Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 2 — 22 May 2012

**Product data sheet** 

## 1. General description

The NTBA104 is a 4-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 4-bit input-output ports (An and Bn), one output enable input ( $\overline{OE}$ ) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied at any voltage between 1.2 V and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between 1.2 V, and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between any voltage between 1.65 V, making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and  $\overline{OE}$  are referenced to V<sub>CC(A)</sub> and pins Bn are referenced to V<sub>CC(B)</sub>. A HIGH level at pin  $\overline{OE}$  causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I<sub>OFF</sub>. The I<sub>OFF</sub> circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

## 2. Features and benefits

- Wide supply voltage range:
  - ◆ V<sub>CC(A)</sub>: 1.2 V to 3.6 V and V<sub>CC(B)</sub>: 1.65 V to 5.5 V
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - ◆ HBM JESD22-A114E Class 2 exceeds 2500 V for A port
  - ◆ HBM JESD22-A114E Class 3B exceeds 15000 V for B port
  - MM JESD22-A115-A exceeds 200 V
  - CDM JESD22-C101E exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from –40 °C to +85 °C and –40 °C to +125 °C



# 3. Ordering information

Table 1.	Ordering	information
	Ordening	mormation

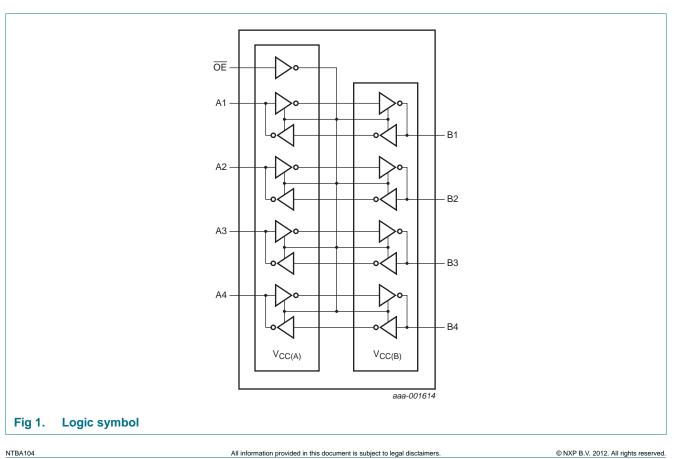
Type number	Package							
	Temperature range	Name	Description	Version				
NTBA104BQ	–40 °C to +125 °C	DHVQFN14	plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 14 terminals; body $2.5 \times 3 \times 0.85$ mm	SOT762-1				
NTBA104GU16	–40 °C to +125 °C	XQFN16	plastic, extremely thin quad flat package; no leads; 16 terminals; body 1.80 x 2.60 x 0.50 mm	SOT1161-1				
NTBA104GU12	–40 °C to +125 °C	XQFN12	plastic, extremely thin quad flat package; no leads; 12 terminals; body 1.70 x 2.0 x 0.50 mm	SOT1174-1				

# 4. Marking

#### Table 2. Marking codes

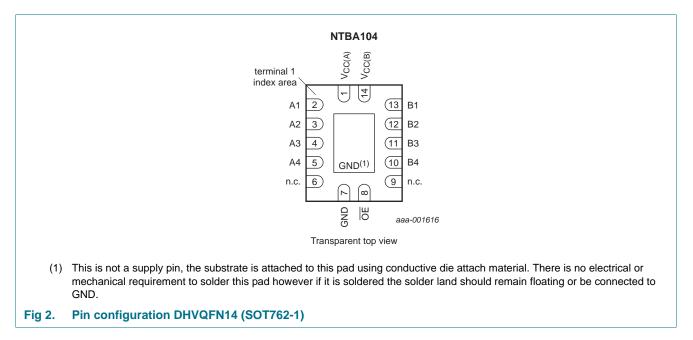
Type number	Marking code
NTBA104BQ	BA104
NTBA104GU16	tA4
NTBA104GU12	tA

