## **HEF4014B**

8-bit static shift register Rev. 11 — 24 November 2021

**Product data sheet** 

## 1. General description

The HEF4014B is an 8-bit shift register with synchronous parallel enable. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of  $V_{\text{DD}}$ .

## 2. Features and benefits

- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-B exceeds 200 V
- Specified from -40 °C to +85 °C

## 3. Applications

- Parallel-to-serial converter
- Serial data queueing
- · General purpose register

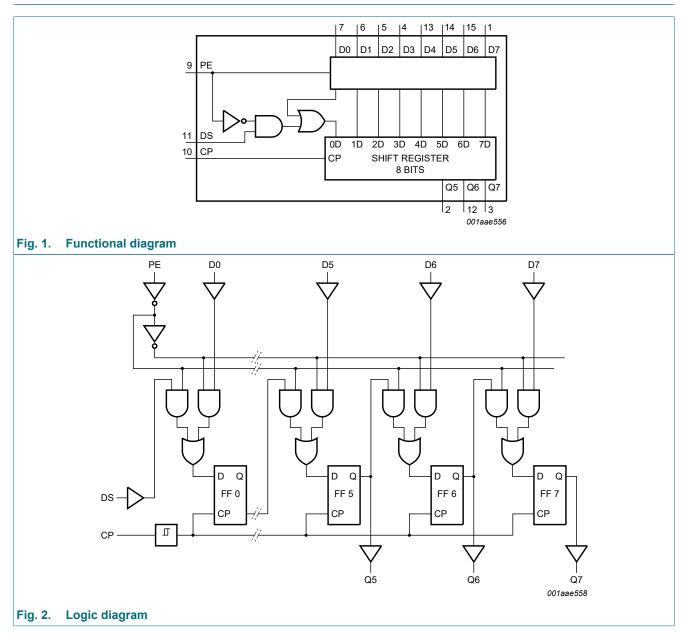
## 4. Ordering information

Table 1. Ordering information							
Type number	Package	Package					
	Temperature range	Name	Description	Version			
HEF4014BT	-40 °C to +85 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1			

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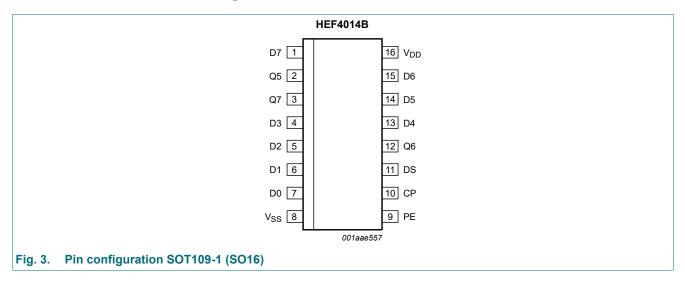
#### 8-bit static shift register

## 5. Functional diagram



## 6. Pinning information

#### 6.1. Pinning



### 6.2. Pin description

#### Table 2. Pin description

Symbol	Pin	Description
Q5 to Q7	2, 12, 3	output
D0 to D7	7, 6, 5, 4, 13, 14, 15, 1	parallel data input
V <sub>SS</sub>	8	ground supply voltage
PE	9	parallel enable input
СР	10	clock input (LOW-to-HIGH edge-triggered)
DS	11	serial data input
V <sub>DD</sub>	16	supply voltage

## 7. Functional description

#### Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; nD = HIGH or LOW;  $\uparrow = LOW$ -to-HIGH clock transition;  $\downarrow = HIGH$ -to-LOW clock transition.

Number of clock	Inputs	Inputs			Outputs			
transitions	СР	DS	PE	Q5	Q6	Q7		
Serial operation	I		<b>I</b>					
1	1	1D	L	X	Х	Х		
2	1	2D	L	X	Х	Х		
3	1	3D	L	X	Х	Х		
6	1	X	L	1D	Х	Х		
7	1	X	L	2D	1D	Х		
8	1	X	L	3D	2D	1D		
	$\downarrow$	X	Х	no change	no change	no change		
Parallel operation					1			
1	1	X	Н	D5	D6	D7		
	↓	X	Х	no change	no change	no change		

## 8. Limiting values

#### Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{I}$ < -0.5 V or $V_{I}$ > $V_{DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{\rm O}$ < -0.5 V or $V_{\rm O}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = -40 °C to +85 °C	-	500	mW
Р	power dissipation	per output	-	100	mW

## 9. Recommended operating conditions

#### Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>DD</sub>	supply voltage		3	-	15	V
VI	input voltage		0	-	V <sub>DD</sub>	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	-	3.75	µs/V
		V <sub>DD</sub> = 10 V	-	-	0.5	µs/V
		V <sub>DD</sub> = 15 V	-	-	0.08	µs/V

