

MC9S08LL64 Rev. 7.1, 08/2012

# MC9S08LL64 Series Data Sheet

by: Automotive and Industrial Solutions Group

This is the MC9S08LL64 Series Data Sheet set consisting of the following files:

- MC9S08LL64 Data Sheet Addendum, Rev 1
- MC9S08LL64 Series Data Sheet, Rev 7





# Freescale Semiconductor Data Sheet Addendum

MC9S08LL64AD Rev. 1, 08/2012

# MC9S08LL64 Data Sheet Addendum

by: Automotive and Industrial Solutions Group

This document describes corrections to the *MC9S08LL64 Series Data Sheet*, order number MC9S08LL64. For convenience, the addenda items are grouped by revision. Please check our website at http://www.freescale.com for the latest updates.

The current available version of the MC9S08LL64 Series Data Sheet is Revision 7.

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**Addendum for Revision 7** 

# 1 Addendum for Revision 7

Table 1. MC9S08LL64 Data Sheet Rev 7 Addendum

Location		Description					
Section 3.7, "Supply Current Characteristics"/Table 9/Page 23	In the table, for	ne table, for numbers 3 and 4, change "LPS" to "LPR".					
Section 3.12, "ADC Characteristics"/Page 33	Add the followin	dd the following data of the ADC conversion clock frequency:					
	Characteris tic	Conditions	Symb	Min	Тур	Max	Unit
	ADC	ADLPC=0, ADHSC=1	f <sub>ADCK</sub>	1.0	_	8	MHz
	Conversion Clock	ADLPC=0, ADHSC=0		1.0	_	5	
	Frequency	ADLPC=1, ADHSC=0		1.0	_	2.5	

# 2 Revision History

Table 2 provides a revision history for this document.

**Table 2. Revision History Table** 

Rev. Number	Substantive Changes	Date of Release
1.0	Initial release. Correct errors in the following sections:  • Section 3.7, "Supply Current Characteristics"  • Section 3.12, "ADC Characteristics"	07/2012



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MC9S08LL64AD Rev. 1 08/2012



# Freescale Semiconductor Data Sheet: Technical Data

An Energy Efficient Solution by Freescale

# MC9S08LL64 Series

Covers: MC9S08LL64 and MC9S08LL36

- 8-Bit HCS08 Central Processor Unit (CPU)
  - Up to 40 MHz CPU at 3.6 V to 2.1 V across temperature range of –40 °C to 85 °C
  - Up to 20 MHz at 2.1 V to 1.8 V across temperature range of –40 °C to 85 °C
  - HC08 instruction set with added BGND instruction
  - Support for up to 32 interrupt/reset sources
- · On-Chip Memory
  - Dual array flash read/program/erase over full operating voltage and temperature
  - Random-access memory (RAM)
  - Security circuitry to prevent unauthorized access to RAM and flash contents
- · Power-Saving Modes
  - Two low-power stop modes
  - Reduced-power wait mode
  - Low-power run and wait modes allow peripherals to run while voltage regulator is in standby
  - Peripheral clock gating register can disable clocks to unused modules, thereby reducing currents
  - Very low-power external oscillator that can be used in stop2 or stop3 modes to provide accurate clock source to time-of-day (TOD) module
  - 6 μs typical wakeup time from stop3 mode
- Clock Source Options
  - Oscillator (XOSC) Loop-control Pierce oscillator; crystal or ceramic resonator range of 31.25 kHz to 38.4 kHz or 1 MHz to 16 MHz
  - Internal Clock Source (ICS) Internal clock source module containing a frequency-locked-loop (FLL) controlled by internal or external reference; precision trimming of internal reference allows 0.2% resolution and 2% deviation over temperature and voltage; supporting bus frequencies from 1 MHz to 20 MHz
- · System Protection
  - Watchdog computer operating properly (COP) reset with option to run from dedicated 1 kHz internal clock source or bus clock
  - Low-voltage warning with interrupt
  - Low-voltage detection with reset or interrupt
  - Illegal opcode detection with reset; illegal address detection with reset
  - Flash block protection
- Development Support
  - Single-wire background debug interface
  - Breakpoint capability to allow single breakpoint setting during in-circuit debugging (plus two more breakpoints in on-chip debug module)
  - On-chip in-circuit emulator (ICE) debug module containing three comparators and nine trigger modes

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Rev. 7, 4/2012





64-LQFP Case 840F



80-LQFP Case 917A

#### Peripherals

- LCD Up to 8×36 or 4×40 LCD driver with internal charge pump and option to provide an internally-regulated LCD reference that can be trimmed for contrast control
- ADC —10-channel, 12-bit resolution; up to 2.5  $\mu s$  conversion time; automatic compare function; temperature sensor; operation in stop3; fully functional from 3.6 V to 1.8 V
- IIC Inter-integrated circuit bus module to operate at up to 100 kbps with maximum bus loading; multi-master operation; programmable slave address; interrupt-driven byte-by-byte data transfer; broadcast mode; 10-bit addressing
- ACMP Analog comparator with selectable interrupt on rising, falling, or either edge of comparator output; compare option to fixed internal reference voltage; outputs can be optionally routed to TPM module; operation in stop3
- SCIx Two full-duplex non-return to zero (NRZ) modules (SCI1 and SCI2); LIN master extended break generation; LIN slave extended break detection; wakeup on active edge
- SPI Full-duplex or single-wire bidirectional;
   double-buffered transmit and receive; master or slave mode; MSB-first or LSB-first shifting
- TPMx Two 2-channel (TPM1 and TPM2); selectable input capture, output compare, or buffered edge- or center-aligned PWM on each channel
- TOD (Time-of-day) 8-bit, quarter second counter with match register; external clock source for precise time base, time-of-day, calendar, or task scheduling functions
- VREFx Trimmable via an 8-bit register in 0.5 mV steps; automatically loaded with room temperature value upon reset; can be enabled to operate in stop3 mode; trim register is not available in stop modes.
- · Input/Output
  - Dedicated accurate voltage reference output pin, 1.15 V output (VREFOx); trimmable with 0.5 mV resolution
  - Up to 39 GPIOs, two output-only pins
  - Hysteresis and configurable pullup device on all input pins; configurable slew rate and drive strength on all output pins
- · Package Options
  - 14mm × 14mm 80-pin LQFP, 10 mm × 10 mm 64-pin LQFP





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# **Revision History**

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

http://freescale.com/

The following revision history table summarizes changes contained in this document.

Rev	Date	Description of Changes
3	03/2009	Incorporated revisions for customer release.
4	08/2009	Completed all the TBDs; corrected Pin out in the Figure 2, Figure 3 and Table 2; updated $V_{OH}$ , $II_{In}I$ , $II_{OZ}I$ , $R_{PU}$ , $R_{PD}$ , added $II_{INT}I$ in the Table 8; updated Table 9; updated ERREFSTEN and added LCD in the Table 10; updated $I_{ADACK}I$ , $I$
5	1/2010	Added 80-pin LQFP package information for MC9S08LL36.
6	6/2011	Changed the ERREFSTEN to EREFSTEN, updated the VREFOx to 1.15 V Added LCD specification in the Table 10.
7	4/2012	Updated II <sub>In</sub> I in the Table 8.

# **Related Documentation**

Find the most current versions of all documents at: http://www.freescale.com

Reference Manual —MC9S08LL64RM

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.





# 1 Devices in the MC9S08LL64 Series

Table 1 summarizes the feature set available in the MC9S08LL64 series of MCUs.

Table 1. MC9S08LL64 Series Features by MCU and Package

Feature	MC9S08	BLL64	MC9S08LL36		
Package	80-pin LQFP	64-pin LQFP	80-pin LQFP	64-pin LQFP	
FLASH	64 k (32,768 and 32		36 K (24,576 and 12		
RAM	400	00	4000	0	
ACMP	yes	S	yes	i	
ADC	10-ch	8-ch	10-ch	8-ch	
IIC	yes	S	yes	1	
IRQ	yes	S	yes	1	
KBI	8		8		
SCI1	yes	S	yes		
SCI2	yes	S	yes	i	
SPI	yes	S	yes	i	
TPM1	2-c	h	2-ch	1	
TPM2	2-c	h	2-ch	1	
TOD	yes		yes	1	
LCD	8×36 4×40	8×24 4×28	8×36 4×40	8×24 4×28	
VREFO1	yes	no	yes	no	
VREFO2	no	yes	no	yes	
I/O pins <sup>1</sup>	39	37	39	37	

<sup>&</sup>lt;sup>1</sup> The 39 I/O pins include two output-only pins and 18 LCD GPIO.

The block diagram in Figure 1 shows the structure of the MC9S08LL64 series MCU.



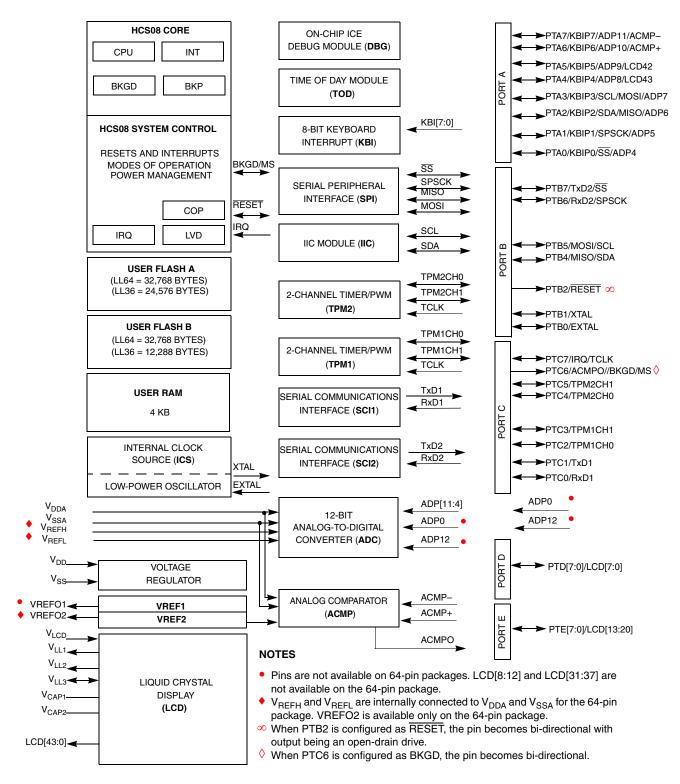


Figure 1. MC9S08LL64 Series Block Diagram



# 2 Pin Assignments

This section shows the pin assignments for the This section shows the pin assignments for the MC9S08LL64 series devices.

