# 600mA Step-down DCIDC Converter with Synchronous Rectifier 

NO.EA-305-180529

## OUTLINE

The RP507K001B is a CMOS-based $600 \mathrm{~mA}^{(1)}$ step-down DC/DC converter with synchronous rectifier. Internally, a single converter consists of an oscillator, a reference voltage unit, an error amplifier, a switching control circuit, a soft-start circuit, an under voltage lockout (UVLO) circuit, an over current protection circuit, a thermal shutdown circuit and switching transistors.
Replacing diodes with built-in switching transistors improves the efficiency of rectification. Therefore, by simply using an inductor, resistors and capacitors as the external components, a low ripple high efficiency synchronous rectifier step-down DC/DC converter can be easily configured.
The RP507K001B has an over current protection circuit which supervises the inductor peak current in each switching cycle, and turns the high-side driver off if the current exceeds the Lx current limit. The RP507K001B also contains a thermal shutdown circuit which detects overheating of the converter and stops the converter operation to protect it from damage if the junction temperature exceeds the specified temperature.
The RP507K001B is PWM/VFM auto switching control in which mode automatically switches from PWM mode to high-efficiency VFM mode in low output current.
The RP507K001B is available in DFN(PLP)1616-6D package which achieves high-density mounting on boards. For an input capacitor (Cin) and an output capacitor (Соит), the smaller sized 0402/1005 (inch/ mm) capacitor can be used. Output voltage is adjustable with external divider resistors.

## FEATURES

- Input Voltage Range
- Output Voltage Range
............................. 0.7 V to 5.5 V
(Note: As for 1.0 V or less, input voltage range is limited.)
- Feedback Voltage Accuracy $\qquad$ $\pm 9 \mathrm{mV}\left(\mathrm{V}_{\mathrm{FB}}=0.6 \mathrm{~V}\right)$
- Temperature-Drift Coefficient of Feedback Voltage

Typ. $\pm 100 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$

- Oscillator Frequency ............................................ Typ. 2.0MHz
- Maximum Duty Cycle

100\%

- Built-in Driver ON Resistance

Typ. Pch. $0.38 \Omega$, Nch. $0.3 \Omega\left(\mathrm{~V}_{\mathrm{in}}=3.6 \mathrm{~V}\right)$

- Supply Current (at no load)

Typ. $34 \mu \mathrm{~A}$

- Standby Current

Max. $5 \mu \mathrm{~A}$

- UVLO Detector Threshold

Typ. 2.0V

- Soft-start Time...................................................... Typ. 150 $\mu \mathrm{s}$
- Lx Current Limit Circuit......................................... Typ. 1A
- Package

DFN(PLP)1616-6D

[^0]
## APPLICATIONS

- Power source for portable equipment such as cellular, PDA, DSC, Notebook PC, smartphone
- Power source for Li-ion battery-used equipment


## SELECTION GUIDE

| Product Name | Package | Quantity per Reel | Pb Free | Halogen Free |
| ---: | :---: | :---: | :---: | :---: |
| RP507K001B-TR | DFN(PLP)1616-6D | $5,000 \mathrm{pcs}$ | Yes | Yes |

Output voltage ( $\mathrm{V}_{\mathrm{SET}}$ ) is adjustable with external divider resistors.
Recommended output voltage range is from 0.7 V to 5.5 V .
RP507K001B has an auto-discharge function ${ }^{(1)}$.

## BLOCK DIAGRAMS



[^1]
## PIN DESCRIPTIONS

- DFN(PLP) $1616-6 \mathrm{D}$


BOTTOM VIEW


## RP507K: DFN(PLP)1616-6D

| Pin No. | Symbol | Description |
| :---: | :---: | :--- |
| 1 | CE | Chip Enable Pin ("H" Active) |
| 2 | AGND | Ground Pin ${ }^{(1)}$ |
| 3 | PGND | Ground Pin ${ }^{(1)}$ |
| 4 | Lx | Lx Switching Pin |
| 5 | Vin $^{2}$ | Input Pin |
| 6 | VFB | Feedback Pin |

The exposed tab on the bottom of the package enhances thermal performance and is electrically connected to GND (substrate level). It is recommended that the exposed tab be connected to the ground plane on the board or otherwise be left open.

