KTFRDMPT2001EVMUG
FRDMPT2001EVM evaluation board
Rev. 1.2 — 13 November 2018　　　　　　　　　　　　**User guide**

1　FRDMPT2001EVM

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Figure 1. FRDMPT2001EVM

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2 Important notice

NXP provides the enclosed product(s) under the following conditions:

This evaluation kit is intended for use of ENGINEERING DEVELOPMENT OR EVALUATION PURPOSES ONLY. It is provided as a sample IC pre-soldered to a printed circuit board to make it easier to access inputs, outputs, and supply terminals. This evaluation board may be used with any development system or other source of I/O signals by simply connecting it to the host MCU or computer board via off-the-shelf cables. This evaluation board is not a Reference Design and is not intended to represent a final design recommendation for any particular application. Final device in an application will be heavily dependent on proper printed circuit board layout and heat sinking design as well as attention to supply filtering, transient suppression, and I/O signal quality.

The goods provided may not be complete in terms of required design, marketing, and or manufacturing related protective considerations, including product safety measures typically found in the end product incorporating the goods. Due to the open construction of the product, it is the user's responsibility to take any and all appropriate precautions with regard to electrostatic discharge. In order to minimize risks associated with the customers applications, adequate design and operating safeguards must be provided by the customer to minimize inherent or procedural hazards. For any safety concerns, contact NXP sales and technical support services.

Should this evaluation kit not meet the specifications indicated in the kit, it may be returned within 30 days from the date of delivery and will be replaced by a new kit.

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3   Overview

The FRDMPT2001EVM evaluation module provides a platform for developing and testing automotive fuel-injection control systems based on NXP's PT2001 direct injection predriver IC. The FRDMPT2001EVM contains PT2001 Programmable Solenoid Controller (PSC) and provides connections for up to four fuel injectors, two fuel pumps (half-bridge) and a DC/DC converter.

The evaluation module consists of the FRDMPT2001EVM board and an MCU companion board plugged on the bottom.

Two options are provided for the MCU companion:

1. FRDM-KL25Z board (default configuration) allows the developer to use NXP's SPIGen software to directly access the PT2001 on the FRDMPT2001EVM board. This also allows the developer to be quickly familiar with PT2001 without having the need to write any MCU code (see Section 5.3 "FRDM-KL25Z board").
2. S32K144EVB-Q100 board, this kit includes the MCU S32K144 an automotive Kinetis processor which offers the high-speed performance required to evaluate PT2001 automotive fuel system designs. NXP's S32 Design Studio software serves as the platform for developing application-specific MCU code and downloading it to the S32K144EVB-Q100 through the OpenSDA port.

For both MCU kits, the developer interacts with the PT2001 by connecting a USB cable between a USB port on a host PC and a mini or micro USB port on the MCU kits. Programming the PT2001 microcode and setting initial register should be done using PT2001 Developer Studio software.

4 Getting started

The NXP analog product development boards provide an easy-to-use platform for evaluating NXP products. These development boards support a range of analog, mixed-signal, and power solutions. These boards incorporate monolithic integrated circuits and system-in-package devices that use proven high-volume technology. NXP products offer longer battery life, a smaller form factor, reduced component counts, lower cost, and improved performance in powering state-of-the-art systems.

The tool summary page for FRDMPT2001EVM is at http://www.nxp.com/FRDMPT2001EVM. The overview tab on this page provides an overview of the device, a list of device features, a description of the kit contents, links to supported devices and a **Get Started** section.

The **Get Started** section provides information applicable to using the FRDMPT2001EVM.

1. Go to http://www.nxp.com/FRDMPT2001EVM.
2. On the **Overview** tab, locate the **Jump To** navigation feature on the left side of the window.
3. Select the **Get Started** link.
4. Review each entry in the **Get Started** section.
5. Download an entry by clicking on the linked title.

After reviewing the **Overview** tab, visit the other related tabs for additional information:

- **Documentation**: Download current documentation.
- **Software & Tools**: Download current hardware and software tools.
- **Buy/Parametrics**: Purchase the product and view the product parametrics.

After downloading files, review each file, including the user guide, which includes setup instructions. If applicable, the bill of materials (BOM) and supporting schematics are also available for download in the **Get Started** section of the **Overview** tab.

4.1 Kit contents/packing list

The FRDMPT2001EVM contents include:

- Assembled and tested FRDMPT2001EVM board mounted to a FRDM-KL25Z board in an anti-static bag
- S32K144EVB-Q100 in case a higher performance MCU is required
- Quick start guide
- Warranty card

4.2 Required equipment

To use this kit, you need:

- 1/8" blade screwdriver for connecting the loads
- DC power supply: 12 V with minimum 5.0 A current handling capability, depending on load requirements
- USB Standard A (male) to micro-B (male) cable (for included K144 Freedom board)
- USB Standard A (male) to mini-B (male) cable (for KL25Z Freedom board)
- Typical loads (direct injection fuel injectors)
- FRDM-KL25Z Freedom Development Platform for SPI communication
- NXP SPIGen software (for use with FRDM-KL25Z based SPI Dongle)

KTFRDMPT2001EVMUG

User guide

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Rev. 1.2 — 13 November 2018

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4 / 25

- NXP's S32 Design Studio software (for use with the S32K144EVB-Q100)
- NXP's PT2001 Developer Studio (for use with the FRDMPT2001EVM)

4.3 System requirements

The kit requires the following to function properly with the software:

- A USB enabled computer with Windows 7 or later

5 Getting to know the hardware

The FRDMPT2001EVM consists of two boards:

- the FRDMPT2001EVM board and an attached FRDM-KL25Z board (SPIGEN can be used in this configuration)
- an optional S32K144EVB-Q100 may also be used with the FRDMPT2001EVM

The following sections describe all three boards.

5.1 FRDMPT2001EVM board

5.1.1 Board overview

The FRDMPT2001EVM serves as the interface between the PT2001 and the components it controls. The board contains a commercial version of the PT2001 and connectors for up to four fuel injectors, two fuel pumps and a DC/DC converter.

5.1.2 Board features

The board features are as follows:

