NXS0104-Q100

Dual supply translating transceiver; open drain; auto direction sensing

Rev. 4 — 13 November 2020

Product data sheet

1. General description

The NXS0104-Q100 is a 4-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 4-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). $V_{CC(A)}$ can be supplied at any voltage between 1.65 V and 3.6 V and $V_{CC(B)}$ can be supplied at any voltage between 2.3 V and 5.5 V, making the device suitable for translating between any of the voltage nodes (1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins An and OE are referenced to $V_{CC(A)}$ and pins Bn are referenced to $V_{CC(B)}$. A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
 - Specified from -40 °C to +85 °C and from -40 °C to +125 °C
- Wide supply voltage range:
 - V_{CC(A)}: 1.65 V to 3.6 V and V_{CC(B)}: 2.3 V to 5.5 V
- Maximum data rates:
 - Push-pull: 24 Mbps
- I_{OFF} circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
 - HBM: ANSI/ESDA/Jedec JS-001 Class 2 exceeds 2.5 kV for A port
 - HBM: ANSI/ESDA/Jedec JS-001 Class 3B exceeds 15 kV for B port
 - MIL-STD-883, method 3015 Class 2 exceeds 2.5 kV for A port
 - MIL-STD-883, method 3015 Class 3B exceeds 15 kV for B port
 - IEC61000-4-2 contact discharge exceeds 8000 V for B port
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- DHVQFN package with Side-Wettable Flanks enabling Automatic Optical Inspection (AOI) of solder joints

3. Ordering information

Table 1. Ordering information

Type number	Package			
	Temperature range	Name	Description	Version
NXS0104PW-Q100	-40 °C to +125 °C	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1
NXS0104BQ-Q100	-40 °C to +125 °C	DHVQFN14	plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 14 terminals; body 2.5 × 3 × 0.85 mm	SOT762-1

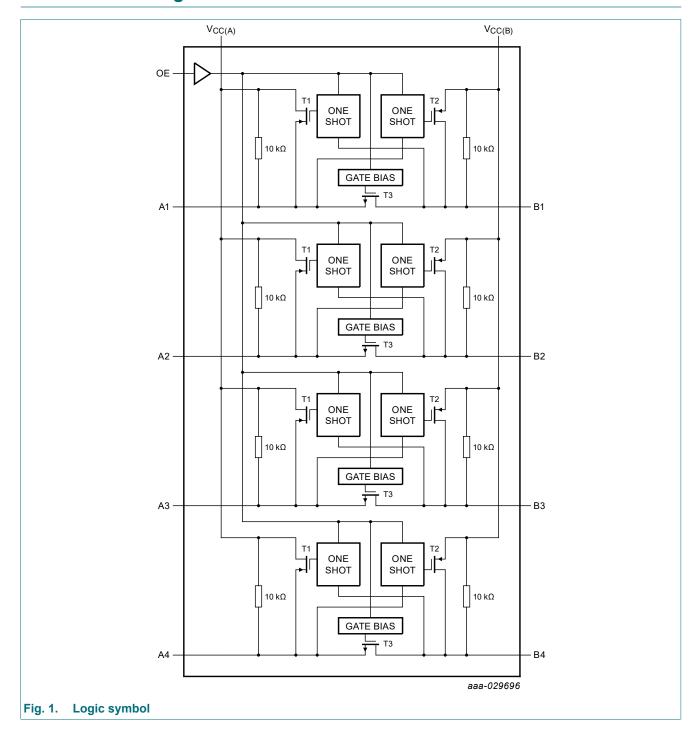


4. Marking

Table 2. Marking

Type number	Marking code
NXS0104PW-Q100	NXS0104
NXS0104BQ-Q100	S0104

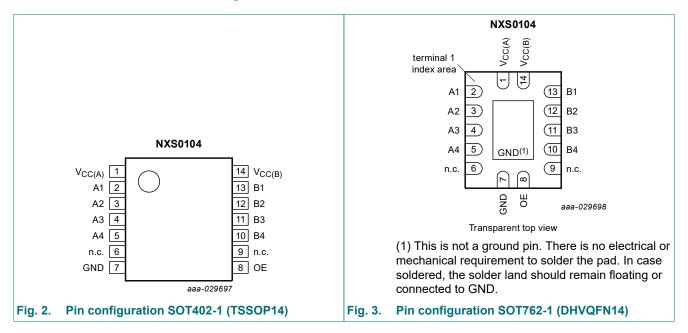
5. Functional diagram



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6. Pinning information

6.1. Pinning



6.2. Pin description

Table 3. Pin description

table of the decomposition						
Symbol	Pin	Description				
V _{CC(A)}	1	supply voltage A				
A1, A2, A3, A4	2, 3, 4, 5	data input or output (referenced to V _{CC(A)})				
n.c.	6, 9	not connected				
GND	7	ground (0 V)				
OE	8	output enable input (active HIGH; referenced to V _{CC(A)})				
B4, B3, B2, B1	10, 11, 12, 13	data input or output (referenced to V _{CC(B)})				
V _{CC(B)}	14	supply voltage B				

