

TEA2017ABT/2

Digital configurable LLC and DCM/QR PFC controller

Rev. 1.1 — 17 May 2023 Product data sheet

1 General description

The TEA2017ABT is a digital configurable LLC and PFC combo controller for highefficiency resonant power supplies. It includes the LLC controller and a PFC controller that works in DCM/QR mode. The TEA2017ABT enables building a complete resonant power supply which is easy to design and has a very low component count. The TEA2017ABT comes in a low profile and narrow body-width SO16 package.

The TEA2017ABT digital architecture is based on a high-speed configurable hardware state machine ensuring very reliable real-time performance. During the power supply development, many operation and protection settings of the LLC and PFC controller can be adjusted by loading new settings into the device to meet specific application requirements. The configurations can be fully secured to prevent unauthorized copying of the proprietary TEA2017ABT configuration content.

In contrast to traditional resonant topologies, the TEA2017ABT shows a very high efficiency at low loads due to the LLC low-power mode. This mode operates in the power region between continuous switching (also called high-power mode) and burst mode.

Because the TEA2017ABT regulates the LLC output voltage of the system via the primary capacitor voltage, it has accurate information about the power delivered to the output. This measured output power defines the mode of operation (burst mode, lowpower mode, or high-power mode). The transition levels of the operating modes can be easily programmed into the device.

The TEA2017ABT contains all protections like overtemperature protection (OTP), overcurrent protection (OCP), overvoltage protection (OVP), overpower protection (OPP), open-loop protection (OLP), and capacitive mode regulation (CMR). Each of these protections can be configured independently and accurately by programming parameters inside the device.

The device contains a low-voltage and a high-voltage silicon technology for high-voltage start-up, integrated drivers, level shifter, protections, and circuitry assuring zero-voltage switching.

The TEA2017ABT/TEA2095T combination gives an easy to design, highly efficient, and reliable power supply, providing 90 W to 500 W, with a minimum of external components. The system provides a very low no-load input power (< 75 mW; total system including the TEA2017ABT/TEA2095T combination) and high efficiency from minimum to maximum load. This power supply meets the efficiency regulations of Energy Star, the Department of Energy, the Eco-design directive of the European Union, the European Code of Conduct, and other guidelines. So, any auxiliary low-power supply can be omitted.

To enhance readability, only typical values are given in this document, except in the parametric tables (Section 9, Section 10, and Section 11). If values in the text differ from the values for the same parameter in the parametric tables, the values in these tables are leading.

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2 Features and benefits

2.1 Distinctive features

- **•** Complete functionality of a PFC and LLC controller in a single small-size SO16 package
- **•** Integrated high-voltage start-up
- **•** Integrated drivers and high-voltage level shifter (LS)
- **•** High-side driver directly supplied from the low-side driver output
- **•** Accurate boost voltage regulation
- **•** PFC that works in DCM/QR mode
- **•** Integrated X-capacitor discharge without additional external components
- **•** Power good function
- **•** PFC jitter for optimized EMI performance
- **•** Excellent power factor (PF) and total harmonic distortion (THD), as the PFC current compensates for the input filter current
- **•** Several parameters can easily be configured during evaluation with use of the graphical user interface (GUI), like:
	- **–** Operating frequencies to be outside the audible area at all operating modes
	- **–** Soft start and soft stop in burst mode, reducing the audible noise
	- **–** Accurate transition levels between operation modes (high-power mode/low-power mode/burst mode)
	- **–** Enabling/disabling the lower power mode
- **•** Can easily be combined with an external standby supply

2.2 Green features

- **•** Valley/zero voltage switching for minimum switching losses
- **•** Extremely high efficiency from low load to high load
- **•** Compliant with latest energy-saving standards and directives (Energy Star, EuP)
- **•** Excellent no-load input power (< 75 mW for TEA2017ABT/TEA2095T combination)

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2.3 Protection features

- **•** Independently configurable levels and timers
- **•** Many protections can independently be set to latched, safe restart, or latched after several attempts to restart
- **•** Supply undervoltage protection (UVP)
- **•** Overpower protection (OPP)
- **•** Internal and external overtemperature protection (OTP)
- **•** Capacitive mode regulation (CMR)
- **•** Accurate overvoltage protection (OVP)
- **•** Overcurrent protection (OCP)
- **•** Inrush current protection (ICP)
- **•** Brownin/brownout protection
- **•** Disable input
- **•** Input to reset all protections

3 Applications

- **•** Desktop and all-in-one PCs
- **•** Gaming power supplies
- **•** LCD television
- **•** Notebook adapters and general-purpose adapters
- **•** Printers

4 Ordering information

Table 1. Ordering information

5 Marking

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6 Block diagram

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7 Pinning information

7.1 Pinning

7.2 Pin description

Table 3. Pin description

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8 Functional description

8.1 Supply voltages

The TEA2017ABT includes:

- **•** A high-voltage supply pin for start-up (DRAINPFC)
- **•** A general supply to be connected to an external auxiliary winding (SUPIC pin)
- **•** A floating supply for the high-side driver (SUPHS pin)

8.1.1 Start-up and supply voltage

Initially, the capacitor on the SUPIC pin is charged via the DRAINPFC pin. The DRAINPFC pin is connected to the drain voltage of the PFC MOSFET. Internally, a high-voltage current source is located between the DRAINPFC pin and the SUPIC pin (see Figure 3).

The maximum current of the internal current source is limited to $I_{ch(SUPIC)}$. To limit the IC dissipation, the charge current is reduced when the current source exceeds its maximum temperature.

At start-up, when the SUPIC reaches the $V_{\text{start(SUP|C)}}$ level, it is continuously regulated to this start level with a hysteresis $(V_{start(hys)SUPIC})$.

When the start level is reached, it reads the internal MTP (multi-time programmable memory) and defines the settings.

When the settings have been defined, the PFC starts up. When the SNSBOOST reaches the minimum level $V_{\text{start(SNSBOOST)}}$, the LLC also starts switching (see Figure 4 and Figure 5).

When start-up is complete and the LLC controller is operating, the LLC transformer auxiliary winding supplies the SUPIC pin. In this operational state, the HV start-up source is disabled.

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When the system enters the protection mode, it cannot be supplied via the auxiliary winding. So, the SUPIC pin is regulated to $V_{start(SUPIC)}$ via the DRAINPFC pin.

During the non-switching period of the burst mode, the SUPIC is regulated to the V_{low(SUPIC}) when SUPIC drops to below this level. It regulates the voltage with a hysteresis of $V_{\text{low(hys)SUPIC}}$. In this way, the system avoids that the SUPIC undervoltage protection ($V_{\text{uvp}(S\cup PIC)}$) is triggered because of a long non-switching period in burst mode. However, the system must be designed such that the internal current source at the DRAINPFC pin is only active at start-up and extreme output voltage overshoots, followed by a long time of non-switching. Continuous use of this current source increases the input power and affects the lifetime of the product. The DRAINPFC pin is also used for valley detection, for X-capacitor discharge, and for providing a second PFC OVP protection.

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When the SUPIC voltage drops to below $V_{rst(SUPIC)}$, the TEA2017ABT restarts.

To ensure that the internal current source can start up the system and supply the controller during the non-switching period in burst-mode, it is advised that only a capacitive load is connected to the SUPIC in the application.

8.1.2 High-side driver floating supply (SUPHS pin)

As the voltage range on the SUPIC pin exceeds that of the maximum external MOSFETs gate-source voltage, the external bootstrap capacitor C_{SUPHS} cannot directly be supplied from the SUPIC.

To provide an external supply for the high-side driver without the need of additional external components, the GateLS output is designed such that it can drive the lowside MOSFET and supply the high-side MOSFET (patent number US20180234015; see Figure 6).

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The external bootstrap buffer capacitor C_{SUPHS} supplies the high-side driver. The bootstrap capacitor is connected to the low-side driver supply, the GATELS pin, and the half-bridge node (HB) via an external diode (D_{SUPHS}). When GATELS is active high and the HB node is pulled low, C_{SUPHS} is charged.

Careful selection of the appropriate diode minimizes the voltage drop between the GATELS and SUPHS pins, especially when large MOSFETs and high switching frequencies are used. A great voltage drop across the diode reduces the gate drive of the high-side MOSFET.