- PT2001 direct injection predriver integrated circuit
- external MOSFETs
- power-conditioning circuitry
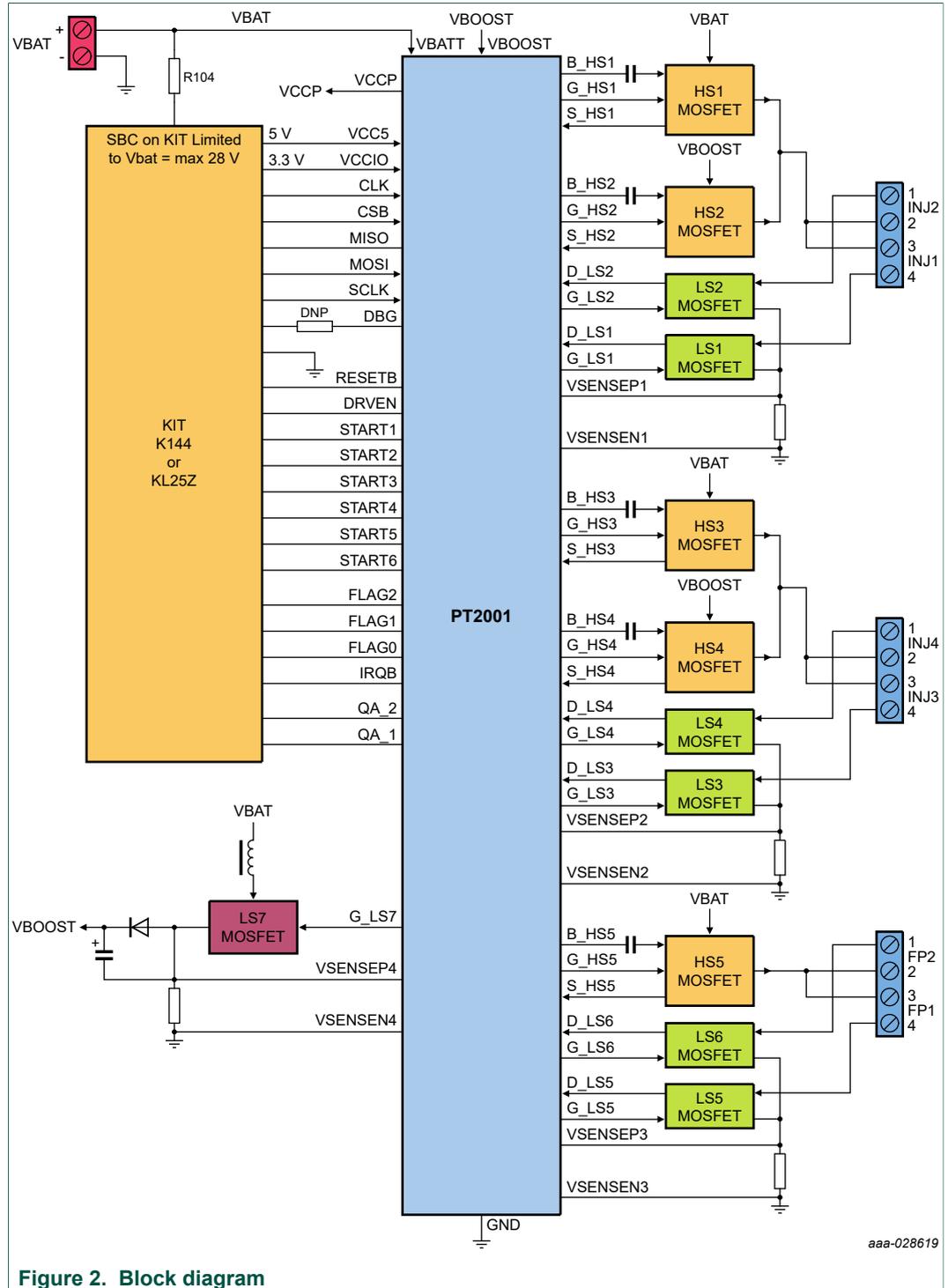- +12 V to +36 V VSUPP power to the PT2001

5.1.3 Block diagram

Figure 2. Block diagram

Note: The PT2001 supports up to 72 V on the battery line, but the SBC UJA1169 on S32K144 kit only supports 40 V as maximum rating and 28 V full performance. Therefore, the board supply should be limited to 28 V or the MCU kit should be supplied externally (R104 resistor to be removed in this case).

5.1.4 Device features

Table 1. Device features

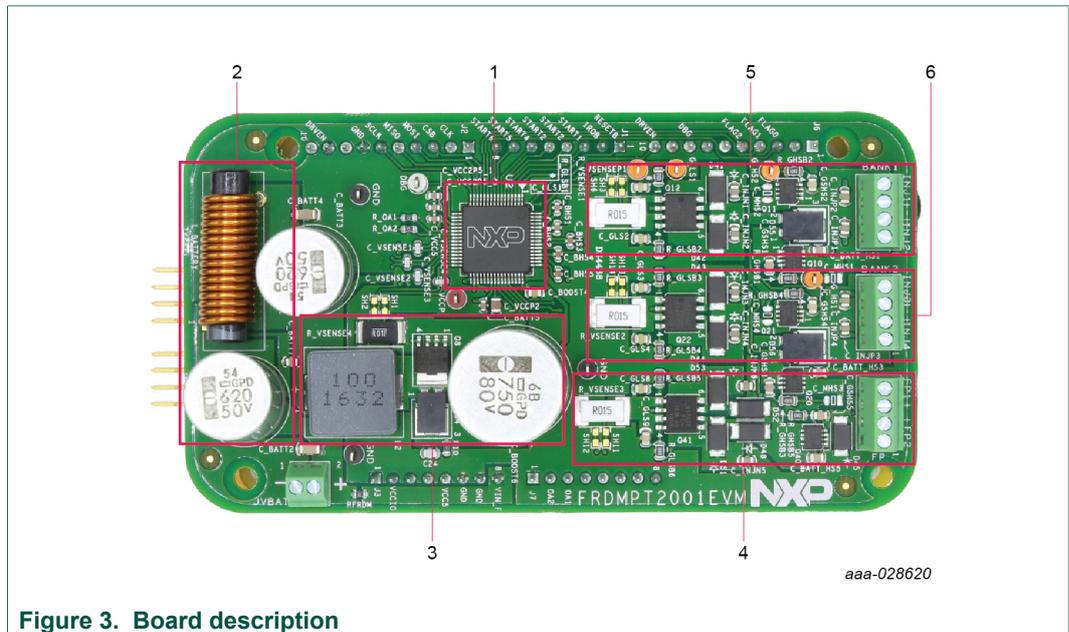| Device	Description	Features
PT2001	Programmable solenoid controller, five high-side and seven low-side controls	• Battery voltage range, 5.5 V < VBATT < 32 V • Predrive operating voltage up to 72 V • High-side/low-side predrive PWM capability up to 100 kHz • Four selectable slew rates with all predrivers • Eight selectable, predefined VDS monitoring thresholds • Encryption for microcode protection • Integrated 1.0 MHz back-up clock
S32K144 MCU	Microcontroller	• 112 MHz ARM Cortex-M4 core with SFPU • Modified Harvard architecture to support tightly coupled RAM and 4 KB I/D cache • Hardware security engine supporting SHE specification • 128-bit unique identification (UID) number per chip • Internal 48 MHz RC (IRC) oscillator • Up to six FlexCAN, a maximum of two with FD support • FlexIO emulating communication protocols (example, SPI, UART, and so on) • Supports ISO 26262 ASIL B
MKL25Z128VLK4 MCU	Microcontroller	• Cortex-M0+ core running at up to 72 MHz (up to 96 MHz for high-speed run) over full voltage and temperature range (−40 ˚C to +105 ˚C) • Up to 512 KB flash with 64-byte flash cache, up to 128 KB RAM • 16 to 32 KB ROM with integrated bootloader • Security circuitry to prevent unauthorized access to RAM and flash contents • Up to 16-bit ADC with configurable resolution, sample time and conversion speed/power. Integrated temperature sensor. Single or differential input mode operation in order to achieve improved noise rejection. • High-speed comparator with internal 6-bit DAC • One six-channel and two 2-channel,16-bit low-power timer PWM modules with DMA support

5.1.5 Board description

Figure 3. Board description

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KTFRDMPT2001EVMUG

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User guide

Rev. 1.2 — 13 November 2018

7 / 25

Table 2. Board description

Number	Name	Description
1	PT2001	Programmable solenoid controller
2	Pi filter	Circuitry to remove undesired frequencies
3	DC/DC	DC/DC converter to generate BOOST voltage
4	Fuel pump	One high-side and one low-side control for high pressure fuel pump
5	Injector Bank 1	Two high-side and two low-side controls for fuel injectors 1 and 2
6	Injector Bank 2	Two high-side and two low-side controls for fuel injectors 3 and 4