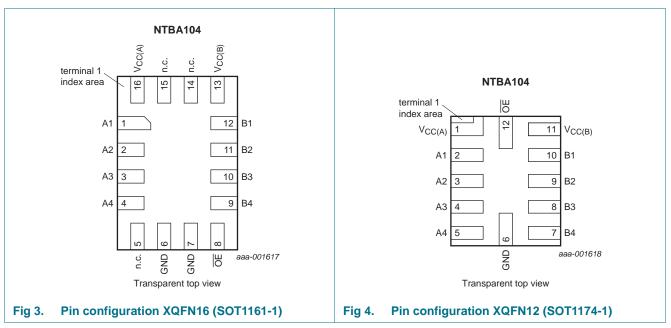
# 5. Functional diagram



# 6. Pinning information

## 6.1 Pinning





Symbol	Pin			Description
	SOT762-1	SOT1161-1	SOT1174-1	
V <sub>CC(A)</sub>	1	16	1	supply voltage A
A1, A2, A3, A4	2, 3, 4, 5	1, 2, 3, 4	2, 3, 4, 5	data input or output (referenced to $V_{CC(A)}$ )
n.c.	6, 9	5, 14, 15	-	not connected
GND	7	6, 7	6	ground (0 V)
OE	8	8	12	output enable input (active LOW; referenced to $V_{CC(A)}$ )
B4, B3, B2, B1	10, 11, 12, 13	9, 10, 11, 12	7, 8, 9, 10	data input or output (referenced to $V_{CC(B)}$ )
V <sub>CC(B)</sub>	14	13	11	supply voltage B

## 6.2 Pin description

# 7. Functional description

#### Table 4. Function table<sup>[1]</sup>

Supply voltage		Input	Input/output	
V <sub>CC(A)</sub> V <sub>CC(B)</sub>		OE	An	Bn
1.2 V to $V_{CC(B)}$	1.65 V to 5.5 V	Н	Z	Z
1.2 V to $V_{CC(B)}$	1.65 V to 5.5 V	L	input or output	output or input
GND <sup>[2]</sup>	GND <sup>[2]</sup>	Х	Z	Z

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

[2] When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into power-down mode.

# 8. Limiting values

#### Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

			0		,
Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B		-0.5	+6.5	V
VI	input voltage		<u>[1]</u> –0.5	+6.5	V
Vo	output voltage	Active mode	<u>[1][2][3]</u> –0.5	V <sub>CCO</sub> + 0.5	V
		Power-down or 3-state mode	<u>[1]</u> –0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>1</sub> < 0 V	-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	-50	-	mA
lo	output current	$V_{O} = 0 V$ to $V_{CCO}$	[2] _	±50	mA
I <sub>CC</sub>	supply current	$I_{CC(A)}$ or $I_{CC(B)}$	-	100	mA
I <sub>GND</sub>	ground current		-100	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C

#### Dual supply translating transceiver; auto direction sensing; 3-state

#### Table 5. Limiting values ...continued

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40 \ ^{\circ}C$ to +125 $^{\circ}C$	<u>[4]</u> _	250	mW

[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

[2]  $V_{CCO}$  is the supply voltage associated with the output.

[3]  $V_{CCO}$  + 0.5 V should not exceed 6.5 V.

[4] For DHVQFN14 packages: above 60 °C the value of P<sub>tot</sub> derates linearly at 4.5 mW/K.

# 9. Recommended operating conditions

#### Table 6. Recommended operating conditions<sup>[1][2]</sup>

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		1.2	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
Vo	output voltage	Power-down or 3-state mode; $V_{CC(A)} = 1.2 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$			
		A port	0	3.6	V
		B port	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
$\Delta t / \Delta V$	input transition rise and fall rate	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	40	ns/V

[1] The A and B sides of an unused I/O pair must be held in the same state, both at  $V_{CCI}$  or both at GND.

[2]  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

# **10. Static characteristics**

#### Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V);  $T_{amb} = 25$  °C.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>OH</sub>	HIGH-level output voltage	A port; $V_{CC(A)}$ = 1.2 V; $I_O$ = -20 $\mu$ A	-	1.1	-	V
V <sub>OL</sub>	LOW-level output voltage	A port; $V_{CC(A)}$ = 1.2 V; $I_O$ = 20 $\mu$ A	-	0.09	-	V
I	input leakage current	OE input; V <sub>I</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	-	±1	μA
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_0 = 0$ V to $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	[1] -	-	±1	μΑ
I <sub>OFF</sub>	power-off leakage current	A port; V <sub>1</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0 V to 5.5 V	-	-	±1	μΑ
		B port; V <sub>1</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V	-	-	±1	μA

