## **BGU7007**

# SiGe:C Low Noise Amplifier MMIC for GPS, GLONASS, Galileo and Compass

Rev. 4. — 18 January 2017

**Product data sheet** 

## 1. Product profile

#### 1.1 General description

The BGU7007 is, also known as the GPS1102M, a Low Noise Amplifier (LNA) for GNSS receiver applications in a plastic leadless 6-pin, extremely small SOT886 package. The BGU7007 requires only one external matching inductor and one external decoupling capacitor.

The BGU7007 adapts itself to the changing environment resulting from co-habitation of different radio systems in modern cellular handsets. It has been designed for low power consumption and optimal performance when jamming signals from co-existing cellular transmitters are present. At low jamming power levels it delivers 18.5 dB gain at a noise figure of 0.85 dB. During high jamming power levels, resulting for example from a cellular transmit burst, it temporarily increases its bias current to improve sensitivity.

#### **CAUTION**



This device is sensitive to ElectroStatic Discharge (ESD). Therefore care should be taken during transport and handling.

#### 1.2 Features and benefits

- Covers full GNSS L1 band, from 1559 MHz to 1610 MHz
- Noise figure (NF) = 0.85 dB
- Gain 18.5 dB
- High input1 dB compression point P<sub>i</sub> (1dB) of −12 dBm
- High out of band IP3<sub>i</sub> of 4 dBm
- Supply voltage 1.5 V to 3.1 V
- Power-down mode current consumption < 1 μA</p>
- Optimized performance at low supply current of 4.8 mA
- Integrated temperature stabilized bias for easy design
- Requires only one input matching inductor and one supply decoupling capacitor
- Input and output DC decoupled
- ESD protection on all pins (HBM > 2 kV)
- Integrated matching for the output
- Small 6-pin leadless package 1 mm × 1.45 mm × 0.5 mm
- 110 GHz transit frequency SiGe:C technology



#### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

#### 1.3 Applications

 LNA for GPS, GLONASS, Galileo and Compass (BeiDou) in smart phones, feature phones, tablet PCs, Personal Navigation Devices, Digital Still Cameras, Digital Video Cameras, RF Front End modules, complete GPS chipset modules and theft protection (laptop, ATM)

#### 1.4 Quick reference data

Table 1. Quick reference data

f = 1559 MHz to 1610 MHz;  $V_{CC}$  = 1.8 V;  $P_i$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 5.6 nH inductor; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
$V_{CC}$	supply voltage	RF input AC coupled		1.5	-	3.1	V
I <sub>CC</sub>	supply current	$V_{\text{ENABLE}} \ge 0.8 \text{ V}$					
		P <sub>i</sub> < -40 dBm		3.4	4.8	6.1	mΑ
		$P_i = -20 \text{ dBm}$		8.9	12.8	15.9	mΑ
Gp	power gain	$P_i$ < $-40$ dBm, no jammer		16.5	18.5	20.5	dB
		$P_i = -20 \text{ dBm}$		17.5	19.5	21.5	dB
NF	noise figure	$P_i$ < -40 dBm, no jammer	[1]	-	0.85	1.2	dB
		$P_i < -40$ dBm, no jammer	[2]	-	0.90	1.3	dB
		$P_i = -20 \text{ dBm}$		-	1.2	1.6	dB
P <sub>i(1dB)</sub>	input power at 1 dB	f = 1559 MHz to 1610 MHz					
	gain compression	V <sub>CC</sub> = 1.5 V		-16	-13	-	dBm
		V <sub>CC</sub> = 1.8 V		-15	-12	-	dBm
		$V_{CC} = 2.85 \text{ V}$		-14	-11	-	dBm
IP3 <sub>i</sub>	input third-order intercept point	f = 1.575 GHz					
		V <sub>CC</sub> = 1.5 V	[3]	1	4	-	dBm
		V <sub>CC</sub> = 1.8 V	[3]	1	4	-	dBm
		V <sub>CC</sub> = 2.85 V	[3]	2	5	-	dBm

<sup>[1]</sup> PCB losses are subtracted.

