High performance multiplexer/demultiplexer switch for Thunderbolt applications

Rev. 4 — 27 March 2014

**Product data sheet** 

## 1. General description

The CBTL05024 is a multiplexer/demultiplexer switch chip optimized to interface the Thunderbolt/MiniDP connector with Thunderbolt systems. It supports 10.3125 Gbit/s Thunderbolt or DisplayPort v1.2 channels.

The TB MUX is a 3 : 1 switch that selects between Thunderbolt data path and DisplayPort v1.2 side-band signals — either DDC or AUX.

The DP MUX is a 2 : 1 switch that selects between DP ML (DisplayPort Main Link) and LS TX/RX signals. Both LSTX and LSRX are the side-band signals for Thunderbolt channel.

This chip also includes HPD and CA\_DET buffers for HPD\_IN and CA\_DET control signals.

CBTL05024 is powered by a 3.3 V supply and it is available in a 3 mm  $\times$  3 mm HVQFN24 package with 0.4 mm pitch.

## 2. Features and benefits

#### 2.1 TB MUX 3 : 1 switch

- This 3 : 1 switch is implemented by two cascaded 2 : 1 switches
  - The first 2 : 1 10G MUX is controlled by TB\_ENA, AUXIO\_EN and DP\_PD pins
  - The second 2 : 1 AUX MUX is controlled by CA\_DET signal multiplexing of the 720 Mbit/s Differential FAUX (or 1 Mbit/s AUX) and DDC (Direct Display Control) signals
  - When CA\_DET is HIGH, DDC path is selected
- Differential TB channel
  - Low insertion loss: –1.3 dB at 5 GHz
  - ◆ Low return loss: < -20 dB at 5 GHz
  - Low ON-state resistance: 8  $\Omega$
  - Bandwidth: 10 GHz
  - ◆ Low off-state isolation: –20 dB at 5 GHz
  - Low crosstalk: –36 dB at 5 GHz
  - Differential input voltage V<sub>ID</sub>: 1.2 V (maximum)
- Differential AUX channel
  - Low insertion loss: -1.1 dB at 5 MHz; -1.8 dB at 360 MHz
  - Low return loss: –18 dB at 5 MHz; –16 dB at 360 MHz



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- Low ON-state resistance: 13  $\Omega$  (typical); 16  $\Omega$  (maximum)
- Bandwidth: 3 GHz
- ◆ Low off-state isolation: –80 dB at 5 MHz; –55 dB at 360 MHz
- ◆ Low crosstalk: –26 dB at 2.7 GHz
- Common-mode input voltage V<sub>IC</sub>: 0 V to 3.3 V
- Differential input voltage V<sub>ID</sub>: 1.4 V (maximum)
- DDC channel
  - ON-state resistor: 50 Ω (maximum)
  - 100 kHz 3.3 V voltage swing signal
- Both AUXIO+ and AUXIO– outputs have 85 kΩ (±20 %) resistors
  - The 85 kΩ AUXIO– pull-up resistor
  - The 85 k $\Omega$  AUXIO+ pull-down resistor is always present

## 2.2 **DP MUX 2 : 1 switch**

- Multiplexes between differential DP ML signal and LSTX/LSRX signals
- The DP ML (DisplayPort Main Link) runs up to HBR2 data rate of 5.4 Gbit/s
- The low speed DC-coupled signals LSTX and LSRX are 3.3 V single-ended signals that operate at 1 Mbit/s
- 5.4 Gbit/s DP-DPMLO path for DP MUX
  - ◆ Low insertion loss for DP-DPMLO path: -1.2 dB at 2.7 GHz
  - Low return loss for DP-DPMLO path: –15 dB at 2.7 GHz
  - Low ON-state resistance for DP-DPMLO path: 9  $\Omega$
  - High bandwidth: 5.5 GHz
  - ◆ Low off-state isolation: –20 dB at 2.7 GHz
  - ◆ Low crosstalk: –25 dB at 2.7 GHz
  - Common-mode input voltage VIC: 0 V to 3.3 V
  - Differential input voltage V<sub>ID</sub>: 1.4 V (maximum)
- LS-DPMLO path for DP MUX
  - ◆ Low insertion loss: single-ended insertion loss (ON) is -1.0 dB at 5 MHz
  - ◆ Low return loss: single-ended return loss (ON) is -20 dB at 5 MHz
  - Low ON-state resistance: 16  $\Omega$  (typical) for V<sub>DD</sub> = 3.3 V
  - High bandwidth: Single-ended –3 dB bandwidth is 1 GHz
  - Low off-state isolation: single-ended insertion loss (OFF) is -60 dB at 5 MHz
  - Low crosstalk: –40 dB at 5 GHz