7. Functional description

Table 4. Function table

 $H = HIGH \text{ voltage level}; L = LOW \text{ voltage level}; X = don't care; Z = high-impedance OFF-state.}$

Supply voltage		Input	Input/output		
V _{CC(A)} [1] V _{CC(B)}		OE	An	Bn	
1.65 V to 3.6 V	2.3 V to 5.5 V	L	Z	Z	
1.65 V to 3.6 V	2.3 V to 5.5 V	Н	input or output	output or input	
GND[2]	GND[2]	X	Z	Z	

- [1] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$ and $V_{CC(A)}$ must not exceed 3.6 V.
- [2] When either $V_{CC(A)}$ or $V_{CC(B)}$ is at GND level, the device goes into power-down mode.

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8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V _{CC(A)}	supply voltage A			-0.5	+6.5	V
V _{CC(B)}	supply voltage B			-0.5	+6.5	V
VI	input voltage	A port and OE input	[1]	-0.5	+6.5	V
		B port	[1]	-0.5	+6.5	V
Vo	output voltage	Active mode	[1] [2]			
		A or B port		-0.5	V _{CCO} + 0.5	V
		Power-down or 3-state mode	[1]			
		A port		-0.5	+4.6	V
		B port		-0.5	+6.5	V
I _{IK}	input clamping current	V _I < 0 V		-50	-	mA
I _{OK}	output clamping current	V _O < 0 V		-50	-	mA
Io	output current	$V_O = 0 V \text{ to } V_{CCO}$	[2]	-	±50	mA
I _{CC}	supply current	I _{CC(A)} or I _{CC(B)}		-	100	mA
I_{GND}	ground current			-100	-	mA
T _{stg}	storage temperature			-65	+150	°C
P _{tot}	total power dissipation	T _{amb} = -40 °C to +125 °C	[3]	-	500	mW

^[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

9. Recommended operating conditions

Table 6. Recommended operating conditions [1] [2]

Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC(A)}	supply voltage A		1.65	3.6	V
$V_{CC(B)}$	supply voltage B		2.3	5.5	V
T _{amb}	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	A or B port; push-pull driving			
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	-	10	ns/V
		OE input			
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	-	10	ns/V

^[1] The A and B sides of an unused I/O pair must be held in the same state, both at V_{CCI} or both at GND.

^[2] V_{CCO} is the supply voltage associated with the output.

^[3] For SOT402-1 (TSSOP14) package: P_{tot} derates linearly with 7.3 mW/K above 81 °C. For SOT762-1 (DHVQFN14) package: P_{tot} derates linearly with 9.6 mW/K above 98 °C.

^[2] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$ and $V_{CC(A)}$ must not exceed 3.6 V.

10. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.[1]

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I _I	input leakage current	OE input; $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	-	-	±1	μΑ
l _{OZ}	OFF-state output current	A or B port; OE = 0 V; $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	-	-	±1	μΑ
O		A port; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$ to 5.5 V	-	-	±1	μA
	current	B port; V _{CC(B)} = 0 V; V _{CC(A)} = 0 V to 3.6 V	-	-	±1	μA
Cı	input capacitance	OE input; V _{CC(A)} = 3.3 V; V _{CC(B)} = 3.3 V	-	2	-	pF
C _{I/O}	input/output	A port; V _{CC(A)} = 3.3 V; V _{CC(B)} = 3.3 V				
	capacitance	enabled	-	10	-	pF
		disabled	-	4	-	pF
		B port; V _{CC(A)} = 3.3 V; V _{CC(B)} = 3.3 V				
		enabled	-	10	-	pF
		disabled	-	7	-	pF

^[1] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$ and $V_{CC(A)}$ must not exceed 3.6 V.

Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

V _{CC(A)}	V _{CC(A)} V _{CC(B)}						
	2.5 V		3.3 V		5.0 V		
	I _{CC(A)}	I _{CC(B)}	I _{CC(A)}	I _{CC(B)}	I _{CC(A)}	I _{CC(B)}	
1.8 V	0.1	0.5	0.1	1.5	0.1	4.6	μΑ
2.5 V	0.1	0.1	0.1	0.8	0.1	3.8	μΑ
3.3 V	-	-	0.1	0.1	0.1	2.8	μΑ

Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).[1]

Symbol	Parameter	Conditions	-40 °C to	+85 °C	+85 °C -40 °C to +125 °C		
			Min	Max	Min	Max	
V_{IH}	HIGH-level input	A port					
voltage	V _{CC(A)} = 1.65 V to 1.95 V; V _{CC(B)} = 2.3 V to 5.5 V	V _{CC(A)} - 0.2	$V_{CC(A)}$	V _{CC(A)} - 0.2	V _{CC(A)}	V	
		V _{CC(A)} = 2.3 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	V _{CC(A)} - 0.4	$V_{CC(A)}$	V _{CC(A)} - 0.4	V _{CC(A)}	V
		B port					
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	V _{CC(B)} - 0.4	V _{CC(B)}	V _{CC(B)} - 0.4	$V_{CC(B)}$	V
		OE input					
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	0.65V _{CC(A)}	V _{CC(A)}	0.65V _{CC(A)}	V _{CC(A)}	V

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Symbol	Parameter	Conditions	-40 °C t	o +85 °C	-40 °C to	+125 °C	Unit
			Min	Max	Min	Max	
V _{IL}	LOW-level input	A or B port					
	voltage	V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	0	0.15	0	0.15	V
		OE input					
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	0	0.35V _{CC(A)}	0	0.35V _{CC(A)}	V
V _{OH}	HIGH-level	A port; $I_O = -20 \mu A$; $V_I \ge V_{CC(B)} - 0.4 V$					
	output voltage	V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	0.67V _{CC(A)}	-	0.67V _{CC(A)}	-	V
		B port; $I_O = -20 \mu A$; $V_I \ge V_{CC(A)} - 0.2 V$					
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	0.67V _{CC(B)}	-	0.67V _{CC(B)}	-	V
O_	LOW-level	A or B port; $I_O = 1$ mA; $V_I \le 0.15$ V					
	output voltage	V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	-	0.4	-	0.4	V
l _l	input leakage current	OE input; $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	-	±2	-	±12	μA
l _{OZ}	OFF-state output current	A or B port; $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	-	±2	-	±12	μA
l _{OFF}	power-off leakage current	A port; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 0 \text{ V to } 5.5 \text{ V}$	-	±2	-	±12	μA
		B port; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(A)} = 0 \text{ V}$ to 3.6 V	-	±2	-	±12	μA
I _{CC}	supply current	OE = 0 V or V _{CC(A)} ; An, Bn open					
		I _{CC(A)}					
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	-	2.4	-	15	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-	2.2	-	15	μA
		V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V	-	-1	-	-8	μΑ
		I _{CC(B)}					
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	-	12	-	30	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-	-1	-	-5	μΑ
		V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V	-	1	-	6	μΑ
		I _{CC(A)} + I _{CC(B)}					
		V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V	-	14.4	-	45	μΑ

^[1] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$ and $V_{CC(A)}$ must not exceed 3.6 V.

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Dual supply translating transceiver; open drain; auto direction sensing

11. Dynamic characteristics

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 4 to Fig. 6.

Symbol	Parameter	Conditions			Vc	C(B)			Unit
			2.5 V :	± 0.2 V		± 0.3 V	5.0 V ±	± 0.5 V	1
			Min	Max	Min	Max	Min	Max	ns
V _{CC(A)} =	1.8 V ± 0.15 V								
t _{PHL}	HIGH to LOW propagation delay	A to B	-	4.6	-	4.7	-	5.8	ns
t _{PLH}	LOW to HIGH propagation delay	A to B	-	7.1	-	6.8	-	7.0	ns
t _{PHL}	HIGH to LOW propagation delay	B to A	-	4.4	-	4.5	-	4.7	ns
t _{PLH}	LOW to HIGH propagation delay	B to A	-	5.3	-	4.5	-	0.5	ns
t _{en}	enable time	OE to A, B [1]	-	200	-	200	-	200	ns
t _{dis}	disable time	OE to A, B; no external load [1] [2]	-	35	-	35	-	35	ns
		OE to A	-	140	-	140	-	145	ns
		OE to B	-	125	-	175	-	125	ns
t _{TLH}	LOW to HIGH	A port	3.2	9.5	2.3	9.3	1.8	7.6	ns
	output transition time	B port	3.3	10.8	2.7	9.1	2.7	7.6	ns
t_{THL}	HIGH to LOW	A port	2.0	5.9	1.9	6.0	1.7	13.3	ns
	output transition time	B port	2.9	7.6	2.8	7.5	2.8	10.0	ns
t _{sk(o)}	output skew time	between channels [3]	-	0.7	-	0.7	-	0.7	ns
t _W	pulse width	data inputs	41	-	41	-	41	-	ns
f _{data}	data rate		-	24	-	24	-	24	Mbps

