Output Voltages	
V <sub>/RST</sub> (N version)	0.3V to +6.0V
V <sub>/RST</sub> , V <sub>RST</sub> (H and L versions)	$-0.3V$ to $V_{DD} + 0.3V$
Ambient Temperature Range (T <sub>A</sub> )	–40°C to +85°C
Package Thermal Resistance (θ <sub>JA</sub> )	256°C/W

### **Electrical Characteristics**

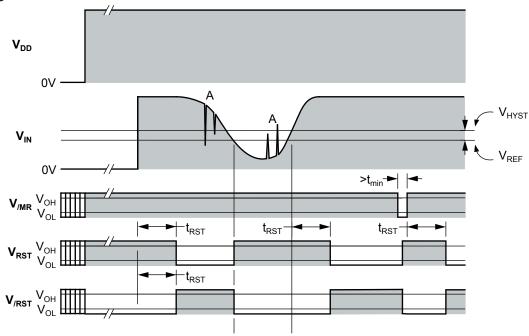
 $V_{DD}$  = 3.3V;  $T_A$  = +25°C, **bold** values indicate –40°C ≤  $T_A$  ≤ +85°C; unless noted

Symbol	Parameter	Condition	Min	Тур	Max	Units
$\overline{I_{DD}}$	Supply Current	V <sub>DD</sub> = V <sub>IN</sub> = 3.3V; /MR, RST, /RST open		3.0		μA
IN, UNDER	-VOLTAGE DETECTOR INPUT	•				-
$\overline{V_{REF}}$	Under-Voltage Threshold	T <sub>A</sub> = 25°C	295	300	305	mV
$\overline{V_{HYST}}$	Hysteresis Voltage			3		mv
I <sub>IN</sub>	Input Current			5		pА
		$T_{MIN} \le T_A \le T_{MAX}$			10	nA
RESET OU	TPUTS (/RST, RST)	•	•			
t <sub>PROP</sub>	Propagation Delay	$V_{IN} = (V_{REF(MAX)} + 100mV)$ to $V_{IN} = (V_{REF(MIN)} - 100mV)$		20		μs
t <sub>RST</sub>	Reset Pulse Width		140		280	ms
V <sub>OL</sub>	RST or /RST Output Voltage Low	$I_{SINK} = 1.6mA;$ $V_{DD} \ge 1.6V$			0.3	V
		I <sub>SINK</sub> = 100μA; V <sub>DD</sub> ≥ 1.2V, <b>Note 4</b>			0.3	V
V <sub>OH</sub>	RST or /RST Output Voltage High	$I_{SOURCE} = 500\mu\text{A};$ $V_{DD} \ge 1.5\text{V}$	0.8V <sub>DD</sub>			V
	(H and L Version Only)	I <sub>SOURCE</sub> = 10μA; V <sub>DD</sub> ≥ 1.2V, <b>Note 4</b>	0.8V <sub>DD</sub>			V
MANUAL R	RESET INPUTS (/MR)	•	<u> </u>		•	
$\overline{V_{IH}}$	Input High Voltage	1.5V ≤ V <sub>DD</sub> ≤ 5.5V	0.7V <sub>DD</sub>			V
$\overline{V_{IL}}$	Input Low Voltage	1.5V ≤ V <sub>DD</sub> ≤ 5.5V			0.3V <sub>DD</sub>	V
t <sub>PROP</sub>	Propagation Delay	V <sub>/MR</sub> < V <sub>IL</sub>		5		μs
t <sub>MIN</sub>	Minimum Input Pulse Width	Reset Occurs, V <sub>/MR</sub> < V <sub>IL</sub>		33		ns
I <sub>PU</sub>	Internal Pull-Up Current			100		nA
I <sub>IN</sub>	Input Current, /MR	V <sub>/MR</sub> < V <sub>IL</sub>		100		nA

- Note 1. Exceeding the absolute maximum rating may damage the device.
- Note 2. The device is not guaranteed to function outside its operating rating.
- Note 3. Devices are ESD sensitive. Handling precautions recommended. Human body model, 1.5k in series with 100pF.
- **Note 4.**  $V_{DD}$  operating range is 1.5V to 5.5V. Output is guaranteed to be asserted down to  $V_{DD}$  = 1.2V.