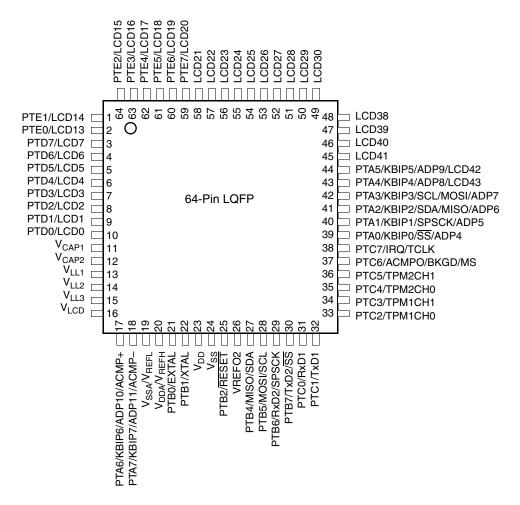


Figure 2. 64-Pin LQFP



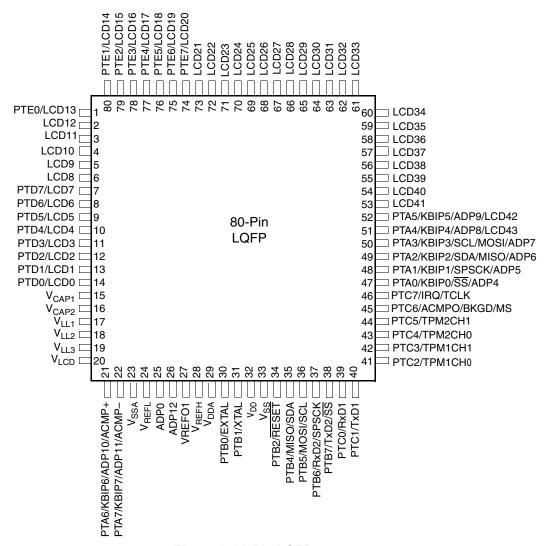


Figure 3. 80-Pin LQFP

Table 2. Pin Availability by Package Pin-Count

		< Lowest Priority> Highest					
80	64	Port Pin	Alt 1	Alt 2	Alt3	Alt4	
1	2	PTE0	LCD13				
2		LCD12					
3		LCD11					
4		LCD10					
5		LCD9					
6		LCD8					

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Table 2. Pin Availability by Package Pin-Count (continued)

		< Lowest Priority> Highest						
80	64	Port Pin	Alt 1	Alt 2	Alt3	Alt4		
7	3	PTD7	LCD7					
8	4	PTD6	LCD6					
9	5	PTD5	LCD5					
10	6	PTD4	LCD4					
11	7	PTD3	LCD3					
12	8	PTD2	LCD2					
13	9	PTD1	LCD1					
14	10	PTD0	LCD0					
15	11	V <sub>CAP1</sub>						
16	12	V <sub>CAP2</sub>						
17	13	V <sub>LL1</sub>						
18	14	$V_{LL2}$						
19	15	$V_{LL3}$						
20	16	$V_{LCD}$						
21	17	PTA6	KBIP6	ADP10	ACMP+			
22	18	PTA7	KBIP7	ADP11	ACMP-			
23	19	V <sub>SSA</sub>						
24	19	V <sub>REFL</sub>						
25		ADP0						
26		ADP12						
27		VREFO1						
28	20	V <sub>REFH</sub>						
29	20	$V_{DDA}$						
30	21	PTB0		EXTAL				
31	22	PTB1		XTAL				
32	23	$V_{DD}$						
33	24	$V_{SS}$						
34	25	PTB2	RESET					
	26	VREFO2						
35	27	PTB4	MISO	SDA				
36	28	PTB5	MOSI	SCL				
37	29	PTB6	RxD2	SPSCK				
38	30	PTB7	TxD2	SS				
39	31	PTC0	RxD1					
40	32	PTC1	TxD1					
41	33	PTC2	TPM1CH0					
42	34	PTC3	TPM1CH1					
43	35	PTC4	TPM2CH0					



Table 2. Pin Availability by Package Pin-Count (continued)

	< Lowest Priority> Highest					
80	64	Port Pin	Alt 1	Alt 2	Alt3	Alt4
44	36	PTC5	TPM2CH1			
45	37	PTC6	ACMPO	BKGD	MS	
46	38	PTC7	IRQ	TCLK		
47	39	PTA0	KBIP0		SS	ADP4
48	40	PTA1	KBIP1		SPSCK	ADP5
49	41	PTA2	KBIP2	SDA	MISO	ADP6
50	42	PTA3	KBIP3	SCL	MOSI	ADP7
51	43	PTA4	KBIP4	ADP8	LCD43	
52	44	PTA5	KBIP5	ADP9	LCD42	
53	45	LCD41				
54	46	LCD40				
55	47	LCD39				
56	48	LCD38				
57		LCD37				
58		LCD36				
59		LCD35				
60		LCD34				
61		LCD33				
62		LCD32				
63		LCD31				
64	49	LCD30				
65	50	LCD29				
66	51	LCD28				
67	52	LCD27				
68	53	LCD26				
69	54	LCD25				
70	55	LCD24				
71	56	LCD23				
72	57	LCD22				
73	58	LCD21				
74	59	PTE7	LCD20			
75	60	PTE6	LCD19			
76	61	PTE5	LCD18			
77	62	PTE4	LCD17			
78	63	PTE3	LCD16			
79	64	PTE2	LCD15			
80	1	PTE1	LCD14			



# 3 Electrical Characteristics

### 3.1 Introduction

This section contains electrical and timing specifications for the MC9S08LL64 series of microcontrollers available at the time of publication.

# 3.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding, the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

**Table 3. Parameter Classifications** 

Р	Those parameters are guaranteed during production testing on each individual device.
С	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
Т	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
D	Those parameters are derived mainly from simulations.

#### NOTE

The classification is shown in the column labeled "C" in the parameter tables where appropriate.

# 3.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in Table 4 may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high-static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{DD}$ ) or the programmable pullup resistor associated with the pin is enabled.

**Table 4. Absolute Maximum Ratings** 

Rating	Symbol	Value	Unit
Supply voltage	$V_{DD}$	-0.3 to +3.8	٧
Maximum current into V <sub>DD</sub>	I <sub>DD</sub>	120	mA
Digital input voltage	V <sub>In</sub>	$-0.3$ to $V_{DD} + 0.3$	V
Instantaneous maximum current Single pin limit (applies to all port pins) <sup>1, 2, 3</sup>	I <sub>D</sub>	± 25	mA
Storage temperature range	T <sub>stg</sub>	-55 to 150	°C

Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V<sub>DD</sub>) and negative (V<sub>SS</sub>) clamp voltages, then use the larger of the two resistance values.

#### 3.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take  $P_{I/O}$  into account in power calculations, determine the difference between actual pin voltage and  $V_{SS}$  or  $V_{DD}$  and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and  $V_{SS}$  or  $V_{DD}$  will be very small.

**Table 5. Thermal Characteristics** 

Rating	Symbol	Value	Unit		
Operating temperature range (packaged)	T <sub>A</sub>	T <sub>L</sub> to T <sub>H</sub> -40 to 85	°C		
Maximum junction temperature	$T_J$	95	°C		
Thermal resistance Single-layer board					
80-pin LQFP	Δ	55	°C/W		
64-pin LQFP	$\theta_{\sf JA}$	73	O/VV		
Thermal resistance Four-layer board					
80-pin LQFP	0	42	°C/W		
64-pin LQFP	$\theta_{\sf JA}$	54	O/ VV		

The average chip-junction temperature (T<sub>I</sub>) in °C can be obtained from:

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 $<sup>^{2}</sup>$  All functional non-supply pins, except for PTB2 are internally clamped to  $V_{SS}$  and  $V_{DD}$ .

Power supply must maintain regulation within operating V<sub>DD</sub> range during instantaneous and operating maximum current conditions. If positive injection current (V<sub>In</sub> > V<sub>DD</sub>) is greater than I<sub>DD</sub>, the injection current may flow out of V<sub>DD</sub> and could result in external power supply going out of regulation. Ensure external V<sub>DD</sub> load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).



$$T_{J} = T_{A} + (P_{D} \times \theta_{JA})$$
 Eqn. 1

where:

 $T_A = Ambient temperature, °C$ 

 $\theta_{JA}$  = Package thermal resistance, junction-to-ambient, °C/W

 $P_{D} = P_{int} + P_{I/O}$ 

 $P_{int} = I_{DD} \times V_{DD}$ , Watts — chip internal power

 $P_{I/O}$  = Power dissipation on input and output pins — user determined

For most applications,  $P_{I/O} \ll P_{int}$  and can be neglected. An approximate relationship between  $P_D$  and  $T_J$  (if  $P_{I/O}$  is neglected) is:

$$P_D = K \div (T_{.1} + 273^{\circ}C)$$
 Eqn. 2

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_\Delta + 273^{\circ}C) + \theta_{A\Delta} \times (P_D)^2$$
 Eqn. 3

where K is a constant pertaining to the particular part. K can be determined from Equation 3 by measuring  $P_D$  (at equilibrium) for a known  $T_A$ . Using this value of K, the values of  $P_D$  and  $T_J$  can be obtained by solving Equation 1 and Equation 2 iteratively for any value of  $T_A$ .

# 3.5 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions should be taken to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits. During the device qualification, ESD stresses were performed for the human body model (HBM), the machine model (MM) and the charge device model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless instructed otherwise in the device specification.