#### Table 7. Typical static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>CC</sub>	supply current	$V_I = 0 V \text{ or } V_{CCI}; I_O = 0 A$	[2]			
		$I_{CC(A)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	0.05	-	μΑ
		$I_{CC(B)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	3.3	-	μΑ
		$I_{CC(A)} + I_{CC(B)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	3.5	-	μΑ
CI	input capacitance	$\overline{\text{OE}}$ input; $\text{V}_{\text{CC}(\text{A})}$ = 1.2 V to 3.6 V; $\text{V}_{\text{CC}(\text{B})}$ = 1.65 V to 5.5 V	-	2.0	-	рF
1/0	input/output capacitance	A port; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	4.0	-	pF
		B port; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	7.5	-	pF

[1]  $V_{CCO}$  is the supply voltage associated with the output.

[2]  $V_{CCI}$  is the supply voltage associated with the input.

#### Table 8. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	–40 °C to +85 °C		–40 °C to	+125 °C	Unit	
				Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
	LOW-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub> = -20 μA	[2]					
		A port; $V_{CC(A)} = 1.4$ V to 3.6 V		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
		B port; $V_{CC(B)}$ = 1.65 V to 5.5 V		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
	LOW-level	I <sub>O</sub> = 20 μA	[2]					
	output voltage	A port; $V_{CC(A)} = 1.4$ V to 3.6 V		-	0.4	-	0.4	V
		B port; $V_{CC(B)}$ = 1.65 V to 5.5 V		-	0.4	-	0.4	V
I	input leakage current	$  \overline{\text{OE}} \text{ input; } V_{\text{I}} = 0 \text{ V to } 3.6 \text{ V;} \\ V_{\text{CC}(\text{A})} = 1.2 \text{ V to } 3.6 \text{ V;} \\ V_{\text{CC}(\text{B})} = 1.65 \text{ V to } 5.5 \text{ V} $		-	±2	-	±5	μΑ
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V or $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	[2]	-	±2	-	±10	μΑ
I <sub>OFF</sub>	power-off leakage	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0 V to 5.5 V		-	±2	-	±10	μA
	current	B port; V <sub>1</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V		-	±2	-	±10	μΑ

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions	–40 °C t	to +85 °C	-40 °C to	o +125 °C	Unit
			Min	Max	Min	Max	
I <sub>CC</sub>	supply current	$V_{I} = 0 V \text{ or } V_{CCI}; I_{O} = 0 A$ [1]					
		I <sub>CC(A)</sub>					
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	15	μA
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μA
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	2	-	15	μA
		$V_{CC(A)} = 0 V; V_{CC(B)} = 5.5 V$	-	-2	-	-15	μA
		I <sub>CC(B)</sub>					
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	15	μA
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μA
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	-2	-	-15	μA
		$V_{CC(A)} = 0 V; V_{CC(B)} = 5.5 V$	-	2	-	15	μA
		$I_{CC(A)} + I_{CC(B)}$					
		$V_{CC(A)} = 1.4 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$	-	10	-	40	μΑ

#### Table 8. Static characteristics ... continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

[1] V<sub>CCI</sub> is the supply voltage associated with the input.

[2]  $V_{CCO}$  is the supply voltage associated with the output.

## **11. Dynamic characteristics**

 Table 9.
 Typical dynamic characteristics for temperature 25 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for waveforms see Figure 5 and Figure 6.

Symbol	Parameter	Conditions			V <sub>C</sub>	С(В)		Unit
				1.8 V	2.5 V	3.3 V	5.0 V	
$V_{CC(A)} = 1$	1.2 V; T <sub>amb</sub> = 25 °C							
t <sub>pd</sub>	propagation delay	A to B		5.9	4.8	4.4	4.2	ns
		B to A		5.6	4.8	4.5	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		0.5	0.5	0.5	0.5	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	9.3	9.3	9.3	9.3	ns
		OE to B; no external load	[2]	8.7	7.7	7.6	7.1	ns
		OE to A		81	69	83	68	ns
		OE to B		81	69	83	68	ns
t <sub>t</sub>	transition time	A port		4.0	4.0	4.1	4.1	ns
		B port		2.6	2.0	1.7	1.4	ns

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80

Mbps

#### Dual supply translating transceiver; auto direction sensing; 3-state

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Voltages a	are referenced to GN	ID (ground = 0 V); for test	circuit see	Figure 7; f	or waveforms	see <u>Figure 5</u>	and Figure	<u>ə 6</u> .	
Symbol	Parameter	Conditions		V <sub>CC(B)</sub>					
				1.8 V	2.5 V	3.3 V	5.0 V		
t <sub>sk(o)</sub>	output skew time	between channels	[3]	0.2	0.2	0.2	0.2	ns	
t <sub>W</sub>	pulse width	data inputs		15	13	13	13	ns	

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#### Typical dynamic characteristics for temperature 25 °C<sup>[1]</sup> ... continued Table 9.

