

**PCA9412; PCA9412A** 3.0 MHz, 300 mA, DC-to-DC boost converter Rev. 1 — 9 June 2017

Product data sheet

## 1. General description

The PCA9412 and PCA9412A are highly efficient 3.0 MHz, 300 mA, step-up DC-to-DC converters. They convert input voltages from 2.5 V to 5.25 V to a fixed output voltage of 5.4 V.

These devices are optimized for battery-powered applications. High efficiency of up to 94 % enables an extended battery life in all portable designs. Step-up operation at a switching frequency of 3 MHz allows using 1  $\mu$ H inductor or smaller.

### 2. Features and benefits

- Efficiency up to 94 %
- $V_{IN} \ge V_O$ , (Pass-Through Mode Operation)
- Load disconnect
- Current-mode controller
- Soft start function for limiting inrush current with true load disconnect
- Overcurrent and over-temperature protection
- The PCA9412 totally disconnects input to output when disabled
- The PCA9412A connects input to output when disabled
- Wafer-Level Chip-Size Package (WLCSP) with 0.4 mm pitch; allows for the use of a smaller antenna, or for greater signal strength

### 3. Applications

- Smartphones
- NFC terminals

#### **Ordering information** 4.

#### Table 1. **Ordering information**

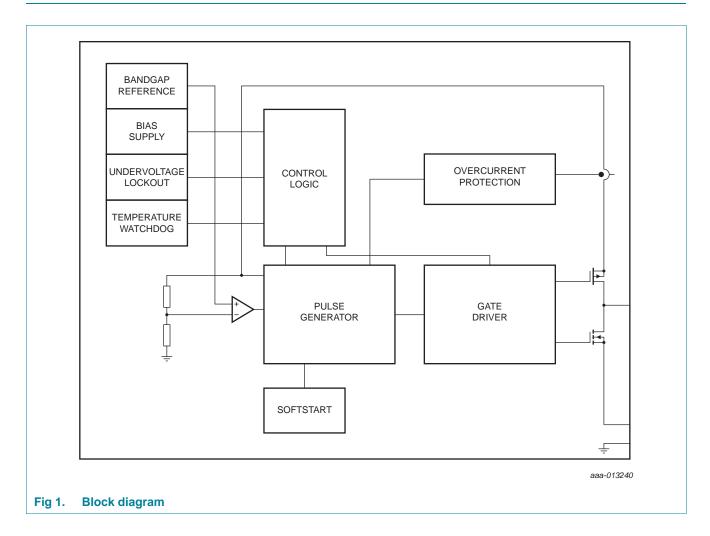
Type number	Topside	Package		
	mark	Name	Description	Version
PCA9412UK	P12	WLCSP9	wafer-level chip-size package; 9 bumps; body 1.24 $\times$ 1.24 $\times$ 0.525 mm	-
PCA9412AUK	12A	WLCSP9	wafer-level chip-size package; 9 bumps; body 1.24 $\times$ 1.24 $\times$ 0.525 mm	-



### 4.1 Ordering options

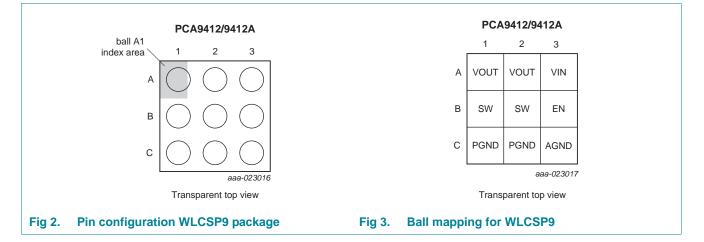
Table 2. Orderi	Table 2. Ordering options						
Type number	Orderable part number	Package	Packing method	Minimum order quantity	Temperature		
PCA9412UK	PCA9412UKZ	WLCSP9	REEL 7" Q1/T1 *SPECIAL MARK CHIPS DP	3000	$T_{amb} = -40 \ ^{\circ}C \ to \ +85 \ ^{\circ}C$		
PCA9412AUK	PCA9412AUKZ	WLCSP9	REEL 7" Q1/T1 *SPECIAL MARK CHIPS DP	3000	$T_{amb} = -40 \text{ °C to } +85 \text{ °C}$		