Table 6. ESD and Latch-up Test Conditions

odel Description Symbol Va

Model	Description	Symbol	Value	Unit
	Series resistance	R1	1500	Ω
Human body model	Storage capacitance	С	100	pF
	Number of pulses per pin	_	3	
Charge	Series resistance	R1	0	Ω
device	Storage capacitance	С	200	pF
model	Number of pulses per pin	_	3	

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#### **DC Characteristics**

Table 6. ESD and Latch-up Test Conditions (continued)

Model	Description	Symbol	Value	Unit
Latch-up	Minimum input voltage limit		-2.5	٧
Lateri-up	Maximum input voltage limit		7.5	V

**Table 7. ESD and Latch-Up Protection Characteristics** 

No.	Rating <sup>1</sup>	Symbol	Min	Max	Unit
1	Human body model (HBM)	V <sub>HBM</sub>	±2000	_	V
2	Charge device model (CDM)	V <sub>CDM</sub>	±500	_	V
3	Latch-up current at T <sub>A</sub> = 85°C	I <sub>LAT</sub>	±100	_	mA

Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

# 3.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

**Table 8. DC Characteristics** 

Num	С	C	Characteristic	Symbol	Condition	Min	Typ <sup>1</sup>	Max	Unit
1		Operating Vol	tage			1.8		3.6	V
	С	PTA[0:3], PTA[6:7], PTB[0:7], PTC[0:7] <sup>2</sup> , low-drive strength		l I	$V_{DD} > 1.8 \text{ V}$ $I_{Load} = -0.6 \text{ mA}$	V <sub>DD</sub> - 0.5	_	_	
2	Р	Output high - voltage	PTA[0:3], PTA[6:7], PTB[0:7], PTC[0:7] <sup>2</sup> ,	'] <sup>2</sup> ,	$V_{DD} > 2.7 \text{ V}$ $I_{Load} = -10 \text{ mA}$	V <sub>DD</sub> – 0.5	_	_	V
	О		high-drive strength		$V_{DD} > 1.8 V$ $I_{Load} = -3 \text{ mA}$	V <sub>DD</sub> – 0.5	1	1	
	С	Output high voltage	PTA[4:5], PTD[0:7], PTE[0:7], low-drive strength	PTE[0:7], w-drive strength [4:5], PTD[0:7], PTE[0:7],	$V_{DD} > 1.8 \text{ V}$ $I_{Load} = -0.5 \text{ mA}$	V <sub>DD</sub> - 0.5	-	-	
3	Р		PTA[4:5], PTD[0:7],		$V_{DD} > 2.7 \text{ V}$ $I_{Load} = -2.5 \text{ mA}$	V <sub>DD</sub> - 0.5	_	_	V
	С		high-drive strength		$V_{DD} > 1.8 V$ $I_{Load} = -1 \text{ mA}$	V <sub>DD</sub> – 0.5	1	_	
4	D	Output high current	Max total I <sub>OH</sub> for all ports	I <sub>OHT</sub>		_	_	100	mA
	C	0.11	PTA[0:3], PTA[6:7], PTB[0:7], PTC[0:7], low-drive strength		$V_{DD} > 1.8 \text{ V}$ $I_{Load} = 0.6 \text{ mA}$	_	_	0.5	
5		Output low - voltage	PTA[0:3], PTA[6:7], PTB[0:7], PTC[0:7],		$V_{DD} > 2.7 V$ $I_{Load} = 10 \text{ mA}$	_	_	0.5	V
			high-drive strength	l I	$V_{DD} > 1.8 V$ $I_{Load} = 3 \text{ mA}$	_	_	0.5	



# **Table 8. DC Characteristics (continued)**

Num	С		Characteristic	Symbol	Condition	Min	Typ <sup>1</sup>	Max	Unit
	С	Outrout law	PTA[4:5], PTD[0:7], PTE[0:7], low-drive strength		V <sub>DD</sub> > 1.8 V I <sub>Load</sub> = 0.5 mA	_	_	0.5	
6	Р	Output low voltage	PTA[4:5], PTD[0:7], PTE[0:7],	$V_{OL}$	$V_{DD} > 2.7 V$ $I_{Load} = 3 \text{ mA}$	_	_	0.5	V
	С		high-drive strength		$V_{DD} > 1.8 V$ $I_{Load} = 1 \text{ mA}$	_	_	0.5	
7	D	Output low current	Max total I <sub>OL</sub> for all ports	I <sub>OLT</sub>		_	_	100	mA
8	Р	Input high	all digital inputs	V <sub>IH</sub>	V <sub>DD</sub> > 2.7 V	0.70 x V <sub>DD</sub>	_	_	
	С	voltage	an angitan mpato	<u>.</u>	V <sub>DD</sub> > 1.8 V	0.85 x V <sub>DD</sub>		_	V
9	Р	Input low	all digital inputs	$V_{IL}$	V <sub>DD</sub> > 2.7 V	_		0.35 x V <sub>DD</sub>	
	С	voltage	an angital impato	· IL	V <sub>DD</sub> > 1.8 V	_		0.30 x V <sub>DD</sub>	
10	С	Input hysteresis	all digital inputs	$V_{hys}$		0.06 x V <sub>DD</sub>	_	_	mV
			all input only pins except for		$V_{In} = V_{DD}$	_	0.025	1	μΑ
11	Р	Input leakage	LCD only pins (LCD 8-12, 21-41)	ll <sub>In</sub> l	$V_{In} = V_{SS}$		0.025	1	μА
	•	current	L OD anhanina (LOD 0.40	''In'	$V_{In} = V_{DD}$	_	100	150	μА
			LCD only pins (LCD 8-12, 21-41)		$V_{ln} = V_{SS}$	_	0.025	1	μА
12	Р	Hi-Z (off-state) leakage current	all input/output (per pin)	ll <sub>OZ</sub> l	$V_{In} = V_{DD}$ or $V_{SS}$	_	0.025	1	μА
13	Р	Total leakage current <sup>3</sup>	Total leakage current for all pins	I <sub>InT</sub>	$V_{In} = V_{DD}$ or $V_{SS}$	_	_	3	μΑ
14	Р	Pullup, Pulldown resistors	all non-LCD pins when enabled	R <sub>PU,</sub> R <sub>PD</sub>		17.5	_	52.5	kΩ
15	Р	Pullup, Pulldown resistors	LCD/GPIO pins when enabled	R <sub>PU,</sub> R <sub>PD</sub>		35	_	77	kΩ
		DC injection	Single pin limit			-0.2	_	0.2	mA
16	D	current <sup>4, 5,</sup>	Total MCU limit, includes sum of all stressed pins	I <sub>IC</sub>	$V_{IN} < V_{SS}, V_{IN} > V_{DD}$	<b>-</b> 5	_	5	mA
17	С	Input Capacitance, all pins		C <sub>In</sub>		_	_	8	pF
18	С	RAM retention voltage		V <sub>RAM</sub>		_	0.6	1.0	V
19	С	POR re-arm voltage <sup>7</sup>		V <sub>POR</sub>		0.9	1.4	2.0	V
20	D	POR re-arm	OR re-arm time			10	_	_	μS
21	Р	Low-voltage d	letection threshold	t <sub>POR</sub>	V <sub>DD</sub> falling V <sub>DD</sub> rising		1.84 1.92	1.88 1.96	V



#### **DC Characteristics**

Num	С	Characteristic	Symbol	Condition	Min	Typ <sup>1</sup>	Max	Unit
22	Р	Low-voltage warning threshold	$V_{LVW}$	V <sub>DD</sub> falling V <sub>DD</sub> rising		2.14	2.2	٧
23	Р.	Low-voltage inhibit reset/recover hysteresis	V <sub>hys</sub>		_	80	_	mV
24	Р	Bandgap Voltage Reference <sup>8</sup>	$V_{BG}$		1.15	1.17	1.18	V

<sup>&</sup>lt;sup>1</sup> Typical values are measured at 25°C. Characterized, not tested

### PULLUP RESISTOR TYPICALS - Non LCD pins

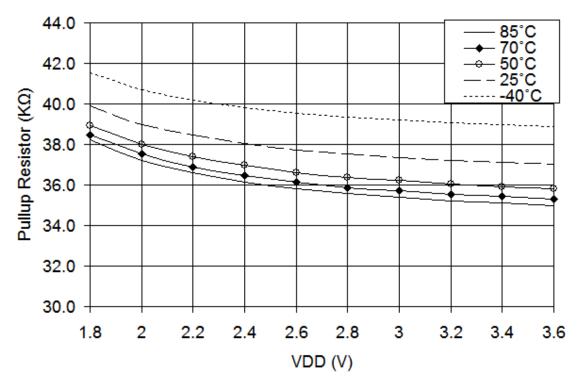


Figure 4. Non LCD pins I/O Pullup Typical Resistor Values

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<sup>&</sup>lt;sup>2</sup> All I/O pins except for LCD pins in Open Drain mode.

Total leakage current is the sum value for all GPIO pins. This leakage current is not distributed evenly across all pins but characterization data shows that individual pin leakage current maximums are less than 250 nA.

 $<sup>^4</sup>$  All functional non-supply pins, except for PTB2 are internally clamped to  $V_{SS}$  and  $V_{DD}$ .

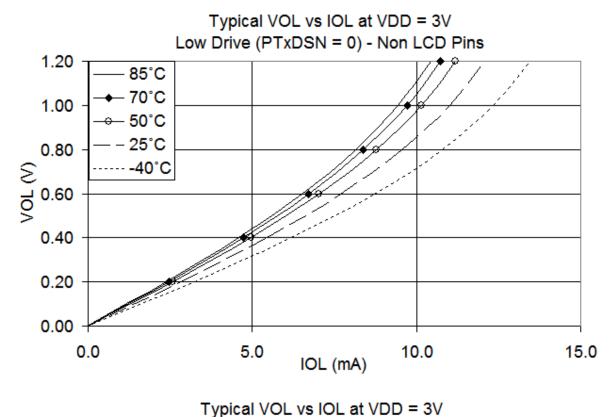
Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.

Power supply must maintain regulation within operating V<sub>DD</sub> range during instantaneous and operating maximum current conditions. If the positive injection current (V<sub>In</sub> > V<sub>DD</sub>) is greater than I<sub>DD</sub>, the injection current may flow out of V<sub>DD</sub> and could result in external power supply going out of regulation. Ensure that external V<sub>DD</sub> load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

POR will occur below the minimum voltage.

