## HEF4027B-Q100

# Dual JK flip-flop Rev. 2 — 7 December 2021

Product data sheet

### 1. General description

The HEF4027B-Q100 is a dual positive-edge triggered JK flip-flop featuring independent set direct (nSD), clear direct (nCD), clock inputs (nCP) and complementary outputs (nQ and  $n\overline{Q}$ ). Data is accepted when nCP is LOW, and transferred to the output on the positive-going edge of the clock. The asynchronous clear-direct (nCD) and set-direct (nSD) are independent and override the nJ, nK, and nCP inputs. Schmitt-trigger action in the clock input makes the circuit highly tolerant to slower clock rise and fall times. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of  $V_{DD}$ .

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

### 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)
  - Specified from -40 °C to +85 °C
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- · High noise immunity
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
  - MIL-STD-833, method 3015 exceeds 2000 V
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-A exceeds 200 V (C = 200 pF, R = 0  $\Omega$ )
- · Complies with JEDEC standard JESD 13-B

### 3. Applications

- Registers
- Counters
- · Control circuits

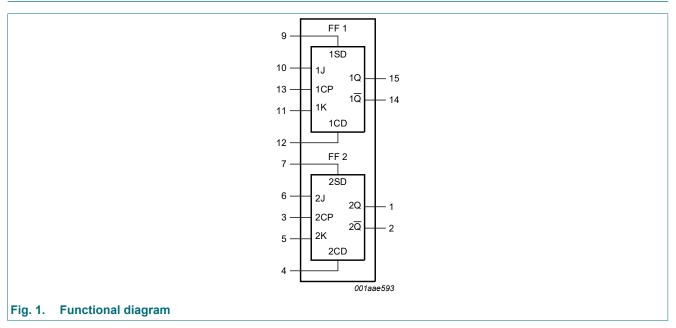
### 4. Ordering information

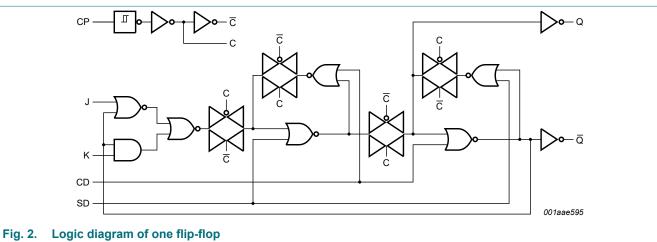
#### **Table 1. Ordering information**

Type number	Package						
	Temperature range	Name	Description	Version			
HEF4027BT-Q100	-40 °C to +85 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1			



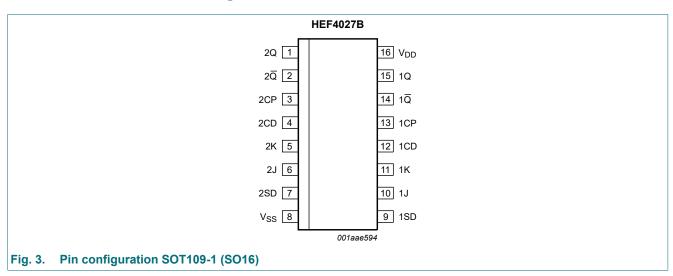
## 5. Functional diagram





## 6. Pinning information

### 6.1. Pinning



### 6.2. Pin description

Table 2. Pin description

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Symbol	Pin	Description				
V <sub>SS</sub>	8	ground supply voltage				
1SD, 2SD	9, 7	asynchronous set-direct input (active HIGH)				
1J, 2J	10, 6	synchronous input				
1K, 2K	11, 5	synchronous input				
1CD, 2CD	12, 4	asynchronous clear-direct input (active HIGH)				
1CP, 2CP	13, 3	clock input (LOW-to-HIGH edge-triggered)				
1 <del>Q</del> , 2 <del>Q</del>	14, 2	complement output				
1Q, 2Q	15, 1	true output				
$V_{DD}$	16	supply voltage				