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## ABSOLUTE MAXIMUM RATINGS

| Absolute Maximum Ratings |  | (AGND=PGND=0V) |  |
| :---: | :---: | :---: | :---: |
| Symbol | Item | Rating | Unit |
| VIN | Vis Input Voltage | -0.3 to 6.5 | V |
| VLx | Lx Pin Voltage | -0.3 to $\mathrm{V}_{\mathrm{IN}}+0.3$ | V |
| $V_{\text {ce }}$ | CE Pin Input Voltage | -0.3 to 6.5 | V |
| $V_{\text {FB }}$ | VFb Pin Voltage | -0.3 to 6.5 | V |
| ILX | Lx Pin Output Current | 1 | A |
| PD | Power Dissipation ${ }^{(1)}$ (DFN(PLP)1616-6D, JEDEC STD. 51-7) | 1580 | mW |
| Tj | Junction Temperature | -40 to 125 | ${ }^{\circ} \mathrm{C}$ |
| Tstg | Storage Temperature Range | -55 to 125 | ${ }^{\circ} \mathrm{C}$ |

## ABSOLUTE MAXIMUM RATINGS

Electronic and mechanical stress momentarily exceeded absolute maximum ratings may cause the permanent damages and may degrade the life time and safety for both device and system using the device in the field. The functional operation at or over these absolute maximum ratings are not assured.

## RECOMMENDED OPERATING CONDITIONS

Recommended Operating Conditions

| Symbol | Item |  | Rating | Unit |
| :---: | :--- | :--- | :---: | :---: |
| $\mathrm{V}_{\mathrm{IN}}$ | Input Voltage | $1.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{SET}}{ }^{(2)}$ | 2.3 to 5.5 | V |
|  |  | $0.9 \mathrm{~V} \leq \mathrm{V}_{\mathrm{SET}}<1.0 \mathrm{~V}$ | 2.3 to 5.25 |  |
|  |  | $0.7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{SET}}<0.9 \mathrm{~V}$ | 2.3 to 4.5 |  |
| Ta | Operating Temperature Range | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |  |

## RECOMMENDED OPERATING CONDITIONS

All of electronic equipment should be designed that the mounted semiconductor devices operate within the recommended operating conditions. The semiconductor devices cannot operate normally over the recommended operating conditions, even if when they are used over such ratings by momentary electronic noise or surge. And the semiconductor devices may receive serious damage when they continue to operate over the recommended operating conditions.

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## ELECTRICAL CHARACTERISTICS