8.2 LLC system regulation

The TEA2017ABT regulates the output power by adjusting the voltage across the primary capacitor. Compared to a standard frequency control loop, it has the advantage that the control loop has a constant gain and the IC has information about the output power. So, the operation mode transition levels are derived from the output power.

Although the TEA2017ABT uses the primary capacitor voltage as a regulation parameter, all application values, like the resonant inductances, resonant capacitor, and primary MOSFETs remain unchanged compared to a frequency-controlled LLC converter. A secondary TL431 circuitry with an optocoupler connected to the primary SNSFB pin continuously regulates the output voltage.

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8.2.1 Output power regulation loop

Figure 7 shows the output power regulation loop of V_{cap} control as used by the TEA2017ABT. Figure 8 shows a corresponding timing diagram.

When the divided resonant capacitor voltage (V_{SNSCAP}) exceeds the capacitor voltage high level ($V_{hs(SNSCAP)}$), the high-side MOSFET is switched off (see Figure 8 (t1)). After a short delay, the low-side MOSFET is switched on. Because of the resonant current, the resonant capacitor voltage initially increases further but eventually drops.

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When the divided capacitor voltage (V_{SNSCAP}) drops to below the capacitor voltage low level $(V_{ls(SNSCAP)})$, the low-side MOSFET is switched off (see Figure 8 (t2)). After a short delay, the high-side MOSFET is switched on. Figure 8 shows that the switching frequency is a result of this switching behavior. In a frequency-controlled system, the frequency is a control parameter and the output power is a result. The TEA2017ABT regulates the power and the frequency is a result.

The difference between the high and low capacitor voltage level is a measure of the delivered output power. The value of the primary optocurrent, defined by the secondary TL431 circuitry, determines the difference between the high and low capacitor voltages.

Figure 8 also shows the behavior at a transient. If the output load increases, the current pulled out of the SNSFB pin decreases. The result is that the TEA2017ABT increases the high-level capacitor voltage and lowers the low-level capacitor voltage. The output power increases and eventually the output voltage increases to its regulation level.

To minimize no-load input power of the system, the primary current into the optocoupler is continuously regulated to $I_{\text{req}(\text{SNSFB})}$ (see Section 8.4).

8.2.2 Output voltage start-up

At start-up, when the system slowly increases the ΔV_{SNSCAP} , it continuously monitors the primary current via the SNSCURLLC pin. When the voltage at this pin exceeds the $V_{\text{imtr(ocp)}}$ level, increasing the ΔV_{SNSCAP} is on hold until the voltage at the SNSCURLLC pin drops to below the $V_{\text{imtr}(\text{ocp})}$ level again (see Figure 9). The output current is regulated and its voltage shows a nice ramp during start-up. It also avoids that during startup the OCP (overcurrent protection) is triggered. In this way, the LLC converter behaves like a limited current source during start-up.

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8.3 Modes of operation

Figure 10 shows the control curve between the output power and the voltage difference between the high and low capacitor voltage levels.

When the output power (P_{out}) is at its maximum, the low capacitor voltage level $(V_{ls(SNSCAP)})$ is at its minimum, and the high capacitor voltage $(V_{hs(SNSCAP)})$ is at its maximum level. The maximum ΔV_{SNSCAP} ($V_{hs(SNSCAP)}$ – $V_{ls(SNSCAP)}$), which is the divided ΔV_{Cr} voltage, corresponds to the maximum output power.

When the output load decreases, the ΔV_{SNSCAP} voltage decreases. As a result, the output power decreases and the output voltage is regulated. This mode is called highpower mode. Figure 8 shows a timing diagram of the system operating in high-power mode.

When the output power drops to below the transition level $(P_{t(lp)})$, the system enters the low-power mode. The $P_{t(1p)}$ level can be initialized via the MTP.

To compensate for the non-switching period in low-power mode, also called hold period, ΔVSNSCAP is initially increased at entering the low-power mode (see Section 8.3.2). In low-power mode, the output power is regulated by adapting ΔV_{SNSCAP} , until it reaches a minimum. The system then enters the burst mode (see Section 8.3.3).

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8.3.1 High-power mode

In high-power mode, the system operates as described in **Section 8.2.1. Figure 11** shows a flow diagram of the high-power mode.

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Initially, GATELS is on and GATEHS is off. The external bootstrap buffer capacitor (C_{SUPHS}) is charged via the GATELS pin and an external diode. The system remains in this state for at least the minimum on-time $(t_{on(min)})$ of GATELS. Before entering the next state, one of the following conditions must be fulfilled:

- The V_{SNSCAP} voltage drops to below the minimum V_{SNSCAP} voltage (V_{Is(SNSCAP)})
- The measured current exceeds the OCP level (see Section 8.6.15)
- The system is close to capacitive mode (see **Section 8.6.14)**
- The maximum on-time $(t_{on(max)})$, a protection that maximizes the time the high-side or low-side MOSFET is kept on, is exceeded.

To avoid false detection of the HB peak voltage, the system remains in this state until the minimum non-overlap time $(t_{no(min)})$ is exceeded. When this time is exceeded and it detects the peak of the HB node and the measured resonant current is negative (or zero), it enters the next state.

If the system does not detect a peak at the HB node, it also enters the next state when the maximum non-overlap time $(t_{no(max)})$ is exceeded under the condition of a negative (or zero) resonant current.

Finally, the third and fourth states (see Figure 11) describe the GATEHS and GATEHS to GATELS transition criteria which are the inverse of the first two states.

8.3.2 Low-power mode

At low loads, the efficiency of a resonant converter drops as the magnetization and the switching losses become dominant. A low-power mode ensures high efficiency at lower loads because it reduces the magnetization and switching losses.

When the output power drops to below the $P_{t(1p)}$ level, the system enters the low-power mode (see **Figure 10** and **Figure 12**). It continues switching for 3 half-cycles (low-side, high-side, low-side) with an MTP selectable duty cycle. To ensure a constant output power level, it increases the energy per cycle ($V_{hs(SNSCAP)} - V_{ls(SNSCAP)}$) at the same time.

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As the system continuously tracks the primary capacitor voltage, it knows exactly when to enter the "hold" period. It can also continue again at exactly the correct voltage and current levels of the resonant converter. In this way, a "hold" period can be introduced which reduces the magnetization and switching losses without any additional losses. The currents I_{D1} and I_{D2} (see Figure 12) are the secondary currents through diodes D1 and D2 (see Figure 7).

When in low-power mode the output power is further reduced, the amount of energy per cycle (= ΔV_{SNSCAP}) is reduced and the duty cycle remains the same (see Figure 13).

When in low-power mode the system reaches the programmable minimum energy per cycle (= ΔV_{SNSCAP}), it enters burst mode.

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8.3.3 Burst mode

In burst mode, the system alternates between operating in low-power mode and an extended hold state (see Figure 14). Because of this additional extended hold period, the magnetization and switching losses are further reduced. So, the efficiency of the system is increased.

Figure 14 shows that all operating frequencies are outside the audible area. The minimum low-power frequency can be set with a parameter. Within a low-power period, the system is switching at the resonant frequency of the converter, which is typically between 50 kHz and 200 kHz. The burst frequency $(1/T_{burst})$ can be programmed out side the audible noise area.

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8.3.3.1 Frequency regulation

When the primary optocurrent (I_{SNSFB}) drops to below $I_{\text{start(burst)}}$ (100 µA typical), a new burst-on period is started. The end of the burst-on period depends on the calculated number of low-power cycles. The number of low-power cycles within a burst-on period is continuously adjusted so that the total burst period (T_{burst}) is at least the period defined by the setting (see Figure 15).

The system continuously measures the burst period from the start of the previous burston period to a new burst-on period. At t1, the measured burst period (T_{burst}) equals the required T_{burst} . So, the next number of low-power cycles equals the number of previous low-power cycles. At a constant output power, the system expects that when the next burst-on period has the same number of low-power cycles as the previous burst-on period, the burst period (T_{burst}) remains constant.

At a positive transient (t2), a new low-power cycle is started immediately to minimize the drop in output voltage. The measured time period, at time t2, is below the targeted burst period. The system increases the number of burst cycles. At t3, it measures the burst period again. In this example, the burst period is still below the targeted burst period. So, the system increases the number of low-power cycles again and again until the measured burst period equals the target burst period, which occurs at t4.