## 5. Block diagram



#### **Pinning information** 6.

#### Pinning 6.1

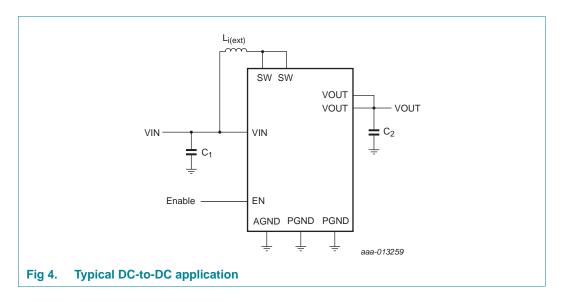


### 6.2 Pin description

#### Table 3. **Pin description**

#### Symbol Pin Description VOUT A1, A2 Output voltage. This pin is the output voltage terminal; connect directly to COUT. VIN A3 Input voltage. Connect to Li-Ion battery input power source. SW B1, B2 Switching node. Connect to inductor. B3 ΕN Enable. Used to enable/disable the device; HIGH = enabled. Non-A version: EN low = total disconnect A version: EN low = forced pass through PGND C1, C2 Power ground. This is the power return for the IC. COUT capacitor should be returned with the shortest path possible to these pins. AGND C3 Analog ground. This is the signal ground reference for the IC. All voltage levels are measured with respect to this pin; connect to PGND at a single point. The AGND pin should be flooded over by the ground plane that is connecting the PGND pins to both the input caps and the output caps.

## 7. Functional description



The step-up converter (Figure 4) generates a regulated constant output voltage.

### 7.1 Enable (EN) pin

EN pin enables the boost converter when HIGH. However the effect of the EN when LOW has two methods of operation, depending on which device is used.

PCA9412 device: the EN pin when LOW causes the part to go into a total disconnect mode from input to output.

PCA9412A device: EN pin when LOW forces the part into Pass Through mode where the output voltage is the same as the input voltage. This device emulates a conventional boost converter (without the voltage drop of the internal diode).

When the EN pin is pulled HIGH it should be held HIGH for at least 500  $\mu$ s for the device to properly initialize. This is for getting the forced Pass Through mode set up properly. Shorter pulses may cause unpredictable behavior.

Table 4. Operating modes					
Mode	Description	Invoked when			
LIN	linear start-up	V <sub>IN</sub> > V <sub>OUT</sub>			
SS	boost soft-start	V <sub>IN</sub> < V <sub>OUT</sub> < V <sub>OUT</sub> (target)			
BST	boost operating mode	$V_{OUT} = V_{OUT(TARGET)}$			
PT	pass-through mode	$V_{IN} > V_{OUT(TARGET)}$ or in the advanced part when EN is pulled LOW			

### 7.1.1 Pass-Through (PT) mode

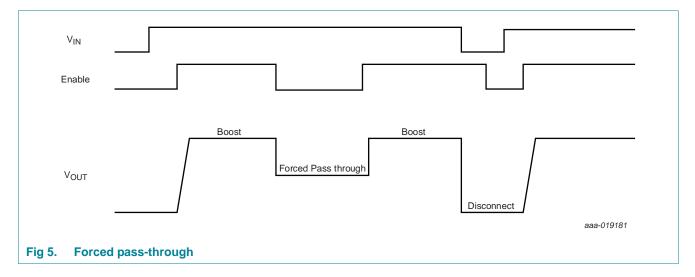
With both devices, the device automatically transitions from Boost Mode to Pass-Through Mode if  $V_{IN}$  goes above the  $V_{OUT}$  target. In Pass-Through Mode, the device provides a very low impedance path from  $V_{IN}$  to  $V_{OUT}$ . Entry to the Pass-Through Mode is triggered

by condition where  $V_{IN} > V_{OUT}$  target. Pass-Through Mode exit is triggered when  $V_{OUT}$  going down reaches the target  $V_{OUT}$  voltage. During Automatic Pass-Through Mode, the PMOS overcurrent protection remains enabled.

In the PCA9412A, user can force the device in Forced Pass-Through Mode through the EN pin. If the EN pin is pulled HIGH, the device starts operating in Boost Mode. Once the EN pin is pulled LOW, the device is forced into Pass-Through Mode. To disable the device, the input supply voltage must be removed. The device cannot start-up in Forced Pass-Through Mode. During start-up, keep the EN pulled HIGH for 500  $\mu$ s, before pulling it LOW and putting the device into Forced Pass-Through Mode. The EN pin has an internal pull-down resistor (see Figure 5 for the sequence).

#### Table 5.Enable

EN logic level	Description Non-A	Description A
LOW	Power-down isolated output	Forced pass-through
HIGH	Boost mode	Boost mode



### 7.2 Inrush current limiter (soft start)

The PCA9412 and PCA9412A have an integrated pre-charge circuit that prevents large inrush currents when input voltage is applied. This inrush is accompanied with a current limit that shuts down the device, and runs a delay timer then attempts a restart.

Once the output voltage reaches the input voltage the soft start function is enabled to limit the maximum current in boost time and to reduce an input voltage dip. Therefore the system has a turn-on procedure which starts up step-by-step and limits the inrush current via a duty cycle control up to the maximum current capability.