## 2.3 General

- The input of the HPD (Hot Plug Detect) buffer is 5 V tolerant
- HPDOUT and CA\_DETOUT buffers
  - $\blacklozenge$  CA\_DET input leakage current < 0.1  $\mu A$  to prevent driving the 1  $M\Omega$  pull-down to a HIGH level
- Integrated LSRX buffer with 1 MΩ pull-down resistor (R1) on the LSRX buffer input
- Integrated 8.75 kΩ pull-up resistor (R4) on the LSTX pin

- When AUXIO\_EN = 1, TB\_ENA = 0 and DP\_PD = 1, the CBTL05024 is in Detect mode
  - ◆ AUXIO+ and AUXIO- of the TB MUX are disabled
  - LS path is selected in DP MUX
  - CA\_DET and HPD buffers are on
  - When the CBTL05024 is in Detect mode, this chip consumes < 18  $\mu$ W
- Patent-pending high bandwidth analog pass-gate technology
- Very low intra-pair differential skew (5 ps typical)
- Back current protection on connector pins (AUXIO+/-, DPMLO+/-, CA\_DET and HPD pins)
- All channels support rail-to-rail input voltage
- All CMOS input buffer with hysteresis
- Single 3.3 V ± 10 % power supply
- HVQFN24 3 mm × 3 mm package, 0.4 mm pitch, exposed center pad for thermal relief and electrical ground
- ESD: 2000 V HBM, 1000 V CDM
- Operating temperature range –20 °C to 85 °C

## 3. Ordering information

#### Table 1.Ordering information

Type number	Topside	Package	kage				
	marking	Name	Description	Version			
CBTL05024BS	024	HVQFN24	plastic thermal enhanced very thin quad flat package; no leads; 24 terminals; body $3 \times 3 \times 0.85$ mm <sup>[1]</sup>	SOT905-1			

[1] Maximum package height is 1 mm.

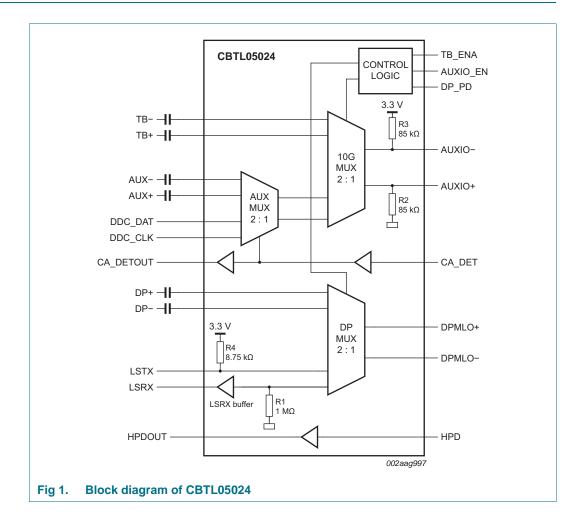
## 3.1 Ordering options

#### Table 2.Ordering options

Type number	Orderable part number	Package	Packing method	Minimum order quantity	Temperature
CBTL05024BS	CBTL05024BSHP	HVQFN24	Reel 13" Q2/T3 *standard mark SMD	6000	$T_{amb} = -20 \ ^{\circ}C \ to \ +85 \ ^{\circ}C$

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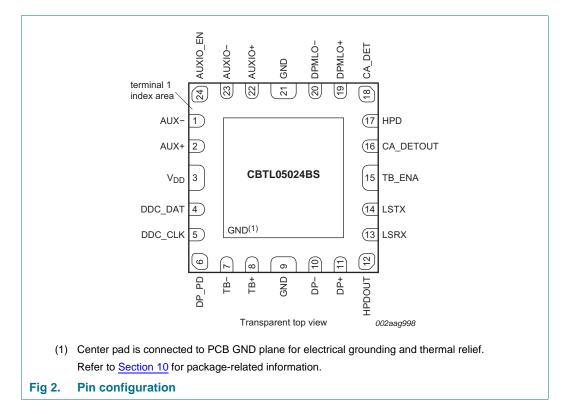
## 4. Block diagram



