Low-power X-tal driver with enable and internal resistor; 3-state

Rev. 6 — 11 December 2020

Product data sheet

1. General description

The 74AUP1Z125 is a crystal driver with enable, internal resistor and 3-state output. When not in use the $\overline{\text{EN}}$ input can be driven HIGH, putting the device in a low power disable mode with X1 pulled HIGH via R_{PU}, X2 set LOW and Y in the high impedance OFF-state. In disable mode the output Y assumes the high impedance OFF-state. Schmitt trigger action on the $\overline{\text{EN}}$ input makes the circuit tolerant to slower input rise and fall times across the entire V_{CC} range from 0.8 V to 3.6 V. Schmitt-trigger action at all inputs makes the circuit tolerant of slower input rise and fall times.

2. Features and benefits

- Wide supply voltage range from 0.8 V to 3.6 V
- High noise immunity
- ESD protection:
 - HBM JESD22-A114F Class 3A exceeds 5000 V
 - MM JESD22-A115-A exceeds 200 V
 - CDM JESD22-C101E exceeds 1000 V
- Latch-up performance exceeds 100 mA per JESD78B Class II
- Overvoltage tolerant inputs to 3.6 V
- Low noise overshoot and undershoot < 10 % of V_{CC}
- I_{OFF} circuitry provides partial power-down mode operation at output Y
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

3. Ordering information

Table 1. Ordering in	nformation										
Type number	Package	Package									
	Temperature range	Name	Description	Version							
74AUP1Z125GW	-40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363							
74AUP1Z125GM	-40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1.45 × 0.5 mm	SOT886							
74AUP1Z125GN	-40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 0.9 × 1.0 × 0.35 mm	SOT1115							
74AUP1Z125GS	-40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 1.0 × 1.0 × 0.35 mm	SOT1202							

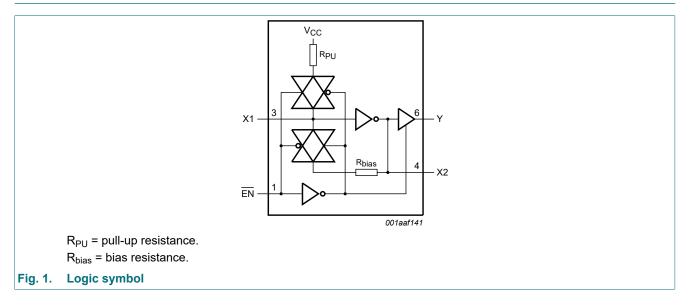
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4. Marking

Table 2. Marking						
Type number	Marking code [1]					
74AUP1Z125GW	55					
74AUP1Z125GM	55					
74AUP1Z125GN	55					
74AUP1Z125GS	55					

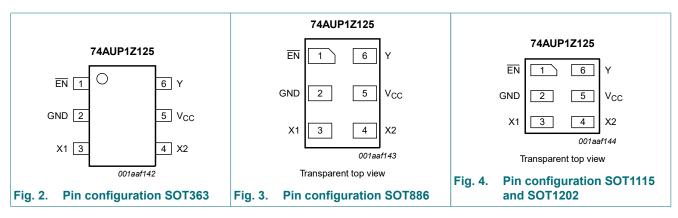
[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

5. Functional diagram



6. Pinning information





6.2. Pin description

Table 3. Pin description						
Symbol	Pin	Description				
EN	1	enable input (active LOW)				
GND	2 ground (0 V)					
X1	3	data input				
X2	4	unbuffered output				
V _{CC}	5	supply voltage				
Υ	6	data output				

7. Functional description

Table 4. Function table

H = *HIGH* voltage level; *L* = *LOW* voltage level; *Z* = *high-impedance OFF-state*.

Input C		Output			
EN X1 X2		X2	Y		
L	L	Н	Н		
L	Н	L	L		
Н	L	Н	Z		
Н	Н	L	Z		

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC}	supply voltage		-0.5	+4.6	V
I _{IK}	input clamping current	V _I < 0 V	-50	-	mA
VI	input voltage	[1]	-0.5	+4.6	V
I _{OK}	output clamping current	V _O < 0 V	-50	-	mA
Vo	output voltage	Active mode and Power-down mode [1]	-0.5	+4.6	V
I _O	output current	$V_{O} = 0 V \text{ to } V_{CC}$	-	±20	mA
I _{CC}	supply current		-	50	mA
I _{GND}	ground current		-50	-	mA
T _{stg}	storage temperature		-65	+150	°C
P _{tot}	total power dissipation	$T_{amb} = -40 \text{ °C to } +125 \text{ °C}$ [2]	-	250	mW

[1] The input and output voltage ratings may be exceeded if the input and output current ratings are observed.

For SOT363 (SC-88) package: P_{tot} derates linearly with 3.7 mW/K above 83 °C.
 For SOT886 (XSON6) package: P_{tot} derates linearly with 3.3 mW/K above 74 °C.
 For SOT1115 (XSON6) package: P_{tot} derates linearly with 3.2 mW/K above 71 °C.
 For SOT1202 (XSON6) package: P_{tot} derates linearly with 3.3 mW/K above 74 °C.

