## 74LVC1T45-Q100; 74LVCH1T45-Q100

## Dual supply translating transceiver; 3-state

Rev. 4-1 December 2020

## 1. General description

The 74LVC1T45-Q100; 74LVCH1T45-Q100 are single bit, dual supply transceivers with 3-state outputs that enable bidirectional level translation. They feature two 1-bit input-output ports ( A and B ), a direction control input (DIR) and dual supply pins $\left(\mathrm{V}_{\mathrm{CC}(\mathrm{A})}\right.$ and $\left.\mathrm{V}_{\mathrm{CC}(\mathrm{B})}\right)$. Both $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ and $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$ can be supplied with any voltage between 1.2 V and 5.5 V . This flexibility makes the device suitable for translating between any of the low voltage nodes ( $1.2 \mathrm{~V}, 1.5 \mathrm{~V}, 1.8 \mathrm{~V}, 2.5 \mathrm{~V}, 3.3 \mathrm{~V}$ and 5.0 V ). Pins $A$ and DIR are referenced to $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ and pin B is referenced to $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$. A HIGH on DIR allows transmission from $A$ to $B$ and a LOW on DIR allows transmission from $B$ to $A$.

The devices are fully specified for partial power-down applications using $\mathrm{I}_{\text {OFF }}$. The $\mathrm{I}_{\text {OFF }}$ circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ or $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$ are at GND level, both A port and B port are in the high-impedance OFF-state.
Active bus hold circuitry in the 74LVCH1T45-Q100 holds unused or floating data inputs at a valid logic level.
This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

## 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
- Specified from $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ and from $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
- Wide supply voltage range:
- $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}: 1.2 \mathrm{~V}$ to 5.5 V
- $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}: 1.2 \mathrm{~V}$ to 5.5 V
- High noise immunity
- Complies with JEDEC standards:
- JESD8-7 (1.2 V to 1.95 V )
- JESD8-5 (1.8 V to 2.7 V )
- JESD8C (2.7 V to 3.6 V )
- JESD36 (4.5 V to 5.5 V )
- ESD protection:
- HBM JESD22-A114F Class 3A exceeds 4000 V
- CDM JESD22-C101E exceeds 1000 V
- Maximum data rates:
- 420 Mbps ( 3.3 V to 5.0 V translation)
- 210 Mbps (translate to 3.3 V ))
- 140 Mbps (translate to 2.5 V )
- 75 Mbps (translate to 1.8 V )
- 60 Mbps (translate to 1.5 V )
- Suspend mode
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- $\pm 24 \mathrm{~mA}$ output drive $\left(\mathrm{V}_{\mathrm{CC}}=3.0 \mathrm{~V}\right)$
- Inputs accept voltages up to 5.5 V
- Low power consumption: $16 \mu \mathrm{~A}$ maximum $\mathrm{I}_{\mathrm{CC}}$
- I Ioff circuitry provides partial Power-down mode operation


## 3. Ordering information

Table 1. Ordering information

| Type number | Package |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  | Temperature range | Name | Description | Version |
| 74LVC1T45GW-Q100 | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | SC-88 | plastic surface-mounted package; 6 leads | SOT363 |
| 74LVCH1T45GW-Q100 |  | XSON6 | plastic extremely thin small outline package; <br> no leads; 6 terminals; body $1 \times 1.45 \times 0.5 \mathrm{~mm}$ | SOT886 |
| 74LVC1T45GM-Q100 | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |  |  |  |

## 4. Marking

## Table 2. Marking

| Type number | Marking code [1] |
| :--- | :--- |
| 74LVC1T45GW-Q100 | V5 |
| 74LVCH1T45GW-Q100 | X5 |
| 74LVC1T45GM-Q100 | V5 |

[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

## 5. Functional diagram



Fig. 1. Logic symbol


Fig. 2. Logic diagram

## 6. Pinning information

### 6.1. Pinning



74LVC1T45-Q100 74LVCH1T45-Q100

Fig. 3. Pin configuration SOT363 (SC-88)

74LVC1T45-Q100


Fig. 4. Pin configuration SOT886 (XSON6)

### 6.2. Pin description

Table 3. Pin description

| Symbol | Pin | Description |
| :--- | :--- | :--- |
| $V_{\text {CC(A) }}$ | 1 | supply voltage port A and DIR |
| GND | 2 | ground $(0 \mathrm{~V})$ |
| A | 3 | data input or output |
| B | 4 | data input or output |
| DIR | 5 | direction control |
| $V_{C C(B)}$ | 6 | supply voltage port B |

## 7. Functional description

Table 4. Function table
$H=$ HIGH voltage level; L = LOW voltage level; $X=$ don't care; $Z=$ high-impedance OFF-state.

| Supply voltage | Input | Input/output [1] |  |
| :--- | :--- | :--- | :--- |
| $\mathbf{V}_{\mathbf{C C}(\mathrm{A})}, \mathbf{V}_{\mathrm{CC}(\mathrm{B})}$ | DIR | A | B |
| 1.2 V to 5.5 V | L | $\mathrm{~A}=\mathrm{B}$ | input |
| 1.2 V to 5.5 V | H | input | B = A |
| GND $[2]$ | X | Z | Z |

[1] The input circuit of the data $I / O$ is always active.
[2] When either $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ or $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$ is at GND level, the device goes into suspend mode.

## 8. Limiting values

Table 5. Limiting values
In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions |  | Min | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CC(A) }}$ | supply voltage A |  |  | -0.5 | +6.5 | V |
| $\mathrm{V}_{\text {CC(B) }}$ | supply voltage B |  |  | -0.5 | +6.5 | V |
| $I_{\text {IK }}$ | input clamping current | $\mathrm{V}_{1}<0 \mathrm{~V}$ |  | -50 | - | mA |
| $\mathrm{V}_{1}$ | input voltage |  | [1] | -0.5 | +6.5 | V |
| $\mathrm{l}_{\mathrm{OK}}$ | output clamping current | $\mathrm{V}_{\mathrm{O}}<0 \mathrm{~V}$ |  | -50 | - | mA |
| $\mathrm{V}_{\mathrm{O}}$ | output voltage | Active mode | [1] [2] [3] | -0.5 | $\mathrm{V}_{\mathrm{CCO}}+0.5$ | V |
|  |  | Suspend or 3-state mode | [1] | -0.5 | +6.5 | V |
| Io | output current | $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ to $\mathrm{V}_{\mathrm{Cco}}$ | [2] | - | $\pm 50$ | mA |
| $\mathrm{I}_{\mathrm{CC}}$ | supply current | $\mathrm{ICC}_{\text {( } ~}^{\text {) }}$ or $\mathrm{I}_{\mathrm{CC}(\mathrm{B})}$ |  | - | 100 | mA |
| $\mathrm{I}_{\text {GND }}$ | ground current |  |  | -100 | - | mA |
| $\mathrm{T}_{\text {stg }}$ | storage temperature |  |  | -65 | +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{P}_{\text {tot }}$ | total power dissipation | $\mathrm{T}_{\text {amb }}=-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | [4] | - | 250 | mW |

[1] The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.
[2] $\mathrm{V}_{\mathrm{CCO}}$ is the supply voltage associated with the output port.
[3] $\mathrm{V}_{\mathrm{CCO}}+0.5 \mathrm{~V}$ should not exceed 6.5 V .
[4] For SOT363 (SC-88) package: $\mathrm{P}_{\text {tot }}$ derates linearly with $3.7 \mathrm{~mW} / \mathrm{K}$ above $83^{\circ} \mathrm{C}$.
For SOT886 (XSON6) package: $P_{\text {tot }}$ derates linearly with $3.3 \mathrm{~mW} / \mathrm{K}$ above $74^{\circ} \mathrm{C}$.

## 9. Recommended operating conditions

Table 6. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CC( }}(\mathrm{P})$ | supply voltage A |  | 1.2 | 5.5 | V |
| $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$ | supply voltage B |  | 1.2 | 5.5 | V |
| $V_{1}$ | input voltage |  | 0 | 5.5 | V |
| $\mathrm{V}_{\mathrm{O}}$ | output voltage | Active mode [1] | 0 | $\mathrm{V}_{\mathrm{CcO}}$ | V |
|  |  | Suspend or 3-state mode | 0 | 5.5 | V |
| $\mathrm{T}_{\text {amb }}$ | ambient temperature |  | -40 | +125 | ${ }^{\circ} \mathrm{C}$ |
| $\Delta \mathrm{t} / \Delta \mathrm{V}$ | input transition rise and fall rate | $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | - | 20 | $\mathrm{ns} / \mathrm{V}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.4 \mathrm{~V}$ to 1.95 V | - | 20 | $\mathrm{ns} / \mathrm{V}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=2.3 \mathrm{~V}$ to 2.7 V | - | 20 | $\mathrm{ns} / \mathrm{V}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=3 \mathrm{~V}$ to 3.6 V | - | 10 | $\mathrm{ns} / \mathrm{V}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=4.5 \mathrm{~V}$ to 5.5 V | - | 5 | $\mathrm{ns} / \mathrm{V}$ |

[1] $\mathrm{V}_{\mathrm{cco}}$ is the supply voltage associated with the output port.
[2] $\mathrm{V}_{\mathrm{CC}}$ is the supply voltage associated with the input port.