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

data rate

f<sub>data</sub>

ten is the same as tPZL and tPZH.

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_{t}$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ 

[2] Delay between  $\overline{OE}$  going HIGH and when the outputs are actually disabled.

Skew between any two outputs of the same package switching in the same direction. [3]

#### Table 10. Dynamic characteristics for temperature range –40 °C to +85 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for wave forms see Figure 5 and Figure 6.

Symbol Parameter	Conditions	V <sub>CC(B)</sub>								Unit		
				1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	-
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V											
t <sub>pd</sub>	propagation	A to B		1.4	12.9	1.2	10.1	1.1	10.0	0.8	9.9	ns
	delay	B to A		0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.9	1.0	12.9	1.0	12.9	1.0	12.9	ns
		OE to B; no external load	[2]	1.0	18.7	1.0	15.8	1.0	15.1	1.0	14.4	ns
		OE to A		-	320	-	260	-	260	-	280	ns
		OE to B		-	-	200	-	200	-	200	-	ns
t <sub>t</sub>	transition	A port		0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V											
t <sub>pd</sub>	propagation	A to B		1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
	delay	B to A		1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.7	1.0	11.7	1.0	11.7	1.0	11.7	ns
		OE to B; no external load	[2]	1.0	16.9	1.0	14.5	1.0	13.7	1.0	12.7	ns
		OE to A		-	260	-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		0.8	4.1	0.8	4.1	0.8	4.1	0.8	4.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns

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Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	0.15 V	2.5 V :		1	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	-
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		20	-	17	-	17	-	17	-	ns
f <sub>data</sub>	data rate			-	49	-	60	-	60	-	60	Mbp
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
	delay	B to A		-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	9.7	1.0	9.7	1.0	9.7	ns
		OE to B; no external load	[2]	-	-	1.0	12.9	1.0	12.0	1.0	11.0	ns
		OE to A		-	-	-	200	-	200	-	200	ns
		OE to B		-	-	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
	time	B port		-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	12	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	85	-	100	-	100	Mbp
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation	A to B		-	-	-	-	0.9	4.7	0.8	4.0	ns
	delay	B to A		-	-	-	-	1.0	4.9	0.9	3.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.4	1.0	9.4	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	11.3	1.0	10.4	ns
		OE to A		-	-	-	-	-	260	-	260	ns
		OE to B		-	-	-	-	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	2.5	0.7	2.5	ns
	time	B port		-	-	-	-	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbp

 Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C[1] ...continued

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}.$ 

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_{t}$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ 

[2] Delay between  $\overline{OE}$  going HIGH and when the outputs are actually disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

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## Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions					٧ <sub>cc</sub>	:(В)				Unit
				1.8 V <del>1</del>	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
/ <sub>CC(A)</sub> =	1.5 V ± 0.1 V											
pd	propagation	A to B		1.4	15.9	1.2	13.1	1.1	13.0	0.8	12.9	ns
	delay	B to A		0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μs
dis	disable time	OE to A; no external load	[2]	1.0	13.5	1.0	13.5	1.0	13.5	1.0	13.5	ns
		OE to B; no external load	[2]	1.0	19.9	1.0	16.8	1.0	16.1	1.0	15.2	ns
		OE to A		-	340	-	280	-	280	-	300	ns
		OE to B		-	220	-	220	-	220	-	220	ns
ťt	transition	A port		0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
	time	B port		0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
sk(o)	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
W	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
data	data rate			-	40	-	40	-	40	-	40	Mbp
$I_{CC(A)} =$	1.8 V ± 0.15 V											
pd	propagation	A to B		1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns
	delay	B to A		1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns
en	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
dis	disable time	OE to A; no external load	[2]	1.0	12.3	1.0	12.3	1.0	12.3	1.0	12.3	ns
		OE to B; no external load	[2]	1.0	18.1	1.0	15.3	1.0	14.5	1.0	13.5	ns
		OE to A		-	280	-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t	transition	A port		0.8	6.2	0.8	6.1	0.8	6.1	0.8	6.1	ns
	time	B port		0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
sk(o)	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
W	pulse width	data inputs		22	-	19	-	19	-	19	-	ns
data	data rate			-	45	-	55	-	55	-	55	Mbp
	2.5 V ± 0.2 V											
pd	propagation	A to B		-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
	delay	B to A		-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
en	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
dis	disable time	OE to A; no external load	[2]	-	-	1.0	10.1	1.0	10.1	1.0	10.1	ns
		OE to B; no external load	[2]	-	-	1.0	13.5	1.0	12.7	1.0	11.7	ns
		OE to A		-	-	-	220	-	220	-	220	ns
		OE to B		-	-	-	220	-	220	-	220	ns
t	transition	A port		-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
•	time	B port				0.7	4.6	0.5	4.8	0.4	4.7	