Low-power X-tal drive

9. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions			
V _{CC}	supply voltage				
VI	input voltage				
Vo	output voltage				
T _{amb}	ambient temperature				
Δt/ΔV	input transition rise and fall rate	V _{CC} = 0.8 V to 3.6 V			

10. Static characteristics

Table 7. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol Parameter V _{IH} HIGH-level input voltage V _{IL} LOW-level input voltage	Parameter	Conditions	Ta	_{mb} = 25	°C	T _{amb} = -40 °C	
		Min	Тур	Max	Min		
V _{IH}	HIGH-level input voltage	X1 input; V _{CC} = 0.8 V to 3.6 V	0.75V _{CC}	-	-	0.75V _{CC}	
		EN input					
		V _{CC} = 0.8 V	0.70V _{CC}	-	-	0.70V _{CC}	
		V _{CC} = 0.9 V to 1.95 V	0.65V _{CC}	-	-	0.65V _{CC}	
		V _{CC} = 2.3 V to 2.7 V	1.6	-	-	1.6	
		V _{CC} = 3.0 V to 3.6 V	2.0	-	-	2.0	
V _{IL}	LOW-level input voltage	X1 input; V _{CC} = 0.8 V to 3.6 V	-	-	0.25V _{CC}	-	
		EN input					
		V _{CC} = 0.8 V	-	-	0.30V _{CC}	-	
		V _{CC} = 0.9 V to 1.95 V	-	-	0.35V _{CC}	-	
		V _{CC} = 2.3 V to 2.7 V	-	-	0.7	-	
		V _{CC} = 3.0 V to 3.6 V	-	-	0.9	-	

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Symbol	Parameter	Conditions	Ta	_{mb} = 25 °	°C	T _{amb} = -40 °C
			Min	Тур	Max	Min
V _{OH}	HIGH-level output voltage	Y output; V _I at X1 input = V _{IH} or V _{IL}				
		I_{O} = -20 µA; V_{CC} = 0.8 V to 3.6 V	V _{CC} - 0.1	-	-	V _{CC} - 0.1
		I _O = -1.1 mA; V _{CC} = 1.1 V	0.75V _{CC}	-	-	0.7V _{CC}
		I _O = -1.7 mA; V _{CC} = 1.4 V	1.11	-	-	1.03
		I _O = -1.9 mA; V _{CC} = 1.65 V	1.32	-	-	1.30
		I _O = -2.3 mA; V _{CC} = 2.3 V	2.05	-	-	1.97
		I _O = -3.1 mA; V _{CC} = 2.3 V	1.9	-	-	1.85
		I _O = -2.7 mA; V _{CC} = 3.0 V	2.72	-	-	2.67
		I _O = -4.0 mA; V _{CC} = 3.0 V	2.6	-	-	2.55
		X2 output; V_1 = GND or V_{CC}				
		I_{O} = -20 µA; V_{CC} = 0.8 V to 3.6 V	V _{CC} - 0.1	-	-	V _{CC} - 0.1
		I _O = -1.1 mA; V _{CC} = 1.1 V	0.75V _{CC}	-	-	0.7V _{CC}
		I _O = -1.7 mA; V _{CC} = 1.4 V	1.11	-	-	1.03
		I _O = -1.9 mA; V _{CC} = 1.65 V	1.32	-	-	1.30
		I _O = -2.3 mA; V _{CC} = 2.3 V	2.05	-	-	1.97
		I _O = -3.1 mA; V _{CC} = 2.3 V	1.9	-	-	1.85
		I _O = -2.7 mA; V _{CC} = 3.0 V	2.72	-	-	2.67
		I _O = -4.0 mA; V _{CC} = 3.0 V	2.6	-	-	2.55

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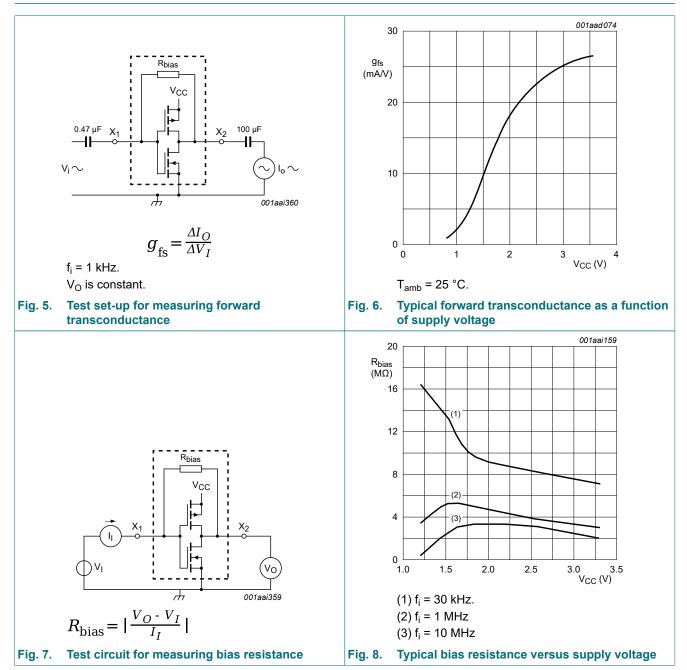
Symbol	Parameter	Conditions	Т	amb = 25	T _{amb} = -40 °	
			Min	Тур	Мах	Min
I1 input lea Ipu pull-up c IOZ OFF-stat IOFF power-of ΔIOFF additional	LOW-level output voltage	Y output; V _I at X1 input = V _{IH} or V _{IL}				
		I_{O} = 20 µA; V_{CC} = 0.8 V to 3.6 V	-	-	0.1	-
		I _O = 1.1 mA; V _{CC} = 1.1 V	-	-	0.3V _{CC}	-
		I _O = 1.7 mA; V _{CC} = 1.4 V	-	-	0.31	-
		I _O = 1.9 mA; V _{CC} = 1.65 V	-	-	0.31	-
		I _O = 2.3 mA; V _{CC} = 2.3 V	-	-	0.31	-
		I _O = 3.1 mA; V _{CC} = 2.3 V	-	-	0.44	-
		I _O = 2.7 mA; V _{CC} = 3.0 V	-	-	0.31	-
		I _O = 4.0 mA; V _{CC} = 3.0 V	-	-	0.44	-
VOL LOW-le I IOW-le I Input les I Pull-up of IOZ OFF-sta IOFF Power-of ΔIOFF addition		X2 output; $V_I = GND$ or V_{CC}				
		I_{O} = 20 µA; V_{CC} = 0.8 V to 3.6 V	-	-	0.1	-
		I _O = 1.1 mA; V _{CC} = 1.1 V	-	-	0.3V _{CC}	-
		I _O = 1.7 mA; V _{CC} = 1.4 V	0. (0. (0.	0.31	-	
		I _O = 1.9 mA; V _{CC} = 1.65 V	-	-	0.31	-
VOL LC VOL LC I Inf I Inf IOZ OF IOFF add		I _O = 2.3 mA; V _{CC} = 2.3 V	-	-	0.31	-
		I _O = 3.1 mA; V _{CC} = 2.3 V	-	-	0.44	-
		I _O = 2.7 mA; V _{CC} = 3.0 V	-	-	0.31	-
		I _O = 4.0 mA; V _{CC} = 3.0 V	-	-	0.44	-
li	input leakage current	X1 input; $V_I = \overline{EN} = V_{CC}$; $V_{CC} = 0$ V to 3.6 V	-	-	±0.1	-
		$\overline{\text{EN}}$ input; V _I = GND to 3.6 V; V _{CC} = 0 V to 3.6 V	-	-	±0.1	-
I _{pu}	pull-up current	X1 input; $\overline{EN} = V_{CC}$; V _I = GND; V _{CC} = 0.8 V to 3.6 V	-	-	15	-
I _{OZ}	OFF-state output current	Y output; V _O = 0 V to 3.6 V; V _{CC} = 0 V to 3.6 V; $\overline{EN} = V_{CC}$	-	-	±0.1	-
I _{OFF}	power-off leakage current	Only for output Y and input \overline{EN} . V _I or V _O = 0 V to 3.6 V; V _{CC} = 0 V	-	-	±0.2	-
Δl _{OFF}	additional power-off leakage current	Only for output Y and input \overline{EN} . V _I or V _O = 0 V to 3.6 V; V _{CC} = 0 V to 0.2 V	-	-	±0.2	-