- RP507K001B

| Symbol | Item | Conditions | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $V_{\text {FB }}$ | Feedback Output Voltage | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {CE }}=3.6 \mathrm{~V}$ | 0.591 | 0.600 | 0.609 | V |
| $\Delta \mathrm{V}_{\text {FB }} / \Delta \mathrm{T}$ | Feedback Output Voltage Temperature Coefficient | $-40^{\circ} \mathrm{C} \leq \mathrm{Ta} \leq 85^{\circ} \mathrm{C}$ |  | $\pm 100$ |  | ppm/ ${ }^{\circ} \mathrm{C}$ |
| fosc | Oscillator Frequency | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{CE}}=3.6 \mathrm{~V}\left(\mathrm{~V}_{\mathrm{SET}}(1) \leq 2.6 \mathrm{~V}\right), \\ & \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{CE}}=\mathrm{V}_{\mathrm{SET}}+1 \mathrm{~V}\left(\mathrm{~V}_{\mathrm{SET}}>2.6 \mathrm{~V}\right) \end{aligned}$ | 1.7 | 2.0 | 2.3 | MHz |
| IdD | Supply Current | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {CE }}=\mathrm{V}_{\text {FB }}=3.6 \mathrm{~V}$ |  | 32 | 45 | $\mu \mathrm{A}$ |
| Istandby | Standby Current | $\mathrm{V}_{\mathrm{IN}}=5.5 \mathrm{~V}, \mathrm{~V}_{\text {ce }}=0 \mathrm{~V}$ |  | 0 | 5 | $\mu \mathrm{A}$ |
| Iceh | CE "H" Input Current | $\mathrm{V}_{\text {In }}=\mathrm{V}_{\text {ce }}=5.5 \mathrm{~V}$ | -1 | 0 | 1 | $\mu \mathrm{A}$ |
| Icel | CE "L" Input Current | $\mathrm{V}_{\mathrm{IN}}=5.5 \mathrm{~V}, \mathrm{~V}_{\text {ce }}=0 \mathrm{~V}$ | -1 | 0 | 1 | $\mu \mathrm{A}$ |
| Ivfbr | VFB "H" Input Current | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\mathrm{FB}}=5.5 \mathrm{~V}, \mathrm{~V}_{\text {ce }}=0 \mathrm{~V}$ | -1 | 0 | 1 | $\mu \mathrm{A}$ |
| Ivfbl | VFB "L" Input Current | $\mathrm{V}_{\mathrm{IN}}=5.5 \mathrm{~V}, \mathrm{~V}_{\text {ce }}=\mathrm{V}_{\mathrm{FB}}=0 \mathrm{~V}$ | -1 | 0 | 1 | $\mu \mathrm{A}$ |
| tdis | Auto Discharge Time ${ }^{(2)}$ | $\mathrm{V}_{\text {IN }}=2.3 \mathrm{~V}, \mathrm{~V}_{\text {CE }}=0 \mathrm{~V}, \mathrm{Cout}=10 \mu \mathrm{~F}$ |  | 5 | 10 | ms |
| ILxLEAKH | Lx Leakage Current "H" | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\mathrm{LX}}=5.5 \mathrm{~V}, \mathrm{~V}_{\text {CE }}=0 \mathrm{~V}$ | -1 | 0 | 5 | $\mu \mathrm{A}$ |
| ILXLEAKL | Lx Leakage Current "L" | $\mathrm{V}_{\text {IN }}=5.5 \mathrm{~V}, \mathrm{~V}_{\text {CE }}=\mathrm{V}_{\text {LX }}=0 \mathrm{~V}$ | -5 | 0 | 1 | $\mu \mathrm{A}$ |
| $V_{\text {cen }}$ | CE "H" Input Voltage | $\mathrm{V}_{\mathrm{IN}}=5.5 \mathrm{~V}$ | 1.0 |  |  | V |
| Vcel | CE "L" Input Voltage | $\mathrm{V}_{\mathrm{IN}}=2.3 \mathrm{~V}$ |  |  | 0.4 | V |
| Ronp | On Resistance of Pch Tr. | $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}, \mathrm{ILX}=-100 \mathrm{~mA}$ |  | 0.38 |  | $\Omega$ |
| Ronn | On Resistance of Nch Tr. | $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}, \mathrm{ILX}=-100 \mathrm{~mA}$ |  | 0.3 |  | $\Omega$ |
| Maxduty | Maximum Duty Cycle |  | 100 |  |  | \% |
| tstart | Soft-start Time | $\begin{aligned} & \mathrm{V}_{I N}=\mathrm{V}_{\text {CE }}=3.6 \mathrm{~V}\left(\mathrm{~V}_{\text {SET }} \leq 2.6 \mathrm{~V}\right), \\ & \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {CE }}=\mathrm{V}_{\text {SET }}+1 \mathrm{~V}\left(\mathrm{~V}_{\text {SET }}>2.6 \mathrm{~V}\right) \end{aligned}$ |  | 150 | 300 | $\mu \mathrm{S}$ |
| ILxLim | Lx Current Limit | $\begin{aligned} & \mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {CE }}=3.6 \mathrm{~V}\left(\mathrm{~V}_{\text {SET }} \leq 2.6 \mathrm{~V}\right), \\ & \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {CE }}=\mathrm{V}_{\text {SET }}+1 \mathrm{~V}\left(\mathrm{~V}_{\text {SET }}>2.6 \mathrm{~V}\right. \end{aligned}$ | 800 | $\begin{gathered} 100 \\ 0 \end{gathered}$ |  | mA |
| Vuvloi | UVLO Detector Threshold | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {CE }}$ | 1.9 | 2.0 | 2.1 | V |
| Vuvloz | UVLO Released Voltage | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {CE }}$ | 2.0 | 2.1 | 2.2 | V |
| TTSD | Thermal Shutdown Temperature | Junction Temperature |  | 140 |  | ${ }^{\circ} \mathrm{C}$ |
| TTSR | Thermal Shutdown Released Temperature | Junction Temperature |  | 100 |  | ${ }^{\circ} \mathrm{C}$ |

Note: Test circuit is "OPEN LOOP" and AGND=PGND=0V unless otherwise specified.