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## 5. Pinning information

## 5.1 Pinning



## 5.2 Pin description

Symbol	Pin	Туре	Description
Data path sig	nals		1
AUX–	1	differential I/O	AUX differential signals. The input to this pin must
AUX+	2	differential I/O	be AC-coupled externally.
TB-	7	differential I/O	Thunderbolt differential signals. These output
TB+	8	differential I/O	signals must be AC-coupled externally.
AUXIO-	23	differential I/O	Differential signals for TB MUX.
AUXIO+	22	differential I/O	
DDC_CLK	5	single-ended I/O	Pair of single-ended terminals for DDC clock and
DDC_DAT	4	single-ended I/O	data signals.
DP-	10	differential I/O	High-speed differential pair. The input to this pin
DP+	11	differential I/O	must be AC-coupled externally.
DPMLO-	20	differential I/O	Differential signals for DP MUX.
DPMLO+	19	differential I/O	
LSRX	13	single-ended output	Single-ended TB low speed receive signal.
LSTX	14	single-ended I/O	Single-ended TB low speed transmit signal.
Control signa	ls		
HPDOUT	12	CMOS output	Output buffer for HPD.
HPD	17	CMOS input	HPD input with 5 V tolerance.
CA_DET	18	CMOS input	When CA_DET = HIGH, DDC_CLK and DDC_DAT is selected. When CA_DET = LOW, AUX path is selected.
CA_DETOUT	16	CMOS output	3.3 V CMOS output buffer for CA_DET.
TB_ENA	15	CMOS input	The control input signal to enable Thunderbolt path for TB MUX.
AUXIO_EN	24	CMOS input	The control signal for TB MUX.
DP_PD	6	CMOS input	The control signal for DP MUX. This MUX must work during initial power-up that might have $V_{DD} = 2.3$ V.
3.3 V supply o	ption		1
V <sub>DD</sub>	3	Power	3.3 V supply. Pin 3 must be connected to system power supply.
Ground conne	ections		·
GND	9, 21	Ground	Supply ground (0 V).
GND	center pad	Ground	The center pad must be connected to GND plane for both electrical grounding and thermal relief.

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## 6. Functional description

Refer to Figure 1 "Block diagram of CBTL05024".

The following sections describe the individual block functions and capabilities of the device in more detail.

## 6.1 Buffer function tables

Table 4. HPD bu	iffer
HPD input	HPDOUT output
0	0
1	1

#### Table 5.CA\_DET buffer

CA_DET input	CA_DETOUT output
0	0
1	1

## 6.2 AUX MUX function table

#### Table 6. 2 : 1 AUX MUX function

CA_DET input	AUXIO
0	AUX
1	DDC

### 6.3 Operation modes of both DPML MUX and TB MUX

Table 7. Operation modes								
AUXIO_EN	TB_ENA	DP_PD	CA_DET	AUXIO	DPMLO	Modes	R3	R2
0	Х	0	Х	3-state	3-state	DP Standby mode	ON	ON
0	Х	1	Х	3-state	LS	Standby mode	ON	ON
1	0	0	0	AUX input	DP input	DP mode	ON	ON
1	0	0	1	DDC	DP input	DP++ mode	ON	ON
1	0	1	Х	3-state	LS	Detect mode	ON	ON
1	1	0	1	ТВ	DP input	Test mode <sup>[1]</sup>	OFF	ON
1	1	0	0	3-state	3-state	Sleep mode	OFF	ON
1	1	1	Х	ТВ	LS	TB mode	OFF	ON

[1] HPD must be LOW during Test mode.

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#### **Limiting values** 7.

#### Table 8. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage	[1]	-0.3	+4.6	V
VI	input voltage	[1]	-0.3	+5.5	V
T <sub>stg</sub>	storage temperature		-65	+150	°C
V <sub>ESD</sub>	electrostatic discharge	HBM [2]	-	2000	V
voltage		CDM [3]	-	1000	V

[1] All voltage values, except differential voltages, are with respect to network ground terminal.