8.3.3.2 Negative transient response

When the system operates in burst mode, it defines the new number of cycles at the start of a new burst cycle. If the output load is reduced just after the start of a new burst cycle, the output voltage shows an overshoot (see Figure 16).

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At t1, the system starts with a new burst cycle period. Shortly later at t2, the output load is reduced. As a result the output voltage shows an overshoot and the optocoupler current increases. To limit the overshoot, the system also ends the burst cycle when the optocoupler current exceeds the Istop(burst) level.

8.3.3.3 Burst-mode delay function

When the output power drops to below the burst-mode power level, the system normally starts to operate in burst mode. If the output power is only below the burst-mode power level for a short time, to continue switching may be preferred. For example, to avoid audible noise or when using a multioutput configuration.

Entering burst mode can be delayed by using the burst-mode delay function. The output power has to be below the burst-mode power level for a minimum adjustable time then (see Figure 17).

If, during the burst-mode delay time, the output voltage cannot be regulated properly and continues to increase, the system enters burst mode anyway.

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8.3.3.4 Burst-mode exit delay function

When the system is in burst mode and a positive transient occurs, it may be preferred to leave the burst mode and restart the burst-mode delay function (see Figure 18).

When the LLC is switching for a time that exceeds the burst-mode exit delay time and the output load exceeds the burst-mode level, the system leaves the burst mode. The burstmode delay function is activated again. The burst-mode exit delay time can be set with a parameter.

In this way, the transient response is improved at a variable load while the system was initially in burst mode.

8.4 Optobias regulation

In a typical application, the output voltage is sensed using a TL431 and connected to the SNSFB pin of the TEA2017ABT via an optocoupler (see Figure 29). Because of the behavior of the TL431, the current through the optocoupler is at the maximum level when the output power is at the minimum level. It is therefore one of the most critical parameters to achieve the required no-load input power. To achieve maximum efficiency at low load/no load, the TEA2017ABT continuously regulates the optocurrent to a low level that is independent of the output load.

Because of the parasitic capacitance at the optocoupler collector, a very low optocurrent reduces the transient response of the system. So, the TEA2017ABT applies a fixed voltage at the SNSFB pin. It measures the current through the optocoupler which defines the required output power. Via an additional internal circuitry, which adds an offset to the required output power, the optocurrent is continuously (slowly) regulated to the $I_{\text{real(SNSFB)}}$ level (= 80 μA typical). This level is independent of the output power.

At a positive load transient, the optocurrent initially decreases (see Figure 8; I_{SNSFR}). The TEA2017ABT immediately increases the ΔV_{SNSCAP} which again increases the output power.

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Figure 19 shows that when the optocurrent decreases, the internal voltage across the 12 kΩ resistor drops to below the targeted level of 960 mV (= 80 μA (typical) × 12 kΩ). The TEA2017ABT then slowly increases an additional offset at the power level (ΔP). It continues to increase the additional offset until the optocurrent reaches the target of 80 μA (typical). When the optocurrent increases due to a transient, the additional offset to the power level is decreased. As a result, the output voltage decreases which again decreases the optocurrent. In this way, the optocurrent is continuously regulated to the I_{reg(SNSFB)} level.

The behavior of the internal circuitry connected to the SNSFB pin is the same as the behavior of the traditional circuitry. The fixed voltage at the SNSFB pin and the continuous regulation of the optocurrent level does not influence the regulation level. The advantage, however, is a reduction in no-load input power and an optimization of the transient response.

When the system operates in low-power mode at the minimum energy per cycle and at minimum duty cycle, it can no longer reduce the optocurrent level to the $I_{\text{real(SNSFB)}}$ target (» 80 μA typical). If the output power decreases further and the optocurrent increases to above the level of Istart(burst)

(» 100 μA typical), the burst mode is triggered. When the output power drops to below this level again, a new burst cycle is started (see Figure 14 and Figure 15).

8.5 Power factor correction (PFC) regulation

To achieve a high power factor (PF) and low total harmonic distortion (THD), the input current of the power supply must follow the mains input voltage. However, as the filter capacitances cause a shift of 90° between the mains input current and its voltage, the input filter disrupts PF and THD. To improve PF and THD, the average PFC current is in accordance with a shifted sine wave (see Figure 20).

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As the mains input current (I $_{\sf MANS}$) is the sum of the current through the filter capacitances (I_{C_total}) and the PFC current (I_{PFC}), it approaches a sine waveform.

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The output voltage control loop defines the amplitude of the shifted sine wave. If more power is requested to the output, the amplitude of the shifted sine wave increases.

The power factor correction circuit of the TEA2017ABT works in DCM/QR mode.

8.5.1 PFC switching frequency

The average PFC current is in accordance with a shifted sine wave. The PFC switching frequency is a function of this desired PFC current (see Figure 21). However, it is limited to the minimum and maximum frequency. These frequencies can be set using a parameter.

At the start of a mains cycle, the desired PFC current is zero and the PFC does not switch. When the PFC starts switching, the desired current is initially low and the PFC switching frequency is at minimum level. When the desired PFC current increases, the switching frequency increases as well until it reaches its maximum level.

Every switching cycle, the system calculates the PFC on-time such that its average current is in accordance with the desired PFC current and its frequency is in accordance with the above frequency curve. In this way, the system reaches the maximum efficiency at low loads, while keeping the ripple to a minimum at higher loads.

8.5.2 Frequency jitter

To optimize the EMI performance, an additional jitter can be added to the operating frequency of the PFC. The amplitude and modulation frequency of the jitter can be set using a parameter.

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8.5.3 DCM/QR mode of operation

At the start of a mains cycle, the desired PFC current is low and the PFC switching frequency is at minimum level. The PFC is then switching in DCM mode.

When the desired PFC current increases toward the center of the mains, the PFC switching frequency increases as well. The system automatically enters QR mode (see Figure 22).

The PFC MOSFET is only turned on when the previous secondary stroke has ended (transformer must be demagnetized) and the voltage across the PFC MOSFET has reached a minimum value. To detect transformer demagnetization and the minimum voltage across the PFC MOSFET switch, the control IC continuously monitors the voltage across the PFC MOSFET and the current through the PFC circuitry. As a result, the PFC switching frequency can drop to below the minimum set frequency.

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8.5.4 PFC start-up

At start-up, the PFC output voltage increases in line with an RC curve (see Figure 23).

At t1, the mains is connected and the PFC output voltage equals the peak voltage of the mains. At t2, the PFC starts switching and its output voltage increase in line with an RC curve.

Starting up with an RC curve has the advantage that after start-up, the PFC output voltage does not show any overshoot which avoids that the OVP is triggered. It also ensures that, at start-up, the on-time slowly increases from a minimum value to the regulation level, avoiding audible noise.

The RC time value can be programmed via the MTP.

8.5.5 Output voltage regulation

The PFC output voltage is externally divided using a high-ohmic resistive divider, which is connected to the SNSBOOST pin. The internal digital control loop, which compares the SNSBOOST voltage with an accurately trimmed reference voltage $(V_{\text{realSNSBOOST}})$, regulates the amplitude of the desired PFC current (see Figure 21).

The PFC current is measured via an external sense resistor connected to the SNSCURPFC pin. To ensure proper switching, the measured PFC current is internally filtered.

8.5.6 PFC burst mode

When the LLC is in burst mode and its duty cycle is below an adjustable entry level, the PFC enters burst mode.

When the LLC is out of burst mode or its duty cycle exceeds the entry level plus adjustable hysteresis, the PFC leaves burst mode.

Figure 24 shows the behavior of the PFC in burst mode.

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When the PFC is in burst mode and its output voltage drops to below the regulation level minus an adjustable ripple voltage, the PFC starts switching. When it reaches the regulation level again, the PFC stops switching.

When the ripple voltage is set to zero, the PFC always starts switching as soon as the LLC starts switching. When the output voltage reaches the regulation level and the LLC stops switching, the PFC stops switching as well.

When the PFC is activated in burst mode, it continues switching until it reaches the regulation level. As, during this time, the LLC may already have stopped switching, the system is not supplied via the auxiliary winding and the SUPIC capacitor is discharged.

To avoid that the SUPIC voltage reaches the $V_{\text{uvp(SUPIC)}}$ level, which causes the system to restart, the PFC stops switching when the SUPIC reaches $V_{low(SUPIC)}$ level. The system then enters the non-operating state and the internal current source is activated to supply the IC.