## 7. Functional description

#### **Table 3. Function table**

 $H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level; \ X = don't \ care.; \ \uparrow = positive-going \ transition.$ 

Inputs		Outputs				
nSD	nCD	nCP	nJ	nK	nQ	nQ
Н	L	Х	X	Х	Н	L
L	Н	Х	X	Х	L	Н
Н	Н	X	X	X	Н	Н
L	L	1	L	L	no change	no change
L	L	1	Н	L	Н	L
L	L	1	L	Н	L	Н
L	L	<b>↑</b>	Н	Н	nQ	nQ

## 8. Limiting values

#### **Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{I} < -0.5 \text{ V or } V_{I} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{O}$ < -0.5 V or $V_{O}$ > $V_{DD}$ + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature	in free air	-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> -40 °C to +85 °C	-	500	mW
Р	power dissipation	per output	-	100	mW

## 9. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		3	15	V
VI	input voltage		0	$V_{DD}$	V
T <sub>amb</sub>	ambient temperature	in free air	-40	+85	°C
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	3.75	μs/V
		V <sub>DD</sub> = 10 V	-	0.5	µs/V
		V <sub>DD</sub> = 15 V	-	0.08	μs/V

### 10. Static characteristics

### **Table 6. Static characteristics**

 $V_{SS}$  = 0 V;  $V_I$  =  $V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	$V_{DD}$ $T_{amb} = -40$		T <sub>amb</sub> =	+25 °C	T <sub>amb</sub> =	+85 °C	Unit
				Min	Max	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level input voltage	I <sub>O</sub>   < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
$V_{IL}$	LOW-level input voltage	I <sub>O</sub>   < 1 μA	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	LOW-level output voltage	I <sub>O</sub>   < 1 μA	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V

Symbol	Parameter	Conditions	Conditions V <sub>DD</sub>		-40 °C	T <sub>amb</sub> =	+25 °C	T <sub>amb</sub> =	+85 °C	Unit
				Min	Max	Min	Max	Min	Max	
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V <sub>O</sub> = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V <sub>O</sub> = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I <sub>OL</sub>	LOW-level output current	V <sub>O</sub> = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		V <sub>O</sub> = 0.5 V	10 V	1.3	-	1.1	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
Iı	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μΑ
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	4.0	-	4.0	-	30	μΑ
			10 V	-	8.0	-	8.0	-	60	μΑ
			15 V	-	16.0	-	16.0	-	120	μΑ
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

## 11. Dynamic characteristics

**Table 7. Dynamic characteristics** 

 $V_{SS}$  = 0 V;  $T_{amb}$  = 25 °C unless otherwise specified; for test circuit see Fig. 7.

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula [1]	Min	Тур	Max	Unit
t <sub>PHL</sub>	HIGH to LOW	$CP \rightarrow Q, \overline{Q};$	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns
	propagation delay	see Fig. 4	10 V	29 ns + (0.23 ns/pF)C <sub>L</sub>	-	40	80	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
		$CD \rightarrow Q$ ;	5 V	93 ns + (0.55 ns/pF)C <sub>L</sub>	-	120	240	ns
		see Fig. 4	10 V	33 ns + (0.23 ns/pF)C <sub>L</sub>	-	45	90	ns
			15 V	27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns
	$SD \to \overline{Q}$ ;	5 V	113 ns + (0.55 ns/pF)C <sub>L</sub>	-	140	280	ns	
		see Fig. 4	10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	$CP \rightarrow Q, \overline{Q};$	5 V	58 ns + (0.55 ns/pF)C <sub>L</sub>	-	85	170	ns
		see Fig. 4	10 V	27 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
		$CD \rightarrow \overline{Q}$ ;	5 V	48 ns + (0.55 ns/pF)C <sub>L</sub>	-	75	150	ns
		see Fig. 4	10 V	24 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns
			15 V	17 ns + (0.16 ns/pF)C <sub>L</sub>	-	25	50	ns
		$SD \rightarrow Q;$	5 V	43 ns + (0.55 ns/pF)C <sub>L</sub>	-	70	140	ns
		see Fig. 4	10 V	19 ns + (0.23 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	17 ns + (0.16 ns/pF)C <sub>L</sub>	-	25	50	ns
t <sub>t</sub>	transition time	see Fig. 4	5 V [2]	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>su</sub>	set-up time	$J, K \rightarrow CP;$	5 V		50	25	-	ns
		see Fig. 5	10 V		30	10	-	ns
			15 V		20	5	-	ns