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## THEORY OF OPERATION

## Operation of Step-Down DCI DC Converter and Output Current

The step-down DC/ DC converter charges energy in the inductor when Lx Tr. turns "ON", and discharges the energy from the inductor when Lx Tr. turns "OFF" and operates with less energy loss, so that a lower output voltage ( $\mathrm{V}_{\text {out }}$ ) than the input voltage ( $\mathrm{V}_{\mathrm{II}}$ ) can be obtained.
The operation of the step-down DC/ DC converter is explained in the following figures.


Figure 1. Basic Circuit


Figure 2. Inductor Current (IL) flowing through Inductor

Step1. Pch Tr. turns "ON" and IL (i1) flows, $L$ is charged with energy. At this moment, i1 increases from the minimum inductor current (ILmin), which is OA, and reaches the maximum inductor current (ILmax) in proportion to the on-time period (ton) of Pch Tr.
Step2. When Pch Tr. turns "OFF", L tries to maintain IL at ILmax, so L turns Nch Tr. "ON" and IL (i2) flows into L.

Step3. i2 decreases gradually and reaches ILmin after the open-time period (topen) of Nch Tr., and then Nch Tr. turns "OFF". This is called discontinuous current mode.

As the output current (lout) increases, the off-time period (toff) of Pch Tr. runs out before IL reaches ILmin. The next cycle starts, and Pch Tr. turns "ON" and Nch Tr. turns "OFF", which means IL starts increasing from ILmin. This is called continuous current mode.

In the case of PWM control system, Vout is maintained by controlling ton. During PWM control, the oscillator frequency (fosc) is being maintained constant.

As shown in Figure 2. when the step-down DC/ DC operation is constant, ILmin and ILmax during ton of Pch Tr. would be same as during toff of Pch Tr.

The current differential between ILmax and ILmin is described as $\Delta \mathrm{I}$.

```
However,
    T = 1 / fosc = ton + toff
    Duty (%) = ton / T }\times100=\mathrm{ ton }\times\mathrm{ fosc }\times10
    topen \leq toff
```

In Equation 1, "Vout $\times$ topen / L" shows the amount of current change in "OFF" state. Also, "(VIN $\left.-V_{\text {out }}\right) \times$ ton / L" shows the amount of current change at "ON" state.

## Discontinuous Mode and Continuous Mode

As illustrated in Figure 3., when lout is relatively small, topen<toff. In this case, the energy charged into L during ton will be completely discharged during toff, as a result, ILmin=0. This is called discontinuous mode.

When lout is gradually increased, eventually topen=toff and when lout is increased further, eventually ILmin>0. This is called continuous mode.


Figure 3. Discontinuous Mode


Figure 4. Continuous Mode

In the continuous mode, the solution of Equation 1 is described as tonc.

$$
\text { tonc }=T \times V_{\text {out }} / V_{\text {IN }}
$$

Equation 2

When ton<tonc, it is discontinuous mode, and when ton=tonc, it is continuous mode.

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## VFM Mode

In low output current, the IC automatically switches into VFM mode in order to achieve high efficiency. In VFM mode, ton is forced to end when the inductor current reaches the pre-set ILmax. In the VFM mode, ILmax is typically set to 180 mA . When ton reaches 1.5 times of $\mathrm{T}=1 / \mathrm{fosc}$, ton will be forced to end even if the inductor current is not reached ILmax.


Figure 5. VFM Mode

## Output Current and Selection of External Components

The following equations explain the relationship between output current and peripheral components used in the diagrams in "TYPICAL APPLICATIONS".

Ripple Current P-P value is described as IRP, ON resistance of Pch Tr. is described as RonP, ON resistance of Nch Tr. is described as Ronn, and DC resistor of the inductor is described as RL.