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Symbol	Parameter	Conditions	Т	_{amb} = 25 °	°C	T _{amb} = -40 °C
			Min	Тур	Max	Min
I _{CC}	supply current	V_I = GND or V_{CC} ; I_O = 0 A; V_{CC} = 0.8 V to 3.6 V	-	-	75	-
ΔI _{CC}	additional supply current	$\overline{\text{EN}}$ input; V _I = V _{CC} - 0.6 V; I _O = 0 A; V _{CC} = 3.3 V	-	-	40	-
CI	input capacitance	X1 input; V_{CC} = 0 V to 3.6 V; V _I = GND or V _{CC}	-	1.3	-	-
$\frac{\Delta I_{CC}}{C_{I}} = \frac{\text{addition}}{\text{input ca}}$ $\frac{C_{O}}{g_{fs}} = \frac{\text{forward}}{\text{forward}}$		$\overline{\text{EN}}$ input; V _{CC} = 0 V to 3.6 V; V _I = GND or V _{CC}	-	0.8	-	-
$ \frac{\Delta I_{CC}}{C_{I}} = \frac{1}{100} $	output capacitance X2 output; $V_0 = GND$; $V_{CC} = 0 V$		-	1.5	-	-
		Y output; $V_0 = GND$; $V_{CC} = 0 V$	-	1.7	-	-
9 _{fs}	forward transconductance	see <u>Fig. 5</u> and <u>Fig. 6</u>				
		V _{CC} = 0.8 V	-	-	-	-
		V _{CC} = 1.1 V to 1.3 V	0.2	-	9.9	-
		V _{CC} = 1.4 V to 1.6 V	3.9	-	17.7	1.8
		V _{CC} = 1.65 V to 1.95 V	7.9	-	24.3	7.5
		V _{CC} = 2.3 V to 2.7 V	18	-	30.7	15.0
		V _{CC} = 3.0 V to 3.6 V	20.5	-	32.4	17.8
R _{bias}	bias resistance	$\overline{\text{EN}}$ = GND; f _i = 0 Hz; V _I = 0 V or V _{CC} ; see <u>Fig. 7</u> ; for frequency behavior see <u>Fig. 8</u>	1.08	1.62	3.08	1.07

11. Test circuits and graphs



12. Dynamic characteristics

Table 8. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 11.

Symbol	Parameter	Conditions		25 °C		-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ[1]	Мах	Min	Max	Min	Max	
C _L = 5 p	F		1						-	
t _{pd}	propagation	X1 to X2; see Fig. 9 [2]								
	delay	V _{CC} = 0.8 V	-	6.2	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	0.9	2.3	4.4	0.9	4.8	0.9	5.3	ns
		V _{CC} = 1.4 V to 1.6 V	0.7	1.7	3.1	0.6	3.4	0.6	3.8	ns
		V _{CC} = 1.65 V to 1.95 V	0.5	1.4	2.6	0.5	2.9	0.5	3.2	ns
		V _{CC} = 2.3 V to 2.7 V	0.4	1.1	2.0	0.4	2.3	0.4	2.6	ns
		V _{CC} = 3.0 V to 3.6 V	0.3	1.0	1.8	0.3	2.1	0.3	2.4	ns
		X1 to Y; see Fig. 9 [2]								
		V _{CC} = 0.8 V	-	18.5	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	2.8	5.9	12.5	3.2	14.8	3.2	16.3	ns
		V _{CC} = 1.4 V to 1.6 V	2.2	4.2	7.7	2.6	9.1	2.6	10.1	ns
		V _{CC} = 1.65 V to 1.95 V	1.9	3.5	6.2	2.2	7.8	2.2	8.6	ns
		V _{CC} = 2.3 V to 2.7 V	1.6	2.9	4.8	1.9	6.2	1.9	6.9	ns
		V _{CC} = 3.0 V to 3.6 V	1.4	2.6	4.1	1.7	4.7	1.7	5.2	ns
t _{en}	enable time	EN to Y; see <u>Fig. 10</u> [3]								
		V _{CC} = 0.8 V	-	31.2	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	3.1	6.1	13.8	2.9	16.3	2.9	18.0	ns
		V _{CC} = 1.4 V to 1.6 V	2.5	4.3	8.2	2.3	9.7	2.3	10.7	ns
		V _{CC} = 1.65 V to 1.95 V	2.1	3.6	6.5	2.0	7.6	2.0	8.4	ns
		V _{CC} = 2.3 V to 2.7 V	1.8	2.9	4.8	1.7	5.8	1.7	6.4	ns
		V _{CC} = 3.0 V to 3.6 V	1.7	2.6	4.1	1.7	4.7	1.7	5.2	ns
t _{dis}	disable time	EN to Y; see <u>Fig. 10</u> [4]								
		V _{CC} = 0.8 V	-	11.1	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	2.5	4.5	9.0	2.9	9.4	2.9	10.4	ns
		V _{CC} = 1.4 V to 1.6 V	2.0	3.3	6.4	2.3	6.7	2.3	7.4	ns
		V _{CC} = 1.65 V to 1.95 V	1.9	3.2	6.0	2.0	6.4	2.0	7.1	ns
		V _{CC} = 2.3 V to 2.7 V	1.4	2.3	4.4	1.7	4.7	1.7	5.2	ns
		V _{CC} = 3.0 V to 3.6 V	1.7	2.6	4.4	1.7	4.9	1.7	5.4	ns