5.1.6 Test point definitions

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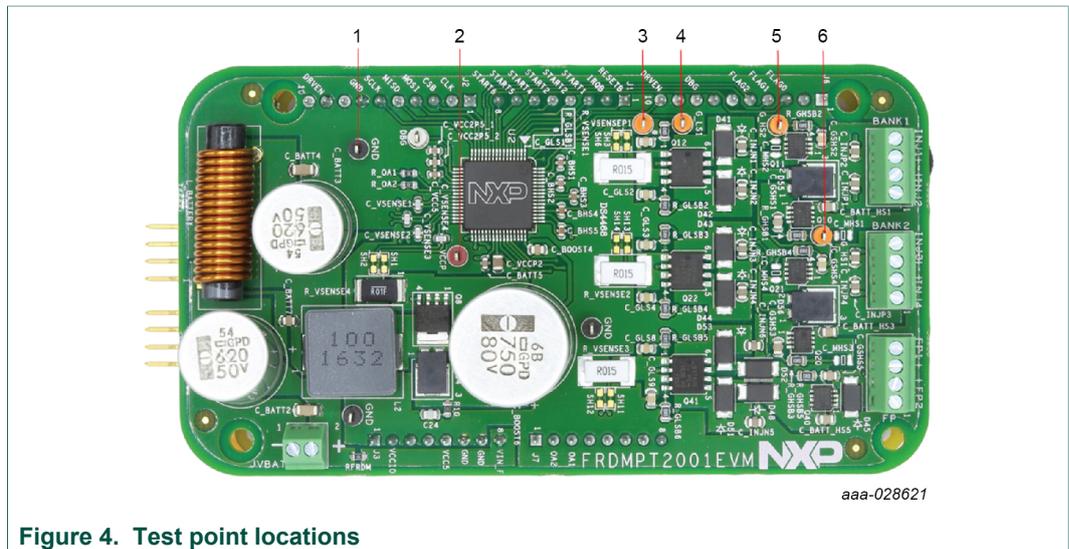
Figure 4. Test point locations

Table 3. Test point definitions

Number	Name	Description
1	GND	Ground test point
2	VCCP	VCCP voltage
3	VSENSEP1	Positive current sense 1
4	G_LS1	Gate1 low-side
5	G_HS2	Gate2 high-side
6	G_HS1	Gate1 high-side

KTFRDMPT2001EVMUG

User guide **Rev. 1.2 — 13 November 2018**

8 / 25

5.1.7 Connectors

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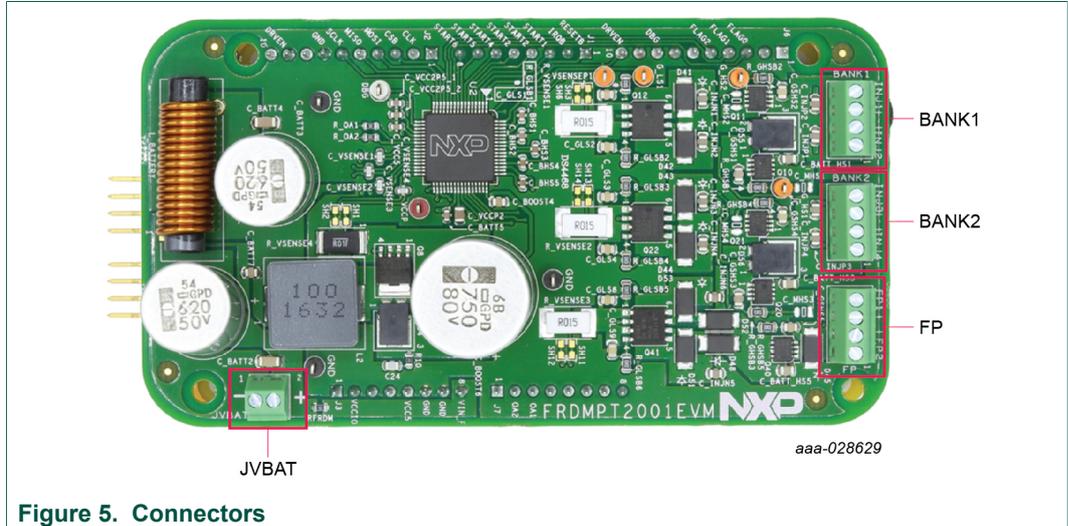
Figure 5. Connectors

Table 4. Input connectors

Name	Description	Connection
JVBAT	Power supply input	Screw terminal 1: Ground
		Screw terminal 2: 12 V to 28 V

Table 5. Output connectors

Name	Description	Connection
BANK1	Bank output 1 (injector1 and 2)	Screw terminal 1: low-side driveINJ2−
		Screw terminal 2: high-side drive INJ2+
		Screw terminal 3: high-side drive INJ1+
		Screw terminal 4: low-side driveINJ1−
BANK2	Bank output 2 (injector3 and 4)	Screw terminal 1: low-side drive INJ4−
		Screw terminal 2: high-side drive INJ4+
		Screw terminal 3: high-side drive INJ3+
		Screw terminal 4: low-side driveINJ3−
FP	Fuel pump output 1 and 2	Screw terminal 1: low-side drive FP2−
		Screw terminal 2: high-side drive FP2+
		Screw terminal 3: high-side drive FP1+
		Screw terminal 4: low-side drive FP1−

5.2 S32K144EVB-Q100 board

The S32K144EVB-Q100 features the S32K144 MCU, an automotive Kinetis processor which provides the high-speed performance required to evaluate PT2001 automotive fuel system designs. While the S32K144EVB-Q100 offers a range of capabilities, its primary purpose when used with the FRDMPT2001EVM is to control SPI and digital I/O communications with the PT2001.

KTFRDMPT2001EVMUG

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User guide

Rev. 1.2 — 13 November 2018

9 / 25

In that context, two on-board switches (SW2 and SW3) allow developers to control the PT2001 when using the example projects provided on the FRDMPT2001EVM tool summary page. The board also includes a potentiometer for RPM control and three LEDs that light to indicate when a PT2001 fault occurs.

For additional information on this board, see http://www.nxp.com/S32K144EVB.

5.3 FRDM-KL25Z board

NXP's Freedom development platform is a set of software and hardware tools that provide an ideal platform for the rapid prototyping of microcontroller-based applications. The FRDM-KL25Z board is a key component of the development platform.

The board features a Kinetis L Series microcontroller, the industry's first microcontroller built on the Arm® Cortex®-M0+ processor. It makes use of the USB, the built in LEDs and the I/O ports available with NXP's Kinetis KL2x family of microcontrollers. When used in conjunction with the FRDMPT2001EVM, the FRDM-KL25Z controls SPI communication between the evaluation board and a PC. It permits the user to regulate the power outputs and implement the features of the device on the evaluation board.

The FRDM-KL25Z also monitors the SPI registers, thereby facilitating the use of safety and advanced diagnostic functions.

For additional information on the FRDM-KL25Z board, see https://www.nxp.com/FRDM-KL25Z .

6 Operating the FRDMPT2001EVM with SPIGen and the FRDM-KL25Z

In the out-of-box configuration, the FRDMPT2001EVM's PT2001 device can only be exercised by downloading the appropriate microcode. To access the device's registers and internal memory, the developer must replace the S32K144EVB-Q100 with a FRDM-KL25Z board. With the FRDM-KL25Z serving as an SPI dongle, the developer can then use NXP's SPIGen software to communicate with the device.

6.1 Preparing to use the FRDM-KL25Z

Before the FRDM-KL25Z can be used in conjunction with FRDMPT2001EVM board, the following steps must be taken:

1. Install SPIGen on the host PC.
2. Download microcode to the FRDM-KL25Z.
3. Connect the FRDM-KL25Z to the FRDMPT2001EVM board.

The following sections describe each step in detail.