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C<sup>[1]</sup>

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Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	- 0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs;		-	-	14	-	13	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	75	-	80	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation	A to B		-	-	-	-	0.9	7.7	0.8	7.0	ns
	delay	B to A		-	-	-	-	1.0	7.9	0.9	6.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.9	1.0	9.9	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	12.1	1.0	10.9	ns
		OE to A		-	-	-	-	-	280	-	280	ns
		OE to B		-	-	-	-	-	220	-	220	ns
tt	transition	A port		-	-	-	-	0.7	4.5	0.7	4.5	ns
	time	B port		-	-	-	-	0.5	4.1	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

Table 11. Dynamic characteristics for temperature range –40 °C to +125 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for wave forms see Figure 5 and Figure 6.

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{en}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}.$ 

 $t_{dis}$  is the same as  $t_{\mathsf{PLZ}}$  and  $t_{\mathsf{PHZ}}.$   $t_t$  is the same as  $t_{\mathsf{THL}}$  and  $t_{\mathsf{TLH}}$ 

[2] Delay between  $\overline{OE}$  going HIGH and when the outputs are actually disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions				V <sub>CC(A)</sub>				Unit
			1.2 V	1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V	
						V <sub>CC(B)</sub>				
			1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V	
T <sub>amb</sub> = 2	25 °C									
C <sub>PD</sub>	power	outputs enabled; OE = GND								
	dissipation capacitance	A port: (direction A to B)	5	5	5	5	5	5	5	pF
		A port: (direction B to A)	8	8	8	8	8	8	8	pF
		B port: (direction A to B)	18	18	18	18	18	18	18	pF
		B port: (direction B to A)	13	16	12	12	12	12	13	pF
		outputs disabled; $OE = V_{CC(A)}$								
		A port: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	pF

# **Table 12.** Typical power dissipation capacitance

[1]  $C_{PD}$  is used to determine the dynamic power dissipation (P<sub>D</sub> in  $\mu$ W).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

 $f_i$  = input frequency in MHz;

 $f_o = output frequency in MHz;$ 

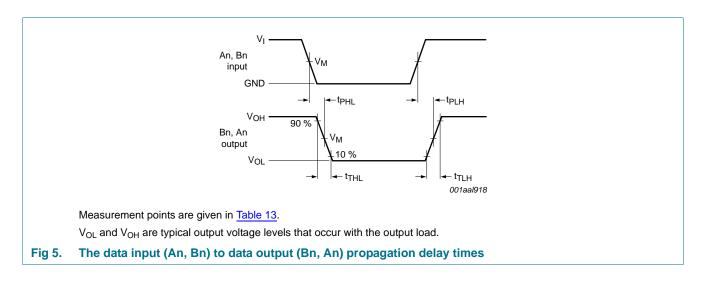
 $C_L$  = load capacitance in pF;

V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_0)$  = sum of the outputs.

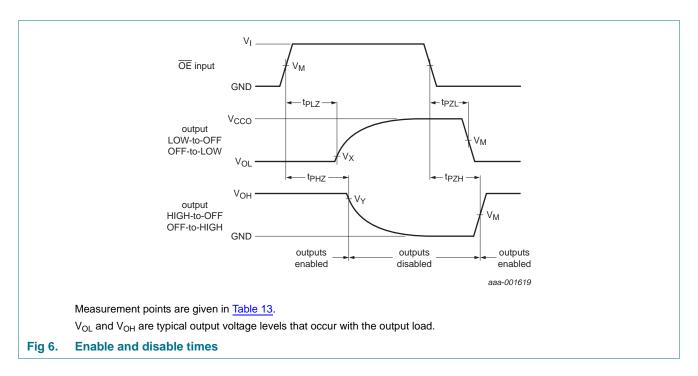
# 12. Waveforms



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#### Dual supply translating transceiver; auto direction sensing; 3-state