8.5.7 PFC burst mode soft start/soft stop

To reduce the audible noise, a soft start and a soft stop can be added to the PFC burst mode. During a soft start, the average PFC current starts at zero and increases to the required level. A soft stop implies that the average PFC current decreases from the regulation level down to zero. The rates of increase and decrease are independently adiustable.

8.5.8 Valley switching and demagnetization

The PFC MOSFET of the TEA2017ABT is switched on after the transformer is demagnetized.

To reduce switching losses and electromagnetic interference (EMI), the next stroke is started when the PFC MOSFET drain-source voltage is at its minimum (valley switching). The demagnetization and valley detection are measured via the SNSCURPFC and the DRAINPFC pin.

If no valley signal is detected on the DRAINPFC pin, the controller generates a valley signal $(t_{to(vrec)})$; 7 µs typical) after demagnetization is detected.

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8.5.9 Frequency limitation

To optimize the transformer and minimize switching losses, the PFC switching frequency is limited to $f_{sw(PFC)max}$.

To avoid audible noise, the minimum frequency is limited to $f_{sw(PFC)min}$.

To ensure correct control of the PFC MOSFET under all circumstances, the minimum offtime is limited at $t_{off(PFC)min}$.

All frequency limitation values are adjustable.

8.5.10 Mains voltage compensation (SNSMAINS pin)

The equation for the transfer function of a power factor corrector is a function of the mains input voltage. In a typical application, the result is a low bandwidth for low-mains input voltages. At high-mains input voltages, the mains harmonic reduction (MHR) requirements may be hard to meet.

To compensate for the mains input voltage influence, the TEA2017ABT contains a correction circuit. The input voltage is measured via the SNSMAINS pin (see Section 8.6.4). The information is fed to an internal mains compensation circuit. With this compensation, it is possible to keep the regulation loop bandwidth constant over the full mains input range. The result is that a mains voltage-independent transient response on load steps is yielded, while still complying with class-D MHR requirements.

8.5.11 Active X-capacitor discharge

The TEA2017ABT provides an active X-capacitor discharge after the mains voltage is disconnected. When the mains input voltage (and so also the measured current into the SNSMAINS pin) increases, the system assumes the presence of a mains voltage. When the mains voltage does not increase for a minimum period of $t_{d(dch)}$, the X-capacitor is discharged via the DRAINPFC pin. When the mains is reconnected, the discharge current is disabled again.

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8.6 Protections

Table 4 gives an overview of the available protections.

Table 4. Protections overview

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Table 4. Protections overview*...continued*

Protection	Description	Action	PFC	LLC	Protection register
maximum on-time	maximum on-time of the LLC MOSFET	LLC MOSFET switched off; continue operation			Y
CMR	capacitive mode regulation	system ensures that mode of operation is inductive			Y
OCP	overcurrent protection	switch off cycle-by-cycle; After several consecutive cycles, LLC and PFC are either latched or safe restart [1]	off	off	Y
STARTUP MAX	maximum start-up time	LLC and PFC are either latched or safe restart [1]	off	off	Υ
OPP	overpower protection	LLC and PFC are either latched or safe restart [1]	off	off	Υ

[1] Selectable via a parameter at the MTP.

When the system is in a latched or safe restart protection, the SUPIC voltage is regulated to its start level via the DRAINPFC pin.

8.6.1 Undervoltage protection SUPIC

When the voltage on the SUPIC pin is below its undervoltage level $V_{\text{uvp(SUPIC)}}$, the PFC and LLC converter stop switching. The capacitors at the SUPIC pin are recharged via the DRAINPFC pin.

When the SUPIC supply voltage exceeds its start level, the system restarts.

8.6.2 MTP fail

At start-up, when the SUPIC reaches 12 V, the system reads the parameters from the internal MTP. If reading the MTP failed, a protection is triggered. A mains reset is required before the system starts. During this time, the PFC and LLC remain off.

8.6.3 Internal overtemperature protection (OTP)

An accurate internal temperature protection is provided in the circuit. When the junction temperature exceeds the thermal shutdown temperature, the PFC and the LLC stop switching.

The response of the internal OTP follows the setting of the external OTP. It can be either latched or safe restart.

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8.6.4 Brownin/brownout and external overtemperature protection

On the TEA2017ABT, the mains measurement and external temperature measurement are combined at the SNSMAINS pin (see Figure 25).

The TEA2017ABT continuously measures the SNSMAINS voltage via an A/D converter and waits until it detects a peak (t1). This peak value is internally stored and used for the mains compensation. The output of the A/D converter is used for brownout/brownin detection.

During an NTC measurement, which is enabled during the peak of the mains, an internal current source of $I_{O(SNSMAINS)}$ is switched on. With the external NTC and diode, the internal current source generates a voltage at the SNSMAINS pin. If this voltage remains below the $V_{\text{det(SNSMAINS)}}$ level, the external OTP protection is triggered after

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 $t_{d(oto)}$. The internal current source is turned on until the SNSMAINS voltage exceeds the $V_{\text{det(SNSMAINS)}}$ level level or a maximum time of $t_{\text{det(max/NTC}}$.

The external resistor, which is connected between mains_L/mains_N and the SNSMAINS pin, can be either 20 MΩ or 10 MΩ. The amount of mains resistor can either be one (only connected to the mains-L or mains-N) or two (one connected to the mains-L and the other to the mains-N). However, the selected parameter of the resistor value and number of resistors must correspond to the application.

8.6.5 Short-circuit protection/fast disable

The PFC and LLC do not start switching until the voltage on the SNSBOOST pin exceeds $V_{\text{scpl}(\text{start})}$. This function acts as short circuit protection for the boost voltage.

When the SNSBOOST pin is shorted to ground or the SNSBOOST pull-up resistor is disconnected, this protection inhibits switching.

This function can also be used as a fast disable. If this pin is shorted to ground via an external MOSFET, the system either stops switching or enters the protection mode followed by safe restart or latched protection. In this way, an additional external protection can be added.

When the fast disable function is selected to stop switching only, it can be combined with a reset of all protections. The MTP bit "fast disable FLR" must be enabled then. So, if any protection is triggered, it is reset when the SNSBOOST voltage drops to below the $V_{\text{scp}(stop)}$ level for at least t_{diffr} . When the SNSBOOST voltage exceeds the Vscp(start) level, the PFC resumes switching. When the SNSBOOST voltage exceeds the V_{start(SNSBOOST)} level, the LLC resumes switching.

8.6.6 Brownout mains

To prevent the PFC from operating at very low mains input voltages, the PFC stops switching with a soft stop when the measured mains voltage drops to below the brownout level. When the mains voltage exceeds the brownin level, the PFC restarts with a soft start. To avoid that the system is interrupted during a short mains interruption, a delay can be set before the brownout function is active.

Typically, only the PFC stops switching and the LLC continues at a brownout. Due to the large PFC bulk capacitor, the LLC can continue for a long period while the mains is already disconnected. So, the option to stop the LLC at a brownout after a given delay can be selected with a parameter.

8.6.7 Overvoltage protection (SNSBOOST pin)

To prevent output overvoltage during load steps and mains transients, a PFC output overvoltage protection circuit is built in. When the voltage on the SNSBOOST pin exceeds the $V_{stop(ovp)PFC}$ level, switching of the power factor correction circuit is inhibited. When the SNSBOOST pin voltage drops to below the regulation level ($V_{\text{real} \text{SNSBOOST}}$) again, the switching of the PFC recommences.

When an OVP at the SNSBOOST is detected for a minimum period (can be set using a parameter), the LLC can be disabled.

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8.6.8 Overvoltage protection (DRAINPFC pin)

To prevent output overvoltage of the PFC due to a disturbed SNSBOOST pin, an additional PFC output overvoltage protection is available. This overvoltage protection is measured via the DRAINPFC pin.

To avoid false triggering, measuring the DRAINPFC is blanked for $t_{\text{leb(OVP)PFC}}$ after the PFC MOSFET is switched off.

The DRAINPFC overvoltage protection level and the delay before it enters the protection state can be set with parameters.

The DRAINPFC overvoltage protection can be a latched, a safe restart, or a latched after safe restart protection.