## 2. Pinning information

Table 2. Pinning

Pin	Description	Simplified outline Graphic symb	ool
1	GND		
2	GND	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	
3	RF_IN		<del></del> 6
4	V <sub>CC</sub>		
5	ENABLE	1 2 3 2 1 syr.	n129
6	RF_OUT	Transparent top view	

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<sup>[2]</sup> Including PCB losses.

<sup>[3]</sup>  $f_1 = 1713 \text{ MHz}$ ;  $f_2 = 1851 \text{ MHz}$ ;  $P_1 = P_2 = -30 \text{ dBm}$ .

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## 3. Ordering information

Table 3. Ordering information

Type number	Package				
	Name	Description	Version		
BGU7007	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 $\times$ 1.45 $\times$ 0.5 mm	SOT886		

## 4. Marking

Table 4. Marking codes

Type number	Marking code
BGU7007	B6

## 5. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC}$	supply voltage	RF input AC coupled	-0.5	5.0	V
$V_{ENABLE}$	voltage on pin ENABLE	V <sub>ENABLE</sub> < V <sub>CC</sub> + 0.6	<u>[2]</u> –0.5	5.0	V
$V_{RF\_IN}$	voltage on pin RF_IN	DC; $V_{RF_IN} < V_{CC} + 0.6$	[2][3] -0.5	5.0	V
$V_{RF\_OUT}$	voltage on pin RF_OUT	DC; $V_{RF\_OUT} < V_{CC} + 0.6$	[2][3] -0.5	5.0	V
Pi	input power		-	0	dBm
P <sub>tot</sub>	total power dissipation	T <sub>sp</sub> ≤ 130 °C	<u>[1]</u>	55	mW
T <sub>stg</sub>	storage temperature		-65	150	°C
Tj	junction temperature		-	150	°C
V <sub>ESD</sub>	electrostatic discharge voltage	Human Body Model (HBM); According JEDEC standard 22-A114E	-	4	kV
		Charged Device Model (CDM); According JEDEC standard 22-C101B	-	1	kV

<sup>[1]</sup>  $T_{sp}$  is the temperature at the soldering point of the emitter lead.

## 6. Thermal characteristics

Table 6. Thermal characteristics

Symbol	Parameter	Conditions	Тур	Unit
$R_{th(j-sp)}$	thermal resistance from junction to solder point		225	K/W

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<sup>[2]</sup> Warning: due to internal ESD diode proctection, the applied DC voltage should not exceed V<sub>CC</sub> + 0.6 and shall not exceed 5.0 V in order to avoid excess current.

<sup>[3]</sup> The RF input and RF output are AC coupled through internal DC blocking capacitors.