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Symbol	Parameter	Conditions			Vc	C(B)			Unit
			2.5 V	± 0.2 V	3.3 V	± 0.3 V	5.0 V :	± 0.5 V	
			Min	Max	Min	Max	Min	Max	
V _{CC(A)} =	2.5 V ± 0.2 V								
t _{PHL}	HIGH to LOW propagation delay	A to B	-	3.2	-	3.3	-	3.4	ns
t _{PLH}	LOW to HIGH propagation delay	A to B	-	3.5	-	4.4	-	4.6	ns
t _{PHL}	HIGH to LOW propagation delay	B to A	-	3.0	-	3.6	-	4.3	ns
t _{PLH}	LOW to HIGH propagation delay	B to A	-	2.5	-	1.6	-	0.7	ns
t _{en}	enable time	OE to A, B [1]	-	200	-	200	-	200	ns
t _{dis}	disable time	OE to A, B; no external load [1] [2]	-	35	-	35	-	35	ns
		OE to A	-	105	-	105	-	105	ns
		OE to B	-	125	-	175	-	120	ns
t _{TLH}	LOW to HIGH	A port	2.8	7.5	2.6	6.6	1.8	6.5	ns
	output transition time	B port	3.2	8.5	2.9	7.3	2.4	6.3	ns
t _{THL}	HIGH to LOW	A port	1.9	5.7	1.9	5.5	1.8	5.3	ns
	output transition time	B port	2.2	7.8	2.4	6.7	2.6	6.6	ns
$t_{sk(o)}$	output skew time	between channels [3]	-	0.7	-	0.7	-	0.7	ns
t_{W}	pulse width	data inputs	41	-	41	-	41	-	ns
f _{data}	data rate		-	24	-	24	-	24	Mbps
$V_{CC(A)} =$	3.3 V ± 0.3 V								
t _{PHL}	HIGH to LOW propagation delay	A to B	-	-	-	2.4	-	3.1	ns
t _{PLH}	LOW to HIGH propagation delay	A to B	-	-	-	4.2	-	4.4	ns
t _{PHL}	HIGH to LOW propagation delay	B to A	-	-	-	2.5	-	3.3	ns
t _{PLH}	LOW to HIGH propagation delay	B to A	-	-	-	2.5	-	2.6	ns
t _{en}	enable time	OE to A, B	-	-	-	200	-	200	ns
t _{dis}	disable time	OE to A, B; no external load [1] [2]	-	-	-	35	-	35	ns
		OE to A	-	-	-	150	-	150	ns
		OE to B	-	-	-	170	-	120	ns
t _{TLH}	LOW to HIGH	A port	-	-	2.3	6.2	1.9	6.3	ns
	output transition time	B port	-	-	2.5	6.9	2.1	7.4	ns
t _{THL}	HIGH to LOW	A port	-	-	2.0	5.4	1.9	5.0	ns
	output transition time	B port	-	-	2.3	7.4	2.4	7.6	ns
t _{sk(o)}	output skew time	between channels [3]	-	-	-	0.7	-	0.7	ns
t _W	pulse width	data inputs	-	-	41	-	41	-	ns
f _{data}	data rate		-	-	-	24	-	24	Mbps

 t_{en} is the same as t_{PZL} and t_{PZH} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} .

^[2] [3] These values are guaranteed by design.

Skew between any two outputs of the same package switching in the same direction.

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Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 4 to Fig. 6.