Low-power X-tal driver with enable and internal resistor; 3-state

Symbol	Parameter	Conditions		25 °C		-40 °C to +85 °C		-40 °C to +125 °C		Unit
				Typ[1]	Max	Min	Мах	Min	Max	-
C _L = 10	pF					1			-	
t _{pd}	propagation	X1 to X2; see Fig. 9 [2]								
	delay	V _{CC} = 0.8 V	-	9.6	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	1.2	3.1	6.1	1.2	6.8	1.2	7.5	ns
		V _{CC} = 1.4 V to 1.6 V	1.0	2.3	4.0	0.9	4.6	0.9	5.1	ns
		V _{CC} = 1.65 V to 1.95 V	0.8	1.9	3.3	0.7	3.8	0.7	4.2	ns
		V _{CC} = 2.3 V to 2.7 V	0.6	1.5	2.7	0.6	3.1	0.6	3.5	ns
		V _{CC} = 3.0 V to 3.6 V	0.5	1.3	2.4	0.5	2.7	0.5	3.0	ns
		X1 to Y; see Fig. 9 [2]								
		V _{CC} = 0.8 V	-	21.4	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	3.2	6.7	14.3	3.6	16.2	3.6	17.9	ns
		V _{CC} = 1.4 V to 1.6 V	2.1	4.9	8.9	3.0	10.1	3.0	11.2	ns
		V _{CC} = 1.65 V to 1.95 V	1.9	4.1	6.9	2.6	8.0	2.6	8.8	ns
		V _{CC} = 2.3 V to 2.7 V	2.1	3.4	5.4	2.3	6.6	2.3	7.3	ns
		V _{CC} = 3.0 V to 3.6 V	1.8	3.1	4.8	2.1	5.6	2.1	6.2	ns
t _{en}	enable time	EN to Y; see <u>Fig. 10</u> [3]								
		V _{CC} = 0.8 V	-	34.4	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	3.6	6.9	15.5	3.4	16.0	3.4	17.6	ns
		V _{CC} = 1.4 V to 1.6 V	2.3	5.0	9.3	2.2	9.6	2.2	10.6	ns
		V _{CC} = 1.65 V to 1.95 V	2.0	4.2	7.2	1.9	7.9	1.9	8.7	ns
		V _{CC} = 2.3 V to 2.7 V	1.8	3.4	5.5	1.7	6.4	1.7	7.1	ns
		V _{CC} = 3.0 V to 3.6 V	1.7	3.2	4.9	1.7	5.5	1.7	6.1	ns
t _{dis}	disable time	EN to Y; see <u>Fig. 10</u> [4]								
		V _{CC} = 0.8 V	-	13.0	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	3.4	5.7	10.4	3.4	10.8	3.4	11.9	ns
		V _{CC} = 1.4 V to 1.6 V	2.1	4.2	7.6	2.2	8.0	2.2	8.8	ns
		V _{CC} = 1.65 V to 1.95 V	2.2	4.3	7.3	1.9	7.6	1.9	8.4	ns
		V _{CC} = 2.3 V to 2.7 V	1.6	3.1	5.3	1.7	5.5	1.7	6.1	ns
		V _{CC} = 3.0 V to 3.6 V	2.1	3.8	6.0	1.7	6.5	1.7	7.2	ns

Low-power X-tal driver with enable and internal resistor; 3-state

Symbol	Parameter	Conditions		25 °C		-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ[1]	Max	Min	Мах	Min	Max	
C _L = 15	pF	1				1				
t _{pd}	propagation	X1 to X2; see Fig. 9 [2]								
	delay	V _{CC} = 0.8 V	-	13.0	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	1.6	3.8	7.9	1.4	8.8	1.4	9.7	ns
		V _{CC} = 1.4 V to 1.6 V	1.3	2.8	4.9	1.1	5.7	1.1	6.3	ns
		V _{CC} = 1.65 V to 1.95 V	1.0	2.3	4.0	0.9	4.7	0.9	5.2	ns
		V _{CC} = 2.3 V to 2.7 V	0.8	1.9	3.2	0.8	3.7	0.8	4.1	ns
		V _{CC} = 3.0 V to 3.6 V	0.7	1.6	2.9	0.7	3.3	0.7	3.7	ns
		X1 to Y; see Fig. 9 [2]								
		V _{CC} = 0.8 V	-	24.2	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	3.6	7.5	16.1	4.0	17.6	4.0	19.4	ns
		V _{CC} = 1.4 V to 1.6 V	3.0	5.4	9.7	3.3	10.6	3.3	11.7	ns
		V _{CC} = 1.65 V to 1.95 V	2.2	4.6	7.7	2.9	9.0	2.9	9.9	ns
		V _{CC} = 2.3 V to 2.7 V	2.0	3.9	6.1	2.6	7.3	2.6	8.1	ns
		V _{CC} = 3.0 V to 3.6 V	2.0	3.6	5.4	2.3	5.9	2.3	6.5	ns
t _{en}	enable time	EN to Y; see <u>Fig. 10</u> [3]								
		V _{CC} = 0.8 V	-	37.5	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	4.0	7.7	17.2	3.7	17.5	3.7	19.3	ns
		V _{CC} = 1.4 V to 1.6 V	3.0	5.5	10.0	2.5	10.2	2.5	11.3	ns
		V _{CC} = 1.65 V to 1.95 V	2.3	4.7	7.9	2.1	9.2	2.1	10.2	ns
		V _{CC} = 2.3 V to 2.7 V	2.0	3.9	6.2	2.0	7.4	2.0	8.2	ns
		V _{CC} = 3.0 V to 3.6 V	2.0	3.6	5.5	1.9	6.0	1.9	6.6	ns