### 7.3 Thermal protection

The PCA9412 and PCA9412A have an integrated thermal protection. The protection circuit senses the internal temperature of the chip and switches off the integrated PMOS power switch transistor when temperature reaches 150 °C. After the temperature returns to a safe value 20 °C below the shutdown temperature, the system restarts in the pre-charge phase.

### 7.4 Overcurrent protection

Overcurrent protection circuit senses the current through the integrated PMOS. If the diagnostic circuit detects an overcurrent, the system switches off the PMOS and NMOS to break the current flow, and a 20 ms timeout is started. Once the 20 ms timeout expires, the part restarts in the pre-charge phase.

### 8. Limiting values

#### Table 6. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>IN</sub>	voltage on pin IN		-0.5	+6.0	V
Vi	input voltage	on pin EN	-0.3	V <sub>IN</sub> + 0.3 V, up to +6.0 V	V
Vo	output voltage	on pins SW, OUT	-0.5	+6.0	V
P <sub>tot</sub>	total power dissipation	[1]			
T <sub>stg</sub>	storage temperature		-65	+150	°C
Tj	junction temperature		-40	+125	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
V <sub>ESD</sub>	electrostatic discharge voltage	human body model (JESD22-001)	-2	+2	kV

[1] Internally limited

## 9. Recommended operating conditions

#### Table 7.Operating conditions

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V <sub>IN</sub>	voltage on pin IN			2.5	-	5.25	V
Vi	input voltage	on pin EN		-0.3	-	V <sub>IN</sub>	V
C <sub>1</sub>	external input capacitance	V <sub>IN</sub> = 4.8 V	[1]	2.0	4.2	-	μF
C <sub>2</sub>	external output capacitance	V <sub>O</sub> = 5.4 V	[1]	3.0	4.2	10	μF
L <sub>i(ext)</sub>	external input inductance		[1]	0.47	1	2.2	μH

[1] This is the capacitance at 5.25 V bias. Check application section for more details.

## **10. Static characteristics**

#### Table 8. Static characteristics

At recommended input voltages and  $T_{amb} = -40$  °C to +85 °C; voltages are referenced to GND (ground = 0 V); unless otherwise specified.

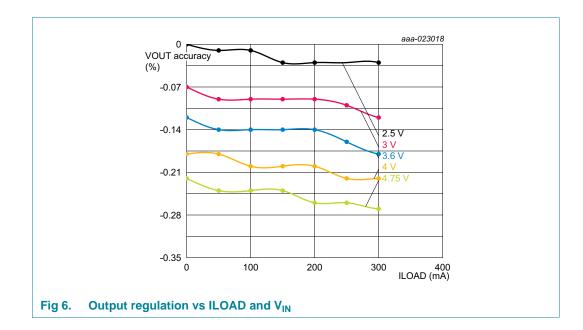
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Input voltage a	and input current	1		I		
V <sub>IN</sub>	input voltage		2.5	3.6	5.25	V
l <sub>Q</sub>	supply current	EN = 0 V	-	3.0	10.0	μA
		EN = 1.8 V, V <sub>IN</sub> = 2.5 V	-	36	-	mA
		EN = 1.8 V, V <sub>IN</sub> = 4.8 V	-	11	-	mA
		EN = 1.8 V, V <sub>IN</sub> = 5.25 V	-	3.57	-	mA
Output voltage	and output current	1				
V <sub>OUT</sub>	output voltage	$I_O \ge 15 \text{ mA}$	5.24	5.4	5.56	V
I <sub>OUT(lim)</sub>	output current limit	EN = HIGH[1], V <sub>IN</sub> = 2.5 V to 5.25 V	300	-	-	mA
f <sub>o(boost)</sub>	boost output frequency		2.91	3	3.09	MHz
V <sub>th(r)(UVLO)</sub>	rising threshold voltage on V <sub>IN</sub> UVLO		1.9	2.1	2.3	V
V <sub>th(f)(UVLOhyst)</sub>	falling UVLO hysteresis		70	-	120	mV
V <sub>o(noise_p-p_coh)</sub>	V <sub>o</sub> coherent	100 kHz to 1.5 MHz, $V_{IN}$ < 4.8 V			2	mV
	peak-to-peak noise	12 MHz to 15 MHz, $V_{IN}$ < 4.8 V			2	mV
V <sub>o(noise_rms)</sub>	Vo rms noise (incoherent	100 kHz to 1.5 MHz, $V_{IN}$ < 4.8 V			660	μV rms
	noise)	12 MHz to 15 MHz, V <sub>IN</sub> < 4.8 V			660	μV rms
Control input a	and timing			i		
VIH	HIGH-level input voltage	pins EN	1.16	-	-	V
VIL	LOW-level input voltage	pins EN	-	-	0.4	V
t <sub>startup</sub>	start-up time		-	500	600	μS
Over-temperat	ure protection	1				
T <sub>sd</sub>	shutdown temperature		-	150	-	°C
T <sub>sd(hys)</sub>	hysteresis of shutdown temperature		-	20	-	°C