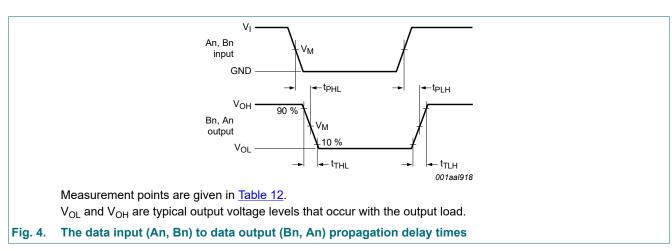
Symbol	Parameter	Conditions		V _{CC(B)}							
			2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V			
			Min	Max	Min	Max	Min	Max			
V _{CC(A)} =	1.8 V ± 0.15 V			<u> </u>							
t _{PHL}	HIGH to LOW propagation delay	A to B	-	5.8	-	5.9	-	7.3	ns		
t _{PLH}	LOW to HIGH propagation delay	A to B	-	8.5	-	8.5	-	8.8	ns		
t _{PHL}	HIGH to LOW propagation delay	B to A	-	5.5	-	5.7	-	5.9	ns		
t _{PLH}	LOW to HIGH propagation delay	B to A	-	6.7	-	5.7	-	0.7	ns		
t _{en}	enable time	OE to A, B [1]	-	200	-	200	-	200	ns		
t _{dis}	disable time	OE to A, B; no external load [1] [2]	-	45	-	45	-	45	ns		
		OE to A	-	140	-	140	-	145	ns		
		OE to B	-	125	-	175	-	125	ns		
t _{TLH}	LOW to HIGH	A port	3.2	11.9	2.3	11.7	1.8	9.5	ns		
	output transition time	B port	3.3	13.5	2.7	11.4	2.7	9.5	ns		
t _{THL}	HIGH to LOW	A port	2.0	7.4	1.9	7.5	1.7	16.7	ns		
	output transition time	B port	2.9	9.5	2.8	9.4	2.8	12.5	ns		
t _{sk(o)}	output skew time	between channels [3]	-	0.8	-	8.0	-	0.8	ns		
t _W	pulse width	data inputs	50	-	41	-	41	-	ns		
f _{data}	data rate		-	20	-	24	-	24	Mbps		
$V_{CC(A)} =$	2.5 V ± 0.2 V										
t _{PHL}	HIGH to LOW propagation delay	A to B	-	4.0	-	4.2	-	4.3	ns		
t _{PLH}	LOW to HIGH propagation delay	A to B	-	4.4	-	5.2	-	5.5	ns		
t _{PHL}	HIGH to LOW propagation delay	B to A	-	3.8	-	4.5	-	5.4	ns		
t _{PLH}	LOW to HIGH propagation delay	B to A	-	3.2	-	2.0	-	0.9	ns		
t _{en}	enable time	OE to A, B [1]	-	200	-	200	-	200	ns		
t _{dis}	disable time	OE to A, B; no external load [1] [2]	-	45	-	45	-	45	ns		
		OE to A	-	105	-	105	-	105	ns		
		OE to B	-	125	-	175	-	120	ns		
t _{TLH}	LOW to HIGH	A port	2.8	9.3	2.6	8.3	1.8	7.8	ns		
	output transition time	B port	3.2	10.4	2.9	9.7	2.4	8.3	ns		
t _{THL}	HIGH to LOW	A port	1.9	7.2	1.9	6.9	1.8	6.7	ns		
	output transition time	B port	2.2	9.8	2.4	8.4	2.6	8.3	ns		
t _{sk(o)}	output skew time	between channels [3]	-	8.0	-	0.8	-	0.8	ns		
t _W	pulse width	data inputs	50	-	41	-	41	-	ns		
f _{data}	data rate		-	20	-	24	-	24	Mbps		

Dual supply translating transceiver; open drain; auto direction sensing

Symbol	Parameter	Conditions				Vc	C(B)			Unit
				2.5 V ± 0.2 V		3.3 V	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	
V _{CC(A)} =	3.3 V ± 0.3 V									
t _{PHL}	HIGH to LOW propagation delay	A to B		-	-	-	3.0	-	3.9	ns
t _{PLH}	LOW to HIGH propagation delay	A to B		-	-	-	5.3	-	5.5	ns
t _{PHL}	HIGH to LOW propagation delay	B to A		-	-	-	3.2	-	4.2	ns
t _{PLH}	LOW to HIGH propagation delay	B to A		-	-	-	3.2	-	3.3	ns
t _{en}	enable time	OE to A, B	[1]	-	-	-	200	-	200	ns
t _{dis}	disable time	OE to A, B; no external load [1	1] [2]	-	-	-	45	-	45	ns
		OE to A		-	-	-	150	-	150	ns
		OE to B		-	-	-	170	-	120	ns
t _{TLH}	LOW to HIGH	A port		-	-	2.3	7.0	1.9	7.4	ns
	output transition time	B port		-	-	2.5	8.0	2.1	9.3	ns
t _{THL}	HIGH to LOW	A port		-	-	2.0	6.8	1.9	6.3	ns
	output transition time	B port		-	-	2.3	9.3	2.4	9.5	ns
t _{sk(o)}	output skew time	between channels	[3]	-	-	-	0.8	-	0.8	ns
t _W	pulse width	data inputs		-	-	41	-	41	-	ns
f _{data}	data rate			-	-	-	24	-	24	Mbps

- t_{en} is the same as t_{PZL} and $t_{\text{PZH}};\,t_{\text{dis}}$ is the same as t_{PLZ} and $t_{\text{PHZ}}.$
- These values are guaranteed by design.
- [2] [3] Skew between any two outputs of the same package switching in the same direction.