First, when Pch Tr. is "ON", the following equation is satisfied.

$$
\begin{equation*}
\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {OUT }}+\left(\mathrm{RoNP}+\mathrm{RL}_{\mathrm{L}}\right) \times \text { lout }+\mathrm{L} \times \mathrm{I}_{\mathrm{RP}} / \text { ton } . \tag{Equation 3}
\end{equation*}
$$

Second, when Pch Tr. is "OFF" (Nch Tr. is "ON"), the following equation is satisfied.

$$
\mathrm{L} \times \mathrm{I}_{\mathrm{RP}} / \text { toff }=\text { Ronn } \times \text { lout }+\mathrm{V}_{\text {out }}+\mathrm{RL} \times \text { lout } .
$$

Equation 4

Put Equation 4 into Equation 3 to solve ON duty of Pch Tr. (Don $=$ ton $/($ toff + ton $)$ ):

$$
\text { Don }=(\text { Vout }+ \text { Ronn } \times \text { lout }+ \text { RL } \times \text { lout }) /(\text { Vin }+ \text { Rons } \times \text { lout }- \text { Ronp } \times \text { lout }) .
$$

Equation 5

Ripple Current is described as follows:

$$
\begin{equation*}
I_{\text {RP }}=\left(V_{\text {IN }}-\text { Vout }- \text { Ronp } \times \text { lout }- \text { RL } \times \text { lout }\right) \times \text { Don } / \text { fosc } / L . \tag{Equation 6}
\end{equation*}
$$

Peak current that flows through $L$, and $L x$ Tr. is described as follows:
ILxmax $=$ lout $+\mathrm{IRP}_{\mathrm{RP}} / 2$ $\qquad$ Equation 7
$\star$ Please consider ILxmax when setting conditions of input and output, as well as selecting the external components.
$\star$ The above calculation formulas are based on the ideal operation of the ICs in continuous mode.

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## Timing Chart

## (1) Soft-start Time

## Starting-up with CE Pin

The IC starts to operate when the CE pin voltage ( $\mathrm{V}_{\mathrm{CE}}$ ) exceeds the threshold voltage. The threshold voltage is preset between CE "H" input voltage ( V сен ) and CE "L" input voltage ( $\mathrm{V}_{\text {сег }}$ ).
After the start-up of the IC, soft-start circuit starts to operate. Then, after a certain period of time, the reference voltage ( $V_{\text {REF }}$ ) in the IC gradually increases up to the specified value.


Soft-start time starts when soft-start circuit is activated, and ends when the reference voltage reaches the specified voltage.
$\star$ Soft start time is not always equal to the turn-on speed of the step-down DC/ DC converter. Please note that the turn-on speed could be affected by the power supply capacity, the output current, the inductance value and the Cout value.

## Starting-up with Power Supply

After the power-on, when VIN exceeds the UVLO released voltage (VuvLoz), the IC starts to operate. Then, softstart circuit starts to operate and after a certain period of time, $\mathrm{V}_{\text {REF }}$ gradually increases up to the specified value. Soft-start time starts when soft-start circuit is activated, and ends when $V_{\text {REF }}$ reaches the specified voltage.

$\star$ Please note that the turn-on speed of Vout could be affected by the power supply capacity, the output current, the inductance value, the Cout value and the turn-on speed of $\mathrm{V}_{\text {IN }}$ determined by $\mathrm{C}_{\mathrm{IN}}$.

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## (2) Under Voltage Lockout (UVLO) Circuit

If $V_{\text {IN }}$ becomes lower than $V_{\text {SET }}$, the step-down DC/ DC converter stops the switching operation and ON duty becomes $100 \%$, and then Vout gradually drops according to Vin.
If the $\mathrm{V}_{\text {IN }}$ drops more and becomes lower than the UVLO detector threshold (VuvLo1), the UVLO circuit starts to operate, $\mathrm{V}_{\text {REF }}$ stops, and Pch and Nch built-in switch transistors turn "OFF". As a result, Vout drops according to the Cout capacitance value and the load.
To restart the operation, VIN needs to be higher than Vuvloz. The timing chart below shows the voltage shifts of $V_{\text {REF }}, V_{L x}$ and $V_{\text {out }}$ when $V_{\text {in }}$ value is varied.