8.6.9 Overcurrent protection, inrush protection (SNSCURPFC pin)

The PFC current is measured via an external sense resistor (R_{SENSE}) connected to the SNSCURPFC pin (see $Figure 29$). If the voltage drops to below $V_{ocp(PEC)}$, the PFC MOSFET is turned off. It resumes switching at the next cycle, under the condition that the voltage at the SNSCURPFC is above the $V_{ocp(PFC)}$ level. Otherwise, it remains off until this requirement is fulfilled. It avoids that the PFC MOSFET is turned on during an inrush.

To ensure that the OCP level is not exceeded due to disturbance caused by a turn-on of the PFC MOSFET, the OCP level is filtered via an internal 1 MHz filter.

8.6.10 PFC coil short protection (SNSCURPFC pin)

If the PFC coil is shorted, the overcurrent protection is triggered continuously. To avoid overheating, the system enters the protection state when the OCP is continuously triggered for a selectable number of switching cycles. The PFC and LLC converters stop switching and a restart follows.

8.6.11 Undervoltage protection SUPHS

To ensure a minimum drive voltage at the high-side driver output (GATEHS), this driver is turned off when its voltage is below the minimum level $(V_{\text{SUPHS}} < V_{\text{rst(SUPHS)}})$.

8.6.12 Undervoltage protection boost

The PFC output voltage is measured via a resistive divider connected to the SNSBOOST pin. The voltage at the SNSBOOST pin must exceed the start level $(V_{\text{SNSBOOST}} > V_{\text{start(SNSBOOST)}})$ before the LLC converter is allowed to start switching.

When the system is operating and the voltage at the SNSBOOST pin drops to below the minimum level ($V_{SNSBOOST}$ < $V_{uvp(SNSBOOST)}$), the LLC converter stops switching. When it exceeds the start level, it restarts.

8.6.13 Overvoltage protection (SUPIC pin)

When the voltage at the SUPIC pin exceeds the $V_{O(\text{ovp})SUPIC}$ level for $t_{d(\text{ovp})SUPIC}$, the OVP protection is triggered. The voltage at the SUPIC pin is continuously monitored via an internal A/D converter.

The OVP protection level and the OVP delay time can be selected with a parameter.

The OVP function can also be disabled.

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8.6.14 Capacitive mode regulation (CMR)

The TEA2017ABT has a capacitive mode regulation (CMR) which ensures that the system is always operating in inductive mode and avoids operation in capacitive mode.

At lower input voltage or higher output power and depending on the resonant design, the resonant current can already approach zero before the capacitor voltage reaches the regulation level.

When the resonant current has changed polarity before the switches are turned off and the other switch is turned on, hard switching occurs. This event is called capacitive mode. To avoid that the LLC operates in capacitive mode, the system also switches off the highside/low-side switch when the resonant current approaches zero.

Figure 26 shows the signals that occur when a resonant converter is switching in CMR mode. At t1 (and also at t3), the low-side switch is on while the resonant current approaches zero before V_{SNSCAP} reaches $V_{IS(SNSCAP)}$. At t2, the resonant current is also close to changing polarity while the divided capacitor voltage (V_{SNSCAP}) has not reached the $V_{hs(SNSCAP)}$ level yet. To avoid a turn-off of the high-side switch at a negative current or the low side at a positive current, the system also turns off the high-side/lowside switch when the primary current approaches zero. So at t2, the high-side switch is turned off because the primary current is close to zero. At t_3 (and also at t_1), the lowside switch is turned off, although V_{SNSCAP} did not reach the regulation level $(V_{IS/NSCAP})$ yet. The primary current is measured via an external sense resistor connected to the SNSCURLLC pin. The capacitive mode protection levels are V_{reg(capm)} (−100 mV typical and +100 mV typical). These levels can be adjusted with a parameter.

In this mode, the amount of output power is reduced and the output voltage decreases.

The TEA2017ABT does not enter a so-called "capacitive mode protection", but avoids this mode of operation.

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8.6.15 Overcurrent protection

The system measures the LLC primary current continuously via a sense resistor connected to the SNSCURLLC pin. If the measured voltage exceeds the fixed overcurrent level $(V_{ocp(LLC)})$, the corresponding switch (GATELS/GATEHS) is turned off, but the system continues to switch. In this way, the primary current is limited to the OCP level.

The OCP level can be adjusted via the external sense resistor.

If the OCP is continuously triggered for an adjustable time, the system enters the OCP protection state. The OCP protection state can also be disabled. However, the primary current is always limited to the OCP level cycle-by-cycle.

8.6.16 Maximum start-up time

At start-up, the PFC starts switching. When the PFC output voltage exceeds a minimum level, the LLC starts switching as well.

If the output voltage of the LLC is not in regulation within an adjustable time after the LLC has started switching, the maximum start-up time protection is triggered.

The maximum start-up time $(t_{\text{startup}(\text{max})})$ can be set with the parameter "Maximum startup time". If this protection is triggered, the system is latched, safe restart, or latched after safe restart, which follows the setting of the OPP.

8.6.17 Overpower protection

For the overpower protection, three levels can be set:

- **•** Absolute maximum output power, which is the highest output power level. When the output power exceeds this maximum level, it is limited cycle-by-cycle. If the output power exceeds this maximum, the output voltage decreases. The maximum output power can be set to a percentage of the rated output power.
- **•** A first overpower level, which is below the maximum output power level. When the output power exceeds this power level, a timer is started. When this timer exceeds a predefined value, the system enters the protection state. The PFC and the LLC are switched off.

This power level can be set to a predefined level below the selected maximum output power. So, if the maximum output power is set to 170 % and this first overpower level is set to −20 %, the timer is started at 150 % of the rated output power.

The timer of the first overpower level can also be set. The first overpower level can also be disabled.

• A second overpower level, which is typically below the first overpower level. When the output power exceeds this power level, a timer is started. When this timer exceeds a predefined value, the system enters the protection state. The PFC and the LLC are switched off.

This power level can be set to a predefined level below the selected maximum output power. So, if the output power is set to 170 % and this second overpower level is set to −50 %, the timer is started at 120 % of the rated output power.

The timer of the second overpower level can be set to a predefined level. The second overpower level can also be disabled.

The overpower function can be either latched, safe restart, or latched after safe restart. Section 8.6.18 describes this function.

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8.6.18 Latched, safe restart, or latched after safe restart

When a protection is selected to be latched, the system stops switching when this protection is triggered. The system only restarts after a fast latch reset (see Section 8.6.19) or when the SUPIC supply voltage drops below the UVP level.

When a protection is selected to be safe restart, the system continuously restarts after a predefined safe restart time. This safe restart time is the same for all protection functions. It can be set with a parameter.

When selecting "latched after safe restart", a protection is initially a safe restart protection. If the failure occurs again within a specific time, it latches eventually.

Figure 27 shows an example of when the OVP is set to latched after safe restart. Initially at an OVP, the system restarts after the safe restart time. An internal counter is then set to '1'. If the protection is triggered again, the counter is increased. If the counter reaches the number as set with a parameter, the system latches. If no protection is triggered within 65 seconds, the counter is reset.

8.6.19 Fast latch reset

If a protection is triggered, the system enters the protection state. Especially when the protection is latched, this function is inconvenient during production tests. So, when the mains voltage is below the brownout level for a specified time, the system also restarts. This time can be set with a parameter. This function is called fast latch reset.

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8.7 Power good function

The TEA2017ABT provides a power good function via the SNSFB pin.

The primary function of the SNSFB pin is to regulate the output voltage via an optocoupler. So, it measures the current that is drawn from the SNSFB. Via an internal 12 k $Ω$ resistor, it regulates the output power. The output power regulation is independent of the voltage level of the SNSFB pin. So, the voltage level at the SNSFB pin is used to indicate if the system is about to stop operating, a so-called power good signal. The voltage at the SNSFB pin can be used to generate a secondary power good signal using an external MOSFET and an optocoupler.

At start-up, the SNSFB voltage is at a high level, pulling down the secondary power good signal. As soon as the system enters the operating state (see Figure 4), the SNSFB goes low. The external power good signal becomes active high.

The SNSFB voltage becomes active high, lowering the secondary power good signal when:

- The voltage on the SNSBOOST pin drops to below V_{det(SNSBOOST})
- **•** The OPP counter is close to its end value
- **•** The converter is about to stop due to an OTP protection
- **•** When the LLC converter is about to stop due to an OVP on the SNSBOOST when this function is enabled
- **•** When the LLC converter is about to stop due to a mains brownout when this function is enabled

To avoid any disturbance of the regulation loop, the increase and decrease of the SNSFB voltage is in alignment with a predefined ramp.