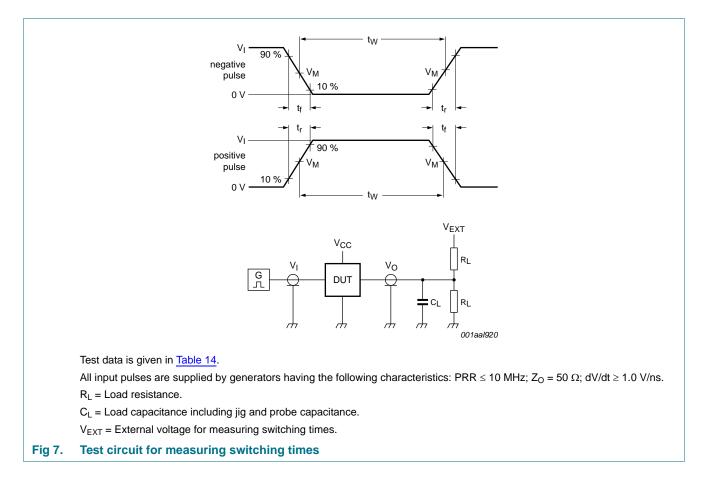
#### Table 13. Measurement points<sup>[1]</sup>

Supply voltage	Input	Output		
V <sub>cco</sub>	V <sub>M</sub>	V <sub>M</sub>	Vx	V <sub>Y</sub>
1.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V
$1.5~V\pm0.1~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V
$1.8~V\pm0.15~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$2.5~V\pm0.2~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$3.3~V\pm0.3~V$	0.5V <sub>CCI</sub>	$0.5V_{CCO}$	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V
$5.0~V\pm0.5~V$	0.5V <sub>CCI</sub>	$0.5V_{CCO}$	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V

[1] V<sub>CCI</sub> is the supply voltage associated with the input and V<sub>CCO</sub> is the supply voltage associated with the output.

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#### Dual supply translating transceiver; auto direction sensing; 3-state



#### Table 14. Test data

Supply voltag	le	Input		Load		V <sub>EXT</sub>		
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V [1]	∆t/∆V	CL	RL <sup>[2]</sup>	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ<sup>[3]</sup></sub>
1.2 V to 3.6 V	1.65 V to 5.5 V	V <sub>CCI</sub>	$\leq$ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>

[1] V<sub>CCI</sub> is the supply voltage associated with the input.

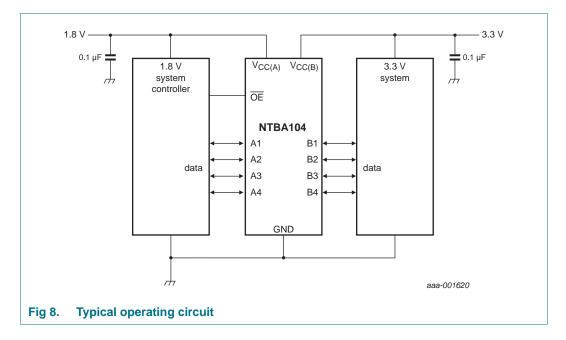
[2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 M\Omega$ ; for measuring enable and disable times,  $R_L = 50 K\Omega$ .

 $\label{eq:V_CCO} \mbox{is the supply voltage associated with the output.}$ 

# **13. Application information**

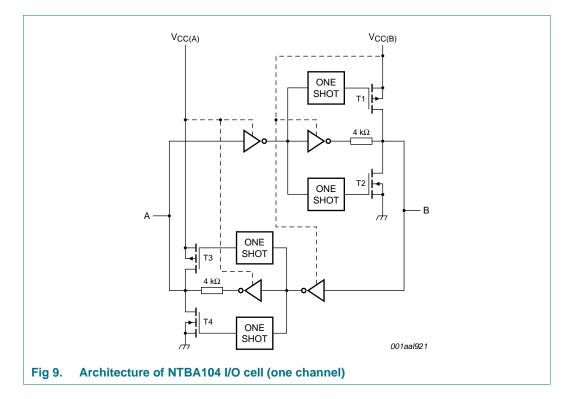
## **13.1 Applications**

Voltage level-translation applications. The NTBA104 can be used to interface between devices or systems operating at different supply voltages. See <u>Figure 8</u> for a typical operating circuit using the NTBA104.