$\star$ Falling edge (operating) and rising edge (releasing) waveforms of Vout could be affected by the initial voltage of Cout and the output current of Vout.

## (3) Over Current Protection Circuit

Over current protection circuit supervises the inductor peak current (the peak current flowing through Pch Tr.) in each switching cycle, and if the current exceeds the $L_{x}$ current limit (ILxLim), it turns off Pch Tr. ILxlim of the RP507K001B is set to Typ. 1000 mA .

Notes: ILxLIM could be easily affected by self-heating or ambient environment. If the $\mathrm{V}_{\mathrm{IN}}$ drops dramatically or becomes unstable due to short-circuit, protection operation could be affected.


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## APPLICATION INFORMATION

## Typical Application

(Adjustable Output Voltage Type)


Table 1. Recommended Components

| Symbol | Value | Components | Part Number |
| :---: | :---: | :---: | :---: |
| Cin | 4.7 $\mu \mathrm{F}$ | Ceramic Capacitor | C1005X5R0J475M (TDK) <br> JMK105BBJ475MV (Taiyo Yuden) <br> GRM155R60J475ME47 (Murata) |
| Cout | 10 $\mu \mathrm{F}$ | Ceramic <br> Capacitor | GRM155R60J106ME44 (Murata) JMK105CBJ106MV (Taiyo Yuden) |
| L | $2.2 \mu \mathrm{H}$ | Inductor | LQM21PN2R2NGC (Murata) CIG21L2R2MNE (Samsung Electro-Mechanics) MIPSZ2012D2R2 (FDK) |
|  | $4.7 \mu \mathrm{H}$ |  | CIG21L4R7MNE (Samsung Electro-Mechanics) MIPS2520D4R7 (FDK) |

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## TECHNICAL NOTES

When using the RP507K001B, please consider the following points.

- AGND and PGND must be wired to the GND plane when mounting on boards.
- Ensure the $\mathrm{V}_{\mathrm{IN}}$ and AGND/ PGND lines are sufficiently robust. A large switching current flows through the AGND/ PGND lines, the VDD line, the Vout line, an inductor, and Lx. If their impedance is too high, noise pickup or unstable operation may result. Set the external components as close as possible to the IC and minimize the wiring between the components and the IC, especially between a capacitor ( $\mathrm{C}_{\mathrm{IN}}$ ) and the $\mathrm{V}_{\mathbb{I N}}$ pin. The wiring between a resistor for setting output voltage $\left(R_{1}\right)$ and an inductor $(L)$ and between $L$ and Load should be separated.
- Choose a low ESR ceramic capacitor. The capacitance of $C_{\operatorname{IN}}$ should be more than or equal to $4.7 \mu \mathrm{~F}$. The capacitance of a capacitor (Cout) should be $10 \mu \mathrm{~F}$.
- The Inductance value should be set within the range of $1.5 \mu \mathrm{H}$ to $4.7 \mu \mathrm{H}$. However, the inductance value is limited by output voltage, so please refer to the table below. The phase compensation of this IC is designed according to the Cout and $L$ values. Choose an inductor that has small DC resistance, has enough allowable current and is hard to cause magnetic saturation. If the inductance value of an inductor is extremely small, the peak current of $L_{x}$ may increase. The increased $L_{x}$ peak current reaches " $L x$ limit current" to trigger over current protection circuit even if the load current is less than 600mA.
Table 2. Set Output Voltage Range vs. Inductance Range

| Set Output Voltage (V) | Inductance |  |  |
| :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{SET}}$ | $\mathrm{L}=1.5 \mu \mathrm{H}$ | $\mathrm{L}=2.2 \mu \mathrm{H}$ | $\mathrm{L}=4.7 \mu \mathrm{H}$ |
| $0.7 \sim 1.0$ | Ok | Good | - |
| $1.1 \sim 1.7$ | - | Good | - |
| $1.8 \sim 2.5$ | - | Good | Ok |
| $2.6 \sim$ | - | Ok | Good |

- Over current protection circuit may be affected by self-heating or power dissipation environment.
- The output voltage (Vout) is adjustable by changing the $\mathrm{R}_{1}$ and $\mathrm{R}_{2}$ values as follows.

$$
V_{\text {OUT }}=V_{F B} \times\left(R_{1}+R_{2}\right) / R_{2} \quad\left(0.7 \mathrm{~V} \leq V_{\text {OUT }} \leq 5.5 \mathrm{~V}\right)
$$

- The recommended resistance values for $\mathrm{R}_{1}, \mathrm{R}_{2}$ and $\mathrm{C}_{1}$ are as follows.