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Low-power X-tal driver with enable and internal resistor; 3-state

Symbol	Parameter	Conditions		25 °C		-40 °C t	o +85 °C	+85 °C -40 °C to +125 °C		Unit
			Min	Typ[1]	Max	Min	Max	Min	Max	
t _{dis}	disable time	EN to Y; see Fig. 10 [4]								
		V _{CC} = 0.8 V	-	14.8	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	4.3	6.8	11.2	3.7	12.4	3.7	13.7	ns
		V _{CC} = 1.4 V to 1.6 V	3.0	5.1	8.1	2.5	8.9	2.5	9.8	ns
		V _{CC} = 1.65 V to 1.95 V	3.0	5.4	8.0	2.1	9.3	2.1	10.3	ns
		V _{CC} = 2.3 V to 2.7 V	2.1	3.9	6.1	2.0	7.3	2.0	8.1	ns
		V _{CC} = 3.0 V to 3.6 V	2.9	5.1	7.2	1.9	7.9	1.9	8.7	ns
C _L = 30	pF	1				1			1	
t _{pd}	propagation	X1 to X2; see Fig. 9 [2]								
	delay	V _{CC} = 0.8 V	-	23.2	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	2.4	6.0	13.1	2.2	14.8	2.2	16.3	ns
		V _{CC} = 1.4 V to 1.6 V	2.0	4.2	7.6	1.8	9.0	1.8	9.9	ns
		V _{CC} = 1.65 V to 1.95 V	1.7	3.6	6.1	1.5	7.2	1.5	8.0	ns
		V _{CC} = 2.3 V to 2.7 V	1.4	2.9	4.8	1.3	5.7	1.3	6.3	ns
		V _{CC} = 3.0 V to 3.6 V	1.2	2.5	4.3	1.1	5.1	1.1	5.7	ns
		X1 to Y; see Fig. 9 [2]								
		V _{CC} = 0.8 V	-	32.6	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	4.8	9.6	21.0	5.0	21.7	5.0	23.9	ns
		V _{CC} = 1.4 V to 1.6 V	4.0	6.9	12.4	4.3	13.5	4.3	14.9	ns
		V _{CC} = 1.65 V to 1.95 V	2.9	5.9	9.8	3.8	10.7	3.8	11.8	ns
		V _{CC} = 2.3 V to 2.7 V	2.7	5.0	7.5	3.3	8.2	3.3	9.1	ns
		V _{CC} = 3.0 V to 3.6 V	2.7	4.7	6.8	3.1	7.7	3.1	8.5	ns
t _{en}	enable time	EN to Y; see Fig. 10 [3]								
		V _{CC} = 0.8 V	-	47.1	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	5.2	9.9	21.0	4.8	21.7	4.8	23.9	ns
		V _{CC} = 1.4 V to 1.6 V	4.0	7.1	12.4	3.1	13.5	3.1	14.9	ns
		V _{CC} = 1.65 V to 1.95 V	3.0	6.0	9.9	2.8	10.7	2.8	11.8	ns
		V _{CC} = 2.3 V to 2.7 V	2.7	5.0	7.7	2.6	8.1	2.6	9.0	ns
		V _{CC} = 3.0 V to 3.6 V	2.7	4.8	6.8	2.6	7.7	2.6	8.5	ns
t _{dis}	disable time	EN to Y; see Fig. 10 [4]								
		V _{CC} = 0.8 V	-	20.3	-	-	-	-	-	ns
		V _{CC} = 1.1 V to 1.3 V	6.0	10.2	15.3	4.8	16.5	4.8	18.2	ns
		V _{CC} = 1.4 V to 1.6 V	4.4	7.8	11.2	3.1	12.3	3.1	13.6	ns
		V _{CC} = 1.65 V to 1.95 V	5.1	8.8	12.5	2.8	13.3	2.8	14.7	ns
		V _{CC} = 2.3 V to 2.7 V	3.6	6.3	8.6	2.6	9.5	2.6	10.5	ns
		V _{CC} = 3.0 V to 3.6 V	5.2	8.8	11.5	2.6	13.0	2.6	14.3	ns

Low-power X-tal driver with enable and internal resistor; 3-state

Symbol	Parameter	Conditions		25 °C		-40 °C to	o +85 °C	-40 °C to	+125 °C	Unit
			Min	Typ[1]	Мах	Min	Max	Min	Мах	
C _L = 5 pl	C _L = 5 pF, 10 pF, 15 pF and 30 pF									
d	power dissipation capacitance	$f_i = 1 \text{ MHz}; \overline{EN} = GND;$ [5] [6] V ₁ = GND to V _{CC}								
		V _{CC} = 0.8 V	-	7.1	-	-	-	-	-	pF
		V _{CC} = 1.1 V to 1.3 V	-	12.9	-	-	-	-	-	pF
		V _{CC} = 1.4 V to 1.6 V	-	19.2	-	-	-	-	-	pF
		V _{CC} = 1.65 V to 1.95 V	-	19.9	-	-	-	-	-	pF
		V _{CC} = 2.3 V to 2.7 V	-	21.6	-	-	-	-	-	pF
		V _{CC} = 3.0 V to 3.6 V	-	24.3	-	-	-	-	-	pF

[1] All typical values are measured at nominal V_{CC}.

 t_{pd} is the same as t_{PLH} and t_{PHL} . [2]

[3] t_{en} is the same as t_{PZH} and t_{PZL} .