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula [1]	Min	Тур	Max	Unit
t <sub>h</sub>	hold time	$J, K \rightarrow CP;$	5 V		25	0	-	ns
		see Fig. 5	10 V		20	0	-	ns
		15 V		15	5	-	ns	
t <sub>W</sub>	pulse width CP LOW; minimum width; see Fig. 5	•	5 V		80	40	-	ns
		10 V		30	15	-	ns	
	300 <u>1 lg. 0</u>	15 V		24	12	-	ns	
		SD, CD HIGH;	5 V		90	45	-	ns
		minimum width; see Fig. 6	10 V		40	20	-	ns
		366 <u>i ig. 0</u>	15 V		30	15	-	ns
t <sub>rec</sub>	recovery time	SD, CD inputs;	5 V		+20	-15	-	ns
		see Fig. 6	10 V		+15	-10	-	ns
			15 V		+10	-5	-	ns
f <sub>max</sub>	maximum	CP input;	5 V		4	8	-	MHz
	frequency	J = K = HIGH; see <u>Fig. 5</u>	10 V		12	25	-	MHz
		366 <u>1 lg. J</u>	15 V		15	30	-	MHz

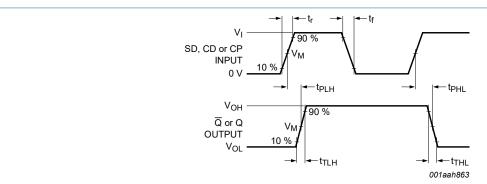
<sup>[1]</sup> The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

Table 8. Dynamic power dissipation  $P_D$ 

 $P_D$  can be calculated from the formulas shown.  $V_{SS}$  = 0 V;  $t_r$  =  $t_f$  ≤ 20 ns;  $T_{amb}$  = 25 °C.

Symbol	Parameter	$V_{DD}$	Typical formula for P <sub>D</sub> (μW)	Where:
$P_D$	dynamic power	5 V	$P_{D} = 900 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	f <sub>i</sub> = input frequency in MHz
	dissipation	10 V	$P_D = 4500 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f <sub>o</sub> = output frequency in MHz C <sub>L</sub> = output load capacitance in pF
		15 V	$P_D = 13200 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	$V_{DD}$ = supply voltage in V $\Sigma(f_0 \times C_L)$ = sum of the outputs

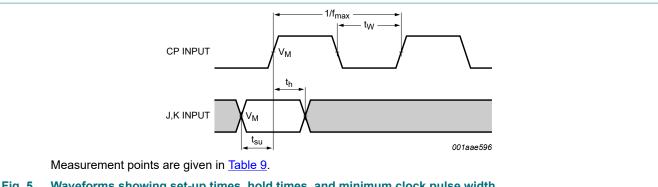
### 11.1. Waveforms and test circuit



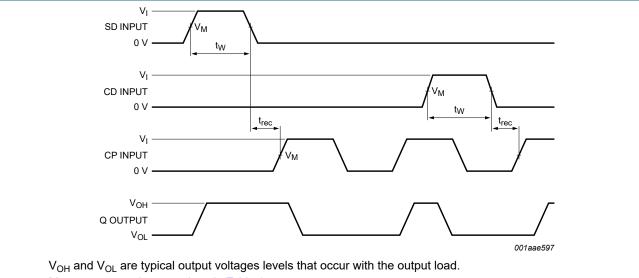
 $V_{OH}$  and  $V_{OL}$  are typical output voltages levels that occur with the output load. Measurement points are given in <u>Table 9</u>.