11.1. Waveforms and test circuit



Dual supply translating transceiver; open drain; auto direction sensing

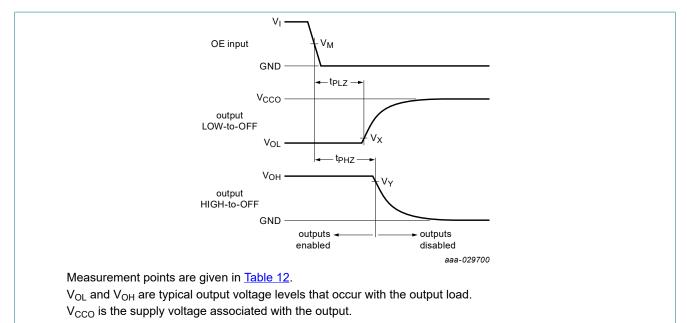
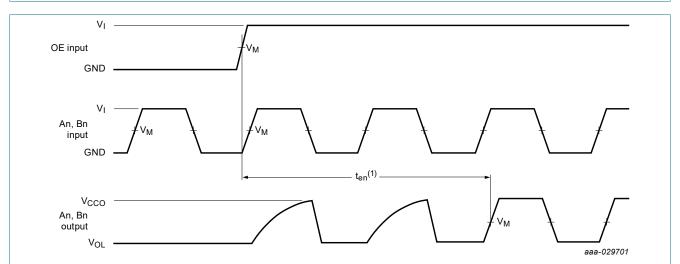


Fig. 5. Disable times



(1) The enable time (t_{en}) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. See also Section 12.6

Measurement points are given in Table 12.

V_{OL} is a typical output voltage level that occur with the output load.

 V_{CCO} is the supply voltage associated with the output.

Fig. 6. Enable times

Table 12. Measurement points

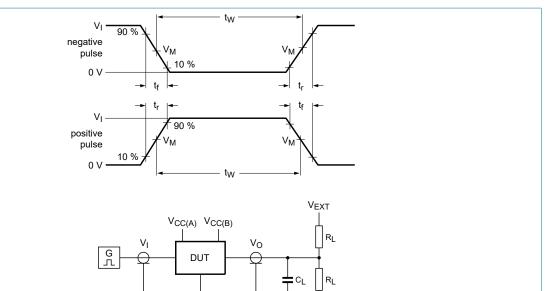
Supply voltage	Input	Output		
V _{cco}	V _M [1]	V _M [2]	V _X	V _Y
1.8 V ± 0.15 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.15 V	V _{OH} - 0.15 V
2.5 V ± 0.2 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.15 V	V _{OH} - 0.15 V
3.3 V ± 0.3 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.3 V	V _{OH} - 0.3 V
5.0 V ± 0.5 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.3 V	V _{OH} - 0.3 V

^[1] V_{CCI} is the supply voltage associated with the input.

^[2] V_{CCO} is the supply voltage associated with the output.

Dual supply translating transceiver; open drain; auto direction sensing

aaa-029721



Test data is given in Table 13.

All input pulses are supplied by generators having the following characteristics:

PRR \leq 10 MHz; $Z_O = 50 \Omega$; $dV/dt \geq 1.0 V/ns$.

R_L = Load resistance.

C_L = Load capacitance including jig and probe capacitance.

V_{EXT} = External voltage for measuring switching times.

Fig. 7. Test circuit for measuring switching times

Table 13. Test data

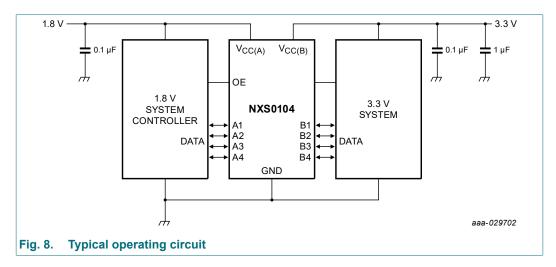
Supply voltage		Input		Load		V _{EXT}			
V _{CC(A)}	V _{CC(B)}	V _I [1]	Δt/ΔV	CL	R _L [2]	t _{PLH} , t _{PHL}	t _{PZH} , t _{PHZ}	t _{PZL} , t _{PLZ} [3]	
1.65 V to 3.6 V	2.3 V to 5.5 V	V _{CCI}	≤ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V _{CCO}	

- [1] V_{CCI} is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements, $R_L = 1 \text{ M}\Omega$. For measuring enable and disable times, $R_L = 50 \text{ k}\Omega$.
- [3] V_{CCO} is the supply voltage associated with the output.