- Human Body Model: ANSI/ESDA/JEDEC JDS-001-2012 (Revision of ANSI/ESDA/JEDEC JS-001-2011), [2] ESDA/JEDEC Joint standard for ESD sensitivity testing, Human Body Model - Component level; Electrostatic Discharge Association, Rome, NY, USA; JEDEC Solid State Technology Association, Arlington, VA, USA.
- Charged Device Model: JESD22-C101E December 2009 (Revision of JESD22-C101D, October 2008), [3] standard for ESD sensitivity testing, Charged Device Model - Component level; JEDEC Solid State Technology Association, Arlington, VA, USA.

#### **Recommended operating conditions** 8.

Table 9.	Operating conditions						
Symbol	Parameter	Conditions	Min	Тур	Max	Unit	
V <sub>DD</sub>	supply voltage	3.3 V supply option	3.0	3.3	3.6	V	
		initial supply voltage [1] before power supply negotiation done	2.3	-	-	V	
VI	input voltage	CMOS inputs	-0.3	-	+5.5	V	
		MUX I/O pins	-0.3	-	V <sub>DD</sub> + 0.3	V	
T <sub>amb</sub>	ambient temperature	operating in free air	-20	-	+85	°C	

#### Operating conditions Table 0

During power supply negotiation only a limited supply voltage is available. The control logic and [1] multiplexers must be in full function with degraded performance. The channel between LSTX/LSRX and DPMLO+/– must work. The initial R<sub>on</sub> of DP MUX in Table 14 should be < 50  $\Omega$ .

## 9. Characteristics

## 9.1 Device general characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>DD</sub>	supply current <sup>[1]</sup>	TB mode; V <sub>DD</sub> = 3.6 V	-	0.25	0.35	mA
P <sub>cons</sub> power consumption[1]	power consumption <sup>[1]</sup>	TB mode; $V_{DD}$ = 3.6 V; AUXIO_EN = 1, TB_ENA = 1 and DP_PD = 1	-	0.825	1.26	mW
		DP or DP++ modes; AUXIO_EN = 1, TB_ENA = 0 and DP_PD = 0	-	0.66	1.00	mW
		Sleep or DP Standby modes; (AUXIO_EN = 1, TB_ENA = 1 and CA_DET = DP_PD = 0) for Sleep mode or (AUXIO_EN = 0 and DP_PD = 0) for DP Standby mode	-	1	18	μW
		Detect mode; AUXIO_EN = 1, TB_ENA = 0 and DP_PD = 1	-	1	18	μW
		Standby mode; AUXIO_EN = 0, TB_ENA = X and DP_PD = 1	-	1	18	μW
startup	start-up time	supply voltage valid to channel specified operating characteristics	-	100	500	μS
rcfg	reconfiguration time	DP_PD, AUXIO_EN, TB_ENA or CA_DET state change to channel specified operating characteristics	[2] -	50	100	μS

[1] Do not include current through R4.

[2] Outputs are undefined during reconfiguration, including enable and disable time of the multiplexers.

