

FS6500, FS4500: ASIL B

Safety power system basis chip with CAN FD and LIN transceivers

Rev. 3 — 14 April 2021

Product short data sheet

1 General description

The FS6500/FS4500 SMARTMOS devices are a multi-output, power supply, integrated circuit, including CAN Flexible Data (FD) and/or LIN transceivers, dedicated to the automotive market.

Multiple switching and linear voltage regulators, including low-power mode (32 μ A) are available with various wake-up capabilities. An advanced power management scheme is implemented to maintain high efficiency over a wide range of input voltages (down to 2.7 V) and output current ranges (up to 2.2 A).

The FS6500/FS4500 includes configurable fail-safe/fail silent safety behavior and features, with two fail-safe outputs, becoming a full part of a safety oriented system partitioning, to reach a high integrity safety level (up to ASIL B).

The built-in CAN FD interface fulfills the ISO 11898- $2^{(12)}$ and $-5^{(13)}$ standards. The LIN interface fulfills LIN protocol specifications 2.0, $2.1^{(22)}$, $2.2^{(23)}$, and SAE J2602- $2^{(24)}$.

High temperature capability up to T_A = 125 °C and T_J = 150 °C, compliant with AEC-Q100 Grade 1 automotive qualification.

2 Features and benefits

- Battery voltage sensing and MUX output pin
- Highly flexible SMPS pre-regulator, allowing two topologies: non-inverting buck-boost and standard buck
- Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A, 1.5 A or 2.2 A) or LDO (0.5 A)
- Linear voltage regulator dedicated to auxiliary functions, or to sensor supply (V_{CCA} tracker or independent), 5.0 V, or 3.3 V
- Linear voltage regulator dedicated to MCU Analog/Digital (A/D) reference voltage or I/Os supply (V_{CCA}), 5.0 V, or 3.3 V
- 3.3 V keep alive memory supply available in low-power mode
- Long duration timer, counting up to 6 months with 1.0 s resolution
- Multiple wake-up sources in low-power mode: CAN, LIN, IOs, LDT
- Five configurable I/Os

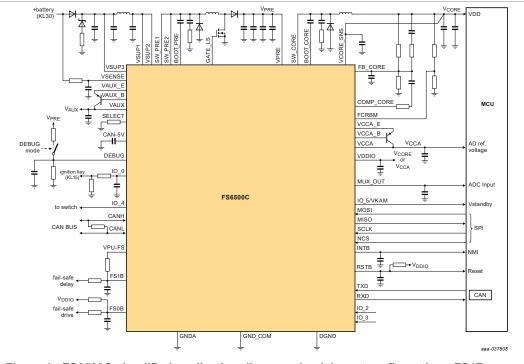
3 Applications

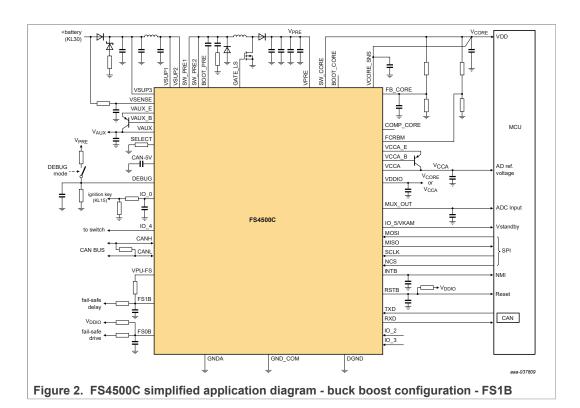
- Drive Train Electrification (BMS, Hybrid EV and HEV, Inverter, DC-DC, Alterno Starter)
- Drive Train Chassis and Safety (Active Suspension, Steering, Safety Domain Gateway)
- Power Train (EMS, TCU, Gear Box)
- ADAS (LDW, Radar, Sensor Fusion Safety area)



- On board charger
- Motor control

4 Simplified application diagrams





5 Ordering information

5.1 Part number definition

MC33FS <u>c</u> 5 <u>x</u> <u>y</u> <u>z</u> AE/R2

Table 1. Part number breakdown

Code	Option	Variable	Description
С	4 series	V typo	Linear
	6 series	V _{CORE} type	DC-DC
x	0		0.5 A or 0.8 A
	1	V _{CORE} current	1.5 A
	2		2.2 A
у	5		None
	6	Functions	FS1B
	7	FullCuons	LDT
	8		FS1B and LDT
z	N		None
	С	Physical interface	CAN FD
	К	Filysical illellace	LIN only
	L		CAN FD and LIN