12. Application information

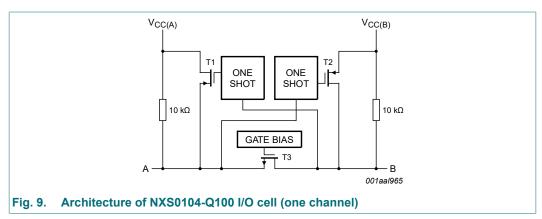
12.1. Applications

Voltage level-translation applications. The NXS0104-Q100 can be used in point-to-point applications to interface between devices or systems operating at different supply voltages. The device is primarily targeted at I²C or 1-wire which use open-drain drivers, it may also be used in applications where push-pull drivers are connected to the ports, however the NXB0104-Q100 may be more suitable.



12.2. Architecture

The architecture of the NXS0104-Q100 is shown in Fig. 9. The device does not require an extra input signal to control the direction of data flow from A to B or B to A.



The NXS0104-Q100 is a "switch" type voltage translator, it employs two key circuits to enable voltage translation:

- 1. A pass-gate transistor (N-channel) that ties the ports together.
- 2. An output edge-rate accelerator that detects and accelerates rising edges on the I/O pins.

The gate bias voltage of the pass gate transistor (T3) is set at approximately one threshold voltage above the V_{CC} level of the low-voltage side. During a LOW-to-HIGH transition the output one-shot accelerates the output transition by switching on the PMOS transistors (T1, T2) bypassing the 10 k Ω pull-up resistors and increasing current drive capability. The one-shot is activated once the input transition reaches approximately 0.5V_{CCI}; it is de-activated approximately 50 ns after the output reaches 0.5V_{CCO}. During the acceleration time the driver output resistance is between approximately 50 Ω and 70 Ω .

Dual supply translating transceiver; open drain; auto direction sensing

To avoid signal contention and minimize dynamic I_{CC} , the user should wait for the one-shot circuit to turn-off before applying a signal in the opposite direction. Pull-up resistors are included in the device for DC current sourcing capability.

12.3. Input driver requirements

As the NXS0104-Q100 is a switch type translator, properties of the input driver directly effect the output signal. The external open-drain or push-pull driver applied to an I/O determines the static current sinking capability of the system; the max data rate, HIGH-to-LOW output transition time (t_{THL}) and propagation delay (t_{PHL}) are dependent upon the output impedance and edge-rate of the external driver. The limits provided for these parameters in the datasheet assume a driver with output impedance below 50 Ω is used.

12.4. Output load considerations

The maximum lumped capacitive load that can be driven is dependant upon the one-shot pulse duration. In cases with very heavy capacitive loading there is a risk that the output will not reach the positive rail within the one-shot pulse duration. To avoid excessive capacitive loading and to ensure correct triggering of the one-shot it's recommended to use short trace lengths and low capacitance connectors on NXS0104-Q100 PCB layouts. To ensure low impedance termination and avoid output signal oscillations and one-shot re-triggering, the length of the PCB trace should be such that the round trip delay of any reflection is within the one-shot pulse duration.

12.5. Power up

During operation $V_{CC(A)}$ must never be higher than $V_{CC(B)}$, however during power-up $V_{CC(B)} \ge V_{CC(B)}$ does not damage the device, so any power supply can be ramped up first. There is no special power-up sequencing required. The NXS0104-Q100 includes circuitry that disables all output ports when either $V_{CC(A)}$ or $V_{CC(B)}$ is switched off.

12.6. Enable and disable

An output enable input (OE) is used to disable the device. Setting OE to LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ($t_{\rm dis}$ with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ($t_{\rm en}$) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

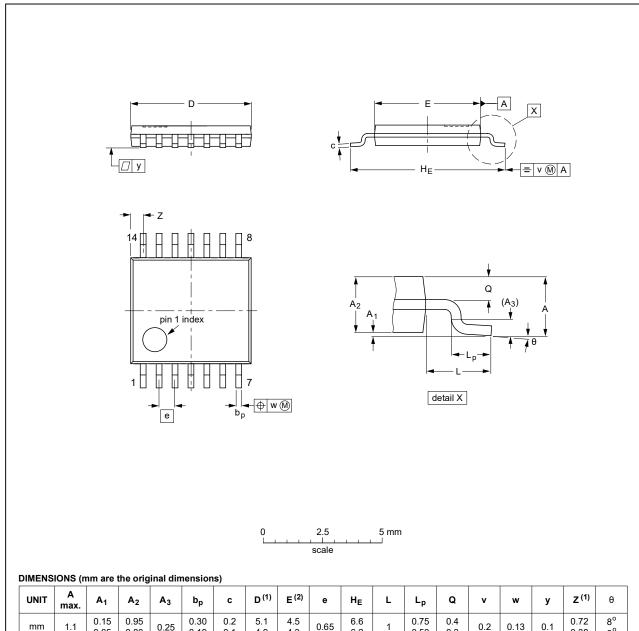
12.7. Pull-up or pull-down resistors on I/O lines