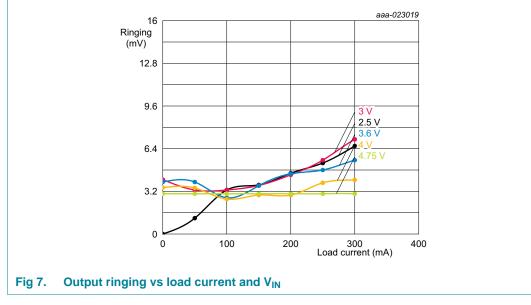
#### Table 8. Static characteristics ... continued

At recommended input voltages and  $T_{amb} = -40$  °C to +85 °C; voltages are referenced to GND (ground = 0 V); unless otherwise specified.

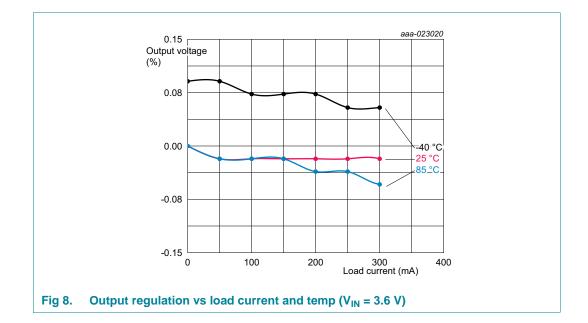
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Switches		1				
R <sub>DSon</sub>	drain-source on-state	N-channel FET	-	70	-	mΩ
resistance	P-channel FET	-	80	-	mΩ	
IL	leakage current	V <sub>IN</sub> = 3.6 V; EN = LOW	0	0.051	10	μA
R <sub>pd(en_low)</sub>	enable pull down	EN = LOW	450	640	800	kΩ
I(ena-pulldown)	enable pull down current	EN = HIGH, VIN ≥ 2.5 V	-	100	-	nA

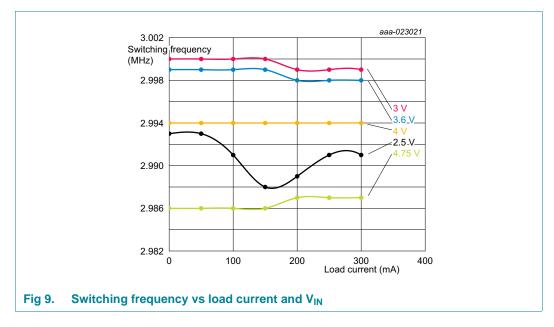
[1] EN = HIGH is a common condition for the listed voltage and current cases.