5.2 Part numbers list

Table 2. Orderable part variations

Part Number	Temperature (T _A)	Package	FS1B	LDT	VCORE	VCORE type	VKAM On	CAN FD	LIN	ASIL	Note
MC33FS4505NAE			0	0	0.5 A	Linear	by SPI	0	0	В	
MC33FS4505CAE			0	0	0.5 A	Linear	by SPI	1	0	В	
MC33FS4505KAE			0	0	0.5 A	Linear	By SPI	0	1	В	
MC33FS4505LAE			0	0	0.5 A	Linear	By SPI	1	1	В	
MC33FS4506NAE			1	0	0.5 A	Linear	by SPI	0	0	В	
MC33FS4506CAE	-		1	0	0.5 A	Linear	by SPI	1	0	В	
MC33FS4507NAE			0	1	0.5 A	Linear	by SPI	0	0	В	
MC33FS4507CAE	-		0	1	0.5 A	Linear	by SPI	1	0	В	
MC33FS4507KAE	-		0	1	0.5 A	Linear	by SPI	0	1	В	
MC33FS4507LAE	-		0	1	0.5 A	Linear	by SPI	1	1	В	
MC33FS4508NAE	-		1	1	0.5 A	Linear	by SPI	0	0	В	
MC33FS4508CAE			1	1	0.5 A	Linear	by SPI	1	0	В	
MC33FS6505NAE	-		0	0	0.8 A	DC-DC	by SPI	0	0	В	
MC33FS6505CAE	-		0	0	0.8 A	DC-DC	by SPI	1	0	В	
MC33FS6505KAE	-		0	0	0.8 A	DC-DC	by SPI	0	1	В	
MC33FS6505LAE			0	0	0.8 A	DC-DC	by SPI	1	1	В	
MC33FS6506NAE	-		1	0	0.8 A	DC-DC	by SPI	0	0	В	
MC33FS6506CAE	-	-40 °C to 125 °C 48-pin LQFP exposed pad	1	0	0.8 A	DC-DC	by SPI	1	0	В	
MC33FS6507NAE	–40 °C to		0	1	0.8 A	DC-DC	by SPI	0	0	В	[
MC33FS6507CAE	125 °C		0	1	0.8 A	DC-DC	by SPI	1	0	В	'
MC33FS6507KAE	_	F	0	1	0.8 A	DC-DC	by SPI	0	1	В	
MC33FS6507LAE	_		0	1	0.8 A	DC-DC	by SPI	1	1	В	
MC33FS6508NAE	_		1	1	0.8 A	DC-DC	by SPI	0	0	В	
MC33FS6508CAE	_		1	1	0.8 A	DC-DC	by SPI	1	0	В	
MC33FS6515NAE	_		0	0	1.5 A	DC-DC	by SPI	0	0	В	
MC33FS6515CAE	-		0	0	1.5 A	DC-DC	by SPI	1	0	В	
MC33FS6515KAE			0	0	1.5 A	DC-DC	by SPI	0	1	В	
MC33FS6515LAE	-		0	0	1.5 A	DC-DC	by SPI	1	1	В	
MC33FS6516NAE			1	0	1.5 A	DC-DC	by SPI	0	0	В	
MC33FS6516CAE			1	0	1.5 A	DC-DC	by SPI	1	0	В	
MC33FS6517NAE			0	1	1.5 A	DC-DC	by SPI	0	0	В	
MC33FS6517CAE			0	1	1.5 A	DC-DC	by SPI	1	0	В	
MC33FS6517KAE			0	1	1.5 A	DC-DC	by SPI	0	1	В	
MC33FS6517LAE			0	1	1.5 A	DC-DC	by SPI	1	1	В	
MC33FS6518NAE			1	1	1.5 A	DC-DC	by SPI	0	0	В	
MC33FS6518CAE			1	1	1.5 A	DC-DC	by SPI	1	0	В	
MC33FS6525NAE			0	0	2.2 A	DC-DC	by SPI	0	0	В	
MC33FS6525CAE			0	0	2.2 A	DC-DC	by SPI	1	0	В	

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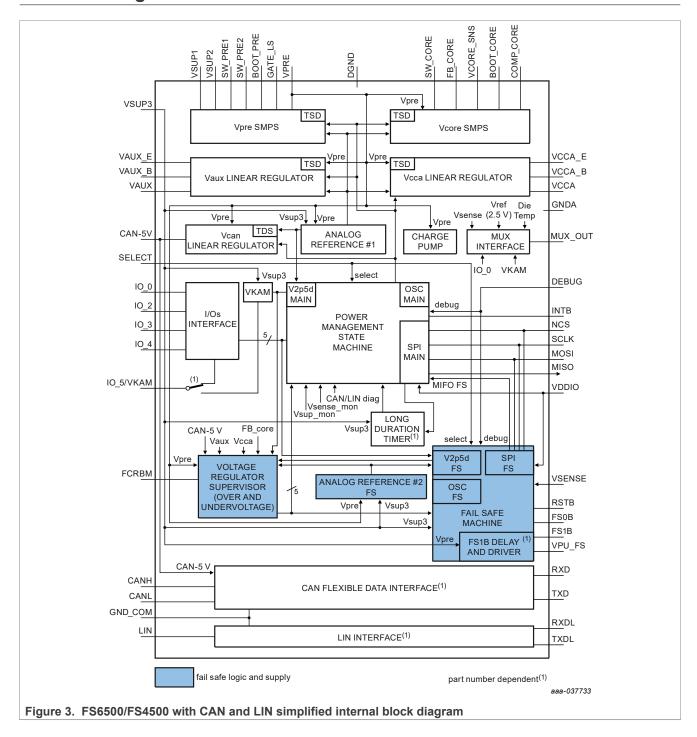
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Table 2. Orderable part variations...continued

Part Number	Temperature (T _A)	Package	FS1B	LDT	VCORE	VCORE type	VKAM On	CAN FD	LIN	ASIL	Notes
MC33FS6525KAE			0	0	2.2 A	DC-DC	by SPI	0	1	В	
MC33FS6525LAE			0	0	2.2 A	DC-DC	by SPI	1	1	В	
MC33FS6526NAE			1	0	2.2 A	DC-DC	by SPI	0	0	В	
MC33FS6526CAE			1	0	2.2 A	DC-DC	by SPI	1	0	В	
MC33FS6527NAE			0	1	2.2 A	DC-DC	by SPI	0	0	В	
MC33FS6527CAE			0	1	2.2 A	DC-DC	by SPI	1	0	В	
MC33FS6527KAE			0	1	2.2 A	DC-DC	by SPI	0	1	В	
MC33FS6527LAE			0	1	2.2 A	DC-DC	by SPI	1	1	В	
MC33FS6528NAE			1	1	2.2 A	DC-DC	by SPI	0	0	В	
MC33FS6528CAE			1	1	2.2 A	DC-DC	by SPI	1	0	В	

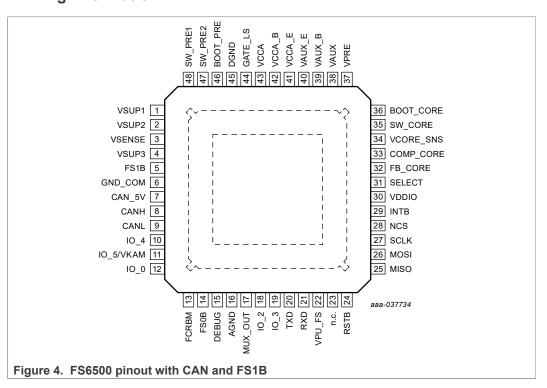
^[1] To order parts in tape and reel, add the R2 suffix to the part number.