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## 7. Characteristics

Table 7. Characteristics

f = 1559 MHz to 1610 MHz;  $V_{CC}$  = 1.8 V;  $V_{ENABLE}$  >= 0.8 V;  $P_i$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 5.6 nH inductor; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
$V_{CC}$	supply voltage	RF input AC coupled		1.5	-	3.1	V
I <sub>CC</sub>	supply current	$V_{\text{ENABLE}} \ge 0.8 \text{ V}$					
		$P_i < -40 \text{ dBm}$		3.4	4.8	6.1	mΑ
		$P_i = -20 \text{ dBm}$		8.9	12.8	15.9	mΑ
		$V_{\text{ENABLE}} \leq 0.35 \text{ V}$		-	-	1	μΑ
$T_{amb}$	ambient temperature			-40	+25	+85	°C
$G_p$	power gain	T <sub>amb</sub> = 25 °C					
		$P_i < -40$ dBm, no jammer		16.5	18.5	20.5	dB
		$P_i = -20 \text{ dBm}$ , no jammer		17.5	19.5	21.5	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$		17.5	19.5	21.5	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$		17.5	19.5	21.5	dB
		$-40  ^{\circ}\text{C} \le \text{T}_{amb} \le +85  ^{\circ}\text{C}$					
		P <sub>i</sub> < −40 dBm, no jammer		16	-	21	dB
		$P_i = -20$ dBm, no jammer		17	-	22	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$		17	-	22	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$		17	-	22	dB
RLin	input return loss	$P_i < -40 \text{ dBm}$		5	7	-	dB
		$P_i = -20 \text{ dBm}$		7	10	-	dB
$RL_{out}$	output return loss	$P_i < -40 \text{ dBm}$		12	18	-	dB
		$P_i = -20 \text{ dBm}$		15	24	-	dB
ISL	isolation			22	24	-	dB
NF	noise figure	T <sub>amb</sub> = 25 °C					
		P <sub>i</sub> < −40 dBm, no jammer	<u>[1]</u>	-	0.85	1.2	dB
		P <sub>i</sub> < −40 dBm, no jammer	[2]	-	0.90	1.3	dB
		$P_i = -20 \text{ dBm}$ , no jammer		-	1.2	1.6	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$		-	1.1	1.5	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$		-	1.3	1.7	dB
		$-40~^{\circ}\text{C} \le \text{T}_{amb} \le +85~^{\circ}\text{C}$					
		P <sub>i</sub> < −40 dBm, no jammer		-	-	1.7	dB
		P <sub>i</sub> = −20 dBm, no jammer		-	-	1.9	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$		-	-	1.8	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$		-	-	2.0	dB

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Table 7. Characteristics ... continued

f = 1559 MHz to 1610 MHz;  $V_{CC}$  = 1.8 V;  $V_{ENABLE}$  >= 0.8 V;  $P_i$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 5.6 nH inductor; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
P <sub>i(1dB)</sub>	input power at 1 dB gain compression	f = 1559 MHz to 1610 MHz					
		V <sub>CC</sub> = 1.5 V		-16	-13	-	dBm
		V <sub>CC</sub> = 1.8 V		-15	-12	-	dBm
		V <sub>CC</sub> = 2.85 V		-14	-11	-	dBm
		f = 806 MHz to 928 MHz					
		V <sub>CC</sub> = 1.5 V	<u>[3]</u>	-16	-13	-	dBm
		V <sub>CC</sub> = 1.8 V	<u>[3]</u>	-15	-12	-	dBm
		V <sub>CC</sub> = 2.85 V	<u>[3]</u>	-15	-12	-	dBm
		f = 1612 MHz to 1909 MHz					
		V <sub>CC</sub> = 1.5 V	<u>[3]</u>	-14	-11	-	dBm
		V <sub>CC</sub> = 1.8 V	<u>[3]</u>	-13	-10	-	dBm
		V <sub>CC</sub> = 2.85 V	<u>[3]</u>	-11	-8	-	dBm
IP3 <sub>i</sub>	input third-order intercept point	f = 1.575 GHz					
		V <sub>CC</sub> = 1.5 V	<u>[4]</u>	1	4	-	dBm
		V <sub>CC</sub> = 1.8 V	<u>[4]</u>	1	4	-	dBm
		V <sub>CC</sub> = 2.85 V	<u>[4]</u>	2	5	-	dBm
t <sub>on</sub>	turn-on time		<u>[5]</u>	-	-	2	μS
t <sub>off</sub>	turn-off time		<u>[5]</u>	-	-	1	μS
K	Rollett stability factor			1	-	-	

<sup>[1]</sup> PCB losses are subtracted.

Table 8. ENABLE (pin 5)

 $-40 \ ^{\circ}\text{C} \le T_{amb} \le +85 \ ^{\circ}\text{C}; \ 1.5 \ \text{V} \le \text{V}_{CC} \le 3.1 \ \text{V}$ 

V <sub>ENABLE</sub> (V)	State
≤ 0.35	OFF
≥ 0.8	ON

<sup>[2]</sup> Including PCB losses.

<sup>[3]</sup> Out of band.