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# **Timing Diagram**

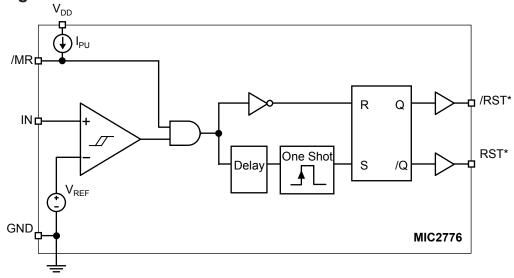


Propagation delays not shown for clarity.

Note A. The MIC2776 ignores very brief transients. See "Applications Information" for details.

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### **Functional Diagram**



\* Pinout and polarity vary by device type. See ordering information table.

## **Functional Description**

#### IN, Under-Voltage Detector Input

The voltage present at the IN pin is compared to the internal 300mV reference voltage. A reset is triggered if and when  $V_{\rm IN}$  falls below  $V_{\rm REF}$ . Typically, a resistor divider is used to scale the input voltage to be monitored such that  $V_{\rm IN}$  will fall below  $V_{\rm REF}$  as the voltage being monitored falls below the desired trip-point. Hysteresis is employed to prevent chattering due to noise.

#### RST, /RST Reset Output

Typically, the MIC2776 is used to monitor the power supply of intelligent circuits such as microcontrollers and microprocessors. By connecting the reset output of a MIC2776 to the reset input of a  $\mu$ C or  $\mu$ P, the processor will be properly reset at power-on and during power-down and brown-out conditions. In addition, asserting /MR, the manual reset input, will activate the reset function.

The reset outputs are asserted any time /MR is asserted or if  $V_{IN}$  drops below the threshold voltage. The reset outputs remain asserted for  $t_{RST}(min)$  after  $V_{IN}$  subsequently returns above the threshold boundary and /MR is released. A reset pulse is also generated at power-on.

#### /MR, Manual Reset Input

The ability to initiate a reset via external logic or a manual switch is provided in addition to the MIC2776's automatic supervisory functions. Driving the /MR input to a logic low causes an immediate and unconditional reset to occur. Assuming  $V_{\text{IN}}$  is within tolerance when /MR is released (returns high), the reset output will be de-asserted no less than  $t_{\text{RST}}$  later. /MR may be driven by a logic signal, or mechanical switch. Typically, a momentary push-button switch is connected such that /MR is shorted to ground when the switch contacts close. The switch may be connected directly between /MR and GND. /MR has an internal 100nA pull-up current to  $V_{\text{DD}}$  and may be left open if unused.

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### **Application Information**

#### **Programming the Voltage Threshold**

Referring to the "Typical Application Circuit", the voltage threshold is calculated as follows:

$$V_{TH} = V_{REF} \times \frac{(R1+R2)}{R2}$$

where 
$$V_{REF} = 0.300V$$

In order to provide the additional criteria needed to solve for the resistor values, the resistors can be selected such that the two resistors have a given total value, that is, R1 + R2 =  $R_{TOTAL}$ . Imposing this condition on the resistor values provides two equations that can be solved for the two unknown resistor values. A value such as  $1M\Omega$  for  $R_{TOTAL}$  is a reasonable choice since it keeps quiescent current to a generally acceptable level while not causing any measurable errors due to input bias currents. The larger the resistors, the larger the potential errors due to input bias current ( $I_{\rm IN}$ ). The maximum recommended value of  $R_{\rm TOTAL}$  is  $3M\Omega$ .