## 10. Static characteristics

Table 7. Typical static characteristics at $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$
At recommended operating conditions; voltages are referenced to GND (ground = 0 V ). [1] [2]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{OH}}$ | HIGH-level output voltage | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{IH}}$ or $\mathrm{V}_{\mathrm{IL}} ; \mathrm{I}_{\mathrm{O}}=-3 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=1.2 \mathrm{~V}$ | - | 1.09 | - | V |
| $\mathrm{V}_{\mathrm{OL}}$ | LOW-level output voltage | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\text {IH }}$ or $\mathrm{V}_{\text {IL }} ; \mathrm{l}_{\mathrm{O}}=3 \mathrm{~mA} ; \mathrm{V}_{\text {CCO }}=1.2 \mathrm{~V}$ | - | 0.07 | - | V |
| $I_{1}$ | input leakage current | $\begin{aligned} & \text { DIR input; } \mathrm{V}_{\mathrm{I}}=0 \mathrm{~V} \text { to } 5.5 \mathrm{~V} \text {; } \\ & \mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V} \text { to } 5.5 \mathrm{~V} \end{aligned}$ | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {BHL }}$ | bus hold LOW current | A or B port; $\mathrm{V}_{\mathrm{I}}=0.42 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | - | 19 | - | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {BHH }}$ | bus hold HIGH current | A or B port; $\mathrm{V}_{1}=0.78 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | - | -19 | - | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {BHLO }}$ | bus hold LOW overdrive current | A or B port; $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | - | 19 | - | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {BHHO }}$ | bus hold HIGH overdrive current | A or B port; $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | - | -19 | - | $\mu \mathrm{A}$ |
| loz | OFF-state output current | A or B port; $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{Cco}}$; $\mathrm{V}_{\mathrm{CcO}}=1.2 \mathrm{~V}$ to 5.5 V | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
| loff | power-off leakage current | A port; $\mathrm{V}_{1}$ or $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ to 5.5 V ; $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=0 \mathrm{~V}$; $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$ to 5.5 V | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
|  |  | $\begin{aligned} & \mathrm{B} \text { port; } \mathrm{V}_{\mathrm{I}} \text { or } \mathrm{V}_{\mathrm{O}}=0 \mathrm{~V} \text { to } 5.5 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}(\mathrm{~B})}=0 \mathrm{~V} ; \\ & \mathrm{V}_{\mathrm{CC}(\mathrm{~A})}=1.2 \mathrm{~V} \text { to } 5.5 \mathrm{~V} \end{aligned}$ | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
| $\mathrm{C}_{1}$ | input capacitance | DIR input; $\mathrm{V}_{\mathrm{I}}=0 \mathrm{~V}$ or 3.3 V ; $V_{C C(A)}=V_{C C(B)}=3.3 \mathrm{~V}$ | - | 2.2 | - | pF |
| $\mathrm{C}_{1 / \mathrm{O}}$ | input/output capacitance | A and B port; suspend mode; $\mathrm{V}_{\mathrm{O}}=3.3 \mathrm{~V} \text { or } 0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}(\mathrm{~A})}=\mathrm{V}_{\mathrm{CC}(\mathrm{~B})}=3.3 \mathrm{~V}$ | - | 6.0 | - | pF |

[1] $\mathrm{V}_{\mathrm{CCI}}$ is the supply voltage associated with the data input port.
[2] $\mathrm{V}_{\mathrm{CCO}}$ is the supply voltage associated with the output port.
[3] To guarantee the node switches, an external driver must source/sink at least $I_{B H L O} /_{\text {BHHO }}$ when the input is in the range $\mathrm{V}_{I L}$ to $\mathrm{V}_{\text {IH }}$.
Table 8. Static characteristics
At recommended operating conditions; voltages are referenced to GND (ground = 0 V ). [1] [2]

| Symbol | Parameter | Conditions | $-40{ }^{\circ} \mathrm{C}$ to +85 ${ }^{\circ} \mathrm{C}$ |  | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Min | Max |  |
| $\mathrm{V}_{\mathrm{IH}}$ | HIGH-level input voltage | data input |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | 0.8 V CCl | - | 0.8 V CCI | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.4 \mathrm{~V}$ to 1.95 V | $0.65 \mathrm{~V}_{\mathrm{CCI}}$ | - | $0.65 \mathrm{~V}_{\mathrm{CCI}}$ | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=2.3 \mathrm{~V}$ to 2.7 V | 1.7 | - | 1.7 | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=3.0 \mathrm{~V}$ to 3.6 V | 2.0 | - | 2.0 | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=4.5 \mathrm{~V}$ to 5.5 V | $0.7 \mathrm{~V}_{\mathrm{CCI}}$ | - | $0.7 \mathrm{~V}_{\mathrm{CCI}}$ | - | V |
|  |  | DIR input |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | $0.8 \mathrm{~V} \mathrm{VCC}_{(\mathrm{A})}$ | - | $0.8 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.4 \mathrm{~V}$ to 1.95 V | $0.65 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | - | $0.65 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=2.3 \mathrm{~V}$ to 2.7 V | 1.7 | - | 1.7 | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=3.0 \mathrm{~V}$ to 3.6 V | 2.0 | - | 2.0 | - | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=4.5 \mathrm{~V}$ to 5.5 V | $0.7 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | - | $0.7 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | - | V |


| Symbol | Parameter | Conditions | $-40{ }^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  | $-40^{\circ} \mathrm{C}$ to $+125{ }^{\circ} \mathrm{C}$ |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Min | Max |  |
| VIL | LOW-level input voltage | data input |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | - | $0.2 \mathrm{~V}_{\mathrm{CCI}}$ | - | $0.2 \mathrm{~V}_{\mathrm{CCI}}$ | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.4 \mathrm{~V}$ to 1.95 V | - | $0.35 \mathrm{~V}_{\mathrm{CCI}}$ | - | $0.35 \mathrm{~V}_{\mathrm{CCI}}$ | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=2.3 \mathrm{~V}$ to 2.7 V | - | 0.7 | - | 0.7 | V |
|  |  | $\mathrm{V}_{\text {CCI }}=3.0 \mathrm{~V}$ to 3.6 V | - | 0.8 | - | 0.8 | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=4.5 \mathrm{~V}$ to 5.5 V | - | $0.3 \mathrm{~V}_{\mathrm{CCI}}$ | - | 0.3 V CCl | V |
|  |  | DIR input |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ | - | $0.2 \mathrm{~V}_{\text {CC(A) }}$ | - | $0.2 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.4 \mathrm{~V}$ to 1.95 V | - | $0.35 \mathrm{~V}_{\text {CC(A) }}$ | - | $0.35 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=2.3 \mathrm{~V}$ to 2.7 V | - | 0.7 | - | 0.7 | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=3.0 \mathrm{~V}$ to 3.6 V | - | 0.8 | - | 0.8 | V |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=4.5 \mathrm{~V}$ to 5.5 V | - | $0.3 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | - | $0.3 \mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | V |
| $\mathrm{V}_{\mathrm{OH}}$ | HIGH-level output voltage | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{IH}}$ |  |  |  |  |  |
|  |  | $\mathrm{I}_{\mathrm{O}}=-100 \mu \mathrm{~A} ; \mathrm{V}_{\mathrm{CCO}}=1.2 \mathrm{~V}$ to 4.5 V | $\mathrm{V}_{\mathrm{CcO}}-0.1$ | - | $\mathrm{V}_{\mathrm{CCO}}-0.1$ | - | V |
|  |  | $\mathrm{I}_{\mathrm{O}}=-6 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=1.4 \mathrm{~V}$ | 1.0 | - | 1.0 | - | V |
|  |  | $\mathrm{I}_{\mathrm{O}}=-8 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=1.65 \mathrm{~V}$ | 1.2 | - | 1.2 | - | V |
|  |  | $\mathrm{I}_{\mathrm{O}}=-12 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=2.3 \mathrm{~V}$ | 1.9 | - | 1.9 | - | V |
|  |  | $\mathrm{l}_{\mathrm{O}}=-24 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=3.0 \mathrm{~V}$ | 2.4 | - | 2.4 | - | V |
|  |  | $\mathrm{I}_{\mathrm{O}}=-32 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=4.5 \mathrm{~V}$ | 3.8 | - | 3.8 | - | V |
| $\mathrm{V}_{\text {OL }}$ | LOW-level output voltage | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\text {IL }}$ |  |  |  |  |  |
|  |  | $\mathrm{I}_{\mathrm{O}}=100 \mu \mathrm{~A} ; \mathrm{V}_{\mathrm{CCO}}=1.2 \mathrm{~V}$ to 4.5 V | - | 0.1 | - | 0.1 | V |
|  |  | $\mathrm{I}_{\mathrm{O}}=6 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=1.4 \mathrm{~V}$ | - | 0.3 | - | 0.3 | V |
|  |  | $\mathrm{l}_{\mathrm{O}}=8 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=1.65 \mathrm{~V}$ | - | 0.45 | - | 0.45 | V |
|  |  | $\mathrm{I}_{\mathrm{O}}=12 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=2.3 \mathrm{~V}$ | - | 0.3 | - | 0.3 | V |
|  |  | $\mathrm{l}_{\mathrm{O}}=24 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=3.0 \mathrm{~V}$ | - | 0.55 | - | 0.55 | V |
|  |  | $\mathrm{I}_{\mathrm{O}}=32 \mathrm{~mA} ; \mathrm{V}_{\mathrm{CCO}}=4.5 \mathrm{~V}$ | - | 0.55 | - | 0.55 | V |
| 1 | input leakage current | DIR input; $\mathrm{V}_{\mathrm{I}}=0 \mathrm{~V}$ to 5.5 V ; $\mathrm{V}_{\mathrm{CCI}}=1.2 \mathrm{~V}$ to 5.5 V | - | $\pm 2$ | - | $\pm 10$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {BHL }}$ | bus hold LOW current | A or B port |  |  |  |  |  |
|  |  | $\mathrm{V}_{1}=0.49 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=1.4 \mathrm{~V}$ | 15 | - | 10 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{I}}=0.58 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=1.65 \mathrm{~V}$ | 25 | - | 20 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{1}=0.70 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=2.3 \mathrm{~V}$ | 45 | - | 45 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{1}=0.80 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=3.0 \mathrm{~V}$ | 100 | - | 80 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{1}=1.35 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=4.5 \mathrm{~V}$ | 100 | - | 100 | - | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {BHH }}$ | bus hold HIGH current | A or B port |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{I}}=0.91 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=1.4 \mathrm{~V}$ | -15 | - | -10 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{I}}=1.07 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=1.65 \mathrm{~V}$ | -25 | - | -20 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{I}}=1.60 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=2.3 \mathrm{~V}$ | -45 | - | -45 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{1}=2.00 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=3.0 \mathrm{~V}$ | -100 | - | -80 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{I}}=3.15 \mathrm{~V} ; \mathrm{V}_{\mathrm{CCI}}=4.5 \mathrm{~V}$ | -100 | - | -100 | - | $\mu \mathrm{A}$ |