When the system enters protection mode (OVP, OCP, or UVP), it pulls high the SNSFB pin and stops switching immediately.

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8.8 Settings

The TEA2017ABT has an internal MTP at which different settings can be programmed.

The TEA2017ABT settings can be found in Section 13.

Disclaimer:

The MTP parameter settings can be changed using the "Ringo" GUI software of NXP Semiconductors. Before the user can change any MTP parameters using the GUI, the terms and conditions in the start-up pop-up screen must be accepted.

8.8.1 General settings

8.8.1.1 Protection register

When the TEA2017ABT triggers a protection, it can be read which protection was triggered. Even when the root cause of the protection is solved and the converter continues switching, the information about the protection remains until the software program (Ringo GUI) clears it.

8.8.1.2 Supply start level

The SUPIC start level can be selected between 12 V and 19 V. Typically, a level of 19 V is selected. When the TEA2017ABT is externally supplied, for instance via a standby supply, the lower start level of 12 V can be used.

After start-up, when the MTP is read and a 12 V start level is selected, charging via the PFCDRAIN is disabled, as the system assumes that it is externally supplied.

8.8.1.3 Read lock

Normally, the software tool can read all the programmed settings. This option can be used to verify the correct settings or for failure analyses.

However, once in production, enabling the "Read lock" bit protects the parameters. Then it is not possible anymore to read the MTP content. It can however still be reset to the default values and also clear the read lock parameter.

8.8.1.4 Write lock

To avoid that the MTP content (accidentally) gets overwritten, a write-lock bit can be set. It can, however, still be reset to the default values and clear the write lock parameter.

8.8.1.5 Reset to the default values

When the MTP is reset, it implies that all parameters are set to a default value. The default values normally do not correspond to the original MTP values. They are chosen such that a general application works properly.

When the MTP is reset, the MTP can be read and written again.

8.8.1.6 Customer MTP code

When in production, the content of the MTP can be hidden when the read lock bit is enabled. To get access to the content of the MTP, a unique customer code can be programmed. This customer code provides information about the MTP content.

This customer code can always be read, even when the read lock bit is enabled.

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8.8.2 PFC settings

8.8.2.1 Soft-start time

For the start-up time of the PFC, the following RC time periods can be selected: 13 ms, 25 ms, 51 ms, or 102 ms.

8.8.2.2 Active X-capacitor discharge

When the TEA2017ABT detects that the mains is disconnected, the X-capacitor discharge is activated after a delay of $t_{\rm d(dch)}$. The following delays can be selected: 100 ms, 200 ms, and 400 ms. This function can also be disabled.

8.8.2.3 Mains measurement impedance

To realize a low no-load input power level, the external resistor connected to the SNSMAINS pin for measuring the mains input voltage is typically 20 MΩ.

However, some applications request a maximum resistance of 10 MΩ. With this bit, 10 MΩ or 20 MΩ can be selected for the external resistor without affecting the mains voltage-related levels like brownin and brownout.

8.8.2.4 Number of mains resistors

To achieve the lowest possible no-load input power, a single mains sense resistor can be used. If continuously measuring the mains voltage is necessary, two mains resistors can be used.

For proper functionality, the resistor value and number of resistors in the application are required to correspond to the IC settings.

8.8.2.5 PFC mode of operation

The PFC of the TEA2017ABT works in DCM/QR mode. However, the frequency varies between the minimum and maximum frequency.

The option to disable the PFC can be selected for evaluation purposes.

8.8.2.6 PFC minimum and maximum frequency

The minimum switching frequency of the PFC can be set within a range from 25 kHz to 80 kHz. The PFC always waits until the PFC coil is demagnetized before starting the next cycle. As a result, the switching frequency can drop to below the minimum frequency.

The maximum frequency can be set within a range from 75 kHz to 250 kHz.

8.8.2.7 Burst mode: Output voltage ripple

When the PFC enters burst mode, it stops switching when the SNSBOOST voltage, which reflects the PFC output voltage, reaches its regulation level and the LLC stops switching. When the voltage at the SNSBOOST pin has dropped to a programmed level, the PFC is enabled again. For the difference between these two levels the following values can be selected: 70 mV, 105 mV, 140 mV, 175 mV, 210 mV, 245 mV, and 280 mV. These values typically correspond with a ripple on the PFC output voltage of 10 V, 16 V, 22 V, 28 V, 34 V, 40 V, and 46 V.

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The PFC burst mode can also be synchronized to the LLC burst mode. It then follows the on and off periods of the LLC. However, it ensures that the SNSBOOST reaches its regulation level.

8.8.2.8 Burst mode: Soft-start/soft-stop time

To minimize audible noise of the PFC, a burst mode soft start and soft stop can be independently selected. The selectable values are: normal, short, and long. The additional soft-start and soft-stop can also be disabled.

8.8.3 LLC settings

8.8.3.1 LLC disable

Especially for validation purposes, an option is available to disable the LLC. When the LLC is disabled, a restart is required.

8.8.3.2 Start-up

Maximum (start-up) frequency

The maximum switching frequency of the LLC is limited to a value, which is defined using a parameter. This value also defines the maximum switching frequency during start-up. The maximum frequency can be set to different values ranging from 150 kHz to 800 kHz.

LLC soft-start time

The LLC soft-start time defines the rate at which the converter lowers its switching frequency. This rate can be selected between 2 and 20 which leads to a start-up time of approximately between 1 ms and 10 ms. However, it depends on the LLC design. A higher speed lowers the start-up time. However, it can cause a high charge current and an overshoot at the output voltage.

Maximum primary current during start-up

At start-up, the LLC starts switching at the maximum frequency and ramps down the frequency until the ΔV_{SNSCAP} reaches the required level. If during this start-up time the primary current, which reflects the output current, reaches a predefined level, the frequency is temporarily not further reduced until the primary current drops to below the level again. This level is measured via the SNSCURLLC pin. The following values can be selected: 0.5 V, 0.75 V, 1.0 V, or 1.25 V.

8.8.3.3 LLC switching

ΔVSNSCAP dump level

When the system is in low-power mode, a switching period is followed by a waiting period. The system ensures that it continues at the same stage as where it stopped. To reach the maximum efficiency, the end of the last switching cycle can be fine-tuned. For the ΔV_{SNSCAP} dump level, values between 2.525 V and 2.7 V can be selected in steps of 25 mV.

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Minimum non-overlap time

To ensure that the GATEHS is properly turned off before the GATELS is turned on, and vice versa, there is a minimum non-overlap time. For the minimum non-overlap time, the following values can be selected: 100 ns, 230 ns, 350 ns, 500 ns.

Maximum non-overlap time

When the system does not detect a valley at the HB node after turning off GATEHS, the system turns on the GATELS after the maximum non-overlap time. The same counts when a peak at the HB node is not detected after turning off the GATELS and turning on the GATEHS. For the maximum non-overlap time, the following values can be selected: 0.5 μs, 0.7 μs, 0.9 μs, or 1.1 μs.

Maximum on-time

When the on-time of the GATELS or GATEHS exceeds the maximum on-time, the switch is turned off and the LLC converter starts the next cycle. For the maximum on-time, the following values can be selected: 10 μs, 20 μs, 30 μs, or 38 μs.

Capacitive mode regulation

When the voltage at the SNSCURLLC pin, which reflects the resonant current, drops to below a predefined value, the LLC converter starts the next switching cycle. In this way, the TEA2017ABT avoids that the converter operates in capacitive mode. For the capacitive mode regulation, the following values can be selected: 20 mV to 160 mV in steps of 20 mV.

LLC maximum ringing time

When the LLC operates in LP mode, it counts the amount of ringings. If a ringing is not detected, it assumes a peak after the timeout. This timeout can be set to 3 μs, 5 μs, 7.5 μs, or 10 μs. The appropriate value depends on the application. It must be chosen just above the maximum ringing period.

8.8.3.4 Feedback

Optocoupler current

To achieve a low no-load input power, the current through the optocoupler must be set at a low level. However, depending on the selected optocoupler, a higher optocoupler current may be requested. So, the optocoupler current can be set to different values ranging from 80 μA to 1.2 mA.

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8.8.3.5 Operation modes

HP-LP transition level

When the output power drops to below a predefined level, the system switches from the HP to the LP mode. The HP-LP transition level can be set to different values ranging from 10 % to 54 %.