6.1.1 Installing SPIGen on the host PC

SPIGen currently runs on Windows 7, Windows 8 and Windows 10 operating systems. The procedure for installing the software is as follows:

1. Go to the FRDMPT2001EVM tool summary page at http://www.nxp.com/FRDMPT2001EVM and locate the Software & Tools tab.
2. From the list of files, download the SPIGen software as well as the associated configuration files.

KTFRDMPT2001EVMUG

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User guide

Rev. 1.2 — 13 November 2018

10 / 25

Run the install program from the desktop. Follow the guidance of the installation wizard through the rest of the process.

6.1.2 Connecting the FRDM-KL25Z to the FRDMPT2001EVM

When connected to the FRDMPT2001EVM board, the FRDM-KL25Z allows developers to drive the evaluation board inputs to operate injectors or other solenoid loads via the GPIOs and SPI pins. The FRDM-KL25Z can also read and write the SPI registers, thereby allowing the user to modify PT2001 parameters and the advanced diagnostic functions.

The procedure for configuring the FRDMPT2001EVM for use with the FRDM-KL25Z is as follows:

1. Detach the S32K144EVB-Q100 from the FRDMPT2001EVM board.
2. Place connector blocks on the outer rows of all four Arduino connectors on the FRDM-KL25Z.
3. Attach the FRDM-KL25Z under FRDMPT2001EVM board such that connector J3 on the FRDMPT2001EVM aligns with connector J9 on the FRDM-KL25Z and connector J2 on the FRDMPT2001EVM aligns with connector J2 on the FRDM-KL25Z.

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4. Connect the Standard-A plug of the USB cable to the host PC. Connect the mini-B plug on the cable to the port labeled **USBKL25Z** on the FRDM-KL25Z.

6.1.3 Downloading microcode to the FRDM-KL25Z

Note that this procedure requires a Standard-A (male) to mini-B (male) USB cable.

1. Go to the P&E Microcomputer Systems OpenSDA page at http://www.pemicro.com/opensda and in the **OpenSDAFirmware (MSD & Debug)** box, click to download the **Firmware Apps** zip file.
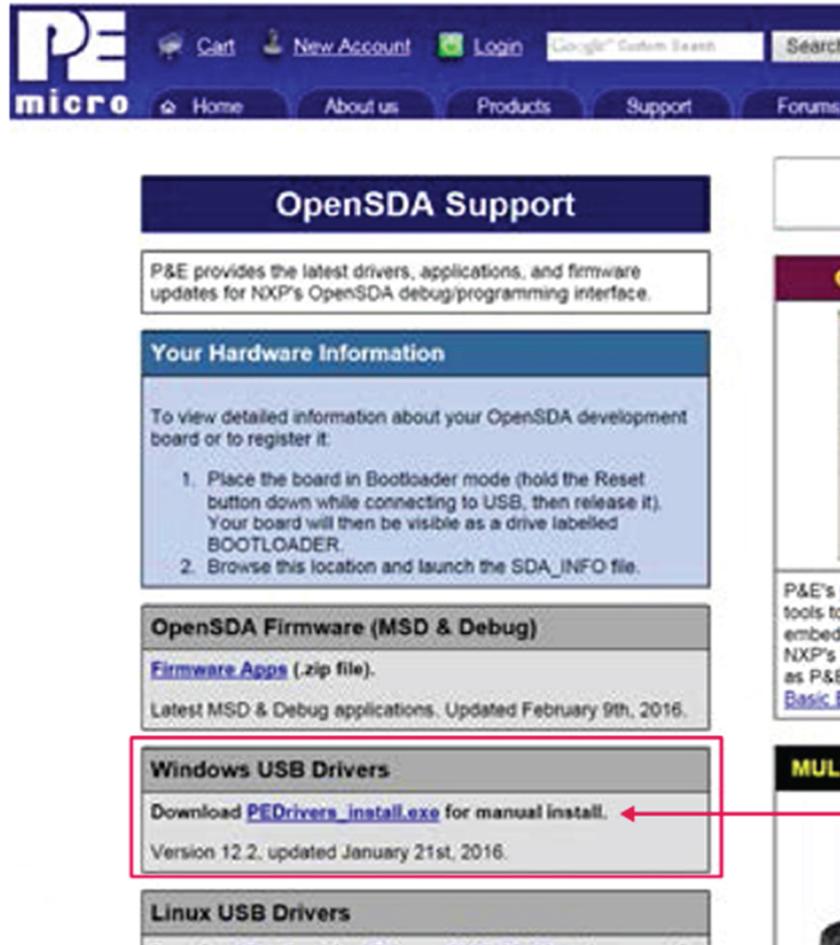
aaa-028636

2. When the download completes, unzip the file contents to a folder on the host PC.

3. Connect the Standard A plug of the USB cable to the host PC.

4. On the FRDM-KL25Z, press and hold down the Reset button. With the button held down, attach the mini-B plug of the USB cable to the FRDM-KL25Z USB port labeled **SDA**. Then release the Reset button. A blinking LED indicates the board is in Bootloader mode.

5. Open Windows Explorer on the host PC. An icon labeled **BOOTLOADER** appears as a removable drive on the PC.

6. From the files extracted from the PEMicro zip file, locate the driver file named **MSDDEBUG-FRDM-KL25Z_Pemicro_v118.SDA**. Drag and drop this file onto the BOOTLOADER icon.

7. Unplug the USB mini-B plug then re-insert the plug back into the SDA port. A blinking LED on the board indicates that the FRDM-KL25Z is in bootloader mode.

8. Locate the SPIGEN **UsbSpiDongleKL25Zv507.srec** image folder in the SPIGEN folder (C:\Program Files (x86)\SPIGen\SPI Dongle Firmware).

9. Copy and paste or drag and drop the .srec file to the FRDM-KL25Z removable drive icon on the host PC.

10. Unplug the USB cable from the FRDM-KL25Z SDA port.

6.2 Configuring the hardware for use with the FRDM-KL25Z

To run the examples included in the software bundle, the following connections and setup must be performed:

1. Make sure SPIGen 7.0 (or higher) is installed on the PC and it can communicate with the Freedom board FRDM-KL25Z. A blue LED, lights on the FRDM-KL25Z when SPIGen is running and the board is properly connected.

2. Connect the FRDM-KL25Z to the PC using the USB KL25Z port (left side of SW1). The USB_PWR LED on the FRDMPT2001EVM should be illuminated.

3. With the power supply switched off, attach the +12 VDC supply to the VSUPP input connector on the FRDMPT2001EVM. Make sure that the power supply is connected to the correct GND and +12 V terminals on the board. The current capability of the +12 V supply must exceed the maximum total current required by the number of loads that can be simultaneously ON.