## **10. Static characteristics**

#### Table 6. Static characteristics

 $V_{SS} = 0 V$ ;  $V_{I} = V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> =	-40 °C	T <sub>amb</sub> = +25 °C		T <sub>amb</sub> = +85 °C		Unit
				Min	Max	Min	Max	Min	Max	
VIH	HIGH-level input voltage	IGH-level input voltage  Ι <sub>O</sub>   < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level input voltage	I <sub>O</sub>   < 1 μA	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub>   < 1 μΑ	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	LOW-level output voltage	I <sub>O</sub>   < 1 μΑ	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V <sub>O</sub> = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V <sub>O</sub> = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I <sub>OL</sub>	LOW-level output current	V <sub>O</sub> = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		V <sub>O</sub> = 0.5 V	10 V	1.3	-	1.1	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
l <sub>l</sub>	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μA
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	20	-	20	-	150	μA
			10 V	-	40	-	40	-	300	μA
			15 V	-	80	-	80	-	600	μA
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

## **11. Dynamic characteristics**

#### Table 7. Dynamic characteristics

 $T_{amb} = 25 \ ^\circ C; V_{SS} = 0 \ V.$ 

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula [1]	Min	Тур	Max	Unit
t <sub>PHL</sub>	HIGH to LOW	CP to Qn;	5 V	103 ns + (0.55 ns/pF)C <sub>L</sub>	-	130	260	ns
	propagation delay	see <u>Fig. 4</u>	10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t <sub>PLH</sub>	LOW to HIGH	CP to Qn;	5 V	88 ns + (0.55 ns/pF)C <sub>L</sub>	-	115	230	ns
	propagation delay	see <u>Fig. 4</u>	10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t <sub>t</sub>	transition time	Qn output;	5 V [2]	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
		see <u>Fig. 4</u>	10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>W</sub>	pulse width	CP input;	5 V		70	35	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Fig. 5</u>	15 V		24	12	-	ns
t <sub>su</sub>	set-up time	PE to CP;	5 V		40	10	-	ns
		see <u>Fig. 5</u>	10 V		25	5	-	ns
		15 V		15	0	-	ns	
		DS to CP;	5 V		+35	-5	-	ns
		see <u>Fig. 5</u>	10 V		+25	-5	-	ns
			15 V		25	0	-	ns
		Dn to CP;	5 V		+35	-5	-	ns
		see <u>Fig. 5</u>	10 V		+25	-5	-	ns
			15 V		25	0	-	ns
t <sub>h</sub>	hold time	PE to CP;	5 V		+25	-5	-	ns
		see <u>Fig. 5</u>	10 V		20	0	-	ns
			15 V		15	0	-	ns
		DS to CP;	5 V		30	15	-	ns
		see <u>Fig. 5</u>	10 V		20	10	-	ns
			15 V		15	7	-	ns
	Dn to	Dn to CP;	5 V		30	15	-	ns
	see <u>Fig. 5</u>	10 V		20	10	-	ns	
			15 V		15	7	-	ns
f <sub>clk(max)</sub>	maximum clock	see Fig. 5	5 V		6	13	-	MHz
. ,	frequency		10 V		15	30	-	MHz
			15 V		20	40	-	MHz

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown ( $C_L$  in pF). [2]  $t_t$  is the same as  $t_{THL}$  and  $t_{TLH}$ .

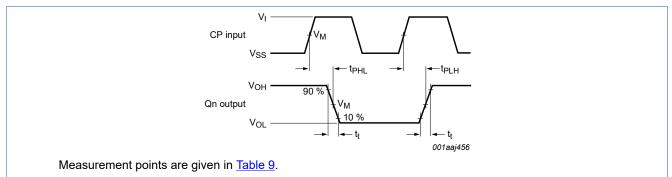
#### 8-bit static shift register

#### Table 8. Dynamic power dissipation P<sub>D</sub>

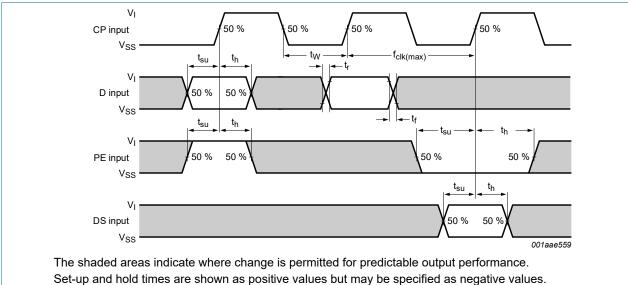
 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0$  V;  $t_r = t_f \le 20$  ns;  $T_{amb} = 25$  °C.