 $<sup>^{8}</sup>$  Factory trimmed at  $V_{DD}$  = 3.0 V, Temp = 25  $^{\circ}$ C





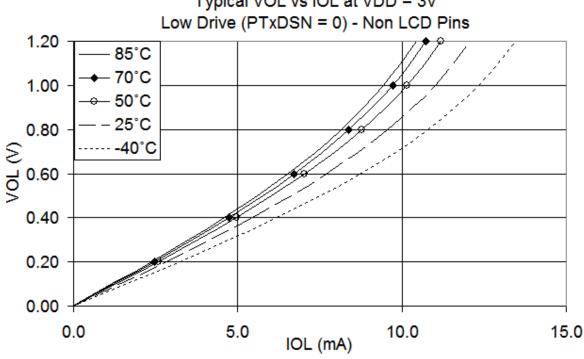


Figure 5. Typical Low-Side Driver (Sink) Characteristics (Non LCD Pins) — Low Drive (PTxDSn = 0)



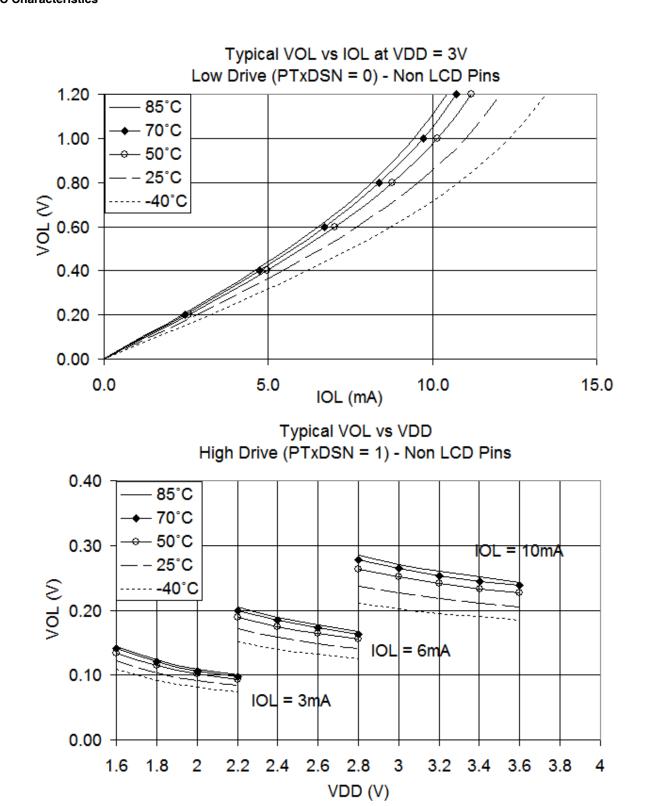


Figure 6. Typical Low-Side Driver (Sink) Characteristics(Non LCD Pins) — High Drive (PTxDSn = 1)



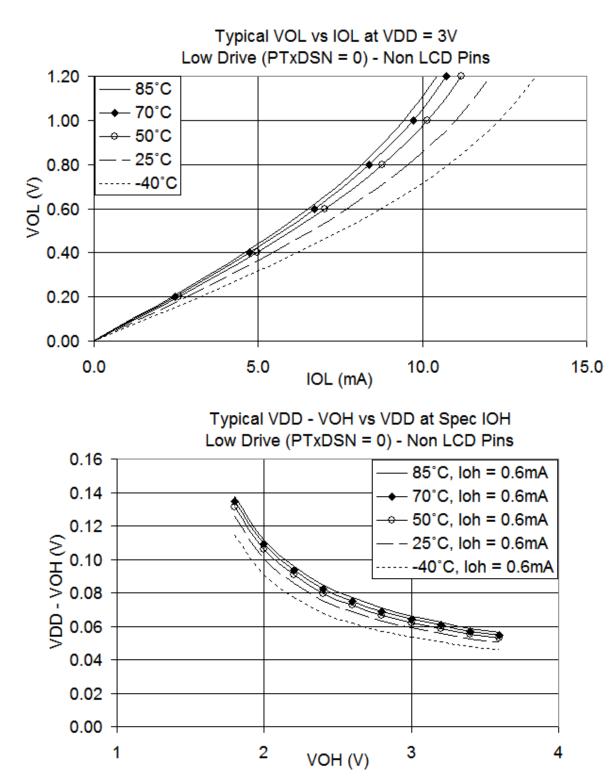
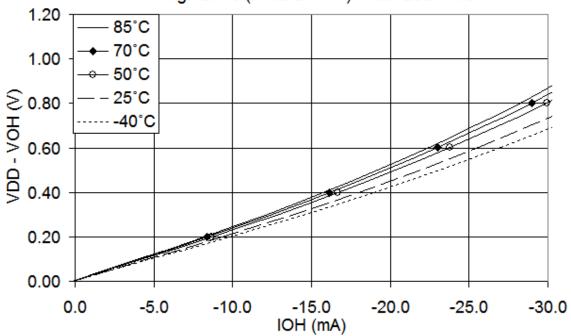


Figure 7. Typical High-Side (Source) Characteristics (Non LCD Pins)— Low Drive (PTxDSn = 0)





# TYPICAL VDD - VOH VS IOH at VDD = 3.0V High Drive (PTxDSN = 1) - Non LCD Pins



Typical VOh vs VDD High Drive (PTxDSN = 1) - Non LCD Pins

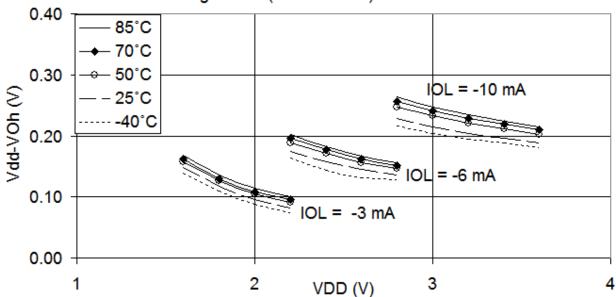


Figure 8. Typical High-Side (Source) Characteristics(Non LCD Pins) — High Drive (PTxDSn = 1)



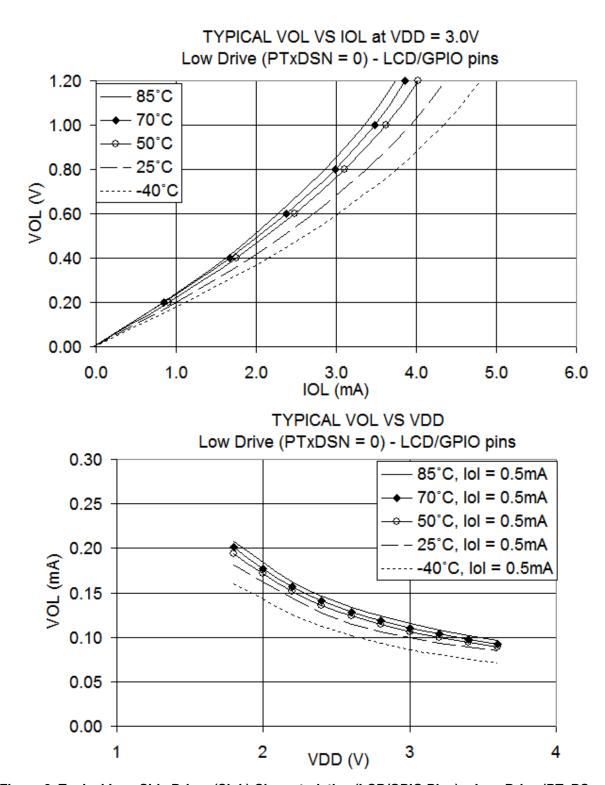
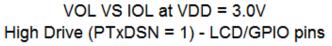
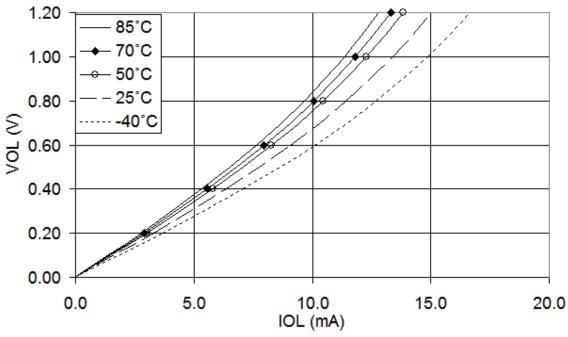


Figure 9. Typical Low-Side Driver (Sink) Characteristics (LCD/GPIO Pins)— Low Drive (PTxDSn = 0)



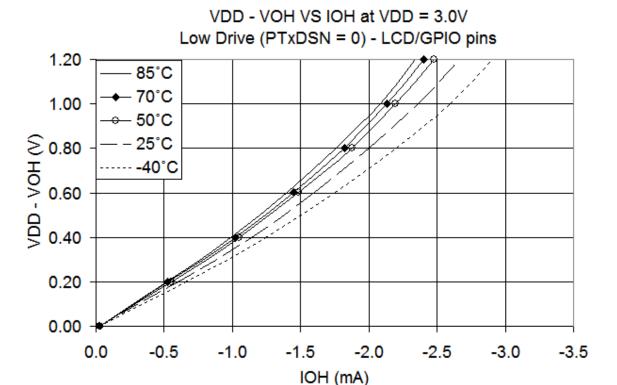




## TYPICAL VOL VS VDD High Drive (PTxDSN = 1) - LCD/GPIO pins 0.30 85°C - 70°C 0.25 IOL = 3 mA- 50°C 25°C 0.20 -40°C 0.15 0.10 IOL = 1 mΑ 0.05 0.00 2 3 1 VDD (V)

Figure 10. Typical Low-Side Driver (Sink) Characteristics (LCD/GPIO Pins) — High Drive (PTxDSn = 1)