Table 3. Set Output Voltage Range vs. Resistor \& Capacitor Range

| Set Output Voltage (V) | Resistor (k) |  | Capacitor (pF) |
| :---: | :---: | :---: | :---: |
| $\mathbf{V}_{\text {SET }}$ | $\mathbf{R}_{\mathbf{1}}$ | $\mathbf{R}_{\mathbf{2}}$ | $\mathbf{C}_{\mathbf{1}}$ |
| 1.0 | 120 | 180 | 22 |
| 1.2 | 180 | 180 | 22 |
| 1.5 | 270 | 180 | 22 |
| 1.8 | 240 | 120 | 22 |
| 2.5 | 380 | 120 | 15 |
| 2.8 | 275 | 75 | 15 |
| 3.3 | 270 | 60 | 15 |

$\star$ The performance of power source circuits using this IC largely depends on the peripheral circuits. When selecting the peripheral components, please consider the conditions of use. Do not allow each component, PCB pattern and the IC to exceed their respected rated values (voltage, current, and power) when designing the peripheral circuits.

## Reference PCB Layout

RP507K001B (PKG: DFN(PLP)1616-6D) PCB Layout


* R11 and R12 are arranged as a substitute for R1 so that two resistors can be connected in series.


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## TYPICAL CHARACTERISTICS


2) Output Voltage vs. Input Voltage





3) Feedback Voltage vs. Temperature RP507K001B

4) Efficiency vs. Output Current


RP507K001B Vout=3.3V


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5) Supply Current vs. Temperature

RP507K001B Vоит=1.8V (Vin=3.6V)

7) DCIDC Output Waveform

RP507K001B Vout=1.0V (Vin=3.6V)


RP507K001B Vout=3.3V $\mathrm{L}=4.7 \mu \mathrm{H}$ (MIPS2520D4R7)

6) Supply Current vs. Input Voltage RP507K001B Vout $=1.8 \mathrm{~V}$


RP507K001B Vоит=1.0V ( $\mathrm{V}_{\text {in }}=3.6 \mathrm{~V}$ )



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8) Oscillator Frequency vs. Temperature

9) Oscillator Frequency vs. Input Voltage

10) Soft-start Time vs. Temperature

11) UVLO Detector Threshold / Released Voltage vs. Temperature

UVLO Detector Threshold


UVLO Released Voltage

12) CE Input Voltage vs. Temperature

CE"H" Input Voltage(Vin=5.5V)

13) Lx Current Limit vs. Temperature

14) On Resistance of Pch Tr. vs. Temperature Temperature


CE"L" Input Voltage (Vin=2.3V)

15) On Resistance of Nch Tr. vs.


## RP507K001B

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16) Load Transient Response (Cout=10رF GRM155R60J106ME44)





RP507K001B (Vin=3.6V, Vоut=1.2V)



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RP507K001B (Vin=5.0V, Vout=3.3V)


RP507K001B ( $\mathrm{V}_{\text {In }}=5.0 \mathrm{~V}$, $\mathrm{V}_{\text {out }}=3.3 \mathrm{~V}$ )



RP507K001B (Vin=5.0V, Vоut=3.3V)


RP507K001B ( $\mathrm{V}_{\mathrm{IN}}=5.0 \mathrm{~V}$, $\mathrm{V}_{\text {out }}=3.3 \mathrm{~V}$ )


The power dissipation of the package is dependent on PCB material, layout, and environmental conditions.
The following measurement conditions are based on JEDEC STD. 51-7.