Symbol	Parameter	V <sub>DD</sub>	Typical formula for $P_D$ ( $\mu$ W)	Where:
PD	dynamic power	5 V		f <sub>i</sub> = input frequency in MHz;
	dissipation	10 V		f <sub>o</sub> = output frequency in MHz; C <sub>L</sub> = output load capacitance in pF;
		15 V		$V_{DD}$ = supply voltage in V; $\Sigma(C_L \times f_o)$ = sum of the outputs.

#### 11.1. Waveforms and test circuit







Set-up and hold times are shown as positive values but may be specified a Measurement points are given in <u>Table 9</u>.

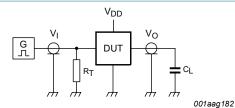
#### Table 9. Measurement points

Supply voltage	Input	Output
V <sub>DD</sub>	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>

Fig. 5. Minimum clock pulse width, and set-up and hold times for PE to CP, DS to CP, and D to CP

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Test data is given in <u>Table 10</u>.

Definitions for test circuit:

 $C_L$  = load capacitance including jig and probe capacitance.

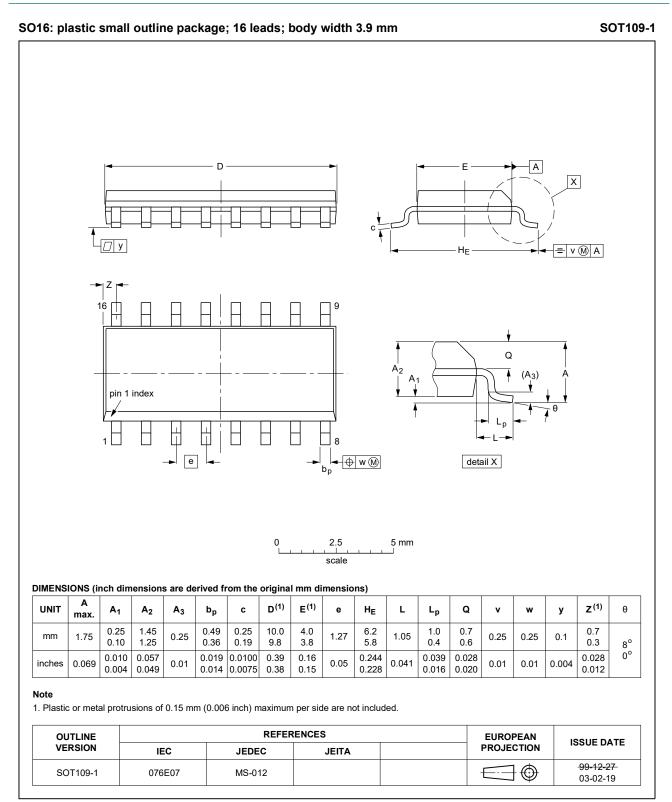
 $R_T$  = termination resistance should be equal to the output impedance  $Z_o$  of the pulse generator.

#### Fig. 6. Test circuit for measuring switching times

#### Table 10. Test data

Supply voltage	Input	Load	
V <sub>DD</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	$V_{SS}$ or $V_{DD}$	≤ 20 ns	50 pF

## 12. Package outline



#### Fig. 7. Package outline SOT109-1 (SO16)

HEF4014B

## 13. Abbreviations

Acronym	Description
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

## 14. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4014B v.11	20211124	Product data sheet	-	HEF4014B v.10
Modifications:	• <u>Section 1</u> a	and <u>Section 2</u> updated.		,
HEF4014B v.10	20181017	Product data sheet	-	HEF4014B v.9
Modifications:	of Nexperia		-	nply with the identity guidelines e where appropriate.
HEF4014B v.9	20160321	Product data sheet	-	HEF4014B v.8
Modifications:	Type numb	er HEF4014BP (SOT38-4)	) removed.	
HEF4014B v.8	20111121	Product data sheet	-	HEF4014B v.7
Modifications:	<ul><li>Legal page</li><li>Changes ir</li></ul>	s updated. n "General description" and	l "Features and ben	efits".
HEF4014B v.7	20110914	Product data sheet	-	HEF4014B v.6
HEF4014B v.6	20091102	Product data sheet	-	HEF4014B v.5
HEF4014B v.5	20090624	Product data sheet	-	HEF4014B v.4
HEF4014B v.4	20090122	Product data sheet	-	HEF4014B_CNV v.3
HEF4014B_CNV v.3	19950101	Product specification	-	HEF4014B_CNV v.2
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