## 9.2 3:1 TB MUX channel characteristics

### Table 11. TB channel of 2 : 1 10G MUX dynamic and static characteristics

Parameter	Conditions	Min	Тур	Max	Unit	
differential insertion loss	channel is OFF			I		
	f = 5 GHz	-	-20	-	dB	
	f = 100 MHz	-	-55	-	dB	
	channel is ON			I		
	f = 5 GHz	-	-1.3	-	dB	
	f = 100 MHz	-	-1	-	dB	
differential return loss	f = 5 GHz	-	-20	-	dB	
	f = 100 MHz	-	-22	-	dB	
differential near-end crosstalk	adjacent channels are ON					
	f = 5 GHz	-	-18	-	dB	
	f = 2.7 GHz	-	-25	-	dB	
	f = 100 MHz	-	-60	-	dB	
	f = 1 MHz	-	-70	-	dB	
ON-state resistance	V <sub>DD</sub> = 3.3 V; V <sub>I</sub> = 3.3 V; I <sub>I</sub> = 5 mA	-	8.5	12	Ω	
	differential insertion loss differential return loss differential near-end crosstalk	$\begin{array}{ c c c c } \mbox{differential insertion loss} & \begin{tabular}{ c c c } \mbox{channel is OFF} \\ \hline f = 5 \mbox{ GHz} \\ \hline f = 100 \mbox{ MHz} \\ \end{tabular} \\ tabula$	$ \begin{array}{ c c c c } \mbox{differential insertion loss} & \begin{tabular}{ c c c } \mbox{channel is OFF} & \end{tabular} & tab$	$ \begin{array}{ c c c c c } \mbox{differential insertion loss} & \begin{tabular}{ c c c c } \mbox{channel is OFF} & \end{tabular} & \end$	$ \begin{array}{ c c c c c } \mbox{differential insertion loss} & \begin{tabular}{ c c c c } \mbox{channel is OFF} & & & -20 & -& & & & & & & & & & & & & & & & & &$	

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#### Table 11. TB channel of 2 : 1 10G MUX dynamic and static characteristics ... continued

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
B <sub>-3dB</sub>	-3 dB bandwidth	differential	-	10	-	GHz
t <sub>PD</sub>	propagation delay	between AUXIO and TB	-	70	-	ps
t <sub>sk(dif)</sub>	differential skew time	intra-pair	-	5	-	ps
VI	input voltage	TB+/TB- and AUXIO+/AUXIO-	0	-	V <sub>DD</sub> + 0.3	V
V <sub>ID</sub>	differential input voltage	TB+/TB- and AUXIO+/AUXIO-	-	-	1.2	V

#### Table 12. AUX - AUXIO channel of AUX MUX dynamic and static characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit		
DDIL	differential insertion loss	channel is OFF						
		f = 5 MHz	-	-80	-	dB		
		f = 360 MHz	-	-60	-	dB		
		channel is ON			I			
		f = 5 MHz	-	-1.1	-	dB		
		f = 360 MHz	-	-1.2	-	dB		
DDRL	differential return loss	f = 5 MHz	-	-19	-	dB		
		f = 360 MHz	-	-18	-	dB		
DDNEXT	differential near-end crosstalk	adjacent channels are ON						
		f = 5 GHz	-	-18	-	dB		
		f = 2.7 GHz	-	-25	-	dB		
		f = 100 MHz	-	-60	-	dB		
		f = 1 MHz	-	-70	-	dB		
R <sub>on</sub>	ON-state resistance	$\label{eq:VDD} \begin{array}{l} V_{DD} = 3.3 \text{ V}; \text{ I}_{I} = 10 \text{ mA}; \\ V_{IC} = 0.9 V_{DD} \text{ for AUXIO-}; \\ V_{IC} = 0.1 V_{DD} \text{ for AUXIO+} \end{array}$	-	13	16	Ω		
B <sub>-3dB</sub>	-3 dB bandwidth	differential	-	3	-	GHz		
t <sub>PD</sub>	propagation delay	between AUX and AUXIO	-	70	-	ps		
t <sub>sk(dif)</sub>	differential skew time	intra-pair	-	5	-	ps		
VI	input voltage	AUX+/AUX- and AUXIO+/AUXIO-	0	-	V <sub>DD</sub>	V		
V <sub>IC</sub>	common-mode input voltage	AUX+/AUX- and AUXIO+/AUXIO-	0	-	V <sub>DD</sub>	V		
V <sub>ID</sub>	differential input voltage	AUX+/AUX- and AUXIO+/AUXIO-	-	-	1.4	V		
I <sub>LIH</sub>	HIGH-level input leakage current	AUX+/AUX- pins; $V_{DD}$ = max; $V_{I}$ = $V_{DD}$	-	-	±1	μA		
I <sub>LIL</sub>	LOW-level input leakage current	AUX+/AUX- pins; $V_{DD}$ = max; $V_{I}$ = GND	-	-	±1	μA		
		1						