Applying this criteria and rearranging the  $V_{TH}$  expression to solve for the resistor values gives:

$$R2 = \frac{\left(R_{TOTAL}\right)\left(V_{REF}\right)}{V_{TH}}$$

$$R1 = R_{TOTAL} - R2$$

### **Application Example**

Figure 1 below illustrates a hypothetical MIC2776 application in which the MIC2776 is used to monitor the core supply of a high-performance CPU or DSP. The core supply,  $V_{CORE}$ , in this example is 1.0V ±5%. The main power rail and I/O voltage,  $V_{I/O}$ , is 2.5V ±5%. As shown in Figure 1, the MIC2776 is powered by  $V_{I/O}$ . The minimum value of  $V_{I/O}$  is 2.5V –5% = 2.375V; the maximum is 2.5V +5% = 2.625V. This is well within the MIC2776's power supply range of 1.5V to 5.5V.

Resistors R1 and R2 must be selected to correspond to the  $V_{CORE}$  supply of 1.0V. The goal is to insure that the core supply voltage is adequate to insure proper operation, i.e.,  $V_{CORE} \ge (1.0V - 5\%) = 0.950V$ . Because there is always a small degree of uncertainty due to the accuracy of the resistors, variations in the devices' voltage reference, etc., the threshold will be set slightly below this value. The potential variation in the MIC2776's voltage reference is specified as  $\pm 1.5\%$ . The resistors chosen will have their own tolerance specification. This example will assume the use of 1% accurate resistors. The potential worst-case error contribution due to input bias current can be calculated once the resistor values are chosen. If the guidelines above regarding the maximum total value of R1+R2 are followed, this error contribution will be very small thanks to the MIC2776's very low input bias current.

To summarize, the various potential error sources are:

- Variation in V<sub>REF</sub>: specified at ±1.5%
- Resistor tolerance: chosen by designer (typically ≤ ±1%)
- Input bias current, I<sub>IN</sub>: calculated once resistor values are known, typically very small

Taking the various potential error sources into account, the threshold voltage will be set slightly below the minimum  $V_{CORE}$  specification of 0.950V so that when the actual threshold voltage is at its maximum, it will not intrude into the normal operating range of  $V_{CORE}$ . The target threshold voltage will be set as follows:

Given that the total tolerance on  $V_{TH}$  is  $[V_{REF}$  tolerance] + [resistor tolerance]

= 
$$\pm 1.5\%$$
 +  $\pm 1\%$  =  $\pm 2.5\%$ , and  $V_{TH(max)}$  =  $V_{CORE(min)}$ , then  $V_{CORE(min)}$  =  $V_{TH}$  + 2.5%  $V_{TH}$  = 1.025  $V_{TH}$ ,

therefore, solving for 
$$V_{TH}$$
 results in

$$V_{TH} = \frac{V_{CORE(min)}}{1.025} = \frac{0.950}{1.025} = 0.9268V$$

Solving for R1 and R2 using this value for  $\rm V_{TH}$  and the equations above yields:

R1 = 
$$676.3k\Omega \approx 673k\Omega$$
  
R2 =  $323.7k\Omega \approx 324k\Omega$ 

The resulting circuit is shown in Figure 1.

#### **Input Bias Current Effects**

Now that the resistor values are known, it is possible to calculate the maximum potential error due to input bias current,  $I_{\text{IN}}$ . As shown in the "Electrical Characteristics" table, the maximum value of  $I_{\text{IN}}$  is 10nA. (Note that the typical value is a much smaller 5pA!) The magnitude of the offset caused by  $I_{\text{IN}}$  is given by:

$$V_{ERROR} = I_{IN(max)} \times (R1||R2) = V_{ERROR} = \pm 1 \times 10^{-8} \text{A} \times 2.189 \times 10^{5} \Omega = V_{ERROR} = \pm 2.189 \times 10^{-3} \text{V} = V_{ERROR} = \pm 2.189 \text{mV}$$

The typical error is about three orders of magnitude lower than this - close to one microvolt! Generally, the error due to input bias can be discounted. If it is to be taken into account, simply adjust the target threshold voltage downward by this amount and recalculate R1 and R2. The resulting value will be very close to optimum. If accuracy is more important than the quiescent current in the resistors, simply reduce the value of R<sub>TOTAL</sub> to minimize offset errors.