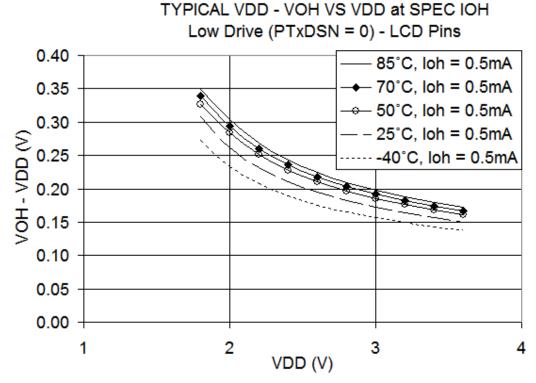
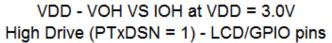
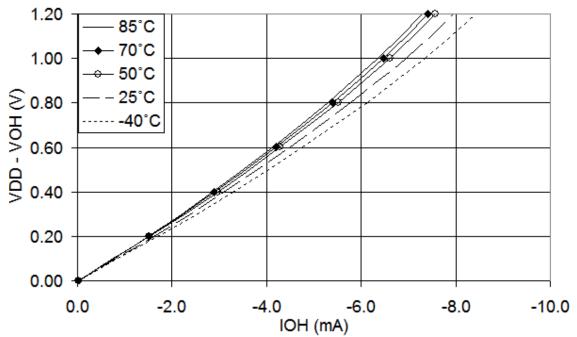


Figure 11. Typical High-Side (Source) Characteristics (LCD/GPIO Pins)— Low Drive (PTxDSn = 0)









VOH - VDD VS VDD at SPEC IOH High Drive (PTxDSN = 1) - LCD Pins

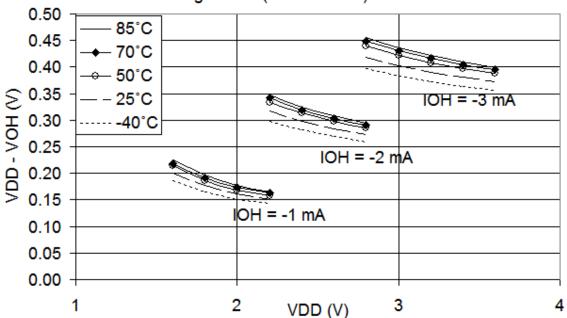


Figure 12. Typical High-Side (Source) Characteristics (LCD/GPIO Pins) — High Drive (PTxDSn = 1)



# 3.7 Supply Current Characteristics

This section includes information about power supply current in various operating modes.

**Table 9. Supply Current Characteristics** 

Num	С	Parameter	Symbol	Bus Freq	V <sub>DD</sub> (V)	Typ <sup>1</sup>	Max	Unit	Temp (°C)	
	Т			20 MHz		13.75	17.9			
1	Т	Run supply current FEI mode, all modules on	RI <sub>DD</sub>	10 MHz	3	7	_	mA	-40 to 85	
	Т	· ·		1 MHz		2	1			
	Т	Run supply current		20 MHz		8.9	_			
2	Т	FEI mode, all modules off	RI <sub>DD</sub>	10 MHz	3	5.5	_	mA	-40 to 85	
	Т			1 MHz		0.9	_			
3	Т	Run supply current LPS=0, all modules on	RI <sub>DD</sub>	16 kHz FBILP	3	185		μΑ	40 to 85	
	Т		טטייי	16 kHz FBELP		115		μν	40 10 03	
	_	Run supply current					_		0 to 70	
4	Т	LPS=1, all modules off, running from Flash	- RI <sub>DD</sub>	16 kHz	3	25	_	μА	-40 to 85	
-	_	Run supply current	מטייי	FBELP		7.0	1	μ, τ	0 to 70	
	Т	LPS=1, all modules off, running from RAM				7.3	_		-40 to 85	
	Т	Wait mode supply current FEI mode, all modules off	WI <sub>DD</sub>	20 MHz	3	4.57	6			
5	Т			8 MHz		2	_	mA	-40 to 85	
	Т			1 MHz		0.73				
	Р					0.4	1.3		-40 to 25	
	С				3	4	6		70	
6	Р	Stop2 mode supply current	S2I <sub>DD</sub>	n/a		8.5	13	μΑ	85	
	С		DD			0.35	1		-40 to 25	
	С				2	3.9	5		70	
	С					7.7	10		85	
	Р					0.65	1.8		-40 to 25	
	С				3	5.7	8		70	
7	Р	Stop3 mode supply current No clocks active	S3I <sub>DD</sub>	S3I <sub>DD</sub>	n/a		12.2	20	μΑ	85
	С						0.6	1.5		-40 to 25
	С				2	5	6.8		70	
	С		1			11.5	14		85	

<sup>1</sup> Typical values are measured at 25 °C. Characterized, not tested



#### **Supply Current Characteristics**

**Table 10. Stop Mode Adders** 

Num	С	Parameter	Condition		Tempera	nture (°C)	)	Units
Nulli		Parameter	Condition	-40	25	70	85	Offics
1	Т	LPO		100	100	150	175	nA
2	Т	EREFSTEN	RANGE = HGO = 0	750	750	800	850	nA
3	Т	IREFSTEN <sup>1</sup>		63	70	77	81	μА
4	Т	TOD	Does not include clock source current	50	50	75	100	nA
5	Т	LVD <sup>1</sup>	LVDSE = 1	110	110	112	115	μА
6	Т	ACMP <sup>1</sup>	Not using the bandgap (BGBE = 0)	12	12	20	23	μА
7	Т	ADC <sup>1</sup>	ADLPC = ADLSMP = 1 Not using the bandgap (BGBE = 0)	95	95	101	120	μА
8	Т	LCD	VIREG enabled for Contrast control, 1/8 Duty cycle, 8x24 configuration for driving 192 segments, 32 Hz frame rate, No LCD glass connected.	1	1	6	13	μА
9	Т	LCD	LCD configured for 1/8 duty cycle, 8x24 configuration for driving 192 segments, 32 Hz frame rate, no LCD glass connected.	0.2	0.24	0.5	0.65	μА

<sup>&</sup>lt;sup>1</sup> Not available in stop2 mode.

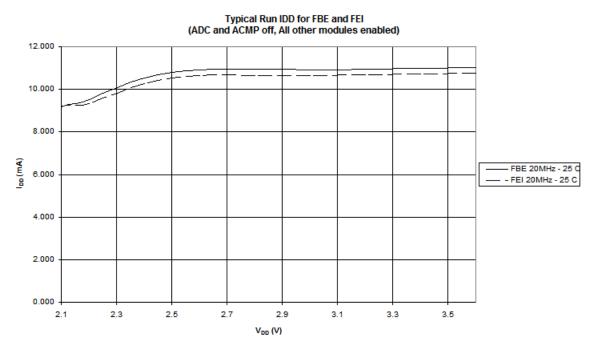


Figure 13. Typical Run  $I_{DD}$  for FBE and FEI,  $I_{DD}$  vs.  $V_{DD}$  (ADC and ACMP off, All Other Modules Enabled)

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# 3.8 External Oscillator (XOSCVLP) Characteristics

Reference Figure 14 and Figure 15 for crystal or resonator circuits.

Table 11. XOSCVLP and ICS Specifications (Temperature Range = -40 to 85°C Ambient)

Num	С	Characteristic	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1	С	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0) High range (RANGE = 1), high gain (HGO = 1) High range (RANGE = 1), low power (HGO = 0)	f <sub>lo</sub> f <sub>hi</sub> f <sub>hi</sub>	32 1 1	_ _ _	38.4 16 8	kHz MHz MHz
2	D	Load capacitors Low range (RANGE=0), low power (HGO=0) Other oscillator settings	C <sub>1,</sub> C <sub>2</sub>	See Note <sup>2</sup> See Note <sup>3</sup>			
3	D	Feedback resistor Low range, low power (RANGE=0, HGO=0) <sup>2</sup> Low range, high gain (RANGE=0, HGO=1) High range (RANGE=1, HGO=X)	R <sub>F</sub>		— 10 1	_ _ _	МΩ
4	D	Series resistor — Low range, low power (RANGE = 0, HGO = 0) <sup>2</sup> Low range, high gain (RANGE = 0, HGO = 1) High range, low power (RANGE = 1, HGO = 0) High range, high gain (RANGE = 1, HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	R <sub>S</sub>				kΩ
5	С	Crystal start-up time <sup>4</sup> Low range, low power Low range, high gain High range, low power High range, high gain	t CSTL t CSTH	  -  -  -	600 400 5 15	_ _ _ _	ms
6	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE mode FBE or FBELP mode	f <sub>extal</sub>	0.03125 0		20 20	MHz MHz

<sup>&</sup>lt;sup>1</sup> Data in Typical column was characterized at 3.0 V, 25 °C or is typical recommended value.

<sup>&</sup>lt;sup>2</sup> Load capacitors (C<sub>1</sub>,C<sub>2</sub>), feedback resistor (R<sub>F</sub>) and series resistor (R<sub>S</sub>) are incorporated internally when RANGE = HGO = 0.

<sup>&</sup>lt;sup>3</sup> See crystal or resonator manufacturer's recommendation.

<sup>&</sup>lt;sup>4</sup> Proper PC board layout procedures must be followed to achieve specifications.