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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Oymbol	T di difficici	Certaitions		'yp	Max	onic
Ron	ON-state resistance	$V_{DD} = 3.3 \text{ V}; I_I = 10 \text{ mA}$	-	35	50	Ω
C <sub>in</sub>	input capacitance	$V_{DD} = 3.3 \text{ V}; V_I = 3.3 \text{ V}$	-	0.2	-	pF
t <sub>PD</sub>	propagation delay	between DDC and AUXIO	-	70	-	ps
I <sub>LIH</sub>	HIGH-level input leakage current	DDC_DAT and DDC_CLK pins; $V_{DD}$ = max; $V_{I}$ = $V_{DD}$	-	-	±1.5	μA
I <sub>LIL</sub>	LOW-level input leakage current	DDC_DAT and DDC_CLK pins; $V_{DD}$ = max; $V_{I}$ = GND	-	-	±1.5	μA

#### Table 13. DDC - AUXIO channel of AUX MUX dynamic and static characteristics

## 9.3 DP MUX channel characteristics

#### Table 14. Channel dynamic and static characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit	
DDIL	differential insertion loss	DP-DPMLO path; channel is OFF					
		f = 2.7 GHz	-	-20	-	dB	
		f = 1.35 GHz	-	-35	-	dB	
		f = 100 MHz	-	-50	-	dB	
		DP-DPMLO path; channel is ON				I	
		f = 2.7 GHz	-	-1.2	-	dB	
		f = 1.35 GHz	-	-1.1	-	dB	
		f = 100 MHz	-	-0.8	-	dB	
$\alpha_{il(se)}$	single-ended insertion loss	LS-DPMLO path; channel is OFF; f = 5 MHz	-	-60	-	dB	
		LS-DPMLO path; channel is ON; f = 5 MHz	-	-1	-	dB	
DDRL	differential return loss	DP-DPMLO path					
		f = 2.7 GHz	-	-15	-	dB	
		f = 100 MHz	-	-20	-	dB	
$\alpha_{rl(se)}$	single-ended return loss	LS-DPMLO path; f = 5 MHz	-	-18	-	dB	
DDNEXT	differential near-end crosstalk	adjacent channels are ON					
		f = 5 GHz	-	-18	-	dB	
		f = 2.7 GHz	-	-25	-	dB	
		f = 100 MHz	-	-60	-	dB	
		f = 1 MHz	-	-70	-	dB	
R <sub>on</sub>	ON-state resistance	DP-DPMLO path; $V_{DD}$ = 3.3 V; I <sub>I</sub> = 5 mA	-	9	12	Ω	
		LS-DPMLO path; $V_{DD}$ = 3.3 V; I <sub>I</sub> = 5 mA	-	16	22	Ω	
		initial ON-state resistance before power supply negotiation done; $V_{DD} = 2.3 \text{ V}; I_I = 5 \text{ mA}$	-	35	50	Ω	
B <sub>-3dB</sub>	-3 dB bandwidth	differential; DP-DPMLO path	-	5.5	-	GHz	
		single-ended; LS-DPMLO path	-	1	-	GHz	
t <sub>PD</sub>	propagation delay	between DP+/DP- and DPMLO+/DPMLO-	-	100	-	ps	
t <sub>sk(dif)</sub>	differential skew time	intra-pair	-	5	-	ps	

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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
VI	input voltage	LSTX/LSRX to DPMLO+/DPMLO- channel	-0.3	-	V <sub>DD</sub> + 0.3	V
V <sub>IC</sub>	common-mode input voltage	DP+/DP- and DPMLO+/DPMLO-	0	-	V <sub>DD</sub>	V
V <sub>ID</sub>	differential input voltage	DP+/DP- to DPMLO+/DPMLO- channel	-	-	1.4	V
I <sub>LIH</sub>	HIGH-level input leakage current	DP+/DP- and DPMLO+ pins; $V_{DD}$ = max; $V_{I}$ = $V_{DD}$	-	-	±1	μA
		DPMLO- pins; $V_{DD}$ = max; $V_{I}$ = $V_{DD}$	-	-	±5	μA
I <sub>LIL</sub>	LOW-level input leakage current	DP+/DP- and DPMLO+/DPMLO- pins; $V_{DD}$ = max; $V_{I}$ = GND	-	-	±1	μA

#### Table 14. Channel dynamic and static characteristics ...continued

## 9.4 Control signals characteristics

#### Table 15. CA\_DET input buffer characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>IH</sub>	HIGH-level input voltage		2	-	-	V
V <sub>IL</sub>	LOW-level input voltage		-	-	0.8	V
ILI		measured with input at V <sub>IH</sub> = V <sub>DD</sub> [1] and V <sub>IL</sub> = 0 V	-	-	0.1	μA

[1] The leakage current on CA\_DET pin must not drive the 1 M $\Omega$  pull-down to a HIGH level.