HP-LP transition hysteresis

When the system operates in LP mode, it switches over to HP mode when the output power exceeds the selected HP-LP transition level plus a hysteresis. For the hysteresis, the following values can be selected: 10 %, 20 %, 30 %, or 40 % of the selected HP-LP transition level. So, if the rated output at 100 % is 100 W, the HP-LP transition level is set at 30 % and the hysteresis is set at 10 %. The eventual hysteresis is 3 W.

LP-BM transition level

When the output power drops below the LP-BM transition level, the system enters burst mode. The LP-BM transition level can be set to different values ranging from 1 % to 25 %.

The actual LP-BM transition level can deviate from the selected value due to delays in the system. The deviation is most noticeable at low LP-BM transition levels. In this case, the LP-BM transition level can be fine-tuned in steps of 1 %.

BM-LP transition level

When the system operates in burst mode and output power increases to exceed the LP-BM transition level plus a hysteresis level, the system enters low-power mode. For the hysteresis, levels in the range from 5 % to 50 % can be selected, which are related to the selected LP-BM transition level. So, if the rated output at 100 % is 100 W, the LP-BM transition is set at 10 %, and the hysteresis at 50 %, the system switches from burst mode to low-power mode at a level of 15 W.

BM-LP transition level filter

When the output power slowly increases, the system ensures a smooth transition when leaving burst mode and entering low-power mode by setting a burst-mode-to-low-powermode transition filter. When the output power exceeds the BM-LP transition level plus hysteresis for 2, 4, 8, or 16 burst cycles, it leaves the burst mode and enters the lowpower mode. At a large transient at the output, the system immediately leaves burst mode.

BM repetition frequency

When the system operates in burst mode, it is regulated to a fixed frequency. This frequency can be set to different values ranging from 20 Hz to 3.2 kHz.

BM E/C (Energy-per-cycle) increase

As the TEA2017ABT regulates the output via the primary capacitor voltage, it offers the ability to increase the output power per switching cycle when it enters burst mode. For the increase of output power per switching cycle, also called E/C (Energy-per-cycle), different values can be set ranging from 1 to 4. When, for instance, the E/C is set to 4, the system increases the E/C with a factor of 4 when it enters burst mode. The initial duty cycle is then 25 %. Increasing the E/C in burst mode increases the efficiency of the system, but at the cost of a higher output voltage ripple.

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BM soft start/soft stop

To minimize the audible noise in burst mode, a soft start and a soft stop can be added. The soft start and soft stop can be independently initialized, whereas the number of softstart/soft-stop cycles can be set between 0 and 4. In this way, the soft-start and soft-stop cycle can be optimized depending on the selected transformer.

BM minimum cycles

As additional soft-start and soft-stop cycles reduces the audible noise, it increases the switching losses. To optimize the number of normal switching cycles in relation to the added soft-start and soft-stop switching cycles, the minimum number of normal switching cycles that can be selected ranges from 1 to 12.

Burst end SNSFB current

When the system operates in burst mode, it adjusts the number of switching cycles such that burst frequency corresponds to the selected burst frequency. If during these switching cycles the output load decreases, the output voltage increases as the system has calculated the number of required switching cycles. If the measured optocoupler current at the SNSFB pin exceeds a certain level, the system ends the burst switching cycle. This level can be between a factor of 2.5, 3.75, 5, or 7.5 times the selected optocoupler current level.

Burst delay

Entering the burst mode can be postponed with a delay from 0.2 s to 4 s. The delay can also be set to 0, implying that when the output power drops to below the burst mode entry level, the system immediately enters burst mode. The burst mode delay can also be set to infinite. The system does not enter burst mode and remains switching.

Burst-mode exit delay

When the LLC is switching for a time that exceeds the burst-mode exit delay time and the output load exceeds the burst-mode level, the system leaves the burst mode. The burstmode exit delay time ($t_{burst-exit}$) can be set from 160 μs to 4 ms in 16 steps.

Low-power frequency

The frequency of the low-power mode can be selected by defining the ringing number at which the next low-power cycle must be started. The selection options are from 1 to 8 in steps of 1.

SNSBOOST compensation

A ripple at the input voltage of an LLC converter normally results in a ripple in the output voltage. To minimize the ripple at the output voltage, the TEA2017ABT measures the input voltage of the LLC via the SNSBOOST pin and compensates the SNSCAP voltage via a feed-forward compensation. As the required compensation depends on the external components, it can be set at 8 different compensation levels.

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8.8.4 Protection settings

8.8.4.1 General protections

Fast latch reset delay time

When the system does not detect a mains voltage for a programmed period, it assumes that the mains is disconnected and resets all protections. When the mains voltage exceeds the brownin level again, the system restarts. The delay between detecting a brownout (including the brownout delay time) and resetting all protections can be programmed to different values ranging from 0 s to 10 s.

Safe restart time

When the system is in protection mode and the triggered protection is programmed as safe restart, it restarts after a safe-restart time. This time can be set at different values ranging from 0.5 s to 10 s.

Fast disable

When the SNSBOOST voltage is pulled below the $V_{\text{scp}(stop)}$ level, the system enters the protection state. The response can be set to on/off, latched, or safe restart.

Reset of protections

If the fast disable is activated, it can be selected if all triggered protections must be reset.

When using an external standby supply, the preference may be that, if the main converter is turned off, all protections are reset. It can then easily be applied via the SNSBOOST pin.

External OTP level

The external application temperature is measured via an NTC connected to the SNSMAINS pin. To be able to set the appropriate NTC value and OTP level, the internal current used to measure the external NTC value can be set between 150 µA and 1050 µA in steps of 150 µA.

To avoid false triggering, an internal delay occurs before the system enters protection. This delay can be set to different values between 0.5 s and 8 s.

The response of the external OTP can be latched, safe restart, or latched after safe restart. The external OTP function can also be disabled.

Internal OTP level

The internal OTP is fixed at 135 °C. When the internal OTP is triggered, it follows the same response as selected for the external OTP, being either latched, safe restart, or latched after safe restart.

8.8.4.2 PFC general protections

Brownin/brownout level

For the brownin level, several values can be selected ranging from 67 V (AC) to 185 V (AC). For the hysteresis between the brownin and brownout level, several values can be selected from 2 V (AC) to 17 V (AC). The given values depend on the resistor values in the application and their tolerances.

When the mains voltage is below the brownout period for a selectable amount of time. the system enters the brownout state. For this time, several values can be selected ranging from 25 ms to 1.2 s.

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PFC OCP level

The PFC OCP level is fixed to $V_{ocp(PFC)}$. The external sense resistor can select the corresponding current value.

PFC maximum on-time

The maximum on-time of the PFC equals 1 / minimum frequency. Where the minimum frequency set by the MTP and the possible additional frequency jitter defines the minimum frequency.

PFC coil short protection

When the PFC continuously triggers the OCP, the system eventually enters the protection state. A counter is increased by 3 every PFC switching cycle where the OCP level is exceeded. It is decreased by 1 every cycle where the level is below the OCP level. When the counter reaches 2500, 5000, or 12500, the system enters the protection state. This function can also be disabled.

PFC output OVP

The PFC output voltage is measured via the SNSBOOST pin and the DRAINPFC pin. For the OVP at the SNSBOOST pin, the following values can be selected: 2.60 V, 2.63 V, 2.65 V, or 2.70 V.

When an OVP is detected at the SNSBOOST pin, the PFC stops switching and continues again when its voltage drops below the regulation level.

For the OVP at the DRAINPFC pin, the following values can be selected: 475 V, 500 V, 525 V, or 550 V. To avoid false triggering, a delay can be selected of 100 cycles, 250 cycles, or 1000 switching cycles. During this delay, the output voltage of the PFC is limited to this maximum value.

The response of an OVP at the DRAINPFC pin can be latched, safe restart, or latched after safe restart. This function can also be disabled.

Valley detection timeout

When the PFC MOSFET is off and the current through the PFC coil becomes zero, the coil is demagnetized. Normally, shortly after the demagnetization, the drain voltage starts to ring and a valley is detected. When the system detects demagnetization but does not detect a valley shortly after, the ringing may be too small to detect a valley. So, when demagnetization is detected, it assumes a valley within a specified time. For this time, the following values can be selected: 2 μs, 3 μs, 5 μs, or 7 μs.