Fig. 4. Waveforms showing rise, fall, and transition times, and propagation delays

<sup>[2]</sup>  $t_t$  is the same as  $t_{TLH}$  and  $t_{THL}$ .



Waveforms showing set-up times, hold times, and minimum clock pulse width Fig. 5.

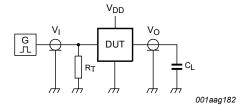


Measurement points are given in Table 9.

Fig. 6. Waveforms showing pulse widths and recovery times

**Table 9. Measurement points** 

Supply voltage	Input	Output
$V_{DD}$	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>



Test data is given in Table 10.

Definitions for test circuit:

 $C_L$  = load capacitance including jig and probe capacitance.

 $R_T$  = termination resistance should be equal to the output impedance  $Z_0$  of the pulse generator.

Fig. 7. Test circuit

Table 10. Test data

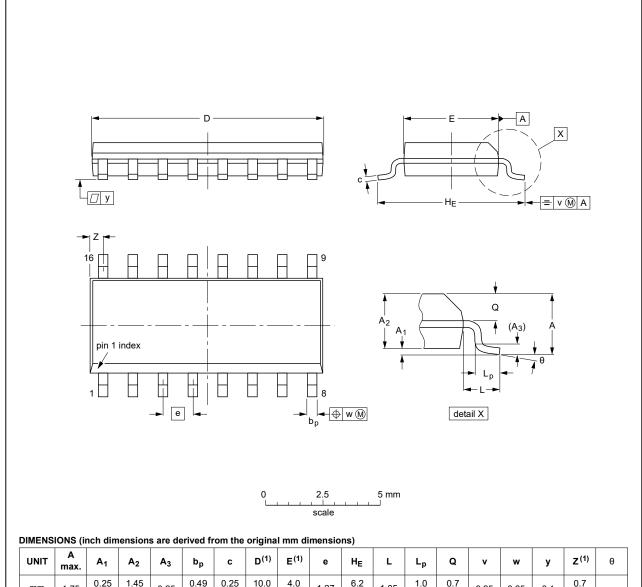
Supply voltage	Input	Load	
$V_{DD}$	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	≤ 20 ns	50 pF

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## 12. Package outline



SOT109-1



UNIT	A max.	<b>A</b> <sub>1</sub>	A <sub>2</sub>	<b>A</b> <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(1)</sup>	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	10.0 9.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01		0.0100 0.0075	0.39 0.38	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.020	0.01	0.01	0.004	0.028 0.012	0°

#### Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

	OUTLINE		REFER	EUROPEAN	ISSUE DATE		
	VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
	SOT109-1	076E07	MS-012				<del>99-12-27</del> 03-02-19

Fig. 8. Package outline SOT109-1 (SO16)

### 13. Abbreviations

#### **Table 11. Abbreviations**

Acronym	Description
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MIL	Military
MM	Machine Model

## 14. Revision history

### Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
HEF4027B_Q100 v.2	20211207	Product data sheet	-	HEF4027B_Q100 v.1	
Modifications:	Nexperia.		n redesigned to comply with the identity guidelines on new company name where appropriate.		
HEF4027B_Q100 v.1	20130626	Product data sheet	-	-	

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### 15. Legal information

#### **Data sheet status**

Document status [1][2]	Product status [3]	Definition		
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.		
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SN74LVC74APW SN74LVC74AD SN74HC273DWR MC74HC11ADG M74HC175B1R M74HC174RM13TR 74ALVTH16374ZQLR

74ALVTH32374ZKER 74VHC9273FT(BJ) 74VHCV374FT(BJ) 74VHCV574FT(BJ) SN74LVC74ADR SN74HC574PWR SN74HC374AN

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