4. Attach loads (Injectors) to the INJ1, INJ2, INJ3, INJ4, INJ5 and INJ6 output terminals as desired.

5. Turn on the +12 V supply. The +5.0 V LED illuminates, indicating that the board is properly connected.
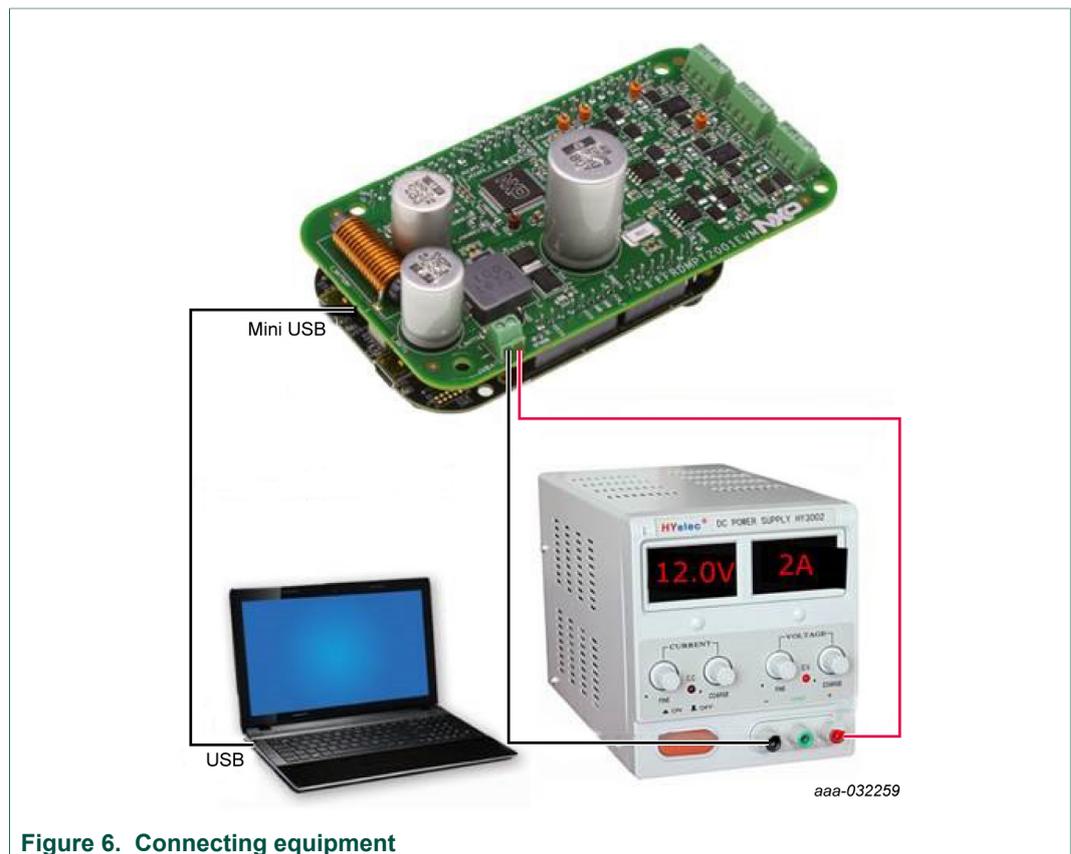
Figure 6. Connecting equipment

6.3 Using SPIGen

6.3.1 Configuring the SPIGen software

1. In the Windows Start menu, go to **Programs** -> **SPIGen** and click the SPIGen icon.

This icon appears on the Windows desktop if the appropriate option is selected during installation.

2. When the SPIGen Graphical User Interface (GUI) appears, go to the file menu in the upper-left corner and select **Open**. A file selection window opens. In the bottom-right corner of the window, the drop-down box value should be set to **SPIGen Files (*.spi)**. If the configuration file name has a .txt extension, set this value to **All Files (*.*)**.

3. Browse for the SPIGen configuration file downloaded from the tool summary page (see Section 6.1.1 "Installing SPIGen on the host PC").
Select the configuration file and click **Open**. SPIGen creates a SPI command generator configured specifically for the FRDMPT2001EVM board.

The GUI is shown in Figure 7. The text at the top is the name of the configuration file that is loaded. The left side panel displays folders that group user interfaces. The interfaces in the pre-installed PT2001 folder pertain specifically to the board FRDMPT2001EVM. When the configuration file loads, SPIGen is assigned a FRDMPT2001EVM specific list of **Extra Pins** and **Quick Commands**.

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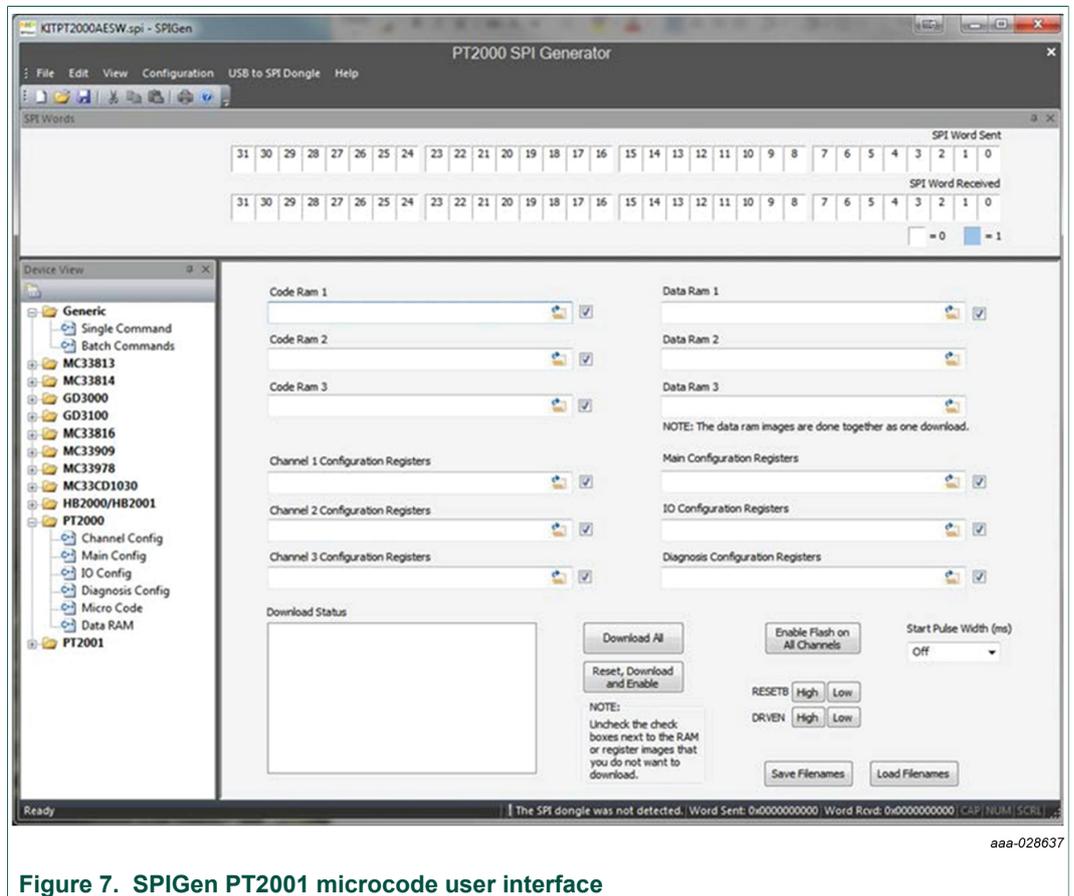
Figure 7. SPIGen PT2001 microcode user interface

6.3.2 Running an example file

1. With the FRDMPT2001EVM and FRDM-KL25Z configuration as described in Section 6.2 "Configuring the hardware for use with the FRDM-KL25Z", launch the SPIGen program.

2. Load the configuration file, by clicking **File** -> **Open** and browsing to the KITPT2001SW.spi file located inside the **Injector Demo Files** directory.

3. In the **Device View** panel, expand the **PT2001** folder and click **MicroCode**.

KTFRDMPT2001EVMUG

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User guide

Rev. 1.2 — 13 November 2018

14 / 25

4. In the SPIGen menu bar, click **Files** -> **Open** and select the **SPIGenPT2001Files.txt** included in the project example. All cells in the micro code page (Code Ramx, Data Ramx, Channelx, Main, IO, and Diagnostics Configuration Registers) should populate with the appropriate path.