<sup>[4]</sup>  $f_1 = 1713 \text{ MHz}$ ;  $f_2 = 1851 \text{ MHz}$ ;  $P_1 = P_2 = -30 \text{ dBm}$ .

<sup>[5]</sup> Within 10 % of the final gain.

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## 8. Application information

#### 8.1 GNSS LNA

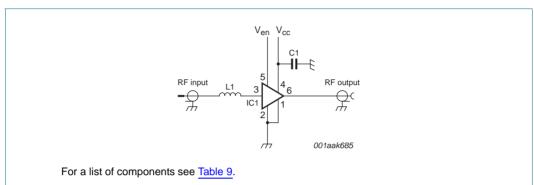
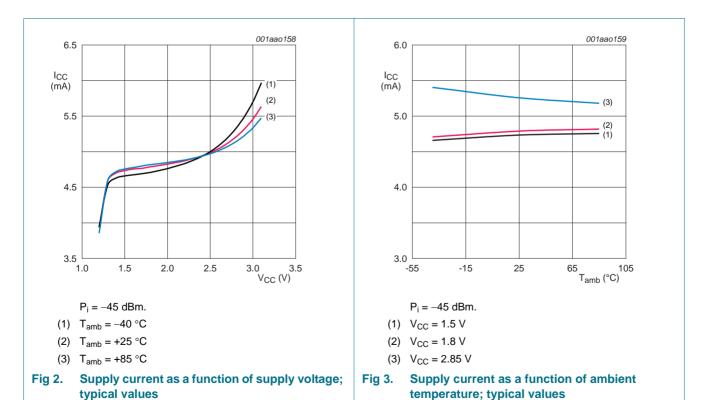


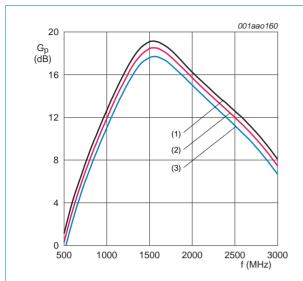
Fig 1. Schematics GNSS LNA evaluation board

**Table 9. List of components** For schematics see Figure 1.

Component	Description	Value	Supplier	Remarks
C1	decoupling capacitor	1 nF	various	
IC1	BGU7007	-	NXP	
L1	high quality matching inductor	5.6 nH	Murata LQW15A	



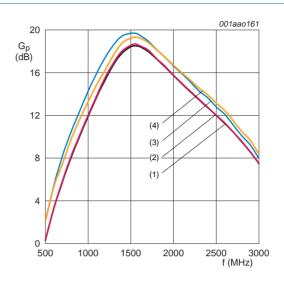
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$$V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$$

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

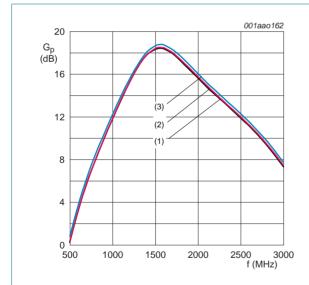
Fig 4. Power gain as a function of frequency; typical values



$$V_{CC} = 1.8 \text{ V}; T_{amb} = 25 ^{\circ}\text{C}.$$

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

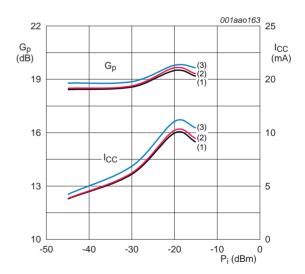
Fig 5. Power gain as a function of frequency; typical values



 $P_i = -45 \text{ dBm}; T_{amb} = 25 \text{ }^{\circ}\text{C}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

