

NTE1892 & NTE1892A Integrated Circuit Dual Bi-Directional Motor Driver with Brake Function and Thermal Shutdown

Description:

The NTE1892 and NTE1892A are bi-directional motor drivers in a 12-Lead SIP type package and consists of two full bridge drivers designed for use in a two DC motor control circuit.

Features:

- Two Separate Full Bridge Drivers (Only one circuit can be switched by the Select (S_F) Input).
- Wide Operating Voltage Range: V_{CC} = 4V to 16V
- TTL, PMOS, CMOS Outputs, Capable of Direct Drive
- Low Output Saturation Voltage
- Built-in Clamp Diode
- High Output Drive Current: I_Omax = ±2A
- Braking Mode Input
- Internal Thermal Shutdown Protection

Applications:

- Audio Tape Deck Player
- Radio/Cassette Player
- Video Cassette Recorder
- Home Equipment Use

Absolute Maximum Ratings: $(T_A = +25^{\circ}C)$ unless otherwise specified)	
Supply Voltage 1, V _{CC(1)}	0.5V to +18V
Supply Voltage 2 (NTE1892 Only, Note 1), V _{CC(2)}	
Driver Supply Voltage, V _{CC} ,	
Input Voltage, V _i	
Output Voltage, V _O	$\cdot \cdot \cdot -2V$ to $V_{CC}+2.5V$
Peak Output Current (top = 10ms, relative cycle 0.2Hz Max), Iomax	
NTE1892	
NTE1892A	
Continuous Output Current 1, I _{O(1)}	
Continuous Output Current 2 (NTÉ1892 Only, Note 1), I _{O(2)}	± 600mA
Power Dissipation ($T_A = +75^{\circ}C$), P_D	
NTE1892	1.6W
NTE1892A	830mw
Operating Temperature Range, Topr	400 1 7500
NTE1892	
NTE1892A	
Storage Temperature Range, T _{stg}	55° t0 +125°C
Note 1. With external heat sink (3000mm ² x 1.5mm)	

Recommended Operating Conditions: $(T_A = +25^{\circ}C \text{ unless otherwise specified})$

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Supply Voltage	V _{CC}		4	12	16	V
Output Current	Io		-	-	±300	mA
High-Level Input Voltage	V _{IH}	Input S ₁ , S ₂ , S _E	2	-	V_{CC}	V
Low-Level Input Voltage	V _{IL}	Input S ₁ , S ₂ , S _E	0	-	0.4	V
Motor Braking Interval NTE1892	t _s		10	100	-	ms
NTE1892A			100	-	_	ms
Thermal Shutdown Temperature	t _{j(shut)}	V _{CC} ≥ 7V	_	150	-	°C

Electrical Characteristics: $(T_A = +25^{\circ}C \text{ unless otherwise specified})$

Parameter	Symbol	Те	Min	Тур	Max	Unit	
Output Leakage Current	I _{O(LEAK)}	$V_{CC} = V_{CC'} = 18V,$ $V_{S1} = V_{S2} = 0V,$	V _O = 18V	_	_	100	μΑ
		$V_{S1} - V_{S2} - 0V$, $V_{SE} = 0V \text{ or } 2V$	$V_O = 0V$	_	_	-100	μΑ
High-Level Output Voltage	V _{OH}	$V_{CC} = V_{CC'} = 12V$	$I_{OH(1)} = -200mA$	10.8	-	-	V
			$I_{OH(1)} = -500mA$	10.7	-	-	V
Low-Level Output Voltage	V _{OL}	$V_{CC} = V_{CC'} = 12V I_{OL} = 200 \text{mA}$		-	-	0.5	V
			I _{OL} = 500mA	-	-	1.35	V
High-Level Input Current	I _{IH}	$V_{CC} = V_{CC'} = 12V,$	50	-	120	μΑ	
Low-Level Input Current	I _{IL}	$V_{CC} = V_{CC'} = 12V, V_i = 0V$			-	120	μΑ
Supply Current	I _{CC}	$V_{CC} = V_{CC'} = 12V$	$V_{SE} = 0V, V_{S1} = V_{S2} = 0V$	-	_	10	mA
			$V_{SE} = 0V, V_{S1} = 0V, V_{S2} = 2V$	-	-	20	mA