5. Click **Reset, Download and Enable** to load and enable the PT2001.

6. In the **Start Pulse Width (ms)** cell, select the appropriate duration.

7. In the **Device View** panel, in the **PT2001** folder, click **Channel Config**. Select **Channel 1**.

    a. Check to assure that **flash enable** is selected in the **Register:**cell.

    b. Click **Read** and ensure that the **checksum failure** bit is not set.

    c. Make sure that bits 3, 4 and 5 are set as shown below.
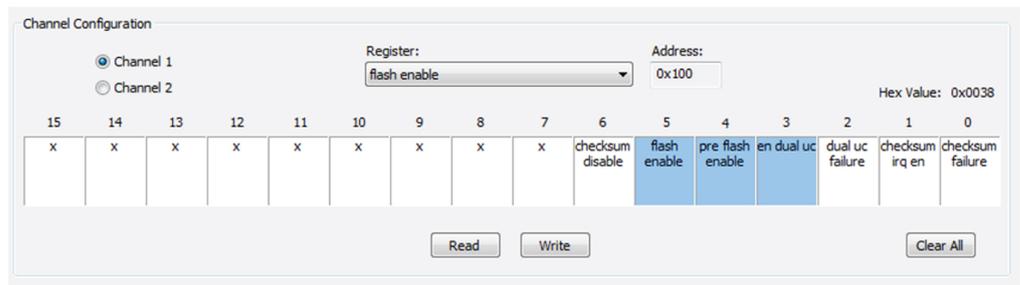
aaa-028638

8. Repeat the **Channel Config** process for **Channel 2**.

6.3.3 Reading and writing registers

SPIGen can also be used to read and write the registers on the PT2001. There are four different register configuration pages under the PT2001 **Device View**:

*   Channel configuration
*   Main configuration
*   IO configuration
*   Diagnosis configuration

The channel configuration register page covers both channels and is shown in Figure 8.

KTFRDMPT2001EVMUG

User guide

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Rev. 1.2 — 13 November 2018

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15 / 25
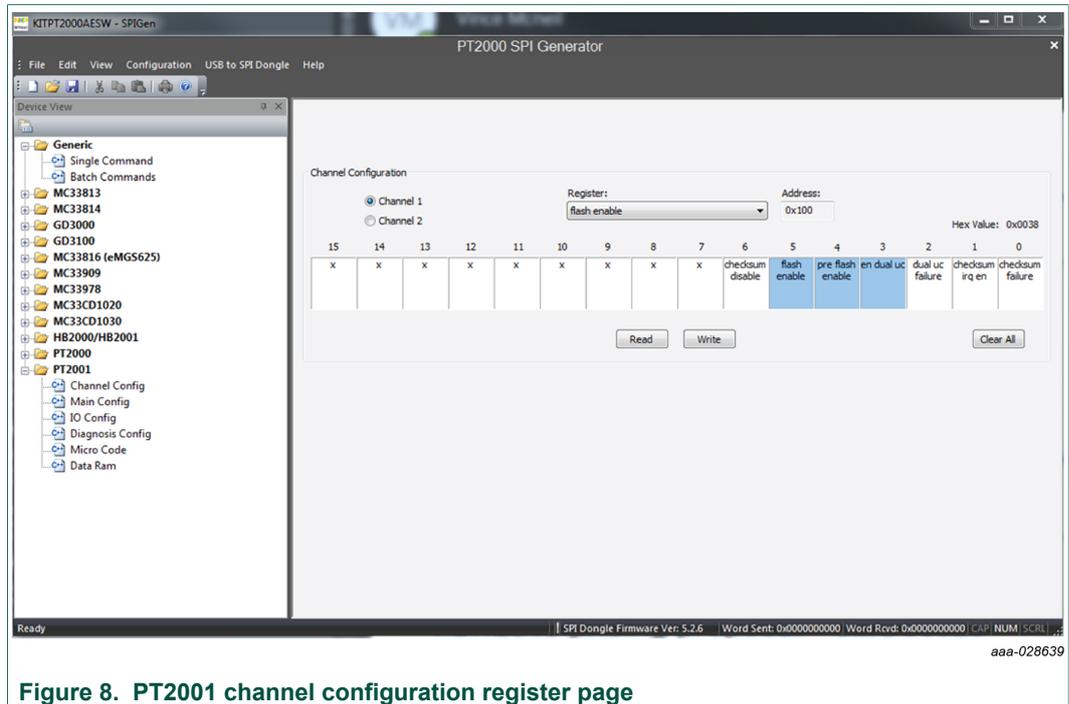
Figure 8. PT2001 channel configuration register page

To read or write a specific register on the PT2001, select the register name from the **Register** drop-down on the top center of the page. The register address will be shown to the right of the name. To read the contents of the register, click **Read**. The bits that are set (1) are colored blue; the bits that are cleared (0) are colored white.

To write to a specific register, click on the bits to be changed to set them to the proper state. Then click **Write**. The read and write process is the same for the other register groups which can be accessed by clicking on the register group name under PT2001 in the **Device View** window.

7 Operating the FRDMPT2001EVM with the S32K144EVB-Q100

The FRDMPT2001EVM ships with a S32K144EVB-Q100 board. It can be attached via Arduino™ connectors on the bottom side of the FRDMPT2001EVM board. In this configuration, the PT2001 functionality can only be exercised by downloading the appropriate microcode to the device.

7.1 Configuring the hardware for use with the FRDMPT2001EVM

1. Connect the micro-B plug on the USB cable to the USB port on the S32K144EVB-Q100 board. Connect the USB cable's Standard A plug to the host PC. An icon named EVB-S32K144 appears as a removable drive on the host PC.

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User guide

Rev. 1.2 — 13 November 2018

16 / 25
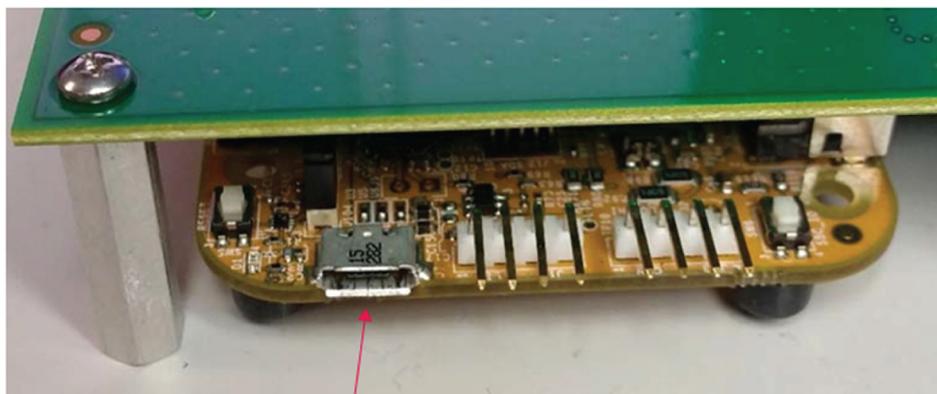
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2. With the power supply switched off, attach the +12 VDC supply to the VSUPP input connector on the FRDMPT2001EVM board. Make sure that the power supply is connected to the correct GND and +12 V terminals on the board. The current capability of the +12 V supply must exceed the maximum total current required by the number of loads that can be ON simultaneously.

3. Attach loads (Injectors) to the INJ1, INJ2, INJ3, and INJ4 output terminals as desired.

4. Turn on the +12 V supply. The +5.0 V LED illuminates, indicating that the board is properly connected.

7.2 Downloading microcode

To use the FRDMPT2001EVM in a development environment, the developer must install an NXP Integrated Design Environment (IDE) to download and run microcode. The procedure for downloading microcode differs depending on whether the microcode is being downloaded to the S32K144EVB-Q100 or to the FRDMPT2001EVM.