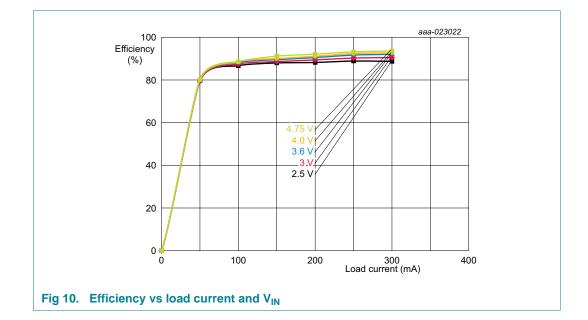


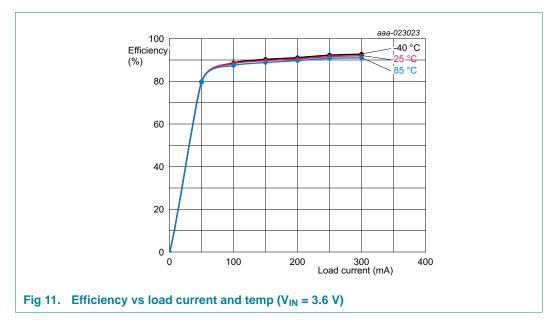


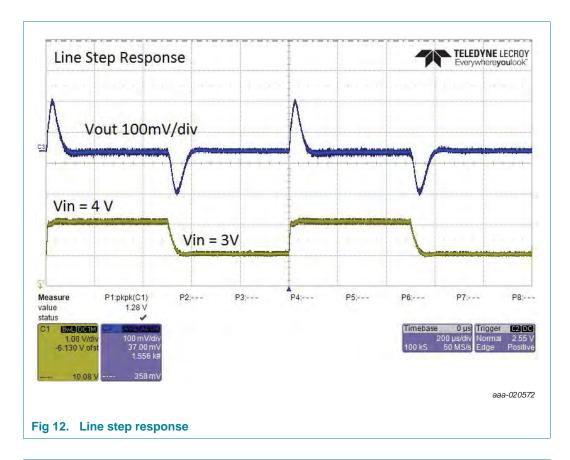
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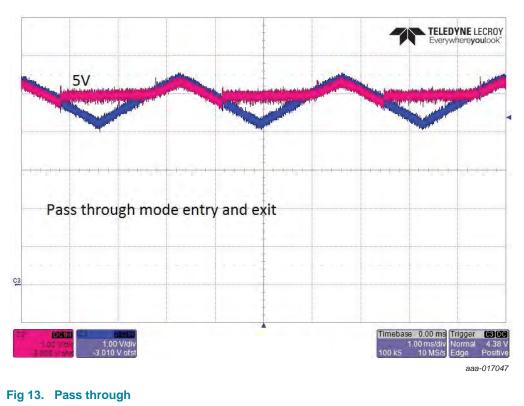


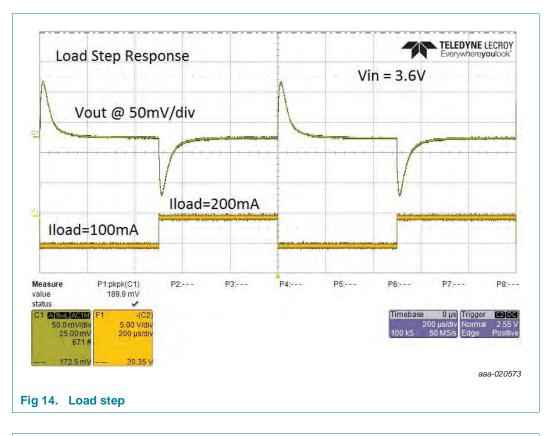


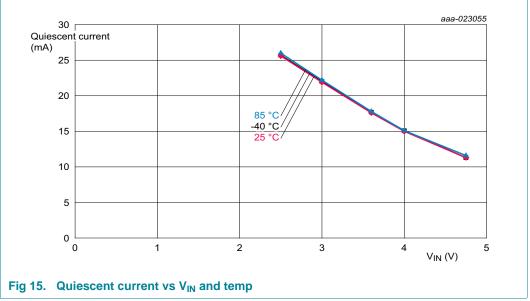












### **11. Application information**

### **11.1 Overcurrent protection**

Conventional Boost convertors have no output current limit protection. Additionally they have a phantom power path made up of the inductor and output diode connecting the input directly to the output; this causes an inrush of current when power is applied. The PCA9412 has extra provisions to prevent the inrush current and output current limit problems.

To implement these protections this device has a start-up state machine. This machine includes a two-stage pre-charge of the output circuitry:

- Stage 1, Inrush control: a 1 A current source is turned on providing a path from input to output while a voltage comparator and a timer1 are active. If the output voltage doesn't reach V<sub>IN</sub> - 200 mV within 1 ms, the device goes into the fault state. If the output voltage reaches 200 mV below the input voltage first the state machine advances to the boost mode soft start state.
- Stage 2, Boost Soft-Start: Starting from V<sub>OUT</sub> = V<sub>IN</sub>, the output will ramp up to V<sub>OUT</sub> target. The PMOS current limit will be enabled during this stage.

The current levels are implemented through the synchronous rectifier transistor properties and drive states.

### 11.2 Thermal shutdown

A thermal shutdown state shuts out all other states out until the device has cooled to the (HiTemp – Thysteresis) turn back on temperature, and then it enters the fault state.

### 11.3 Fault recovery

When a fault occurs, the device has a fault state that disables the output for 20 ms. After the 20 ms timeout, the device will attempt a restart starting from the inrush state.

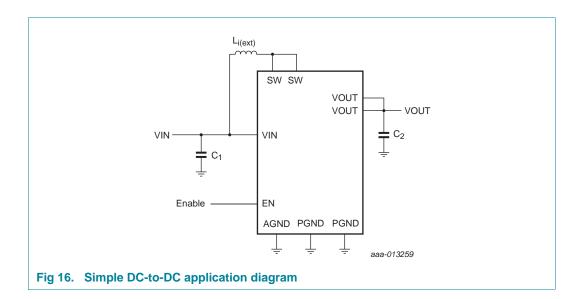
#### 11.4 Enable delay

Once the device has been running and gets disabled, it cannot be re-enabled until the output voltage discharges down to the input voltage. The device has an internal pull-down to accomplish this, however in the absence of any external load this will take 3 ms. Any external load will shorten the time it takes to get re-enabled.