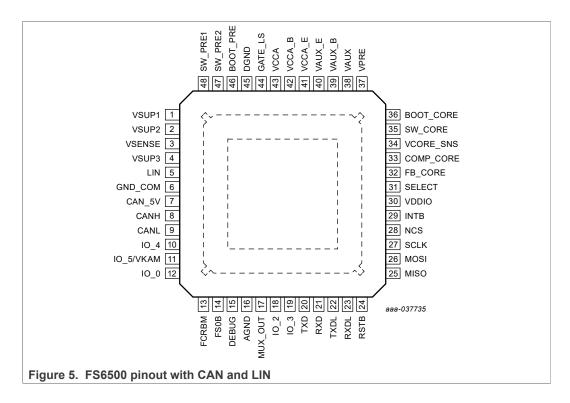
6 Block diagram

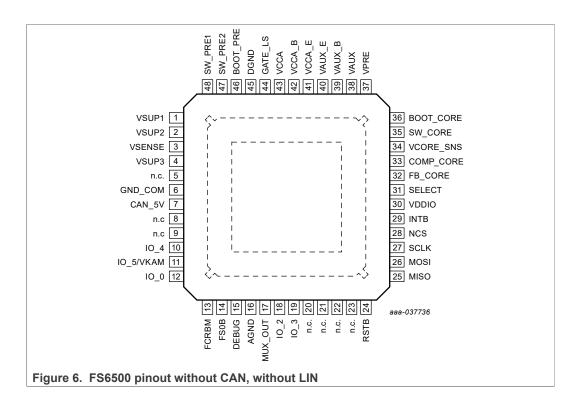


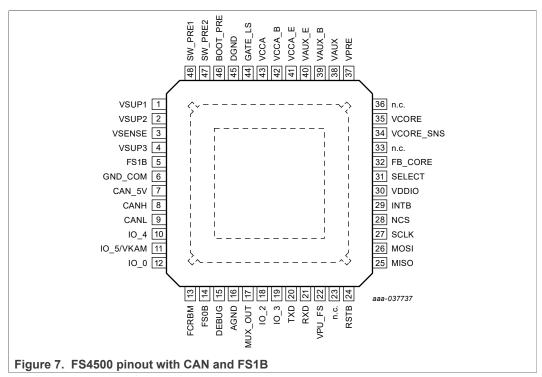
7 Pinning information

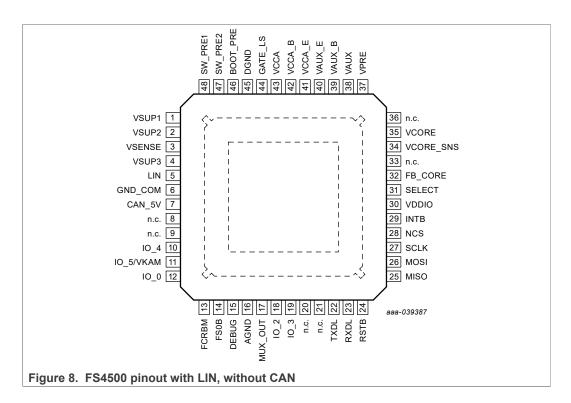
7.1 Pinning information











7.2 Pin description

A functional description of each pin can be found in the full data sheet.

Table 3. FS6500/FS4500 pin definition

Pin number	Pin name	Туре	Definition			
1	VSUP1	A_IN	Power supply of the device. An external reverse battery protection diode in series is mandatory			
2	VSUP2	A_IN	econd power supply. Protected by the external reverse battery protection diode sed for VSUP1. VSUP1 and VSUP2 must be connected together externally.			
3	VSENSE	A_IN	ensing of the battery voltage. Must be connected prior to the reverse battery of otection diode.			
4	VSUP3	A_IN	Third power supply dedicated to the device supply. Protected by the external reverse battery protection diode used for VSUP1. Must be connected between the reverse protection diode and the input PI filter.			
5	LIN	A_IN/OUT	LIN single-wire bus transmitter and receiver.			
	or FS1B	D_OUT	Second output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected, with a configurable delay or duration versus FS0B output terminal. Open drain structure.			
			exclusive. The differentiation is made by part numbers. When LIN is available, FS1B ther LIN, nor FS1B functions are used, this pin must be left open.			
6	GND_COM	GROUND	Dedicated ground for physical layers			
7	CAN_5V	A_OUT	Output voltage for the embedded CAN FD interface			
8	CANH	A_IN/OUT	CAN output high. If CAN function is not used, this pin must be left open.			
9	CANL	A_IN/OUT	CAN output low. If CAN function is not used, this pin must be left open.			

FS6500-FS4500SDS-ASILB

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Table 3. FS6500/FS4500 pin definition...continued