7.2.1 Downloading microcode to the S32K144EVB-Q100

The procedure for downloading microcode to the S32K144 device on the S32K144EVB-Q100 consist of the following steps:

1. Installing NXP's S32 Design Studio.
2. Downloading the S32K144EVB-Q100 example project file.
3. Importing the example project file into S32 Design Studio.
4. Customizing (optional) and building the example project file firmware image.
5. Downloading the firmware image to the S32K144EVB-Q100.

The following sections describe each of these steps in detail.

KTFRDMPT2001EVMUG

User guide

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Rev. 1.2 — 13 November 2018

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17 / 25

7.2.1.1 Installing S32 Design Studio

NXP's S32 Design Studio allows developers to customize the S32K144EVB-Q100's MCU code to meet application-specific requirements. The S32 Design Studio IDE is a complimentary integrated development environment that enables editing, compiling and debugging of automotive and ultra-reliable designs. Based on free, open-source software including Eclipse IDE, GNU Compiler Collection (GCC) and GNU Debugger (GDB), the S32 Design Studio IDE is a straightforward development tool with no code size limitations.

This procedure explains how to obtain and install the latest version of S32 Design Studio. If S32 Design Studio is already installed on the host PC, skip this section.

1. Obtain the latest S32 Design Studio installer file from the NXP website www.nxp.com/ S32DS.
2. Run the executable file and follow the instructions.

The S32 Design Studio SDK library is distributed with the IDE already integrated, so no explicit action is required to add or link it manually.

7.2.1.2 Downloading the S32K144EVB-Q100 example file

The Software & Tools tab on the FRDMPT2001EVM tool summary page contains an example microcode project file. This project demonstrates a typical application that exercises the functionality of the fuel injectors and the fuel pump controllers. Developers can download this file and edit the source code to accommodate their application.

To download the example file, do the following:

1. Go to the tool summary page at http://www.nxp.com/FRDMPT2001EVM and click on the Software & Tools tab.
2. Locate and download the zip file named S32K144_PT2001_EXAMPLE.zip.
3. Unzip this file into a folder on the computer that has the S32 Design Studio installed.

7.2.1.3 Importing the example file

Once the demo file has been downloaded, the developer must import it into S32 Design Studio. The procedure is as follows:

1. Open S32 Design Studio.
2. From the S32 Design Studio menu bar, click **File** -> **Import**. A **Select** window opens.
3. In the **Select** window, expand the folder named **General**. Then select **Existing Projects into Workspace** and then click **Next**. An **Import Projects** window opens.
4. In the **Import Project** window, browse for and select the root directory containing the example file. In the **Projects** panel, select the example file. Then click **Finish**. See Figure 9.

KTFRDMPT2001EVMUG

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User guide

Rev. 1.2 — 13 November 2018

18 / 25

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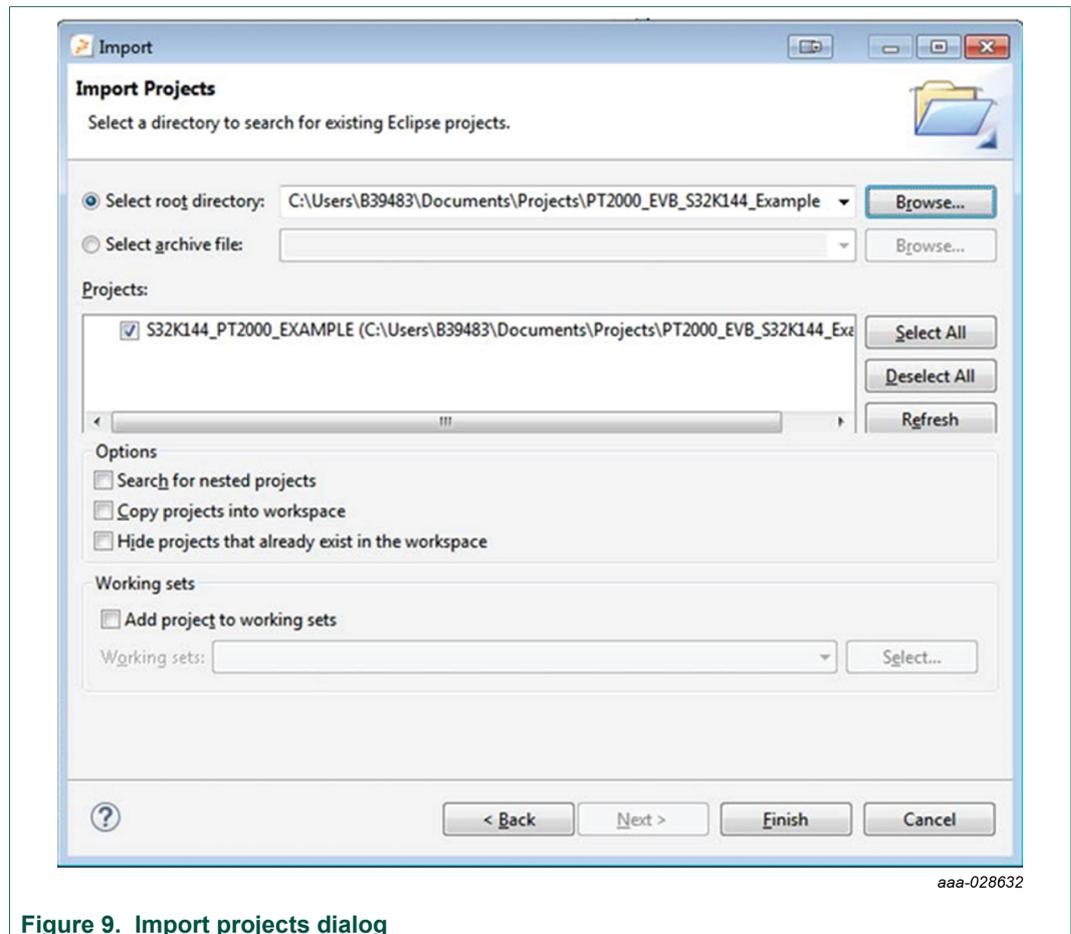
Figure 9. Import projects dialog

The example file appears in the Project Explorer panel on the left side of the IDE.

7.2.1.4 Customizing and building the example file

Developers can flash the MCU on the S32K144EVB-Q100 with the unmodified example file microcode. The source code can also be modified to meet the specific requirements of their application. In either case, the project must be built in S32 Design Studio before downloading the microcode.