### 11.5 Connection diagram

The DC-to-DC converter requires an external inductor and two decoupling capacitors.

#### 3.0 MHz, 300 mA, DC-to-DC boost converter



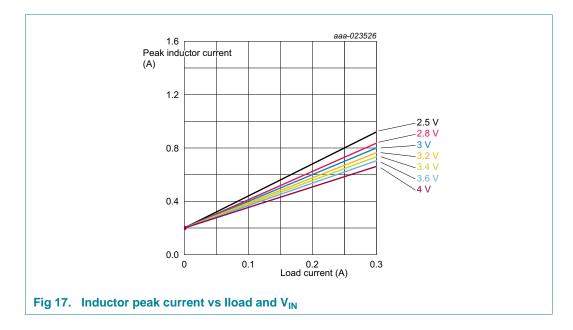
### **11.6 Recommended inductors**

In order to ensure proper operation of the step-up DC-to-DC converter an inductor with a sufficient inductance and sufficient saturation current value needs to be used. Recommended inductance is 1  $\mu$ H. Using this recommended 0603 inductor puts a 300 mA current limit on the circuit; this inductor has a 800 mA saturation current. For more output current a larger, higher saturation current inductor will be required according to Figure 17. The saturation current of the inductor has to be properly chosen for the input voltage and load current range. The lower the input voltage the higher the input current for a given load current. Once the saturation current of the inductor is reached, the ferromagnetic core of the inductor will show a rapid nonlinear behavior and the output current capability of the circuit will drop significantly.

#### Table 9. Recommended inductors

Inductor	Manufacturer	Product	Parameter	Package size
L	Abracon	ASMPH-0603-1R0M-T	1 μΗ	0603

#### 3.0 MHz, 300 mA, DC-to-DC boost converter



### **11.7** Input capacitor

To eliminate unwanted voltage transients at the input, place an input decoupling capacitor of at least 2.2  $\mu$ F as close as possible to the input pin. Due to the voltage dependence of the capacitor, care should be taken that the effective capacitance of 2  $\mu$ F is available at input voltages up to 5.25 V. To ensure best performance, it is recommended to use a capacitor with a low Equivalent Series Resistance (ESR). When using a capacitor with X5R or X7R dielectric keep in mind that the capacitance drops significantly with voltage, thus a 22  $\mu$ F cap will actually only have 3.5  $\mu$ F at 5.4 V as shown in Table 10.

Table 10.	Recommended	input	capacitors
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Manufacturer	Product	Parameter	Package size
Samsung	CL05A106MQ5NUNC	10 μf 6.3 V, 2.2 μF at 5.4 V	0402
TDK	C1608X5R0J226M080AC	22 μf at 6.3 V, 3.5 μF at 5.4 V	0603

### **11.8 Output capacitor**

Because of the narrow voltage-dependent capacitance spread, high temperature stability and low ESR at high frequencies, it is recommended to use the dielectric X7R or X5R. The rated capacitance of the output capacitor will be much greater than the actual capacitance at the 5.4 V output voltage. The device requires at least 3  $\mu$ F of output capacitance at its rated output voltage for suppression of ringing, overshoot, as well as for loop stability. We recommend a 22  $\mu$ F 6.3 V capacitor that is actually a 3.5  $\mu$ F capacitor when biased at 5.4 V.

#### Table 11. Recommended output capacitors

Сар	Manufacturer	Product	Parameter	Package size
C <sub>2</sub>	TDK	C1608X5R0J226M080AC	22 μF 6.3 V, 3.5 μF at 5.4 V	0603

When the space on the application board allows, it is recommended to use two capacitors instead of a single large value. The reason is that the equivalent series inductance reduces to half when using two capacitors with the same value and this helps the capacitors to work more efficiently against high frequency noise where it can be reduced by a factor of 2. The minimum capacitance needed can either be obtained with a single 22  $\mu$ F capacitor or two 10  $\mu$ F capacitors when the space allows and lower noise is targeted; keep in mind that the bulk capacitance at the output voltage needs to be greater than 3.0  $\mu$ F for control loop stability, and two large capacitors will have superior performance when compared with two smaller capacitors. The boost factor, output current, switching frequency and the desired peak to peak ripple limit define the minimum capacitance needed.