Measurement Conditions

| Item | Measurement Conditions |
| :--- | :--- |
| Environment | Mounting on Board (Wind Velocity $=0 \mathrm{~m} / \mathrm{s}$ ) |
| Board Material | Glass Cloth Epoxy Plastic (Four-Layer Board) |
| Board Dimensions | $76.2 \mathrm{~mm} \times 114.3 \mathrm{~mm} \times 0.8 \mathrm{~mm}$ |
| Copper Ratio | Outer Layer (First Layer): Less than 95\% of 50 mm Square <br> Inner Layers (Second and Third Layers): Approx. 100\% of 50 mm Square <br> Outer Layer (Fourth Layer): Approx. 100\% of 50 mm Square |
| Through-holes | $\phi 0.2 \mathrm{~mm} \times 15 \mathrm{pcs}$ |

Measurement Result
$\left(\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{Tjmax}=125^{\circ} \mathrm{C}\right)$

| Item | Measurement Result |
| :--- | :---: |
| Power Dissipation | 1580 mW |
| Thermal Resistance ( $\theta \mathrm{ja}$ ) | $\theta \mathrm{ja}=63^{\circ} \mathrm{C} / \mathrm{W}$ |
| Thermal Characterization Parameter ( $\psi \mathrm{jj})$ ) | $\psi j \mathrm{jt}=33^{\circ} \mathrm{C} / \mathrm{W}$ |

Өja: Junction-to-Ambient Thermal Resistance
$\psi j$ t: Junction-to-Top Thermal Characterization Parameter


Power Dissipation vs. Ambient Temperature


Measurement Board Pattern


DFN(PLP)1616-6D Package Dimensions (Unit: mm)

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## Sales \& Support Offices

## Ricoh Electronic Devices Co., Ltd.

Shin-Yokohama Office (International Sales)
2-3, Shin-Yokohama 3-chome, Kohoku-ku, Yokohama-shi, Kanagawa, 222-8530, Japan Phone: +81-50-3814-7687 Fax: +81-45-474-0074
Ricoh Americas Holdings, Inc.
675 Campbell Technology Parkway, Suite 200 Campbell, CA 95008, U.S.A.
Phone: +1 -408-610-3105
Ricoh Europe (Netherlands) B.V.
Semiconductor Support Centre
Prof. W.H. Keesomlaan 1, 1183 DJ Amstelveen, The Netherlands
Phone: +31-20-5474-309
Ricoh International B.V. - German Branch
Semiconductor Sales and Support Centre
Oberrather Strasse 6, 40472 Düsseldorf, Germany
Phone: +49-211-6546-0
Ricoh Electronic Devices Korea Co., Ltd. 3F, Haesung Bldg, 504, Teheran-ro, Gangnam-gu, Seoul, 135-725, Korea Phone: +82-2-2135-5700 Fax: +82-2-2051-5713
Ricoh Electronic Devices Shanghai Co., Ltd.

Ricoh Electronic Devices Shanghai Co., Ltd.
Shenzhen Branch
1205, Block D(Jinlong Building), Kingkey 100, Hongbao Road, Luohu District
henzhen, China
Ricoh Electronic Devices Co., Ltd.
Taipei office
Room 109, 10F-1, No.51, Hengyang Rd., Taipei City, Taiwan
Phone: +886-2-2313-1621/1622 Fax: +886-2-2313-1623 $\square$

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[^0]:    ${ }^{(1)}$ This is an approximate value, because output current depends on conditions and external components.

[^1]:    ${ }^{(1)}$ Auto-discharge function quickly lowers the output voltage to 0 V , when the chip enable signal is switched from the active mode to the standby mode, by releasing the electrical charge accumulated in the external capacitor.

[^2]:    ${ }^{(1)}$ No. 2 pin and No. 3 pin must be wired to the GND plane when mounting on boards.

[^3]:    ${ }^{(1)}$ Refer to POWER DISSIPATION for detailed information
    ${ }^{(2)} V_{\text {SET }}=$ Set Output Voltage

[^4]:    (1) $\mathrm{V}_{\text {SET }}=$ Set Output Voltage
    (2) It starts when the CE pin is low and ends when $V_{\text {Out }} \leq \mathrm{V}_{\text {SET }} \times 0.1$.

[^5]:    * The tab on the bottom of the package shown by circle is a substrate potential (GND). It is recommended that this tab be connected to the ground plane on the board but it is possible to leave the tab floating.