A_OUT Digital input: Pin status can be read through the SPI. Can be used to monitor signals from another IC for safety purposes (when used with IO_5). Wake-up capability: Can be selectable to wake-up on edges or levels. Output gate driver: Can drive a logic level low-side NMOS transistor. Controll the SPI. Can be used as digital input with wake-up capability or as an analog output providing keep alive memory supply in low-power mode. Analog input: Pin status can be read through the SPI. Can be used to monitor signals from another IC for safety purposes (when used with IO_4). Wake-up capability: Can be selectable to wake-up on edges or levels. Supply output: Provide keep alive memory supply in low-power mode. Analog input: Pin status can be read through the SPI. Can be used to monitor signals from another IC for safety purposes (when used with IO_4). Wake-up capability: Can be selectable to wake-up on edges or levels. Supply output: Provide keep alive memory supply in low-power mode Analog input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. ForBM A_IN Feedback core resistor bridge monitoring: For safety purposes, this pin is used monitor the middle point of a redundant resistor bridge connected on V _{CORE} (in parallel to the one used to set the V _{CORE} voltage). If not used, this pin must be connected directly to FB_CORE. First output of the safety block (active low). The pin is asserted low at start-up: when a fault condition is detected. Open drain structure.	Pin number	Pin name	Туре	Definition
D_IN A_OUT Digital input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Can be used to monitor signals from another IC for safety purposes (when used with IO_4), Wake-up capability: Can be selectable to wake-up on edges or levels. Supply output: Provide keep alive memory supply in low-power mode IO_0 A_IN D_IN D_IN Can be used as analog or digital input (load dump proof) with wake-up capability (selectable) Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. FCRBM A_IN Feedback core resistor bridge monitoring: For safety purposes, this pin is used monitor the middle point of a redundant resistor bridge connected on V _{CORE} (in parallel to the one used to set the V _{CORE} voltage). If not used, this pin must be connected directly to FB_CORE. First output of the safety block (active low). The pin is asserted low at start-up: when a fault condition is detected. Open drain structure. Debug mode entry input AGND GROUND Analog ground connection MUX_OUT A_OUT Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. TXD D_IN Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. Transceiver input from the MCU which controls the state of the CAN-bus. Internal put to VDDIO. If CAN function is not used, this pin must be left open. TXDL D_IN Transceiver input from the MCU controlling the state of the LIN bus. Internal put to VDDIO. or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions	10	IO_4	_	Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_5). Wake-up capability: Can be selectable to wake-up on edges or levels. Output gate driver: Can drive a logic level low-side NMOS transistor. Controlled by
Selectable Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels.	11	IO_5/VKAM	D_IN	providing keep alive memory supply in low-power mode. Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_4). Wake-up capability: Can be selectable to wake-up on edges or levels.
monitor the middle point of a redundant resistor bridge connected on V _{CORE} (in parallel to the one used to set the V _{CORE} voltage). If not used, this pin must be connected directly to FB_CORE. 14 FS0B D_OUT First output of the safety block (active low). The pin is asserted low at start-up when a fault condition is detected. Open drain structure. 15 DEBUG D_IN Debug mode entry input 16 AGND GROUND Analog ground connection 17 MUX_OUT A_OUT Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI. 18 IO_2:3 D_IN Digital input pin with wake-up capability (logic level compatible) 19 Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. 20 TXD D_IN Transceiver input from the MCU which controls the state of the CAN-bus. Internative to VDDIO. If CAN function is not used, this pin must be left open. 21 RXD D_OUT Receiver output which reports the state of the CAN-bus to the MCU if CAN function is not used, this pin must be left open. 22 TXDL D_IN Transceiver input from the MCU controlling the state of the LIN bus. Internal put to VDDIO. 23 or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open.	12	10_0	_	Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI.
when a fault condition is detected. Open drain structure. DEBUG D_IN Debug mode entry input AGND GROUND Analog ground connection MUX_OUT A_OUT Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI. Digital input pin with wake-up capability (logic level compatible) Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. TXD D_IN Transceiver input from the MCU which controls the state of the CAN-bus. Internated by the control of the control of the CAN-bus. Internated by the control of the	13	FCRBM	A_IN	Feedback core resistor bridge monitoring: For safety purposes, this pin is used to monitor the middle point of a redundant resistor bridge connected on V_{CORE} (in parallel to the one used to set the V_{CORE} voltage). If not used, this pin must be connected directly to FB_CORE.
AGND GROUND Analog ground connection MUX_OUT A_OUT Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI. INDEX DESCRIPTION DIGITAL INTERPRETATION OF THE PRINCE OF THE P	14	FS0B	D_OUT	First output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected. Open drain structure.
MUX_OUT A_OUT Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI. IO_2:3 D_IN Digital input pin with wake-up capability (logic level compatible) Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. IXD D_IN Transceiver input from the MCU which controls the state of the CAN-bus. Internet pull-up to VDDIO. If CAN function is not used, this pin must be left open. RXD D_OUT Receiver output which reports the state of the CAN-bus to the MCU if CAN function is not used, this pin must be left open. IXDL D_IN Transceiver input from the MCU controlling the state of the LIN bus. Internal put to VDDIO. or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.	15	DEBUG	D_IN	Debug mode entry input
parameter is available at MUX-OUT through the SPI. 18 IO_2:3 D_IN Digital input pin with wake-up capability (logic level compatible) 19 Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. 20 TXD D_IN Transceiver input from the MCU which controls the state of the CAN-bus. Interpull-up to VDDIO. If CAN function is not used, this pin must be left open. 21 RXD D_OUT Receiver output which reports the state of the CAN-bus to the MCU If CAN function is not used, this pin must be left open. 22 TXDL D_IN Transceiver input from the MCU controlling the state of the LIN bus. Internal put to VDDIO. or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. 23 RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.	16	AGND	GROUND	Analog ground connection
Digital input: Pin status can be read through the SPI. Wake-up capability: Can be selectable to wake-up on edges or levels. TXD D_IN Transceiver input from the MCU which controls the state of the CAN-bus. Interpull-up to VDDIO. If CAN function is not used, this pin must be left open. RXD D_OUT Receiver output which reports the state of the CAN-bus to the MCU If CAN function is not used, this pin must be left open. TXDL D_IN Transceiver input from the MCU controlling the state of the LIN bus. Internal put to VDDIO. or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.	17	MUX_OUT	A_OUT	
pull-up to VDDIO. If CAN function is not used, this pin must be left open. RXD D_OUT Receiver output which reports the state of the CAN-bus to the MCU If CAN function is not used, this pin must be left open. TXDL D_IN Transceiver input from the MCU controlling the state of the LIN bus. Internal put to VDDIO. or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.		IO_2:3	D_IN	Digital input: Pin status can be read through the SPI.
If CAN function is not used, this pin must be left open. TXDL D_IN Transceiver input from the MCU controlling the state of the LIN bus. Internal put to VDDIO. or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.	20	TXD	D_IN	1.
to VDDIO. or VPU_FS A_OUT Pull-up output for FS1B function. LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.	21	RXD	D_OUT	· · ·
LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.	22	TXDL	D_IN	Transceiver input from the MCU controlling the state of the LIN bus. Internal pull-up
is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open. RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.		or VPU_FS	A_OUT	Pull-up output for FS1B function.
23 RXDL D_OUT Receiver output reporting the state of the LIN bus to the MCU.		is not, and vi	ce versa.	• •
	23			1