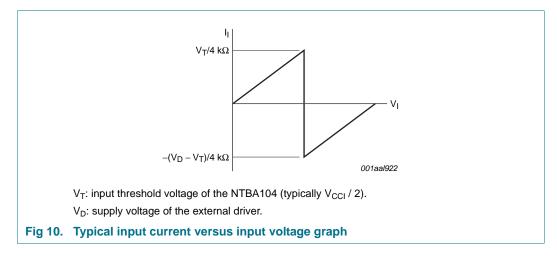
#### 13.2 Architecture

The architecture of the NTBA104 is shown in Figure 9. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NTBA104 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shots turn on the PMOS transistors (T1, T3) for a short duration, accelerating the low-to-high transition. Similarly, during a falling edge, the one shots turn on the NMOS transistors (T2, T4) for a short duration, accelerating the high-to-low transition. During output transitions the typical output impedance is 70  $\Omega$  at V<sub>CCO</sub> = 1.2 V to 1.8 V, 50  $\Omega$  at V<sub>CCO</sub> = 1.8 V to 3.3 V and 40  $\Omega$  at V<sub>CCO</sub> = 3.3 V to 5.0 V.



#### 13.3 Input driver requirements

For correct operation, the device driving the data I/Os of the NTBA104 must have a minimum drive capability of  $\pm 2$  mA See <u>Figure 10</u> for a plot of typical input current versus input voltage.



#### 13.4 Power up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTBA104 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### 13.5 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = HIGH causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes HIGH and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken LOW. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to  $V_{CC(A)}$  through a pull-up resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

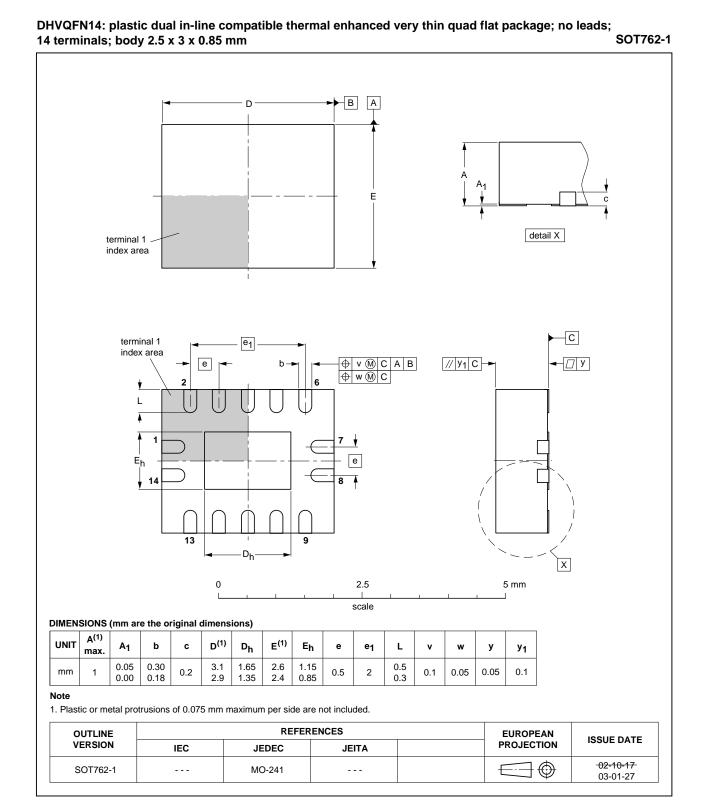
#### 13.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously the NTBA104 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be kept higher than 50 k $\Omega$ . For this reason the NTBA104 is not recommended for use in open drain driver applications such as 1-Wire or I<sup>2</sup>C. For these applications, the NTSA104 level translator is recommended.