Fig 6. Power gain as a function of frequency; typical values



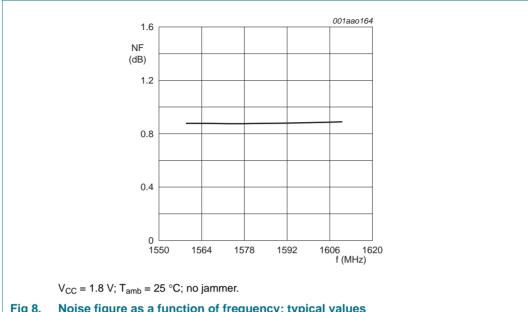
 $T_{amb} = 25 \, ^{\circ}\text{C}; f = 1575 \, \text{MHz}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

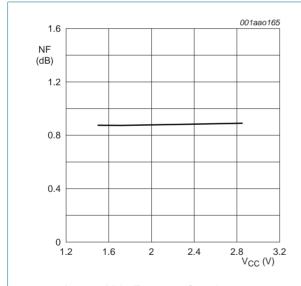
Fig 7. Power gain as a function of input power; typical values

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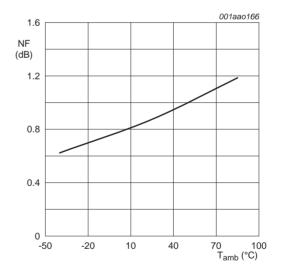


Noise figure as a function of frequency; typical values Fig 8.



f = 1575 MHz;  $T_{amb} = 25 \,^{\circ}\text{C}$ ; no jammer.

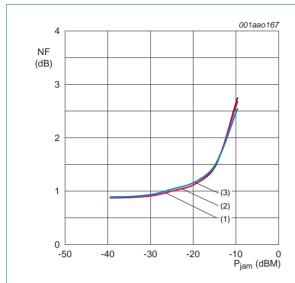
Fig 9. Noise figure as a function of supply voltage; typical values



f = 1575 MHz;  $V_{CC} = 1.8 \text{ V}$ ; no jammer.

Fig 10. Noise figure as a function of ambient temperature; typical values

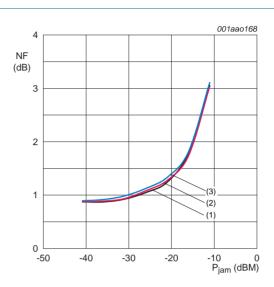
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 $f_{jam}$ = 850 MHz;  $T_{amb}$  = 25 °C; f = 1575 MHz.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

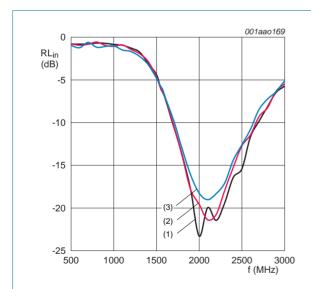
Fig 11. Noise figure as a function of jamming power; typical values



 $f_{jam}$ = 1850 MHz;  $T_{amb}$  = 25 °C; f = 1575 MHz.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

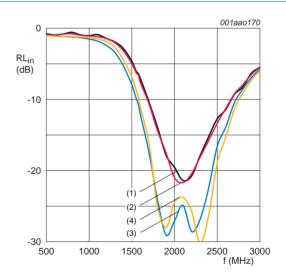
Fig 12. Noise figure as a function of jamming power; typical values



 $V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 13. Input return loss as a function of frequency; typical values

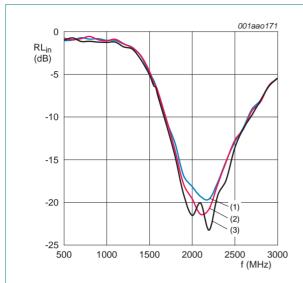


 $V_{CC} = 1.8 \text{ V}; T_{amb} = 25 \,^{\circ}\text{C}.$ 

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 14. Input return loss as a function of frequency; typical values

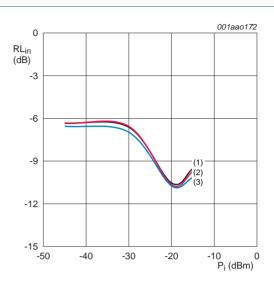
#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



$$P_i = -45$$
 dBm;  $T_{amb} = 25$  °C.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