Table 3. FS6500/FS4500 pin definition...continued

Pin number	Pin name	Туре	Definition
24	RSTB	D_OUT	This output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to detect external reset and fault condition. Open drain structure.
25	MISO	D_OUT	SPI bus. Master input slave output
26	MOSI	D_IN	SPI bus. Master output slave input
27	SCLK	D_IN	SPI Bus. Serial clock
28	NCS	D_IN	Not chip select (active low)
29	INTB	D_OUT	This output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.
30	VDDIO	A_IN	Input voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.
31	SELECT	D_IN	Hardware selection pin for VAUX and VCCA output voltages
32	FB_CORE	A_IN	VCORE voltage feedback. Input of the error amplifier.
33	COMP_ CORE	A_OUT	Compensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).
34	VCORE_ SNS	A_IN	VCORE input voltage sense
35	SW_CORE	A_OUT	VCORE output switching point for FS6500 series
	or VCORE	A_OUT	VCORE output voltage for FS4500 series
36	BOOT_ CORE	A_IN/OUT	Bootstrap capacitor for VCORE internal NMOS gate drive For FS4500 series, this pin must be left open (NC).
37	VPRE	A_IN	VPRE input voltage sense
38	VAUX	A_OUT	VAUX output voltage. External PNP ballast transistor. Collector connection
39	VAUX_B	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Base connection
40	VAUX_E	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Emitter connection
41	VCCA_E	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Emitter connection
42	VCCA_B	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Base connection
43	VCCA	A_OUT	VCCA output voltage. External PNP ballast transistor. Collector connection
44	GATE_LS	A_OUT	Low-side MOSFET gate drive for non-inverting buck-boost configuration
45	DGND	GROUND	Digital ground connection
46	BOOT_PRE	A_IN/OUT	Bootstrap capacitor for the VPRE internal NMOS gate drive
47	SW_PRE2	A_OUT	Second pre-regulator output switching point
48	SW_PRE1	A_OUT	First pre-regulator output switching point

8 Maximum ratings

Table 4. Maximum ratings

All voltages are with respect to ground, unless otherwise specified. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Symbol	Ratings	Value	Unit	Notes
Electrical ratio	ngs			
V _{SUP1/2/3}	DC voltage at power supply pins	-1.0 to 40	V	[1]
V _{SENSE}	DC voltage at battery sense pin (with ext R in series mandatory)	-14 to 40	V	
V _{SW1,2}	DC voltage at SW_PRE1 and SW_PRE2 Pins	-1.0 to 40	V	
V _{PRE}	DC voltage at VPRE Pin	-0.3 to 8	V	
V _{GATE_LS}	DC voltage at Gate_LS pin	-0.3 to 8	V	
V _{BOOT_PRE}	DC voltage at BOOT_PRE pin	-1.0 to 50	V	
V _{SW_CORE}	DC voltage at SW_CORE pin	-1.0 to 8	V	
V _{CORE_SNS}	DC voltage at VCORE_SNS pin	0.0 to 8	V	
V _{BOOT_CORE}	DC voltage at BOOT_CORE pin	0.0 to 15	V	
V _{FB_CORE}	DC voltage at FB_CORE pin	-0.3 to 2.5	V	
V _{COMP_CORE}	DC voltage at COMP_CORE pin	-0.3 to 2.5	V	
V _{FCRBM}	DC voltage at FCRBM pin	-0.3 to 8	V	
V _{AUX_B,E}	DC voltage at VAUX_B, VAUX_E pins	-0.3 to 40	V	
V _{AUX}	DC voltage at VAUX pin	-2.0 to 40	V	
V _{CCA_B,E}	DC voltage at VCCA_B, VCCA_E pins	-0.3 to 8	V	
V _{CCA}	DC voltage at VCCA pin	-0.3 to 8	V	
V _{DDIO}	DC voltage at VDDIO pin	-0.3 to 8	V	
V _{CAN_5V}	DC voltage on CAN_5V pin	-0.3 to 8	V	
V _{PU_FS}	DC voltage at VPU_FS pin	-0.3 to 8	V	
V _{FSxB}	DC voltage at FS0B, FS1B pins (with ext R in series mandatory)	-0.3 to 40	V	
V _{DEBUG}	DC voltage at DEBUG pin	-0.3 to 40	V	
V _{IO_0,4}	DC voltage at IO_0, IO_4 pins (with ext R in series mandatory)	-0.3 to 40	V	
V _{IO_5}	DC voltage at IO_5 pin	-0.3 to 20	V	
V _{KAM}	DC voltage at VKAM pin	-0.3 to 8	V	
V_{DIG}	DC voltage at INTB, RSTB, MISO, MOSI, NCS, SCLK, MUX_OUT, RXD, TXD, TXDL, IO_2, IO_3 pins	-0.3 to 8	V	
V _{SELECT}	DC voltage at SELECT pin	-0.3 to 8	V	
V _{BUS_CAN}	DC voltage on CANL, CANH pins	–27 to 40	V	
I_lsense	V _{SENSE} maximum current capability	-5.0 to 5.0	mA	
I_IO _{0, 4, 5}	IOs maximum current capability (IO_0, IO_4, IO_5)	-5.0 to 5.0	mA	
ESD voltage		1		
Human body	model (JESD22/A114) ⁽¹⁹⁾ – 100 pF, 1.5 kΩ			,
V _{ESD-HBM1}	• All pins	±2.0	kV	[2]
V _{ESD-HBM2}	 VSUP1, 2, 3, VSENSE, VAUX, IO_0,4, FS0B, FS1B, DEBUG 	±4.0	kV	
V _{ESD-HBM3}	CANH, CANL	±6.0	kV	
V _{ESD-HBM4}	• LIN	±8.0	kV	

FS6500-FS4500SDS-ASILB

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Table 4. Maximum ratings ...continued