PFC minimum off-time

To avoid false triggering of the demagnetization and valley detection, a minimum offtime of the PFC driver output can be selected. The available values are 500 ns, 750 ns, 1000 ns, and 1500 ns.

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8.8.4.3 LLC general protections

Maximum start-up time

When the LLC starts switching, it expects that its output voltage reaches the regulation level within a maximum start-up time. For the maximum start-up time, the following values can be selected: 25 ms, 50 ms, 100 ms, and 200 ms.

LLC brownout level (SNSBOOST)

When the voltage at the SNSBOOST drops below a predefined level, the LLC converter enters the protection state. When the SNSBOOST voltage exceeds the brownin level, the LLC converter starts switching again.

For the LLC brownout level at the SNSBOOST, a level in the range from 1.0 V to 2.05 V can be selected.

LLC brownin level (SNSBOOST)

The LLC brownin level defines the minimum voltage at the SNSBOOST pin before the LLC starts switching. For this level, a value ranging from 1.5 V to 2.4 V can be selected.

LLC brownout timer (SNSMAINS)

When the mains is disconnected, the PFC stops switching after its brownout delay. Normally, the LLC converter continues switching until the input voltage of the LLC drops to below a minimum (V_{uvp(SNSBOOST)}) level. Especially at a minimum load at the output, the LLC dropping to the minimum level can take a long time.

A timer can be initialized that disables the LLC converter when a brownout is detected at the mains input. For this time, a value can be selected ranging from 125 ms to 6 s. The option that the LLC converter remains switching until its input voltage drops to below a minimum level can also be selected.

LLC maximum input voltage (SNSBOOST)

When an OVP is detected on the SNSBOOST pin, the PFC always stops switching. The response of the LLC can be set to either continue operation or stop switching. A delay can be set to either 5 ms, 50 ms, or 1250 ms.

Power limit

The maximum output power of the converter is limited by the controller. The limitation ensures that the applied load is below the maximum rating-selected components. For the maximum output power, several levels between 100 % and 200 % of the rated power can be selected.

OPP level 1

When the output power exceeds a first OPP level, a first counter is started. When the output power continuously exceeds this OPP level for a selected period, the system enters protection state. For the OPP level, a level between 0 % and −50 % below the selected power limit can be selected.

For the time, a value between 50 ms to 40 s can be selected. The response of this protection can be latched, safe restart, or latched after safe restart. This OPP level can also be disabled.

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OPP level 2

When the output power exceeds a second OPP level, a second counter is started. When the output power continuously exceeds this OPP level for a selected period, the system enters protection state. For the OPP level, a level in the range from −10 % to −50 % below the selected power limit can be selected.

For the time, a value ranging from 50 ms to 3 s can be selected. The response of this protection follows the selected response of the OPP level 1. This OPP level can also be disabled.

OPP duty cycle

When the output power exceeds the OPP with a duty cycle of 50 %, the OPP may or may not be triggered. So, the duty cycle at which the OPP is triggered eventually can be set using a parameter to 11 %, 20 %, 33 %, or 50 %.

OVP protection

In a resonant converter, the voltage at the SUPIC pin reflects the output voltage. When the SUPIC voltage exceeds a defined level, the OVP protection is triggered. The level can be set between 1 V and 16 V above the start level in steps of 1 V.

To avoid false triggering, a delay can be set at different values ranging from 10 μs to 800 μs. The response of this protection can be latched, safe restart, or latched after safe restart. This OVP function can also be disabled.

OVP duty cycle

To minimize the sensitivity of the OVP function, a duty cycle can be set at which the OVP is eventually triggered. This parameter can be set to 11 %, 20 %, 33 %, or 50 %. If, for example, the OVP delay is set to 800 μs, the duty cycle to 50 %, and the SUPIC voltage exceeds the OVP level for 300 μs and drops to below the OVP level for 500 μs, the OVP is never triggered.

OCP protection

The current in the resonant tank is measured at the SNSCURLLC pin. When the voltage at this pin exceeds the OCP level, the corresponding switch (GATELS or GATEHS) is turned off and the system starts the next cycle. So, the LLC current is limited cycle-bycycle.

If the OCP occurs for a defined number of cycles, the OCP protection is triggered. The number of cycles can be set to different values between 5 and 1000.

The response of this protection can be latched, safe restart, or latched after safe restart. The OCP protection function can also be disabled. However, the LLC current remains limited cycle-by-cycle.

8.8.5 Power good settings

The power good function gives a prewarning to the load that the converter is switched off due to disconnected mains or a triggered protection.

Power good time

The power good time is the time between the power good signal indicating that the converter is about to be switched off and the time the converter eventually stops switching. This delay can be set to 4 ms, 6 ms, 8 ms, or 10 ms.

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Power good at OTP

The power good signal can give a prewarning when the converter is switched off due to an OTP detection. The OTP can be either an internal or an external OTP.

This function can be enabled or disabled. The delay between the transition of the power good signal and the moment that the converter stops switching equals the power good time.

Power good at OPP

The power good signal can give a prewarning when the converter is switched off due to an OPP detection. The prewarning can be given when the output power exceeds the OPP level1 or OPP level2 for the defined time.

This function can be enabled or disabled. The delay between the transition of the power good signal and the moment that the converter stops switching equals the power good time.

Power good at mains brownout

The power good signal can give a prewarning when the LLC converter is switched off due to a brownout detection at the mains input of the converter.

This function can be enabled or disabled. The delay between the transition of the power good signal and the moment that the converter stops switching equals the power good time.

Power good at LLC brownout level (SNSBOOST)

When the measured voltage at the SNSBOOST pin drops to below the selected LLC brownout level, the LLC converter stops switching. It normally occurs due to a disconnected mains.

The power good signal can give a prewarning when the converter is switched off due to this LLC brownout detection. When the voltage at the SNSBOOST drops to below a selectable value, the power good feature is triggered. The level can be selected between 1 V and 2.05 V.

Power good at OVP (SNSBOOST)

The TEA2017ABT offers a setting option to stop the LLC operation at an SNSBOOST OVP. When the LLC converter is switched off due to an SNSBOOST OVP, the power good signal can give a prewarning. This function can be enabled or disabled. The delay between the transition of the power good signal and the moment the converter stops switching equals the power good time.

Power good ready delay

When the output voltage is in regulation after start-up, power good indicates that the output voltage is in regulation. A delay can be set between the time the output voltage reaches the regulation level and the transition of the power good signal. This delay can be set at different values between 0 s and 1 s.

Power good transition time

The power good function is combined with the feedback network connected at the SNSFB pin. To avoid that a trigger of the power good function disturbs the regulation loop, its transition time must have a predefined value. This time can be set at 0.85 ms, 1.8 ms, 2.6 ms, or 3.5 ms.

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9 Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

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Table 5. Limiting values*...continued*

In accordance with the Absolute Maximum Rating System (IEC 60134).

[1] Although the GATE pins are output pins, the maximum voltage of these pins must not exceed the maximum drive output voltage by 20 %.

10 Thermal characteristics

Table 6. Thermal characteristics

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11 Characteristics

Table 7. Characteristics

Tamb = 25 °C; VSUPIC = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified.

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Table 7. Characteristics*...continued*

Tamb = 25 °C; VSUPIC = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified.

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Table 7. Characteristics*...continued*

Tamb = 25 °C; VSUPIC = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified.

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Digital configurable LLC and DCM/QR PFC controller

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Table 7. Characteristics*...continued*

Tamb = 25 °C; VSUPIC = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified.

Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

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Table 7. Characteristics*...continued*

Tamb = 25 °C; VSUPIC = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified.

Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

[1] Covered by correlating measurement

[2] As the minimum limit determines the application design, the maximum limit is not relevant.

12 Application information

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Ringo parameter settings

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Table 8. Ringo parameter/IC parameter settings*...continued*

Digital configurable LLC and DCM/QR PFC controller

Table 8. Ringo parameter/IC parameter settings*...continued*

Digital configurable LLC and DCM/QR PFC controller

Table 8. Ringo parameter/IC parameter settings*...continued*

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14 Package outline

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15 Revision history

Table 9. Revision history

Digital configurable LLC and DCM/QR PFC controller

16 Legal information

16.1 Data sheet status

[1] Please consult the most recently issued document before initiating or completing a design.
[2] The term 'short data sheet' is explained in section "Definitions".

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