| Symbol | Parameter | Conditions | $-40{ }^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Min | Max |  |
| $\mathrm{I}_{\text {BHLO }}$ | bus hold LOW overdrive current | A or B port [3] |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.6 \mathrm{~V}$ | 125 | - | 125 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.95 \mathrm{~V}$ | 200 | - | 200 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=2.7 \mathrm{~V}$ | 300 | - | 300 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=3.6 \mathrm{~V}$ | 500 | - | 500 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=5.5 \mathrm{~V}$ | 900 | - | 900 | - | $\mu \mathrm{A}$ |
| Івнно | bus hold HIGH overdrive current | A or B port [3] |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.6 \mathrm{~V}$ | -125 | - | -125 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=1.95 \mathrm{~V}$ | -200 | - | -200 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=2.7 \mathrm{~V}$ | -300 | - | -300 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=3.6 \mathrm{~V}$ | -500 | - | -500 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CCI}}=5.5 \mathrm{~V}$ | -900 | - | -900 | - | $\mu \mathrm{A}$ |
| loz | OFF-state output current | A or B port; $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{Cco}}$; $\mathrm{V}_{\mathrm{Cco}}=1.2 \mathrm{~V}$ to 5.5 V | - | $\pm 2$ | - | $\pm 10$ | $\mu \mathrm{A}$ |
| loff | power-off leakage current | $\begin{aligned} & \mathrm{A} \text { port; } \mathrm{V}_{\mathrm{I}} \text { or } \mathrm{V}_{\mathrm{O}}=0 \mathrm{~V} \text { to } 5.5 \mathrm{~V} \text {; } \\ & \mathrm{V}_{\mathrm{CC}(\mathrm{~A})}=0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}(\mathrm{~B})}=1.2 \mathrm{~V} \text { to } 5.5 \mathrm{~V} \end{aligned}$ | - | $\pm 2$ | - | $\pm 10$ | $\mu \mathrm{A}$ |
|  |  | B port; $\mathrm{V}_{\mathrm{I}}$ or $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ to 5.5 V ; <br> $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.2 \mathrm{~V}$ to 5.5 V | - | $\pm 2$ | - | $\pm 10$ | $\mu \mathrm{A}$ |
| ICC | supply current | A port; $\mathrm{V}_{\mathrm{I}}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{CCI}} ; \mathrm{I}_{\mathrm{O}}=0 \mathrm{~A}$ |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}, \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$ to 5.5 V | - | 8 | - | 8 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}, \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.65 \mathrm{~V}$ to 5.5 V | - | 3 | - | 3 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=5.5 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=0 \mathrm{~V}$ | - | 2 | - | 2 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=5.5 \mathrm{~V}$ | -2 | - | -2 | - | $\mu \mathrm{A}$ |
|  |  | B port; $\mathrm{V}_{\mathrm{I}}=0 \mathrm{~V}$ or $\mathrm{V}_{\text {CCI }} ; \mathrm{I}_{\mathrm{O}}=0 \mathrm{~A}$ |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}, \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$ to 5.5 V | - | 8 | - | 8 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{C C(A)}, \mathrm{V}_{C C(B)}=1.65 \mathrm{~V}$ to 5.5 V | - | 3 | - | 3 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{C C(B)}=5.5 \mathrm{~V} ; \mathrm{V}_{C C(A)}=0 \mathrm{~V}$ | - | 2 | - | 2 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{C C(B)}=0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=5.5 \mathrm{~V}$ | -2 | - | -2 | - | $\mu \mathrm{A}$ |
|  |  | $\begin{aligned} & \text { A plus B port }\left(I_{\operatorname{CCC}(A)}+I_{\mathrm{CC}(\mathrm{~B})}\right) ; \mathrm{I}_{\mathrm{O}}=0 \mathrm{~A} \text {; } \\ & \mathrm{V}_{\mathrm{I}}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{CCI}} \end{aligned}$ |  |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}, \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$ to 5.5 V | - | 16 | - | 16 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}, \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.65 \mathrm{~V}$ to 5.5 V | - | 4 | - | 4 | $\mu \mathrm{A}$ |
| $\Delta I_{\text {cc }}$ | additional supply current | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}, \mathrm{V}_{\mathrm{CC}(\mathrm{B})}=3.0 \mathrm{~V}$ to 5.5 V |  |  |  |  |  |
|  |  | A port; A port at $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}-0.6 \mathrm{~V}$; DIR at $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$; B port = open | - | 50 | - | 75 | $\mu \mathrm{A}$ |
|  |  | DIR input; DIR at $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ - 0.6 V ; A port at $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ or GND ; $B$ port $=$ open | - | 50 | - | 75 | $\mu \mathrm{A}$ |
|  |  | B port; B port at $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}-0.6 \mathrm{~V}$; <br> DIR at GND; A port $=$ open | - | 50 | - | 75 | $\mu \mathrm{A}$ |

[1] $\mathrm{V}_{\mathrm{CCI}}$ is the supply voltage associated with the data input port.
[2] $\mathrm{V}_{\mathrm{cco}}$ is the supply voltage associated with the output port.
[3] To guarantee the node switches, an external driver must source/sink at least $\mathrm{I}_{\mathrm{BHLO}} / \mathrm{I}_{\mathrm{BH}}$. when the input is in the range $\mathrm{V}_{\mathrm{IL}}$ to $\mathrm{V}_{\mathrm{IH}}$.
[4] For non bus hold parts only (74LVC1T45-Q100).

## 11. Dynamic characteristics

Table 9. Typical dynamic characteristics at $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.2 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$
Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6

| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\mathrm{CC} \text { (B) }}$ |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | 5.0 V |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | A to B |  | 10.6 | 8.1 | 7.0 | 5.8 | 5.3 | 5.1 | ns |
|  |  | $B$ to $A$ |  | 10.6 | 9.5 | 9.0 | 8.5 | 8.3 | 8.2 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | A to B |  | 10.1 | 7.1 | 6.0 | 5.3 | 5.2 | 5.4 | ns |
|  |  | B to A |  | 10.1 | 8.6 | 8.1 | 7.8 | 7.6 | 7.6 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to A |  | 9.4 | 9.4 | 9.4 | 9.4 | 9.4 | 9.4 | ns |
|  |  | DIR to $B$ |  | 12.0 | 9.4 | 9.0 | 7.8 | 8.4 | 7.9 | ns |
| $\mathrm{t}_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to A |  | 7.1 | 7.1 | 7.1 | 7.1 | 7.1 | 7.1 | ns |
|  |  | DIR to B |  | 9.5 | 7.8 | 7.7 | 6.9 | 7.6 | 7.0 | ns |
| $t_{\text {PzH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | 20.1 | 17.3 | 16.7 | 15.4 | 15.9 | 15.2 | ns |
|  |  | DIR to $B$ | [1] | 17.7 | 15.2 | 14.1 | 12.9 | 12.4 | 12.2 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | 22.1 | 18.0 | 17.1 | 15.6 | 16.0 | 15.5 | ns |
|  |  | DIR to B | [1] | 19.5 | 16.5 | 15.4 | 14.7 | 14.6 | 14.8 | ns |

[1] $t_{\text {Pzh }}$ and $t_{\text {PzL }}$ are calculated values using the formula shown in Section 13.4
Table 10. Typical dynamic characteristics at $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$ and $\mathrm{T}_{\text {amb }}=25^{\circ} \mathrm{C}$
Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.

| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | 5.0 V |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | A to B |  | 10.6 | 9.5 | 9.0 | 8.5 | 8.3 | 8.2 | ns |
|  |  | $B$ to $A$ |  | 10.6 | 8.1 | 7.0 | 5.8 | 5.3 | 5.1 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 10.1 | 8.6 | 8.1 | 7.8 | 7.6 | 7.6 | ns |
|  |  | $B$ to $A$ |  | 10.1 | 7.1 | 6.0 | 5.3 | 5.2 | 5.4 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to A |  | 9.4 | 6.5 | 5.7 | 4.1 | 4.1 | 3.0 | ns |
|  |  | DIR to B |  | 12.0 | 6.1 | 5.4 | 4.6 | 4.3 | 4.0 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 7.1 | 4.9 | 4.5 | 3.2 | 3.4 | 2.5 | ns |
|  |  | DIR to B |  | 9.5 | 7.3 | 6.6 | 5.9 | 5.7 | 5.6 | ns |
| $\mathrm{t}_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | 20.1 | 15.4 | 13.6 | 11.7 | 11.0 | 10.7 | ns |
|  |  | DIR to $B$ | [1] | 17.7 | 14.4 | 13.5 | 11.7 | 11.7 | 10.7 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | 22.1 | 13.2 | 11.4 | 9.9 | 9.5 | 9.4 | ns |
|  |  | DIR to B | [1] | 19.5 | 15.1 | 13.8 | 11.9 | 11.7 | 10.6 | ns |

[1] $\quad t_{\text {PzH }}$ and $t_{\text {pzL }}$ are calculated values using the formula shown in Section 13.4

Table 11. Typical power dissipation capacitance at $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$ and $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$
Voltages are referenced to GND (ground = 0 V). [1] [2]

| Symbol | Parameter | Conditions | $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ and $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$ |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 1.8 V | 2.5 V | 3.3 V | 5.5 V |  |
| $\mathrm{C}_{\text {PD }}$ | power dissipation capacitance | A port: (direction A to B); <br> B port: (direction $B$ to $A$ ) | 2 | 3 | 3 | 4 | pF |
|  |  | A port: (direction B to A); B port: (direction A to B) | 15 | 16 | 16 | 18 | pF |

[1] $C_{P D}$ is used to determine the dynamic power dissipation ( $P_{D}$ in $\mu \mathrm{W}$ ).
$P_{D}=C_{P D} \times V_{C C}{ }^{2} \times f_{i} \times N+\Sigma\left(C_{L} \times V_{C C}{ }^{2} \times f_{0}\right)$ where:
$\mathrm{f}_{\mathrm{i}}=$ input frequency in MHz ;
$\mathrm{f}_{\mathrm{o}}=$ output frequency in MHz;
$\mathrm{C}_{\mathrm{L}}=$ load capacitance in pF ;
$\mathrm{V}_{\mathrm{CC}}=$ supply voltage in V ;
$\mathrm{N}=$ number of inputs switching;
$\Sigma\left(C_{L} \times V_{C C}{ }^{2} \times f_{0}\right)=$ sum of the outputs.
[2] $f_{i}=10 \mathrm{MHz} ; \mathrm{V}_{\mathrm{I}}=G N D$ to $\mathrm{V}_{\mathrm{Cc}} ; \mathrm{t}_{\mathrm{r}}=\mathrm{t}_{\mathrm{f}}=1 \mathrm{~ns} ; \mathrm{C}_{\mathrm{L}}=0 \mathrm{pF} ; \mathrm{R}_{\mathrm{L}}=\infty \Omega$.
Table 12. Dynamic characteristics for temperature range $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for wave forms see Fig. 5 and Fig. 6

| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}$ |  |  |  |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\begin{gathered} 1.5 \mathrm{~V} \\ \pm 0.1 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 1.8 \mathrm{~V} \\ \pm 0.15 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 2.5 \mathrm{~V} \\ \pm 0.2 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 3.3 \mathrm{~V} \\ \pm 0.3 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 5.0 \mathrm{~V} \\ \pm 0.5 \mathrm{~V} \end{gathered}$ |  |  |
|  |  |  |  | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.4 \mathrm{~V}$ to 1.6 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | $A$ to $B$ |  | 2.8 | 21.3 | 2.4 | 17.6 | 2.0 | 13.5 | 1.7 | 11.8 | 1.6 | 10.5 | ns |
|  |  | $B$ to $A$ |  | 2.8 | 21.3 | 2.6 | 19.1 | 2.3 | 14.9 | 2.3 | 12.4 | 2.2 | 12.0 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.6 | 19.3 | 2.2 | 15.3 | 1.8 | 11.8 | 1.7 | 10.9 | 1.7 | 10.8 | ns |
|  |  | $B$ to $A$ |  | 2.6 | 19.3 | 2.4 | 17.3 | 2.3 | 13.2 | 2.2 | 11.3 | 2.3 | 11.0 | ns |
| $\mathrm{t}_{\mathrm{PHZ}}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 3.0 | 18.7 | 3.0 | 18.7 | 3.0 | 18.7 | 3.0 | 18.7 | 3.0 | 18.7 | ns |
|  |  | DIR to B |  | 3.5 | 24.8 | 3.5 | 23.6 | 3.0 | 11.0 | 3.3 | 11.3 | 2.8 | 10.3 | ns |
| $\mathrm{t}_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 2.4 | 11.4 | 2.4 | 11.4 | 2.4 | 11.4 | 2.4 | 11.4 | 2.4 | 11.4 | ns |
|  |  | DIR to B |  | 2.8 | 18.3 | 3.0 | 17.2 | 2.5 | 9.4 | 3.0 | 10.1 | 2.5 | 9.4 | ns |
| $t_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to $A$ | [1] | - | 39.6 | - | 36.3 | - | 24.3 | - | 22.5 | - | 21.4 | ns |
|  |  | DIR to B | [1] | - | 32.7 | - | 29.0 | - | 24.9 | - | 23.2 | - | 21.9 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 44.1 | - | 40.9 | - | 24.2 | - | 22.6 | - | 21.3 | ns |
|  |  | DIR to B | [1] | - | 38.0 | - | 34.0 | - | 30.5 | - | 29.6 | - | 29.5 | ns |