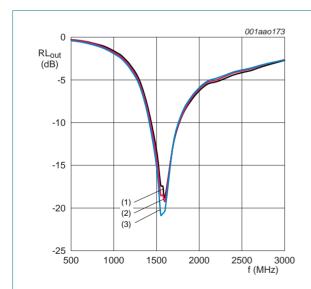
Fig 15. Input return loss as a function of frequency; typical values



 $T_{amb} = 25 \, ^{\circ}C; f = 1575 \, MHz.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

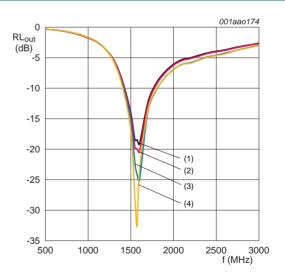
Fig 16. Input return loss as a function of input power; typical values



 $V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 17. Output return loss as a function of frequency; typical values

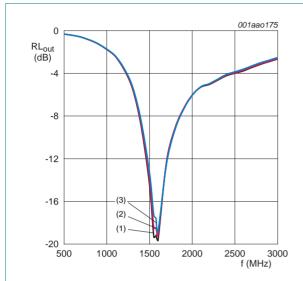


 $V_{CC}$  = 1.8 V;  $T_{amb}$  = 25 °C.

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 18. Output return loss as a function of frequency; typical values

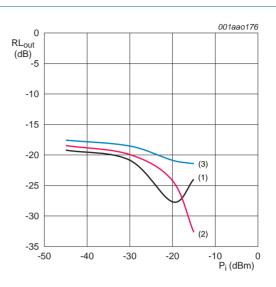
#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



$$P_i = -45$$
 dBm;  $T_{amb} = 25$  °C.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

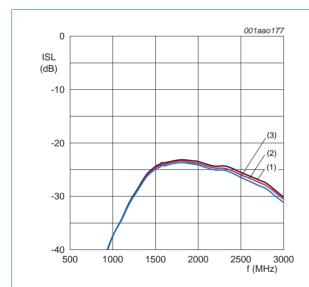
Fig 19. Output return loss as a function of frequency; typical values



$$T_{amb} = 25 \, ^{\circ}C; f = 1575 \, MHz.$$

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

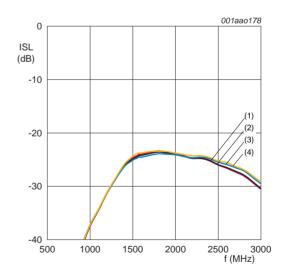
Fig 20. Output return loss as a function of input power; typical values



 $V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 21. Isolation as a function of frequency; typical values

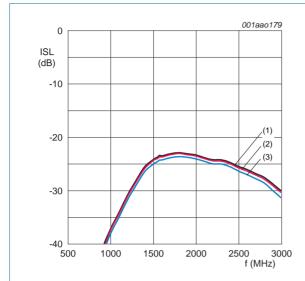


 $V_{CC} = 1.8 \text{ V}; T_{amb} = 25 \,^{\circ}\text{C}.$ 

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 22. Isolation as a function of frequency; typical values

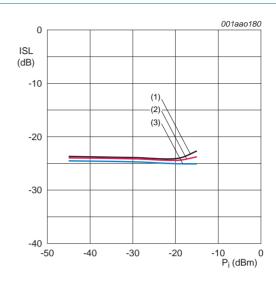
#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



$$P_i = -45$$
 dBm;  $T_{amb} = 25$  °C.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