#### Table 16. HPD input buffer characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>IH</sub>	HIGH-level input voltage		2	-	5	V
V <sub>IL</sub>	LOW-level input voltage		-	-	0.8	V

#### Table 17. TB\_ENA, DP\_PD or AUXIO\_EN input characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>IH</sub>	HIGH-level input voltage	CMOS inputs	$0.7  imes V_{DD}$	-	-	V
V <sub>IL</sub>	LOW-level input voltage	CMOS inputs	-	-	$0.3\times V_{DD}$	V
ILI	input leakage current	measured with input at $V_{IH} = V_{DD}$ and $V_{IL} = 0 V$	-	1	10	μA

#### Table 18. CA\_DETOUT and HPDOUT output buffer characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>OL</sub>	LOW-level output voltage	$I_{OL} = 2 \text{ mA}; V_{DD} = 3 \text{ V}$	0	-	0.4	V
V <sub>OH</sub>	HIGH-level output voltage	pull-up voltage; $I_{OH} = -2 \text{ mA}$ ; $V_{DD} = 3 \text{ V}$	2.5	-	-	V
t <sub>PD</sub>	propagation delay	load capacitance $C_L = 5 \text{ pF}$	-	50	100	ns

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## 9.5 Integrated LSRX buffer characteristics

#### Table 19. LSRX buffer characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>th(LH)</sub>	positive-going threshold voltage	input; V_{DD} = 3.3 V $\pm$ 10 %	0.9	1.1	1.24	V
		input; $V_{DD} = 2.3 V$	0.8	0.9	1.02	V
V <sub>th(HL)</sub>		input; V_{DD} = 3.3 V $\pm$ 10 %	0.58	0.7	0.84	-
		input; $V_{DD} = 2.3 V$	0.5	0.57	0.63	V
V <sub>OL</sub>	LOW-level output voltage	I <sub>OL</sub> = 2 mA; V <sub>DD</sub> = 3 V	-	0.2	0.4	V
		$I_{OL} = 0.5 \text{ mA}; V_{DD} = 2.3 \text{ V}$	-	0.1	0.2	V
V <sub>OH</sub>	HIGH-level output voltage	pull-up voltage; $I_{OH} = -2 \text{ mA}$ ; V <sub>DD</sub> = 3 V	2.5	-	-	V
		pull-up voltage; $I_{OH} = -0.5 \text{ mA}$ ; $V_{DD} = 2.3 \text{ V}$	2.1	-	-	V
t <sub>PD</sub>	propagation delay	load capacitance $C_L = 8 pF$	-	2	10	ns

### 9.6 Bias resistor characteristics

#### Table 20. Characteristics of AUXIO+ pin in DP/DP++ mode

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
R <sub>pd</sub>	pull-down resistance	resistor R2; AUXIO_EN = 1, TB_ENA = DP_PD = 0	68	85	102	kΩ

#### Table 21. Characteristics of AUXIO- pin in DP/DP++ mode

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
R <sub>PU</sub>	pull-up resistance	resistor R3;	68	85	102	kΩ
		$AUXIO_EN = 1$ , $TB_ENA = DP_PD = 0$				

#### Table 22. Characteristics of DPMLO- pin in TB mode

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
R <sub>pd</sub>	pull-down resistance	resistor R1; AUXIO_EN = TB_ENA = DP_PD = 1	0.8	1	1.2	MΩ