Dual supply translating transceiver; 3-state

| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\mathrm{CC} \text { (B) }}$ |  |  |  |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\begin{gathered} 1.5 \mathrm{~V} \\ \pm 0.1 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 1.8 \mathrm{~V} \\ \pm 0.15 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 2.5 \mathrm{~V} \\ \pm 0.2 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 3.3 \mathrm{~V} \\ \pm 0.3 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 5.0 \mathrm{~V} \\ \pm 0.5 \mathrm{~V} \end{gathered}$ |  |  |
|  |  |  |  | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.65 \mathrm{~V}$ to 1.95 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | $A$ to $B$ |  | 2.6 | 19.1 | 2.2 | 17.7 | 2.2 | 9.3 | 1.7 | 7.2 | 1.4 | 6.8 | ns |
|  |  | $B$ to $A$ |  | 2.4 | 17.6 | 2.2 | 17.7 | 2.3 | 16.0 | 2.1 | 15.5 | 1.9 | 15.1 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.4 | 17.3 | 2.0 | 14.3 | 1.6 | 8.5 | 1.8 | 7.1 | 1.7 | 7.0 | ns |
|  |  | $B$ to $A$ |  | 2.2 | 15.3 | 2.0 | 14.3 | 2.1 | 12.9 | 2.0 | 12.6 | 1.8 | 12.2 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 2.9 | 17.1 | 2.9 | 17.1 | 2.9 | 17.1 | 2.9 | 17.1 | 2.9 | 17.1 | ns |
|  |  | DIR to B |  | 3.2 | 24.1 | 3.2 | 21.9 | 2.7 | 11.5 | 3.0 | 10.3 | 2.5 | 8.2 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 2.4 | 10.5 | 2.4 | 10.5 | 2.4 | 10.5 | 2.4 | 10.5 | 2.4 | 10.5 | ns |
|  |  | DIR to $B$ |  | 2.5 | 17.6 | 2.6 | 16.0 | 2.2 | 9.2 | 2.7 | 8.4 | 2.4 | 6.4 | ns |
| $\mathrm{t}_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | - | 35.2 | - | 33.7 | - | 25.2 | - | 23.9 | - | 21.8 | ns |
|  |  | DIR to B | [1] | - | 29.6 | - | 28.2 | - | 19.8 | - | 17.7 | - | 17.3 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 39.4 | - | 36.2 | - | 24.4 | - | 22.9 | - | 20.4 | ns |
|  |  | DIR to B | [1] | - | 34.4 | - | 31.4 | - | 25.6 | - | 24.2 | - | 24.1 | ns |
| $\mathbf{V}_{\mathbf{C C}(\mathrm{A})}=\mathbf{2 . 3} \mathbf{~ V}$ to $\mathbf{2 . 7 ~ V}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | A to B |  | 2.3 | 17.9 | 2.3 | 16.0 | 1.5 | 8.5 | 1.3 | 6.2 | 1.1 | 4.8 | ns |
|  |  | $B$ to $A$ |  | 2.0 | 13.5 | 2.2 | 9.3 | 1.5 | 8.5 | 1.4 | 8.0 | 1.0 | 7.5 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.3 | 15.8 | 2.1 | 12.9 | 1.4 | 7.5 | 1.3 | 5.4 | 0.9 | 4.6 | ns |
|  |  | $B$ to $A$ |  | 1.8 | 11.8 | 1.9 | 8.5 | 1.4 | 7.5 | 1.3 | 7.0 | 0.9 | 6.2 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to A |  | 2.1 | 8.1 | 2.1 | 8.1 | 2.1 | 8.1 | 2.1 | 8.1 | 2.1 | 8.1 | ns |
|  |  | DIR to B |  | 3.0 | 22.5 | 3.0 | 21.4 | 2.5 | 11.0 | 2.8 | 9.3 | 2.3 | 6.9 | ns |
| $\mathrm{t}_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 1.7 | 5.8 | 1.7 | 5.8 | 1.7 | 5.8 | 1.7 | 5.8 | 1.7 | 5.8 | ns |
|  |  | DIR to B |  | 2.3 | 14.6 | 2.5 | 13.2 | 2.0 | 9.0 | 2.5 | 8.4 | 1.8 | 5.3 | ns |
| $t_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to $A$ | [1] | - | 28.1 | - | 22.5 | - | 17.5 | - | 16.4 | - | 12.8 | ns |
|  |  | DIR to B | [1] | - | 23.7 | - | 21.8 | - | 14.3 | - | 12.0 | - | 10.6 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 34.3 | - | 29.9 | - | 18.5 | - | 16.3 | - | 13.1 | ns |
|  |  | DIR to B | [1] | - | 23.9 | - | 21.0 | - | 15.6 | - | 13.5 | - | 12.7 | ns |
| $\mathbf{V}_{\mathbf{C C}(\mathrm{A})}=3.0 \mathrm{~V}$ to 3.6 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | A to B |  | 2.3 | 17.1 | 2.1 | 15.5 | 1.4 | 8.0 | 0.8 | 5.6 | 0.7 | 4.4 | ns |
|  |  | $B$ to $A$ |  | 1.7 | 11.8 | 1.7 | 7.2 | 1.3 | 6.2 | 0.7 | 5.6 | 0.6 | 5.4 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.2 | 15.6 | 2.0 | 12.6 | 1.3 | 7.0 | 0.8 | 5.0 | 0.7 | 4.0 | ns |
|  |  | $B$ to $A$ |  | 1.7 | 10.9 | 1.8 | 7.1 | 1.3 | 5.4 | 0.8 | 5.0 | 0.7 | 4.5 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 2.3 | 7.3 | 2.3 | 7.3 | 2.3 | 7.3 | 2.3 | 7.3 | 2.7 | 7.3 | ns |
|  |  | DIR to B |  | 2.9 | 18.0 | 2.9 | 16.5 | 2.3 | 10.1 | 2.7 | 8.6 | 2.2 | 6.3 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 2.0 | 5.6 | 2.0 | 5.6 | 2.0 | 5.6 | 2.0 | 5.6 | 2.0 | 5.6 | ns |
|  |  | DIR to B |  | 2.3 | 13.6 | 2.4 | 12.5 | 1.9 | 7.8 | 2.3 | 7.1 | 1.7 | 4.9 | ns |
| $\mathrm{t}_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | - | 25.4 | - | 19.7 | - | 14.0 | - | 12.7 | - | 10.3 | ns |
|  |  | DIR to B | [1] | - | 22.7 | - | 21.1 | - | 13.6 | - | 11.2 | - | 10.0 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 28.9 | - | 23.6 | - | 15.5 | - | 13.6 | - | 10.8 | ns |
|  |  | DIR to B | [1] | - | 22.9 | - | 19.9 | - | 14.3 | - | 12.3 | - | 11.3 | ns |


| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\mathrm{CC} \text { (B) }}$ |  |  |  |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\begin{gathered} 1.5 \mathrm{~V} \\ \pm 0.1 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 1.8 \mathrm{~V} \\ \pm 0.15 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 2.5 \mathrm{~V} \\ \pm 0.2 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 3.3 \mathrm{~V} \\ \pm 0.3 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 5.0 \mathrm{~V} \\ \pm 0.5 \mathrm{~V} \end{gathered}$ |  |  |
|  |  |  |  | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{V}_{\mathbf{C C}(\mathrm{A})}=4.5 \mathrm{~V}$ to 5.5 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | $A$ to $B$ |  | 2.2 | 16.6 | 1.9 | 15.1 | 1.0 | 7.5 | 0.7 | 5.4 | 0.5 | 3.9 | ns |
|  |  | $B$ to $A$ |  | 1.6 | 10.5 | 1.4 | 6.8 | 1.0 | 4.8 | 0.7 | 4.4 | 0.5 | 3.9 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.3 | 15.3 | 1.8 | 12.2 | 1.0 | 6.2 | 0.7 | 4.5 | 0.5 | 3.5 | ns |
|  |  | $B$ to $A$ |  | 1.7 | 10.8 | 1.7 | 7.0 | 0.9 | 4.6 | 0.7 | 4.0 | 0.5 | 3.5 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 1.7 | 5.4 | 1.7 | 5.4 | 1.7 | 5.4 | 1.7 | 5.4 | 1.7 | 5.4 | ns |
|  |  | DIR to B |  | 2.9 | 17.3 | 2.9 | 16.1 | 2.3 | 9.7 | 2.7 | 8.0 | 2.5 | 5.7 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 1.4 | 3.7 | 1.4 | 3.7 | 1.3 | 3.7 | 1.0 | 3.7 | 0.9 | 3.7 | ns |
|  |  | DIR to B |  | 2.3 | 13.1 | 2.4 | 12.1 | 1.9 | 7.4 | 2.3 | 7.0 | 1.8 | 4.5 | ns |
| $\mathrm{t}_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | - | 23.6 | - | 18.9 | - | 12.2 | - | 11.4 | - | 8.4 | ns |
|  |  | DIR to B | [1] | - | 20.3 | - | 18.8 | - | 11.2 | - | 9.1 | - | 7.6 | ns |
| $t_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 28.1 | - | 23.1 | - | 14.3 | - | 12.0 | - | 9.2 | ns |
|  |  | DIR to B | [1] | - | 20.7 | - | 17.6 | - | 11.6 | - | 9.9 | - | 8.9 | ns |

[1] $t_{\text {PZH }}$ and $t_{\text {PZL }}$ are calculated values using the formula shown in Section 13.4
Table 13. Dynamic characteristics for temperature range $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
Voltages are referenced to GND (ground $=0$ V); for test circuit see Fig. 7; for wave forms see Fig. 5 and Fig. 6

| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\text {cC(B) }}$ |  |  |  |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\begin{gathered} 1.5 \mathrm{~V} \\ \pm 0.1 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 1.8 \mathrm{~V} \\ \pm 0.15 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 2.5 \mathrm{~V} \\ \pm 0.2 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 3.3 \mathrm{~V} \\ \pm 0.3 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 5.0 \mathrm{~V} \\ \pm 0.5 \mathrm{~V} \end{gathered}$ |  |  |
|  |  |  |  | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.4 \mathrm{~V}$ to 1.6 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | A to B |  | 2.5 | 23.5 | 2.1 | 19.4 | 1.8 | 14.9 | 1.5 | 13.0 | 1.4 | 11.6 | ns |
|  |  | $B$ to $A$ |  | 2.5 | 23.5 | 2.3 | 21.1 | 2.0 | 16.4 | 2.0 | 13.7 | 1.9 | 13.2 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.3 | 21.3 | 1.9 | 16.9 | 1.6 | 13.0 | 1.5 | 12.0 | 1.5 | 11.9 | ns |
|  |  | $B$ to $A$ |  | 2.3 | 21.3 | 2.1 | 19.1 | 2.0 | 14.6 | 1.9 | 12.5 | 2.0 | 12.1 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 2.7 | 20.6 | 2.7 | 20.6 | 2.7 | 20.6 | 2.7 | 20.6 | 2.7 | 20.6 | ns |
|  |  | DIR to B |  | 3.1 | 27.3 | 3.1 | 26.0 | 2.7 | 12.1 | 2.9 | 12.5 | 2.5 | 11.4 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to A |  | 2.1 | 12.6 | 2.1 | 12.6 | 2.1 | 12.6 | 2.1 | 12.6 | 2.1 | 12.6 | ns |
|  |  | DIR to B |  | 2.5 | 20.2 | 2.7 | 19.0 | 2.2 | 10.4 | 2.7 | 11.2 | 2.2 | 10.4 | ns |
| $\mathrm{t}_{\text {PzH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | - | 43.7 | - | 40.1 | - | 26.8 | - | 24.9 | - | 23.6 | ns |
|  |  | DIR to B | [1] | - | 36.1 | - | 32.0 | - | 27.5 | - | 25.6 | - | 24.2 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 48.6 | - | 45.1 | - | 26.7 | - | 25.0 | - | 23.5 | ns |
|  |  | DIR to B | [1] | - | 41.9 | - | 37.5 | - | 33.6 | - | 32.6 | - | 32.5 | ns |