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Dual supply translating transceiver; auto direction sensing; 3-state

## 14. Package outline

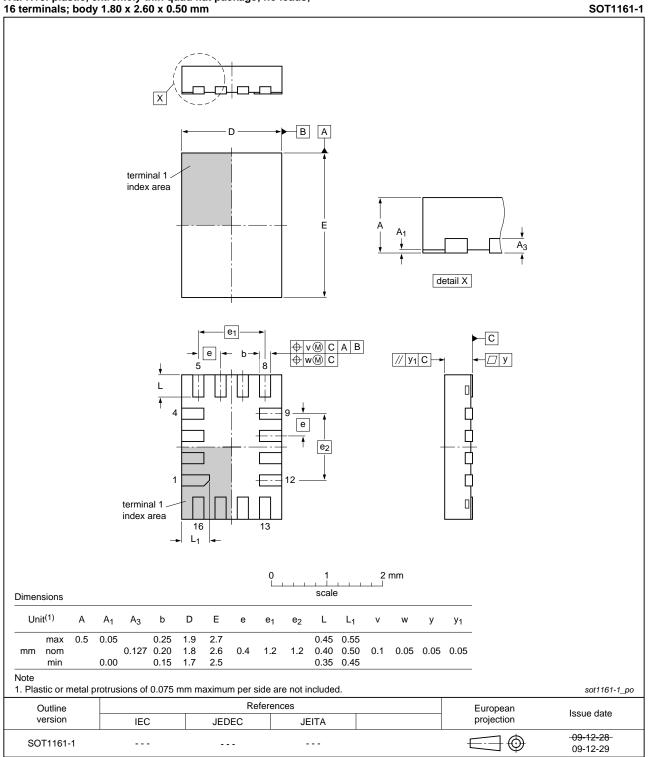


#### Fig 11. Package outline SOT762-1 (DHVQFN14)

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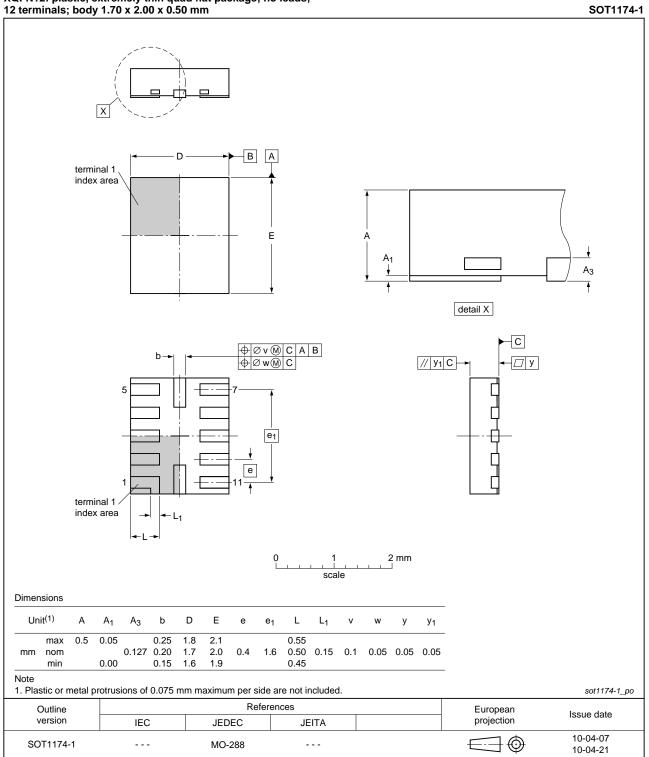


XQFN16: plastic, extremely thin quad flat package; no leads; 16 terminals; body 1.80 x 2.60 x 0.50 mm

#### Fig 12. Package outline SOT1161-1 (XQFN16)

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Dual supply translating transceiver; auto direction sensing; 3-state



XQFN12: plastic, extremely thin quad flat package; no leads; 12 terminals; body 1.70 x 2.00 x 0.50 mm

#### Fig 13. Package outline SOT1174-1 (XQFN12)

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# **15. Abbreviations**

Table 15.	Abbreviations
Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

# 16. Revision history

Table 16. Revision his	story			
Document ID	Release date	Data sheet status	Change notice	Supersedes
NTBA104 v.2	20120522	Product data sheet	-	NTBA104 v.1
Modifications:	<ul> <li>Typical operation</li> </ul>	ating circuit ( <u>Figure 8</u> ) modified	d (errata).	
NTBA104 v.1	20111206	Product data sheet	-	-

# 17. Legal information

#### 17.1 Data sheet status

Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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NTBA104

# **NTBA104**

#### Dual supply translating transceiver; auto direction sensing; 3-state

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# **NTBA104**

Dual supply translating transceiver; auto direction sensing; 3-state

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