The duty cycle (D) needed with 90 % efficiency at a worst case of 2.5 V  $V_{IN}$ .

$$D = I - \frac{Eff \times V_{IN}}{V_{OUT}}$$
(1)

For the minimum input voltage 2.5 V and 5.4 V output voltage  $\rightarrow$  D = 0.58

Using the simplified correlation between the current  $(I_{OUT(max)})$ , ripple  $(V_{ripple})$ , duty cycle (D) and switching frequency  $(f_{sw})$  the minimum  $C_{out}$  capacitance can be calculated as follows:

$$C_{OUT(min)} = I_{OUT(max)} \times \frac{D}{f_{sw} \times V_{ripple}}$$
(2)

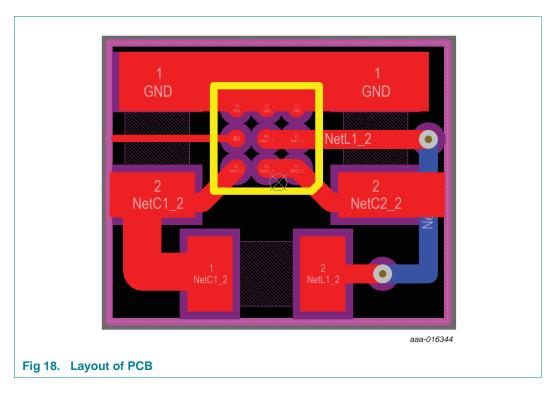
With a sample set of values:  $I_{out}$  = 300 mA, D = 0.58,  $f_{sw}$  = 3 MHz,  $V_{ripple}$  = 20 mV

 $C_{OUT(min)} = 2.87 \ \mu F$  (This is not the nominal value at 0 V bias, it is the derated value at 5.4 V bias).

This value presumes that the ESR and ESL of the capacitor is negligible and the path output-capacitor-ground is as short as possible. Compensating for the listed factors, the minimum output capacitance is specified at 3.0  $\mu$ f at 5.4 V. How much the capacitance degrades at high bias voltage is supplier dependent and especially when 0402 size capacitors are chosen the voltage dependence should be taken into consideration.

### 11.9 Layout of the PCB

The most critical layout constraint of this circuit is that the output Cap C2 be placed as close to the IC as possible. Use short wide traces to connect this capacitor to the IC. See below for an example of the layout detailing the IC and the output capacitor. The connection from switch pin to the inductor should have minimum capacitance to GND.



### 11.10 The effect of having more voltage

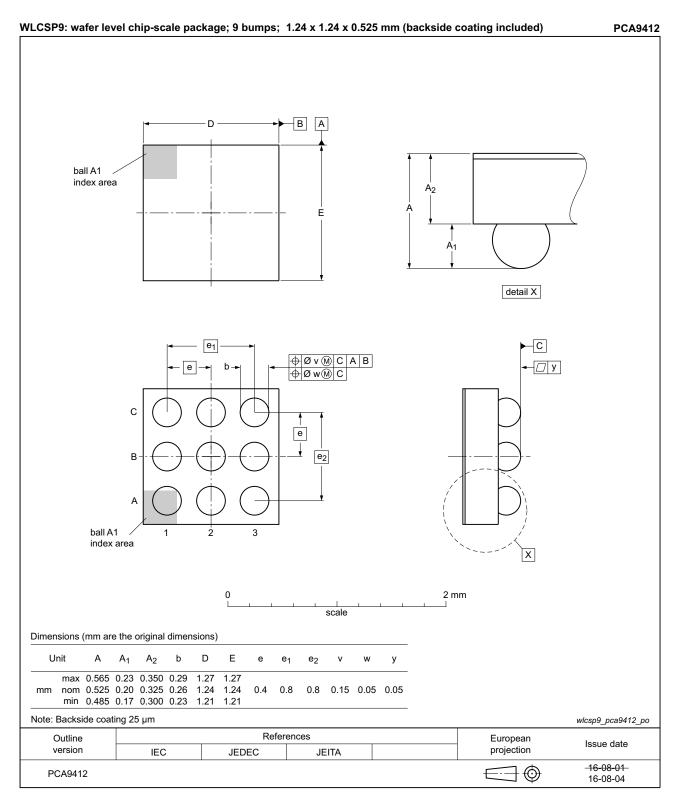
When applying a voltage to the NFC transmitter the signal strength is proportional to the voltage applied.

By using this boost converter the antenna size can be reduced for the same signal strength, or the signal can be increased for the same antenna.

For a 5.4 V output the signal strength is increased to 150 % of the 3.6 V signal strength or the antenna can be made 67 % of the size required by 3.6 V input voltage.