Dual supply translating transceiver; 3-state

| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\mathrm{CC} \text { (B) }}$ |  |  |  |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\begin{gathered} 1.5 \mathrm{~V} \\ \pm 0.1 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 1.8 \mathrm{~V} \\ \pm 0.15 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 2.5 \mathrm{~V} \\ \pm 0.2 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 3.3 \mathrm{~V} \\ \pm 0.3 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 5.0 \mathrm{~V} \\ \pm 0.5 \mathrm{~V} \end{gathered}$ |  |  |
|  |  |  |  | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.65 \mathrm{~V}$ to 1.95 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | $A$ to $B$ |  | 2.3 | 21.1 | 1.9 | 19.5 | 1.9 | 10.3 | 1.5 | 8.0 | 1.2 | 7.5 | ns |
|  |  | $B$ to $A$ |  | 2.1 | 19.4 | 1.9 | 19.5 | 2.0 | 17.6 | 1.8 | 17.1 | 1.7 | 16.7 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.1 | 19.1 | 1.8 | 15.8 | 1.4 | 9.4 | 1.6 | 7.9 | 1.5 | 7.7 | ns |
|  |  | $B$ to $A$ |  | 1.9 | 16.9 | 1.8 | 15.8 | 1.8 | 14.2 | 1.8 | 13.9 | 1.6 | 13.5 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 2.6 | 18.9 | 2.6 | 18.9 | 2.6 | 18.9 | 2.6 | 18.9 | 2.6 | 18.9 | ns |
|  |  | DIR to B |  | 2.8 | 26.6 | 2.8 | 24.1 | 2.4 | 12.7 | 2.7 | 11.4 | 2.2 | 9.1 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 2.1 | 11.6 | 2.1 | 11.6 | 2.1 | 11.6 | 2.1 | 11.6 | 2.1 | 11.6 | ns |
|  |  | DIR to $B$ |  | 2.2 | 19.4 | 2.3 | 17.6 | 1.9 | 10.2 | 2.4 | 9.3 | 2.1 | 7.4 | ns |
| $\mathrm{t}_{\text {PzH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | - | 38.8 | - | 37.1 | - | 27.8 | - | 26.4 | - | 24.1 | ns |
|  |  | DIR to B | [1] | - | 32.7 | - | 31.1 | - | 21.9 | - | 19.6 | - | 19.1 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 43.5 | - | 39.9 | - | 26.9 | - | 25.3 | - | 22.6 | ns |
|  |  | DIR to B | [1] | - | 38.0 | - | 34.7 | - | 28.3 | - | 26.8 | - | 26.6 | ns |
| $\mathbf{V}_{\mathbf{C C}(\mathrm{A})}=2.3 \mathrm{~V}$ to 2.7 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | A to B |  | 2.0 | 19.7 | 2.0 | 17.6 | 1.3 | 9.4 | 1.1 | 6.9 | 0.9 | 5.3 | ns |
|  |  | $B$ to $A$ |  | 1.8 | 14.9 | 1.9 | 10.3 | 1.3 | 9.4 | 1.2 | 8.8 | 0.9 | 8.3 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.0 | 17.4 | 1.8 | 14.2 | 1.2 | 8.3 | 1.1 | 6.0 | 0.8 | 5.1 | ns |
|  |  | $B$ to $A$ |  | 1.6 | 13.0 | 1.7 | 9.4 | 1.2 | 8.3 | 1.1 | 7.7 | 0.8 | 6.9 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to A |  | 1.8 | 9.0 | 1.8 | 9.0 | 1.8 | 9.0 | 1.8 | 9.0 | 1.8 | 9.0 | ns |
|  |  | DIR to B |  | 2.7 | 24.8 | 2.7 | 23.6 | 2.2 | 12.1 | 2.5 | 10.3 | 2.0 | 7.6 | ns |
| $\mathrm{t}_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to $A$ |  | 1.5 | 6.4 | 1.5 | 6.4 | 1.5 | 6.4 | 1.5 | 6.4 | 1.5 | 6.4 | ns |
|  |  | DIR to B |  | 2.0 | 16.1 | 2.2 | 14.6 | 1.8 | 9.9 | 2.2 | 9.3 | 1.6 | 5.9 | ns |
| $t_{\text {PzH }}$ | OFF-state to HIGH propagation delay | DIR to $A$ | [1] | - | 31.0 | - | 24.9 | - | 19.3 | - | 18.1 | - | 14.2 | ns |
|  |  | DIR to B | [1] | - | 26.1 | - | 24.0 | - | 15.8 | - | 13.3 | - | 11.7 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 37.8 | - | 33.0 | - | 20.4 | - | 18.0 | - | 14.5 | ns |
|  |  | DIR to B | [1] | - | 26.4 | - | 23.2 | - | 17.3 | - | 15.0 | - | 14.1 | ns |
| $\mathbf{V}_{\mathbf{C C}(\mathrm{A})}=3.0 \mathrm{~V}$ to 3.6 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | A to B |  | 2.0 | 18.9 | 1.8 | 17.1 | 1.2 | 8.8 | 0.7 | 6.2 | 0.6 | 4.9 | ns |
|  |  | $B$ to $A$ |  | 1.5 | 13.0 | 1.5 | 8.0 | 1.1 | 6.9 | 0.6 | 6.2 | 0.5 | 6.0 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 1.9 | 17.2 | 1.8 | 13.9 | 1.1 | 7.7 | 0.7 | 5.5 | 0.6 | 4.4 | ns |
|  |  | $B$ to $A$ |  | 1.5 | 12.0 | 1.6 | 7.9 | 1.1 | 6.0 | 0.7 | 5.5 | 0.6 | 5.0 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 2.0 | 8.1 | 2.0 | 8.1 | 2.0 | 8.1 | 2.0 | 8.1 | 2.4 | 8.1 | ns |
|  |  | DIR to B |  | 2.6 | 19.8 | 2.6 | 18.2 | 2.0 | 11.2 | 2.4 | 9.5 | 1.9 | 7.0 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to A |  | 1.8 | 6.2 | 1.8 | 6.2 | 1.8 | 6.2 | 1.8 | 6.2 | 1.8 | 6.2 | ns |
|  |  | DIR to B |  | 2.0 | 15.0 | 2.1 | 13.8 | 1.7 | 8.6 | 2.0 | 7.9 | 1.5 | 5.4 | ns |
| $\mathrm{t}_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | - | 28.0 | - | 21.8 | - | 15.5 | - | 14.1 | - | 11.4 | ns |
|  |  | DIR to B | [1] | - | 25.1 | - | 23.3 | - | 15.0 | - | 12.4 | - | 11.1 | ns |
| $\mathrm{t}_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 31.8 | - | 26.1 | - | 17.2 | - | 15.0 | - | 12.0 | ns |
|  |  | DIR to B | [1] | - | 25.3 | - | 22.0 | - | 15.8 | - | 13.6 | - | 12.5 | ns |

Dual supply translating transceiver; 3-state

| Symbol | Parameter | Conditions |  | $\mathrm{V}_{\mathrm{CC} \text { ( } \mathrm{B})}$ |  |  |  |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\begin{gathered} 1.5 \mathrm{~V} \\ \pm 0.1 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 1.8 \mathrm{~V} \\ \pm 0.15 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 2.5 \mathrm{~V} \\ \pm 0.2 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 3.3 \mathrm{~V} \\ \pm 0.3 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} 5.0 \mathrm{~V} \\ \pm 0.5 \mathrm{~V} \end{gathered}$ |  |  |
|  |  |  |  | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}=4.5 \mathrm{~V}$ to 5.5 V |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {PLH }}$ | LOW to HIGH propagation delay | $A$ to $B$ |  | 1.9 | 18.3 | 1.7 | 16.7 | 0.9 | 8.3 | 0.6 | 6.0 | 0.4 | 4.3 | ns |
|  |  | $B$ to $A$ |  | 1.4 | 11.6 | 1.2 | 7.5 | 0.9 | 5.3 | 0.6 | 4.9 | 0.4 | 4.3 | ns |
| $\mathrm{t}_{\text {PHL }}$ | HIGH to LOW propagation delay | $A$ to $B$ |  | 2.0 | 16.9 | 1.6 | 13.5 | 0.9 | 6.9 | 0.6 | 5.0 | 0.4 | 3.9 | ns |
|  |  | $B$ to $A$ |  | 1.5 | 11.9 | 1.5 | 7.7 | 0.8 | 5.1 | 0.6 | 4.4 | 0.4 | 3.9 | ns |
| $\mathrm{t}_{\text {PHZ }}$ | HIGH to OFF-state propagation delay | DIR to $A$ |  | 1.5 | 6.0 | 1.5 | 6.0 | 1.5 | 6.0 | 1.5 | 6.0 | 1.5 | 6.0 | ns |
|  |  | DIR to B |  | 2.6 | 19.1 | 2.6 | 17.8 | 2.0 | 10.7 | 2.4 | 8.8 | 2.2 | 6.3 | ns |
| $t_{\text {PLZ }}$ | LOW to OFF-state propagation delay | DIR to A |  | 1.2 | 4.1 | 1.2 | 4.1 | 1.1 | 4.1 | 0.9 | 4.1 | 0.8 | 4.1 | ns |
|  |  | DIR to B |  | 2.0 | 14.5 | 2.1 | 13.4 | 1.7 | 8.2 | 2.0 | 7.7 | 1.6 | 5.0 | ns |
| $\mathrm{t}_{\text {PZH }}$ | OFF-state to HIGH propagation delay | DIR to A | [1] | - | 26.1 | - | 20.9 | - | 13.5 | - | 12.6 | - | 9.3 | ns |
|  |  | DIR to B | [1] | - | 22.4 | - | 20.8 | - | 12.4 | - | 10.1 | - | 8.4 | ns |
| $t_{\text {PZL }}$ | OFF-state to LOW propagation delay | DIR to A | [1] | - | 31.0 | - | 25.5 | - | 15.8 | - | 13.2 | - | 10.2 | ns |
|  |  | DIR to B | [1] | - | 22.9 | - | 19.5 | - | 12.9 | - | 11.0 | - | 9.9 | ns |