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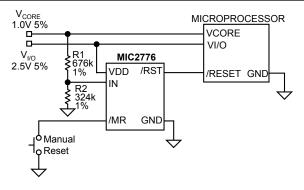


Figure 1. MIC2776 Example Design

#### Interfacing to Processors With Bidirectional Reset Pins

Some microprocessors have reset signal pins that are bidirectional, rather than input only. The Motorola 68HC11 family is one example. Because the MIC2776N's output is open-drain, it can be connected directly to the processor's reset pin using only the pull-up resistor normally required. See Figure 2.

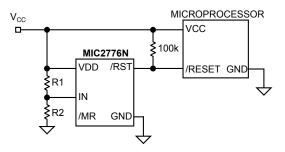


Figure 2. Interfacing to Bidirectional Reset Pin

#### **Transient Response**

The MIC2776 is inherently immune to very short negativegoing "glitches." Very brief transients may exceed the voltage threshold without tripping the output.

As shown in Figure 3, the narrower the transient, the deeper the threshold overdrive that will be ignored by the MIC2776. The graph represents the typical allowable transient duration for a given amount of threshold overdrive that will not generate a reset.

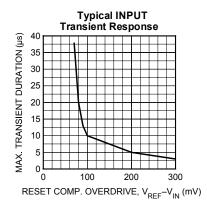


Figure 3. Typical INPUT Transient Response

#### **Ensuring Proper Operation at Low Supply**

At levels of  $V_{DD}$  below 1.2V, the MIC2776L's /RST output driver cannot turn on sufficiently to produce a valid logic-low on the /RST output. In this situation, other circuits driven by /RST could be allowed to float, causing undesired operation. (In most cases, however, it is expected that the circuits driven by the MIC2776L will be similarly inoperative at  $V_{DD} \leq 1.2V$ .)

If a given application requires that /RST be valid below V\_DD = 1.2V, this can be accomplished by adding a pull-down resistor to the /RST output. A value of  $100k\Omega$  is recommended as this is usually an acceptable compromise of leakage current and pull-down current. The resistor's value is not critical, however. See Figure 4.

The statements above also apply to the MIC2776H's RST output. That is, to ensure valid RST signal levels at  $V_{DD} < 1.2V$ , a pull-up resistor (as opposed to a pull-down) should be added to the RST output. A value of  $100k\Omega$  is typical for this application as well. See Figure 5.

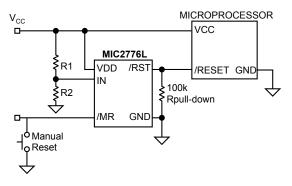


Figure 4. MIC2776L Valid /Reset Below 1.2V

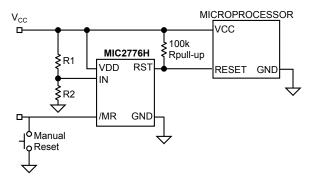
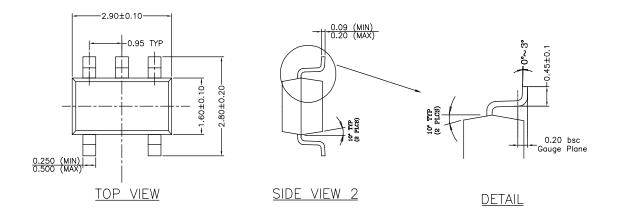
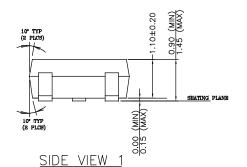


Figure 5. MIC2776H Valid Reset Below 1.2V

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## **Package Information**





- NUIE:
  1. PACKAGE OUTLINE EXCLUSIVE OF MOLD FLASH & BURR.
  2. PACKAGE OUTLINE INCLUSIVE OF SOLER PLATING.
  3. DIMENSION AND TOLERANCE PER ANSI Y14.5M, 1982.
  4. FOOT LENGTH MEASUREMENT BASED ON GAUGE PLANE METHOD.
  5. DIE FACES UP FOR MOLD, AND FACES DOWN FOR TRIM/FORM.

SOT-23-5 (M5)

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