[4]

 t_{dis} is the same as t_{PHZ} and t_{PLZ} . C_{PD} is used to determine the dynamic power dissipation (P_D in μ W). [5]

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where:

 f_i = input frequency in MHz;

 f_o = output frequency in MHz;

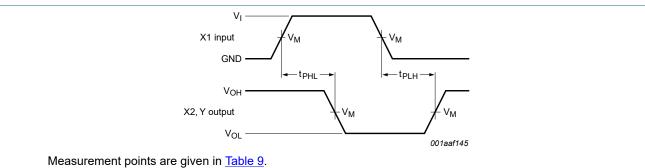
 C_L = output load capacitance in pF;

V_{CC} = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o) = \text{sum of the outputs.}$ [6] Feedback current is included in C_{PD}.

12.1. Waveforms and test circuit



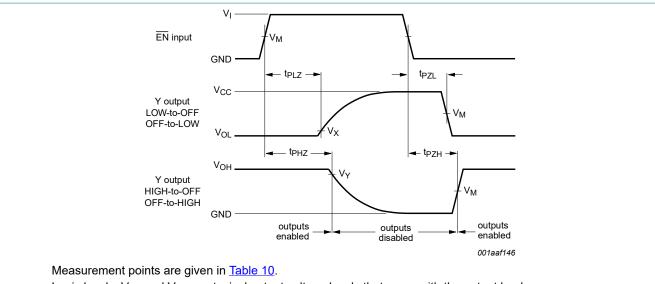
Logic levels: V_{OL} and V_{OH} are typical output voltage levels that occur with the output load.

The input (X1) to output (X2, Y) propagation delays Fig. 9.

Table 9. Measurement points

Supply voltage	Output	Input		
V _{cc}	V _M	V _M	VI	t _r = t _f
0.8 V to 3.6 V	$0.5 \times V_{CC}$	$0.5 \times V_{CC}$	V _{CC}	≤ 3.0 ns

Low-power X-tal driver with enable and internal resistor; 3-state

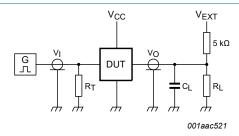


Logic levels: V_{OL} and V_{OH} are typical output voltage levels that occur with the output load.

Fig. 10. Enable and disable times

Table 10. Measurement points

Supply voltage	Input	Output				
V _{cc}	V _M	V _M	V _X	V _Y		
0.8 V to 1.6 V	0.5 × V _{CC}	$0.5 \times V_{CC}$	V _{OL} + 0.1 V	V _{OH} - 0.1 V		
1.65 V to 2.7 V	0.5 × V _{CC}	0.5 × V _{CC}	V _{OL} + 0.15 V	V _{OH} - 0.15 V		
3.0 V to 3.6 V	0.5 × V _{CC}	0.5 × V _{CC}	V _{OL} + 0.3 V	V _{OH} - 0.3 V		



Test data is given in Table 11.

Definitions for test circuit:

R_L = Load resistance.

C_L = Load capacitance including jig and probe capacitance.

 R_T = Termination resistance should be equal to the output impedance Z_o of the pulse generator.

V_{EXT} = External voltage for measuring switching times.

Fig. 11. Test circuit for measuring switching times

Table 11. Test data

Supply voltage	Load	V _{EXT}			
V _{cc}	CL	R _L [1]	t _{PLH} , t _{PHL}	t _{PZH} , t _{PHZ}	t _{PZL} , t _{PLZ}
0.8 V to 3.6 V	5 pF, 10 pF, 15 pF and 30 pF	5 kΩ or 1 MΩ	open	GND	2 × V _{CC}

[1] For measuring enable and disable times $R_L = 5 k\Omega$.

For measuring propagation delays, setup and hold times and pulse width R_L = 1 M Ω .

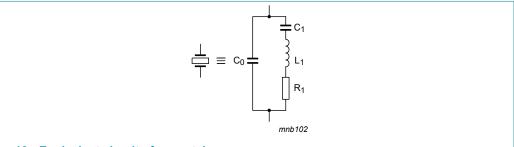
13. Application information

Crystal controlled oscillator circuits are widely used in clock pulse generators because of their excellent frequency stability and wide operating frequency range. The use of the 74AUP1Z125 provides the additional advantages of low power dissipation, stable operation over a wide range of frequency and temperature and a very small footprint. This application information describes crystal characteristics, design and testing of crystal oscillator circuits based on the 74AUP1Z125.

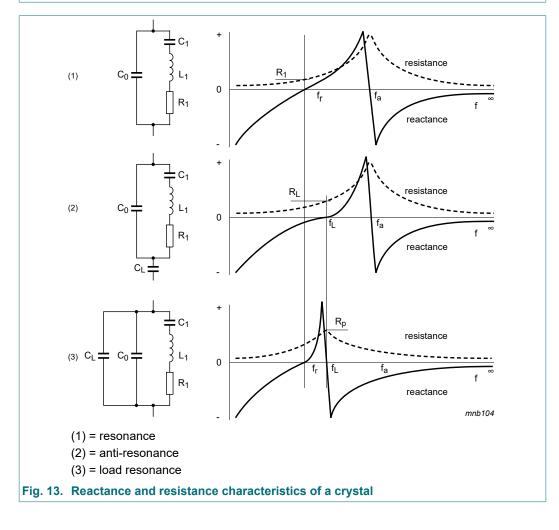
13.1. Crystal characteristics

Fig. 12 is the equivalent circuit of a quartz crystal.