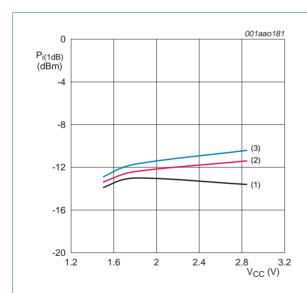
Fig 23. Isolation as a function of frequency; typical values



$$T_{amb} = 25 \, ^{\circ}\text{C}; f = 1575 \, \text{MHz}.$$

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

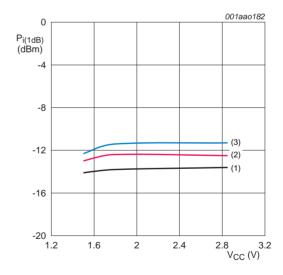
Fig 24. Isolation as a function of input power; typical values



f = 1575 MHz.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 25. Input power at 1 dB gain compression as a function of supply voltage; typical values



f = 850 MHz.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 26. Input power at 1 dB gain compression as a function of supply voltage; typical values

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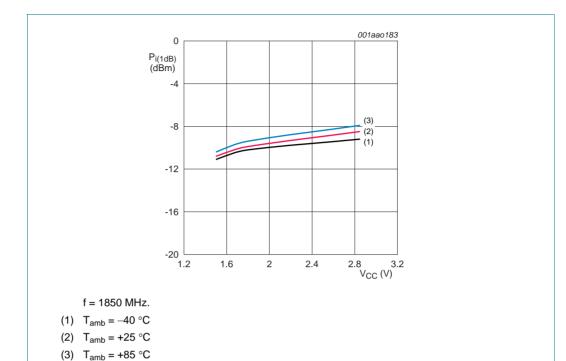
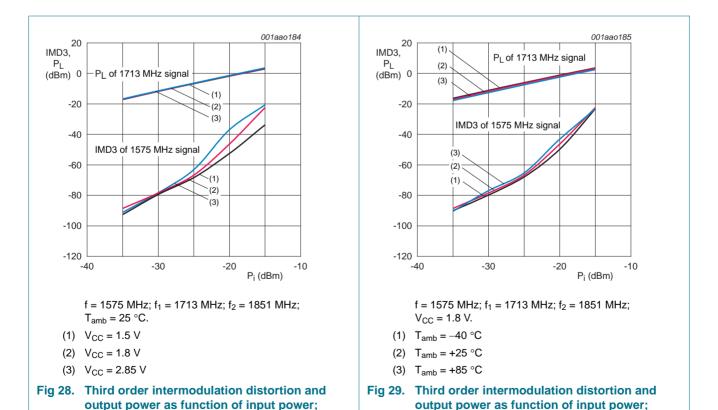


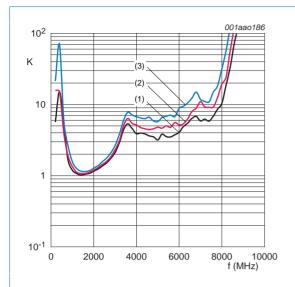
Fig 27. Input power at 1 dB gain compression as a function of supply voltage; typical values



typical values

typical values

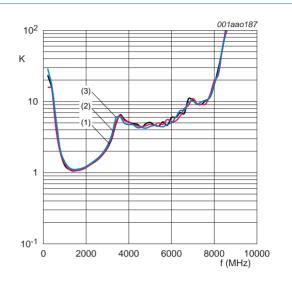
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$$V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$$

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 30. Rollett stability factor as a function of frequency; typical values



 $T_{amb} = 25 \, ^{\circ}\text{C}; \, P_i = -45 \, \text{dBm}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$