#### Table 23. Characteristics of LSTX pin

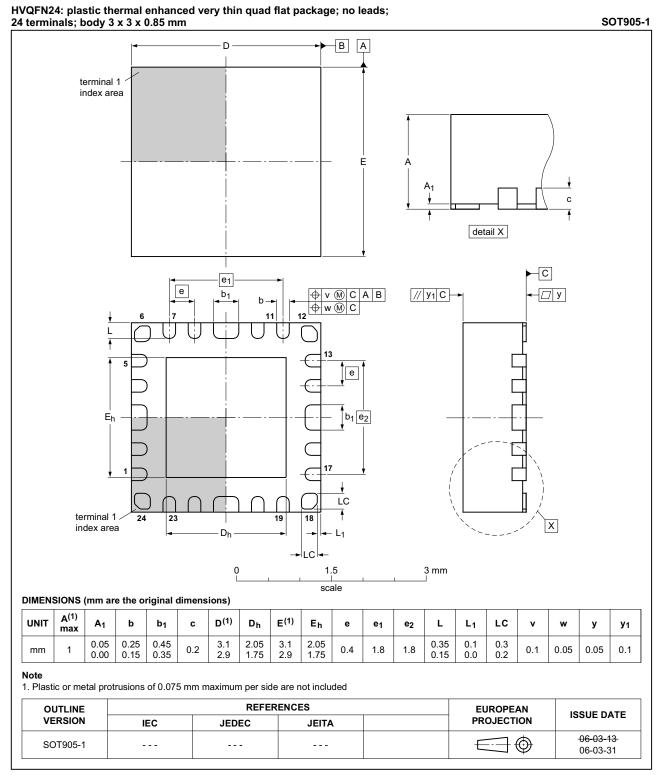
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
R <sub>PU</sub>	pull-up resistance	resistor R4	7	8.75	10.5	kΩ

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## 10. Package outline



#### Package outline SOT905-1 (HVQFN24) Fig 3.

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## 11. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note AN10365 "Surface mount reflow soldering description".

### 11.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

## 11.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- · Board specifications, including the board finish, solder masks and vias
- · Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

### 11.3 Wave soldering

Key characteristics in wave soldering are:

- · Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

### 11.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 4</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 24 and 25

#### Table 24. SnPb eutectic process (from J-STD-020D)

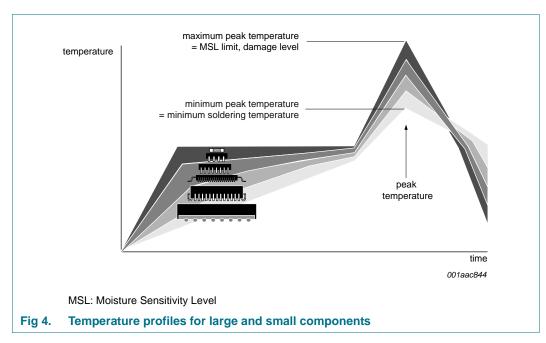
Package thickness (mm)	Package reflow temperature (°C) Volume (mm <sup>3</sup> )		
	< 2.5	235	220
≥ 2.5	220	220	

#### Table 25. Lead-free process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)			
	Volume (mm <sup>3</sup> )			
	< 350	350 to 2000	> 2000	
< 1.6	260	260	260	
1.6 to 2.5	260	250	245	
> 2.5	250	245	245	

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 4.



For further information on temperature profiles, refer to Application Note *AN10365* "Surface mount reflow soldering description".

## **12. Abbreviations**

Table 26. Abbreviations			
Acronym	Description		
CDM	Charged-Device Model		
CMOS	Complementary Metal-Oxide Semiconductor		
DP	DisplayPort		
ESD	ElectroStatic Discharge		
HBM	Human Body Model		
HPD	Hot Plug Detect		
I/O	Input/Output		
MUX	multiplexer		
PCB	Printed-Circuit Board		

## **13. Revision history**

DescurrentID	Deleges deta	Dete abaat status	Change nation	Cum a ma a da a
Document ID	Release date	Data sheet status	Change notice	Supersedes
CBTL05024 v.4	20140327	Product data sheet	-	CBTL05024 v.3
Modifications:	<ul> <li>The security s public.</li> </ul>	tatus of this data sheet has been a	altered from company	confidential to company
CBTL05024 v.3	20131014	Product data sheet	-	CBTL05024 v.2
CBTL05024 v.2	20130715	Product data sheet	-	CBTL05024 v.1

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### 14.1 Data sheet status

Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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#### High performance MUX/deMUX switch for Thunderbolt applications

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