[1] $t_{\text {PZH }}$ and $t_{\text {PZL }}$ are calculated values using the formula shown in Section 13.4

### 11.1. Waveforms and test circuit



Measurement points are given in Table 14.
$\mathrm{V}_{\mathrm{OL}}$ and $\mathrm{V}_{\mathrm{OH}}$ are typical output voltage levels that occur with the output load.
Fig. 5. The data input $(A, B)$ to output $(B, A)$ propagation delay times


Measurement points are given in Table 14.
$\mathrm{V}_{\mathrm{OL}}$ and $\mathrm{V}_{\mathrm{OH}}$ are typical output voltage levels that occur with the output load.
Fig. 6. Enable and disable times
Table 14. Measurement points

| Supply voltage | Input [1] | Output [2] |  |  |
| :--- | :--- | :--- | :--- | :--- |
| $\mathbf{V}_{\mathbf{C C}(\mathbf{A})}, \mathbf{V}_{\mathbf{C C}(\mathrm{B})}$ | $\mathbf{V}_{\mathbf{M}}$ | $\mathbf{V}_{\mathbf{M}}$ | $\mathbf{V}_{\mathbf{X}}$ | $\mathbf{V}_{\mathbf{Y}}$ |
| 1.2 V to 1.6 V | $0.5 \mathrm{~V}_{\mathrm{CCI}}$ | $0.5 \mathrm{~V}_{\mathrm{CCO}}$ | $\mathrm{V}_{\mathrm{OL}}+0.1 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{OH}}-0.1 \mathrm{~V}$ |
| 1.65 V to 2.7 V | $0.5 \mathrm{~V}_{\mathrm{CCI}}$ | $0.5 \mathrm{~V}_{\mathrm{CCO}}$ | $\mathrm{V}_{\mathrm{OL}}+0.15 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{OH}}-0.15 \mathrm{~V}$ |
| 3.0 V to 5.5 V | $0.5 \mathrm{~V}_{\mathrm{CCI}}$ | $0.5 \mathrm{~V}_{\mathrm{CCO}}$ | $\mathrm{V}_{\mathrm{OL}}+0.3 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{OH}}-0.3 \mathrm{~V}$ |

[1] $\mathrm{V}_{\mathrm{CCI}}$ is the supply voltage associated with the data input port.
[2] $\mathrm{V}_{\mathrm{CCO}}$ is the supply voltage associated with the output port.


Test data is given in Table 15.
$\mathrm{R}_{\mathrm{L}}=$ Load resistance.
$C_{L}=$ Load capacitance including jig and probe capacitance.
$\mathrm{R}_{\mathrm{T}}=$ Termination resistance.
$\mathrm{V}_{\mathrm{EXT}}=$ External voltage for measuring switching times.
Fig. 7. Test circuit for measuring switching times
Table 15. Test data

| Supply voltage | Input |  | Load |  | $\mathrm{V}_{\text {EXT }}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}, \mathrm{V}_{\mathbf{C C}(\mathrm{B})}$ | $\mathrm{V}_{1}$ [1] | $\Delta t / \Delta \mathrm{V}$ [2] | $\mathrm{C}_{\mathrm{L}}$ | $\mathbf{R}_{\mathrm{L}}$ | $\mathrm{t}_{\text {PLH }}, \mathrm{t}_{\text {PHL }}$ | $\mathrm{t}_{\text {PZH }}, \mathrm{t}_{\text {PHZ }}$ | $\mathrm{t}_{\text {PZL }}, \mathrm{t}_{\text {PLZ }}$ [3] |
| 1.2 V to 5.5 V | $\mathrm{V}_{\mathrm{CCI}}$ | $\leq 1.0 \mathrm{~ns} / \mathrm{V}$ | 15 pF | $2 \mathrm{k} \Omega$ | open | GND | $2 \mathrm{~V}_{\text {cco }}$ |

[1] $\mathrm{V}_{\mathrm{CCI}}$ is the supply voltage associated with the data input port.
[2] $\mathrm{dV} / \mathrm{dt} \geq 1.0 \mathrm{~V} / \mathrm{ns}$
[3] $\mathrm{V}_{\mathrm{CCO}}$ is the supply voltage associated with the output port.

## 12. Typical propagation delay characteristics


a. HIGH to LOW propagation delay (A to B )

c. HIGH to LOW propagation delay ( B to A )
(1) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$.
(2) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.5 \mathrm{~V}$.
(3) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.8 \mathrm{~V}$.
(4) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=2.5 \mathrm{~V}$.
(5) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=3.3 \mathrm{~V}$.
(6) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=5.0 \mathrm{~V}$.

Fig. 8. Typical propagation delay vs load capacitance; $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.2 \mathrm{~V}$

Dual supply translating transceiver; 3-state

a. HIGH to LOW propagation delay (A to B )

c. HIGH to LOW propagation delay ( B to A )

b. LOW to HIGH propagation delay ( A to B )

d. LOW to HIGH propagation delay ( $B$ to $A$ )
(1) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$.
(2) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.5 \mathrm{~V}$.
(3) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.8 \mathrm{~V}$.
(4) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=2.5 \mathrm{~V}$.
(5) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=3.3 \mathrm{~V}$.
(6) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=5.0 \mathrm{~V}$.

Fig. 9. Typical propagation delay vs load capacitance; $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.5 \mathrm{~V}$

Dual supply translating transceiver; 3-state

a. HIGH to LOW propagation delay (A to B )

c. HIGH to LOW propagation delay ( $B$ to $A$ )

b. LOW to HIGH propagation delay (A to B)

d. LOW to HIGH propagation delay ( B to A )
(1) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$.
(2) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.5 \mathrm{~V}$.
(3) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.8 \mathrm{~V}$.
(4) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=2.5 \mathrm{~V}$.
(5) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=3.3 \mathrm{~V}$.
(6) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=5.0 \mathrm{~V}$.

Fig. 10. Typical propagation delay vs load capacitance; $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=1.8 \mathrm{~V}$

Dual supply translating transceiver; 3-state

a. HIGH to LOW propagation delay (A to B )

c. HIGH to LOW propagation delay ( B to A )

b. LOW to HIGH propagation delay ( A to B )

d. LOW to HIGH propagation delay ( B to A )
(1) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$.
(2) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.5 \mathrm{~V}$.
(3) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.8 \mathrm{~V}$.
(4) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=2.5 \mathrm{~V}$.
(5) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=3.3 \mathrm{~V}$.
(6) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=5.0 \mathrm{~V}$.

Fig. 11. Typical propagation delay vs load capacitance; $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=2.5 \mathrm{~V}$

Dual supply translating transceiver; 3-state

a. HIGH to LOW propagation delay (A to B )

c. HIGH to LOW propagation delay ( B to A )

b. LOW to HIGH propagation delay ( A to B )

d. LOW to HIGH propagation delay ( B to A )
(1) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$.
(2) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.5 \mathrm{~V}$.
(3) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.8 \mathrm{~V}$.
(4) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=2.5 \mathrm{~V}$.
(5) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=3.3 \mathrm{~V}$.
(6) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=5.0 \mathrm{~V}$.

Fig. 12. Typical propagation delay vs load capacitance; $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=3.3 \mathrm{~V}$

Dual supply translating transceiver; 3-state

a. HIGH to LOW propagation delay (A to B )

c. HIGH to LOW propagation delay ( B to A )

b. LOW to HIGH propagation delay ( A to B )

d. LOW to HIGH propagation delay ( B to A )
(1) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.2 \mathrm{~V}$.
(2) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.5 \mathrm{~V}$.
(3) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=1.8 \mathrm{~V}$.
(4) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=2.5 \mathrm{~V}$.
(5) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=3.3 \mathrm{~V}$.
(6) $\mathrm{V}_{\mathrm{CC}(\mathrm{B})}=5.0 \mathrm{~V}$.

Fig. 13. Typical propagation delay vs load capacitance; $\mathrm{T}_{\mathrm{amb}}=25^{\circ} \mathrm{C} ; \mathrm{V}_{\mathrm{CC}(\mathrm{A})}=5.0 \mathrm{~V}$

## 13. Application information

### 13.1. Unidirectional logic level-shifting application

The circuit given in Fig. 14 is an example of the 74LVC1T45-Q100; 74LVCH1T45-Q100 being used in a unidirectional logic level-shifting application.