#### Internal Clock Source (ICS) Characteristics

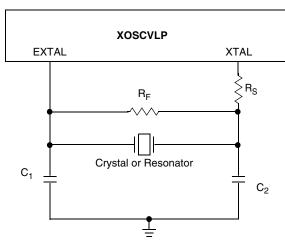


Figure 14. Typical Crystal or Resonator Circuit: High Range and Low Range/High Gain

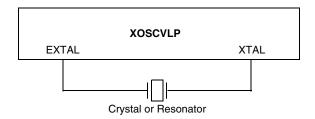


Figure 15. Typical Crystal or Resonator Circuit: Low Range/Low Power

# 3.9 Internal Clock Source (ICS) Characteristics

Table 12. ICS Frequency Specifications (Temperature Range = -40 to 85°C Ambient)

Num	С	Chara	acteristic	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1	С	Average internal reference f	requency — untrimmed	f <sub>int_ut</sub>	25	32.7	41.66	kHz
2	Р	Average internal reference f	f <sub>int_t</sub>	31.25	_	39.06	kHz	
3	Р	Average internal reference f	f <sub>int_t</sub>	_	32.7	_	kHz	
4	Т	Internal reference start-up ti	t <sub>IRST</sub>	_	60	100	μS	
5	Р	DCO output frequency Low range (DFR = 00)		f	12.8	16.8	21.33	MHz
5	c range — untrimmed	Mid range (DFR = 01)	f <sub>dco_ut</sub>	25.6	33.6	42.67	1411 12	
6	Р	DCO output frequency	Low range (DFR = 00)	f	16	_	20	MHz
0	Р	range — trimmed	Mid range (DFR = 01)	- f <sub>dco_t</sub>	32	_	40	IVII IZ
7	С	Resolution of trimmed DCO voltage and temperature (us	$\Delta f_{dco\_res\_t}$	_	±0.1	±0.2	%f <sub>dco</sub>	
8	С	Resolution of trimmed DCO voltage and temperature (no		$\Delta f_{dco\_res\_t}$		± 0.2	±0.4	%f <sub>dco</sub>

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Table 10 ICC Everyones	Considirations	/Tamparatura Da	10 to 05	OC Ambiant	(acatiousel)
Table 12. ICS Frequency	Specifications	(Temberature Ra	ande = -40 to 83	o'C Ambienti	(continued)

Num	С	Characteristic	Symbol	Min	Typ <sup>1</sup>	Max	Unit
9	С	Total deviation of trimmed DCO output frequency over voltage and temperature	Δf <sub>dco_t</sub>	_	+ 0.5 -1.0	±2	%f <sub>dco</sub>
10	С	Total deviation of trimmed DCO output frequency over fixed voltage and temperature range of 0 °C to 70 °C	Δf <sub>dco_t</sub>		± 0.5	±1	%f <sub>dco</sub>
11	С	FLL acquisition time <sup>2</sup>	t <sub>Acquire</sub>		_	1	ms
12	С	Long term jitter of DCO output clock (averaged over 2 ms interval) <sup>3</sup>	C <sub>Jitter</sub>		0.02	0.2	%f <sub>dco</sub>

Data in Typical column was characterized at 3.0 V, 25 °C or is typical recommended value.

#### Deviation of DCO Output from Trimmed Frequency

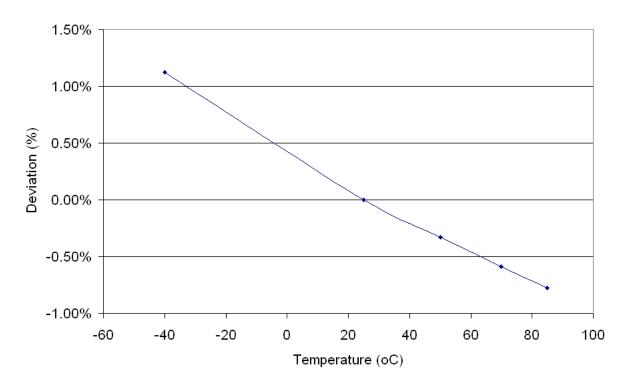


Figure 16. Deviation of DCO Output from Trimmed Frequency (20 MHz, 3.0 V)

<sup>&</sup>lt;sup>2</sup> This specification applies to any time the FLL reference source or reference divider is changed, trim value changed or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f<sub>Bus</sub>. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V<sub>DD</sub> and V<sub>SS</sub> and variation in crystal oscillator frequency increase the C<sub>Jitter</sub> percentage for a given interval.



#### **AC Characteristics**

### 3.10 AC Characteristics

This section describes timing characteristics for each peripheral system.

# 3.10.1 Control Timing

**Table 13. Control Timing** 

Num	С	Rating	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1	D	Bus frequency ( $t_{cyc} = 1/f_{Bus}$ ) $V_{DD} \le 2.1V$ $V_{DD} > 2.1V$	f <sub>Bus</sub>	dc dc	_ _	10 20	MHz
2	D	Internal low power oscillator period	t <sub>LPO</sub>	700	_	1300	μS
3	D	External reset pulse width <sup>2</sup>	t <sub>extrst</sub>	100	_	_	ns
4	D	Reset low drive	t <sub>rstdrv</sub>	$34 \times t_{cyc}$	_	_	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	t <sub>MSSU</sub>	500	_	_	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes <sup>3</sup>	t <sub>MSH</sub>	100	_	_	μS
7	D	IRQ pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>4</sup>	t <sub>ILIH,</sub> t <sub>IHIL</sub>	100 1.5 × t <sub>cyc</sub>	_ _	_ _	ns
8	D	Keyboard interrupt pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>4</sup>	t <sub>ILIH</sub> , t <sub>IHIL</sub>	100 1.5 × t <sub>cyc</sub>	_ _	_ _	ns
9	С	Port rise and fall time —  Low output drive (PTxDS = 0) (load = 50 pF) <sup>5, 6</sup> Slew rate control disabled (PTxSE = 0)  Slew rate control enabled (PTxSE = 1)	t <sub>Rise</sub> , t <sub>Fall</sub>	_	16 23		ns
		Port rise and fall time —  High output drive (PTxDS = 1) (load = 50 pF) <sup>5, 6</sup> Slew rate control disabled (PTxSE = 0)  Slew rate control enabled (PTxSE = 1)	t <sub>Rise</sub> , t <sub>Fall</sub>	=	5 9		ns

Typical values are based on characterization data at  $V_{DD} = 3.0 \text{ V}$ , 25 °C unless otherwise stated.

<sup>&</sup>lt;sup>2</sup> This is the shortest pulse that is guaranteed to be recognized as a reset pin request.

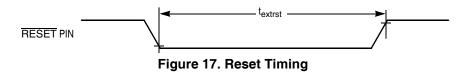
To enter BDM mode following a POR, BKGD/MS should be held low during the power-up and for a hold time of t<sub>MSH</sub> after V<sub>DD</sub> rises above V<sub>LVD</sub>.

<sup>&</sup>lt;sup>4</sup> This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized.

 $<sup>^5</sup>$  Timing is shown with respect to 20%  $\rm V_{DD}$  and 80%  $\rm V_{DD}$  levels. Temperature range –40  $^{\circ}C$  to 85  $^{\circ}C.$ 

<sup>&</sup>lt;sup>6</sup> Except for LCD pins in open drain mode.





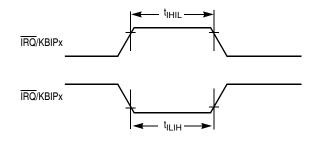


Figure 18. IRQ/KBIPx Timing

# 3.10.2 TPM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

**Table 14. TPM Input Timing** 

No.	С	Function	Symbol	Min	Max	Unit
1	D	External clock frequency	f <sub>TCLK</sub>	0	f <sub>Bus</sub> /4	Hz
2	D	External clock period	t <sub>TCLK</sub>	4	_	t <sub>cyc</sub>
3	D	External clock high time	t <sub>clkh</sub>	1.5	_	t <sub>cyc</sub>
4	D	External clock low time	t <sub>clkl</sub>	1.5	_	t <sub>cyc</sub>
5	D	Input capture pulse width	t <sub>ICPW</sub>	1.5	_	t <sub>cyc</sub>

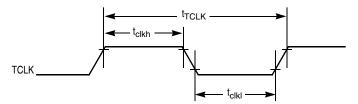


Figure 19. Timer External Clock

#### **AC Characteristics**

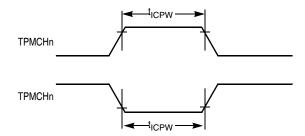


Figure 20. Timer Input Capture Pulse

# 3.10.3 SPI Timing

Table 15 and Figure 21 through Figure 24 describe the timing requirements for the SPI system.

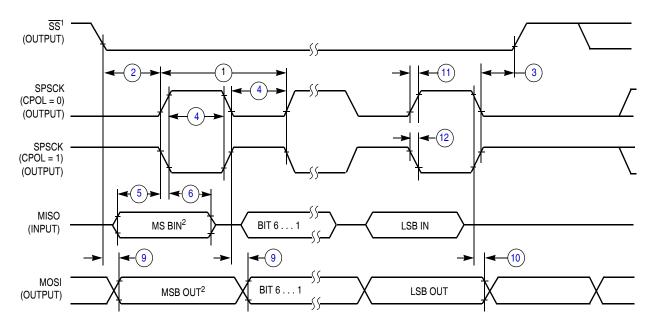
# Table 15. SPI Timing

No.	С	Function	Symbol	Min	Max	Unit
_	D	Operating frequency Master Slave	f <sub>op</sub>	f <sub>Bus</sub> /2048 0	f <sub>Bus</sub> /2 f <sub>Bus</sub> /4	Hz
1	D	SPSCK period Master Slave	t <sub>SPSCK</sub>	2 4	2048 —	t <sub>cyc</sub>
2	D	Enable lead time Master Slave	t <sub>Lead</sub>	1/2 1	11	t <sub>SPSCK</sub> t <sub>cyc</sub>
3	D	Enable lag time Master Slave	t <sub>Lag</sub>	1/2 1	_	t <sub>SPSCK</sub>
4	D	Clock (SPSCK) high or low time Master Slave	twspsck	t <sub>cyc</sub> - 30 t <sub>cyc</sub> - 30	1024 t <sub>cyc</sub>	ns ns
(5)	D	Data setup time (inputs)  Master  Slave	t <sub>SU</sub>	15 15		ns ns
6	D	Data hold time (inputs)  Master  Slave	t <sub>HI</sub>	0 25	_	ns ns
7	D	Slave access time	t <sub>a</sub>	_	1	t <sub>cyc</sub>
8	D	Slave MISO disable time	t <sub>dis</sub>	_	1	t <sub>cyc</sub>
9	D	Data valid (after SPSCK edge)  Master Slave	t <sub>v</sub>	_	25 25	ns ns



**Table 15. SPI Timing (continued)** 

No.	С	Function	Symbol	Min	Max	Unit
10)	D	Data hold time (outputs)  Master  Slave	t <sub>HO</sub>	0	_	ns ns
(1)	D	Rise time Input Output	t <sub>RI</sub> t <sub>RO</sub>	=	t <sub>cyc</sub> – 25 25	ns ns
12)	D	Fall time Input Output	t <sub>FI</sub>		t <sub>cyc</sub> – 25 25	ns ns