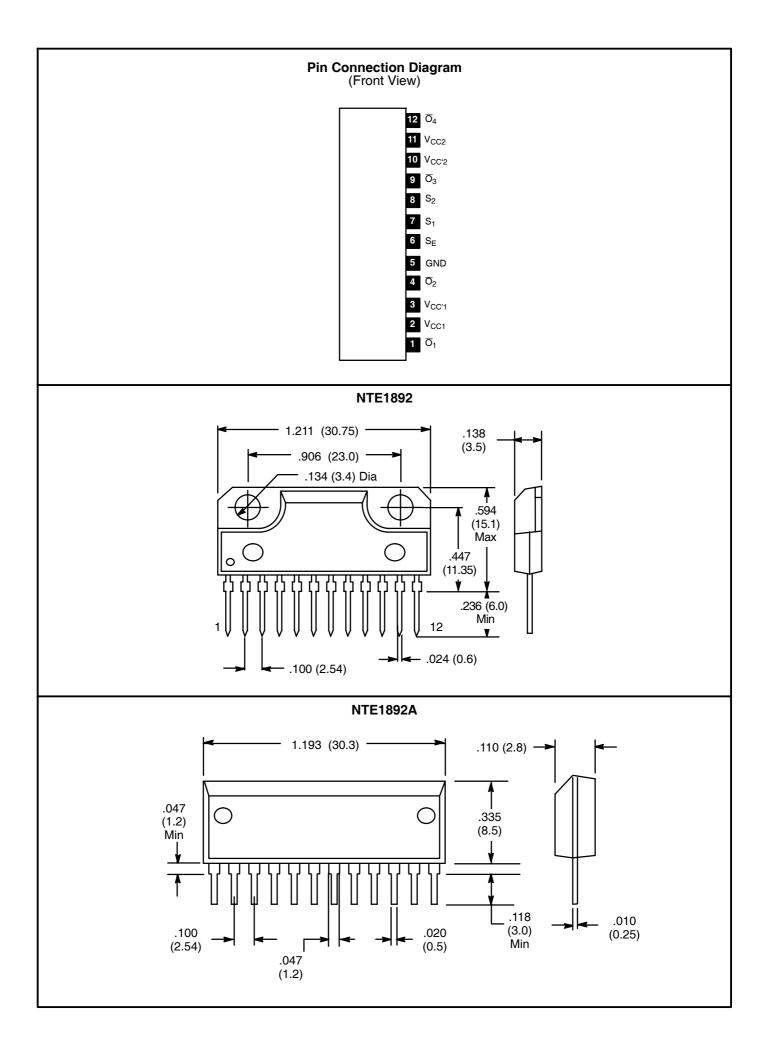
Function:

The NTE1892/NTE1892A, two full bridge motor driver, has the logic circuitry and the quasi-darlington power driver for bi-directional control of two DC motors operating at currents up to 2A.

The input S_E selects one of the bridges and S_1 and S_2 determines the output polarity.

Logic Truth Table:

Input			Output				Note		
S _E	S ₁	S ₂	<u></u> 0 ₁	O ₂	O ₃	\overline{O}_4	Output \overline{O}_1 , \overline{O}_2	Output \overline{O}_3 , \overline{O}_4	
0	0	0	OFF	OFF	OFF	OFF	OPEN	OPEN	
0	1	0	1	0	OFF	OFF	Motor Forward	OPEN	
0	0	1	0	1	OFF	OFF	Motor Reverse	OPEN	
0	1	1	0	0	OFF	OFF	BRAKING	OPEN	
1	0	0	OFF	OFF	OFF	OFF	OPEN	OPEN	
1	1	0	OFF	OFF	1	0	OPEN	Motor Forward	
1	0	1	OFF	OFF	0	1	OPEN	Motor Reverse	
1	1	1	OFF	OFF	0	0	OPEN	BRAKING	



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