All voltages are with respect to ground, unless otherwise specified. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Symbol	Ratings	Value	Unit	Notes
Charge devic	e model (JESD22/C101) ⁽²⁰⁾ :	·		
V _{ESD-CDM1}	All pins	±500	V	
V _{ESD-CDM2}	Corner pins	±750	V	
System level	ESD (gun test)			
	 VSUP1, 2, 3, VSENSE, VAUX, IO_0, 4, 5, FS0B, FS1B 			
V _{ESD-GUN1}	330 Ω/150 pF unpowered according to IEC 61000-4-2: ⁽¹⁶⁾	±8.0	kV	
V _{ESD-GUN2}	330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance	±8.0	kV	
V _{ESD-GUN3}	2.0 kΩ/150 pF unpowered according to ISO 10605 $^{(15)}$	±8.0	kV	
V _{ESD-GUN4}	2.0 kΩ/330 pF powered according to ISO 10605 ⁽¹⁵⁾	±8.0	kV	
	CANH, CANL			
V _{ESD-GUN5}	330 $\Omega/150$ pF unpowered according to IEC 61000-4-2: (16)	±15.0	kV	
V _{ESD-GUN6}	330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance	±12.0	kV	
V _{ESD-GUN7}	2.0 kΩ/150 pF unpowered according to ISO 10605 $^{(15)}$	±15.0	kV	
V _{ESD-GUN8}	2.0 kΩ/330 pF powered according to ISO 10605 ⁽¹⁵⁾	±12.0	kV	
	• LIN			
V _{ESD-GUN9}	330 Ω/150 pF unpowered according to IEC 61000-4-2: ⁽¹⁶⁾	±12.0	kV	
V _{ESD-GUN10}	330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay conformance	±12.0	kV	
V _{ESD-GUN11}	2.0 kΩ/150 pF unpowered according to ISO 10605 ⁽¹⁵⁾	±12.0	kV	
V _{ESD-GUN12}	2.0 kΩ/330 pF powered according to ISO 10605 ⁽¹⁵⁾	±12.0	kV	
Thermal ratin	gs			
T _A	Ambient temperature	-40 to 125	°C	
T _J	Junction temperature	-40 to 150	°C	
T _{STG}	Storage temperature	-55 to 150	°C	
Thermal resis	stance			
$R_{\theta JA}$	Thermal resistance junction to ambient	30	°C/W	[3]
R ₀ JCTOP	Thermal resistance junction to case top	23.8	°C/W	[4]
$R_{\theta JCBOTTOM}$	Thermal resistance junction to case bottom	0.9	°C/W	[5]

All V_{SUPS} ($V_{SUP1/2/3}$) must be connected to the same supply (Figure 1). Compared to AGND.

^[1] [2]

Per JEDEC JESD51-6⁽¹⁷⁾ with the board (JESD51-7)⁽¹⁸⁾ horizontal. [3]

^[4] Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC - 883 Method 1012.1)(21)

Thermal resistance between the die and the solder pad on the bottom of the packaged based on simulation without any interface resistance.

9 Packaging

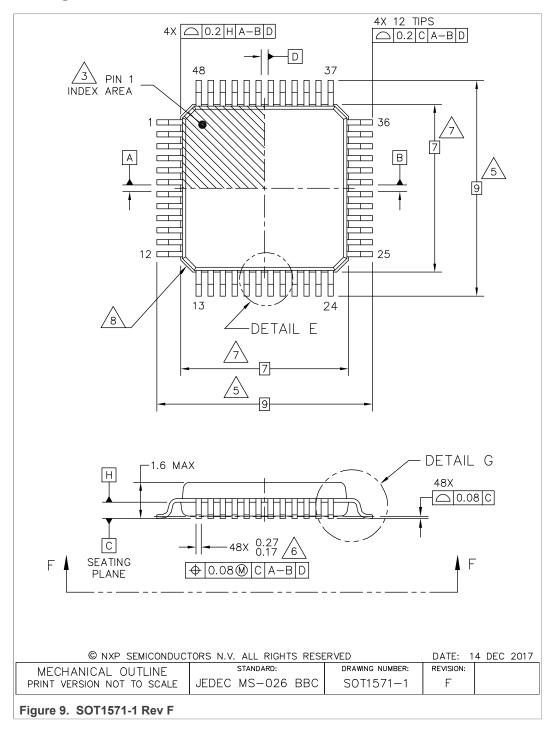
9.1 Package mechanical dimensions

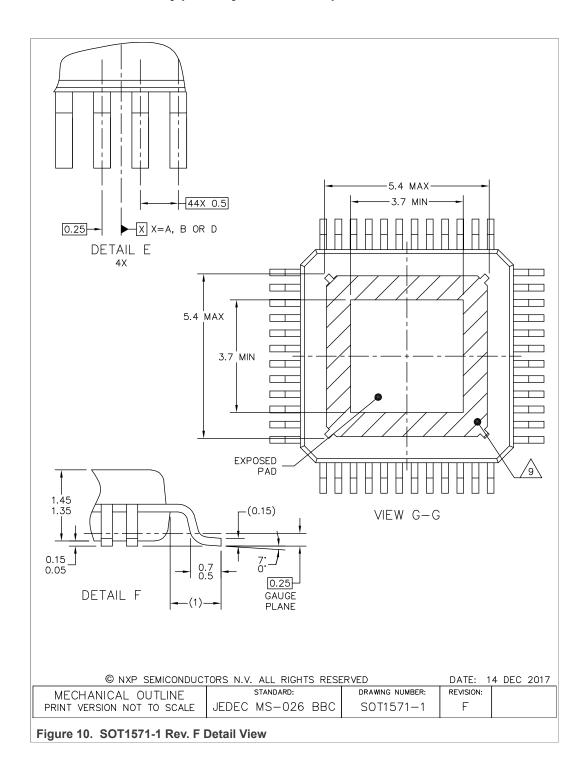
Package dimensions are provided in package drawings. To find the most current package outline drawing, go to www.nxp.com and perform a keyword search for the drawing's document number.