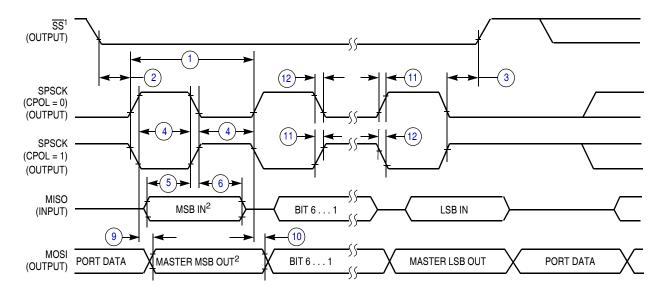
#### NOTES:

- 1. SS output mode (DDS7 = 1, SSOE = 1).
- 2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 21. SPI Master Timing (CPHA = 0)



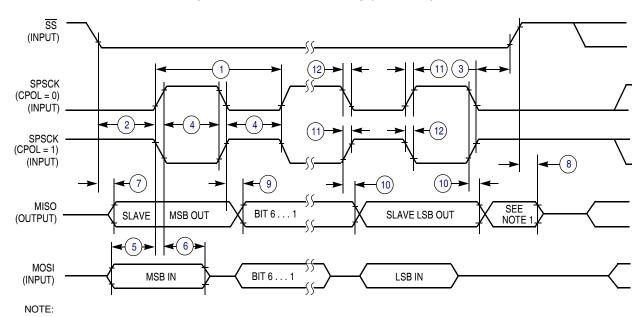
#### **AC Characteristics**



#### NOTES:

- 1.  $\overline{SS}$  output mode (DDS7 = 1, SSOE = 1).
- 2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

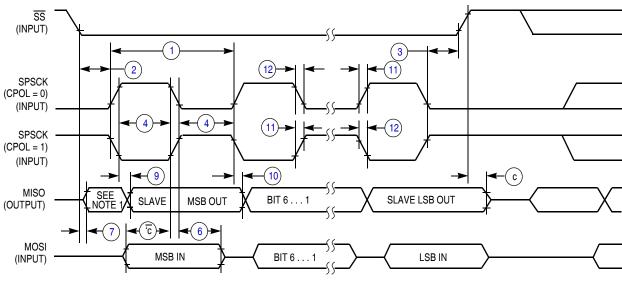
Figure 22. SPI Master Timing (CPHA =1)



1. Not defined but normally MSB of character just received.

Figure 23. SPI Slave Timing (CPHA = 0)





NOTE:

1. Not defined but normally LSB of character just received

Figure 24. SPI Slave Timing (CPHA = 1)

## 3.11 Analog Comparator (ACMP) Electricals

**Table 16. Analog Comparator Electrical Specifications** 

No	С	Characteristic	Symbol	Min	Typical	Max	Unit
1	D	Supply voltage	$V_{DD}$	1.8	_	3.6	V
2	Р	Supply current (active)	I <sub>DDAC</sub>	_	20	35	μΑ
3	D	Analog input voltage	$V_{AIN}$	$V_{SS} - 0.3$	_	$V_{DD}$	V
4	Р	Analog input offset voltage	V <sub>AIO</sub>	_	20	40	mV
5	С	Analog comparator hysteresis	V <sub>H</sub>	3.0	9.0	15.0	mV
6	Р	Analog input leakage current	I <sub>ALKG</sub>	_	_	1.0	μА
7	C	Analog comparator initialization delay	t <sub>AINIT</sub>	_	_	1.0	μS

## 3.12 ADC Characteristics

**Table 17. 12-Bit ADC Operating Conditions** 

No.	Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit
		Absolute	$V_{DDA}$	1.8	_	3.6	V
1	Supply voltage	Delta to V <sub>DD</sub> (V <sub>DD</sub> – V <sub>DDA</sub> ) <sup>2</sup>	ΔV <sub>DDA</sub>	-100	0	100	mV

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### **ADC Characteristics**

**Table 17. 12-Bit ADC Operating Conditions (continued)** 

No.	Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit
2	Ground voltage	Delta to V <sub>SS</sub> (V <sub>SS</sub> – V <sub>SSA</sub> ) <sup>2</sup>	$\Delta V_{SSA}$	-100	0	100	mV
3	Reference voltage high	_	V <sub>REFH</sub>	1.8	$V_{DDA}$	$V_{DDA}$	V
4	Reference voltage low	_	V <sub>REFL</sub>	V <sub>SSA</sub>	$V_{SSA}$	$V_{SSA}$	V
5	Input voltage	_	V <sub>ADIN</sub>	V <sub>REFL</sub>	_	V <sub>REFH</sub>	V
6	Input capacitance	8/10/12-bit modes	C <sub>ADIN</sub>	_	4	5	pF
7	Input resistance	_	R <sub>ADIN</sub>	_	5	7	kΩ

Typical values assume  $V_{DDA} = 3.0 \text{ V}$ , Temp = 25 °C,  $f_{ADCK} = 1.0 \text{ MHz}$  unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>&</sup>lt;sup>2</sup> DC potential difference.

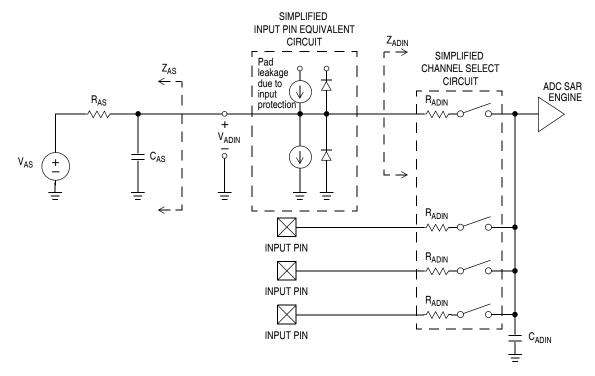


Figure 25. ADC Input Impedance Equivalency Diagram



Table 18. 12-Bit ADC Characteristics ( $V_{REFH} = V_{DDA}, V_{REFL} = V_{SSA}$ )

#	Characteristic	Conditions	С	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
1	Supply current	ADLPC = 1 ADHSC = 0 ADLSMP = 0 ADCO = 1	Т	I <sub>DDA</sub>	_	200	_	μА	
2	Supply current	ADLPC = 1 ADHSC = 1 ADLSMP = 0 ADCO = 1	Т	I <sub>DDA</sub>	_	280	_	μА	
3	Supply current	ADLPC = 0 ADHSC = 0 ADLSMP = 0 ADCO = 1	Т	I <sub>DDA</sub>	_	370	_	μА	
4	Supply current	ADLPC = 0 ADHSC = 1 ADLSMP = 0 ADCO = 1	Т	I <sub>DDA</sub>	_	0.61	_	mA	
5	Supply current	Stop, reset, module off		I <sub>DDA</sub>	_	0.01	0.8	μΑ	
	ADC .	High speed (ADLPC = 0)			2	3.3	5		t <sub>ADACK</sub> =
6	asynchronous clock source	Low power (ADLPC = 1)	- P	f <sub>ADACK</sub>	1.25	2	3.3	MHz	1/f <sub>ADACK</sub>
		Single/first continuous ADLSMP = 0							
7	Sample time	ADHSC = 0 ADLSMP = 0 ADLSTS = XX	С	ts	_	6	_	ADCK	
		ADHSC = 1 ADLSMP = 0 ADLSTS = XX	С	ts	_	10	_		
		Subsequent continuous ADLSMP = 0							
8	Sample time	ADHSC = 0 ADLSMP = 0 ADLSTS = XX	С	ts	_	4	_	ADCK	
		ADHSC = 1 ADLSMP = 0 ADLSTS = XX	С	ts	_	8	_		



## **ADC Characteristics**

Table 18. 12-Bit ADC Characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)

#	Characteristic	Conditions	С	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
		Subsequent Continuous or Single/First Continuous ADLSMP = 1							
		ADHSC = 0 ADLSMP = 1 ADLSTS = 00	С	ts	_	24	_		
		ADHSC = 0 ADLSMP = 1 ADLSTS = 01	С	ts	_	16	_		
		ADHSC = 0 ADLSMP = 1 ADLSTS = 10	С	ts	_	10	_		
9	Sample time	ADHSC = 0 ADLSMP = 1 ADLSTS = 11	С	ts	_	6	_		
		ADHSC = 1 ADLSMP = 1 ADLSTS = 00	С	ts	_	28	_		
		ADHSC = 1 ADLSMP = 1 ADLSTS = 01	С	ts	_	20	_		
		ADHSC = 1 ADLSMP = 1 ADLSTS = 10	С	ts	_	14	_		
		ADHSC = 1 ADLSMP = 1 ADLSTS = 11	С	ts	_	10	_		
		12-bit mode 3.6 > V <sub>DDA</sub> > 2.7V	Т		_	-2.5 to 3.25	±4		
10	Total unadjusted	12-bit mode, 2.7 > V <sub>DDA</sub> > 1.8V	Т	E <sub>TUE</sub>		±3.25	–5.5 to 6.5	LSB <sup>2</sup>	Includes quantization
	error	10-bit mode	Т		_	±1	±2.5		
		8-bit mode	Т		_	±0.5	±1.0		
	Differential	12-bit mode	Т		_	–1 to 1.75	-1.5 to 2.5	0	
11	non-linearity	10-bit mode <sup>3</sup>	Т	DNL		±0.5	±1.0	LSB <sup>2</sup>	
		8-bit mode <sup>3</sup>	Т		_	±0.3	±0.5		



Table 18. 12-Bit ADC Characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)

#	Characteristic	Conditions	С	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
	Integral	12-bit mode	Т		_	-1.5 to 2.25	±2.75		
12	non-linearity	10-bit mode	Т	INL	-	±0.5	±1.0	LSB <sup>2</sup>	
		8-bit mode	Т		_	±0.3	±0.5		
	Zero-scale	12-bit mode	Т		_	±1	-1.25 to 1		
13	error	10-bit mode	Т	E <sub>ZS</sub>	_	±0.5	±1	LSB <sup>2</sup>	$V_{ADIN} = V_{SSA}$
		8-bit mode	Т		_	±0.5	±0.5		
		12-bit mode	Т		_	±1.0	-3.5 to 2.25		
14	Full-scale error	10-bit mode	Т	E <sub>FS</sub>	-	±0.5	±1	LSB <sup>2</sup>	$V_{ADIN} = V_{DDA}$
		8-bit mode	Т		-	±0.5	±0.5		
		12-bit mode			_	-1 to 0	_		
15	Quantization error	10-bit mode	D	EQ	_	_	±0.5	LSB <sup>2</sup>	
		8-bit mode			_	_	±0.5		
		12-bit mode			_	±2	_		4
16	Input leakage error	10-bit mode	D	E <sub>IL</sub>	_	±0.2	±4	LSB <sup>2</sup>	Pad leakage <sup>4</sup> * R <sub>AS</sub>
	error	8-bit mode			_	±0.1	±1.2		7.0
17	Temp sensor	–40 °C− 25 °C	D	m		1.646	_	mV/°C	
	17 slope	25 °C– 125 °C		111		1.769		IIIV/ C	
18	Temp sensor voltage	25°C	D	V <sub>TEMP25</sub>	_	701.2	_	mV	

Typical values assume V<sub>DDA</sub> = 3.0 V, Temp = 25 °C, f<sub>ADCK</sub> = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>&</sup>lt;sup>2</sup> 1 LSB =  $(V_{REFH} - V_{REFL})/2^N$ 

Monotonicity and No-Missing-Codes guaranteed in 10-bit and 8-bit modes.