The reactive and resistive components of the impedance of the crystal alone, and the crystal with a series and a parallel capacitance, is shown in Fig. 13.







74AUP1Z125

15 / 23

13.1.1. Design

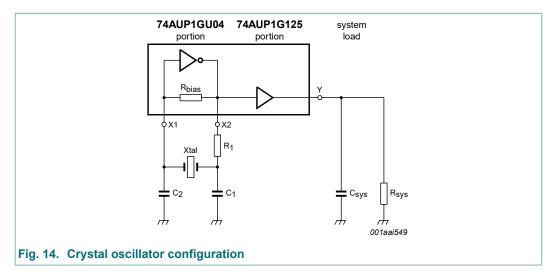
Fig. 14 shows the recommended way to connect a crystal to the 74AUP1Z125. This circuit is basically a Pierce oscillator circuit in which the crystal is operating at its fundamental frequency and tuned by the parallel load capacitance of C_1 and C_2 . C_1 and C_2 are in series with the crystal. They should be approximately equal. R_1 is the drive-limiting resistor and is set to approximately the same value as the reactance of C_1 at the crystal frequency ($R_1 = X_{C1}$). This results in an input to the crystal of 50 % of the rail-to-rail output of X2. This keeps the drive level into the crystal within drive specifications (the designer should verify this). Overdriving the crystal can cause damage.

The internal bias resistor provides negative feedback and sets a bias point of the inverter near mid-supply, operating the 74AUP1GU04 in the high gain linear region.

To calculate the values of C_1 and C_2 , the designer can use the formula:

$$C_L = \frac{C_1 \times C_2}{C_1 + C_2} + C_s$$

 C_L is the load capacitance as specified by the crystal manufacturer. C_s is the stray capacitance of the circuit and for 74AUP1Z125, C_s is equal to an input capacitance of 1.5 pF.



13.1.2. Testing

After the calculations are performed for a particular crystal, the oscillator circuit should be tested. The following simple checks verify the prototype design of a crystal controlled oscillator circuit. Perform the checks after laying out the board:

- Test the oscillator over worst-case conditions (lowest supply voltage, worst-case crystal and highest operating temperature). Adding series and parallel resistors can simulate a worse case crystal.
- Insure that the circuit does not oscillate without the crystal.
- Check the frequency stability over a supply range greater than that which is likely to occur during normal operation.
- Check that the start-up time is within system requirements.

As the 74AUP1Z125 isolates the system loading, once the design is optimized, the single layout may work in multiple applications for any given crystal.

14. Package outline

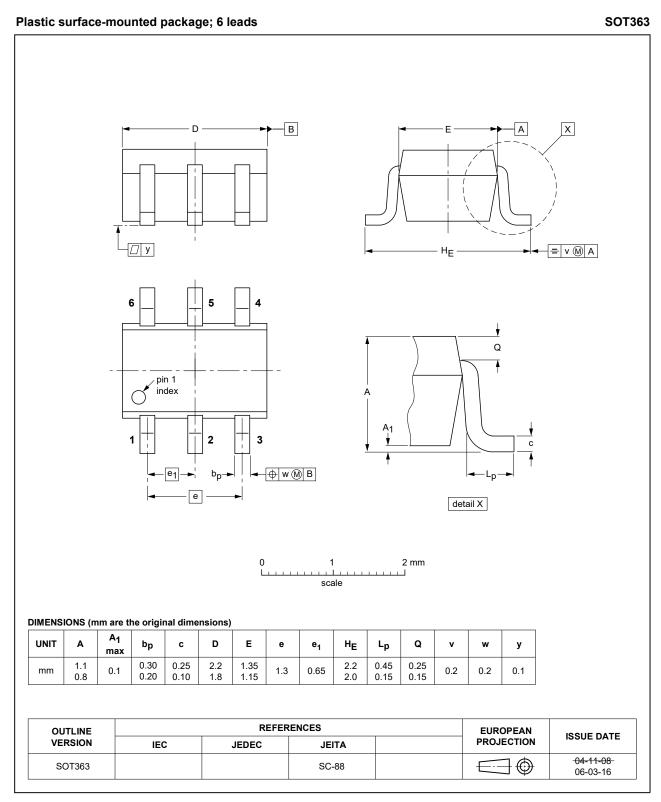


Fig. 15. Package outline SOT363 (SC-88)

Low-power X-tal driver with enable and internal resistor; 3-state

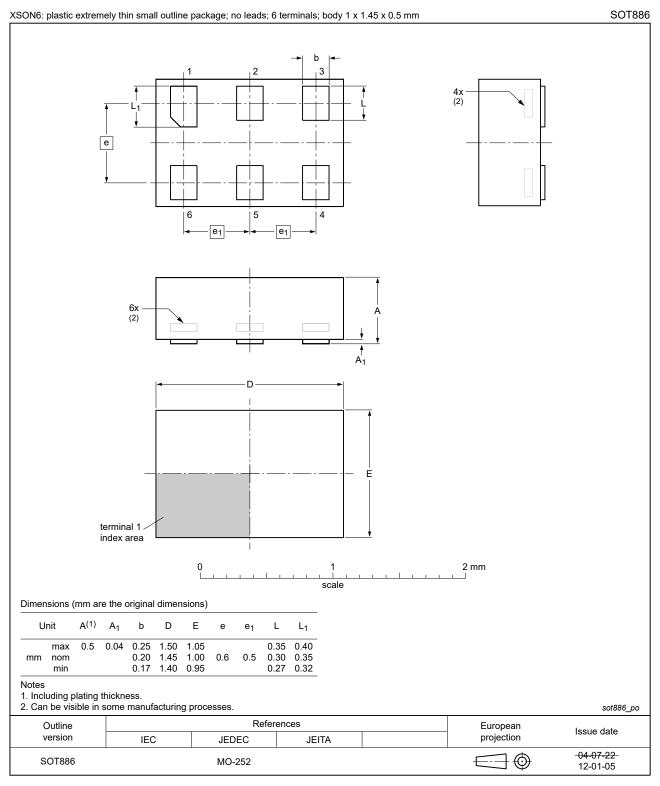


Fig. 16. Package outline SOT886 (XSON6)