Each A port I/O has an internal 10 k Ω pull-up resistor to $V_{CC(A)}$, and each B port I/O has an internal 10 k Ω pull-up resistor to $V_{CC(B)}$. If a smaller value of pull-up resistor is required, an external resistor must be added parallel to the internal 10 k Ω , this will effect the V_{OL} level. When OE goes LOW the internal pull-ups of the NXS0104-Q100 are disabled.

13. Package outline

TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1



UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	Q	v	w	у	Z ⁽¹⁾	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.72 0.38	8° 0°

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	RENCES	EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE
SOT402-1		MO-153			99-12-27 03-02-18

Fig. 10. Package outline SOT402-1 (TSSOP14)

Dual supply translating transceiver; open drain; auto direction sensing

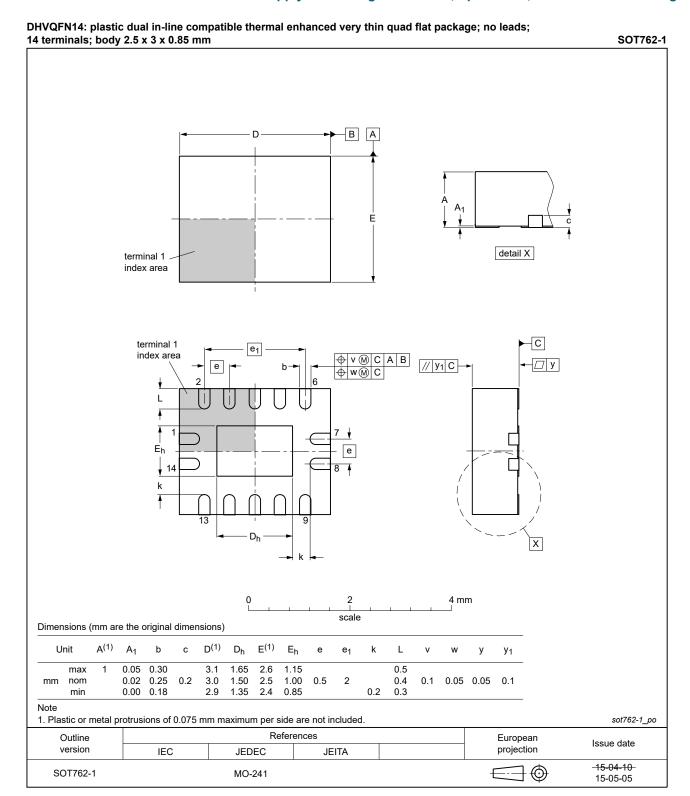


Fig. 11. Package outline SOT762-1 (DHVQFN14)

Dual supply translating transceiver; open drain; auto direction sensing

14. Abbreviations

Table 14. Abbreviations

Acronym	Description
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
I ² C	Inter-Integrated Circuit
MIL	Military
PCB	Printed Circuit Board
PRR	Pulse Rate Repetition

15. Revision history

Table 15. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes				
NXS0104_Q100 v.4	20201113	Product data sheet	-	NXS0104_Q100 v.3				
Modifications:	• <u>Table 10</u> and	• <u>Table 10</u> and <u>Table 11</u> : Disable times updated.						
NXS0104_Q100 v.3	20200827	Product data sheet	-	NXS0104_Q100 v.2				
Modifications:		odated. Perating values for P _{tot} total d <u>Table 11</u> : Footnotes corre	•	n updated.				
NXS0104_Q100 v.2	20190619	Product data sheet	-	NXS0104_Q100 v.1				
Modifications:	 Added type number NXS0104BQ-Q100 (SOT762-1/DHVQFN14). Section 8: total power dissipation changed to 500 mW. 							
NXS0104_Q100 v.1	20190401	Product data sheet	-	-				

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Dual supply translating transceiver; open drain; auto direction sensing

16. Legal information

Data sheet status

Document status [1][2]	Product status [3]	Definition			
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.			
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.			
Product [short] data sheet	Production	This document contains the product specification.			

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- [2] The term 'short data sheet' is explained in section "Definitions".
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