1. To customize the example file, expand the example project tree in the Project Explorer window to view the file folders. The source code is located in the **src** folder and the include files are located in the **include** folder. Double-clicking the file name in the Project Explorer opens the file for editing where changes can be made.
2. To build the project, select the project in the Project Explorer window, then click the hammer icon on the S32 Design Studio toolbar. If there are no errors during the build, the output file is located in the **Debug** folder under the main project folder. The file has a .srec extension (example: S32K144_PT2001_EXAMPLE.srec).
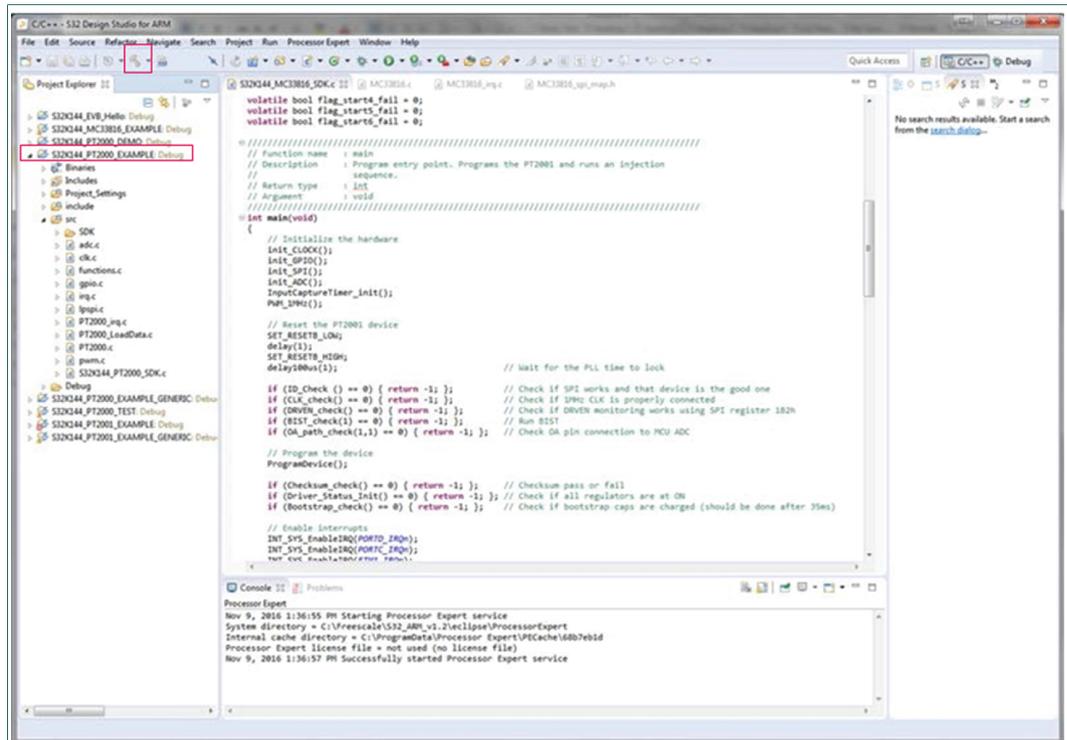
Figure 10. S32 Design Studio build project

7.2.1.5 Downloading the firmware to the S32K144EVB-Q100

1. Connect the micro-B plug on the USB cable to the USB port on the S32K144EVB-Q100 board. Connect the USB cable's Standard A plug to the host PC. An icon named EVB-S32K144 appears as a removable drive on the host PC.
2. To download the firmware, locate the firmware file (S32K144_PT2001_EXAMPLE.srec) on your computer and drag and drop the file onto the EVB-S32K144 icon.

The firmware program begins running immediately after the download has completed.

7.2.2 Updating microcode on the FRDMPT2001EVM

This section provides an overview of the process for updating the microcode on the FRDMPT2001EVM. For information on the process, see *PT2001 Developer Studio User's Guide* (PT2001_IDEUG).

The procedure is as follows:

1. Install NXP's PT2001 Developer Studio.
2. Load, build and regenerate the example projects.
3. Update the S32K144EVB-Q100 with the new project data.

7.2.2.1 Installing PT2001 Developer Studio

1. Obtain the latest version of the PT2001 Developer Studio installer file from the NXP website: http://www.nxp.com/products/power-management/engine-and-dc-motor-

KTFRDMPT2001EVMUG

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User guide

Rev. 1.2 — 13 November 2018

20 / 25

control/powertrain-engine-control/developer-studio-for-PT2001-programmable-%20solenoid-controller:PT2001IDE?tab=Design_Tools_Tab

2. Run the executable file and follow the wizard instructions.

7.2.2.2 Loading, building and regenerating the example projects

Two relevant example projects — **FRDMPT2001EVM Software Files for Peak and Hold with Diagnostics and DCDC** and **FRDMPT2001EVM Software Files for Peak and Hold and DCDC** — are available on the FRDMPT2001EVM tool summary page.

These examples can be used as starting points for developing application specific microcode. For information on how to load and build projects using the IDE, see *PT2001 Developer Studio User's Guide* which can be accessed using the Help menu on the IDE.

After successfully building a project, the PT2001 load data files must be regenerated. To do this,

• In the PT2001 Developer Studio toolbar, select **Tools** -> **Generate PT2001 Load Data Code**. When the regeneration process completes, the Code Generation Results window appears as shown in Figure 11.

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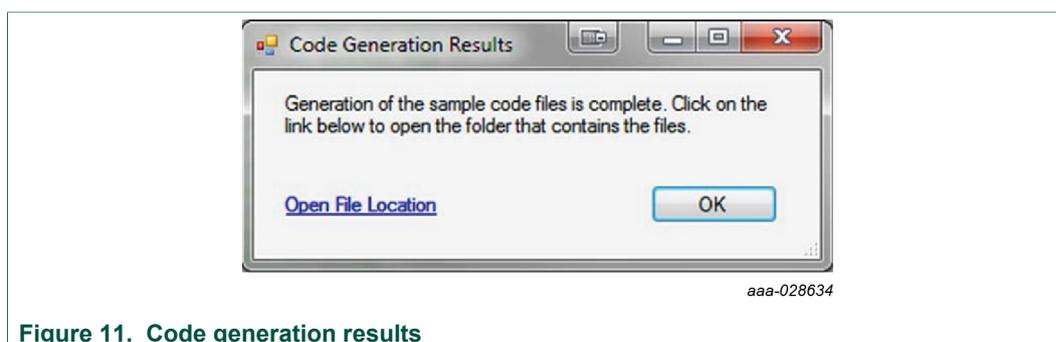
Figure 11. Code generation results

7.2.2.3 Updating the S32K144EVB-Q100

1. In Windows Explorer, open the folder that the generated code files were saved to. Locate the files **PT2001_LoadData.h** and **PT2001_LoadData.c** (usually found in the folder named **sample_code**). These files contain the code RAM, data RAM, and register settings that get loaded into the PT2001. The PT2001 Developer Studio also creates other files that may be useful when creating a new MCU project from scratch. See the *PT2001 Developer Studio User's Guide*, available at http://www.nxp.com/assets/documents/data/en/user-guides/PT2001-IDEUG.pdf for a description of these files and how they are used.

2. To update the S32 design studio project, copy **PT2001_LoadData.c** over the existing file in the src folder of the S32 Design Studio project, and copy the **PT2001_LoadData.h** file over the existing file in the include folder.

3. To run the updated microcode on the EVB, rebuild the project and reload the S32K144EVB-Q100 board as described in Section 7.2.1.5 "Downloading the firmware to the S32K144EVB-Q100".

8 Schematics, board layout and bill of materials

The board schematics, board layout and bill of materials are available at http://www.nxp.com/FRDMPT2001EVM on the Overview tab under Get Started.

9 References

Following are URLs where you can obtain information on related NXP products and application solutions:

NXP.com support pages	Description	URL
FRDMPT2001EVM	Tool summary page	http://www.nxp.com/FRDMPT2001EVM
PT2001	Product summary page	http://www.nxp.com/PT2001
FRDM-KL25Z	Tool summary page	http://www.nxp.com/FRDM-KL25Z
S32K144EVB-Q100	Tool summary page	http://www.nxp.com/S32K144EVB
S32 Design Studio	—	https://www.nxp.com/products/%20power-management/engine-and-%20dcmotor-%0Acontrol/powertrain-%20engine-control/developer-studio-%20for-PT2001-programmablesolenoid-%20%0Acontroller:PT2001IDE?%20tab=Design_Tools_Tab
PT2001 Developer Studio User's Guide	User guide	http://www.nxp.com/assets/%20documents/data/en/user-guides/%20PT2001-IDEUG.pdf

10 Revision history

Revision	Date	Description of changes
1.0	11/2017	Initial release
1.1	7/2018	Updated Section 4
1.2	11/2018	Added Figure 6.

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KTFRDMPT2001EVMUG

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User guide

Rev. 1.2 — 13 November 2018

24 / 25

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