XSON6: extremely thin small outline package; no leads; 6 terminals; body 0.9 x 1.0 x 0.35 mm

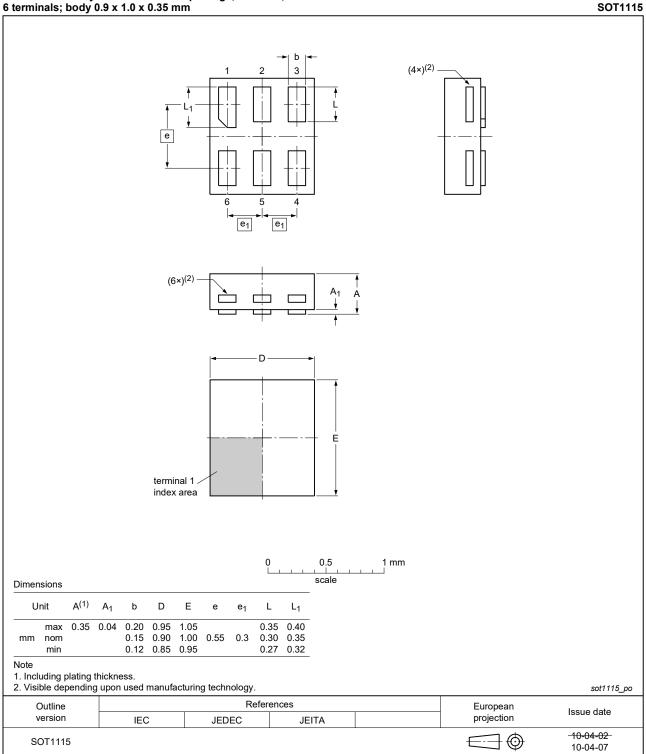
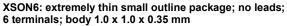


Fig. 17. Package outline SOT1115 (XSON6)



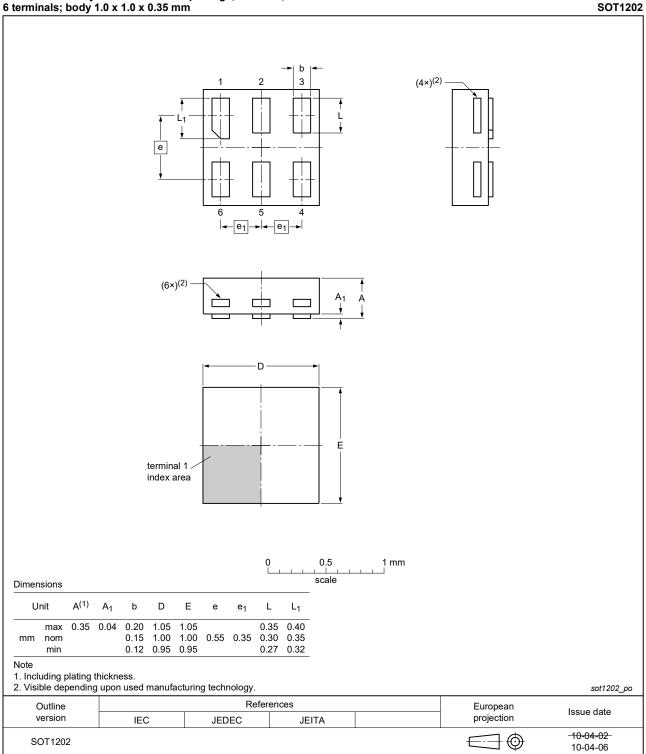


Fig. 18. Package outline SOT1202 (XSON6)

15. Abbreviations

Acronym	Description	
CDM	Charged Device Model	-
DUT	Device Under Test	
ESD	ElectroStatic Discharge	
НВМ	Human Body Model	
MM	Machine Model	

16. Revision history

Table 13. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
74AUP1Z125 v.6	20201211	Product data sheet	-	74AUP1Z125 v.5	
Modifications:	guidelines o Legal texts l Type numbe <u>Section 1</u> up	rmat of this data sheet has been redesigned to comply with the ider nes of Nexperia. Exerts have been adapted to the new company name where appropri umber 74AUP1Z125GF (SOT891 / XSON6) removed. <u>n 1</u> updated. <u>5</u> : Derating values for P _{tot} total power dissipation updated.			
74AUP1Z125 v.5	20120808	Product data sheet	-	74AUP1Z125 v.4	
Modifications:	Package ou	tline drawing of SOT886 (ig. 16) modified.		
74AUP1Z125 v.4	20111201	Product data sheet	-	74AUP1Z125 v.3	
Modifications:	Legal pages	updated.			
74AUP1Z125 v.3	20100909	Product data sheet	-	74AUP1Z125 v.2	
74AUP1Z125 v.2	20080807	Product data sheet	-	74AUP1Z125 v.1	
74AUP1Z125 v.1	20060803	Product data sheet	-	-	

17. Legal information

Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

 Please consult the most recently issued document before initiating or completing a design.

- [2] The term 'short data sheet' is explained in section "Definitions".
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Contents

1. General description	1
2. Features and benefits	1
3. Ordering information	1
4. Marking	2
5. Functional diagram	2
6. Pinning information	2
6.1. Pinning	2
6.2. Pin description	3
7. Functional description	3
8. Limiting values	3
9. Recommended operating conditions	4
10. Static characteristics	4
11. Test circuits and graphs	8
12. Dynamic characteristics	9
12.1. Waveforms and test circuit	13
13. Application information	15
13.1. Crystal characteristics	15
13.1.1. Design	16
13.1.2. Testing	16
14. Package outline	17
15. Abbreviations	21
16. Revision history	21
17. Legal information	22

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