Fig 31. Rollett stability factor as a function of frequency; typical values

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## 9. Package outline

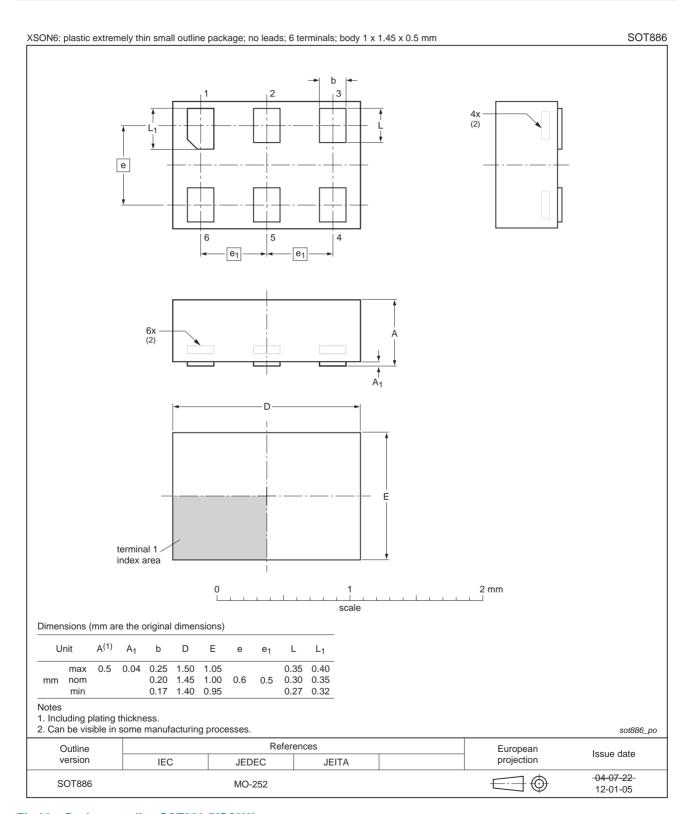


Fig 32. Package outline SOT886 (XSON6)

BGU7007

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## 10. Abbreviations

Table 10. Abbreviations

Acronym	Description
AC	Alternating Current
ATM	Automated Teller Machine (cash dispenser)
DC	Direct Current
GLONASS	GLObal NAvigation Satellite System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
HBM	Human Body Model
MMIC	Monolithic Microwave Integrated Circuit
PC	Personal Computer
PCB	Printed Circuit Board
RF	Radio Frequency
SiGe:C	Silicon Germanium Carbon

## 11. Revision history

#### Table 11. Revision history

BGU7007 v.4 20170118 Product data sheet - BGU7007 v.3  Modifications:  • Section 1: added GPS1102M according to our new naming convention  BGU7007 v.3 <tbd> • BGU7007 v.2  Modifications:  • Added 'Compass' to descriptive title and to Section 1.3 on page 2</tbd>	Document ID	Release date	Data sheet status	Change notice	Supersedes
BGU7007 v.3 <tbd>Product data sheet - BGU7007 v.2</tbd>	BGU7007 v.4	20170118	Product data sheet	-	BGU7007 v.3
	Modifications:	<ul> <li>Section 1: added 0</li> </ul>	SPS1102M according to our new	naming convention	
Modifications: • Added 'Compass' to descriptive title and to Section 1.3 on page 2	BGU7007 v.3	<tbd></tbd>	Product data sheet	-	BGU7007 v.2
	Modifications:	<ul> <li>Added 'Compass'</li> </ul>	to descriptive title and to Section	1.3 on page 2	
<ul> <li>Section 1.2 on page 1: row 6, changed 2.8.5 V to 3.1 V</li> </ul>		<ul> <li>Section 1.2 on page</li> </ul>	<u>e 1</u> : row 6, changed 2.8.5 V to 3.	1 V	
<ul> <li><u>Table 1 on page 2</u>, <u>Table 7 on page 4</u> and <u>Table 8 on page 5</u>: changed value V<sub>CC</sub> from 2.85 V to 3</li> </ul>		<ul> <li>Table 1 on page 2,</li> </ul>	Table 7 on page 4 and Table 8 o	n page 5: changed value Vo	<sub>CC</sub> from 2.85 V to 3.1 V
<ul> <li><u>Table 5 on page 3</u>: Several additions and changes</li> </ul>		<ul> <li>Table 5 on page 3:</li> </ul>	Several additions and changes		
BGU7007 v.2 20111103 Product data sheet - BGU7007 v.1	BGU7007 v.2	20111103	Product data sheet	-	BGU7007 v.1
BGU7007 v.1 20110520 Product data sheet	BGU7007 v.1	20110520	Product data sheet	-	-

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### 12. Legal information

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Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
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