Table 5. Package mechanical dimensions

Package	Suffix	Package outline drawing number
7.0×7.0 , 48–Pin LQFP exposed pad, with 0.5 mm pitch, and a 4.5 × 4.5 exposed pad	AE	98ASA00173D

9.2 Package outline





NOTES: 1. DIMENSIONS ARE IN MILLIMETERS. 2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994. $\sqrt{3}$. PIN 1 FEATURE SHAPE, SIZE AND LOCATION MAY VARY. 4. DATUMS A, B AND D TO BE DETERMINED AT DATUM PLANE H. $\sqrt{5}$ dimension to be determined at seating plane c. $\stackrel{\frown}{6}$ this dimension does not include dambar protrusion. Allowable dambar PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE UPPER LIMIT BY MORE THAN 0.08MM AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT BE LESS THAN 0.07MM. THIS DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25MM PER SIDE. THIS DIMENSION IS MAXIMUM PLASTIC BODY SIZE DIMENSION INCLUDING MOLD MISMATCH. /8\ EXACT SHAPE OF EACH CORNER IS OPTIONAL. $\cancel{9}$ hatched area to be keep out zone for PCB routing. © NXP SEMICONDUCTORS N.V. ALL RIGHTS RESERVED DATE: 14 DEC 2017 STANDARD: DRAWING NUMBER: REVISION:

JEDEC MS-026 BBC

SOT1571-1

F

Figure 11. SOT1571-1 Rev F Notes

MECHANICAL OUTLINE PRINT VERSION NOT TO SCALE

10 Soldering

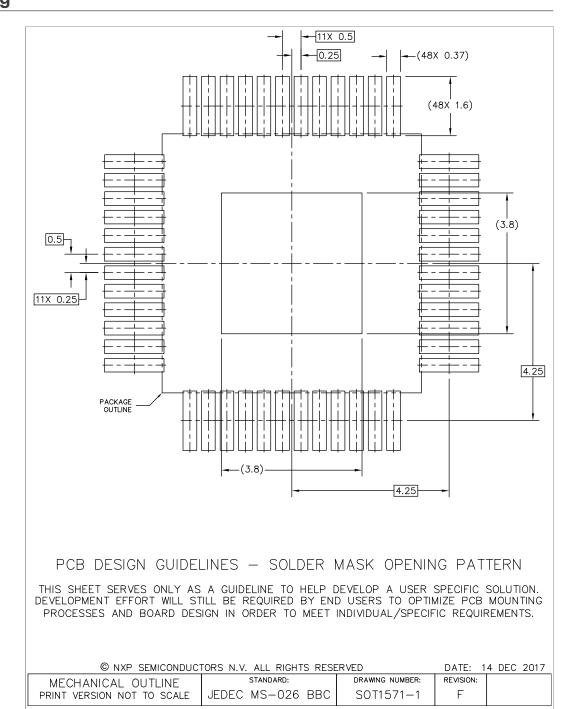


Figure 12. SOT1571-1 Rev. F - PCB design guidelines - solder mask opening pattern

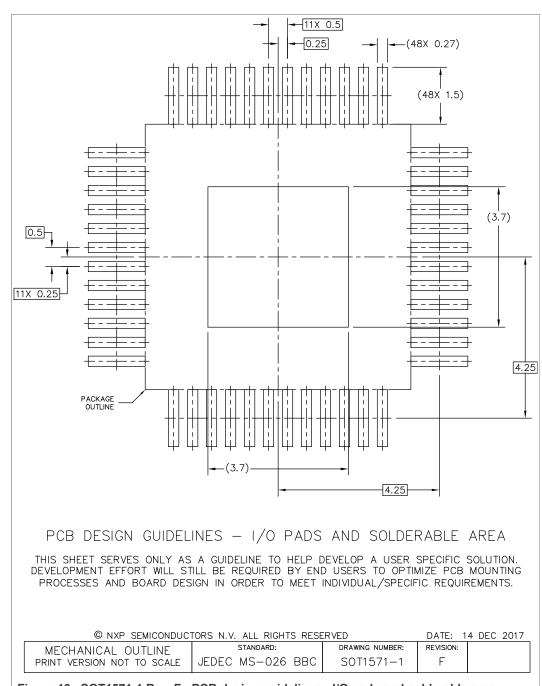


Figure 13. SOT1571-1 Rev. F - PCB design guidelines - I/O pads and solderable area

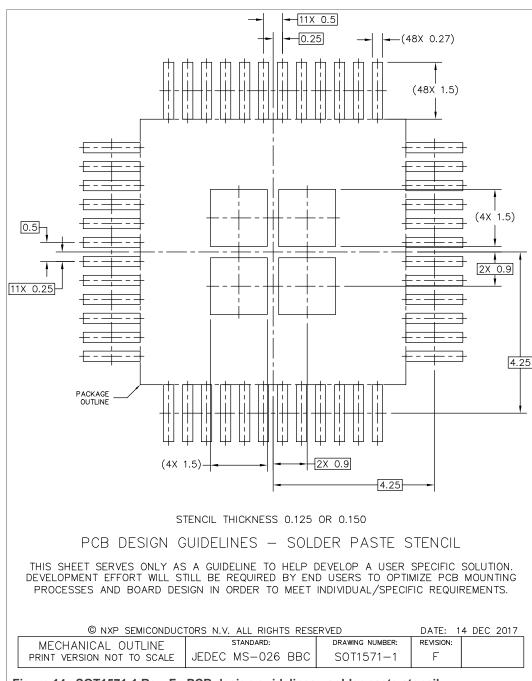


Figure 14. SOT1571-1 Rev. F - PCB design guidelines - solder paste stencil

11 References

Obtain additional information on related NXP products and application solutions through the documents and URLs listed below.