<sup>&</sup>lt;sup>4</sup> Based on input pad leakage current. Refer to pad electricals.



## **VREF Specifications**

# 3.13 VREF Specifications

**Table 19. VREF Electrical Specifications** 

Num	Characteristic	Symbol	Typical	Min	Max	Unit		
1	Supply voltage	V <sub>DD</sub>	_	1.80	3.60	V		
2	Operating temperature range	T <sub>op</sub>	_	-40	105	°C		
3	Maximum load	_	_	_	10	mA		
		Operation across T	emperature		,			
4	V Room Temp	V Room Temp	1.15	_	_	V		
5	Untrimmed –40 °C	Untrimmed –40 °C	_		n Room Temp age	mV		
6	Trimmed –40 °C	Trimmed –40 °C	_	± 1 from Roon	n Temp Voltage	mV		
7	Untrimmed 0 °C	Untrimmed 0 °C	_		n Room Temp age	mV		
	Trimmed 0 °C	Trimmed 0 °C	_	± 0.5 from Room Temp Voltage		mV		
8	Untrimmed 50 °C	Untrimmed 50 °C	_	+1 to -2 from Room Temp Voltage				mV
9	Trimmed 50 °C	Trimmed 50 °C	_	± 0.5 from Roo	mV			
10	Untrimmed 85 °C	Untrimmed 85 °C	_	0 to -4 from Roo	mV			
11	Trimmed 85 °C	Trimmed 85 °C	_	± 0.5 from Roo	m Temp Voltage	mV		
12	Untrimmed 125 °C	Untrimmed 125 °C	_		n Room Temp age	mV		
13	Trimmed 125 °C	Trimmed 125 °C	_	± 1 from Roon	n Temp Voltage	mV		
14	Load bandwidth	_	_	_	_	_		
15	Load regulation mode = 10 at 1mA load	Mode = 10	_	20	100	μV/mA		
16	Line regulation (power supply rejection)	DC	_	± 0.1 from Roo	m Temp Voltage	mV		
10	Ente regulation (power supply rejection)	AC	_	-(	60	dB		
		Power Consu	mption					
17	Powered down Current (Stop Mode, VREFEN = 0, VRSTEN = 0)	I	_	_	.100	μΑ		
18	Bandgap only (Mode[1:0] 00)	I	_	_	75	μΑ		
19	Low-power buffer (Mode[1:0] 01)	I	_	_	125	μΑ		
20	Tight-regulation buffer (Mode[1:0] 10)	I	_	_	1.1	mA		
21	RESERVED (Mode[1:0] 11)	_	_	_	_	_		



#### **LCD Specifications** 3.14

Table 20. LCD Electricals, 3-V Glass

No.	С	Characteristic		Symbol	Min	Тур	Max	Unit
1	D	LCD supply voltage		V <sub>LCD</sub>	.9	1.5	1.8	V
2	D	LCD frame frequency		f <sub>Frame</sub>	28	30	58	Hz
3	D	LCD charge pump capacitance		C <sub>LCD</sub>	_	100	100	nF
4	D	LCD bypass capacitance		C <sub>BYLCD</sub>	_	100	100	nF
5	D	LCD glass capacitance		C <sub>glass</sub>	_	2000	8000	pF
6	D	V <sub>IREG</sub>	HRefSel = 0	V <sub>IREG</sub>	.89	1.00	1.15	V
7	D	VIREG	HRefSel = 1		1.49	1.67	1.85 <sup>1</sup>	V
8	D	V <sub>IREG</sub> trim resolution		$\Delta_{RTRIM}$	1.5	_	_	% V <sub>IREG</sub>
9	D	V <sub>IREG</sub> ripple	HRefSel = 0	_	_	_	.1	V
10	D	VIREG TIPPIE	HRefSel = 1	_	_	1	.15	٧
11	D	V <sub>LCD</sub> buffered adder <sup>2</sup>		I <sub>Buff</sub>	_	1		μΑ

V<sub>IREG</sub> Max can not exceed V<sub>DD</sub> -.15 V
 VSUPPLY = 10, BYPASS = 0

#### 3.15 Flash Specifications

This section provides details about program/erase times and program-erase endurance for the Flash memory.

Program and erase operations do not require any special power sources other than the normal V<sub>DD</sub> supply. For more detailed information about program/erase operations, see the Memory section.

**Table 21. Flash Characteristics** 

No.	С	Characteristic	Symbol	Min	Typical	Max	Unit
1	D	Supply voltage for program/erase -40 °C to 85 °C	V <sub>prog/erase</sub>	1.8	_	3.6	V
2	D	Supply voltage for read operation	V <sub>Read</sub>	1.8	_	3.6	V
3	D	Internal FCLK frequency <sup>1</sup>	f <sub>FCLK</sub>	150	_	200	kHz
4	D	Internal FCLK period (1/FCLK)	t <sub>Fcyc</sub>	5	_	6.67	μS
5	Р	Byte program time (random location) <sup>2</sup>	t <sub>prog</sub>		9		t <sub>Fcyc</sub>
6	Р	Byte program time (burst mode) <sup>2</sup>	t <sub>Burst</sub>		4		t <sub>Fcyc</sub>
7	Р	Page erase time <sup>2</sup>	t <sub>Page</sub>	4000		t <sub>Fcyc</sub>	
8	Р	Mass erase time <sup>2</sup>	t <sub>Mass</sub>	20,000		t <sub>Fcyc</sub>	
9	D	Byte program current <sup>3</sup>	R <sub>IDDBP</sub>	_	4	_	mA



#### **EMC Performance**

**Table 21. Flash Characteristics (continued)** 

No.	С	Characteristic	Symbol	Min	Typical	Max	Unit
10	D	Page erase current <sup>3</sup>	R <sub>IDDPE</sub>	_	6	_	mA
11	С	Program/erase endurance <sup>4</sup> $T_L$ to $T_H = -40$ °C to 85°C $T = 25$ °C	_	10,000	 100,000		cycles
12	С	Data retention <sup>5</sup>	t <sub>D_ret</sub>	15	100	_	years

The frequency of this clock is controlled by a software setting.

## 3.16 EMC Performance

Electromagnetic compatibility (EMC) performance is highly dependent on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 for advice and guidance specifically targeted at optimizing EMC performance.

### 3.16.1 Radiated Emissions

Microcontroller radiated RF emissions are measured from 150 kHz to 1 GHz using the TEM/GTEM Cell method in accordance with the IEC 61967-2 and SAE J1752/3 standards. The measurement is performed with the microcontroller installed on a custom EMC evaluation board while running specialized EMC test software. The radiated emissions from the microcontroller are measured in a TEM cell in two package orientations (North and East).

# 4 Ordering Information

This appendix contains ordering information for the device numbering system MC9S08LL64 and MC9S08LL36 devices. See Table 1 for feature summary by package information.

These values are hardware state machine controlled. User code does not need to count cycles. This information supplied for calculating approximate time to program and erase.

The program and erase currents are additional to the standard run  $I_{DD}$ . These values are measured at room temperatures with  $V_{DD} = 3.0 \text{ V}$ , bus frequency = 4.0 MHz.

Typical endurance for Flash was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale defines typical endurance, please refer to Engineering Bulletin EB619, Typical Endurance for Nonvolatile Memory.

<sup>&</sup>lt;sup>5</sup> Typical data retention values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25 °C using the Arrhenius equation. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618, *Typical Data Retention for Nonvolatile Memory.* 

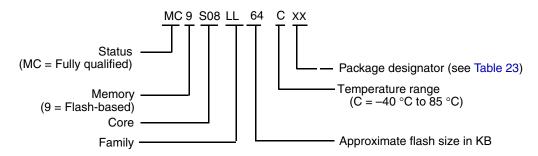


Device Number <sup>1</sup>	Mer	mory	Aveilable Backers 2
Device Number	Flash	RAM	Available Packages <sup>2</sup>
MC9S08LL64	64 KB	4000	80 LQFP
WC9306LL04	64 KB	4000	64 LQFP
MC9S08LL36	36 KB	4000	80 LQFP
WIC9300LL30	36 KB	4000	64 LQFP

**Table 22. Device Numbering System** 

#### 4.1 **Device Numbering System**

Example of the device numbering system:



#### 4.2 **Package Information**

**Table 23. Package Descriptions** 

Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
80	Low Quad Flat Package	LQFP	LK	917A	98ASS23237W
64	Low Quad Flat Package	LQFP	LH	840F	98ASS23234W

#### 4.3 **Mechanical Drawings**

Table 23 provides the available package types and their document numbers. The latest package outline/mechanical drawings are available on the MC9S08LL64 series Product Summary pages at http://www.freescale.com.

To view the latest drawing, either:

- Click on the appropriate link in Table 23, or
- Open a browser to the Freescale website (http://www.freescale.com), and enter the appropriate document number (from Table 23) in the "Enter Keyword" search box at the top of the page.

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See Table 1 for a complete description of modules included on each device.

See Table 23 for package information.



**Mechanical Drawings** 

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