Fig. 14. Unidirectional logic level-shifting application
Table 16. Description unidirectional logic level-shifting application

| Pin | Name | Function | Description |
| :--- | :--- | :--- | :--- |
| 1 | $\mathrm{~V}_{\mathrm{CC}(\mathrm{A})}$ | $\mathrm{V}_{\mathrm{CC} 1}$ | supply voltage of system-1 $(1.2 \mathrm{~V}$ to 5.5 V$)$ |
| 2 | GND | GND | device GND |
| 3 | A | OUT | output level depends on $\mathrm{V}_{\mathrm{CC} 1}$ voltage |
| 4 | B | IN | input threshold value depends on $\mathrm{V}_{\mathrm{CC} 2}$ voltage |
| 5 | DIR | DIR | the GND (LOW level) determines B port to A port direction |
| 6 | $\mathrm{~V}_{\mathrm{CC}(\mathrm{B})}$ | $\mathrm{V}_{\mathrm{CC} 2}$ | supply voltage of system- $2(1.2 \mathrm{~V}$ to 5.5 V$)$ |

### 13.2. Bidirectional logic level-shifting application

Fig. 15 shows the 74LVC1T45-Q100; 74LVCH1T45-Q100 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.


Fig. 15. Bidirectional logic level-shifting application

Table 17 provides a sequence that illustrates data transmission from system-1 to system-2 and then from system-2 to system-1.

Table 17. Description bidirectional logic level-shifting application
H = HIGH voltage level; L = LOW voltage level; Z = high-impedance OFF-state.

| State | DIR CTRL | I/O-1 | I/O-2 | Description |
| :--- | :--- | :--- | :--- | :--- |
| 1 | H | output | input | system-1 data to system-2 |
| 2 | H | Z | Z | system-2 is getting ready to send data to <br> system-1. I/O-1 and I/O-2 are disabled. The <br> bus-line state depends on bus hold. |
| 3 | L | Z | Z | DIR bit is set LOW. I/O-1 and I/O-2 are still <br> disabled. The bus-line state depends on bus <br> hold. |
| 4 | L | input | output | system-2 data to system-1 |

### 13.3. Power-up considerations

The device is designed such that no special power-up sequence is required other than GND being applied first.

Table 18. Typical total supply current ( $\left.\mathrm{I}_{\mathrm{CC}(\mathrm{A})}+\mathrm{I}_{\mathrm{CC}(\mathrm{B})}\right)$

| $\mathrm{V}_{\mathrm{CC}(\mathrm{A})}$ | $\mathrm{V}_{\mathrm{CC} \text { ( } \mathrm{B})}$ |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 V | 1.8 V | 2.5 V | 3.3 V | 5.0 V |  |
| 0 V | 0 | <1 | <1 | <1 | < 1 | $\mu \mathrm{A}$ |
| 1.8 V | < 1 | <2 | <2 | <2 | 2 | $\mu \mathrm{A}$ |
| 2.5 V | < 1 | <2 | <2 | <2 | <2 | $\mu \mathrm{A}$ |
| 3.3 V | <1 | <2 | <2 | <2 | <2 | $\mu \mathrm{A}$ |
| 5.0 V | <1 | 2 | <2 | <2 | <2 | $\mu \mathrm{A}$ |

### 13.4. Enable times

Calculate the enable times for the 74LVC1T45-Q100; 74LVCH1T45-Q100 using the following formulas:

- $t_{\text {PZH }}($ DIR to $A)=t_{\text {PLZ }}($ DIR to $B)+t_{\text {PLH }}(B$ to $A)$
- $t_{\text {PZL }}($ DIR to $A)=t_{\text {PHZ }}($ DIR to $B)+t_{\text {PHL }}(B$ to $A)$
- $t_{\text {PZH }}($ DIR to $B)=t_{\text {PLZ }}($ DIR to $A)+t_{\text {PLH }}(A$ to $B)$
- $t_{\text {PZL }}($ DIR to $B)=t_{\text {PHZ }}$ (DIR to $\left.A\right)+t_{\text {PHL }}$ (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74LVC1T45-Q100; 74LVCH1T45-Q100 initially is transmitting from $A$ to $B$, then the DIR bit is switched, the $B$ port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.

## 14. Package outline



detail X

DIMENSIONS (mm are the original dimensions)

| UNIT | $\mathbf{A}$ | $\mathbf{A}_{\mathbf{1}}$ <br> $\boldsymbol{m a x}$ | $\mathbf{b p}_{\mathbf{p}}$ | $\mathbf{c}$ | $\mathbf{D}$ | $\mathbf{E}$ | $\mathbf{e}$ | $\mathbf{e}_{\mathbf{1}}$ | $\mathbf{H}_{\mathbf{E}}$ | $\mathbf{L}_{\mathbf{p}}$ | $\mathbf{Q}$ | $\mathbf{v}$ | $\mathbf{w}$ | $\mathbf{y}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{m m}$ | 1.1 | 0.1 | 0.30 | 0.25 | 2.2 | 1.35 | 1.3 | 0.65 | 2.2 | 0.45 | 0.25 | 0.2 | 0.2 | 0.1 |
|  | 0.8 | 0.2 | 0.20 | 0.10 | 1.8 | 1.15 | 1.3 | 0.15 | 0.2 | 0.2 | 0.2 |  |  |  |


| OUTLINE <br> VERSION | REFERENCES |  |  | EUROPEAN PROJECTION | ISSUE DATE |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | IEC | JEDEC | JEITA |  |  |
| SOT363 |  |  | SC-88 | $\square$ - | $\begin{aligned} & \hline 04-11-08 \\ & 06-03-16 \end{aligned}$ |

Fig. 16. Package outline SOT363 (SC-88)


Dimensions (mm are the original dimensions)

| Unit |  | $\mathrm{A}^{(1)}$ | $\mathrm{A}_{1}$ | b | D | E | e | $\mathrm{e}_{1}$ | L | $\mathrm{L}_{1}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mm | max | 0.5 | 0.04 | 0.25 | 1.50 | 1.05 | 0.6 | 0.5 | 0.35 | 0.40 |
|  | nom |  |  | 0.20 | 1.45 | 1.00 |  |  | 0.30 | 0.35 |
|  | min |  |  | 0.17 | 1.40 | 0.95 |  |  | 0.27 | 0.32 |

Notes

1. Including plating thickness.
2. Can be visible in some manufacturing processes.
sot886 po

| Outline version | References |  |  |  | European projection | Issue date |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | IEC | JEDEC | JEITA |  |  |  |
| SOT886 | MO-252 |  |  |  | $\bigcirc$ | $\begin{gathered} -04-07-22 \\ 12-01-05 \end{gathered}$ |

Fig. 17. Package outline SOT886 (XSON6)

## 15. Abbreviations

Table 19. Abbreviations

| Acronym | Description |
| :--- | :--- |
| CDM | Charged Device Model |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |

## 16. Revision history

Table 20. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
| :---: | :---: | :---: | :---: | :---: |
| 74LVC_LVCH1T45_Q100 v. 4 | 20201201 | Product data sheet | - | 74LVC_LVCH1T45_Q100 v. 3 |
| Modifications: | - Section 2: ESD specification aligned with Non-Automotive data sheet. <br> - Table 5: Derating values for $\mathrm{P}_{\text {tot }}$ total power dissipation updated. |  |  |  |
| 74LVC_LVCH1T45_Q100 v. 3 | 20190319 | Product data sheet |  | 74LVC_LVCH1T45_Q100 v. 2 |
| Modifications: | - The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia. <br> - Legal texts have been adapted to the new company name where appropriate. <br> - Type number 74LVC1T45GM-Q100 (XSON6/SOT886) added. |  |  |  |
| 74LVC_LVCH1T45_Q100 v. 2 | 20160530 | Product data sheet | - | 74LVC_LVCH1T45_Q100 v. 1 |
| Modifications: | - Table 1: typo corrected in type number |  |  |  |
| 74LVC_LVCH1T45_Q100 v. 1 | 20130328 | Product data sheet | - | - |

## 17. Legal information

## Data sheet status

| Document status <br> [1][2] | Product <br> status [3] | Definition |
| :--- | :--- | :--- |
| Objective [short] <br> data sheet | Development | This document contains data from <br> the objective specification for <br> product development. |
| Preliminary [short] <br> data sheet | Qualification | This document contains data from <br> the preliminary specification. |
| Product [short] <br> data sheet | Production | This document contains the product <br> specification. |

[1] Please consult the most recently issued document before initiating or completing a design.
[2] The term 'short data sheet' is explained in section "Definitions".
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Contents

1. General description ..... 1
2. Features and benefits ..... 1
3. Ordering information ..... 2
4. Marking ..... 2
5. Functional diagram ..... 2
6. Pinning information ..... 3
6.1. Pinning ..... 3
6.2. Pin description ..... 3
7. Functional description. ..... 3
8. Limiting values ..... 4
9. Recommended operating conditions ..... 4
10. Static characteristics .....  5
11. Dynamic characteristics ..... 8
11.1. Waveforms and test circuit. ..... 13
12. Typical propagation delay characteristics ..... 16
13. Application information ..... 22
13.1. Unidirectional logic level-shifting application ..... 22
13.2. Bidirectional logic level-shifting application ..... 22
13.3. Power-up considerations ..... 23
13.4. Enable times ..... 23
14. Package outline ..... 24
15. Abbreviations. ..... 26
16. Revision history ..... 26
17. Legal information ..... 27

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