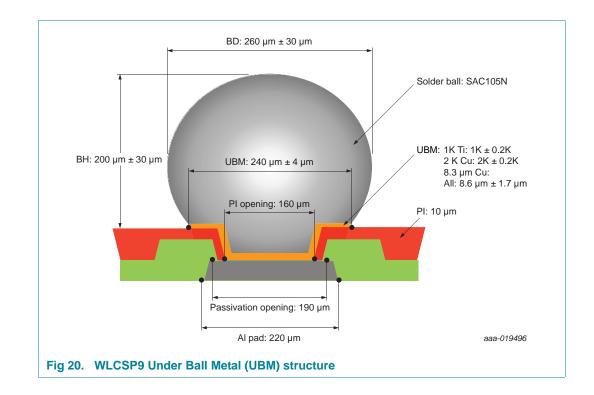
#### 3.0 MHz, 300 mA, DC-to-DC boost converter

### 12. Package outline



#### Fig 19. Package outline WLCSP9

PCA9412



### **13. Soldering of WLCSP packages**

### 13.1 Introduction to soldering WLCSP packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering WLCSP (Wafer Level Chip-Size Packages) can be found in application note *AN10439 "Wafer Level Chip Scale Package"* and in application note *AN10365 "Surface mount reflow soldering description"*.

Wave soldering is not suitable for this package.

All NXP WLCSP packages are lead-free.

### 13.2 Board mounting

Board mounting of a WLCSP requires several steps:

- 1. Solder paste printing on the PCB
- 2. Component placement with a pick and place machine
- 3. The reflow soldering itself

### 13.3 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 21</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues, such as smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature), and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic) while being low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with <u>Table 12</u>.

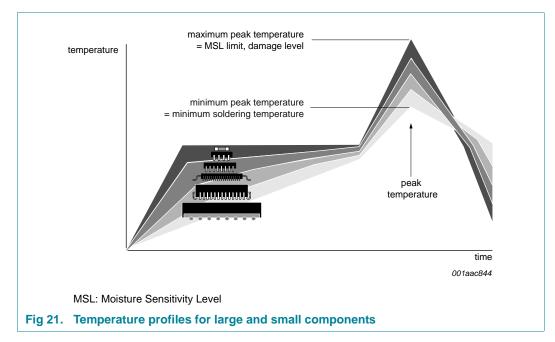
#### Table 12. Lead-free process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C) Volume (mm <sup>3</sup> )			
	< 350	350 to 2000	> 2000	
< 1.6	260	260	260	
1.6 to 2.5	260	250	245	
> 2.5	250	245	245	

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 21.

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For further information on temperature profiles, refer to application note *AN10365* "Surface mount reflow soldering description".

#### 13.3.1 Stand off

The stand off between the substrate and the chip is determined by:

- The amount of printed solder on the substrate
- The size of the solder land on the substrate
- The bump height on the chip

The higher the stand off, the better the stresses are released due to TEC (Thermal Expansion Coefficient) differences between substrate and chip.

#### 13.3.2 Quality of solder joint

A flip-chip joint is considered to be a good joint when the entire solder land has been wetted by the solder from the bump. The surface of the joint should be smooth and the shape symmetrical. The soldered joints on a chip should be uniform. Voids in the bumps after reflow can occur during the reflow process in bumps with high ratio of bump diameter to bump height, i.e. low bumps with large diameter. No failures have been found to be related to these voids. Solder joint inspection after reflow can be done with X-ray to monitor defects such as bridging, open circuits and voids.

#### 13.3.3 Rework

In general, rework is not recommended. By rework we mean the process of removing the chip from the substrate and replacing it with a new chip. If a chip is removed from the substrate, most solder balls of the chip will be damaged. In that case it is recommended not to re-use the chip again.

Device removal can be done when the substrate is heated until it is certain that all solder joints are molten. The chip can then be carefully removed from the substrate without damaging the tracks and solder lands on the substrate. Removing the device must be done using plastic tweezers, because metal tweezers can damage the silicon. The surface of the substrate should be carefully cleaned and all solder and flux residues and/or underfill removed. When a new chip is placed on the substrate, use the flux process instead of solder on the solder lands. Apply flux on the bumps at the chip side as well as on the solder pads on the substrate. Place and align the new chip while viewing with a microscope. To reflow the solder, use the solder profile shown in application note *AN10365 "Surface mount reflow soldering description"*.

#### 13.3.4 Cleaning

Cleaning can be done after reflow soldering.

### 14. References

- [1] **IEC60134** Rating systems for electronic tubes and valves and analogous semiconductor devices
- [2] IEC61340-3-1 Method for simulation of electrostatic effects Human body model (HBM) electrostatic discharge test waveforms
- [3] JESD22-A115C Electrostatic Discharge (ESD) Sensitivity Testing Machine Model (MM)
- [4] NX2-00001 NXP Semiconductors Quality and Reliability Specification
- [5] AN10365 NXP Semiconductors application note "Surface mount reflow soldering description"

## 15. Revision history

### Table 13. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
PCA9412 v.1	20170609	Product data sheet	-	-

**Product data sheet** 

## **16. Legal information**

### 16.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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[2] The term 'short data sheet' is explained in section "Definitions".

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3.0 MHz, 300 mA, DC-to-DC boost converter

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