- (1) **AN5238** FS6500 and FS4500 Safe System Basis Chip Hardware Design and Product Guidelines Application Note https://www.nxp.com/AN5238-DOWNLOAD
- (2) AN4388 Quad Flat Package (QFP) https://www.nxp.com/files/analog/doc/app_note/AN4388.pdf
- (3) **FS6500-FS4500PDTCALC** Power dissipation tool (Excel File) https://www.nxp.com/files/analog/software_tools/FS6500-FS4500-power-dissipation-calculator.xlsx
- (4) V_{CORE} compensation network simulation tool (CNC)^[1]
- (5) **FMEDA** FS6500/FS4500 ASILB FMEDA^[1]
- (6) UM11498 FS6500/FS4500 ASILB Safety manual user guide
- (7) KITFS6507LAEEVM FS6507, System Basis Chip, ASIL B, DC-DC 0.8 A Vcore, LDT, CAN, LIN https://www.nxp.com/KITFS6507LAEEVM
- (8) KITFS4508CAEEVM FS4508, System Basis Chip, ASIL B, Linear 0.5 A Vcore, FS1b, LDT, CAN https://www.nxp.com/KITFS4508CAEEVM
- (9) FS6500 product summary page https://www.nxp.com/FS6500
- (10) FS4500 product summary page https://www.nxp.com/FS4500
- (11) Analog power management homepage https://www.nxp.com/products/power-management
- (12) **ISO 11898-2:2003** Road vehicles Controller area network (CAN) Part 2: High-speed medium access unit https://www.iso.org/standard/33423.html
- (13) **ISO 11898-5:2007** Road vehicles Controller area network (CAN) Part 5: High-speed medium access unit with low-power mode https://www.iso.org/contents/data/standard/04/12/41284.html
- (14) ISO 7637-2:2011 Road vehicles Electrical disturbances from conduction and coupling Part 2: Electrical transient conduction along supply lines only https://www.iso.org/standard/50925.html
- (15) ISO 10605:2008 Road vehicles Test methods for electrical disturbances from electrostatic discharge https://www.iso.org/standard/41937.html
- (16) IEC 61000-4-2:2008 Electromagnetic compatibility (EMC) Part 4-2: Testing and measurement techniques -Electrostatic discharge immunity test https://webstore.iec.ch/publication/4189
- (17) **JESD51-6** INTEGRATED CIRCUIT THERMAL TEST METHOD ENVIRONMENTAL CONDITIONS FORCED CONVECTION (MOVING AIR)
- (18) **JESD51-7** HIGH EFFECTIVE THERMAL CONDUCTIVITY TEST BOARD FOR LEADED SURFACE MOUNT PACKAGES
- (19) JESD22-A114F ELECTROSTATIC DISCHARGE (ESD) SENSITIVITY TESTING HUMAN BODY MODEL (HBM)
- (20) **JESD22-C101F** FIELD-INDUCED CHARGED-DEVICE MODEL TEST METHOD FOR ELECTROSTATIC DISCHARGE WITHSTAND THRESHOLDS OF MICROELECTRONIC COMPONENTS
- (21) MIL-STD-883-1, Method 1012.1 TEST METHOD STANDARD MICROCIRCUITS

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- (22) LIN Specification Package Revision 2.1:2006
 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN-Spec_Pac2_1.pdf
- (23) LIN Specification Package Revision 2.2A:2010 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN_2.2A.pdf
- (24) SAE J2602-2:201211 LIN Network for Vehicle Applications Conformance Test https://www.sae.org/standards/content/j2602/2_201211/
- [1] Available upon request.

12 Revision history

Table 6. Revision history

Document ID	Release date	Data sheet status	Supersedes		
FS6500-FS4500SDS-ASILB v.3.0	20210414	Product	FS6500-FS4500SDS-ASILB v.2.0		
Modifications	 Section 1: replaced "0.8 A" by "1.5 A" Section 2: replaced "Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A) or LDO (0.5 A)" to "Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A, 1.5 A or 2.2 A) or LDO (0.5 A)" Section 5: updated Table 1 and Table 2 (added new part numbers) 				
FS6500-FS4500SDS-ASILB v.2.0	20210111	Product	FS6500-FS4500SDS-ASILB v.1.3		
Modifications	 Revised data sheet status from "Preliminary" to "Product". Section 5.2, revised Table 2 changing "PC33" parts to "MC33" Section 7.2, pin number 11, removed "VKAM can be enabled or disabled by default at power up. The differentiation is made by part numbers." 				
FS6500-FS4500SDS-ASILB v.1.3	20201106	Preliminary	_		
Modifications	 Initial release (Short data sheet version aligned to full data sheet, FS6500, FS4500: ASILB, v.1.3) 				

13 Legal information

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Document status ^{[1][2]}	Product status ^[3]	Definition
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Product short data sheet

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FS6500, FS4500: ASIL B

Safety power system basis chip with CAN FD and LIN transceivers

Tables

Tab. 1. Tab. 2. Tab. 3.	Part number breakdown	Tab. 4. Tab. 5. Tab. 6.	Maximum ratings
Figur	es		
Fig. 1.	FS6500C simplified application diagram -	Fig. 8.	FS4500 pinout with LIN, without CAN
-	buck boost configuration - FS1B2	Fig. 9.	SOT1571-1 Rev F1
Fig. 2.	FS4500C simplified application diagram -	Fig. 10.	SOT1571-1 Rev. F Detail View1
	buck boost configuration - FS1B3	Fig. 11.	SOT1571-1 Rev F Notes 1
Fig. 3.	FS6500/FS4500 with CAN and LIN	Fig. 12.	SOT1571-1 Rev. F - PCB design guidelines
	simplified internal block diagram6		- solder mask opening pattern 1
Fig. 4.	FS6500 pinout with CAN and FS1B7	Fig. 13.	SOT1571-1 Rev. F - PCB design guidelines
Fig. 5.	FS6500 pinout with CAN and LIN7		- I/O pads and solderable area1
Fig. 6.	FS6500 pinout without CAN, without LIN 8	Fig. 14.	SOT1571-1 Rev. F - PCB design guidelines
Fig. 7.	FS4500 pinout with CAN and FS1B8		- solder paste stencil2

Contents

1	General description	1
2	Features and benefits	
3	Applications	1
4	Simplified application diagrams	2
5	Ordering information	
5.1	Part number definition	3
5.2	Part numbers list	4
6	Block diagram	6
7	Pinning information	7
7.1	Pinning information	7
7.2	Pin description	9
8	Maximum ratings	12
9	Packaging	
9.1	Package mechanical dimensions	
9.2	Package outline	
10	Soldering	
11	References	
12	Revision history	
13	Legal information	

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